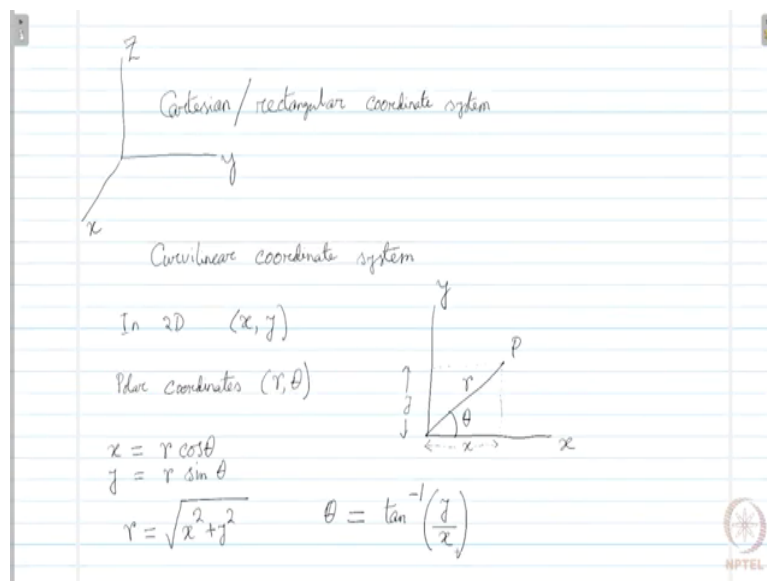


Electromagnetism
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Lecture – 16
Generic curvilinear coordinates systems: Unit vectors and components

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Now, this is the simplest possible curvilinear coordinate system and this is in 2 dimension, but mostly we will deal with 3 dimensional systems. So, we need to go for curvilinear coordinate systems and we need to introduce it in a general fashion.

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Unit vectors in a curvilinear coordinate system

$$\vec{r} = x\hat{x} + y\hat{y} + z\hat{z} \rightarrow \text{Point P in space}$$


$$\vec{r} = \vec{r}(u_1, u_2, u_3)$$

$$\frac{\partial \vec{r}}{\partial u_1} \quad \text{Direction of the tangent vector} \quad \frac{\frac{\partial \vec{r}}{\partial u_1}}{\left| \frac{\partial \vec{r}}{\partial u_1} \right|} = \hat{e}_1$$

$$\frac{\partial \vec{r}}{\partial u_1} = h_1 \hat{e}_1 \quad h_1 = \left| \frac{\partial \vec{r}}{\partial u_1} \right|$$

$$\hat{e}_2, \hat{e}_3$$

$\vec{\nabla} u_1$ is normal to the surface $u_1 = C_1$

$$\hat{E}_1 = \frac{\vec{\nabla} u_1}{|\vec{\nabla} u_1|}; \quad \hat{E}_2 = \frac{\vec{\nabla} u_2}{|\vec{\nabla} u_2|}; \quad \hat{E}_3 = \frac{\vec{\nabla} u_3}{|\vec{\nabla} u_3|}$$


So, we need to first understand how to find out unit vectors in a curvilinear coordinate system. So, if we consider in 3 dimension a vector given by $\vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$, then and if it represents a point P in space then we know \hat{x} , \hat{y} and \hat{z} these are the unit vectors, along x , y and z direction. Now, if we consider that the same vector \vec{r} is represented in a curvilinear coordinate system as a function of u_1 , u_2 and u_3 three coordinates.

And we can consider a tangent vector to the u_1 curve at point P for which u_2 and u_3 are constant; that means, we are talking about $\frac{\partial \vec{r}}{\partial u_1}$ this would be a tangent vector in the u_1 coordinate on the curve represented by \vec{r} and the direction of this tangent vector, can be given as $\frac{\partial \vec{r}}{\partial u_1}$ over the magnitude of $\frac{\partial \vec{r}}{\partial u_1}$ like this.

And this can be called the first unit vector e_1 and; that means, if we have h being h_1 being the first coordinate then $\frac{\partial r}{\partial u_1}$ can be written as $h_1 e_1$ unit vector; that means, h_1 is given as the absolute value of $\frac{\partial r}{\partial u_1}$ this.

Similarly, we can find e_2 and e_3 using the tangents from u_2 and u_3 curves at point P ; and then we have all the unit vectors. Now, we can consider that we can consider the gradient of u_1 this is a vector at P that is normal to the surface $u_1 = c_1$.

So, this is the gradient of u_1 this vector is normal to the surface $u_1 = c_1$. Then a unit vector along this direction can be given as capital E_1 unit vector is the gradient of u_1 over the absolute value of the gradient of u_1 like this. Similarly, E_2 and E_3 ; I mean capital E_2 and capital E_3 can be written as gradient of u_2 over the absolute value of gradient of u_2 .

And E_3 equals gradient of u_3 over the absolute value of the gradient of u_3 , we can write it this way. So, these capital E_1 capital E_2 capital E_3 ; these are normal's these are unit vectors normal to the surface while small e_1 small e_2 and small e_3 these are unit vectors tangential to the surface.

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$$\vec{A} = A_1 \hat{e}_1 + A_2 \hat{e}_2 + A_3 \hat{e}_3 = a_1 \hat{E}_1 + a_2 \hat{E}_2 + a_3 \hat{E}_3$$

$$\vec{A} = c_1 \frac{\partial \vec{r}}{\partial u_1} + c_2 \frac{\partial \vec{r}}{\partial u_2} + c_3 \frac{\partial \vec{r}}{\partial u_3} = c_1 \vec{\alpha}_1 + c_2 \vec{\alpha}_2 + c_3 \vec{\alpha}_3$$

$$\vec{A} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 = c_1 \vec{\beta}_1 + c_2 \vec{\beta}_2 + c_3 \vec{\beta}_3$$

If we want to represent a vector, given by a vector \vec{a} can be represented in terms of the unit vector \hat{e}_1 , \hat{e}_2 , \hat{e}_3 or capital E_1 , E_2 , E_3 in terms of \hat{e}_1 , \hat{e}_2 , \hat{e}_3 ; it would be $A_1 \hat{e}_1 + A_2 \hat{e}_2 + A_3 \hat{e}_3$.

Similarly, in terms of capital E_1 , E_2 , E_3 we are using \hat{e}_1 , \hat{e}_2 , \hat{e}_3 and capital E_1 , E_2 , E_3 . I will in a minute explain what that means, we can represent it this way where small capital A_1 , A_2 , A_3 or small a_1 , a_2 , a_3 ; a_1 , a_2 , a_3 . These are the components of \vec{a} in each system and how we have found out the system one was from the partial derivative of the position vector with respect to u_1 , u_2 , u_3 .

And the other one was from the absolute value of the gradient of the unit vector. Sorry, absolute value of the gradient of u_1 , u_2 , u_3 that way we found these components we can write it in any of the ways. In other words, we can represent \vec{A} as in the first notation here, C

$\frac{1}{r} \frac{\partial u_1}{\partial r} + C_2 \frac{\partial u_2}{\partial r} + C_3 \frac{\partial u_3}{\partial r}$ that is $C_1 \alpha_1$ vector plus $C_2 \alpha_2$ vector plus $C_3 \alpha_3$ vector.

And in so, this is this notation here and the other notation would be like we are writing it here, A is given as C_1 of course, these C_1 and this C_1 are not equal; gradient of u_1 plus C_2 gradient of u_2 plus C_3 gradient of u_3 . That is equal to $C_1 \beta_1$ plus $C_2 \beta_2$ plus $C_3 \beta_3$.

So, we have found out how unit vectors are calculated and so, these capital $C_1 C_2 C_3$ that we have obtained in this notation the first notation are called the contra variant components, while the small $C_1 C_2 C_3$ that we have found in the second approach is called the covariant components.