

Computer Methods of Analysis of Offshore Structures
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Module - 03
Lecture - 03
Response Spectrum (Part - 2)

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- Response Spectrum
- Autocorrelation Function
- White noise Approximation

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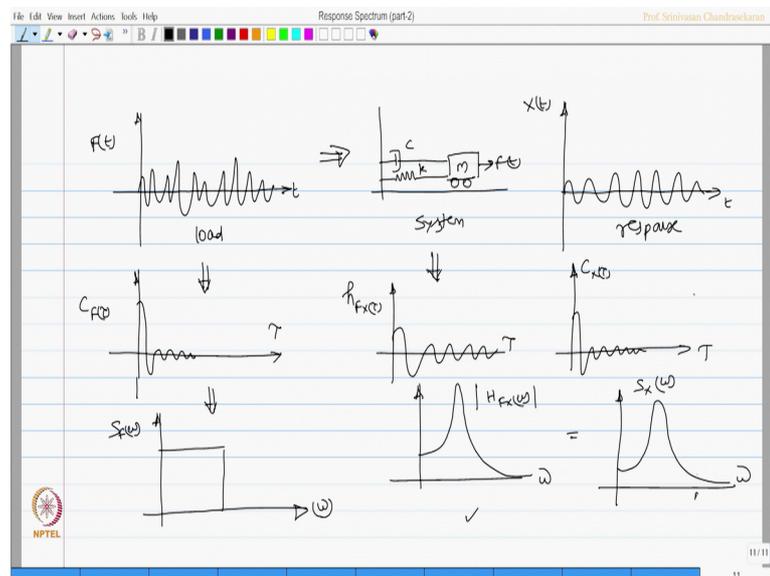
$$S_x(\omega) = |H_{xx}(\omega)|^2 S_f(\omega) \quad (19)$$

Eq(19) gives the relationship between response spectrum ($S_x(\omega)$) and the load spectrum $S_f(\omega)$.

Further, Eq(19) does not contain information about phase shift (ϕ) b/w load and the response. It gives information only about the amplification of amplitude.

S_x omega can be HFX omega square of Sf omega; I call this as equation number 9. So, equation 19 gives the relationship between the response spectrum S_x omega and the load spectrum S_f omega. So, that is a very important relationship we arrived in this lecture further there are some interesting features about equation 19. Equation 19 does not **contains** information about phase shift phi between load and the response. You can see the term is square therefore, the phase shift concept are the parameter is lost. So, it gives information only about the amplification of amplitude that is very important let us try to understand this graphically let us say I have F of t which can be a signal like this on a time scale representing F of t.

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Let us say this is my load I take an autocorrelation of this, the auto correlation function typically comes like this say this is my C F of tau and ultimately this will give me the plot of the transfer function in terms of omega and S F omega which can typically look like this. If I apply this load to a system which a dynamic system which has got a mass which is got a damping force, which is got also a restoring force and external excitation is what we are applied here if this my dynamic system, whose response looks like this on a time history. The system has a property which is transfer function, which can be this way and this can be H FXtau, the system will also have the response whose autocorrelation is given by this plot ultimately the system will have a response.

Which is get amplify for a given damping for various values of omega, which is the mod value of H FXomega. This will now lead to the response of the system in spectral ordinate which is Sx omega which we call as response spectrum. So, this becomes my load spectrum and this becomes my response spectrum and this becomes my transfer function which gives only the information about the amplitude and not about the phase shift between the response applied my response obtained and the force applied on the given system.

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mean value and variance are also important

mean value of the response is given by:

$$m_x = H_{FX0} m_f$$

$$\sigma_x^2 = \int_{-\infty}^{\infty} |H_{FX}(\omega)|^2 S_f(\omega) d\omega$$

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In addition mean value and variance are also important. So, mean value of the response is given by m_x is H_{FX0} of m_f which we already derived and the variance is minus to plus infinity $|H_{FX}(\omega)|^2 S_f(\omega) d\omega$ I call this equation as equation twenty therefore, from the response spectrum.

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from the response spectrum,
 one can compute several statistical quantities which are important for assessing the nature of the response.

For example,
 Std deviation of the response can be readily obtained from Eq (20).

Let us take the response of a linear system with transfer function $H_{FX}(\omega)$, subjected to a stationary load process f

One can compute several statistical quantities which are important for assessing the response.

For example standard deviation of the response can be readily obtained from the variance that is from equation twenty for the response function be the response of a linear system transfer function $H_{FX}(\omega)$ applied or.

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$$\sigma_x^2 = \int_{-\infty}^{\infty} |H_{FX}(\omega)|^2 S_{ff}(\omega) d\omega \quad (21)$$

RHS of the above Eq is to be computed Numerically -
 - application problem to Dynamical systems

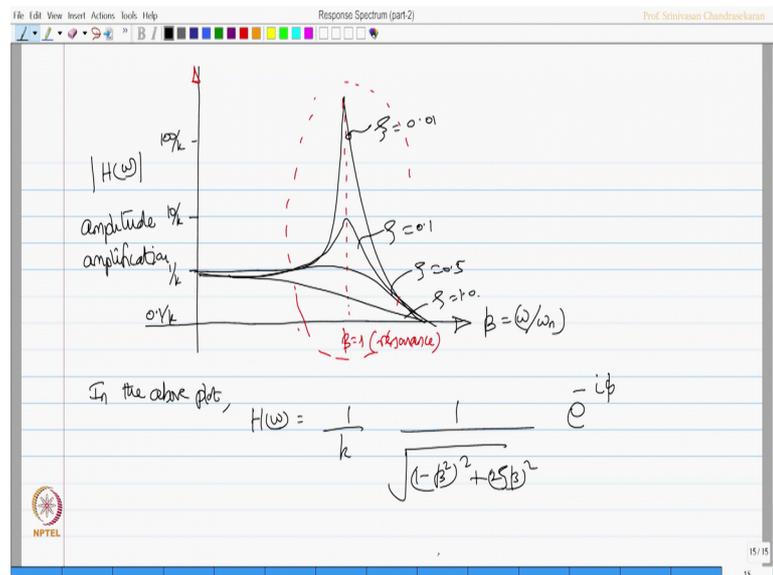
if damping in the system is very small, then
 for $\xi \ll 1$, $|H_{FX}(\omega)|^2$ is very narrow
 which will be epicentred around the resonance frequency ω_r
 ($\omega_r = \omega_n$). Main contribution to the integral Eq (21) comes around the interval close to ω_r

Let us say subjected to a stationary load process f of t σ_x^2 which we wrote earlier as $F_x(\omega)^2 S_f(\omega) d\omega$ is now valid, the right hand side of this

equation is to be computed numerically. Now as an application problem to dynamical systems if damping in the system is very small then for damping to be very small than unity the transfer function is very narrow.

Which will be focused or which will be epicentered around the resonance frequency ω_r where ω_r is ω_n . There is excitation frequency and the natural frequency of the system matches; this implies a very important statement that main contribution to the integral in equation 21, comes around the interval closer to ω_r that is very important statement.

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Let us try to understand this graphically, let us say I tried to plot the ratio of forcing frequency to a natural frequency, let us try to plot this closely in the range of beta equals one which is resonating, let us try to plot in the y axis $h(\omega)$ the absolute values we call amplitude amplification.

Say this is point $1/k$ this is let us say $10/k$ this is $100/k$. Let us say the curve starts from one gets risen and goes to the narrow band here and then falls down steeply this is for zeta equals 0.01 typically. Then look for other zetas zeta 0.1, 0.5 and zeta equals 1.0.

So, friends in the above plot you can see that there is a narrow band focus at resonance which is the main contribution of the integral and $H(\omega)$ is simply $1/k$ the dynamic amplification of factor which we also discussed in the last lecture.

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The image shows a digital whiteboard with handwritten text and a mathematical equation. The text reads: "If $S_f(\omega)$ varies slower than $|H_{fx}(\omega)|^2$, then it is possible to replace $S_f(\omega)$ by $S_0 = S_f(\omega_r)$ ". Below this, the equation $\sigma_x^2 = S_0 \int_{-\infty}^{\infty} |H_{fx}(\omega)|^2 d\omega$ is written. The final sentence states: "This procedure of replacing the input spectrum by a constant is called 'white noise approximation'". The whiteboard interface includes a menu bar at the top with options like File, Edit, View, Insert, Actions, Tools, and Help. The name "Prof. Srinivasan Chandrasekaran" is visible in the top right corner. The NPTEL logo is in the bottom left corner, and the number "16" is in the bottom right corner.

Therefore if the response spectrum varies slower than the transfer function, then it is possible to replace the response the load spectrum by S_0 .

Which is a load spectrum at ω_r hence σ_x^2 is now going to be S_0 minus to plus infinity $|H_{fx}(\omega)|^2 d\omega$, this procedure of replacing the input spectrum by a constant is called white noise approximation.

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A typical feature of the response spectrum:

- Consider a weakly damped dynamic system
- narrow-banded
- response spectrum - narrow banded - weakly damped system.
- This will be dominated largely by $|H_{FX\omega}|^2$

Hence, with the white noise approximation,

$$\sigma_x^2 = S_0 \int_{-\infty}^{\infty} |H_{FX\omega}|^2 d\omega \quad \text{--- (22)}$$

Let us look at a typical feature of the response spectrum, consider a weakly damped dynamic system which will be; obviously, narrow banded. So, the response spectrum will become narrow banded for a weakly damped system. This will be dominated largely by $H_{FX\omega}$ square hence with the white noise approximation σ_x square is S_0 minus to plus infinity $H_{FX\omega}$ square $d\omega$ which is equation 22.

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Summary

- connect the load history to response history of a linear system
- when the load process is a zero-mean process response will follow same nature
- for a weakly damped system, response spectrum can be approximated by white noise approximation
- spectral energy - will be concentrated around the ω_0 only

Let us see the summary what we learnt in this lecture.

We are able to connect the load history to the response history of a linear system, we also said when the load process is a 0 mean process, response will follow same nature further for a weakly damped dynamic systems, response spectrum can be approximated by white noise approximation, where the spectral energy will be epicentered around the resonance frequency only.

We will continue this discussion in the next lecture by explaining more about the response spectrum then we will also discuss the importance and example of stochastic process in analysis of offshore structures.

Thank you.