

Plasma Physics and Applications

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Week – 05

Lecture 21: Vacuum Drift

Hello dear students. In today's class we will continue our discussion of obtaining a combined expression for gradient and curvature drifts. So, in the last class we have seen how an expression for gradient drift and curvature drift can be obtained. So, $V_{\perp} \nabla B$ which is the velocity due to gradient of the magnetic field is $\frac{m}{2q} \frac{V_{\perp}^2}{B} \nabla B$ and the curvature drift velocity is $V_{\parallel} = \frac{1}{q} \frac{m}{r_c} \frac{V_{\parallel}^2}{B^2} \nabla B$. So, these two expressions are valid for a realistic magnetic field which means any magnetic field will have a gradient and also a curvature.

Now we are going to combine these two expressions and write the total drift that the particle will experience whenever it enters into a magnetic field. So, if you look at these two the first term seems to be affecting the perpendicular kinetic energy the second term seems to be affecting the parallel kinetic energy. So, we have seen if you consider a particle to have a velocity V so the perpendicular component is this and this is the parallel component. So, $V^2 = V_{\perp}^2 + V_{\parallel}^2$.

Now this discussion is going to be referred to as vacuum drifts. Now in order to combine these two terms the first difficulty is that let us say even if we ignore whatever appears outside the curl in each term we have one curl between ∇B and the grad B and the other term between r_c and B . So, we have to find out a way wherein both of these curls can be written in a similar way. So, to do that we will consider the cylindrical geometry of a magnetic field and we will try to see how these two terms can be written in the same way. So, let us say we consider the magnetic field like this which is curved in nature like this and with respect to the center r_c is the radius of curvature of the magnetic field.

The magnetic field lines are going or curving towards let us say towards the left. You consider a coordinate system such that this direction is phi cap the direction in which the magnetic field lines are going towards is phi cap. This is the radially outward this one is the radially outward direction this let us say we call it as r cap and this is the z cap. So, we have r phi z coordinate system we have r cap phi cap and z cap. If you want to translate it to a Cartesian coordinate system you have to assume that you define the angle phi such that it is increasing when you measure it away from x axis and towards the y axis the positive y axis.

So, you are taking the magnetic field lines along phi. So, they are rotating along parallel to phi. So, this is the equivalent when you draw it to a Cartesian coordinate system. So, we can write the magnetic field B to be equivalent to B phi as a function of r along phi cap. So, what does it mean? magnetic field is along phi cap it is changing along r.

Vacuum Drifts

$$\vec{B} = B_\theta(r) \hat{\theta}$$

$$\vec{\nabla} B = \frac{dB}{dr} \hat{r}$$

$$\left. \begin{aligned} \vec{v}_{\perp} &= \frac{m v_{\perp}^2}{2q} \frac{\vec{B} \times \vec{\nabla} B}{B^3} \rightarrow \omega_{\perp} \\ \vec{v}_{\parallel} &= \frac{1}{q} \frac{m v_{\parallel}^2}{R_c^2} \frac{\vec{R}_c \times \vec{B}}{B^2} \rightarrow \omega_{\parallel} \end{aligned} \right\}$$

The diagram illustrates vacuum drifts in a magnetic field. It shows curved magnetic field lines with a particle path. A vector diagram shows the magnetic field $\vec{B} = B_\theta(r) \hat{\theta}$ in a cylindrical coordinate system with unit vectors $\hat{r}, \hat{\theta}, \hat{z}$. The radial component $B_r = 0$ and the axial component $B_z = 0$. The particle's total velocity \vec{v} is decomposed into a perpendicular component \vec{v}_{\perp} and a parallel component \vec{v}_{\parallel} . The perpendicular velocity is given by $\vec{v}_{\perp} = \frac{m v_{\perp}^2}{2q} \frac{\vec{B} \times \vec{\nabla} B}{B^3}$ and the parallel velocity by $\vec{v}_{\parallel} = \frac{1}{q} \frac{m v_{\parallel}^2}{R_c^2} \frac{\vec{R}_c \times \vec{B}}{B^2}$. The total velocity is $\vec{v}_{\text{Total}} = \vec{v}_{\perp} + \vec{v}_{\parallel}$ and its magnitude is $v^2 = v_{\perp}^2 + v_{\parallel}^2$.

So, it has a gradient along r. So, as you go along r c it is changing its magnitude is changing. So, for instance you take a unit area here or a unit area here the number of flux lines that will cross that will go through this unit area will be different there in indicating a gradient to be present in this direction. So, we write the del B is equals to del B is the magnitude for example is along r cap. So, the magnetic field is directed along phi cap and it is changing along r cap I hope it is clear.

So, if you take such a magnetic field and then we have all the variables we have established what is del B what is r c. So, we are now trying to see how these two terms can be combined into a single expression. So, let us take some hint from the cylindrical coordinate system if you have del cross B you can write del cross B in the cylindrical coordinate system as $\frac{1}{r} \frac{dB_z}{d\theta} - \frac{dB_\theta}{dz}$ all of it along r cap plus $\frac{dB_r}{dz} - \frac{dB_z}{dr}$ along phi cap plus $\frac{1}{r} \frac{dB_r}{d\theta} + \frac{dB_\theta}{dr}$ along z cap.

of r B_ϕ minus $\frac{1}{r} \frac{\partial B_z}{\partial \phi}$ by $\frac{1}{r} \frac{\partial B_\phi}{\partial z}$ along $\hat{\phi}$. So, now the magnetic field is B_r B_ϕ B_z this is the cylindrical components of the magnetic field vector. But what we have made a specific choice of magnetic field which is like it has gradient along the radial component and it is directed towards the ϕ cap.

If you substitute the magnetic field configuration that we have taken we can write. So, if you are wondering how I got this big expression this is from the you can refer to any standard book which gives the curl of a vector quantity in cylindrical coordinates. So, this is the curl of a vector quantity in cylindrical coordinates. This is pretty standard. So, I have just used the form as it is and I have substituted the components of B that I have taken for this picture.

Curl of a vector quantity in cylindrical coordinates

$$\vec{\nabla} \times \vec{B} = \left(\frac{1}{r} \frac{\partial B_z}{\partial \phi} - \frac{\partial B_\phi}{\partial z} \right) \hat{r} + \left(\frac{\partial B_r}{\partial z} - \frac{\partial B_z}{\partial r} \right) \hat{\phi} + \frac{1}{r} \left(\frac{\partial}{\partial r} (r B_\phi) - \frac{\partial B_r}{\partial \phi} \right) \hat{z}$$

$\vec{B} = (B_r, B_\phi, B_z)$

$$\vec{\nabla} \times \vec{B} = \left(\frac{1}{r} (0) - 0 \right) \hat{r} + (0 - 0) \hat{\phi} + \frac{1}{r} \left(\frac{\partial}{\partial r} (r B_\phi) - 0 \right) \hat{z}$$

$$\vec{\nabla} \times \vec{B} = \left[\frac{1}{r} \frac{\partial}{\partial r} (r B_\phi) \right] \hat{z} \leftarrow$$

Maxwell equations

$$\vec{\nabla} \times \vec{B} = \mu_0 \left(\vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)$$

Vacuum $\Rightarrow \vec{\nabla} \times \vec{B} = 0$

So, if I substitute B_r B_ϕ and B_z values according to the configuration that I have described here what I can write is it is going to be $\frac{1}{r}$ times 0. What does it mean? B_z has no variation along ϕ along the ϕ direction it is not varying that is why the derivative is 0 minus 0 and B_ϕ is also not varying along z direction plus. Just try to match each of these and so that we can understand what is going on. You see this you go back one thing is very clear magnetic field component B_r has a variation B_r changes when r changes it can be it need not be directly proportional, but B_r has a variation, but B_r has a variation B_r changes when r changes and B_ϕ is not changing it is a constant thing. So, B_ϕ is not changing when r is changing when ϕ is changing when z is changing and B_z is itself is 0 actually.

So, if you bring this into the picture so you see $\frac{1}{r} \frac{\partial B_z}{\partial \phi}$ is 0 because that means the z component of the magnetic field itself is 0. So, there is no point of taking a derivative with respect to ϕ B_ϕ $\frac{\partial B_\phi}{\partial z}$ with respect to z with respect to z of course it is not changing that is why it is 0 B_r by B_z $\frac{\partial B_r}{\partial z}$ B_r by $\frac{\partial B_z}{\partial r}$. So, the radial component of the magnetic field of course does not have any variation with respect to

the z coordinate. So, just for ready reference I am drawing the coordinate system here. So, this direction is phi cap out of the board is z cap and this is r cap and

r
B
z
itself
is
0.

$$\nabla \times \vec{B} = \frac{1}{r} \frac{\partial}{\partial r} (r B_\phi) = 0$$

$$\Rightarrow r B_\phi = \text{Constant} = k$$

$$\Rightarrow B_\phi = \frac{k}{r}$$

$$\frac{\partial B_\phi}{\partial r} = -\frac{k}{r^2} = -\frac{B_\phi}{r} \Rightarrow \boxed{B_\phi = \frac{k}{r} \hat{\phi}}$$

at $r = R_c$

$$\boxed{B_\phi = \frac{k}{R_c} \hat{\phi}}$$

Ratio

$$\frac{\nabla |B|}{|B|} = \frac{-\frac{k}{R_c^2} \hat{R}_c}{\frac{k}{R_c}}$$

So, the derivative will obviously be 0. B phi is of course r B phi is changing with respect to r why because so if you take B phi is a coordinate which is going here B phi is this component. So, if you take different values of r and measure B phi you will get different B phi different magnitudes. So, that means that B phi is changing with respect to r. So, that is why I have retained this derivative as it is and the radial component of the magnetic field is not changing with respect to phi.

So, at any value of phi B r will be constant. So, B r this will be 0. So, this is the breakdown of all the terms inside this curve. So, simplifying we will write it simply as del cross B is equals to 0 0 1 by r dou by dou r of r B phi and this entire thing is along z cap. Now from the Maxwell equation we can write del cross B is mu naught J plus epsilon naught dou E by dou t.

$$\frac{\nabla |B|}{|B|} = \frac{-\frac{k}{R_c} \hat{R}_c}{\frac{k}{R_c}} = -\frac{\hat{R}_c}{R_c} = -\frac{\vec{R}_c}{R_c^2}$$

$$\Rightarrow \nabla |B| = |B| \left(\frac{-\vec{R}_c}{R_c^2} \right) \quad \text{--- (1)}$$

$$\hat{R}_c = \frac{\vec{R}_c}{|R_c|}$$

$$v_{\nabla B} = \pm \frac{1}{2} \frac{v_{\perp} R_L}{B^2} (\vec{B} \times \nabla B)$$

$$v_{\nabla B} = \mp \frac{1}{2} \frac{v_{\perp} R_L}{B^2} \vec{B} \times |B| \frac{\vec{R}_c}{R_c^2} \quad [\text{Using (1)}]$$

$$v_{\nabla B} = \mp \frac{1}{2} \frac{v_{\perp}}{B} \left(\frac{m v_{\perp}}{q B} \right) \frac{\vec{B} \times \vec{R}_c}{R_c^2}$$

$$v_{\nabla B} = \mp \frac{1}{2} \frac{v_{\perp}^2}{\omega_c B} \frac{\vec{B} \times \vec{R}_c}{R_c^2}$$

So, this is what we know from the Maxwell equation, but for the configuration of the magnetic field that we have considered we have realized that $\nabla \times B$ is equal to this. Now let us say we consider vacuum where there is no free current density, there is no electric field. So, in that case we can write $\nabla \times B$ the curl of magnetic field will be 0 in vacuum because we will say that there are no current densities which can create a magnetic field. So, in that case what we can do is Maxwell equations in vacuum expect or require $\nabla \times B$ is equals to $\frac{1}{r} \frac{d}{dr} (r B \phi)$ is equals to 0 or we can infer that $r B \phi$ is going to be a constant as long as you are trying to look at the change along r . So, we can write which implies $B \phi$ let us say we assume this constant to be k . $B \phi$ is equals to k by r .

Now if $B \phi$ is k by r $\frac{d}{dr} (B \phi)$ is equals to $-\frac{k}{r^2}$ that is equals to $-\frac{B \phi}{r}$. So, just look at this $B \phi$ the rate of change of $B \phi$ with respect to r is equals to $-\frac{k}{r^2}$. So, as you increase the value of r what is happening to the $B \phi$ we can refer to that $B \phi$ is decreasing. So, this is a minus. That means that you have the gradient how do you have the gradient? Gradient is in this direction as you are moving in this direction with increasing r $B \phi$ is going to be smaller.

$$\vec{v}_{\nabla B} = \frac{1}{2} \frac{v_{\perp}^2}{\omega_c B} \frac{\vec{B} \times \vec{R}_c}{R_c^2}$$

$$= \frac{1}{2} \frac{m v_{\perp}^2}{q B^2} \frac{\vec{B} \times \vec{R}_c}{R_c^2}$$

$$\vec{v}_{\nabla B} = \frac{v_{\perp}}{q B^2} \cdot \frac{\vec{B} \times \vec{R}_c}{R_c^2} \quad \text{--- (2)}$$

$$\vec{v}_R = \frac{m v_{\parallel}^2}{q B^2} \cdot \frac{\vec{R}_c \times \vec{B}}{R_c^2} \quad \text{--- (3)}$$

(2) & (3) can be combined

$$v_{\text{total}} = \frac{m}{q} \left[v_{\parallel}^2 + \frac{v_{\perp}^2}{2} \right] \frac{\vec{R}_c \times \vec{B}}{R_c^2 B^2}$$

So, as you move larger distances you will encounter smaller values of B which means that your magnetic field was strong in the beginning or you can simply infer that the gradient is in this direction ∇B is in this direction. So, this is one inference that comes directly out of this. We now have a form for the magnetic field along this particular direction. So, B is equal to which implies we can write B is equal to k by r phi cap. So, all the description that we have taken in the beginning is very well agreeing with the form of magnetic field that we have obtained.

Something that is a clear validation is it is along phi cap and it is k by r . So, with increasing distance of r the magnitude of B phi is changing or decreasing. Let us say at r is equal to r_c we can write B phi is equal to k by r_c along phi cap. Let us say we at r is equal to r_c this is the value. Now let us take a ratio we are just considering a ratio which we will probably use in some other form.

Let us say we have a ratio of ∇B by $\text{mod } B$ which is equal to using this B phi relation we can write it is minus k by r_c square along r_c cap by k by r_c . Let us say we take this

further what is ∇B by $\text{mod } B$ is equals to $\frac{r}{c}$ is equals to $\frac{r}{c}$. It is quite obvious you see ∇B being directed along r cap but not ϕ cap that is the basic nature B ϕ is along ϕ cap but ∇B has to be along r cap or at r c it is along r c cap. So, upon algebraic simplification we will get it as $\frac{-r}{c}$ cap divided by r c or if you use the definition of a unit vector r c cap is r c vector divided by $\text{mod } r$ c we can write it as $\frac{-r}{c}$ by r c square. So, from this ratio we can write $\text{grad } B$ as B times $\frac{-r}{c}$ by r c square.

So, this is what we are going to use further. So, we have $V \nabla B$ from the earlier expression plus $\frac{1}{2} V$ perpendicular r L by B square times B cross ∇B . How you may ask? This is the relation that we have already derived B cross ∇B . Now, using ∇B for this formula we can write V from this ratio let us say we call this as equation number 1 equals to $\frac{-1}{2} V$ perpendicular r L by B square times B cross $\text{mod } B$ r c by r c square. What have I done? I have using equation 1.

So, $\nabla V \nabla B$ is now going to be $\frac{1}{2} V$ perpendicular r L is m V perpendicular by q B B cross r c by r c square. And you have one more B V perpendicular by B or $V \nabla B$ is equals to $\frac{1}{2} V$ perpendicular square divided by ω c times B cross r c by r c square. So, this is using 1. So, we have $V \nabla B$ is equals to $\frac{1}{2} V$ perpendicular square divided by ω c B B cross r c by r c square. So, this m by q B is what is written as ω c.

For if you are confused how did I get ω c is how I get it. Now going back so let us say we use this relation $V \nabla B$ is equals to $\frac{1}{2} V$ perpendicular square by ω c B times B cross r c by r c square. Rearranging the terms again we will get $\frac{1}{2} m$ V perpendicular square by q B square times B cross r c by r c square. So, this is W perpendicular the perpendicular kinetic energy by q B square into B cross r c by r c square. Now if you remember the earlier expression for the curvature drift.

So, now we had this B cross ∇B what we have done by considering this geometry and making appropriate substitutions we have written B cross ∇B in terms of as B cross r c. So, that it matches with our expression for the curvature drifts. Now we will bring the curvature drift V r is equal to $\frac{1}{2} m$ V parallel square by q B square times r c cross B by r c square. So, we can now let us say we call this equation as 2 and 3. Now we can combine 2 and 3 can be combined and we write V total this is vacuum drifts this is going to be written as $\frac{1}{2} m$ by q times V parallel square plus V perpendicular square by 2 times r c cross B divided by r c square B square.

So, this is the total drift that the particle experiences when it sees a realistic magnetic field. This expression is also referred to as the total drift or vacuum drift why because we have taken $\nabla \times B$ as 0 which is valid for vacuum when there are no additional

current densities and electric fields. Now if you consider this to be the total velocity in the particle experience you can see that this total velocity V_{total} depends on the mass of the particle and also depends on the charge 1 by $q B$ cell. So, different polarities of charges will experience drifts in different directions. So, this is the discussion about combining both the drifts which are curvature and gradient drifts. Thank you.