

Implementing Proportional Controller on SBHS, remotely

Talk To a Teacher

<http://sakshat.ac.in>

National Mission on Education through ICT

<http://spoken-tutorial.org>

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Objectives

In this tutorial we will learn to:

- Use Ziegler Nichols tuning method to calculate proportional controller gain



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- Use Ziegler Nichols tuning method to calculate proportional controller gain
- Modify step test code to design a Proportional controller



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In this tutorial we will learn to:

- Use Ziegler Nichols tuning method to calculate proportional controller gain
- Modify step test code to design a Proportional controller
- Implement this Proportional Controller on SBHS



Software requirements

- **Scilab must be installed on your computer**



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- **Ensure that you have internet connectivity to practice this tutorial**



Software requirements

- **Scilab must be installed on your computer**
- **Ensure that you have internet connectivity to practice this tutorial**
- **I am using Windows-7 32-bit OS**



Prerequisites

- Watch the following tutorial



Prerequisites

- Watch the following tutorial
 - Using SBHS Virtual labs on Windows OS



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- Watch the following tutorial
 - Using SBHS Virtual labs on Windows OS
- Available on the spoken tutorial website



Prerequisites

- Watch the following tutorial
 - Using SBHS Virtual labs on Windows OS
- Available on the spoken tutorial website
- Teaches how to do a step test experiment on SBHS, remotely



Prerequisites

- Watch the following tutorial
 - Using SBHS Virtual labs on Windows OS
- Available on the spoken tutorial website
- Teaches how to do a step test experiment on SBHS, remotely
- Basic knowledge of PID tuning is required



Prerequisites

- Step test experiment code folder must be available



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- Step test experiment code folder must be available
- Step test experiment data file must be available



Prerequisites

- Step test experiment code folder must be available
- Step test experiment data file must be available
- If not, re-do the step test experiment to generate a new data file



Ziegler-Nichols PID tuning methods

PID Tuning rules given by Ziegler-Nichols

- Reaction curve method



Ziegler-Nichols PID tuning methods

PID Tuning rules given by Ziegler-Nichols

- Reaction curve method
- **Instablity method**



Reaction curve method

- Step input is given and output is observed



Reaction curve method

- Step input is given and output is observed
- Exponential response of system



Reaction curve method

- Step input is given and output is observed
- Exponential response of system
- Tangent is drawn at the point of inflection

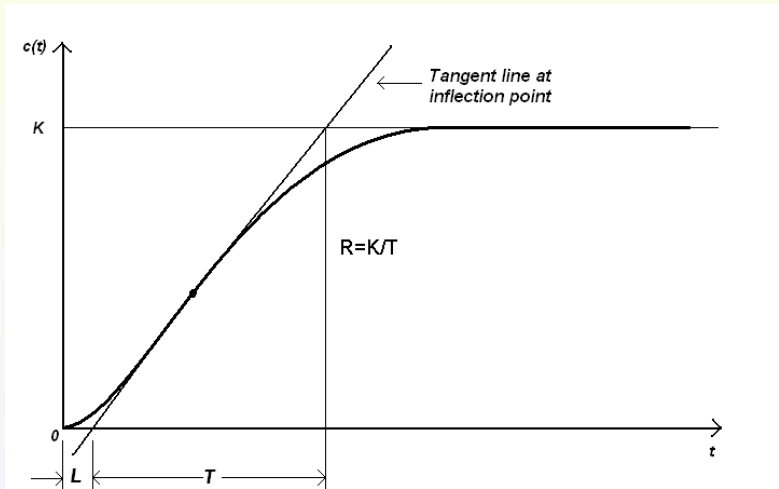


Reaction curve method

- Step input is given and output is observed
- Exponential response of system
- Tangent is drawn at the point of inflection
- Dead time and time constant are computed from the time axis



Step response



Ziegler Nichols PID tuning table

Type of controller	K	τ_i	τ_d
P	$\frac{1}{RL}$	∞	0
PI	$\frac{0.9}{RL}$	$3L$	0
PID	$\frac{1.2}{RL}$	$2L$	$0.5L$



Summary

In this tutorial, we have learnt how to,

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Summary

In this tutorial, we have learnt how to,

- Use Ziegler Nichols tuning method to calculate proportional controller gain for SBHS
- Modify step test code to design a Proportional controller
- Implement the designed Proportional Controller on SBHS



About the Spoken Tutorial Project

- Watch the video available at http://spoken-tutorial.org/What_is_a_Spoken_Tutorial
- It summarises the Spoken Tutorial project
- If you do not have good bandwidth, you can download and watch it



Spoken Tutorial Workshops

The Spoken Tutorial Project Team

- Conducts workshops using spoken tutorials
- Gives certificates to those who pass an online test

For more details, contact

contact@spoken-tutorial.org



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- More information on this Mission is available at:

<http://spoken-tutorial.org/NMEICT-Intro>

