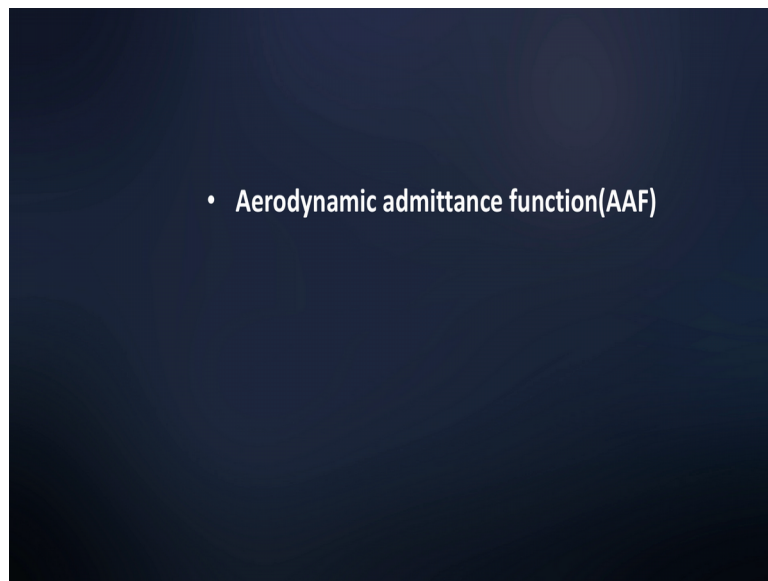


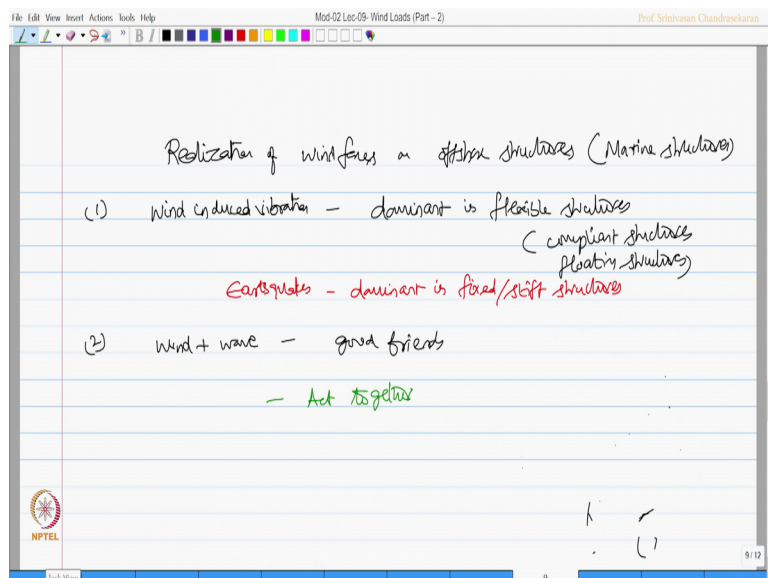
Computer Methods of Analysis of Offshore Structures
Prof. Srinivasan Chandrasekaran
Department of Ocean Engineering
Indian Institute of Technology, Madras

Module - 02
Lecture - 09
Wind Loads (Part - 2)

(Refer Slide Time: 00:17)



(Refer Slide Time: 00:27)



Now, as applicable to marine structures or offshore structures, let us talk about one important point called Realization of wind forces on offshore structures. I mean to some extent we can say this as marine structures also is applicable to coastal structures as well, you can even say this. We have learnt about earthquake as important source in terms of environmental loads, you know wind induced vibrations are actually dominant in flexible structures.

As far as offshore structures are concerned, they are very important in compliant structures, floating structures etcetera just for comparison earthquakes, just for comparison earthquakes are dominant in fixed structures or stiff structures. Most bothering feature is that wind and wave are actually good friends, why because they generally act together.

(Refer Slide Time: 02:03)

File Edit View Insert Actions Tools Help Mod 02 Lec 09 - Wind Loads (Part - 2) Prof. Srinivasan Chandrasekaran

(1) $v = \bar{v} + v(t)$

(2) wind produces low frequency excitation

(3) Gust component is generally modelled probabilistically

(4) Drag force on the members - will be due to wind + waves
 (waves also create inertia force)
 earth quake - create only inertia force (no drag force)

Vibrations caused by (wind + waves) are different from that caused by earthquakes

(5) for design purposes, most codes consider wind as quasi-static process.

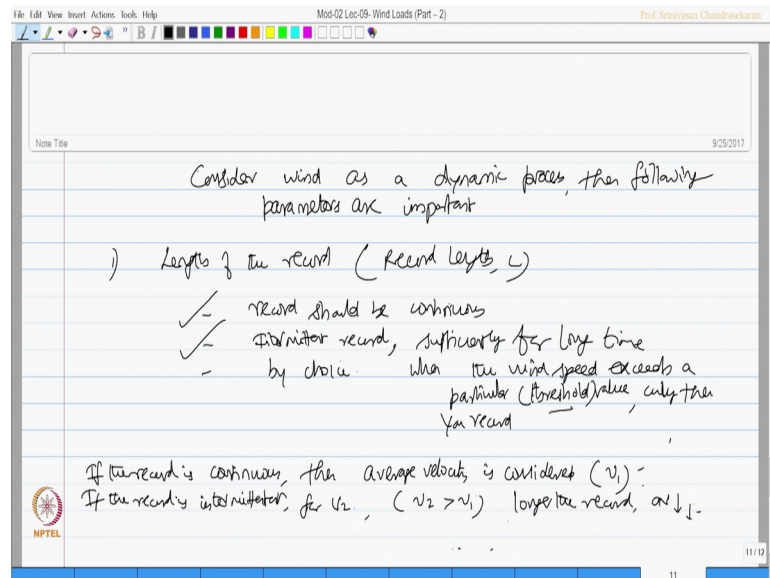
(6) slender structures are wind prone (flexible structures are wind prone)

NPTEL 10/12

So, let us understand few terminologies we know v is now going to be v star plus v of t , the second issue is it is got 2 components the main component and the gust component. We also understand that wind produces low frequency excitation, the third component which is very important the third point is the gust component is generally modeled probabilistically. The fourth point which is important is drag force on the members will be due to wind and wave, waves also create inertia of earth quakes create only inertia force no drag force.

Therefore vibrations caused by wind and waves are different from that caused by earthquakes. The good news is that for design purposes, most of the codes consider wind as quasi static process, but we should remember an important point slender structures are wind prone. So, flexible structures you can say are wind sensitive.

(Refer Slide Time: 04:11)



Suppose if we want to consider wind as dynamic process not as a quasi static process, consider wind as a dynamic process then following parameters are important. One length of the record we can also call this as record length. So, record should be continuous that is one option, can also make intermittent record got sufficiently for long time. Sometimes they are also measured depending upon the choice that is when the wind speed exceeds a particular let us say threshold value, only then you record.

So, recording has got different options it can be continuous it can be intermittent and constant interval, let say every ten seconds every one minute you can record you can also do it by choice right you keep on measuring when the wind speed exceeds its threshold value you record otherwise you do not. If you have a record continuous if the record is continuous, then you take an average is considered for the design.

Let us say that average is v_1 , if the record is intermittent let say the velocity is for v_2 it is seen that v_2 is generally greater than v_1 because longer the record average will be lower ok.

(Refer Slide Time: 06:11)

(2) Average time - is the time @ which the record is averaged

(3) Wind spectrum - input for analysis
- defines the fluctuating component of the wind load

(4) Cross-spectrum - to indicate the spatial dependence

↑ z → x ↓ y

- This is compromised - Aerodynamic admittance function (AAF)

(i) to bypass the rigorous random vibration theory
(ii) AAF can be obtained experimentally, with better accuracy

Second is the average time; average time is the time at which the record is averaged the third factor is a input. So, wind spectrum is an important input for analysis, actually this defines the fluctuating component of the wind load.

The forth one could be something called cross spectrum. Cross spectrum is actually to indicate the spatial dependence of wind velocity along height, along x and along y. It becomes a three dimensional variation will difficult to handle. So, this is compromised in analysis by using aerodynamic admittance function. There are 2 reasons why aerodynamic admittance function is being used; one reason is it is to bypass the rigorous random vibration theory, second AAF can be obtained experimentally with better accuracy.

(Refer Slide Time: 08:11)

AAF - better Quantified

$$F_w(t) = \frac{1}{2} \rho C_d A v^2$$

$$= \frac{1}{2} \rho C_d A (\bar{v} + v(t))^2$$

$$= \frac{1}{2} \rho C_d A \{ \bar{v}^2 + v(t)^2 + 2 \bar{v} v(t) \}$$

we also know that $\bar{v} \gg v(t)$. neglect $v(t)^2$.

$$F_w(t) = \frac{1}{2} \rho C_d A \{ \bar{v}^2 + 2 \bar{v} v(t) \}$$

$$= \frac{1}{2} \rho C_d A \bar{v}^2 + \rho C_d A \bar{v} v(t)$$

steady mean drag force $\equiv F_w$ + fluctuating zero mean force $F_g(t)$ = gust

So, it can be easily quantified. So, aerodynamic admittance function is better quantified. So, we know that the total load because of wind is going to be half rho CdA v square, which can be half rho CdA v bar plus v of t square, which can be expanded as half rho CdA v bar square plus v of t square plus 2 v bar v of t.

We also know that from the literature that v bar is much greater than v of t, we can also neglect v t square. So, doing that we can now say Fw of t is half rho CdA v bar square, plus 2 v bar v of t, which can be said as half rho CdA v bar square plus rho CdA v bar v of t. So, we call this component as steady mean drag force, we call this component as fluctuating zero mean force. Now this can be expressed as steady drag component mean component plus rho CdA v bar v of t, we call this as F g of t. So, g stands for gust.

(Refer Slide Time: 10:39)

Considering wind as ergodic the one-sided power spectral density function of the wind process F_w is related to wind spectrum as follows:

$$S_F^+(\omega) = (\rho C_d A \bar{v})^2 S_u^+(\omega) \quad (6)$$

$$\equiv S_F^+(\omega) = \frac{4 \bar{F}_w^2}{\bar{v}^2} (AAF) S_u^+(\omega) \quad (7)$$

Typical AAF is $\left\{ \chi\left(\frac{\omega \sqrt{A}}{2\pi \bar{v}}\right) \right\}^2$

$\chi\left(\frac{\omega \sqrt{A}}{2\pi \bar{v}}\right) \rightarrow 1$, @ lower frequency
 $\chi\left(\frac{\omega \sqrt{A}}{2\pi \bar{v}}\right) \rightarrow 0$, @ higher frequency

Considering wind as an ergodic process the one-sided power spectral density function of wind process F_w of t is related to wind spectrum as follows is given by $\rho C_d A \bar{v}$ square $S_u \omega$, we call equation number 6. We can now say I replace the gust component with aerodynamic admittance function, I can say this spectrum is now given by $4 \bar{F}_w^2$ by \bar{v} bar square of aerodynamic admittance function of $S_u \omega$ call equation number 7.

Now, typical aerodynamic admittance function is a chi function of ω root of A by $2\pi \bar{v}$ bar square. So, the typical plot of this looks like this, for increase in ω the chi function of ω will vary. So, this becomes 1 and this is 0 so on the other hand, when ω root A by $2\pi \bar{v}$ bar tends to 1 at lower frequency chi function of tends to 0 at higher frequency.

(Refer Slide Time: 13:03)

When $\frac{\omega \sqrt{A}}{2\pi \bar{v}} \rightarrow \infty$, $\chi\left(\frac{\omega \sqrt{A}}{2\pi \bar{v}}\right) \rightarrow 0$

Davenport (1977),

$$\chi(x) = \frac{1}{1+(2x)^{4/3}}$$

That is when $\omega \sqrt{A}$ by $2\pi \bar{v}$ tends to infinity, the χ function of $\omega \sqrt{A}$ by $2\pi \bar{v}$ tends to 0. In general as given by Davenport in 1977 χ of x is equal to 1 by $1 + 2x$ to the power $4/3$.

(Refer Slide Time: 13:43)

Summary

- Aerodynamic load (wind)
- wind process
- factors affecting wind load
- F_D, F_L
- $v = \vec{v}_1 + \vec{v}(t)$
- AAF \equiv approximates the first component

So, friends in this lecture we started understanding aerodynamic load that is wind load caused by wind. We learnt something about the wind process, factors affecting wind load the drag force and the lift force, then wind velocity as got 2 components the main and the

gust component, then aerodynamic admittance function, which approximates the gust component which we plot and understood.

So, in the next lecture we will talk about the wind spectrum and try to learn how the wind spectrum equations can be plotted using a numerical code or a **MATLAB** code, we will do couple of problems to understand how they can be computed by simple hand computations and one can also write the simple program to do this which I will show you in next lecture.

Thank you very much.