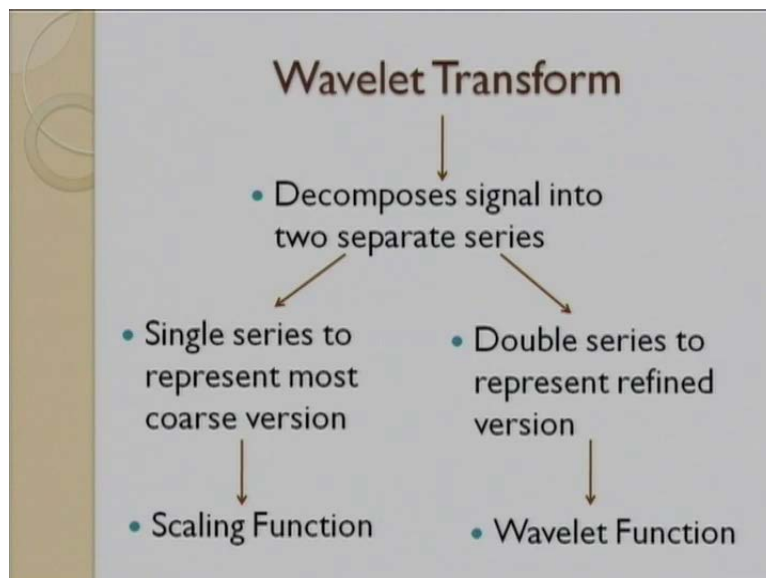


Advanced Digital Signal Processing - Wavelets and Multirate
Prof. V. M. Gadre
Department of Electrical Engineering
Indian Institute of Technology, Bombay

Lecture No. # 47
More Thoughts on Wavelets: Zooming In

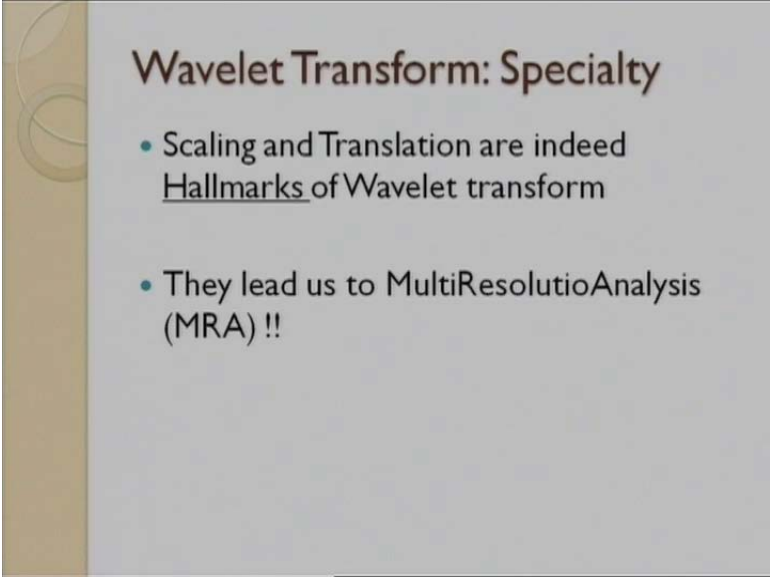
Hello and welcome to lecture number two. We have titled this lecture as the zoom in and zoom out features from wavelet transform, and we are going to continue where we left in the first lecture.

(Refer Slide Time: 00:42)



We saw in the last lecture, that wavelet transform essentially decomposes signal into two separate series; a single series to represent the approximations, that would lead us to scaling function, also popularly known as the father function, and the double series to represent the details; that would lead us to the wavelet function or the mother wavelet.

(Refer Slide Time: 01:08)

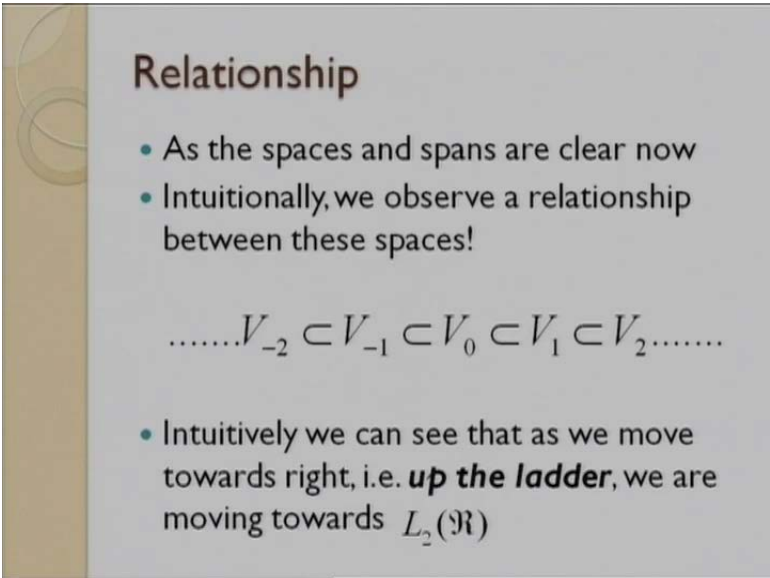


Wavelet Transform: Specialty

- Scaling and Translation are indeed Hallmarks of Wavelet transform
- They lead us to MultiResolutionAnalysis (MRA) !!

Then we also looked at the fact, as to what is this specialty of wavelet transform, and we realized that scaling, translation and dilation, they together are the hallmarks of wavelet transform, and together they lead us to multiresolution analysis or popularly also known as MRA.

(Refer Slide Time: 01:37)



Relationship

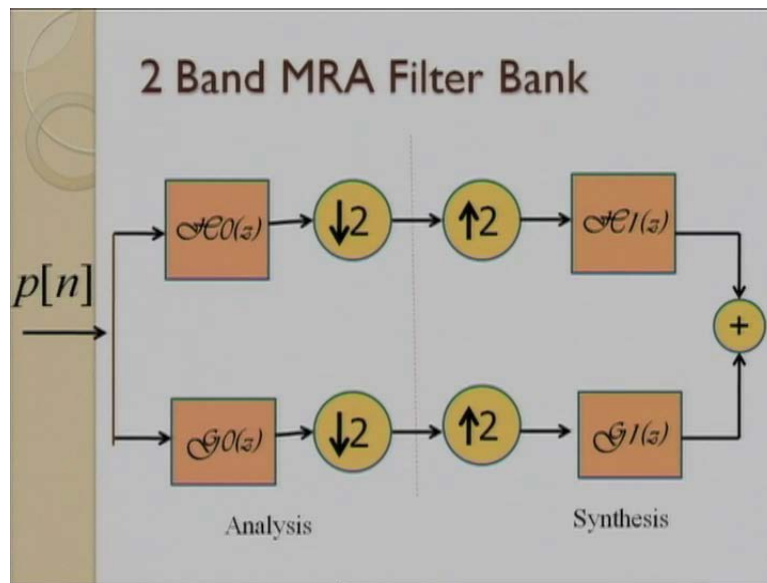
- As the spaces and spans are clear now
- Intuitively, we observe a relationship between these spaces!

$$\dots\dots V_{-2} \subset V_{-1} \subset V_0 \subset V_1 \subset V_2 \dots\dots$$

- Intuitively we can see that as we move towards right, i.e. **up the ladder**, we are moving towards $L_2(\mathfrak{R})$

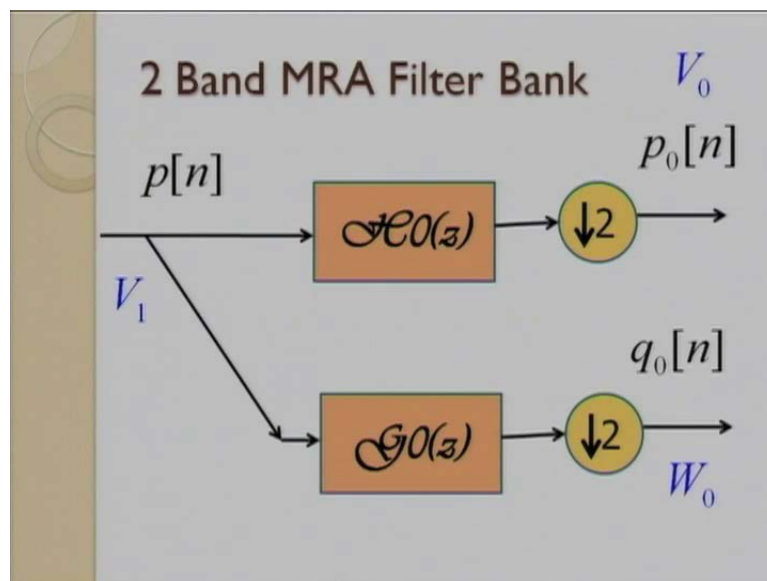
We also saw the nested subsets, and we wanted to move up the ladder. We saw one peculiar way in which multiresolution analysis can be implemented.

(Refer Slide Time: 01:53)



And it is a two band filter bank structure, and then we focused only on the analysis part of it.

(Refer Slide Time: 02:02)



And then we realized that this kind of structure would help us move down the ladder. And then we pose this question, if at all I want to move up the ladder, if at all I want to go on adding up the details, then what kind of framework will help me achieve that, will help me do that. And in this particular lecture, we are going to achieve the same, we are going to first of all define the framework. Once we have done with defining the framework, we will then move on and solve one problem, make our hands dirty to really understand the integrities of

the entire procedure. So, let us start that process; we have realized that the whole MRA multiresolution analysis, is in a way based on the underlying nested subsets.

(Refer Slide Time: 03:14)

The diagram shows the scaling function equation: $\phi(t) = \sqrt{2} \sum_k h_k \phi(2t-k)$. Below the equation, two arrows point down to the terms $\phi(t)$ and $\phi(2t-k)$. Under $\phi(t)$, it is written $\phi(t) \in V_0$ with an arrow pointing to 2^0 . Under $\phi(2t-k)$, it is written $\phi(2t-k) \in V_1$ with an arrow pointing to 2^1 . The title "Scaling function" is written above the equation.

And we can really bring out the essence of this, through two mathematical equations; first the equation of scaling function, which can be written as, $\phi(t)$ to be equal to summation over k of $h_k \phi(2t-k)$. And to normalize this let's add this factor of square root of 2. Now this equation is very special, if I take this factor down, then we can clearly understand that this is indeed $\phi(t)$, and t essentially indicates 2^0 , and then I can say this belongs to subspace V_0 . Similarly, I can also take this factor down, and then we will realize that this is $\phi(2t-k)$, and this essentially means 2^1 , and this belongs to V_1 . So, this feeling of nested subsets, is very nicely captured in this beautiful scaling function, scaling equation. This holds true for the other type of function as well, which is the wavelet function.

(Refer Slide Time: 04:48)

Wavelet Function

$$\psi(t) = \sum_k g_k \phi(2t-k)$$

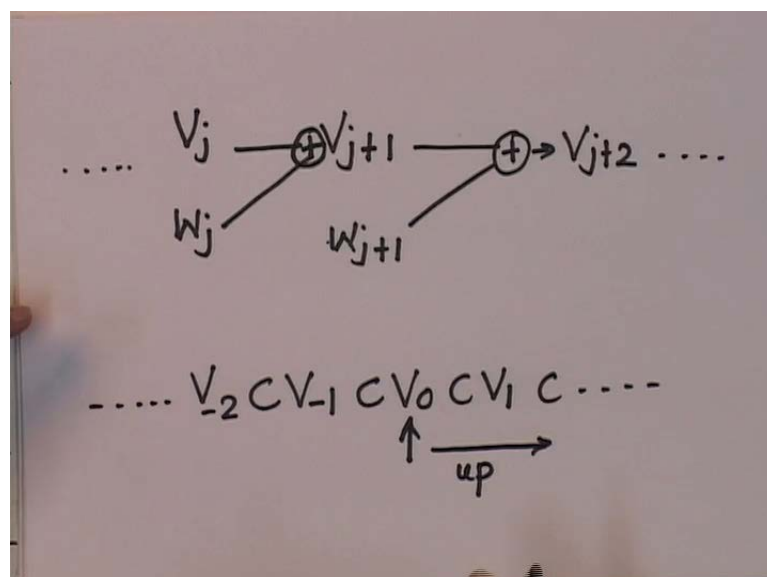
$\downarrow$
 $\psi(1 \cdot t) \in W_0$
 $\downarrow$
 2^0

$\downarrow$
 $\phi(2t-k) \in V_1$
 $\downarrow$
 2^1

$$\underline{V_j = V_{j-1} \oplus W_{j-1}}$$

So, we can write down wavelet function like this; ψ of t , again summed over k values g of k ϕ of twice t minus k . And I can once again sense, that this is simply ψ of $1 \cdot t \cdot 2$ to the power 0, and then I can say this function belongs to W_0 subspace, and this function once again belongs to V of 1, because I have ϕ of twice t minus k and 2 to the power 1, so this still belongs to V of 1. Under looking at these two mathematical equations, now we can once again sense the same equation that we wrote towards the end of last lecture; that V of j would indeed V equal to V of j minus 1, orthogonally added with W of j minus 1. And this once again leads us to the beautiful ladder; that we have been talking about.

(Refer Slide Time: 06:32)



Once we realize that V of j and W of j , together can take me to V of j plus 1, and if I have W of j plus 1, then together they can take me to V of j plus 2 and this continues. And so once again we can write down the same nested subsets; V of minus 2 V of minus 1 V of 0 and this could continue, and last time we pose this question that if I start my analysis, let say in V of 0. Then how I can move in the upward direction so that I will keep adding up different details, and by virtue of doing that I can go really close to the actual signal or the actual function under consideration for analysis, how to achieve that. Now, let us write down the framework for the same. Let say, I have some function, and I have the corresponding projections of that function, so how this entire assembly will help me move in the upward direction.

(Refer Slide Time: 08:10)

$$f_j(x) \in V_j, \text{ Scale} = \frac{1}{2^j}$$

$$\left\{ \frac{2^{j/2}}{\sqrt{2}} \phi(2^j x - k) \right\}_k$$

↓
Normalization

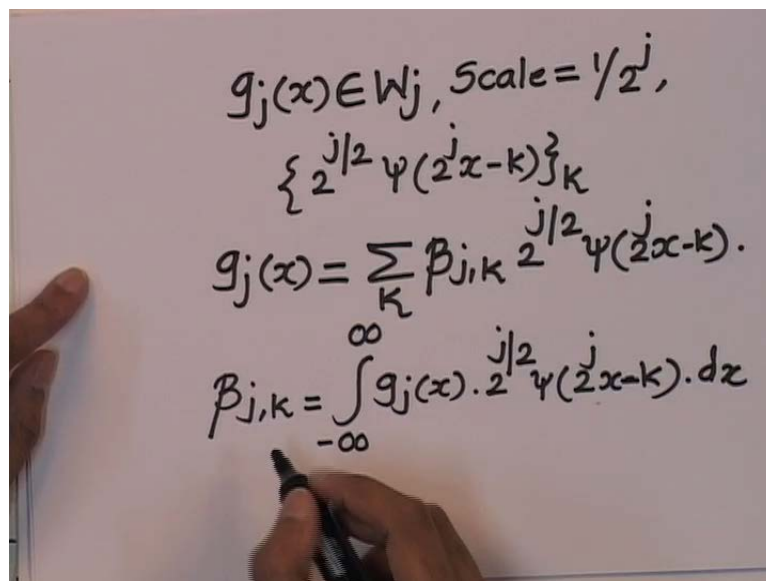
$$f_j(x) = \sum_k \alpha_{j,k} \frac{2^{j/2}}{\sqrt{2}} \phi(2^j x - k)$$

$$\alpha_{j,k} = \int_{-\infty}^{\infty} f_j(x) \frac{2^{j/2}}{\sqrt{2}} \phi(2^j x - k) \cdot dx$$

Let say I have function and I am representing that function, so that it belongs to some subspace V of j , and I can do this with the scale value of 1 upon 2 to the power j . Obviously, in order to be able to span this V of j subspace, I will require the basis function, and since we are talking about V of j spaces; obviously, the basis function is going to be ϕ of t . So, the basis function that will make use of, to span these spaces will be this, for all different values of k . Here k is the translational parameter, and 2 to the power j by 2, this is the normalizing factor, this is for normalization, and because of this normalizing factor my orthogonal basis will get converted into orthonormal basis.

Now, I can very well write down f_j of x in terms of the basis function, and the formula would be summation over k , because k is my translational factor, $\alpha_j k 2$ to the power j by $2 \phi 2$ to the power $j x$ minus k , and we can very well calculate α values like this. We are purposely taken the function to be a function of variable x , just to point out that this is just some variable, it need not be always f of t or x of t . So, we are looking at f dot to make it more generic. So, this is how we can span V_j subspaces, and correspondingly find out the approximation values which are the α values. Let's also write down the framework for W subspaces, and let say same function.

(Refer Slide Time: 11:19)



$$g_j(x) \in W_j, \text{ scale} = 1/2^j,$$

$$\{ 2^{j/2} \psi(2^j x - k) \}_k$$

$$g_j(x) = \sum_k \beta_{j,k} 2^{j/2} \psi(2^j x - k).$$

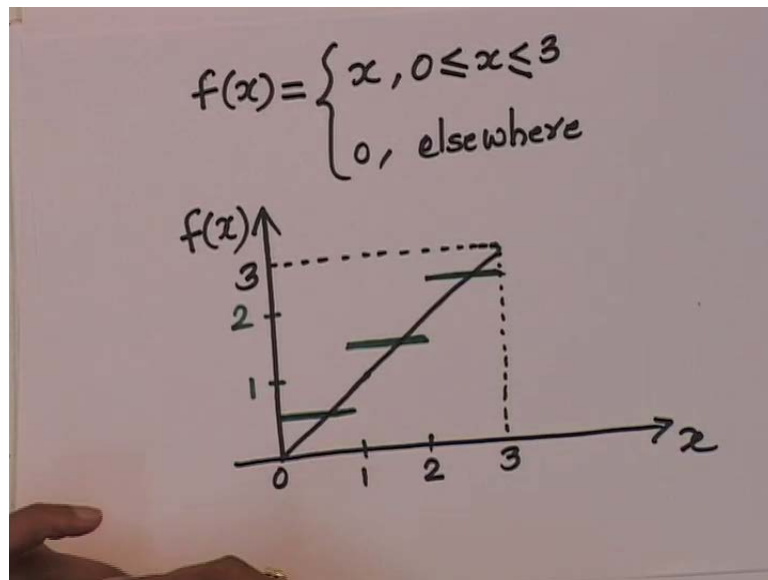
$$\beta_{j,k} = \int_{-\infty}^{\infty} g_j(x) \cdot 2^{j/2} \psi(2^j x - k) \cdot dx$$

Now, I am going to call that function of g of j of x , it belongs to subspace W_j . And we will make use of same scale which is 1 upon 2 to the power j , and in order to be able to span these subspaces, I will require the basis which will be now ψ , and k is once again the translation factor, translation parameter so to say. And I can write down similar equations once again, g_j of x will be equal to summation over k $\beta_j k 2$ to the power j by $2 \psi_j x$ minus k , and we can very well calculate these β values with the similar formula. So, this is how we can calculate β values.

And since we are talking about W subspaces, these β values will give us the details, which are very much required to actually move from one subspace to another subspace. Now, using this framework how can we actually move up the ladder, that is the next question. And in order to be able to answer this question, let us solve one simple problem, let

us take a sample signal, a sample function, and we will apply the framework that we have designed to that signal, to really understand how we can move from one subspace to another, keep on adding the details, and really move in upward direction, in order to be able to then achieve l_2 norm.

(Refer Slide Time: 14:02)



Let's take a simple signal, let say f of x is defined as x for values of x between 0 and 3, and let us say it is 0 elsewhere. We can also think of keeping this interval open by omitting this. And if we plot this signal, it would look like this. So, I have my x axis this is my f of x . Let say this is the simple looking signal, and we want to analyze this signal, using the framework that we have written down. Let us write down the objectives that we really want to achieve.

(Refer Slide Time: 15:19)

Objectives:

$$\begin{array}{l} f_0(x) \in V_0 \\ g_0(x) \in W_0 \end{array} \oplus f_1(x) \in V_1$$
$$\underline{V_0 \oplus W_0 = V_1}$$

We will first of all find out f_0 of x , which belongs to V_0 ; then we will find out g_0 of x which belongs to W_0 . And then we will add these orthogonally to produce f_1 of x which would belong to V_1 , and this is definitely moving up the ladder, from V_0 and W_0 where we are able to generate V_1 , correspondingly we can also find out g_1 that belongs to W_1 , and add V_1 with W_1 to produce V_2 and so on. So, it is very important to understand the process first and so we will restrict our exercise to this. And at the end of it what we really want to prove is V_0 plus W_0 , gives us V_1 , this is what we really want to achieve. So, we have this objective in our mind. Now, let us begin with the first task.

(Refer Slide Time: 16:49)

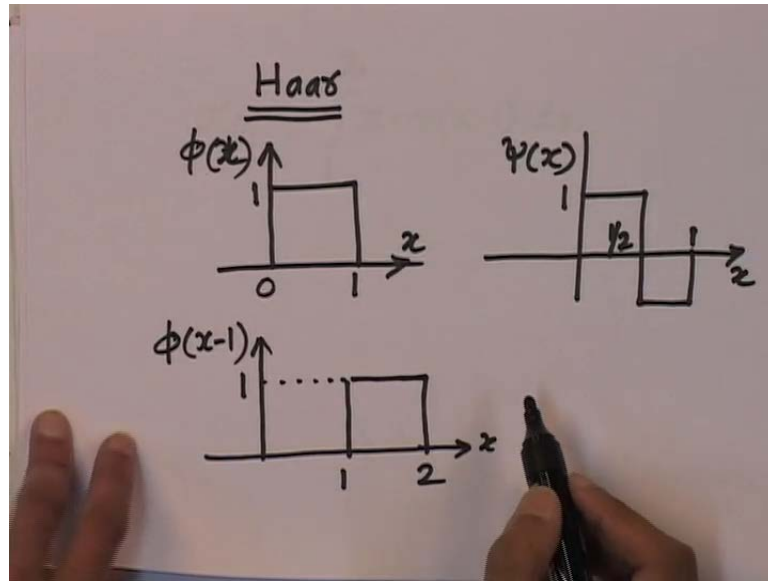
$$f_0(x) = \sum_{k=0}^2 \alpha_{0,k} \phi(x-k)$$
$$\alpha_{0,0} = \int_{-\infty}^{\infty} f_0(x) \cdot 2^{j/2} \phi(2^j x - k) \cdot dx$$
$$= \int_0^1 x \cdot 1 \cdot dx = \left. \frac{x^2}{2} \right|_0^1$$
$$\alpha_{0,0} = \frac{1}{2}$$

And that first task is, we want to find out f_0 of x which belongs to V_0 ; that essentially indicates j value is 0. The scale over here is going to be 1 upon 2 to the power j , which is 1 upon 2 to the power 0 , which is 1 . This essentially indicates that my window of analysis is of length 1 . And then this is my basis function that I will make use of, and if I plug in j is equal to 0 , then this would reduce to, this will go to 1 , and I will be left with x minus k . So, this is my basis function, that I am going to make use of, in order to be able to find out, projection of f on V_0 , so let us do that. Recall the formula, and I can very well write f_0 of x , will be equal to summation over k .

Now, if you remember our signal, the signal exists between 0 and 3 , and now my analysis window is of length one, and so as a result of that I will have to translate my basis function twice. So, the first window of analysis will be from 0 to 1 , then one to 2 , and then 2 to 3 . And I will have to carry out the analysis in three different steps. So, my summation of k will run from 0 to 2 . Then I have $\alpha_j k^j$, so I would write $\alpha_0 k^2$ to the power j by 2 goes to 1 , and then we have already calculated that this will be x minus k . So, boils down to calculating the values of α . Let us begin with the first value when k is equal to 0 . So, let us focus on α_0 . It will be integration from minus infinity to plus infinity, f_0 of x into 2 to the power j by 2 , and now we will plug-in j is equal to 0 , and k is also equal to 0 .

We also understand, that the moment you say k is equal to 0 , we are talking about ϕ of x ; that is the version which is not translated. We will have to here define, which ϕ of x and which ψ of x we are going to make use of, and this is one another beautiful property of wavelet transform. As far as Fourier transform is concerned, or z transform is concerned, the basis is fixed. However, the beauty associated with wavelet transform is, you have choice. You cannot only select, this scaling function and the wavelet function from whatever is available, if you are smart enough, you can also think of designing your own scaling function and wavelet function. We are going to take up this particular topic in the next lecture. However, for the time being, let us restricted to Haar scaling function and wavelet function. So, as far as Haar scaling and wavelet functions are concerned, we typically know how they actually look.

(Refer Slide Time: 21:01)



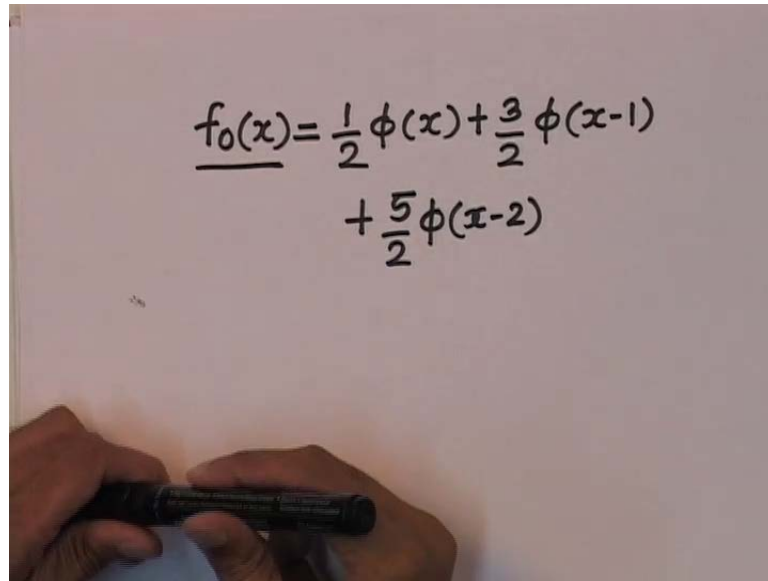
So, we will use Haar scaling and wavelet function. And in case of Haar we know, since we are using x , ϕ of x looks like this, and we also know ψ of x looks like this. So, we will make use of these two functions, to actually solve the problem at our hand. So, this integration bounds limits are now restricted from 0 to 1, and between 0 and 1, we know the nature of our signal f of x , it is going to be x between 0 and 3. So, between 0 and 1 it will be x . So, I can very well write x over here, 2 to the power j by 2 this will go to 1, I do not really have to worry about it. Now, between 0 and 1, when k is equal to 0, I am talking about ϕ of x , because this 2 to the power j is also going to go to 1, and between 0 and 1 this function is going to take a value of 1, and as a result of that, I can plug one for all of this, and then d of x , and this will be x square by 2, that leads us to half. So, α_{00} is half. Correspondingly, let us try and find out the other values of α .

(Refer Slide Time: 23:04)

$$\begin{aligned}\alpha_{0,1} &= \int_1^2 x \cdot \phi(x-1) \cdot dx \\ &= \int_1^2 x \cdot 1 \cdot dx = \left. \frac{x^2}{2} \right|_1^2 \\ \alpha_{0,1} &= \frac{2^2}{2} - \frac{1^2}{2} = \frac{3}{2} \\ \alpha_{0,2} &= \int_2^3 x \cdot 1 \cdot dx = \frac{5}{2}\end{aligned}$$

Lets calculate alpha 0 1. Now my integration would range from 1 to 2, between 1 and 2 my f of x is once again x 2 to the power j by 2 is going to go to 1, and I have phi of x minus 1 d x. Now, how this function looks, if my phi of x looks like this, then obviously, this is how my phi of x minus 1 would look. So, it will have value of 1 between 1 and 2 as simple as that. So, I can very well plug 1 over here, and this will be x square by 2 for limits 1 and 2, and this boils down to. So, alpha 0 1 comes out to be 3 by 2. And then correspondingly, we can calculate alpha 0 2, which will be equal to integration between 2 and 3, x phi of x minus 2 would be 1 between 2 and 3 into d x, and this would come out to be 5 by 2, what does this indicate. These alpha values are nothing else, but the approximate values of this function, that we started off with. We have already seen that f 0 of x, is going to be a projection of function in subspace V 0, and the formula is this. And so it goes without sign; that I can now very well write f 0 of x, in terms of all the alpha values that we have calculated.

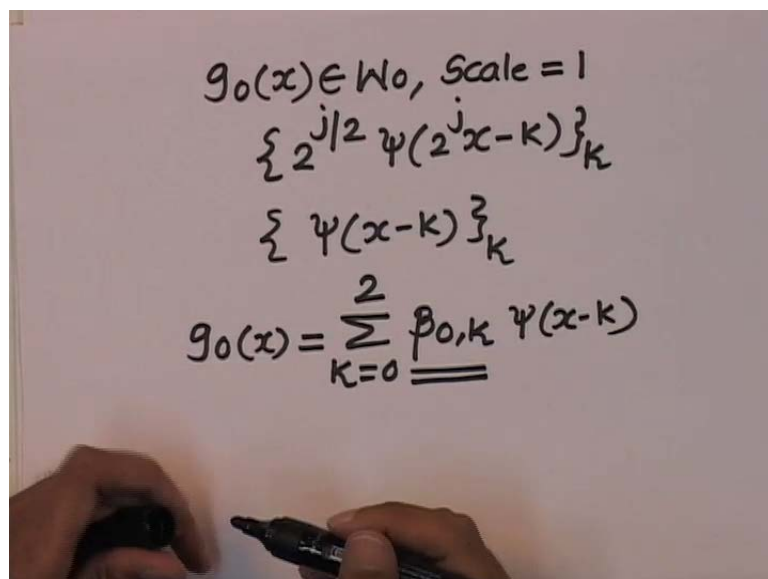
(Refer Slide Time: 25:36)



A photograph of a whiteboard with a handwritten equation. The equation is
$$\underline{f_0(x)} = \frac{1}{2} \phi(x) + \frac{3}{2} \phi(x-1) + \frac{5}{2} \phi(x-2)$$
 The handwriting is in black marker. A person's hands are visible at the bottom, holding a black marker.

And I can write f_0 of x is equal to half into ϕ of x plus 3 by 2 into ϕ of x minus 1 plus ϕ by 2 into ϕ of x minus 2. So, this is how I can very well find out the projections of signal f in subspace V of 0. And if we try and plot it, it will look like this. So, this is my α_{00} , this is my α_{01} , and this is my α_{03} . So, these are neat approximations of the underlying signal.

(Refer Slide Time: 26:54)



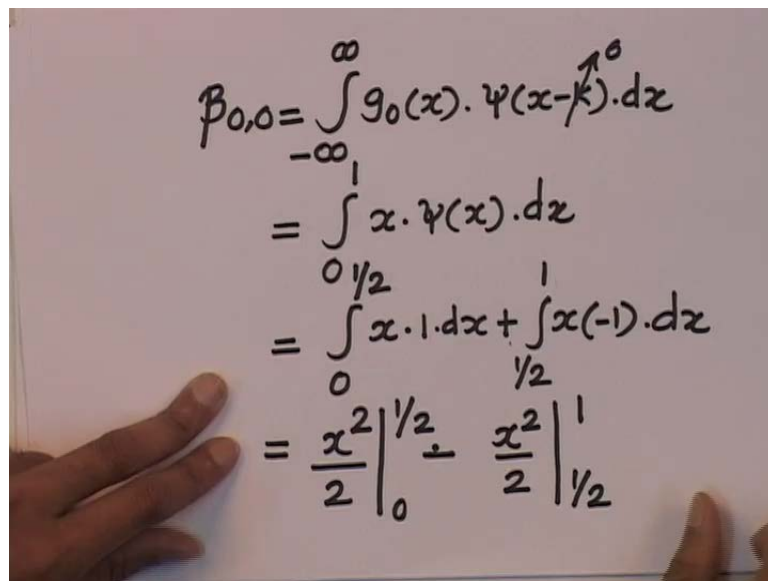
A photograph of a whiteboard with handwritten equations. The equations are:
$$g_0(x) \in W_0, \text{ Scale} = 1$$
$$\{ 2^{j/2} \psi(2^j x - k) \}_k$$
$$\{ \psi(x - k) \}_k$$
$$g_0(x) = \sum_{k=0}^2 \beta_{0,k} \psi(x - k)$$

The handwriting is in black marker. A person's hands are visible at the bottom, holding a black marker.

Now, the next task, and the next task is to find out the projections of signal in W_0 , and we have already written down that we are going to call this projections as g_0 of x , that would

belong to W_0 , this scale will be once again 1 as j is equal to 0, and the basis function will be. We will once again make use of the Haar wavelet function, and since j is equal to 0, this will reduce to a very simple form, k is once again the translation parameter. And now I can write down the g_0 of x will be summation for k values from 0 to 2, and then beta $j_0 k$ values into ψ of x minus k . And the next important task is, to find out all the beta values. And since these are the projections, in W_0 subspace, these beta values will now give the details associated with the signal. So, let us calculate the beta values now.

(Refer Slide Time: 28:22)



$$\begin{aligned}
 \beta_{0,0} &= \int_{-\infty}^{\infty} g_0(x) \cdot \psi(x-k) \cdot dx \\
 &= \int_0^1 x \cdot \psi(x) \cdot dx \\
 &= \int_0^{1/2} x \cdot 1 \cdot dx + \int_{1/2}^1 x \cdot (-1) \cdot dx \\
 &= \left. \frac{x^2}{2} \right|_0^{1/2} - \left. \frac{x^2}{2} \right|_{1/2}^1
 \end{aligned}$$

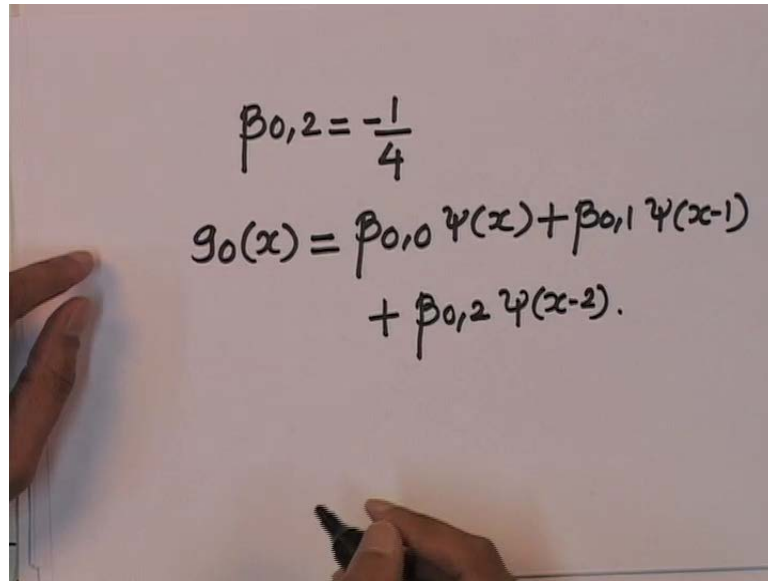
Using the formula, we can very well say beta 0 0; that means, j is equal to 0, and k is also equal to 0, integration from minus infinity to plus infinity g_0 of x into. Now k is 0 so we are talking about ψ of x , and how this function actually looks. We have already seen the nature, we are going to make use of Haar ψ of x , and so it is of this particular nature, and as a result of that, in order to be able to solve this integration, we will have to split it into two parts. So, for k value of 0, the integration would exist only between 0 and 1, g_0 of x is x again, and then we have ψ of x into dx , and due to the very nature of ψ of x , we will split this integration into 2 parts, from 0 to 1/2 x into. Now between 0 and 1/2 ψ of x takes the value of 1, and between 1/2 and 1, it takes the value of minus 1. So, we will plug in these values x into 1 into dx , and then plus between 1/2 and 1 x into minus 1 into dx , and this will result into x^2 by 2 between 0 and 1/2 minus. I will bring this minus sign out x^2 by 2, between 1/2 and 1.

(Refer Slide Time: 30:26)

$$\begin{aligned}\beta_{0,0} &= \frac{1}{8} - \frac{1}{2} + \frac{1}{8} \\ &= -\frac{1}{4} \\ \beta_{0,1} &= \int_1^2 x \cdot \psi(x-1) \cdot dx \\ &= \int_1^{3/2} x \cdot 1 \cdot dx - \int_{3/2}^2 x \cdot 1 \cdot dx \\ &= -\frac{1}{4}\end{aligned}$$

And thus beta 0 0 will result into 2 by 8 minus 1 by 2 plus 1 by 8, this will result into minus 1 by 4. So, this is the first beta factor that we have obtained beta 0 0. Let us work on the next one; that is beta 0 one j is 0 and k is equal to 1, and the integration is going to last between 1 and 2, g 0 of x will be x again into psi of x minus 1 into d x, and how would this look. We know if psi of x looks like this, and psi of x minus 1 will be the translated version of the same. This will exist between 1 and 2. So, this is how psi of x minus 1 is going to look, and we will split the integration again between 1 and 3 by 2 x into 1 into d x minus between 3 by 2 to 2 x into 1 into d x. We can solve this and confirm that this comes out to be minus 1 by 4 as well.

(Refer Slide Time: 32:35)

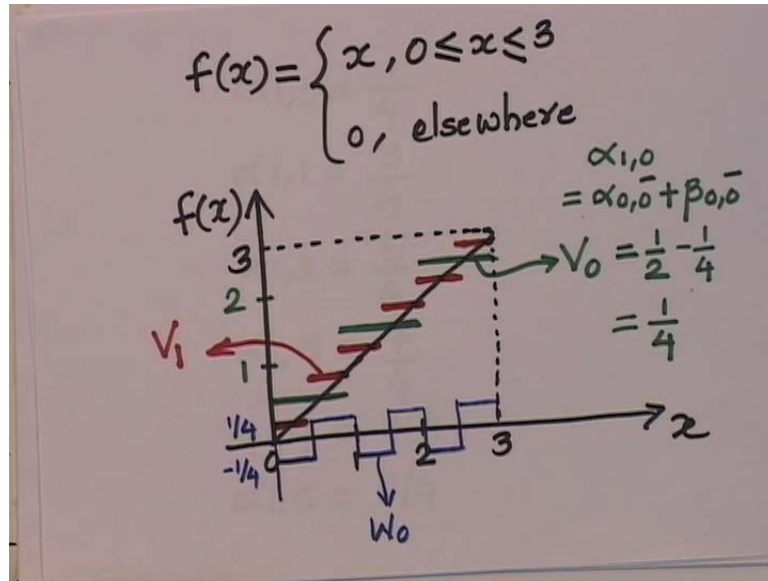


A photograph of a whiteboard with handwritten mathematical equations. The first equation is $\beta_{0,2} = -\frac{1}{4}$. The second equation is $g_0(x) = \beta_{0,0} \psi(x) + \beta_{0,1} \psi(x-1) + \beta_{0,2} \psi(x-2)$. A person's hand is visible on the left side of the whiteboard, and a black marker is visible at the bottom.

$$\beta_{0,2} = -\frac{1}{4}$$
$$g_0(x) = \beta_{0,0} \psi(x) + \beta_{0,1} \psi(x-1) + \beta_{0,2} \psi(x-2).$$

Correspondingly, we can also calculate $\beta_{0,2}$. $V_0 k$ is equal to 2, and I will leave it to the viewers to verify, that $\beta_{0,2}$ also comes out to be minus 1 by 4. So, all the 3 beta values, they have the same value of minus 1 by 4, and what does it indicate. So, we will try and analyze what it actually depicts. But before that, once we have calculated all the beta values, now it is time to write down g_0 of x in terms of its corresponding beta values, because then I can very well write, this will be $\beta_{0,0}$ psi of x plus $\beta_{0,1}$ psi of x minus 1 plus $\beta_{0,2}$ psi of x minus 2. And we can think of plotting this g_0 of x on top of the original signal, and what projection it would have in V_0 that we have already plotted. So, the green lines they indicate the corresponding representation or projection of signal f of x in V_0 .

(Refer Slide Time: 34:06)



Now, we will draw its corresponding projection in W_0 , and it is going to look like this, because all my beta values are negative, the first half is going to be negative, and this will be of value minus 1 by 4, and this is of value plus 1 by 4. So, these are the projections in W_0 subspace and these are my projections in V_0 subspace. Now, if you recall our objective, we wanted to orthogonally add our findings in V_0 and W_0 , to then achieve the projection in V_1 . So, let us see if we can really do that.

(Refer Slide Time: 35:17)

$$\begin{aligned}
 & \underline{j=1} \\
 & f_1(x) \in V_1, \text{ scale} = \frac{1}{2^j} = \frac{1}{2} \\
 & \left\{ 2^{j/2} \phi(2^j x - k) \right\}_k \\
 & \left\{ \sqrt{2} \phi(2x - k) \right\}_k \\
 & f_1(x) = \sum_{k=0}^5 \alpha_{1,k} \sqrt{2} \phi(2x - k)
 \end{aligned}$$

Now, if I want to find out the projections of the same signal in V_1 , I can write down f_1 of x which belongs to V_1 . So, now we can clearly see and sense, that j is equal to 1, and we are actually moving up the ladder. So, my scale is now going to change, the scale is going to be now 1 upon 2 to the power j , which will be equal to half. So, this scale will get reduced to half. And what kind of basis function, will have to make use of, 2 to the power j by 2 and then ϕ 2 to the power j x minus k , k is still remains the translation parameter. And since j is equal to one in our case, this would reduce to square root of 2 into ϕ twice x minus k . So, this will be the basis function that we will make use of.

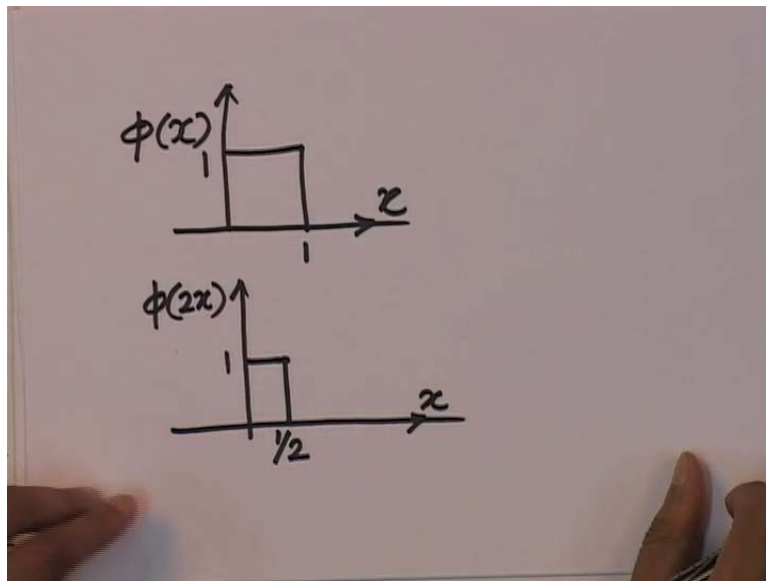
Correspondingly, I can also write down that my f_1 of x , will run over different values of k , and how many values of k . Our original signal lasted from 0 to 3 , now my window of analysis is half, and so I will obviously need 6 different windows in order to **we will** span the entire thing. And so my k value, is now going to run from k is equal to 0 to 5 . I will have to calculate $\alpha_{1,k}$, because I am in V_1 subspace, so j is equal to 1 . And then square root of 2 into ϕ of twice x minus k . So, this is how my f_1 of x . The projection of my original signal on subspace V_1 is going to look. And what we really are interested in at this point and time, is to really see if I can really match, all the α values that I will obtain numerically, to the α values that I can obtain by adding the α values in V_0 with β values in W_0 . And if I can matchup these values, then I would say oh this is definitely working, and I can really move up the ladder. So, let us calculate the $\alpha_{1,k}$ values.

(Refer Slide Time: 37:59)

$$\begin{aligned}
 \alpha_{1,0} &= \int_{-\infty}^{\infty} f_1(x) \cdot 2^{j/2} \phi(2^j x - k) \cdot dx \\
 &= \int_0^{1/2} x \cdot \sqrt{2} \phi(2x) \cdot dx \\
 &= \sqrt{2} \int_0^{1/2} x \cdot 1 \cdot dx \\
 &= \sqrt{2} \cdot \left. \frac{x^2}{2} \right|_0^{1/2} = \sqrt{2} \cdot \frac{1}{8} \\
 \alpha_{1,0} &= \frac{1}{4\sqrt{2}}
 \end{aligned}$$

And let us begin with α_{10} , and k is equal to 0. And we know the formula minus infinity to plus infinity, and then you have f_1 of x into 2 to the power j by 2, ϕ of. And we are discussing a very special case, when j is equal to 1 and k is equal to 0. So, obviously, I am talking about the first interval that would last from 0 to half, between 0 and half f_1 of x will be equal to x^2 to the power j by 2 would go to square root of 2, and then I am talking about ϕ of twice x k is 0. Now, between 0 and half, what value ϕ of twice x will going to take.

(Refer Slide Time: 39:11)

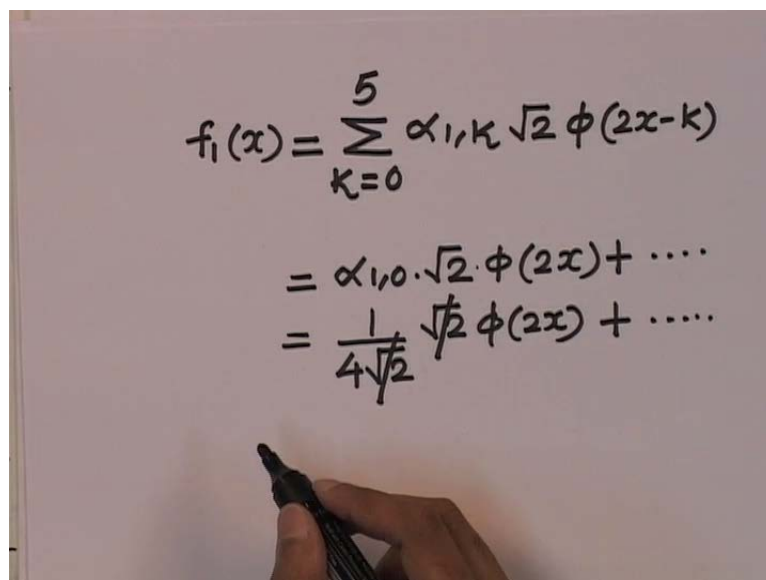


We already know that if my ϕ of x looks like this, then ϕ of twice x is going to be the shrink version of it. And let us not worry about the area under the curve at this point and time, let us worry about the nature, and if we can actually preserve the entire energy or not. So, if this is of my ϕ of twice x is going to look. Then between 0 and half ϕ of twice x is going to take a value of 1, and then I can bring out square root of 2 outside, and this will be integration from 0 to half, x into 1 into dx , and so this will be equal to square root of 2 into x square by 2 between 0 and half, and this will lead us to square root of 2 into 1 upon 8. And probably I can write down a convenient form of the same, and I can say this will be 1 upon 4 square root of 2, essentially the same thing. So, this is how my α_{10} is going to look. Now, let us try and tally this α value, with the geometrical representation that we have over here.

Now, in order to be able to calculate α_{10} , what we will have to do, is to concentrate on the portion between 0 and half, and correspondingly add the α_{00} with β_{00} . Well

alpha 0 0 value is known, and beta 0 0 value is also known. So, what we are saying is, I can calculate alpha 1 0, which will be equal to alpha 0 0 minus. So, I am talking about only the first half of alpha 0 0, plus beta 0 0 minus; that is what we are saying, and we already know these values. So, as far as alpha 0 0 minus is concerned, it is half and as far as beta 0 0 is concerned, it is minus 1 by 4. So, this will eventually lead us to 1 by 4. So, value that we are getting after solving this integration is 1 by 4 square root of 2, but we do not really have to worry about this square root of 2, because this is going to get cancelled out. You remember, we have already done the normalization of our basic functions, and so our basis is not just orthogonal it is also orthonormal. And as a result of that, when I am going to plug-in this alpha 1 0 in the formula, for f 1 of x, this square root of 2 is going to get canceled out, and then this will match up with the value that we have obtained graphically.

(Refer Slide Time: 43:06)

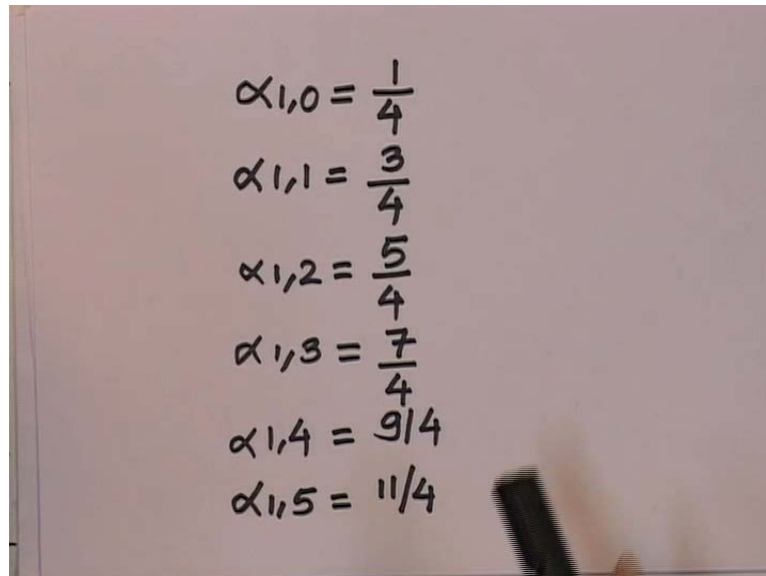


$$\begin{aligned}
 f_1(x) &= \sum_{k=0}^5 \alpha_{1,k} \sqrt{2} \phi(2x-k) \\
 &= \alpha_{1,0} \cdot \sqrt{2} \cdot \phi(2x) + \dots \\
 &= \frac{1}{4\sqrt{2}} \sqrt{2} \phi(2x) + \dots
 \end{aligned}$$

Let see that formula, what I am saying is, I can very well write down f 1 of x to be equal to, summation for k is equal to 0 to 5, and then alpha 1 k values square root of 2 into phi of twice x minus k. So, if you consider the first term in this summation, when k is equal to 0; that is going to be alpha 1 0 into square root of 2 into phi of twice x. And alpha 1 0 that we have calculated is 1 over 4 square root of 2 into square root of 2 into phi of twice x, obviously we have the rest of the series, but I am juts focusing on the first element. And so this square root of 2 will get cancelled with this square root of 2, and will be left with 1 by 4. And this definitely matches with what we have solved in graphically, this is indeed 1 by 4.

Likewise, we can go on finding out the rest of the values of alpha, and convince that it indeed matches up.

(Refer Slide Time: 44:33)



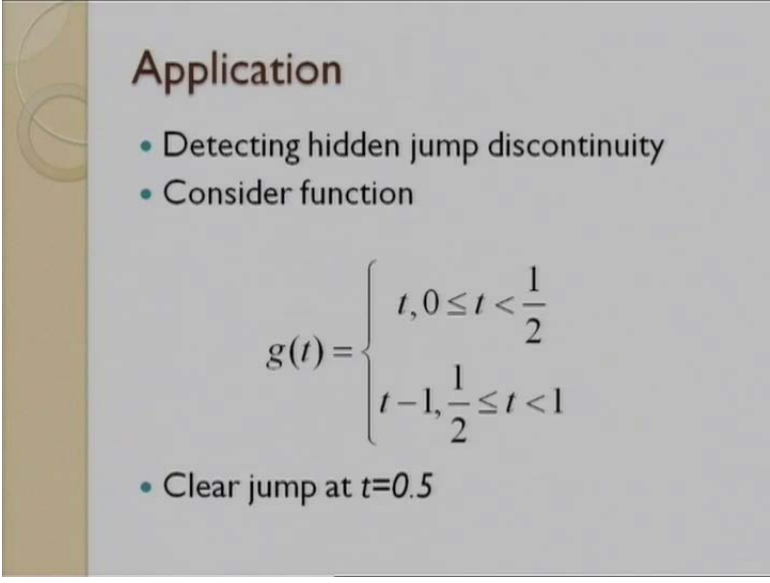
A photograph of a whiteboard with handwritten mathematical expressions. The expressions are arranged vertically and represent the values of $\alpha_{1,k}$ for k from 0 to 5. The handwriting is in black marker.

$$\begin{aligned}\alpha_{1,0} &= \frac{1}{4} \\ \alpha_{1,1} &= \frac{3}{4} \\ \alpha_{1,2} &= \frac{5}{4} \\ \alpha_{1,3} &= \frac{7}{4} \\ \alpha_{1,4} &= \frac{9}{4} \\ \alpha_{1,5} &= \frac{11}{4}\end{aligned}$$

The alpha values in V 1 would look like this; 1 by 4 alpha 1 1 will be 3 by 4 alpha 1 2 will be 5 by 4 alpha 1 3 will be 7 by 4 alpha 1 4 will be 9 by 4, and alpha 1 5 will be 11 by 4. And if I want to plot these values, again on the same graph, now it is going to be interesting, because I am starting with 1 by 4 3 by 4 5 by 4 7 by 4 9 by 4 and 11 by 4, and you will agree that. So, these are my projections in V 1, and it is very easy to see that the approximations; that are obtained in V 1 are much better compare to the approximations those were obtained in V 0. We are able to add some details in V 0 from W 0, and then finally, achieve the projection in V 1. So, this is the mechanism using which, we can not only think of moving up the ladder, but we can also think of making the choice of the scale.

We can think of also making the choice of the translation parameter, and then specifically zoom on to a particular point in my signal or function, which is of greater importance, to really find out something interesting. To convince more on this point, we are going to see another example. We are going to build one function; this function is very specifically design. We are going to understand the beauty associated with this function, and then we will see, what kind of things it will have, when we will try and analyze this function using the wavelet toolbox in matlab.

(Refer Slide Time: 47:22)



Application

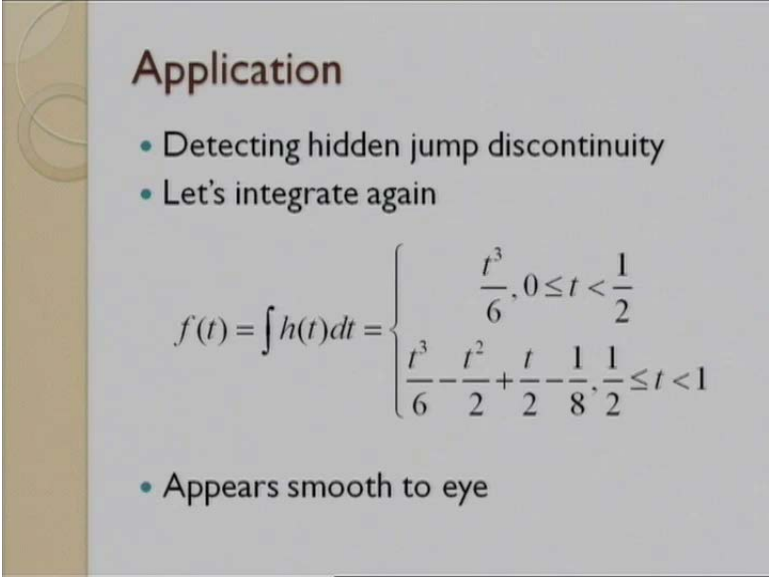
- Detecting hidden jump discontinuity
- Consider function

$$g(t) = \begin{cases} t, & 0 \leq t < \frac{1}{2} \\ t-1, & \frac{1}{2} \leq t < 1 \end{cases}$$

- Clear jump at $t=0.5$

So, if you look at this slide, we will try and find out a hidden jump discontinuity, from a particular function. Let us consider this function; g of t , and looks very interesting, because we can very clearly see, that at half there is a clear discontinuity. Please carefully notice, that t is only less than half, and then over here it is less than or equal to half. So, at half, there is a clear discontinuity that we can notice. However, such kinds of discontinuities are easier to detect. We will complicate the matters slightly, what we will do is, we will integrate that signal g of t , and by virtue of doing the integration, we know that integration essentially is a low pass filtering operation, and we will smooth out that signal. So, the discontinuity, is now not very much visible, however there is still a cusp jump at t is equal to 0.5, and now I virtue of integrating the original signal g of t , this is how the new signal h of t would look. We will complicate the matters further more, and we will integrate h of t as well.

(Refer Slide Time: 48:53)



Application

- Detecting hidden jump discontinuity
- Let's integrate again

$$f(t) = \int h(t)dt = \begin{cases} \frac{t^3}{6}, & 0 \leq t < \frac{1}{2} \\ \frac{t^3}{6} - \frac{t^2}{2} + \frac{t}{2} - \frac{1}{8}, & \frac{1}{2} \leq t < 1 \end{cases}$$

- Appears smooth to eye

We will integrate h of t and finally we will generate f of t . And now this function f of t appears absolutely smooth to our eye, and we may not be able to perceive the discontinuity at point t is equal to half. We will pose this challenging problem to our wavelet toolbox in matlab, and we will see if the toolbox will be able to really find out this discontinuity at t is equal to 0.5. So, this is a simple matlab program that is written. This is how we have declared the timestamps; t_0 is equal to 0 t_1 is half, and we know this is the point where there is discontinuity, and t_2 is equal to 1.

The level of analysis that has been selected is 9, and this is selected out of trial and error and honestly speaking, there is no thumb rule that says to what level one should go, and after doing analysis to what level one should stop. However there is a slight mention of this in the book written by Ingrid Daubechies, which says that if you lose more than seventy percent of the total energy in your signal, then you should actually stop doing further analysis. Based on that we have selected the level to be 9, and this is how the original signal t would look. You can clearly see, that for a given timestamps. The original signal g would look like this, it was t only when t was less than t_1 , and t_1 is 0.5. It was t minus 1 between all the values of t which are greater than t_1 . So, between t_1 and t_2 0.5 and 1, and correspondingly we have generated signals h and f .

Just a gentle reminder that g original signal had a discontinuity at 0.5. We did the integration of that into h and again integrated h to finally get f . So, first of all, lets plot these signals, and

let us see the nature of these signals, and as expected this is my original signal, we can clearly see the discontinuity at 0.5. Then this is the cusp discontinuity, after doing the integration, and after doing the integration of this signal that is double integration of the first signal, there is no visible discontinuity at 0.5. So, this is fairly difficult signal now. Let save this signal. So, I am going to save f , and let save thus this signal as test underscore s i g. And now we can clearly see that there is a mat file called as test underscore s i g dot mat.

We will invoke the wavelet toolbox in mat lab, and we will select the 1 d wavelet. We will load the signal that we have generated, which is test underscore signal. So, this is how the signal actually looks. And now I have freedom of selecting any of these wavelet mothers. Let say we select Daubechies 3, for a level of 9, and we want to carry out the analysis. And you will see a strange thing, at d 1 you can clearly see, that we are able to detect the discontinuity at 0.5. And as we start losing out the information, the crispness of the detection of the discontinuity eventually goes away. Since we have done the entire analysis using Haar wavelets, lets also workout that exercise. So, I am going to select Daubechies 1, which is nothing else, but the first member of Daubechies family and it is Haar.

And if, we do this analysis again, then now you can clearly see that, we are once again able to detect the discontinuity, but with lesser efficiency. So, there is point in selecting the mother wavelet. However, what is striking about this wavelet analysis is, even though we smooth out the function by doing double integration, and now to the naked eye I cannot sense the discontinuity, wavelet transform can still find out such underlying discontinuities. And hence, it makes lot of sense, to invoke the zoom in and zoom out properties of wavelet transform. With this we will conclude this lecture, and we will continue working on, how we can go about generating this scaling function coefficients and wavelet function coefficients in the next lecture. Thank you.