


Introduction to Reliability Engineering
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Lecture 24
Markov Analysis (Contd)

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Hello everyone, welcome back to our discussion on Markov analysis. In previous class, we discussed about degraded systems, we also started discussing about the how to incorporate repair in our Markov diagram and solve it. So, today we will try to solve that problem.

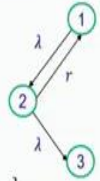
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Two Component System with Repair



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 INTRODUCTION TO RELIABILITY ENGINEERING

$\frac{dP_1(t)}{dt} = -2\lambda P_1(t) + rP_2(t)$	$P_1(t) = \frac{\lambda + r + x_1}{x_1 - x_2} e^{x_1 t} - \frac{\lambda + r + x_2}{x_1 - x_2} e^{x_2 t}$	
$\frac{dP_2(t)}{dt} = 2\lambda P_1(t) - (r + \lambda)P_2(t)$	$P_2(t) = \frac{2\lambda}{x_1 - x_2} e^{x_1 t} - \frac{2\lambda}{x_1 - x_2} e^{x_2 t}$	
$\frac{dP_3(t)}{dt} = \lambda P_2(t)$	$P_3(t) = 1 + \frac{x_2}{x_1 - x_2} e^{x_1 t} - \frac{x_1}{x_1 - x_2} e^{x_2 t}$	
$P_1(t) + P_2(t) + P_3(t) = 1$	$x_1, x_2 = \frac{1}{2} \left[-(3\lambda + r) \pm \sqrt{\lambda^2 + 6\lambda r + r^2} \right]$	

$$R(t) = 1 - P_3(t) = \frac{x_1}{x_1 - x_2} e^{x_1 t} - \frac{x_2}{x_1 - x_2} e^{x_2 t}$$

$$MTTF = \int_0^\infty \left(\frac{x_1}{x_1 - x_2} e^{x_1 t} - \frac{x_2}{x_1 - x_2} e^{x_2 t} \right) dt$$

$$= \frac{-1}{x_1 - x_2} \left[\frac{x_1}{x_2} - \frac{x_2}{x_1} \right] = \frac{-(x_1 + x_2)}{x_1 x_2} = \frac{3\lambda + r}{2\lambda^2}$$

21
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So, in previous class we discuss two component system with repair. So, here we consider that that this let me correct this and make it 2 lambda so, there is no confusion here. So, here we have 2 (sys) 2 components working or 2 systems working one of them is failed in state number 2 and here both the components have failed the when 1 failure and 1 working state is there then there is a repair possibility and once repair is successful within available time, then my system can be restored to back to the condition 1 system state 1 where both components will again start working.

So, here to solve this as we have seen or discussed earlier, we will try to use these 3 equations for P 2 and p 3 as well as p 1 p 2 p 3 is equal to 1 and using these equations, we will try to make a set of equations and try to solve it using the Laplace diagram.

(Refer Slide Time: 01:58)

$\frac{dP_2(t)}{dt} = 2\lambda P_1(t) - (r + \lambda)P_2(t)$ $\frac{dP_3(t)}{dt} = \lambda P_2(t)$ $P_1(t) + P_2(t) + P_3(t) = 1$

$\frac{dP_1(t)}{dt} = 2\lambda [1 - P_1(t) - P_2(t)] - (r + \lambda)P_1(t)$
 $= 2\lambda - P_1(t) [2\lambda + r + \lambda] - 2\lambda P_2(t)$
 $\rightarrow \frac{dP_1(t)}{dt} = 2\lambda - (3\lambda + r)P_1(t) - 2\lambda P_2(t)$

$\mathcal{L}\{P_1(t)\} = Z_1(s) = Z_1$; $P_1(0) = 1, P_2(0) = 0, P_3(0) = 0$

$s Z_1 - P_1(0) = \frac{2\lambda}{s} - (3\lambda + r) Z_1 - 2\lambda Z_3$
 $\Rightarrow s Z_1 + (3\lambda + r) Z_1 + 2\lambda Z_3 = \frac{2\lambda}{s}$
 $\Rightarrow Z_1 [s + 3\lambda + r] + 2\lambda Z_3 = \frac{2\lambda}{s}$

$\begin{bmatrix} s + 3\lambda + r & 2\lambda \\ \lambda & -s \end{bmatrix} \begin{bmatrix} Z_1 \\ Z_3 \end{bmatrix} = \begin{bmatrix} 2\lambda/s \\ 0 \end{bmatrix}$

$\rightarrow x_1, x_2 = \frac{-(3\lambda + r) \pm \sqrt{\beta + r^2 + 6\lambda r}}{2}$

Cramer's
 $Z_3 = \frac{\begin{vmatrix} s + 3\lambda + r & 2\lambda/s \\ \lambda & 0 \end{vmatrix}}{\begin{vmatrix} s + 3\lambda + r & 2\lambda \\ \lambda & -s \end{vmatrix}}$
 $Z_3 = \frac{+ 2\lambda^2/s}{+s(s + 3\lambda + r) + 2\lambda^2}$
 $Z_3 = \frac{2\lambda^2}{s[s^2 + (3\lambda + r)s + 2\lambda^2]}$

I have written these equations here for the reference so, that we can follow up to solve this. To solve this first what we want we will do we want this equation to be 2 probabilities. So, first I will convert this p 1 into P 2 and p 3 so, my both equations when they will then be belonging to P 2 and p 3 only.

So, this will be dP 2 t over dt is equal to 2 lambda into 1 minus P2T minus r plus lambda into P 2 t. Now, this when we solve then if you open this will become 2 lambda minus P 2 T is having r plus lambda negative here and minus 2 lambda here. So, that is 2 lambda plus r plus lambda minus 2 lambda into P 3 t this if we solve further this will become 2 lambda minus here if I solve this this will become 3 lambda plus r into P 2 t minus 2 lambda P3T.

Now, let us consider the Markov transformation sorry, Laplace transformation if we apply Laplace transformation then we are calling Laplace of any probability function Pit let us say that is zis, since s will be common for all so, I will be using for short form as zi. So, if we do this then we know we take the Laplace transform for all for this complete equation, if we do that then Laplace transform of and we know that P 1 0 is equal to 1 p 2 0 is equal to 0 initial conditions are P 3 0 is equal to 0.

We know Laplace transform of differentiation term produces the s into Laplace transform of the term that is z 2 minus z minus p 2 at 0 that is equal to Laplace transform right side so 2 lambda

this is constant value if you take Laplace so, then it will become 1 upon s minus 3λ plus r . Laplace transform of P_2 will be z^2 minus 2λ . Laplace transform of P_3 will be z^3 . $P_2(0)$ is 0 .

So, my equation will turn out to be $s z^2$. I can take this z^2 term there so this will become plus 3λ plus r into z^2 . This also I can take left hand side this will become $2\lambda z^3$ which is equal to 2λ upon s . So, here this equation I can write as z^2 into s plus 3λ plus r plus 2λ into z^3 is equal to 2λ upon s .

Similarly, I can solve this equation if I take a Laplace transform for this this will become s into z^3 minus p_3 at 0 will be equal to λz^2 and P_t equal to 0 at 0 is 0 from here, so, this becomes $s z^3$ is equal to λz^2 . This I can solve take on one side so, this will become λz^2 minus $s z^3$ equal to 0 .

So, I have these two equations let us see equation 1 and equation 2. Now, these two equations if I make a set of equations, then I can make this equation in the matrix form if I convert this into matrix form then for this equation it will become s plus 3λ plus r this is 2λ and from here if I take z^2 multiplied by λ and z^3 multiplied by minus s into $z^2 z^3$ will be equal to this equation is 2λ upon s and this will be 0 this right side is 0 this is 2λ upon s .

So, from system of two equations I have made the matrix equivalent now, this matrix equivalent I can solve using the Cramer's so, Cramer's rule says that if I want to know the z^2 here then z^2 I can evaluate first let us see, we can evaluate z^3 what happens here if we see here my reliabilities probably p_1 plus P_2 and what is p_1 plus p_2 , p_1 plus P_2 is 1 minus p_3 so, or because this is on reliability f_t is equal to P_3 .

So, my reliability is 1 minus f_t that is 1 minus P_3 . So, if I want if I know the z , if I know the P_3 then I can know the reliability directly I do not have to calculate p_1 and P_2 still, we can calculate that, but for the reliability calculation if that is our only aim then knowing z^3 is enough or knowing P_3 is enough so, for P_3 calculation, we can calculate the z^3 .

So, z^3 as we see, z^3 will be equal to so, if I want to calculate z^3 z^3 is on the second second row, so, I have to replace this second column with the output column. So, this determinant of s plus 3λ plus r first column will remain same second column will replace by the output column.

(Refer Slide Time: 12:14)

Handwritten mathematical derivation for partial fraction decomposition:

$$z_3 = \frac{2s^2}{s(s-x_1)(s-x_2)} = \frac{1}{s} + \frac{B}{s-x_1} + \frac{C}{s-x_2}$$

$$z_3 = \frac{1}{s} + \frac{x_2}{x_1-x_2} \cdot \frac{1}{s-x_1} + \frac{x_1}{x_2-x_1} \cdot \frac{1}{s-x_2}$$

Equating coefficients:

$$A+B+C=0$$

$$(x_1+x_2)A + x_1B + x_2C = 0$$

$$x_1x_2A = 2s^2 \Rightarrow A = \frac{2s^2}{x_1x_2} = \frac{2s^2}{s^2 - x_1^2}$$

$$B+C = -1 \Rightarrow B = -1-C$$

$$(x_1+x_2) + x_1B + x_2C = 0$$

$$\Rightarrow x_1+x_2 - x_2(1+C) + x_2C = 0$$

$$\Rightarrow x_1 + x_2 - x_2 - x_2C + x_2C = 0$$

$$\Rightarrow -C(x_1-x_2) = -x_1$$

$$\Rightarrow C = \frac{x_1}{x_1-x_2}$$

$$B = -1 - \frac{x_1}{x_1-x_2} = \frac{-x_1-x_2-x_1}{x_1-x_2} = \frac{-2x_1-x_2}{x_1-x_2}$$

$$B = \frac{x_2}{x_1-x_2}$$

So, what I have I have z_3 is equal to $\frac{2s^2}{s(s-x_1)(s-x_2)}$, $\frac{2s^2}{s^2 - x_1^2}$, $\frac{2s^2}{s^2 - x_2^2}$, $\frac{1}{s}$, $\frac{B}{s-x_1}$ plus $\frac{C}{s-x_2}$. If I solve this here then as we know we can solve this by part so, this will become s into $s-x_1$ into $s-x_2$ and so, if LCM will be this if I divide by s that this will become $s-x_1$ into $s-x_2$ so, A into $s-x_1$ into $s-x_2$ that is $s^2 - x_1s + x_2s - x_1x_2$ plus B into $s-x_2$ plus C into $s-x_1$ so, this will become $s^2 - s(x_1-x_2) - x_1x_2$.

So, that will become $s^2 - x_2s + x_1s - x_1x_2$ similarly, C will get multiplied with $s-x_2$ so, that will be $s^2 - x_1s + x_2s - x_1x_2$. Now, if I compare the term denominator is equal and if I compare the terms on here then we will say because there is no s^2 term here. So, for s^2 terms like I will just do this calculation again $x_1^2 + x_2^2 = x_1^2 + x_2^2 + 2x_1x_2 - 2x_1x_2$ and s terms if I see then plus s into $s-x_1$ plus $s-x_2$ into a , s here is $s-x_1$ and s here is $s-x_2$ and remaining terms are plus $s-x_1$ plus $s-x_2$ into a there is no term without s here. So, that is the only term divided by s into $s-x_1$ into $s-x_2$.

So, if we compare this then $a + b + c$ will be equal to 0 and all are negative. So, if I want I can write it in terms of $s-x_1$ plus $s-x_2$ into a plus $s-x_2$ into B plus $s-x_1$ into C because there is no s term here so, that will also be equal to 0 and last term is $s-x_1$ into $s-x_2$ A that is equal that is the term without s .

So, that is equal to $2\lambda^2$ here or I can say is equal to $2\lambda^2$ upon $x_1 \times x_2$ this $x_1 \times x_2$ if we see here x_1 is 1 with plus sign and x_2 will be with minus sign and we know so, I can say this is A and this is B, so, I can say this is a minus b one will be a plus b another will be a minus b.

So, x_1 , I can write it as x_1 is equal to minus a plus b and x_2 is half of 8 and x_2 I can write as minus a minus b or if I take this and what is A and B here. So, if I take $x_1 \times x_2$ that will be equal to $\frac{1}{4}$ I can take minus here so, this will become plus here $\frac{1}{4}$ minus and a plus b into b minus a will give you $b^2 - a^2$ or this will be $\frac{1}{4}(b^2 - a^2)$ and what is my a here is $3\lambda + r$.

So, A^2 will become $9\lambda^2 + r^2 + 6\lambda r$ and what is b, b is square root of $\lambda^2 + r^2 + 6\lambda r$. So, $b^2 = \lambda^2 + r^2 + 6\lambda r$ whole divided by 4 this if we see $6\lambda r$ will get cancelled r^2 will also get cancelled, and $9\lambda^2 - \lambda^2$ will give $8\lambda^2$ divided by 4 which is equal to $2\lambda^2$.

So, my $x_1 \times x_2$ turns out to be $2\lambda^2$. So, this a will become $2\lambda^2$ upon $2\lambda^2$ that will be equal to 1 my a is 1 so, now, I can use the same thing in these two equations. So, from these two equation b plus c will be equal to minus 1 and if I put a equal to 1 this will become $x_1 + x_2 + x_2 B + x_1 c$ is equal to 0.

Now, these two equations we can solve I can do that I can replace b here. So, b will be equal to minus 1 minus c I can place this here so, this will become $x_1 + x_2 - x_2$ because x_1 become minus x_2 into $1 + C + x_1 c$ is equal to 0.

So, this if I solve further then $x_1 + x_2 - x_2 - x_2 c + x_1 c$ is equal to 0 this is cancelled and if I take this then c into $x_1 - x_2$ is equal to minus x_1 or I can say C is equal to x_1 upon $x_2 - x_1$ if I multiply by minus sign on both sides and this will become $x_1 \times x_2 - x_1$ and what is b, a is equal to 1 we already got C is equal to x_1 upon $x_2 - x_1$ and b is equal to minus 1 minus c.

So, minus 1 minus x 1 upon x 2 minus x 1 so, x 2 minus x 1 if we take common then this will be minus x 2 plus x 1 minus x 1 so, minus sin is 0 so, minus sin can be taken below so, this will become x 2 upon x 2 minus x 1 minus x 2.

Now, here if we see my equation z 3 z 3 will now become a is 1 1 upon s plus b is x 2 upon x 1 minus x 2 into 1 upon s minus x 1 plus C is x 1 upon x 2 minus x 1 and into 1 upon s minus x 2. Now, this equation which we have got, I am removing some equations here because we have already solved this. So, we will have a little bit more space to understand this.

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The image shows a handwritten mathematical derivation for the partial fraction decomposition of $Z_3 = \frac{z^3}{s^2(s-x)}$. The derivation is as follows:

$$Z_3 = \frac{z^3}{s^2(s-x)} = \frac{1}{s} + \frac{A}{s-x} + \frac{B}{s} + \frac{C}{s-x}$$

$$Z_3 = \frac{1}{s} + \frac{x_1}{x_1-x_2} \cdot \frac{1}{s-x_1} + \frac{x_2}{x_2-x_1} \cdot \frac{1}{s-x_2}$$

$$P_3(t) = 1 + \frac{x_1}{x_1-x_2} e^{x_1 t} + \frac{x_2}{x_2-x_1} e^{x_2 t}$$

$$R(t) = 1 - P_3(t)$$

$$R(t) = -\frac{x_1}{x_1-x_2} e^{x_1 t} + \frac{x_2}{x_2-x_1} e^{x_2 t}$$

The derivation also includes the following steps:

$$x_1 = \frac{-a+b}{2}$$

$$x_2 = \frac{-a-b}{2}$$

$$x_1 x_2 = -\frac{1}{4} [b^2 - a^2]$$

$$= \frac{1}{4} [a^2 - b^2]$$

$$= \frac{1}{4} [(a+b)(a-b)] = \frac{(a+b)(a-b)}{4}$$

$$x_1 x_2 = \frac{8x^2}{4} = 2x^2$$

On the right side, the derivation shows the method of equating coefficients:

$$s^2 [A+B+C] + s [-x_1 A - x_2 B - x_1 C] + x_1 x_2 A$$

$$B+C = -1 \Rightarrow B = -1-C$$

$$(x_1+x_2) + x_2 B + x_1 C = 0$$

$$\Rightarrow x_1 + x_2 - x_2(1+C) + x_1 C = 0$$

$$\Rightarrow x_1 + x_2 - x_2 - x_2 C + x_1 C = 0$$

$$= -C(x_2-x_1) + x_1 C$$

$$\Rightarrow C = \frac{x_1}{x_1-x_2}$$

$$B = -1 - \frac{x_1}{x_1-x_2} = \frac{-x_1-x_2-x_1}{x_1-x_2} = \frac{-2x_1-x_2}{x_1-x_2}$$

$$B = \frac{x_2}{x_1-x_2}$$

So, here, we will now take the Laplace inverse, which is quite straightforward here. And Laplace inverse as we know Laplace inverse of 1 upon s is a constant quantity. So, Laplace inverse of z 3, if you take Laplace inverse then z 3 of Laplace inverse of z3 P3T, Laplace of z 3 Laplace of p 3 was z 3, so, Laplace inverse of z3 will be P3T and Laplace of 1 is 1 upon s.

So, Laplace inverse of 1 upon S is 1 plus x 2 upon x 1 minus x 2 and we know Laplace inverse of 1 upon s minus x 1 is e to the power plus x 1 t. Similarly, plus x1 upon x 2 minus x 1 e to the power x 2 t. So, if we see here because x 1 x 2 is known to us, we already have calculated here, if you put x 1 x 2 calculated value from here in this equation, I will get the P3T and RT I can get as 1 minus P3T. So, this will be 1 minus this. So, 1 minus 1 will be 0 and this will be negative sign negative sign if I take below this will become reversal sign reversal will be there.

So, this will become x_2 upon x_2 minus x_1 e to the power $x_1 t$ and this will be plus because this is negative so, this becomes x_2 minus x_1 this becomes x_1 minus x_2 upon x_1 minus x_2 e to the power $x_2 t$ the way we have calculated $P_3(t)$ we can also calculate the $p_2(t)$ in a similar fashion by using the Cramer's rule.

If you see here my r is x_1 upon x_1 minus x_2 x_2 T x_1 upon x_1 minus x_2 e to the power $x_2 t$ if I take this x_1 minus x_2 then this will become minus minus x_2 upon x_1 minus x_2 e to the power $x_1 t$ minus x_2 upon x_1 minus x_2 e to the power $x_1 t$.

(Refer Slide Time: 22:39)

The slide, titled "Two Component System with Repair", contains the following content:

- State Transition Diagram:** A diagram with three states: 1 (top), 2 (middle), and 3 (bottom). Transitions are labeled with rates: 2λ from 1 to 2, λ from 2 to 3, and r from 3 to 2. Handwritten notes include: $P_1(t) + P_2(t) = R(t)$, $1 - P_3(t) = R(t)$, and $P_1(t) = P_2(t)$.
- Differential Equations:**

$$\frac{dP_1(t)}{dt} = -2\lambda P_1(t) + r P_2(t)$$

$$\frac{dP_2(t)}{dt} = 2\lambda P_1(t) - (r + \lambda) P_2(t)$$

$$\frac{dP_3(t)}{dt} = \lambda P_2(t)$$

$$P_1(t) + P_2(t) + P_3(t) = 1$$
- General Solutions:**

$$P_1(t) = \frac{\lambda + r + x_1}{x_1 - x_2} e^{x_1 t} - \frac{\lambda + r + x_2}{x_1 - x_2} e^{x_2 t}$$

$$P_2(t) = \frac{2\lambda}{x_1 - x_2} e^{x_1 t} - \frac{2\lambda}{x_1 - x_2} e^{x_2 t}$$

$$P_3(t) = 1 + \frac{x_2}{x_1 - x_2} e^{x_1 t} - \frac{x_1}{x_1 - x_2} e^{x_2 t}$$

$$x_1, x_2 = \frac{1}{2} \left[-(3\lambda + r) \pm \sqrt{\lambda^2 + 6\lambda r + r^2} \right]$$
- Reliability and MTTF Calculations:**

$$R(t) = 1 - P_3(t) = \frac{x_1}{x_1 - x_2} e^{x_2 t} - \frac{x_2}{x_1 - x_2} e^{x_1 t}$$

$$MTTF = \int_0^{\infty} \left(\frac{x_1}{x_1 - x_2} e^{x_2 t} - \frac{x_2}{x_1 - x_2} e^{x_1 t} \right) dt$$

$$= \frac{-1}{x_1 - x_2} \left[\frac{x_1}{x_2} \right] = \frac{-(x_1 + x_2)}{x_1 x_2} = \frac{3\lambda + r}{2\lambda^2}$$

Same value which we have got there, this is $P_3(t)$ is also saying 1 plus x_2 upon x_1 minus x_2 e to the power $x_1 t$ and this we have written x_1 upon x_2 minus x_1 e to the power $x_2 t$ same value which we have got here same are reflected there. So, we are able to calculate reliability here directly.

(Refer Slide Time: 23:08)

$$Z_3 = \frac{2\lambda^2}{s(s-x_1)(s-x_2)} = \frac{A}{s} + \frac{B}{s-x_1} + \frac{C}{s-x_2}$$

$$Z_3 = \frac{1}{s} + \frac{x_2}{x_1-x_2} \cdot \frac{1}{s-x_1} + \frac{x_1}{x_2-x_1} \cdot \frac{1}{s-x_2}$$

$$f_3(t) = 1 + \frac{x_2}{x_1-x_2} e^{x_1 t} + \frac{x_1}{x_2-x_1} e^{x_2 t}$$

$$R(t) = 1 - f_3(t)$$

$$R(t) = \frac{x_2}{x_1-x_2} e^{x_1 t} + \frac{x_1}{x_2-x_1} e^{x_2 t}$$

Partial Fractions:
 $\frac{2\lambda^2}{s(s-x_1)(s-x_2)} = \frac{A}{s} + \frac{B}{s-x_1} + \frac{C}{s-x_2}$
 $2\lambda^2 = A(s-x_1)(s-x_2) + B[s(s-x_2)] + C[s(s-x_1)]$
 $2\lambda^2 = A[s^2 - (x_1+x_2)s + x_1x_2] + B[s^2 - x_2s] + C[s^2 - x_1s]$
 $2\lambda^2 = (A+B+C)s^2 + [-A(x_1+x_2) - Bx_2 - Cx_1]s + Ax_1x_2$

Solving for A, B, C:
 $B+C = -1 \Rightarrow B = -1-C$
 $(x_1+x_2) + x_2B + x_1C = 0$
 $\Rightarrow x_1+x_2 - x_2(1+C) + x_1C = 0$
 $\Rightarrow x_1+x_2 - x_2 - x_2C - x_1C + x_1C = 0$
 $= -C(x_1-x_2) = -x_1$
 $\Rightarrow C = \frac{x_1}{x_1-x_2}$
 $B = -1 - \frac{x_1}{x_1-x_2} = \frac{-x_1-x_2-x_1}{x_1-x_2} = \frac{-2x_1-x_2}{x_1-x_2}$
 $B = \frac{x_2}{x_1-x_2}$

Final Result:
 $f_3(t) = 1 + \frac{x_2}{x_1-x_2} e^{x_1 t} + \frac{x_1}{x_2-x_1} e^{x_2 t}$
 $R(t) = \frac{x_2}{x_1-x_2} e^{x_1 t} + \frac{x_1}{x_2-x_1} e^{x_2 t}$

If I want to calculate MTTF, then again MTTF will be x_2 upon x_2 minus x_1 into 1 upon x_1 as we see minus lambda it comes so this will be minus sign and again minus of x_1 upon x_1 minus x_2 into 1 upon x_2 . So, we can solve this and we can we will be able to get the values of MTTF also I have explained this for calculating P3T we can follow the same process and we can get the value of P2T also.

I will try I will show you for so that you will be able to follow up better. So, that same process what we have done earlier for P3t, we will follow the same process for P2T, so that you are able to follow it.

(Refer Slide Time: 24:05)

$$Z_2 = \frac{2\lambda}{\begin{vmatrix} s & 1 \\ 0 & -s \end{vmatrix}} = \frac{2\lambda}{-[s(s+3\lambda+1) + 2\lambda^2]} = \frac{2\lambda}{-[s^2 + (3\lambda+1)s + 2\lambda^2]} = \frac{2\lambda}{(s-x_1)(s-x_2)}$$

$$Z_2 = \frac{2\lambda}{(s-x_1)(s-x_2)} = \frac{A}{s-x_1} + \frac{B}{s-x_2}$$

$$Z_2 = \frac{2\lambda}{x_2-x_1} \cdot \frac{1}{s-x_1} + \frac{2\lambda}{x_1-x_2} \cdot \frac{1}{s-x_2}$$

$$= \frac{A(s-x_2) + B(s-x_1)}{(s-x_1)(s-x_2)} = \frac{(A+B)s - [Ax_1 + Bx_2]}{(s-x_1)(s-x_2)}$$

Laplace Inverse

$$p(t) = \frac{2\lambda}{x_2-x_1} e^{x_1 t} + \frac{2\lambda}{x_1-x_2} e^{x_2 t}$$

$$A+B=0 \Rightarrow A=-B$$

$$Ax_1 + Bx_2 = 2\lambda$$

$$-Bx_1 + Bx_2 = 2\lambda$$

$$B(x_2 - x_1) = 2\lambda$$

$$B = \frac{2\lambda}{x_2 - x_1}$$

$$A = \frac{2\lambda}{x_1 - x_2}$$

$$p(t) = 1 - p_1(t) - p_2(t)$$

So, as an exercise, I am doing it for $z^2 t$. Now $z^2 t$ as we have seen here. If we solved from here, then z^2 is the first row. So, that means first column will be replaced by the output column. So, 2λ upon s . So, (deno) determinant of 2λ upon s and 2λ minus s second column will remain as it is 2λ minus s divided by the denominator term we already solved that denominator term came out to be see same thing will come up s minus like we got here.

This value was 2λ square upon s divided by s into this so, rather than 2λ squared by s this this was the determinant value for this that determinant for this was this s into s plus 3λ plus r plus 2λ squared s into s plus 3λ plus r plus 2λ square. Now, this if we solve further this will be equal to this multiply by this will be minus 2λ s into s will be 1 divided by and 2λ into 0 will be 0 and this we already saw this as s square plus 3λ plus r into s plus 2λ squared this was also negative as we got earlier this was also negative. So, this will also become positive again.

Now, we got this value now, to solve this what we can do we can again put it like 2λ upon s minus x_1 and x minus x_2 the $x_1 x_2$ will be same, because this is the same equation with what we solved earlier. So, $x_1 x_2$ are going to be the same value, what we calculated here we only have to solve this for getting the z^2 .

So, this is not t sorry this is z^2 , z^2 function of s . So, j^2 is equal to 2λ upon s minus x^1 into S minus X^2 now, this again I can put it into two parts a upon s minus x^1 plus b upon s minus x^2 . So, if I solve this this will be s minus x^1 into S minus X^2 a into S minus X^2 plus b into S minus X^1 .


So, this implies a plus b into S minus x^1 minus a into x^2 plus b into x^1 divided by s minus x^1 into S minus X^2 now, denominator is same and there is no s term so, we can make equations from here A plus B is equal to 0 and the constant term here is $a \times 2$ plus $b \times 1$ that is equal to 2λ . So, from here I can say a is equal to minus b if I put it here then this will become minus $b \times 2$ plus $b \times 1$ is equal to 2λ .

So, if I take B here common then x^1 minus x^2 is equal to 2λ so, b will be equal to 2λ upon x^1 minus x^2 and as we know what is my a a is minus b so, a will be equal to minus of this so, I can say 2λ minus sign I can take in denominator that will become x^2 minus x^1 so, here I have got a and b both so, my z^2 z^2 I can write it as a upon x minus x^1 that is 2λ upon x^2 minus x^1 into 1 upon s minus x^1 plus B , B is 2λ upon x^1 minus x^2 into 1 upon s minus x^2 this if I solve by Laplace inverse then left hand side will give me $P^2 T$.


And if I solve this first term will come as it is 2λ upon x^2 minus x^1 and this value will give me e to the power $x^1 T$ and second value is 2λ upon x^1 minus x^2 e to the power $x^2 t$. So, this is how $x^1 \times x^2$ is known to me already and λ is also known to me already. So, I can get the P^2 as the function of time.

So, as you see here we are able to calculate P^2 and P^1 I can calculate as 1 minus $P^2 T$ minus $P^3 t$, I do not have to calculate, again, using the same equations for the $P^1 t$, that I can directly calculate as 1 minus $P^2 t$ minus $P^3 t$.

(Refer Slide Time: 30:00)



Two Component System with Repair



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$$\frac{dP_1(t)}{dt} = -2\lambda P_1(t) + rP_2(t) \quad P_1(t) = \frac{\lambda + r + x_1}{x_1 - x_2} e^{x_1 t} - \frac{\lambda + r + x_2}{x_1 - x_2} e^{x_2 t}$$

$$\frac{dP_2(t)}{dt} = 2\lambda P_1(t) - (r + \lambda)P_2(t) \quad P_2(t) = \frac{2\lambda}{x_1 - x_2} e^{x_1 t} - \frac{2\lambda}{x_1 - x_2} e^{x_2 t}$$

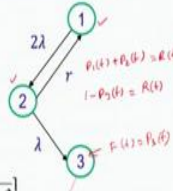
$$\frac{dP_3(t)}{dt} = \lambda P_2(t) \quad P_3(t) = 1 + \frac{x_2}{x_1 - x_2} e^{x_1 t} - \frac{x_1}{x_1 - x_2} e^{x_2 t}$$

$$P_1(t) + P_2(t) + P_3(t) = 1 \quad x_1, x_2 = \frac{1}{2} \left[-(3\lambda + r) \pm \sqrt{\lambda^2 + 6\lambda r + r^2} \right]$$

$$R(t) = 1 - P_3(t) = \frac{x_1}{x_1 - x_2} e^{x_1 t} - \frac{x_2}{x_1 - x_2} e^{x_2 t}$$

$$MTTF = \int_0^\infty \left(\frac{x_1}{x_1 - x_2} e^{x_1 t} - \frac{x_2}{x_1 - x_2} e^{x_2 t} \right) dt$$


$$= \frac{-1}{x_1 - x_2} \left[\frac{x_1}{x_2} - \frac{x_2}{x_1} \right] = \frac{-(x_1 + x_2)}{x_1 x_2} = \frac{3\lambda + r}{2\lambda^2}$$




21
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This same thing is coming here so, here by using these equations we are able to solve and we will be able to get the probability values and relative values also we are able to calculate MTTF also we are able to calculate and $x_1 \times x_2$ is also here.

(Refer Slide Time: 30:28)



Example



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INTRODUCTION TO RELIABILITY ENGINEERING

- A computer system consists of two active parallel processors each having a constant failure rate of 0.5 failure per day. Repair of a failed processor requires an average of one-half of a day (exponential distribution). Evaluate reliability for single day and system MTTF. Compare system reliability and MTTF with case without repair.


$$x_1 = \frac{1}{2} \left[-(3 \cdot 0.5 + 2) + \sqrt{0.5^2 + 6 \cdot 0.5 \cdot 2 + 2^2} \right] = -0.1492$$

$$x_2 = \frac{1}{2} \left[-(3 \cdot 0.5 + 2) - \sqrt{0.5^2 + 6 \cdot 0.5 \cdot 2 + 2^2} \right] = -3.3508$$

$$R(t) = \frac{-0.1492}{-0.1492 + 3.3508} e^{-3.3508t} - \frac{-3.3508}{-0.1492 + 3.3508} e^{-0.1492t}$$

$$= 0.8999$$

$$MTTF = \frac{-0.1492}{(-0.1492 + 3.3508) \cdot 3.3508} - \frac{-3.3508}{(-0.1492 + 3.3508) \cdot 0.1492}$$



25
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So, let us see one example here that a computer system consists of 2 active parallel processor each having a constant failure rate of 2.5 failures per day. So, that means, if I make this diagram then I had 3 states here.

$$\begin{aligned}
x_1 &= \frac{1}{2} \left[-(3 * 0.5 + 2) + \sqrt{0.5^2 + 6 * 0.5 * 2 + 2^2} \right] = -0.1492 \\
x_2 &= \frac{1}{2} \left[-(3 * 0.5 + 2) - \sqrt{0.5^2 + 6 * 0.5 * 2 + 2^2} \right] = -3.3508 \\
R(t) &= \frac{-0.1492}{-0.1492 + 3.3508} e^{-3.3508t} - \frac{-3.3508}{-0.1492 + 3.3508} e^{-0.1492t} \\
&= 0.8999 \\
MTTF &= \frac{-0.1492}{(-0.1492 + 3.3508)3.3508} - \frac{-3.3508}{(-0.1492 + 3.3508)0.1492}
\end{aligned}$$

Now, here 0.5 is for the 1, 1, 1 part 1 processor. So, for 2 processors this will become 1 point 0 failure per day 1 failure per day and for 1 processor it will be 0.5 failure per day and there is a repair repair failure process requires an average 1 half of a day that means, it will be 0.5 so repair rate is half of the day half per day half of the day sorry repair rate is means repair time is 1 upon r mean time to repair is 1 by 2 half day.

So, r will be equal to 1 by 1 by 1 by 2. So, that will become 2 per day in half day repair can complete so, in 1 day you can do 2 repairs. So, this will be 2, r will be equal to 2 and lambda is equal to 0.5. So, if I use the same thing in this equation, I can solve this. So, my x1 values half of minus 3 into lambda plus r so, 3 into lambda is 0.5 r is 2 and square root of so, x 1 I am taking as the positive quantity x 2 I am taking as the negative quantity and this is lambda square plus 6 lambda into r plus r squared. If I solve this this value comes out to be minus 0.1492 x 2 is also same value but sign is negative here.

So, this will be minus 3.3508 because, once we have got x1 and x 2 both then our rt as we calculated earlier our rt was coming out to be x 2 upon x 2 minus x 1 e to the power x 1 T and x1 upon x 1 minus x 2 e to the power x 2 T. So, same thing will happen E to the power x so, if I take x 1 minus x 2 then this term will come first and this will become minus. So, here the formula use this x 1 minus x 2 this is x1 this is minus x 2.

So, x, x 1 upon x 1 minus x 2 e to the power minus x 2 minus x 1 upon x 1 minus x 2 e to the power minus x 1 this formula we have used same formula what we developed earlier and using this we can get the reliability as 0.8999 and MTTF is again as we discussed earlier, MTTF is also

whatever value we get here that will be same here divided by 3.3508. And similarly, whatever value this we got here same as here divided by 0.1492 and this gives me the MTTF.

(Refer Slide Time: 34:01)

Example

- A computer system consists of two active parallel processors each having a constant failure rate of 0.5 failure per day. Repair of a failed processor requires an average of one-half of a day (exponential distribution). Evaluate reliability for single day and system MTTF. Compare system reliability and MTTF with case without repair.

$$x_1 = \frac{1}{2}[-(3 + 0.5 + 2) + \sqrt{0.5^2 + 6 + 0.5 \cdot 2 + 2^2}] = -0.1492$$

$$x_2 = \frac{1}{2}[-(3 + 0.5 + 2) - \sqrt{0.5^2 + 6 + 0.5 \cdot 2 + 2^2}] = -3.3508$$

$$R(t) = \frac{-0.1492}{-0.1492 + 3.3508} e^{-3.3508t} - \frac{-3.3508}{-0.1492 + 3.3508} e^{-0.1492t}$$

$$= 0.8999$$

$$MTTF = \frac{-0.1492}{(-0.1492 + 3.3508)3.3508} - \frac{-3.3508}{(-0.1492 + 3.3508)0.1492}$$

-0.01391	
7.014757	
7.000849 days	

So, using same we can if you want we can solve this in Excel how much value of MTTF is coming. So, I will equal to minus of 0.1492 divided by minus of 0.1492 plus of 3.3508 multiplied with 3.3508. So, this is my first term and second term is equal to minus minus will become plus.

So, that is 3.3508 divided by minus 0.1492 plus 3.3508 multiply with 0.1492. And MTTF will be this plus this. So, my MTTF is coming out to be around 7 days here all values were in per day. So, my MTTF comes out to be approximately 7 days. So, here as you have seen, we are able to calculate reliability and MTTF when repair is considered repair whenever we consider repair as we see that we have the loop because in our equation becomes a little bit complex to solve, but they are solvable.

So, maybe little and if the problem becomes more complex, then we may be able to use other methods like approximation numerical methods to solve the differential equations the same, so we will stop here today we will discuss with one more system in next class. Thank you.