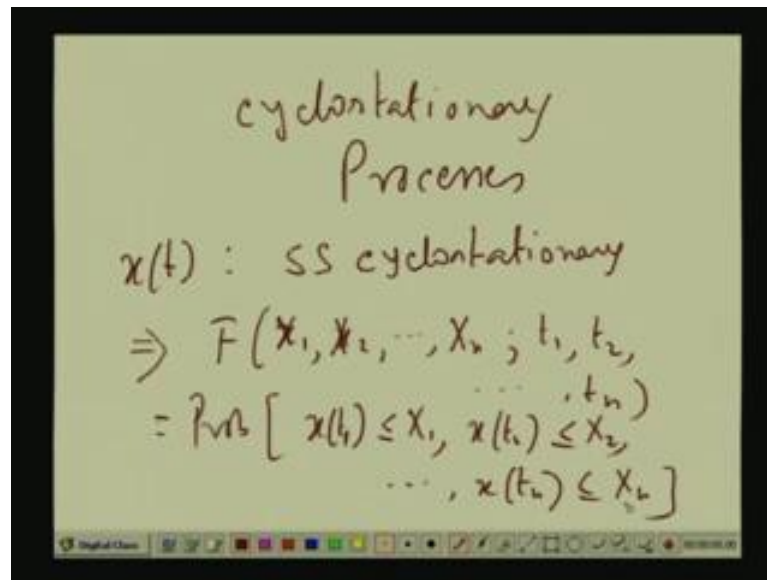


Probability and Random Variables
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Lecture - 31
Cyclostationary Processes

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So, we start today important topic that is Cyclostationary Processes. It is a special kind of random process, which is not fully stationary, but it does exhibit some sort of stationary and occurs frequently in many applications especially, in digital communications also called periodically stationary processes. Actually, these processes are such that their statistics they vary periodically over a constant type period. That is if I talk of a Cyclostationary Process which is strict sense Cyclostationary. That is if x_t is SS; SS stands for strict sense Cyclostationary.

So, this would imply that if you take the probability distribution of F that is let me, make it capital. By the way, what does this mean though we have already done it, but still there is nothing wrong in just restating what you already know. This is the probability joint, probability distribution function of the of the random process x_t . That is it is a joint probability of, that is by definition what is this probability of...

So, what x at t_1 lying less than equal to x_1 x at t_2 lying less than equal to x_2 dot dot dot x at t_n lying less than equal to x_n . These are joint probability, this is called the probability distribution. And this number n this the number of sampling points you have chosen that is purely up to you, You can take it from 0 to up to infinity. Now, if the

processes is stationary, we know if the processes stationary Strict Sense stationary not Cyclostationary.

But Strict Sense stationary that time you have seen that these joint distribution for any n that you choose that does not depend on this exact values of t_1, t_2 to t_n . Rather, if all of them are given a constant shift or constant delay. Then that is if t_1 is replaced by say t_1 plus c t_2 is replaced by t_2 plus c the same c dot dot dot t_n is replaced by the t_n plus c . In other words, if the time origin is shifted by the amount c .

Then, still you get the same distribution function. That it is the statistic does not depend on the exact location of time. There is the relative positions of t_1, t_2 to t_n that is what is important. Then, that is Strict Sense stationary In this case if it is Cyclostationary then this would imply that this is equal to this should imply that this is equal to...

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$$= F(x_1, x_2, \dots, x_n; t_1 + mT, t_2 + mT, \dots, t_n + mT)$$

$x(t)$: SS cyclostationary

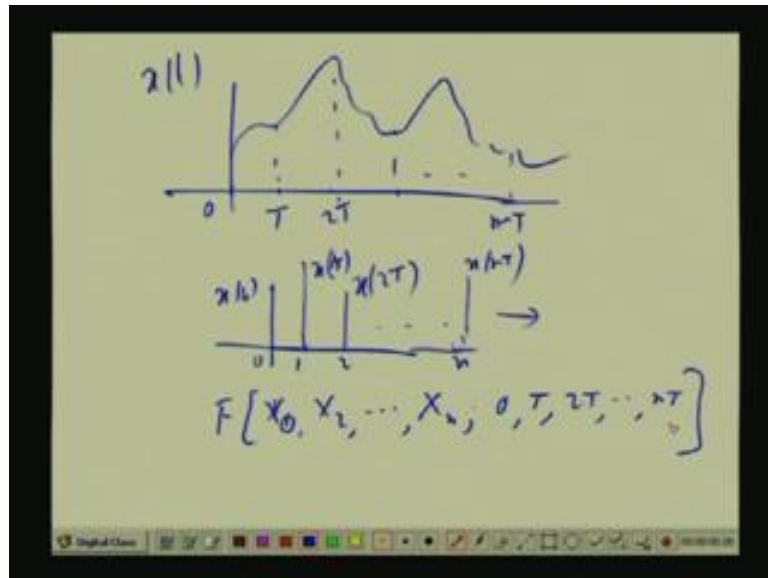
$$\Rightarrow F(x_1, x_2, \dots, x_n; t_1, t_2, \dots, t_n) = \text{Prob} [x(t_1) \leq X_1, x(t_2) \leq X_2, \dots, x(t_n) \leq X_n]$$

If instead of t_1 I get a constant shift which is the integral multiple of a basic time period T . So, t_1 plus either t or $2t$ or $3t$ like that say mT ; M is an integer. Then, again t_2 plus mT m is an integer dot dot dot just a minute. Then, dot dot dot t_n plus mT if they are same. So, that is that joint density joint probability distribution function and also therefore, density whatever it is value may at this time points t_1, t_2 up to t_n ; you will get the same thing.

If you move over either move forward or backward by T for each of the indices or move $2t$ or $3t$ or minus t , minus $2t$, minus $3t$ like that. But in other words, if the time origin is given a shift either to the right or to the left by integral multiple of T , then and only then it will repeat.

So, it is not fully stationary it is not that you know these 2 distributions are same for any shift that you get, but the shift is only m into T is not c . I mean is not true for any c , but the constant c that is the shift of the time origin that is only some integral multiple of a basic period T . Then this is called a Strict Sense Cyclostationary Process or also periodically stationary process. Obviously, this means that suppose you take.

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Suppose this your x_t what you have at you take at 0 t equal to 0 then at T at $2T$ dot dot dot you take these sample at mT . Now, if you just take them what does that mean that, if you take they are this sequence, the sequence that is x_0 . Then, the first sample second sample is x_1 then x that is x_t then x_2 T at 0 'th, 1 , 2 like that. Then, you can easily see that this sequence becomes actually a stationary sequence.

The Strict Sense stationary sequence obviously, because if you want take the joint density here. If you take say few samples, if you take up to the few sample. So, 0 up to n 'th sample x_n T . And you take the joint density that is basically, the joint density here of the sample. Now, if you give a shift there for any amount the shift is actually in integral multiple of T that is if you shift.

So, from 0 you get to 1 from 1 you get to 2 and from 2 you get to 3 . Basically, in time axis you are getting shifted by either T or $2T$ or $3T$ like that. So, by from the Cyclostationary T you should get the same joint distribution function right. So, if you sample it at T , $2T$, $3T$ and all that. Then, the sequence that you get that is Strict Sense stationary this must be obvious.

Because, what is this after all I mean the what is the joint distribution. This is nothing but x_1 x_2 dot dot dot X_n at time 0 T , $2T$ dot dot dot say nT you started x_0 say. And then if

you sample if you give a shift to this sequence. So, 0 is sample moves to fast and like that. That means basically you are giving a time shift by T, but from Cyclostationary of the original process you should get back the same probability distribution function. So that means, there is some relation between or before coming to that.

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$$\tilde{x}(m) = x(mT)$$

$$\downarrow$$

$$= \left(\begin{array}{l} F[\tilde{x}(0), \tilde{x}(1), \dots, \tilde{x}(k)] \\ F[\tilde{x}(1), \tilde{x}(2), \dots, \tilde{x}(k+1)] \end{array} \right)$$

This means that if you really take if you follow the discrete process mT say some sequence x_m as mT . Then, this sequence becomes strictly stationary. Because, here suppose you take as I you take the joint density, joint distribution x tilde 0 x tilde 1 dot dot dot x tilde say anything you can takes a k k sample. If state if you give a shift here, this is state you take x tilde this instead of 0 you jump by 1.

So, 1 x tilde 2 dot dot dot say x tilde k plus 1 these 2 are same that, because comes from the Cyclostationary of the original analog process. Because, this samples corresponds to where, which time indices 0 T up to kT . And here, instead of T instead 0 you are taking advancing by T instead of T you are advancing by 2T. Advancing by T instead of making it 2T and likewise. So, the sample what is and what you sampling at we have to get T that becomes a Strict Sense stationary process. In this context, some relation very much useful 1 is this.

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$$x(t): \text{SS cyclostationary}$$
$$\tilde{x}(t) = x(t - \theta), \quad \theta: \text{r.v.}, \text{ uniform over } 0-T$$
$$\text{claim: } \tilde{x}(t): \text{S.S. stationary}$$
$$\bar{F}(x_1, x_2, \dots, x_n; t_1, \dots, t_n) = \frac{1}{T} \int_0^T F(x_1, \dots, x_n; t_1 - \alpha, \dots, t_n - \alpha) d\alpha$$

That suppose, $x(t)$ is given to be SS Strict Sense Cyclostationary and instead of $x(t)$ you suppose shift it by θ . So, you get another process we call it $\tilde{x}(t)$ when θ is random, θ random variable uniform that is uniformly distributed over 0 to T , which T the same T over which, this is Cyclostationary $x(t)$ is Cyclostationary and the basic period then is T . So, you are shifting it by a θ , but θ is uniformly distributed over 0 to T . So, you get another random process $\tilde{x}(t)$ in that but then our claim: $\tilde{x}(t)$ is Strict Sense stationary strict stationary. And if you take \bar{F} stands for the distribution function, joint distribution for this new process $\tilde{x}(t)$. We take that is equal to this is our claim 1 by T integral 0 to T original distribution function $F(x_1, \dots, x_n; t_1 - \alpha, \dots, t_n - \alpha)$. So, we can prove this first. So, first we consider this what is the meaning of this distribution function.

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$$\begin{aligned} \bar{F}(x_1, \dots, x_n, t_1 + c, \dots, t_n + c) &= \text{Prob. of event } A \\ \text{where } A &= \left\{ \bar{x}_{\frac{t_1}{c}} \leq x_1, \dots, \bar{x}_{\frac{t_n}{c}} \leq x_n \right\} \\ &= P(A) = \int P(A, \theta) d\theta \\ &= \int P(A/\theta) d\theta \end{aligned}$$

When I said $\bar{F}(x_1, \dots, x_n, t_1, \dots, t_n)$. What does it mean? It means, it is equivalent to probability of event A where A is what this new process \bar{x} at t_1 less than equal to x_1 dot dot dot \bar{x} at t_2 less than equal to x_2 \dots \bar{x} at t_n less than equal to x_n , this a probability got it. Now, we have to show that this process \bar{x} at t is Strict Sense stationary. If it is strict sense stationary that means, instead of t_1 , if I give a constant shift c .

So, it is t_1 plus c then t_2 plus c dot dot dot t_n plus c . And then this distribution becomes equivalent to probability of event A , Where event A is simply this that a time t_1 plus c \bar{x} within bracket t_1 plus c less than equal to x_1 dot dot dot \bar{x} at t_n plus c again, less than equal to x_n this is the event. So, instead of t_1 t_2 up to t_n I am just giving a constant shift a constant delay or advancement.

Whatever, you know to the time points by the same I am just shifting all of them by constant amount c . I have to show that, this probability distribution is independent of c . And then only it will be proved that this \bar{x} at t is a Strict Sense stationary process. That is whatever be the shift you give to the time origin on the time axis the probability distribution, the joint probability distribution does not change.

So, we consider this event A which is this that is the process. And value at time point t_1 plus c is value taking less than equal to x_1 comma dot dot dot it is value again, at time point t_n plus c taking values up less than equal to x_n . The joint this is joint event you know these this means, so probability of this event is actually this distribution. Now, 1 thing \bar{x} at t_1 plus c .

So, within that actually what is \bar{x} at t_1 plus c after all It is x at t_1 c plus minus theta by definition of \bar{x} . And therefore in this process \bar{x} there are 2 random components: 1

is coming from the original process $\bar{x}(t)$. So, every time you observe you get some data, but again that is delayed by another variable θ which is also random. So, there are 2 random you know 2 random phenomenon, that are occurring simultaneously, 1 is from this process $\bar{x}(t)$, another the dealing variable θ .

So that means, $P(A)$ is nothing but $P(A, \theta)$ this is joint density of the event A and θ taken some value. And θ is taking values over the range 0 to T . So, this is $P(A, \theta)$ as we know is nothing but $P(A | \theta)$ into $P(\theta)$ and $P(\theta)$ is what θ is given to be uniform from 0 to T . That means, within interval 0 to T its probability density is constant and that is equal to $1/T$. So, that area is 1 so that $1/T$ is $P(\theta)$ by T comes out of the integral and the 0 to T $d\theta$.

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The image shows a digital whiteboard with the following handwritten mathematical derivation:

$$\begin{aligned}
 P(A|\theta) &= P_{\text{prob}} \left[\bar{x}(t_1 + c - \theta) \leq X_1, \right. \\
 &\quad \left. \dots, \bar{x}(t_n + c - \theta) \leq X_n \right] \\
 &= F \left[x_1, \dots, x_n; t_1 + c - \theta, \dots, t_n + c - \theta \right] \\
 &= P(A) = \int_0^T P(A, \theta) d\theta \\
 &= \frac{1}{T} \int_0^T P(A|\theta) d\theta
 \end{aligned}$$

On the right side of the whiteboard, there is a small box containing the definition of the delayed process:

$$\bar{x}(t) = x(t - \theta)$$

That means, that implies what, but what is $P(A | \theta)$ We know the event this is simply joint probability of what. For a given θ what is the value that, the process at time T_1 plus T takes values less than equal to x_1 dot dot dot it is time t_n plus c that is $\bar{x}(t)$ within bracket t_n plus c less than equal to x_n . But we know that, we know these thing that $\bar{x}(t)$ is $x(t)$ minus θ and in this context θ is constant that is given a particular θ .

So, θ is no longer random. So that means, when I say that $\bar{x}(t_1 + c) \leq X_1$ this is equivalent to saying x less than equal to x_1 dot dot dot $x(t_n + c - \theta) \leq X_n$. This is using our notation this is nothing but probability distribution of the original process x_1 dot dot X_n integral. What are the time points $t_1 + c - \theta$ dot dot $t_n + c - \theta$.

So, we have to substitute this $P(A | \theta)$ here in this integral and get that probability. That will be the joint distribution of the delayed process $\bar{x}(t)$. And that will show, that

is independent of this constant c . So, if you really remember this you are going to substitute for $P(A/\theta)$ by θ by this expression multiply by θ integrate from 0 to T and multiply by 1 by T . That means, if I erase this part.

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$$\begin{aligned}
 P(A/\theta) &= P_{\text{mult}} \left[\lambda(t_1+c) \leq X_1, \right. \\
 &\quad \left. \dots, \lambda(t_n+c-\theta) \leq X_n \right] \\
 &= F \left[x_1, \dots, x_n; t_1+c-\theta, \dots, t_n+c-\theta \right] \\
 \bar{F}(x_1, \dots, x_n; t_1+c, \dots, t_n+c) \\
 &= \frac{1}{T} \int_0^T F \left[x_1, \dots, x_n; t_1+c-\theta, \dots, \right. \\
 &\quad \left. t_n+c-\theta \right] d\theta
 \end{aligned}$$

That means, our starting point was this was the starting point t_1 plus c t_n plus c This is equal to this you have seen $P(A/\theta)$ by θ $d\theta$ integral 0 to T multiplied by 1 by T . So, I simply substitute with our expression F actually, from this only using your intuition you can I mean you can make this infinite And say loop θ is integral variable and you are integrating for 1 period, because this distribution is periodic.

If θ jumps over by an if θ is replaced by $\theta + T$, that is θ increases by it jumps by a factor T . You should get back the same probability distribution functions simply, because of the Cyclostationary t . So, this distribution is actually periodic in θ , because if a θ is replaced by $\theta + T$, you would get the same thing. Because, $\theta + T$ means this net thing net time index for all the points they get I mean they get subtracted I mean T get subtracted.

So, that is minus 1 times T gets added. So, from Cyclostationary t you would get the same probability distribution function. So that means, this is in the periodic in θ and you are integrating this over 1 period. So, what value you should get that should not get depend on your t_1 plus c . That is it should not depend on your this constant c . Anyway, this comes from intuition we can easily prove it. We can easily get, what this expression would be. This is actually, simple mathematics now.

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The image shows a handwritten derivation on a whiteboard. At the top, it states $\alpha = \theta - c$. Below this, the first line is $\Rightarrow = \frac{1}{T} \int_{-c}^{T-c} F[x_1, \dots, x_n, t_1 - \alpha, \dots, t_n - \alpha] d\alpha$. The second line shows a change of variables: $= \frac{1}{T} \int_{0}^{T-c} \dots d\alpha$. A third line shows a further transformation: $+ \frac{1}{T} \int_{T-c}^T \dots d\alpha'$. A fourth line shows the substitution $\alpha' = \alpha + T$. The final line is $\Rightarrow \frac{1}{T} \int_0^T F[x_1, \dots, x_n, t_1 - \alpha, \dots, t_n - \alpha] d\alpha$. Arrows indicate the mapping of the integration limits and the variable substitution.

Suppose theta minus c. I say alpha equal to theta minus c. That means, it is integral will be what when theta equal to 0 alpha is minus c. So, from minus c to T minus c. That means, it integral will become equal to 1 by T d alpha. And now, maybe I can erase this part. Then, this integral 1 part it is from 0 to T minus c if you what you can call it 0 plus the same thing comes here d alpha.

Then, again 1 by T in other case it is from minus c to 0 minus the same thing d alpha. Let us consider this second integral is if suppose alpha is replaced by alpha prime plus t. Suppose, I bring a variable alpha prime which is alpha plus t alpha plus t, then what happens when alpha is minus c this becomes T minus c and when alpha is 0 this becomes T.

So, integral limit is changes to this will become T minus c this is alpha prime and this becomes T. And within this we have got this probability distribution function, but alpha to be replaced by alpha prime minus T. So, we have got instead of T1 minus alpha now we have got t1 minus alpha prime minus t tn minus alpha prime minus t. So, everywhere I am going to the constant shift by T and from the Cyclostationary t of the original process. You should get back, the same distribution function as given by this.

Because, going forward or backward by T or twice T or 3T would not change anything right. So, we get back the same thing, and then you replace again alpha prime by alpha by these 2 different variables. So, 2 integrals can be brought together. So, 0 to T minus C at T minus to T, so you basically would get finally, you will get these thing 1 by T 0 to T F.

So, we see this entire thing is independent of that original shift parameter c . So, this the expression we wrote that time. So, this proves that this process x bar t is a Strict Sense stationary process. Actually, this is of an important you know, because the communication sometimes I mean this is based by the way from that you transmit that.

Basically, you choose a pulse and then pulse is multiplied by the symbols and you get a pulse strain each pulse is modulated by a vertical symbol. And that say symbols are coming randomly then entire things becomes and continuous value random process that will becomes Cyclostationary.

But then often that process gets delayed while this in the receiver. And the delay variable θ or phase shift whatever, now that is often found to be uniform as a result the delayed process turns automatically strictly stationary. That is why this context is example is important. Then, if you have x Strict Sense stationary, obviously you have also Wide sense Cyclostationary.

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Wide sense cyclostationary

$$\Rightarrow \eta(t) = E[\lambda(t)]$$

$$= \eta(t+mT), m \in \mathbb{Z}$$

$$\Rightarrow R(t+T, t) = E[\lambda(t+T)\lambda^*(t)]$$

$$= R(t+mT+T, t+mT)$$

Also called WS Cyclostationary here we should imply then if you take the mean at any particular time say x_t . It is no longer like in the case, of stationary process we have seen when you come down to w wss that time it is no longer the joint distribution that we consider we just take the mean and auto and correlation here also. We take the mean and if we call this mean t .

In the case of stationary process, this was this become independent of t , but if is Cyclostationary that is in the case of stationary process if you take any indices $t_1 t_2 t_3$ you should get the same mean. Here it is not sure, you would get the same means provided instead of t you either go forward or backward by T or twice or $3t$ like that.

That is this is equal to when m is an integer that is m is from z . This is number 1 I mean, in the case of correlation that is say R t plus τ and t .

There is 2 integers the 2 time points are taking 1 is the t plus τ another t . This is same as say if you consider real value process, this is same as or in there is a complex value this is this. If it is Cyclostationary then this correlation even that the function of in the case of Strict Sense stationary what happened. These 2 time indices t_1 and t_2 that is t plus τ and t they did not matter, but matter was the separation τ .

In the case of Cyclostationary process this is not so for all t , but for a specific values of t . That is either, as t is replaced by t plus T here and here or t plus $2t$ that time this gap the separation which is always τ that should come into play. That is it should become of a function τ not all not at all t , but at the time points that are separated by integral multiples of T . T is a basic period or it is a Cyclostationary.

So, that is if t is replaced by t plus m into T M being an integral plus τ and t plus mT . Only then these 2 correlation values will be same that is not that the auto this correlation function becomes a, this correlation becomes a function of only their gap or lag that is τ . For any t , but these indeed becomes a function of τ only at certain choices of t . That is either t or t plus mT t plus T t plus $2t$ t plus at this 2 points the gap is again τ between these 2 t of time points time indices, but is not true for any t . So, this is the definition of Wide Sense Cyclostationary t and obviously, you can see that if the process is given to a Strict Sense stationary. It is also Cyclostationary, Wide Sense Cyclostationary are not vice-versa.

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$$\begin{aligned} h(t_1) &= E [x(t_1)] \\ p(x_1, t_1) &\equiv p(x_1, t_1 + mT) \\ &= \text{Prob} \{x_1 \leq x(t_1) \leq x_1 + dx_1\} \\ \int_{-\infty}^{\infty} x_1 p(x_1, t_1) dx_1 &= h(t_1) \\ &= h(t_1 + mT) \end{aligned}$$

Obviously, I mean like in the case of in the case of, we will take the expectation; that means you in the process given to be say strictly say SS Cyclostationary. Then, we know this density is same as t_1 plus any mT . What does this density means, that is probability that x_t x_{t_1} or t_1 plus mT takes values within this range between x_1 we have to come to density now not distribution dx_1 . And what is η_t ; η_t you simply multiply x_1 by this η_{t_1} say that will give you η_{t_1} .

Similarly, if you want to find out that t_1 plus mT instead of t_1 you make it t_1 plus mT . But since, it is Strict Sense Cyclostationary. The 2 densities are same and you get the same result. Suppose, it is Strict Sense Cyclostationary it is also Wide Sense Cyclostationary at least for the mean we have seen same we can see for the correlation also.

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$$R(t+\tau, t) = E. [x(t+\tau) x(t)]$$

$$p[x_1, x_2, t+\tau, t]$$

That is what is $R_{t+\tau}$ consider a real valued case. That is how, will you calculate it you multiply these 2 by the joint density. What is joint density? That is p_{x_1, x_2} at $t+\tau$ and t meaning the joint probability that at x_1 at $t+\tau$ x_2 at t lies between x_1 and $x_1 + dx_1$ and x_2 lies between x_2 and $x_2 + dx_2$. We multiply these 2 functions x_1 and you multiply this by x_1, x_2 integrate over x_1, x_2 over the entire range. Then, you will get this. If t is replaced by $t + mT$ here you would get the same integral is, because from the Strict Sense stationary t the 2 distributions or densities will be same. So, that follows obviously, immediately. So, we do not spend more time on it. So, similar in this case also we can show that.

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$x(t) : \text{W.S. cyclostationary}$
 $\tilde{x}(t) = x(t - \theta)$
 $\theta : \text{r.v., uniform over } 0-T$
 $\Rightarrow \tilde{x}(t) : \text{WSS,}$
 $\bar{\mu} = \frac{1}{T} \int_0^T \mu(t) dt, \tilde{R}(\tau) = \frac{1}{T} \int_0^T R(t+\tau, t) dt$

Suppose, $x(t)$ is Wide Sense and you generate $\tilde{x}(t)$ as where θ is a random variable uniform over 0 to T . Then, our claim is $\tilde{x}(t)$ will be WSS with its mean $\bar{\mu}$ will be $\frac{1}{T} \int_0^T \mu(t) dt$ and correlation $\tilde{R}(\tau)$ will be $\frac{1}{T} \int_0^T R(t+\tau, t) dt$ we prove this.

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$\tilde{p}(x, t) = \tilde{p}(A)$
 $A = \{x - \tilde{x}(t) \leq x \leq x + dx\}$
 $\tilde{p}(x, t) = \int x \tilde{p}(A) dx$
 $\tilde{p}(x, t) = \frac{1}{T} \int_0^T \int x \tilde{p}(A/\theta) dx$
 $\tilde{p}(A) = \frac{1}{T} \int_0^T \tilde{p}(A/\theta) d\theta$

Now, how do we find out this quantity for that matter, we define these density $\tilde{p}(x, t)$ this is same as $\tilde{p}(A)$ where is this event $\tilde{x}(t)$ at this time point t takes values within this zone. At time t this process $\tilde{x}(t)$ takes value within this zone. In that is case, simply $x \tilde{p}(A) dx$, but as I told you earlier $\tilde{p}(A)$ is nothing but $\tilde{p}(A/\theta)$ by θ into $p(\theta)$. And $p(\theta)$ is $\frac{1}{T}$ $\tilde{p}(A)$ is what, seen earlier is $\tilde{p}(A/\theta)$ $d\theta$ over 0 to T .

What is the entire range of theta, but p bar A comma theta we have seen earlier is nothing but p bar A by theta into p theta that is 1 by T. Because, p theta that is uniformly distributed over 0 to T and that 1 by T goes outside and d theta. And here theta is fixed. So, what we get here if you replace p bar A by this expression and inter change the 2 integrals what you get is 1 by T 0 to T.

Then, this integral this T theta comes here this integral minus infinity to infinity x p bar A by theta dx And what is this theta is fixed here. So that means, x bar t taking value x bar t which is also equal to we know x t minus theta and theta is fixed. So, p bar A by theta is same as the probability of x taking value x t minus theta taking value. That is the process xt at time point t minus theta taking value between x2 x plus dx.

So, this will give rise to expected value of the process at t minus theta. I repeat theta is fixed p bar A by theta means for a given theta. So, once theta is fixed look at this event A x bar t is same as xt minus theta. So, probability of A subject to fixed theta is what the probability of x t minus theta this random variable taking values between X to x plus dx. That multiplied by x integrated, that will give rise to the expected value of this random variable x of t minus theta which is eta t of t minus theta right.

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The image shows a handwritten derivation on a whiteboard. The equations are as follows:

$$\begin{aligned} &= \frac{1}{T} \int_0^T \eta(t-\theta) d\theta = \frac{1}{T} \int_0^T \eta(\alpha) d\alpha \\ &= \frac{1}{T} \int_{t-T}^t \eta(\alpha) d\alpha = \frac{1}{T} \int_0^t \eta(\alpha) d\alpha + \frac{1}{T} \int_{t-T}^0 \eta(\alpha) d\alpha \\ \bar{\eta}(t) &= \int_{-\infty}^{\infty} x p(A) dx \quad \left| \alpha' = \alpha + T \right. \\ &= \frac{1}{T} \int_0^T d\theta \int_{-\infty}^{\infty} x \bar{p}(A/\theta) dx \\ &\quad \left. \underbrace{\qquad\qquad\qquad}_{\eta(t-\theta)} \right. \end{aligned}$$

Then, it is very simple you have this integral 1 by T t minus theta. Once again, you know this eta t, because the Cyclostationary t we know this is periodic over a period T so eta t a. Similarly, if theta is replace by theta plus 2 theta plus T or theta minus T will do the same thing, because of the Cyclostationary t. Because, the date argument get shifted either by plus or minus T or plus or minus 2t and so on and so forth.

Or we have integrating this over a entire period of theta. So, what mean eta So, this eta if you plot it as function of argument then basically you are integrating 1 period integrating this function eta over it is 1 period and averaging. So, that should not depend on whether I to I put t here or minus theta here I can call it I can with any variable eta of say alpha d alpha 0 to T 1 by T we can always put like this.

So, this comes physically and again you if we still want to verify it. If you still want to verify this, it is not very difficult you can call this alpha. So that means, when theta is 0 alpha is t and when theta is T is t minus t d theta, because minus d alpha. So, that 2 integral limit is were interchanged essentially, you get 1 by T. As I told you t minus 0. So, it was t lower limit was t upper limit was t minus T, but that gets interchanged.

So, t minus T and then t alpha d alpha and again, this you break in this form we have already done it from 0 plus to t the same the integral. And another, integral is again 1 by T from t minus t to 0 minus same integral. And rest is very simple you can as before you bring in alpha prime as alpha plus t. So, when alpha is t minus T alpha prime is t and when alpha is 0 alpha prime is T and then the 2 integrals is just from under 1 number and you get that result. That means we prove this part.

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The image shows a handwritten derivation on a greenboard. The equations are as follows:

$$\bar{\eta} = \frac{1}{T} \int_0^T \eta(t) dt = \frac{1}{T} \int_{t=0}^{t=T} \eta(t) dt$$

$$\bar{R}(\tau) = \frac{1}{T} \int_0^T R(t+\tau, t) dt$$

$$= E[\bar{x}(t+\tau) \bar{x}(t)]$$

$$= \frac{\int \int x_1 x_2 p(x_1, x_2, t+\tau, t) dx_1 dx_2}{\int_0^T p(A/B) dt}$$

We have proved this part that I call it alpha now again i am calling it T it does not matter it is an integration variable. In the same manner, R bar we wanted to prove that is R bar is basically function for tau 11. Because, it is Strict Sense stationary actually, this should be I should remove this dependence t now. Because this entire thing is a constant you see.

If you replace t by $t + \tau$ if you just substitute t by $t + \tau$ I mean this is just a formula this is just a results which is constant and that is $\bar{\eta}$. Similarly, my claim is that this delayed process is a strict sense stationary process I have not yet proved it. I have proved it by it is mean, but the correlation; that means, I have to show that it the correlation becomes a function of τ only.

So, this will show, but for that, so I am just writing as function of τ , but I have not yet proved it I keep that in mind. We will show we will get it is value, this actually is what this is a general expression. And what is that, as before E of \bar{x} I am assuming real otherwise, you put another star here. And how to carry out this integral, you have to find out that is this should be this bring this joint density $p(x_1, x_2, t + \tau)$ and t, x_1, x_2, dx_1, dx_2 .

But this joint density I can write as a conditional density that, it if it that is this is subject to θ multiplied by p_θ integral 1 by. And p_θ is integral 0 to T and p_θ that is this part I will write as p we call this event A A by θ into 1 by T to 0 to T θ this part. And then what happens you take the integral with respect to θ outside inside you have got x_1, x_2 multiplied by this joint density

What is the meaning of joint density, that is \bar{x} $t + \tau$ taking value between x_1 to $x_1 + dx_1$ and \bar{x} t taking values between x_2 and $x_2 + dx_2$, but \bar{x} $t + \tau$ for a fixed θ now \bar{x} θ is fix here for a \bar{x} $t + \tau$ is same as \bar{x} $t + \tau$ minus θ . And \bar{x} t is same as \bar{x} t minus θ . θ is fixed here mind you, because this is now conditional density. So, if you carry out the integral from the previous study. It is then nothing but this will that outer integral was there equal to T and inside you will have original R at $T + \tau$ minus θ comma t minus θ $d\theta$. So, write in other way here, so what I get may be I go to the next page, what I get is this.

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The image shows a whiteboard with handwritten mathematical equations. The equations are as follows:

$$\bar{R}(\tau) \equiv \bar{R}(t+\tau, t) \quad \left(\begin{array}{l} d' \\ = d + T \end{array} \right)$$

$$= \frac{1}{T} \int_0^T R(t+\tau-\theta, t-\theta) d\theta$$

$$= \frac{1}{T} \int_{t-T}^t R(\alpha+\tau, \alpha) d\alpha$$

Below the third equation, there is a substitution: $t-\theta = \alpha$. The final equation shows the integral split into two parts:

$$= \frac{1}{T} \int_{0^+}^t R(\alpha+\tau, \alpha) d\alpha + \frac{1}{T} \int_{t-T}^{0^-} R(\alpha+\tau, \alpha) d\alpha$$

R bar tau we have to be prove that it is integral function of tau alone. So, still I writing doing before end. So, actual it is as I told you R bar t plus tau comma t this we have shown. It is nothing but this integral original R t plus tau minus theta comma t minus theta d theta. And then this remaining part is very simple if you call if you call theta minus tau to be if you call theta minus tau to be some variable say tau 1 or alpha.

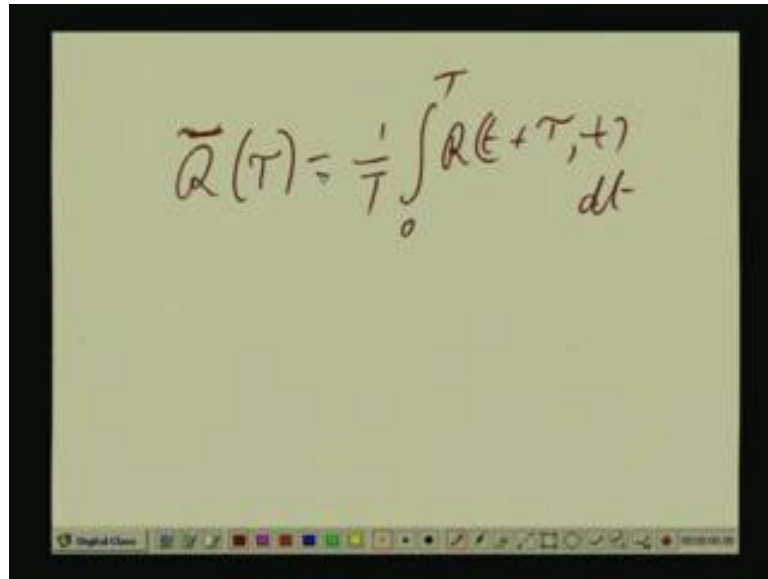
Then, it is integral becomes what same thing I am doing again. In the next class, I will take a just an example of Cyclostationary process, because then we will get a practical feeling. When, theta is 0 alpha is minus tau. So, from minus tau to t minus tau and this becomes R of t minus alpha just a minute it should instead of tau I should take this theta minus t to be alpha.

So, it is when theta is 0 it is T minus t and when theta is T this T minus t. And then R may be I can make a still better still more convenient for you forget about this. Suppose, I call t minus theta which is common as some variable say alpha. That means, this becomes 1 by T when theta is 0 this is t when theta is T it is t minus T or and then d theta becomes minus d alpha. So, this integral limit is will be changed and minus will comes.

So, this becomes this and this remains, because d theta and it is minus d alpha. So, minus comes and the 2 integral limit is are interchanged. So, minus sign goes and this is your alpha plus tau comma alpha. From this again it is obvious, because the entire thing is periodic about alpha over a period at T still if you are not convinced you can break the integral in 2 halves: 1 is from 0 to t that is 0 plus 2t same thing, another is from t minus T to 0 minus same thing dt.

Consider this integral second 1 here again bring this variable alpha prime is alpha plus T same way. So, d alpha and d alpha prime are same when this integrals are with respect to alphas d alpha. So, d alpha and d alpha prime are same and when alpha becomes t minus T alpha prime becomes t. When alpha becomes 0 alpha primes becomes T and the 2 integrals can be brought under same 1 and you get the result, that result that is a function of tau value.

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$$\bar{R}(\tau) = \frac{1}{T} \int_0^T R(t+\tau, t) dt$$

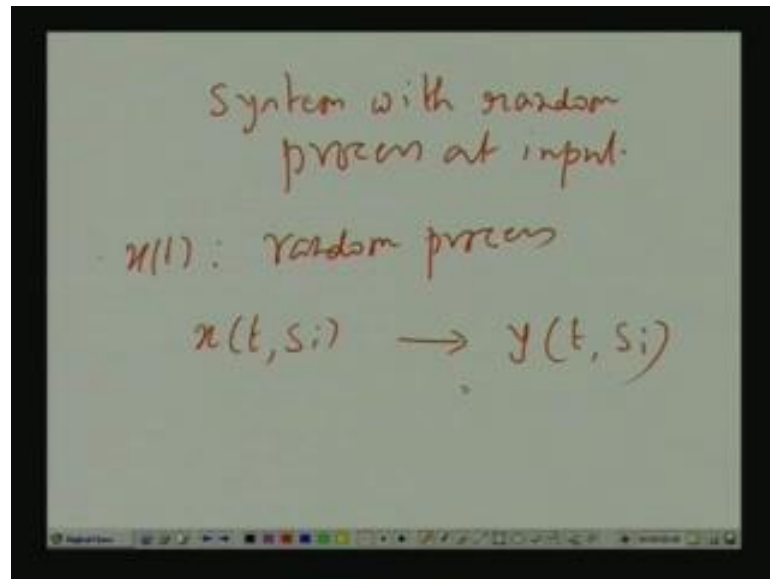
What you get is R you can call it alpha or you can bring back t again, say does not matter, because that is an integration variable T dt. So, you can call it alpha as well instead of t 0 to T 1 by T this is your R bar tau. So, this process is strictly is a Strict Sense stationary. These are some applications in communication we will take 1 example. The example of pulse amplitude modulation was formed PAM, there will be a practical feeling and you understand why we spend some time on it.

After that, we will move to systems that is processing of random processes by some linear systems or non-linear systems time in variance systems and all that. And that will take us to finally, spectral analysis, power spectral density and things like. So, that is all for today.

Thank you very much,

Today, we discuss systems with random processes input.

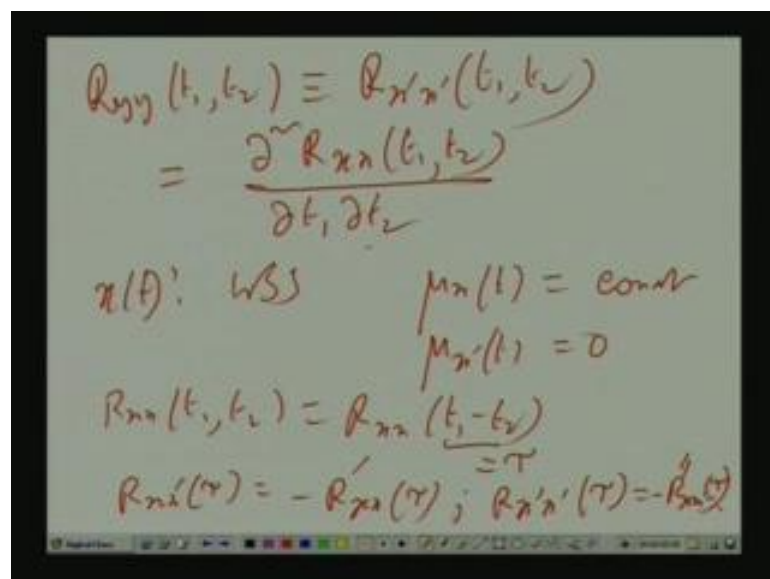
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Suppose, $x(t)$ is a random process; that means, you conduct experiment and with a every time you have an experiment you know we observe 1 wave form right. So, may be 1 particular wave form we denote as before as this, where s_i denotes the i 'th outcome. So, in the i 'th outcome you get an wave form as a function of time. So, this is represented by $x(t, s_i)$. So, is actually function of time s_i just denotes the fact is a just stands for the fact that it is related to the i 'th outcome a particular waveform.

Now, suppose we have some kind of some a rule. We develop or we have in which some kind of rule by which given particular waveform we generate another waveform by a rule some waveform we call it y . And obviously, that wave form also is associated with the i 'th outcome of the experiment.

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So; that means we can write it as $y = t^2$ for example, you can also write it as $y = t^2$. Now, here we have got $R_x(t_1, t_2)$ is a function of actually $R_{xx}(t_1 - t_2, t_1 - t_2)$ equal to say τ . So, it is function of τ . So, here but I do in 1 minute here if you take these derivative $\frac{d}{d\tau} R_{xx}(t_1 - t_2)$. So, t_1, t_2 is τ we differentiate with t_2 first and t_1 first I limit as an exercise to you can easily verify these 2 things. $R_{xx}(\tau)$ $R_{xx}'(\tau)$ you can easily verify will be $R_{xx}(\tau)$ first order derivative and $R_{xx}''(\tau)$ will be second order derivative. So, that is all for today.

Thank you very much.