

**PSG COLLEGE OF ARTS & SCIENCE
(AUTONOMOUS)**

**MCA DEGREE EXAMINATION MAY 2025
(Third Semester)**

Branch- COMPUTER APPLICATIONS

ARTIFICIAL INTELLIGENCE

Time: Three Hours

Maximum: 75 Marks

SECTION-A (10 Marks)

Answer ALL questions

ALL questions carry EQUAL marks (10 × 1 = 10)

Module No.	Question No.	Question	K Level	CO
1	1	Which of the following best describes the nature of environments in AI? a) Static and dynamic environments b) Deterministic and stochastic environments c) Discrete and continuous environments d) All of the above	K1	CO1
	2	Which problem-solving technique begins with an initial state and attempts to reach a goal state through a sequence of actions? a) Uninformed Search b) Problem-solving Agent c) Genetic Algorithm d) Neural Networks	K2	CO1
2	3	Which of the following is an advantage of using alpha-beta pruning in game algorithms? a) Increases the depth of the search tree b) Reduces the time complexity c) Always finds the shortest path d) Guarantees perfect play	K1	CO2
	4	In a Wumpus world scenario, knowledge-based agents use which type of logic to make decisions? a) Predicate Logic b) Temporal Logic c) Propositional Logic d) Description Logic	K2	CO2
3	5	Which form of learning involves the agent making decisions based on feedback from the environment? a) Supervised Learning b) Unsupervised Learning c) Reinforcement Learning d) Semi-supervised Learning	K1	CO3
	6	In the context of decision trees, which criterion is commonly used to decide the best split at a node? a) Mean Squared Error b) Gini Index c) Gradient Descent d) Backpropagation	K2	CO3
4	7	Which of the following is an application of information retrieval in natural language processing? a) Speech Recognition b) Querying a search engine c) Image Classification d) Syntactic Parsing	K1	CO4
	8	Which technology is used in automatic translation of one language into another? a) Machine Learning b) Machine Translation c) Information Extraction d) Speech Synthesis	K2	CO4
5	9	Which of the following is considered a core challenge in robotics perception? a) Object recognition in dynamic environments b) Power supply management c) Path optimization for static environments d) Data storage	K1	CO5
	10	Which aspect of robotics involves generating a sequence of valid configurations that move the robot from its initial position to a goal position? a) Localization b) Motion Planning c) Sensor Fusion d) Reinforcement Learning	K2	CO5

Cont...

SECTION - B (35 Marks)

Answer ALL questions

ALL questions carry EQUAL Marks (5 × 7 = 35)

Module No.	Question No.	Question	K Level	CO
1	11.a.	Develop the types of agents in AI. How do simple reflex agents differ from model-based agents?	K3	CO1
		(OR)		
	11.b.	Compare breadth-first search and depth-limited search. When is each more suitable?		
2	12.a.	Dissect stochastic games. How are they different from deterministic games?	K4	CO2
		(OR)		
	12.b.	Categorize, how does a logical agent work in a knowledge-based system?		
3	13.a.	Appraise the process of training an artificial neural network using backpropagation.	K5	CO3
		(OR)		
	13.b.	Distinguish the differences between reinforcement learning and supervised learning.		
4	14.a.	Measure the role of machine translation in natural language processing.	K5	CO4
		(OR)		
	14.b.	Explain how speech recognition systems work.		
5	15.a.	Discuss the challenges of robot perception and how sensors are used to gather information about the environment.	K6	CO5
		(OR)		
	15.b.	Elaborate the techniques are used to handle uncertainty in real-world robotic systems.		

SECTION -C (30 Marks)

Answer ANY THREE questions

ALL questions carry EQUAL Marks (3 × 10 = 30)

Module No.	Question No.	Question	K Level	CO
1	16	Apply the process of problem formulation in AI. How does a problem-solving agent use this process to achieve a goal?	K3	CO1
2	17	Compare and contrast first-order logic and propositional logic in the context of knowledge representation.	K4	CO2
3	18	Estimate the key features and limitations of supervised learning. Provide examples of algorithms used in supervised learning.	K5	CO3
4	19	Evaluate the process of information extraction in natural language processing.	K5	CO4
5	20	Elucidate a case study on robotic perception systems used in autonomous vehicles.	K6	CO5

Z-Z-Z END