

Plasma Physics and Applications

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Week – 10

Lecture 47: Ion Acoustic Wave - III

Hello dear students. We will continue our discussion on ion acoustic wave from the last class. So in the last class we have derived this expression which is  $n_1$  by  $t$  plus  $n_0 \nabla \cdot U_1$  is equal to 0. So which is the basic continuity equation. Now from the momentum equation we can write  $m_i n_0$  plus  $n_1$  times the convective derivative  $\frac{d}{dt}$  of  $U_0$  plus  $U_1$ . We have taken the advection term to be 0 to begin with is  $-\nabla \cdot \phi_1$  times  $Q n_0$  plus  $n_1$  minus  $\gamma_i$  basically  $\gamma_i k_B T_i \nabla \cdot n_1$ .

So doing the simple algebra of reducing this expression into simpler terms or lesser number of terms we can write  $m_i n_0 \frac{d}{dt} U_1$  plus  $m_i n_1 \frac{d}{dt} U_1$  is equal to  $-\nabla \cdot \phi_1$  becomes  $0 \nabla \cdot \phi_1 n_0$  minus  $\nabla \cdot \phi_1 n_1$ . How did I get this? This is 4 terms to 2 terms.  $\nabla \cdot \phi_0$  becomes 0 and product of this perturbation terms which becomes second order also becomes 0. So, this term also becomes 0.

Why because it is a product of perturbation terms. Product of perturbation terms is considered 0. We neglect it minus  $\gamma_i k_B T_i \nabla \cdot n_1$ . So, we have only one term out of these 4 terms that are being as a product and the  $\gamma_i k_B T_i$  term as it is and this also becomes 0 this becomes. So, this one from our earlier discussion we can write this is equal to  $n_1$  is  $n_0 E \phi_1$  by  $k_B T_i \frac{d}{dt} U_1$  because we already derived that  $n_1$  is  $n_0 E \phi_1$  by  $k_B T_i$ .

So, using this we can write  $M_i n_0 \frac{d}{dt} U_1$  is equal to minus  $E n_0 \nabla \cdot \phi_1$  this one minus  $\gamma_i k_B T_i \nabla \cdot n_1$ . So, this is again a product of second ordered perturbed variables. This can be neglected. So, this term simply becomes 0 or not considered. So, we have this term as it is appearing here and this term and this term.

Let us write the equation for the sake of clarity. So, which is  $m_i n_0 \frac{\partial u_{i1}}{\partial t} = -en_0 \nabla \phi_1 - \gamma_i k_B T_i \nabla n_{i1}$ . Now, we have both the linearized equation. Let us say from here we call it as A and we call this as B. So, we will assume the sinusoidal solutions for the perturbed variables  $n_{i1}$  is oscillating around the mean value  $n_{i1}$  itself to the power of  $i$ .

$$\frac{\partial n_{i1}}{\partial t} + n_0 \nabla \cdot \vec{u}_{i1} = 0 \quad \text{--- (a)} \quad n_{i1} = n_0 \frac{e\phi}{k_B T_e}$$

$$m_i [n_0 + n_{i1}] \left[ \frac{\partial}{\partial t} (u_0 + u_{i1}) + 0 \right] = -\nabla (\phi_0 + \phi_1) q (n_0 + n_{i1}) - \gamma k_B T_i \nabla (n_0 + n_{i1})$$

$$m_i n_0 \left[ \frac{\partial u_{i1}}{\partial t} \right] + m_i n_{i1} \frac{\partial u_{i1}}{\partial t} = -e \nabla \phi_1 n_0 - e \nabla \phi_1 \nabla n_{i1} - \gamma k_B T_i \nabla n_{i1}$$

$$m_i n_0 \left[ \frac{e\phi_1}{k_B T_e} \frac{\partial u_{i1}}{\partial t} \right]$$

$$m_i n_0 \frac{\partial u_{i1}}{\partial t} = -en_0 \nabla \phi_1 - \gamma_i k_B T_i \nabla n_{i1}$$

Let us say we consider only one dimension  $k_x$  minus  $\omega t$  or the  $k$  vector is to be written as  $k_x \hat{i} + k_y \hat{j} + k_z \hat{k}$  and  $R$  is  $x \hat{i} + y \hat{j} + z \hat{k}$ .  $u_{i1}$  is using this in equation A and B. Let us say we call this entire set of equations as C using C in A and B. We can write  $m_i n_0 \frac{\partial u_{i1}}{\partial t} = -en_0 \nabla \phi_1 - \gamma_i k_B T_i \nabla n_{i1}$  times  $i k$ . So, we call this equation as D.

$$m_i n_0 \frac{\partial u_{i1}}{\partial t} = -e n_0 \nabla \phi_1 - \gamma_i k_B T_i \nabla n_{i1} \quad \text{--- (b)}$$

$$\left. \begin{aligned} n_{i1} &= n_{i1} e^{i(kx - \omega t)} \\ u_{i1} &= u_{i1} e^{i(kx - \omega t)} \\ \phi_{1i} &= \phi_{1i} e^{i(kx - \omega t)} \end{aligned} \right\} \text{--- (c)}$$

Using (c) in (a) & (b)

$$m_i n_0 u_{i1} (-i\omega) = -e n_0 (ik) \phi_{1i} - \gamma_i k_B T_i n_{i1} (ik) \quad \text{--- (d)}$$

$$n_{i1} = n_0 \frac{e \phi_{1i}}{k_B T_i}$$

$\hat{k} = k_x \hat{i} + k_y \hat{j} + k_z \hat{k}$   
 $\vec{h} = x \hat{i} + y \hat{j} + z \hat{k}$

Now in this we can substitute  $n_{i1}$  is  $n_0 e \phi_{1i}$  by  $k_B T_i$ . Then we can write it as  $-i \omega m_i n_0 u_{i1}$  is equals to  $-e n_0 i k n_{i1} k_B T_i$  by  $n_0 e$  minus  $\gamma_i k_B T_i n_0 e \phi_{1i}$  by  $k_B T_i$  times  $i k$ . What I have done is I have obtained equation D by substituting the perturbation into this equation into the governing equations which is the momentum equation in this case. So, all of this going into this has given me this equation and into this equation I am substituting  $n_{i1}$  and  $u_{i1}$ . What I have is this.

We can cancel few terms here  $e n_0 k_B T_i k_B T_i$ . What will be left with is  $-i \omega m_i n_0 u_{i1}$  is equals to  $-i k n_{i1} k_B T_i$  minus  $\gamma_i n_0 e \phi_{1i}$  by  $k$ . Let us say we call this equation as in our sequence as equation number. This is the story about the momentum equation. Let us bring the continuity equation by applying the sinusoidal solutions.

We can write  $n_{i1}$  times  $-i \omega$  which is the time derivative  $\frac{d n_{i1}}{d t}$  plus  $n_0 u_{i1}$  times  $i k$  is equals to 0. It simply tells you that  $n_{i1} \omega$  is equals to  $n_0 u_{i1}$  times  $k$ . Substituting for  $n_{i1}$  which is  $n_0 e \phi_{1i}$  by  $k_B T_i$  is equals to  $\omega$  is equals to  $n_0 u_{i1}$  times  $k$ . Which is  $u_{i1}$  is  $e \phi_{1i}$  by  $k_B T_i$  times  $\omega$  by  $k$ . This is equation F.

$$-i\omega m_i n_0 u_{i1} = -e n_0 (ik) n_{i1} \frac{k_B T_e}{n_0 e} - \gamma_i \frac{k_B T_i}{n_0 e} n_0 \frac{e \phi_1}{k_B T_i} ik$$

$$-i\omega m_i n_0 u_{i1} = -ik n_{i1} k_B T_e - \gamma_i n_0 e \phi_1 ik \quad \text{--- (e)}$$

$$\uparrow n_{i1} (-i\omega) + n_0 u_{i1} (ik) = 0$$

$$\underline{n_{i1} \omega = n_0 u_{i1} k}$$

$$n_0 \frac{e \phi_1 \omega}{k_B T} = n_0 u_{i1} k$$

$$\underline{u_{i1}} = \left( \frac{e \phi_1}{k_B T_e} \right) \frac{\omega}{k} \quad \text{--- (f)}$$

Using (f) in (e)

Now using  $u_{i1}$  can be used into this equation into E. So, which is  $u_{i1}$  is still a variable in this equation you see here. In order to simplify or get the dispersion relation we have to eliminate these variables. So,  $u_{i1}$  can be substituted from equation F. So, using F in E the same.

We can write minus  $i\omega m_i n_0 e \phi_1$  by  $k_B T$  times  $\omega$  by  $k$  is minus  $i k n_0 e \phi_1$  by  $k_B T$  times  $k_B T$  minus  $\gamma_i n_0 e \phi_1$  by  $k_B T$  i  $k$ . No, it is not  $e \phi_1$  by  $k_B T$  it is  $e \phi_1$  only. So, this  $n_0$  gets cancelled,  $e \phi_1$  appearing on the left hand side and right hand side gets cancelled. We can now write the equation as minus  $i\omega m_i$  times  $\omega$  by  $k$  is equals to minus  $i k k_B T$  minus  $\gamma_i i k$   $k_B T$ . So, what have we used from the continuity equation and the momentum equation.

$$-i\omega m_i n_0 \left( \frac{e\phi}{k_B T_e} \right) \frac{\omega}{k} = -ik n_0 \left( \frac{e\phi_1}{k_B T} \right) k_B T - \gamma_i n_0 e\phi i k_1$$

$$-i\omega m_i \frac{\omega}{k} = -ik k_B T - \gamma_i i k_1 (k_B T)$$

$$-\frac{\omega^2}{k^2} = \frac{-k_B T_e - \gamma_i k_B T_i}{m_i}$$

$$\frac{\omega}{k} = \sqrt{\frac{k_B T_e + \gamma_i k_B T_i}{m_i}} = \underline{U_s}$$

Doing the simplification so  $i$  will again get cancelled we have minus omega square by  $k$  square is equals to minus  $k_B T_e$  minus  $\gamma_i k_B T_i$  by  $M_i$  or omega square by  $k$  square is square root of  $k_B T_e$  plus  $\gamma_i k_B T_i$  divided by  $M_i$ . At omega by  $k$  it is supposed to be omega by  $k$  not omega by  $k$  square omega by  $k$  is this. So, this is nothing but the velocity. So, this is the dispersion relation for ion acoustic wave which is resembling the speed of sound in a medium. So, we will discuss more consequences of this dispersion relation in the next class. Thank you.