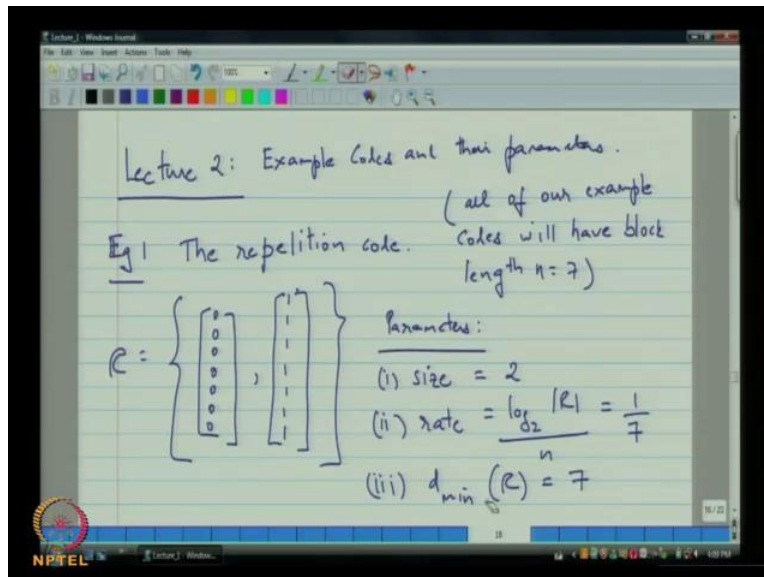


Error Correcting Codes
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Lecture No. # 03
Mathematical Preliminaries: Groups

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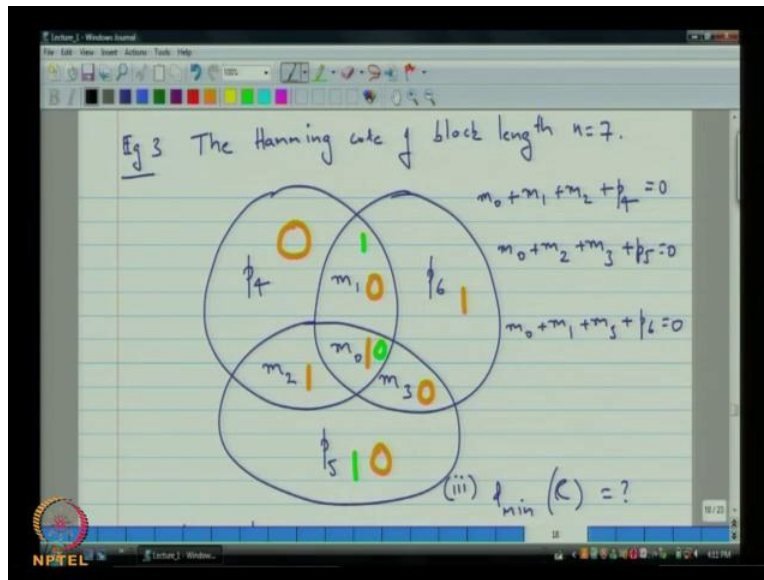


This is the third lecture in our series on Error Correcting Codes, and as before what I would like to do is, I begin with recap of what we did last time. In a nutshell, what we did last time was we look at some examples codes in that parameters, and then towards the end of the last lecture, we try to say well, supposing we have a code whose minimum distance is such and such, then what is how does that relate to the error correcting capability of the code. And we were in the middle of that proof, so we will pick up from that point onwards. First, what I will do is, I will just go over the materials relating to example codes in the parameters. We will go over that quickly, and then after that, I will come back and talk about and continue where we left of in the proof.

Here, if you go down to the part here, you see that example codes in there parameter, I first introduce the repetition code. In the repetition code, all the symbols are the same. The parameters and the codes are the following, the size is 2; the rate of the code is 1 by 7 and the minimum distance of the code is 7. The next code was the single parity check code, and here the condition on the code is that, the sum of the symbols may actually be zero, and as a result you find that the

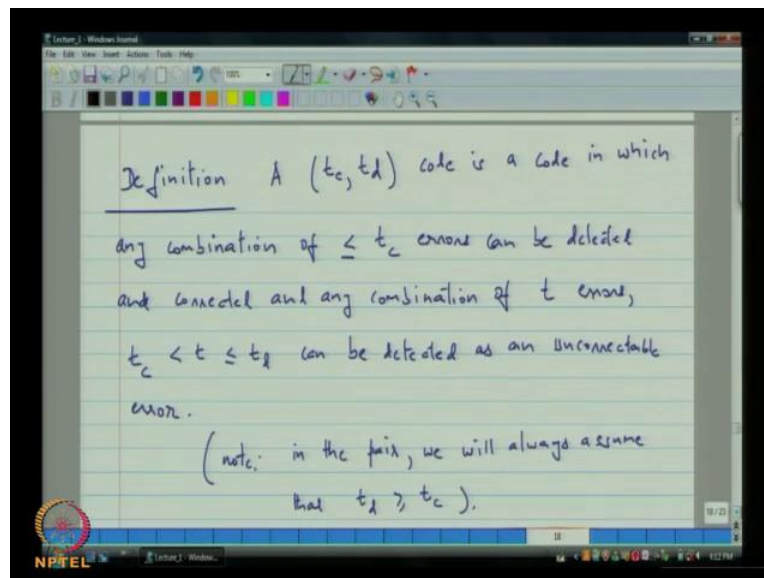
size of the code is 2 to the 6; the rate is 6 by 7, and the minimum distance is 2 and these are two example code words whose distance is 2.

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Then the hamming code; hamming code is defined a little bit differently explained it in terms of these three circles, and I said the way it is defined by introducing certain message symbol m_0 , m_1 , m_2 , and m_3 , and then filling in the corresponding parity, and that gives rise to this equation. And from these equations, it is possible to actually determine the parameters of the code, which in this case turns out to be, so the size of the code is 16, because there are four message symbols; the rate is 4 by 7, the minimum distance you can show 3 and left it to you was an exercise. Later on, we will actually see an alternative, and perhaps simpler way of actually proving that the minimum distance of this code is actually 3.

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Now, next I am moving on to talking about the relationship that exists between the minimum distance of a code and the error correction capability of the code. So that, we begin with definition which says that t_c, t_d code is a code, in which any combination of less than or equal to $t_{sub c}$ errors can be detected and corrected and any combination of two errors, where t lies between $t_{sub c}$ and $t_{sub d}$ can be detected as an uncorrectable error. And in this pair, you will always assume that $t_{sub d}$ is greater than or equal to $t_{sub c}$. So, whenever we define this, it is analytically been implied that while this can be the same as this; the second parameter $t_{sub d}$ can be the same as the first, in general it is larger.

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Theorem 1: A binary block code C of length n is a (t_c, t_d) code iff:

$$d_{\min}(C) \geq t_c + t_d + 1$$

Proof (if part) assume that $d_{\min} \geq t_c + t_d + 1$.

Adopt the following decoding algorithm:

And the theorem that we were in the mixed of rolling is that the binary block code C is a (t_c, t_d) code if and only if the minimum distance of the code is greater than or equal to $t_c + t_d + 1$. And now, iff here means if and only if, so which means we have to prove two things; one is we have to show that if this condition is satisfied, then the code is in fact capable of correcting t_c errors and detecting t_d errors.

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Adopt the following decoding algorithm:

Let \underline{r} be the received vector.

Let for any vector $\underline{a} \in \mathbb{F}_2^n$ define

$$B(\underline{a}, r) = \left\{ \underline{e} \in \mathbb{F}_2^n \mid d(\underline{a}, \underline{e}) \leq r \right\}$$

Diagram: A sphere of radius t_c centered at \underline{x} (a codeword). A received vector \underline{r} is shown inside the sphere. A vector \underline{e} is shown from \underline{x} to \underline{r} . The distance $d(\underline{x}, \underline{r}) \leq t_c$ is indicated. A vector \underline{y} is shown outside the sphere, with $d(\underline{x}, \underline{y}) > t_c$ indicated.

We went through the proof of if part I will go through that once more again, and then pick up for the only if part. So, let us assume that in fact you have given that the minimum distance of the code satisfies the condition like $d \geq t_c + t_d + 1$. And now we are going to show that the code can correct the t_c errors and detect t_d by exhibiting a particular decoding algorithm.

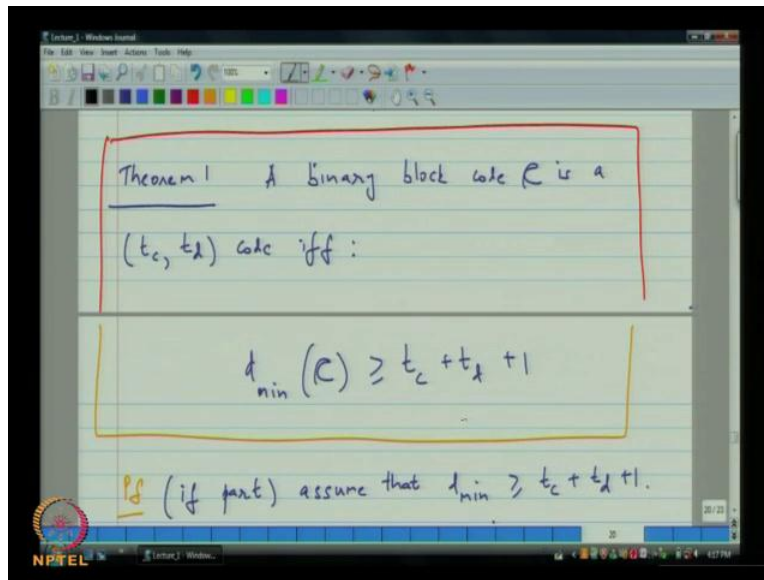
The decoding algorithm runs as follows, so by the way one definition that we use here is that of a ball given any vector a and given a real number r , which you think of as a radius. The ball surrounding the vector, the set of all n tuples where the Hamming distance between a and z is less than or equal to r that is what we defined as a ball and what we done. And what we shown in this figure here, is that here is your receive vector y and decoding algorithm proceeds as follows. We will first of all examine the ball at centered at y whose radius is t_c , and that is the green circle that you see on your screen. Now, given that ball, what we are going to do is we are going to look to see, if there is a codeword that is contained within the ball.

Now, it could be that there is a codeword; it could be that there is more than one codeword or it could be that there is no codeword. At the outside these are the possibilities we narrow down the possibilities as we go along. So, we will first examine the ball or the neighborhood of the vector y whose radius is t_c ; if there is a single codeword in the ball, then we actually declare that x was the transmitted codeword and decode x in the decoding algorithm ends there. On the other hand, if we look at this ball and we find that there is no vector are contained in this ball, then we will say that an uncorrectable error has taken place.

This is very simple. There are two cases and we take different actions depending upon which of the two is actually true, now to show the actually work. Let us examine, what could possibly go wrong? Now, there is another possibility that is maybe; that is running through your mind. What if this ball contains more than one codeword but as will see in the proof that is not going to be possible. I will not discuss that at from this is a special case. Here, now supposing you look at the ball at y of radius t_c , and you happen to find that there is a vector x , and then what you do is you declare that x was a transmitted codeword, what could go wrong? The only thing that can go wrong is, if x was not the transmitted codeword, which means there was some other

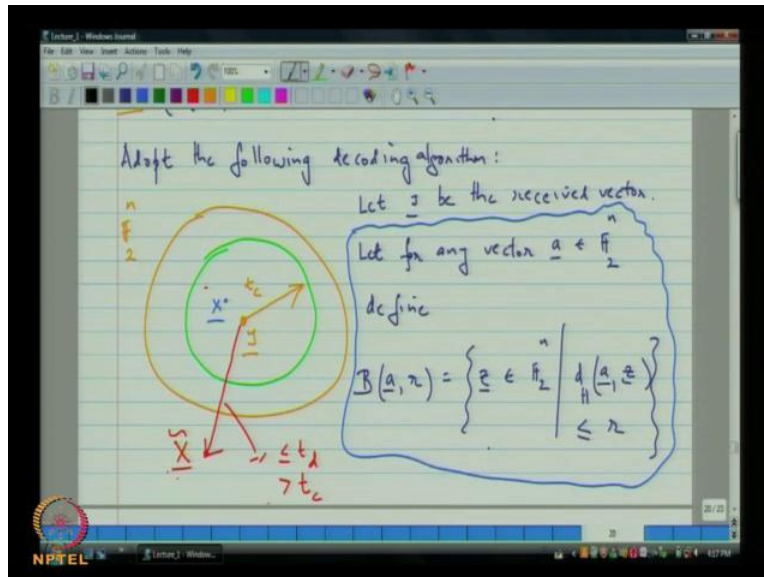
vector, which was the transmitted codeword. Let us, put \tilde{x} with a vigil on top. It pronounced \tilde{x} was actually the transmitted codeword.

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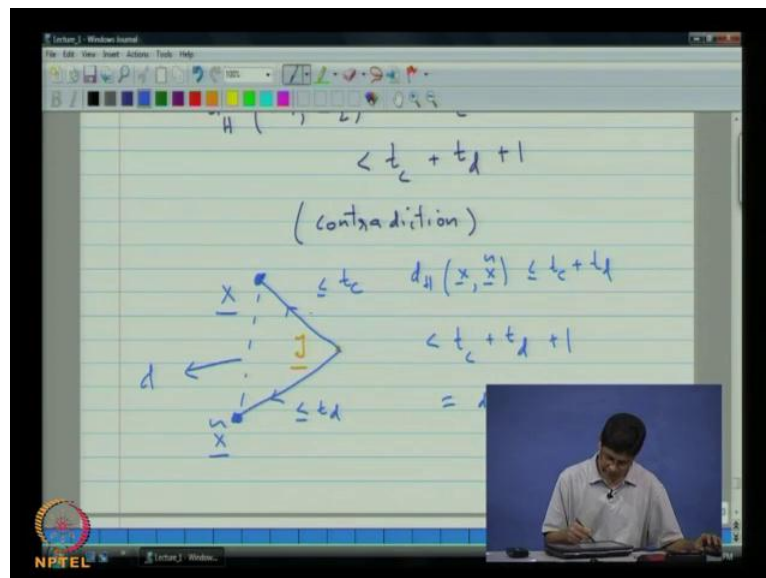
But one thing to keep in mind is that the promises with respect to this code are only and so far as correcting t_c errors and detecting t_d errors. If in fact, it turns out that the number of errors is greater than t_d , then we do not guarantee anything; we do not promise anything; we are not required to deliver anything. So for that reason, it is perfectly fine for the code to break down if the number of errors is more than t_d , so we will keep that in mind.

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Here for that reason, we can restrict our attention to the case, when in fact, the number of errors is less than or equal to $t_{\text{sub } d}$. Let say that here is your transmitted, actual transmitted codeword \tilde{x} , and if it turns out that was not equal to x then you made an error. Now my goal is to show, but this cannot happen, because and the simple reason for that is if you take a look the distance between x and y ; the distance between y and x is less than or equal to $t_{\text{sub } c}$, simply because it belongs to the ball. On the other hand, the Hamming distance between y and \tilde{x} is less than or equal to $t_{\text{sub } d}$. The reason being that your only confining your attention to these situations.

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All right now, if you put the two together then what you actually have is that here, at so after some discussion in which basically, I expand and what I have just said, you have the situation over here, where this thing here is your vector y received. We have x whose Hamming distance is less than or equal to t sub c , and have x tilde whose Hamming distance is less than or equal to t sub d . But that would imply that there are two codeword in the code, whose Hamming distance is less than or equal to t sub c plus t sub d sub d , but that would imply that there are two code words in the code whose Hamming distance is less than or equal to t sub c plus t sub d , because this distance plus this distance is greater than or equal to the distance along a straight line path.

Let me just do one thing here, so the point is that the distance from here to here is less than or equal to the sum of these two distances, which much mean as, if you look at the argument on the right? Here, right naught in blue the Hamming distance between x and x tilde is less than or equal to t sub c plus t sub d plus 1 strictly less, which is the minimum distance of the code. So that is a contradiction, because after all, no two code words in the code can be separated by less than the minimum distance. That proves that this situation is pictured that we showed our front is in fact not possible, it cannot be that the geometric picture looks like this.

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Adopt the following decoding algorithm:

Let y be the received vector.

Let for any vector $a \in \mathbb{F}_2^n$ define

$$B(a, r) = \{ z \in \mathbb{F}_2^n \mid d_H(a, z) \leq r \}$$

if $B(y, t_c)$ contains a codeword

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suppose there is no codeword to be found in $B(y, t_c)$.

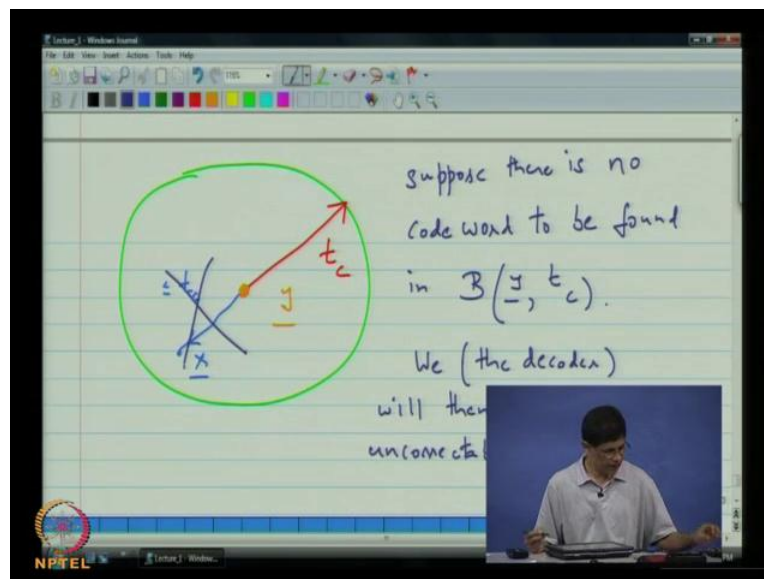
We (the decoder) will then declare an uncorrectable error.

This picture is not a true picture in other words. Now, that leads as to the other situation which is, what if, what if and let me repeat my argument; what if I have my received vector y . And I draw a ball, whose radius is let say t_c and this time and in the middle of decoding algorithm and I find that there is no codeword in this ball another question is what can go wrong? Now, let me put that down. Suppose, there is no codeword to be found in the ball centered at y , whose radius

is $t \leq c$, and then the question is what can go wrong? The only thing that can go wrong is because now what you are going to do is; you are going to actually declare an uncorrectable error. We now, we remind the decoder will then declare an uncorrectable error.

The only thing that can possibly go wrong is, if in fact there was a correctable error; the only way we can wrong is, if there was a correctable error, but what does that mean? That means the only way we could have gone wrong is if there was a vector whose distance the only way in which you could have gone wrong is if there was a codeword c which was correctable there was a codeword, whose which was correctable; there was a codeword and there was a number of errors which was correctable which would imply that there was a codeword whose Hamming distance was less than or equal to $t \leq c$. But there was clearly not possible right, because we started off we look to the ball we found that there was no codeword in there, so there is no question of there been the other possibilities.

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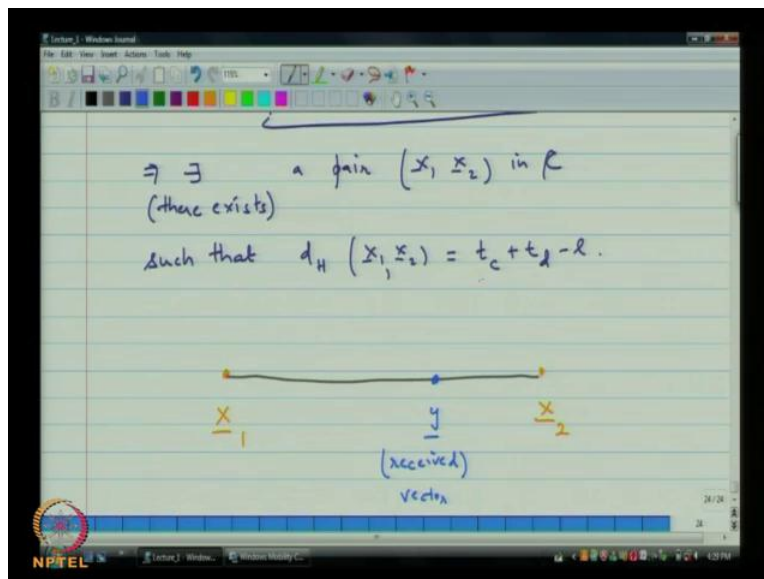


I am just going to draw this but I am going to rule this out just to emphasize this situation is not possible and clearly, we cannot go wrong. The conclusion is that we cannot in this case go wrong. Clearly, the decoder will be correct, since the only way it could possibly go wrong is if there was a correctable error, that is a codeword within Hamming distance $t \leq c$ that of y , but this is impossible by our initial assumption that the ball was empty; that concludes the proof of a if part.

And is possible that the first time you go through this, you are still a little bit puzzled, but you just have to write this throughout on your own.

Now, I am going to proceed to the only if part, so the proof of the only if part, so here, we actually show that the inequality that we are treated down earlier was in fact necessary. We have to show that $d_{\min} \geq t_c + t_d + 1$ is in fact, necessary. Suppose not, which implies that $d_{\min} < t_c + t_d + 1$. Let us say, d_{\min} is equal to $t_c + t_d - 1$ say, l could be 0 or larger than 0. Let us, assume that this was the case; and now, but the fact that the minimum distance of the code is given by an expression like this implies the existing of a pair of code word separated by such a Hamming distance implies, there exist.

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This symbol means there exist, a pair of code words x_1, x_2 in the code C , such that the Hamming distance between x_1 and x_2 is equal to $t_c + t_d - 1$. And now, you let us look at the following picture; you have on the one hand, one side, you have x_1 , and then here, you have x_2 . And I am going to draw a line between these two; and let say that now let say I am going to put down a vector in the middle here, somewhere in the middle, and I am going to call that y . And by y , I am using the symbol y as before to denote the received vector. Now, there is there is

something to prove here, I mean you first of all, what do I mean by vector lying on this line; what I really mean is that the distance from end to end on this line is $t_{\text{sub } c} + t_{\text{sub } d} - 1$.

Let us, choose a vector in such a way that the distance from here to here from x_1 to y is in fact $t_{\text{sub } d}$. This distance let us say is $t_{\text{sub } d}$, and at the remaining distance is let us say $t_{\text{sub } c} - 1$. Now there is something to prove here, because you have to show that given two vectors x_1 and x_2 , whose Hamming distance separation is $t_{\text{sub } c} + t_{\text{sub } d} - 1$ that in fact, you can actually find a vector which is kind of in between them was such that the sum of the distance is from x_1 to y , and from y to x_2 adds up to $t_{\text{sub } c} + t_{\text{sub } d} - 1$. But that well easy to see, because the meaning of Hamming distance or an alternative interpretation of the Hamming distance is simply the number of symbols that you need to change to go from x_1 to x_2 .

You need to change, $t_{\text{sub } c} + t_{\text{sub } d} - 1$ symbols to go from x_1 to x_2 ; so supposing I change $t_{\text{sub } d}$ of them and stop in the middle, then I will be at the vector y , and I meet $t_{\text{sub } c} - 1$ more changes to get to x_2 . This diagram, in other words, this figure makes sense, and it is perfectly possible that x_1 that you have a code in where x_1 and x_2 are the code words, and where y is the received vector.

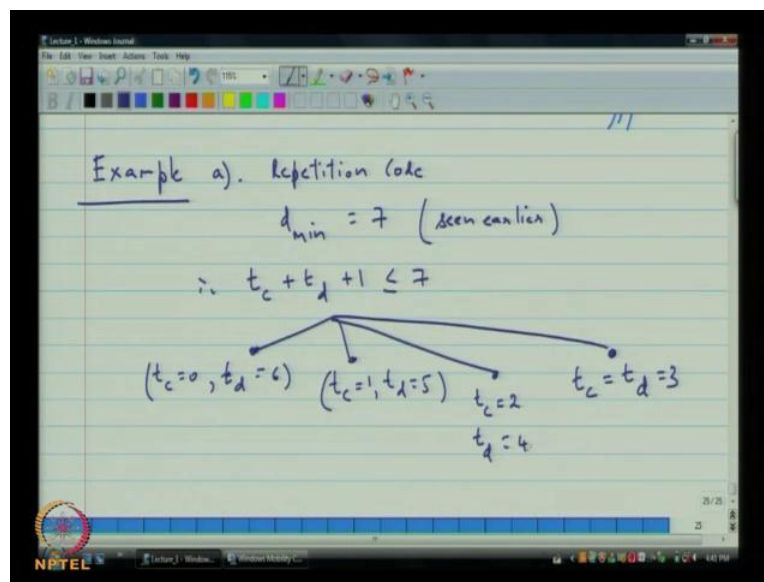
And the problem here is that this situation presents the decoder with dilemma that cannot be resolved, because of what can the receiver do, if it receives y ? It is like the same which says that I am donned, if I do and donned if I do not. The matter what the receiver does in this situation, it is going to potentially been error, the received the decoder being deterministic given y it has to say something, it has to either declare but there is an error and corrected or it has to declare an uncorrectable error. Now, because the distance from x_2 to y is $t_{\text{sub } c} - 1$, which is less than or equal to $t_{\text{sub } c}$, it is possible that y was the result of x_2 been transmitted. So, with that in mind the decoder to take care of that case should given that y was the received vector should have decode to x_2 .

But similarly, it perfectly possible that x_1 was the transmitted vector, and they were $t_{\text{sub } d}$ errors; so both possibilities exist and they call for two different actions in the receiver, in order for the receiver we correct. It is impossible that the matter how you design the decoder? You are going to be an error in one of the two cases; you cannot be wrote write in both cases, and that is

why you cannot correct t_c and detect t_d errors. If the minimum distance was insufficient, so that concludes the proof.

I will just make a brief note along the lines of what I have just said, so will say that the situation about presents the receiver with a dilemma that cannot be resolved. For the case, when y is the received, so thus when d_{\min} is less than $t_c + t_d + 1$, a code cannot be a t_c t_d code and that concludes this proof. And that was a lengthy proof and perhaps you got lost in a couple of in an argument along the way, but just keep at this the result in mind. Namely, that in order for it to be able to be a t_c it means this inequality to be satisfied.

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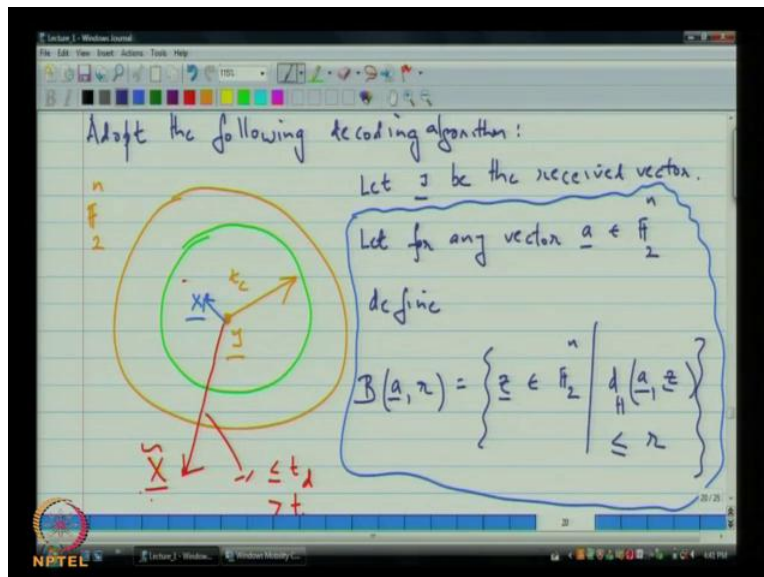


And now, let us go to our example codes. The first code been the repetition code here, the minimum distance of the code was seven so, we say this earlier, and therefore we have the inequality $t_c + t_d + 1 \leq 7$ ok that must be less than or equal to seven. So, that code is t_c t_d code for all pair which satisfies the in equality now the interesting thing is that this inequality is all that is required. You can use the same code at to provide different measures of error correcting capability. So, from this, you can actually use the code on the one hand as a code in which t_c is equal to 0 and t_d is equal to 6. You could use it as a code for which t_c is equal to 1 t_d is equal to 5. And then at the other end of the spectrum, you can also use it as a code for which t_c is equal to t_d is equal to 3. You can use this code in these

different ways; I guess the only one that is really missing in this list. Let me put that down as well is the case, when t_c is equal to 2 and t_d is equal to 4, you can use this code in four different ways.

The one thing that might puzzle you is how is it possible to use the same code to provide different measures of error correcting capability. And the answer is because remember that you are decoding algorithm was centered around, it involved using the value of t_c , because remember we had that you would look in a ball.

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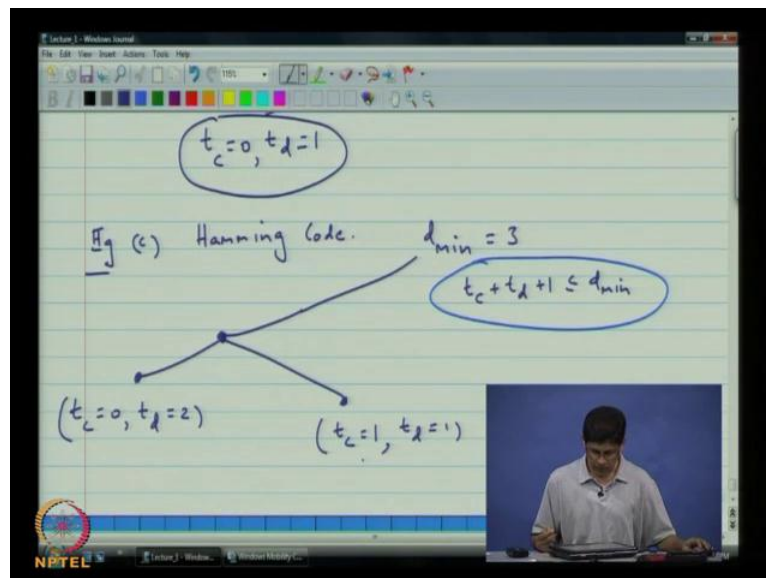
I can find that for you, so in our decoding algorithm what we actually did was we took the received vector drove ball of radius t_c around it and look for a codeword right. Now, t_c was larger or smaller this ball will get bigger or smaller, the decoding algorithm changes with the parameter choose said that you actually choose, and this is what allows the code to provide different measures of error correcting capability. This is for the case of the repetition code.

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The screenshot shows a digital whiteboard interface. At the top, there is a menu bar with options like 'File', 'Edit', 'View', 'Insert', 'Actions', 'Tools', and 'Help'. Below the menu is a toolbar with various drawing tools. The main area of the whiteboard contains handwritten text in blue ink. The text reads: 'Eg b). the single parity-check code.' followed by ' $d_{\min} = 2$ '. To the right of this, the equation ' $t_c + t_d + 1 \leq d_{\min}$ ' is written and circled in blue. A line points from this circled equation to another circled equation below it, which reads ' $t_c = 0, t_d = 1$ '. In the bottom right corner of the whiteboard, there is a small video inset showing a man in a light blue shirt sitting at a desk. The NPTEL logo is visible in the bottom left corner of the whiteboard.

Now, let us look at some of the other codes example b. The single parity check code, here, for this code d_{\min} if you will recall was two so since the minimum distance is small that does not leave a whole lot of room for selecting a parameters. According to so let us put down the equation again that $t_c + t_d + 1$ must be that is d_{\min} . So, it does not leave very much to play. In fact, the only thing that you can really do in this case is choose t_c equal to zero t_d equal to one. So, the code can only be used for detecting single errors, it cannot be used for error correction.

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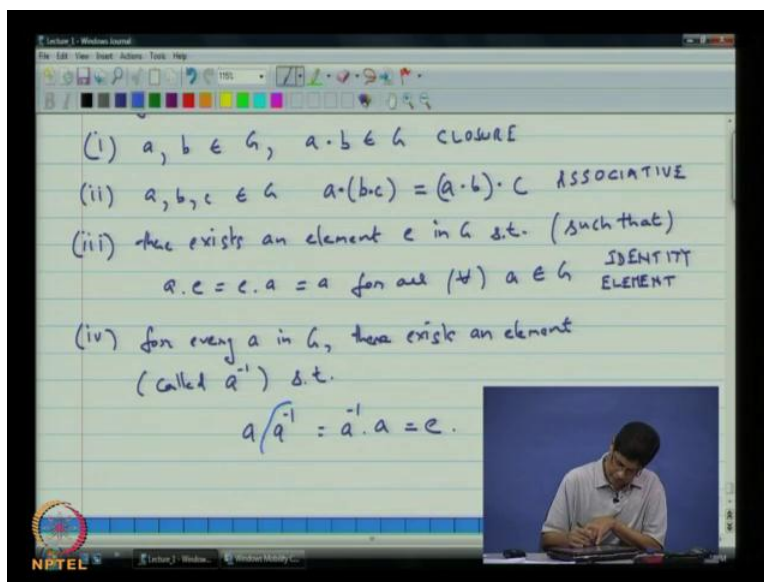


Moving on to our third code example c , which is the Hamming code. So, in the hamming code, the minimum distance of this code was equal to 3. From this, it is clear that the code can be used again with respect to our equation which says that this code can be used in one of two ways actually; in one way you could use it as a $t_{\text{sub } c} = 0$ $t_{\text{sub } d} = 2$. You can detect whereas, but not correct any errors. The other alternative is to correct a single error, and this corresponds to the case when both $t_{\text{sub } c}$ and $t_{\text{sub } d}$ are both equal to 1. You will see in three examples of how of the codes minimum distance and the associated error correction capabilities.

Now, I would like to just say few words about where we are going to go next. We talked about binary codes in general, and now what I would like to do is focus on this sub class of binary codes, which are the so called linear codes. Now linear codes essentially make use of linear algebra but there is also a little bit of group theory, and since I assume that some of you may not have a background in these two areas. What I will do over the course of the next two lectures or so is to actually try to fill in that background. So, we will make a slight detour, we leave coding theory aside for the movement, and we will talk first about groups and sub groups and later on, will talk about rings fields and vector spaces that is going require some passions on your part, to sit through a couple of lectures where we talk about a elementary a very elementary abstract algebra and then you come back to coding theory. Of course, the benefit of these lectures is you

have the background you can just skip quite ahead and catch up couple of lectures later. I am going to go on to discuss some background on groups.

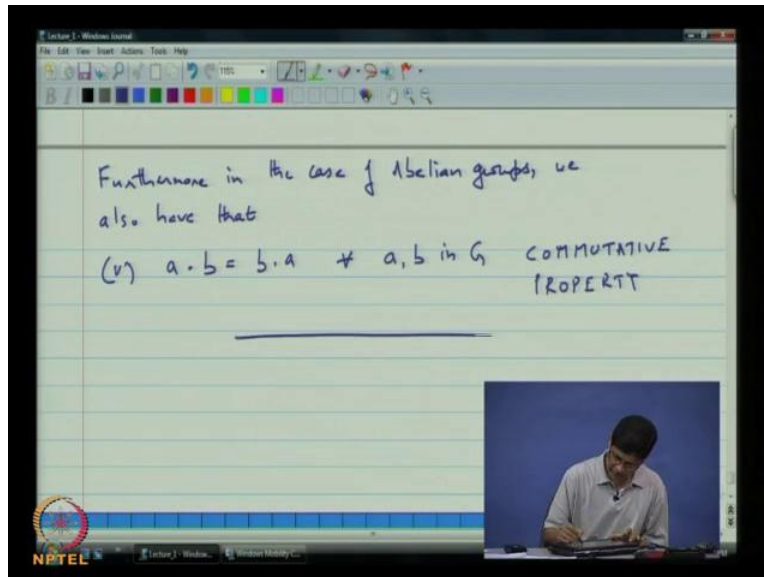
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I will entitle these mathematical preliminaries. So, we will talk firstly about groups, definition: a group G comma dot is a set G along with an operation, which is dot, under which following conditions are satisfied. First of all, if a, b belong to the group, then a dot b must belong to the group, this is called the operation of closure. If you have three elements a, b, c , then and if you are interested in multiplying the three together, in the way in which group them prior to multiplying does not make a difference. Then a times $b \cdot c$, b dot c , so a dot b dot c is equal to a dot b dot c . So you can multiply b and c together first, and then bring an a , why you can multiply a and b and then bring an c and it does not matter. So, this is called the associative property.

The third property is there exist an element e in G , such that so when I write $a \cdot e$ dot you should read that as, such that a times e is equal to e times a is equal to a for all, and I will often write is this symbol to denote all. For all a in G , then four so this axiom is called the axiom of the identity element. The fourth axiom says that, for every a in G there exist an element, which is called a inverse such that, a times a inverse is equal to a inverse times a is equal to e and so, this is pronounced a inverse and this is called the axiom of the inverse. Now, this is four axioms collectively make up a group.

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Often, the groups that we will deal with will be abelian groups, further more in the case of Abelian groups, they also have that $a \cdot b$ is equal to $b \cdot a$ for all a, b in G and this is called the commutative property, other commutative axiom. And Abelian groups, so that those are the five axioms that you define a groups and this make up quick remark that note Abelian groups are also called commutative groups and it is not surprise. So, once again just quickly go through the axioms. There are five is them you need closure that is if... Now you can think of this operation is either multiplication or radiation right now, it is just a binary operation; in our example it will often correspond radiation.

What the first one is saying is that if one operates on two elements you get a third element in the group and this is saying in order which you multiply does not make a difference. There is an identity element, which preserves elements upon multiplication, every element has an inverse, and then case of Abelian groups and often will be with abelian groups, you also have the additional axiom that the elements commute under this operation, which means that the odd in which you write them does not make a difference.

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The whiteboard contains the following handwritten text:

Note: Abelian groups are also called commutative groups.

Eg. $(\mathbb{F}_2^n, +)$ \rightarrow modulo 2 addition (componentwise)

$n=3$ $G = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$

$\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$

In the bottom right corner, there is a small video inset showing a man in a white shirt sitting at a desk, writing on a piece of paper.

So put a some examples, the first example is a consider the set of all n tuples, where the operation is plus, and by plus what we will mean here is modular two addition component wise. For if let say that n is equal to 3, in which case your group your group three, the group G will be comprised of eight vectors. So, your group our G will be comprised of these eight elements and the way in which you actually add is component wise modular tree. So, 0 1 1 plus 1 0 1 would be 0 plus 1, which is 1 1 plus 0, which is 1 1 plus 1 which is 0, because you are doing modular two arithmetic, and you can check that, the axioms has satisfied.

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$$\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

can verify that the axioms are satisfied:
 $\underline{0} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ is the identity element.

For example, so can verify that in particular zero, which is the vector whose components are all zero plays the role of the identity element. So, this is the identity element.

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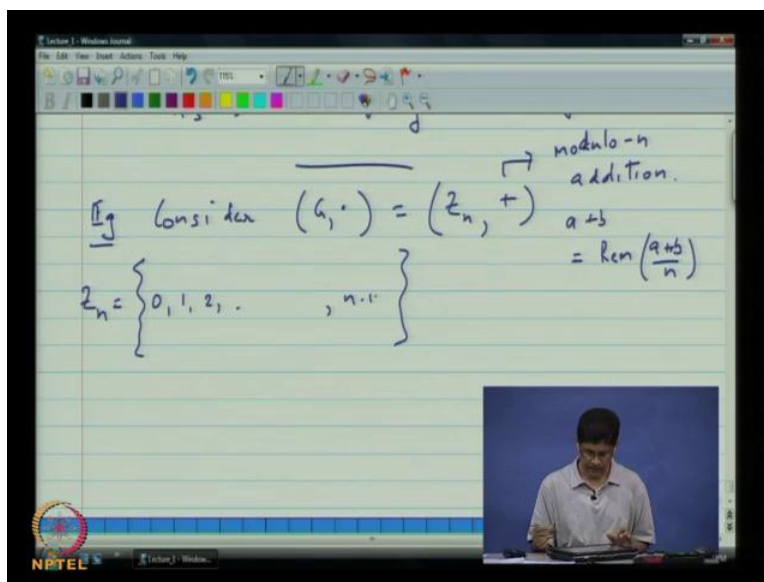
$\underline{0} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ is the identity element.

$a = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ $a^{-1} = ?$ $a^{-1} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = a$!!

And, if you want, if you thinking in terms of the inverse, let say, a is the element 1 0 1 and you might be wondering what is a inverse? Remember that a inverse is some element that has to be added back to a to give you 0. So in this case, since you are doing modular two arithmetic a

inverse is in fact a itself. So, it is equal to a , so that c is for this particular case, and of course addition is commutative here, so this is an example of an Abelian group.

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Let us look at another example, consider G to be \mathbb{Z}_n and $+$ plus. While, this time plus denotes modulo n addition. So, what does modulo n addition mean? It means that $a + b$ is really the remainder after you divide $a + b$ by n . And \mathbb{Z}_n is the set of integers modulo n and strictly speaking, it is a collection of equivalence classes, but we will choose representatives. So, we will pretend that this is just, this particular set, the set of integers ranging from 0 to n minus 1. So, there are n elements in the set.

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The screenshot shows a digital whiteboard interface with a menu bar (File, Edit, View, Insert, Actions, Tools, Help) and a toolbar. The handwritten text on the whiteboard is as follows:

Consider $(G, +) = (Z_n, +)$ addition.
 $a + b = \text{Rem}\left(\frac{a+b}{n}\right)$

$Z_n = \{0, 1, 2, \dots, n-1\}$

identity = 0

$a^{-1} = (n-a)$

Abelian group.

In the bottom right corner, there is a small inset video of a man in a light blue shirt sitting at a desk.

And, once again you can check that the axioms are satisfied. For example, the identity element the identity is zero, if you take two inverse for example, then or more generally, if you take n inverse; if you look at and ask the question, what is a inverse? a inverse is nothing but n minus a , and it is an Abelian group. If you are uncomfortable, with these sets and operations; you might want to go through the axioms and see for yourself, and convince yourself that the axioms actually hold for this particular case. Now, there are some consequences of the axioms that is groups have certain property that follow from your axioms and therefore, which do not need to be stated separately along with the axioms. We will call these derived properties.

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The screenshot shows a digital whiteboard interface with a menu bar (File, Edit, View, Insert, Actions, Tools, Help) and a toolbar. The title "Lecture 1 - Windows Journal" is visible. The main content on the whiteboard is handwritten in blue ink:

Derived Properties

(i) the identity element is unique

— suppose not and suppose that e_1 and e_2 were both identity elements

$\Rightarrow e_1 + e_2 = e_1$

" $\Rightarrow e_2 = e_1$

Below the whiteboard, there is a small inset video of a male lecturer with glasses, wearing a light blue shirt, sitting at a desk. The NPTEL logo is in the bottom left corner of the whiteboard area.

The derived properties are these first of all, the identity element is unique, because suppose not and suppose that e_1 and e_2 were both identity elements. This would imply that $e_1 + e_2$ is equal to e_1 , because after all e_2 is the identity, but on the other hand since, e_1 is the identity that is also equal to e_2 . So, this implies that e_1 equals e_2 and therefore, that shows that the identity element is unique.

(Refer Slide Time: 49:05)

The screenshot shows the same digital whiteboard interface as the previous slide. The handwritten text continues the derivation:

e_1 and e_2 were

$\Rightarrow e_1 + e_2 = e_1$

" $\Rightarrow e_2 = e_1$

(ii) every element has a unique inverse.

Suppose both c and b are inverses of $a \Rightarrow c a b = c (a b) = c e = c$

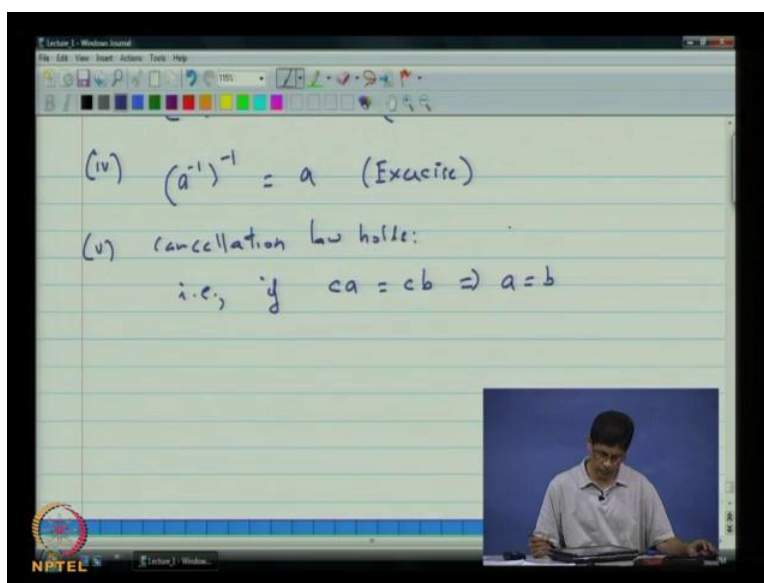
" $(c a) b$

" $(c) b = b < \therefore b = c$

The NPTEL logo is visible in the bottom left corner.

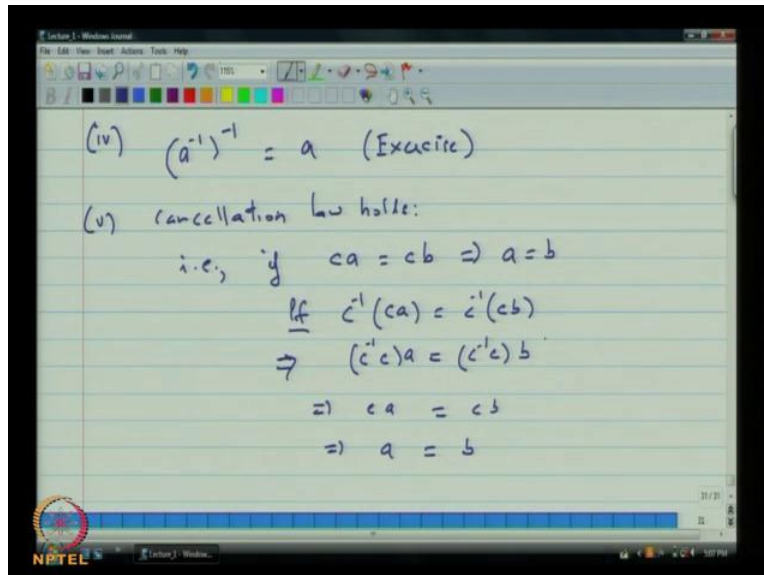
The second property shows that, even the inverse is a unique. Every element has a unique inverse, how do we see that? So let say, again suppose not. Suppose, both c and b inverses of a , but this implies if you consider c times a times b . On the one hand, you can say that this is c times a times b that because b is the inverse of a that c times the identity, which is c . On the other hand, we can wrote this and say that this is c times a times b , and because our c is the identity this is a times b ah sorry this is e times b this is e times b , which is b . So, that proves that therefore, by comparing n results. We see that, b is actually equal to c .

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Then another property, which you can I leave it to you as an exercise is 3 a b inverse is equal to b inverse a inverse so, very quick exercise. This is like matrices; it is like this is also case of matrices, but also hold here. Then four, if you take the inverse of the inverse, then you will actually get the element back also an exercise.

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Then, the cancellation law holds what is that mean? This means, that is, if c times a is equal to c times b that implies a is equal to b . You can sort of cancel c and both sides and the proof is because c inverse times c a these two elements are equal of course, they will remain equal even if you multiply on the lefts by c inverse, but this implies that c inverse c times a , implies, is equal to c inverse c inverse c times b implies that e times a is equal to e times b implies that a is equal to b . So, the cancellation law also holds.

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The whiteboard displays the following content:

$$\Rightarrow (c^T c) a = (c^T c) b$$

$$\Rightarrow c a = c b$$

$$\Rightarrow a = b$$

Below this, it shows:

$$(vi) \quad a^m = \underbrace{a \cdot a \cdot a \cdots a}_{m \text{ times}}$$

The NPTEL logo is visible in the bottom left corner. A small video inset in the bottom right shows a man in a white shirt sitting at a desk.

If you take and we are going to define, when we write a to the m this you mean a times a times a times a m times. Thus one more property in relation to this, but I see that we are running out of time. What I will do is rather than go through that, I continue that next time, I will just summarize what we have actually covered in this lecture. Let me see, if I can zoom out so, that we can see more of the lecture on the slide.

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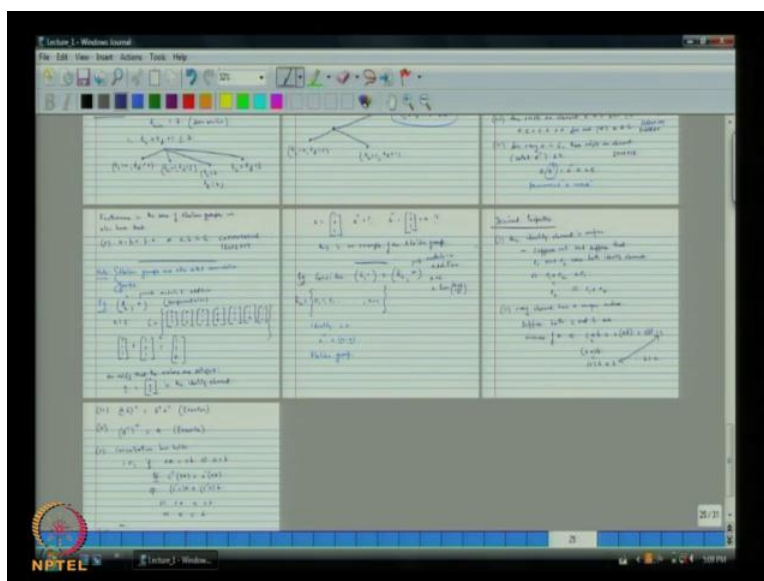
The whiteboard is divided into several sections with handwritten notes and diagrams:

- Top Left:** Text about vector spaces and linear combinations.
- Top Middle:** A diagram showing a vector a and its scalar multiples $2a$ and $3a$ along a line.
- Top Right:** A diagram showing a vector a and its scalar multiples $2a$ and $3a$ in a 2D plane.
- Middle Left:** A diagram showing a vector a and its scalar multiples $2a$ and $3a$ in a 2D plane.
- Middle Middle:** A diagram showing a vector a and its scalar multiples $2a$ and $3a$ in a 2D plane.
- Middle Right:** A diagram showing a vector a and its scalar multiples $2a$ and $3a$ in a 2D plane.
- Bottom Left:** Text about vector spaces and linear combinations.
- Bottom Middle:** A diagram showing a vector a and its scalar multiples $2a$ and $3a$ in a 2D plane.
- Bottom Right:** A diagram showing a vector a and its scalar multiples $2a$ and $3a$ in a 2D plane.

The NPTEL logo is visible in the bottom left corner. A small video inset in the bottom right shows a man in a white shirt sitting at a desk.

We first completed the proof that a code is a t sub c t sub d code if and only if, the inequality t sub c plus t sub d plus 1 is less than or equal to the minimum distance of the code we completed that proof. Then, we went on to talking about mathematical preliminaries to define the axioms that going to making up a group.

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Some examples and then we stated some derived properties. With that, I would like to close and will see in the next time whereas, I mention before for the next two classes will be working on mathematical preliminaries.