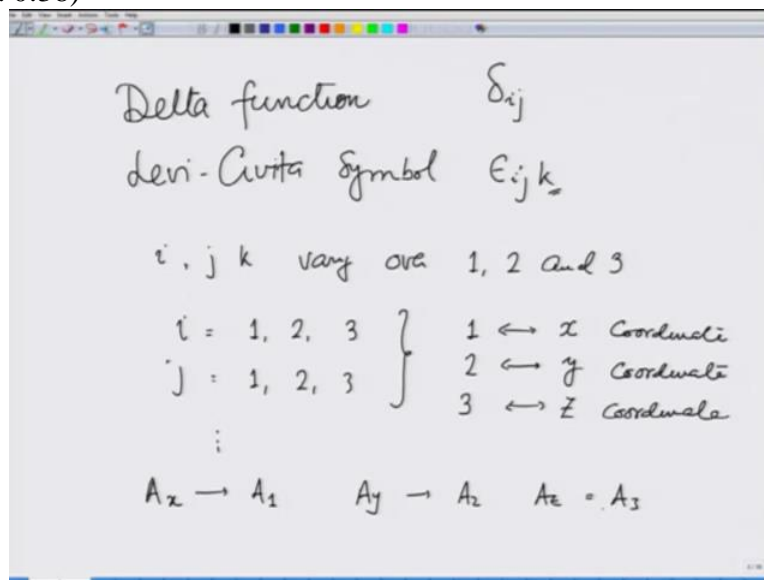


Engineering Mechanics
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Module 1
Lecture No 07
Kronecker Delta and Levi-Civita symbols-I

So far we have looked at vector operations like vector sum, subtracting a vector from another vector, and product of vectors. In this lecture, we are going to look at how symbolically right in a compact way and I am going to introduce something called the delta function.

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And Levi-Civita symbol. This I am going to denote as Delta IJ and this I am going to denote as IJK where I, J or K vary over 1, 2 and 3. That means I could take values 1, 2 or 3, J could take values 1, 2 and 3 and so on. So any any subscript that I use here can take values 1, 2, and 3 and we are going to denote 1 we are going to use 1 for X coordinate, 2 for Y coordinate and 3 for Z coordinate.

So just to make you familiar, for example I am going to write AX for a vector as A1, AY as A2 and AZ as A3. Writing in terms of 1, 2 and 3 makes life easy when we want to express quantities in a compact form.

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$$\vec{A} = \sum_i A_i \hat{e}_i \text{ where}$$
$$\hat{e}_i \rightarrow \text{Unit vector in } i^{\text{th}} \text{ direction}$$
$$\vec{A} = \sum_{i=1,2,3} A_i \hat{e}_i = A_1 \hat{e}_1 + A_2 \hat{e}_2 + A_3 \hat{e}_3$$
$$= A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$x \rightarrow 1$
 $y \rightarrow 2$
 $z \rightarrow 3$

$i, j, k, l, m = 1, 2, 3$

So for example vector A then could be written as summation $\sum A_i \hat{e}_i$ where \hat{e}_i 's unit vector in i^{th} direction. So you can see that if I expand it, it will be summation $\sum_{i=1,2,3} A_i \hat{e}_i$ and that becomes $A_1 \hat{e}_1 + A_2 \hat{e}_2 + A_3 \hat{e}_3$ which when translated into our regular language of X, Y and Z it will become $A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$. So this is just getting used to it that I am going to denote X as 1 I am repeating it, Y as 2 and Z as 3.

And any symbol subscript I, J, K, L, M, all of these vary over 1, 2 and 3. So let me now introduce the delta symbol and Levi-Civita symbol.

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$$\delta_{ij} = 1 \text{ if } i=j$$
$$\delta_{ij} = 0 \text{ if } i \neq j$$
$$\delta_{11} = 1 \quad \delta_{12} = 0 \quad \delta_{13} = 0$$
$$\delta_{21} = 0 \quad \delta_{22} = 1 \quad \delta_{23} = 0$$
$$\delta_{31} = 0 \quad \delta_{32} = 0 \quad \delta_{33} = 1$$
$$\delta_{ij} = 0 \text{ if } i \neq j$$
$$[\delta] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

1st the delta symbol. Delta IJ is going to be defined as it is going to be 1 if I equals J. That means Delta 11 is 1, delta 12 we will see, delta 13 we will see what it is, delta 22 we will see what it is, delta 33 is 1, delta 23, delta 21 and delta 31 and delta 32. So this part we have taken care of by writing delta 11 equals 1, delta 22 equals 1, delta 33 equals 1. And if delta delta IJ is equal to 0, if I is not equal to J.

And therefore, all these terms are going to be 0. If I were to present this delta symbol as a matrix, it's going to be 1, 0, 0, 0, 1, 0, 0, 0, 1. This is delta matrix if you like. So this is an identity matrix. How does it help?

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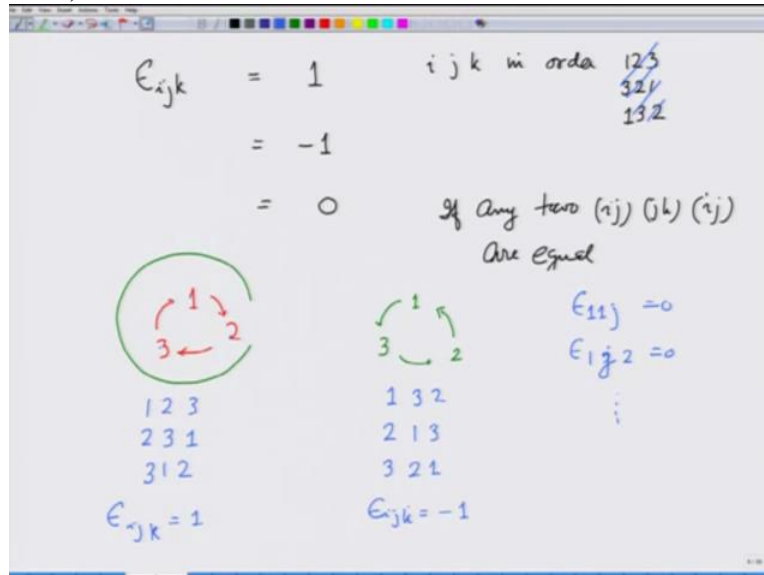
The image shows a handwritten derivation of the dot product of two vectors \vec{A} and \vec{B} . The derivation starts with the standard Cartesian form: $\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$. This is then written in index notation as $A_1 B_1 + A_2 B_2 + A_3 B_3$. Next, it is expressed as a summation over the index i : $\sum_i A_i B_i$. A boxed equation shows the dot product as a double summation over indices i and j : $\vec{A} \cdot \vec{B} = \sum_i \sum_j \delta_{ij} A_i B_j$. Below this, the double summation is expanded into three terms: $\sum_j \delta_{1j} A_1 B_j + \sum_j \delta_{2j} A_2 B_j + \sum_j \delta_{3j} A_3 B_j$. Finally, it simplifies back to the Cartesian form: $A_1 B_1 + A_2 B_2 + A_3 B_3$.

Let us look at that now. If I take A dot B, recall from earlier exercises or earlier lectures that this is nothing but $A_x B_x + A_y B_y + A_z B_z$ which I can write as $A_1 B_1$ in our new notation + $A_2 B_2$ + $A_3 B_3$ which I can also write as summation $\sum A_i B_i$. And in terms of Delta symbol I can write this as summation over I summation over J delta IJ $A_i B_j$.

So this is A dot B. You can very easily see that it actually is the same thing as $A_x B_x + A_y B_y + A_z B_z$. Let us do that just to get more familiar with it. So I have summation over J delta 1J $A_1 B_j$ + I is 2. So that is going to be summation over J delta 2JK $A_2 B_j$ + summation over J I equals 3 delta 3JA $A_3 B_j$. When J is one, I get delta 11 in the 1st term. Let us look at this term, J is 1, I get 1.

So I get A1B1. When J is 2, delta 12 is 0, delta 13 is 0. So the only contribution for the 1st term that comes is A1B1. Similarly in the 2nd term when J is 1, delta 21 is 0. When J is 2, delta 22 to 0. So I get A2B2. + in the last term similarly I get A3B3. So you can say this is a very compact way of writing a dot product.

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A more useful symbol is what I am going to define now, I, J and K. Again, I, J and K vary over 1, 2 and 3. This is equal to 1 or - 1 or equal to 0 depending on how I, J and K combine. So if I have I, J, K in order 1, 2, 3 or its cyclic order, that means 3, 2, 1 or 1, 3, 2, then is going to be 1. This in the other order is going to be - 1 and 0 if any 2 IJ or JK or IJ are equal.

If you find it a little difficult to remember, now let me give you a trick. Let us write, we will take a different colour 1, 2 and 3 in clockwise fashion. And let us also write this in counterclockwise fashion 1, 3, 2, traverse this in counterclockwise way. If 1, 2, 3 appear in any order of this circle, that means if I have 1, 2, 3 or 2, 3, 1, 2, 3, 1, or 3, 1, 2. So this was wrong.

Then I am going to have epsilon I, J, K equal to 1. If I am on the other hand 1, 3, 2 or 2, 1, 3 or 3, 2, 1, then I am going to have Epsilon I, J, K equals - 1. And Epsilon 11 J is 0 no matter what J is. Epsilon 1J2 30 and so on. So you can see very easily that this is a very easy way of remembering it. You put 1, 2, 3 if you are going clockwise. Put it like a clock 1, 2 and 3.

If you are going clockwise, any combination, 1, 2, 3, 3, 2, 1, 2 or 2, 3, 1 gives you Epsilon I, J, K equal to 1. And any counterclockwise combination, 1, 3, 2, 2, 1, 3 or 3, 2, 1 gives you -1 and rest 0.

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$$(\vec{A} \times \vec{B})_i = \sum_{j,k} \epsilon_{ijk} A_j B_k$$

$$j = 1, 2, 3 \quad , \quad k = 1, 2, 3$$

$$(\vec{A} \times \vec{B})_1 = \sum_{j=1,2,3} \sum_{k=1,2,3} \epsilon_{1jk} A_j B_k$$

$$= \sum_k \epsilon_{12k} A_2 B_k + \sum_k \epsilon_{13k} A_3 B_k$$

$$= \epsilon_{123} A_2 B_3 + \epsilon_{132} A_3 B_2$$

$$= A_2 B_3 - A_3 B_2$$

$$= A_y B_z - A_z B_y$$

So now I am going to express the cross product. If I take A cross B, it is Ith components, I could be 1, that is X component, I could be 2, that is Y component, I could be 3, that is Z component is going to be expressed as summation over J and K Epsilon IJKAJBK where J equals 1, 2 or 3. So I am going to sum over 1, 2 and 3 and K also equals 1, 2 or 3. Let us see that. Let us calculate A cross B component 1.

That means I am going to calculate component number X component of this which is going to be summation J equals 1, 2 and 3 summation K1, 2 and 3 Epsilon 1JK AJBK. Let us expand this. If J equals 1, J is 1. If J is 1, for J equals 1, Epsilon 11K is 0. So J could be either 2 or 3 only. So I am going to have Epsilon 12K summed over K I have taken J equal to 2 A2BK for J could be 3. So summation J is 3 and K would be 1, 2 and 3 Epsilon 13KA3BK.

Now, so we have done the sum over J using the fact that Epsilon 11K is 0. Right? So now if I look at Epsilon 1, 2 and K, that is this term. If K is 1, this is 0 because Epsilon 121 is going to be 0. So the only term that I am left with is 1 2 3A2B3 + Epsilon again the 2nd term 13K. If K is one, it is 0. If K is 3, it is 0. So only choice I have is 1, 3, 2A3B2. Now 1, 2, 3, let us make again our 1, this is a clock 1, 2, 3. If I go this way it is 1, 1, 2, 3.

If I go this way, it is - 1. So Epsilon 1, 2, 3, I am going clockwise. So it is going to be 1 so it becomes K2B3. 1, 3, 2 is the other way. So that is going to be - A3B2 which is nothing but AYBZ - AZBY which the correct answer. So you can see by using the symbol I can very easily express all components in one simple formula like this. And then we are going to use the properties of these 2 proved various relationships.

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$$\sum_i \epsilon_{ijk} \epsilon_{ilm} = \epsilon_{1jk} \epsilon_{1lm} + \epsilon_{2jk} \epsilon_{2lm} + \epsilon_{3jk} \epsilon_{3lm}$$

$$= \delta_{jl} \delta_{km} - \delta_{jm} \delta_{kl}$$

One property that we are going to use is going to be Epsilon IJK Epsilon ILM sum over I. That means if I take Epsilon 1 JK Epsilon 1 LM + Epsilon 2 JK Epsilon 2 LN + Epsilon 3 JK Epsilon 3 LN, it is going to be equal to and I am summing over I, so I have summed over I, delta JL delta KM - delta JM delta KL. What I have done is, I have taken J and L in the 1st term and K and M, made their delta symbols, put them here.

Then I took the other combination, that is JM and KL, put a - sign can put the other delta functions. This is a very useful identity. So let us now see how these definitions or expressing vectors like this.