

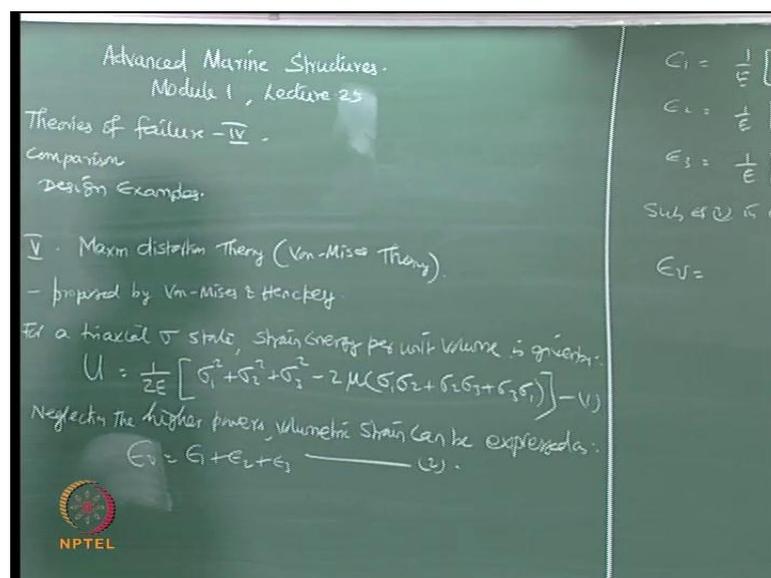
**Advanced Marine Structures**  
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**Lecture - 25**  
**Theories of failure – IV**

So, we will continue to discuss on the topic on advanced marine structures. In the last lecture we discussed about four theories of failure, we understood the importance of why we have to study the theories of failure because, when you take the simple tension test as the reference or the benchmark test based on which, we compute the yield point stresses which is considered as one of the failure criteria, when the stress reached yield point as far as plastic design is concerned. But simple tension test has parallelly other problem, that many of the values simultaneously reach their optimum value like maximum shear, maximum strain energy, principle stress, etcetera.

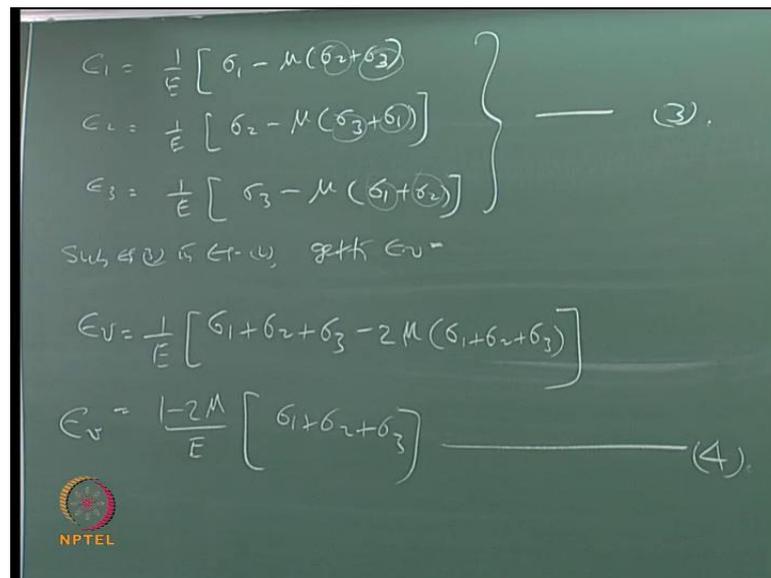
So, we really do not know which will yield or which will lead to the actual category of failure, will it be because of yielding or will it be because of fracture, and what is the application of this theory? Because in certain domains, and in certain theories we said in quadrant one and three they do not agree, and quadrant two and four there are serious discrepancies.

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The fifth theory which will discuss today will be the maximum distortion theory; it is also called as von Mises theory. This theory was proposed by von Mises and Hencky as we saw yesterday. So, the statement of the theory is already given in the last lecture; we will not repeat it here. We will straight away go to the equation. We already said for a triaxial stress state, the strain energy per unit volume absorbed by the body is given by equation one. We can say neglecting the higher powers.

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$$\left. \begin{aligned} \epsilon_1 &= \frac{1}{E} [\sigma_1 - \mu(\sigma_2 + \sigma_3)] \\ \epsilon_2 &= \frac{1}{E} [\sigma_2 - \mu(\sigma_3 + \sigma_1)] \\ \epsilon_3 &= \frac{1}{E} [\sigma_3 - \mu(\sigma_1 + \sigma_2)] \end{aligned} \right\} \text{--- (3)}$$

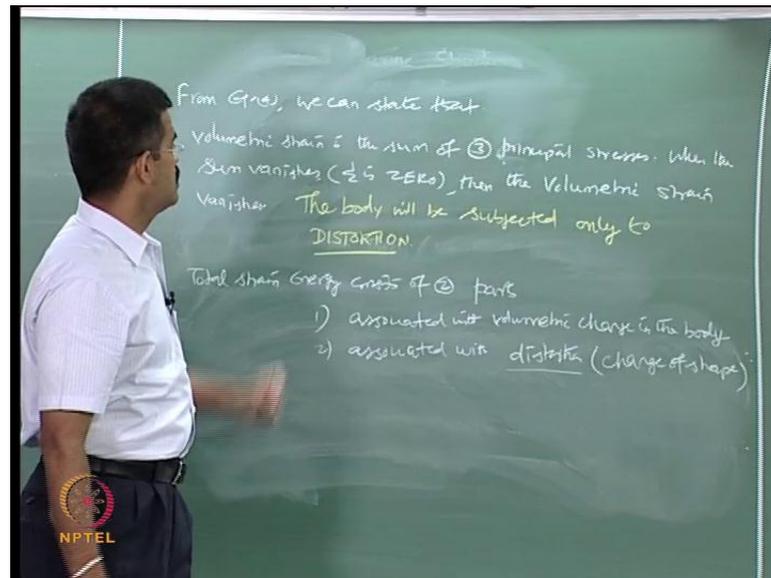
Sub  $\epsilon_1 + \epsilon_2 + \epsilon_3 = \epsilon_v$

$$\epsilon_v = \frac{1}{E} [\sigma_1 + \sigma_2 + \sigma_3 - 2\mu(\sigma_1 + \sigma_2 + \sigma_3)]$$

$$\epsilon_v = \frac{1 - 2\mu}{E} [\sigma_1 + \sigma_2 + \sigma_3] \text{--- (4)}$$

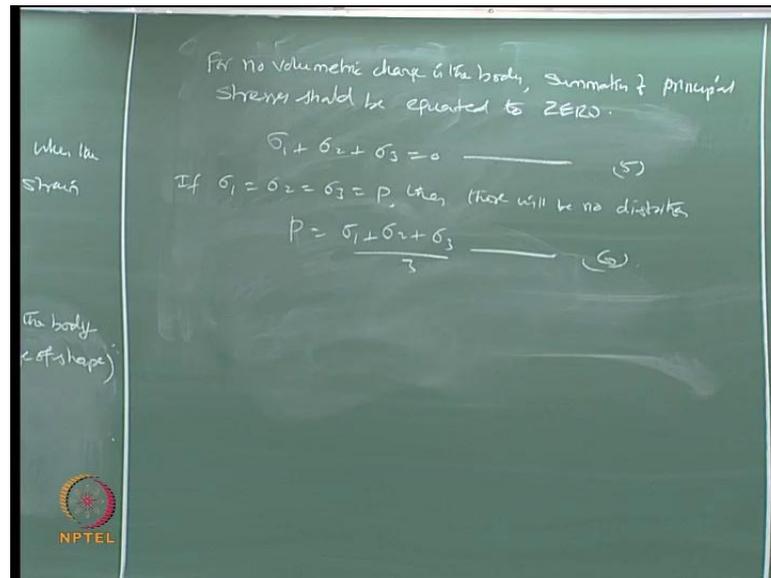
The volumetric strain can be expressed as  $\epsilon_v = \epsilon_1 + \epsilon_2 + \epsilon_3$  where  $\epsilon_1$ ,  $\epsilon_2$ , and  $\epsilon_3$  are the principal strains. I call this as equation number three. I can substitute three and two and get  $\epsilon_v$ . So, substituting equation three in equation two, getting the volumetric strain; the volumetric strain simply substitute and summarize I can write it like this  $\epsilon_v = \frac{1}{E} [\sigma_1 + \sigma_2 + \sigma_3 - 2\mu(\sigma_1 + \sigma_2 + \sigma_3)]$ . You can see here  $\sigma_1$  is twice,  $\sigma_2$  is twice, and  $\sigma_3$  is twice,  $2\mu$  of  $\sigma_1 + \sigma_2 + \sigma_3$ . So, we can also write this as  $\epsilon_v = \frac{1 - 2\mu}{E} (\sigma_1 + \sigma_2 + \sigma_3)$ , call this as equation number four. This is my volumetric strain neglecting the higher powers of the equation one. So, if you look at the equation four we can make a very important statement.

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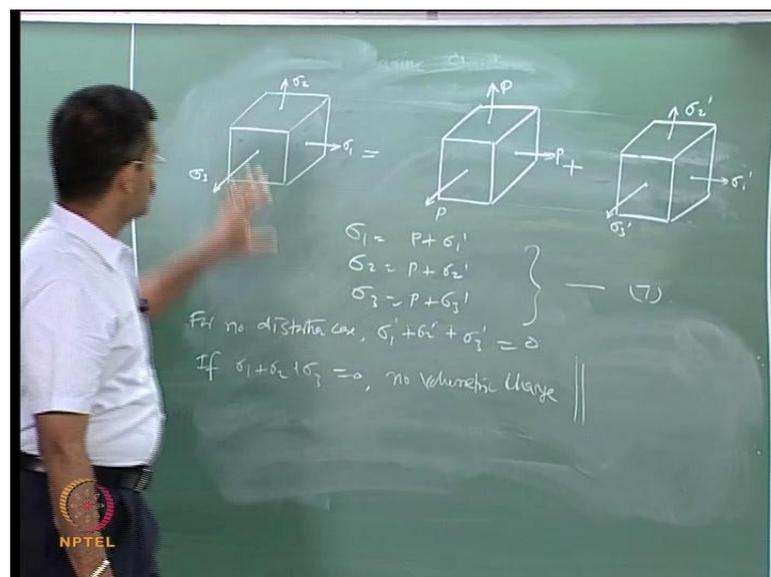
From equation four, we can state that volumetric strain is the sum of three principle stresses. When the sum vanishes or when the summation is zero, then the volumetric strain vanishes from this equation. So, what does it mean? It means that the body will be subjected only to distortion, that is what is, volumetric strain will vanish. Now the total strain energy consists of two parts, one which is associated with volumetric change in the body, the other is associated with distortion which is otherwise the change of shape. Remember change of shape and changes of volume are not same, only the shape changes, volume may remain same. This is what we call as distortion. So, for zero volumetric change, I want to study the maximum distortion theory, therefore I should say that the volumetric change the body is set to zero, for zero volumetric change, as you see from the statement, the summation on the principle stresses should be equated to zero. Let us do that.

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So, for no volumetric change in the body, the summation of principal stresses should be equated to zero. Then you will get pure distortion. Let us say  $\sigma_1 + \sigma_2 + \sigma_3$  is set to 0. Now if  $\sigma_1 = \sigma_2 = \sigma_3 = P$ , then there will be no distortion because the summation is not 0. So, let us say  $P$  is now equal to an average of this. If  $P$  is set as an average of this, it means we can schematically express this.

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Let us say, that will be equal to summation of two things. What you wanted is a triaxial stress state; I can say now this will be equal to, we already said they are equal to

And there is not going to be any distortion. In that case, we say that the stresses additionally created here let us call them as  $\sigma_1$  dash 2 dash and  $\sigma_3$  dash respectively. So, we can write simple equations saying that  $\sigma_1$  is  $P$  plus  $\sigma_1$  dash,  $\sigma_2$  is  $P$  plus  $\sigma_2$  dash,  $\sigma_3$  is  $P$  plus  $\sigma_3$  dash. Let us call this equation number 7. For no distortion case,  $\sigma_1$  dash  $\sigma_2$  dash  $\sigma_3$  dash should be set to 0. If this exists which is not equal to 0, but if  $\sigma_1$  plus  $\sigma_2$  plus  $\sigma_3$  is set 0, no volumetric change. For  $\sigma_1$  dash  $\sigma_2$  dash  $\sigma_3$  dash set to 0, no distortion in that case, two exquisite cases but the triaxial stress state is the combination of this, what I am saying is instead of 1 2 and 3 I am saying this as  $P$  axis. So, this is going to be a combination of these two cases.

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Let  $\sigma_1 = \sigma_2 = \sigma_3 = P$  be substituted in eq (1).

$$U = \frac{1}{2E} [\sigma_1^2 + \sigma_2^2 + \sigma_3^2 - 2\mu (\sigma_1\sigma_2 + \sigma_2\sigma_3 + \sigma_3\sigma_1)]$$

$$= \frac{3P^2}{2E} (1 - 2\mu)$$

$$\sigma_1 + \sigma_2 + \sigma_3 = 3P + \sigma_1' + \sigma_2' + \sigma_3' \quad \text{--- (8)}$$

$$U = \frac{3P^2}{2E} (1 - 2\mu) \quad \text{--- (9)}$$

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In that situation, let  $\sigma_1$ ,  $\sigma_2$  and  $\sigma_3$  is  $P$  be substituted in equation one; equation one is the total strain energy value. Let us see the equation one. I am rewriting it here  $U$  is given by  $\frac{1}{2E} (\sigma_1^2 + \sigma_2^2 + \sigma_3^2 - 2\mu (\sigma_1\sigma_2 + \sigma_2\sigma_3 + \sigma_3\sigma_1))$ ; is this the equation 1. So substituting this, I may get  $\frac{3P^2}{2E} (1 - 2\mu)$ . Already we can also say from this figure that  $\sigma_1 + \sigma_2 + \sigma_3$  is  $3P + \sigma_1$  dash  $\sigma_2$  dash plus  $\sigma_3$  dash. I call this equation number eight. So, now I can say  $U$  is  $\frac{3P^2}{2E} (1 - 2\mu)$  equation 9.

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$$p = \frac{\sigma_1 + \sigma_2 + \sigma_3}{3} \quad \text{Sub in (9)}$$

$$U_v = \left( \frac{1-2\mu}{6E} \right) (\sigma_1 + \sigma_2 + \sigma_3)^2 \quad \text{--- (10)}$$
 Distortion Energy can be found by subtracting  $U_v$  from  $U$ .
 
$$U_{dist} = U - U_v$$

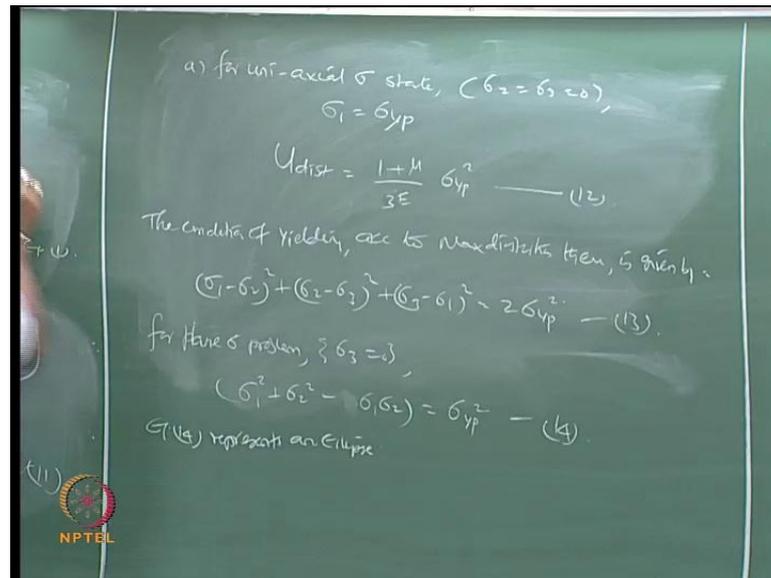
$$U_{dist} = \frac{1}{2E} \left[ \sigma_1^2 + \sigma_2^2 + \sigma_3^2 - 2\mu (\sigma_1\sigma_2 + \sigma_2\sigma_3 + \sigma_3\sigma_1) \right] - \frac{1-2\mu}{6E} (\sigma_1 + \sigma_2 + \sigma_3)^2$$

$$= \frac{1+\mu}{6E} \left[ (\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 \right] \quad \text{--- (11)}$$

So, we already know P is sigma 1 plus sigma 2 plus sigma 3 by 3. So substitute in nine, it becomes 1 minus 2 mu by E of this 3 and this 3 goes away, simply sigma 1 plus sigma 2 plus sigma 3 whole square, this is equation 10. So, if you really wanted to find the distortion energy, it can be found by actually subtracting equation ten from equation one because equation one is a total strain energy which has volumetric change plus distortion both. I subtract this from one, I get the distortion only. So, let us do that. So, U distortion is U minus U volumetric. So, let us do that U distortion. Get this equation, let us see, we have equation one showing U and U v is above. This is actually volumetric. This is going to be 1 minus 2 mu by 6E no, because this is square. This is going to be 6E; please make a change here.

When you substitute it in equation nine, because it is square, it is 6E here, 1 minus 2 mu by 6E of the squares of this. So, substitute from U minus U v and get mu distortion, see what equation we are getting. So, it is going to be 1 by 2E of sigma 1 square sigma 2 square sigma 3 square minus 2 mu of minus 1 minus 2 mu by 6E. So, after simplifying 1 plus mu by 6E of sigma 1 minus sigma 2 the whole square, sigma 2 minus sigma 2 the whole square, sigma 3 minus sigma 1 the whole square is equation 11. Sigma 1 minus sigma 2 1 plus mu by 6E, you can simply and check. So, for any uniaxial state sigma 2 and sigma 3 is going to be zero.

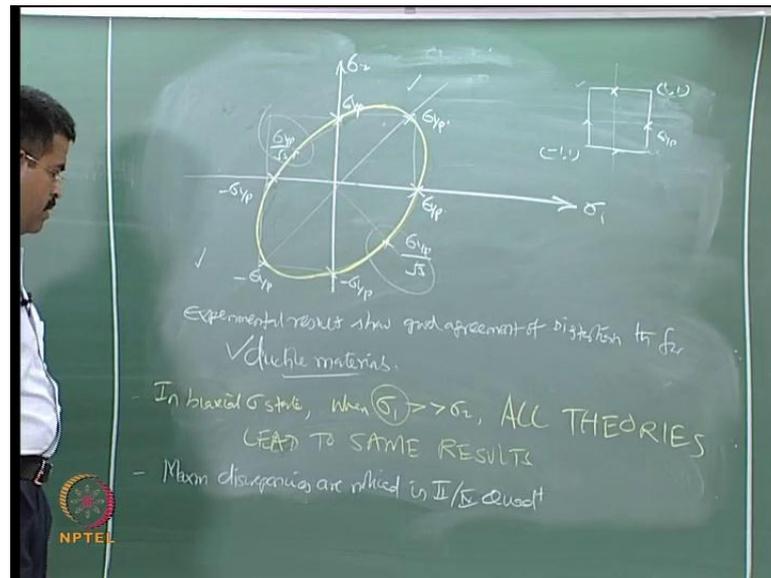
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So, U distortion and we all know that sigma 1 is going to be yield value, that is the definition of the theory. So, U distortion is going to be what will be the value?  $1 + \nu$  by  $3E$  of  $\sigma_y$  square of twice because there is one square here. So, I can say this as equation twelve because there are two squares here. One is sigma 1 here also, one sigma 1 here also; remaining all are zero. So, the condition of yielding according to maximum distortion theory is given by  $(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 = 2 \sigma_y^2$ , call this equation number thirteen. So for a plane stress problem, this equation can be that  $\sigma_3$  is 0 by axis stress state.

This equation can be  $\sigma_1^2 + \sigma_2^2 - \sigma_1 \sigma_2$  is going to be  $\sigma_y^2$ , the 2 goes away because there are two here  $\sigma_y^2$ , which is again an equation of an ellipse. That two goes away, this two here in all the cases, the two goes away. It is an equation of an ellipse, say, equation 14 represents an ellipse. So, let us draw the failure boundary as indicated by the maximum distortion theory and see what are the discrepancies in different quadrant as we saw in the earlier theories. Let me draw these theory boundaries.

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So, these values are all  $\sigma_{yp}$  and the minor axis values will be  $\sigma_{yp}$  by root 3. You can check that and this value is more or less equal, my figure may not show that. Even this is also  $\sigma_{yp}$ , this is also  $\sigma_{yp}$ . So, I can very well see this theory in the first and third quadrants it is agreeing more or less with the maximum principle stress theory whereas in quadrants two and four, the maximum principle stress theory says that this stress will be equal to  $\sigma_{yp}$  because this is the maximum principle stress theory. So, in quadrants two and four, this theory says that the maximum stress will be equal to the yield value, whereas in this case it is only  $1/\sqrt{3}$  of that.

So, there has been a good discrepancy in quadrants two and four given by the distortion theory compared to that of the maximum principle stress theory. So, it has been seen experimentally that experimental results show a good agreement of distortion theory for ductile materials. So, this theory is very good for ductile materials. There is a very important statement you want to make here, when in a biaxial stress state, when  $\sigma_1$  is very large compared to  $\sigma_2$ , when one of the principle stresses is very large compared to the other, all theories lead to same results. What does it mean? All these theories hold good by concluding for a uniaxial stress state.

The problem starts only when it is biaxial or triaxial which is a fact and reality in case of marine structures. When the value is very large compared to the other, then all theories will yield more or less the same results. The second observation we can make

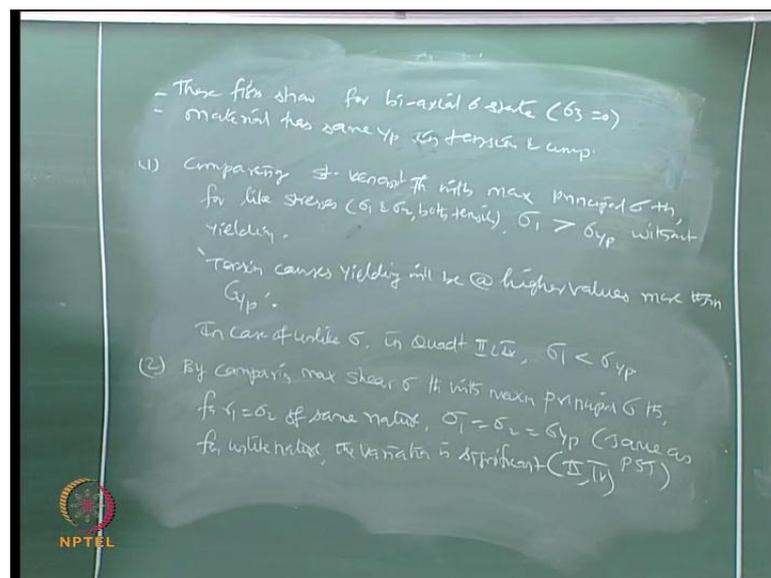


drawing it just adjacent to this so that it is also visible. It is one and the same but I am drawing it adjacent. So, this is my maximum shear stress theory; it is given by Tresca.

Let us draw the total strain energy theory. This is maximum strain energy theory, not maximum, total strain energy; it is not maximum. There is nothing like maximum strain, total strain energy. So, what are these values? We already have them what are these values? They are major axis; major axis  $\sigma_1$ ,  $\sigma_2$ , is it. Total strain energy theory, I think it is  $0.87 \sigma_y$ , why you people are sleeping in the class? You people are sleeping in the class, is it?  $0.87 \sigma_y$  and what are the minor axis values?  $0.6163 \sigma_y$  of course minus. This is the total strain energy theory. Now we will plot the maximum distortion theory.

Just now we plotted it here. They all will touch  $\sigma_y$  in all the corners; all the  $\sigma_y$  in all the corners. So here, and of course all these points will be touched and soon and this value is this plus. What is  $1/\sqrt{3}$ ? I get an ellipse like this. So, this is my maximum distortion theory and this value is  $1/\sqrt{3}$  of  $\sigma_y$  which I already engraved it here, of course minus and this value is  $1/\sqrt{3}$  of  $\sigma_y$  which is  $0.577$ . Now you can easily write good amount of inferences from this figure on these comparisons of theories in single domain.

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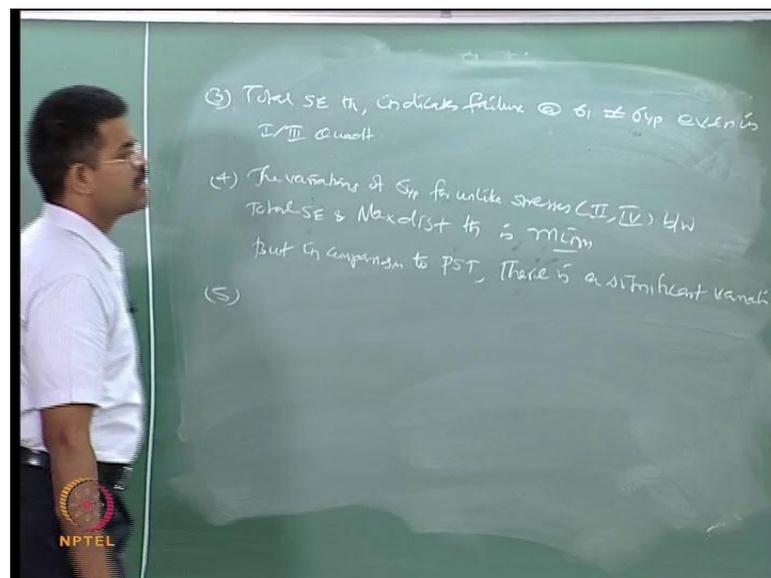


So, these figures show for biaxial stress state, that is  $\sigma_3$  set to zero. It has an assumption material has the same yield point in tension and compression. Let us quickly

compare St.Venant's theory with maximum principle stress theory. By comparing St.Venant's theory which is the maximum strain theory, this one the rhombus with the maximum principles theory which is the white one, it shows for like stresses, that is sigma 1 and sigma 2, both tensile or compressive. Magnitude may remain same sigma 1 might be equal to sigma 2, but they are of the same nature. So, you should look at the quadrants of one and three same nature, maximum principle stress can even exceed sigma y p without yielding.

What does it say is, tension causes yielding will be at higher values more than sigma y p, that is what the statement is. Tension will be more than sigma y p. Of course in case of unlike stresses that is in quadrant two and four, sigma 1 is far lesser than sigma y p, you can see here. This is my rhombus point, it is far lesser than sigma y p. Now I am comparing the maximum shear stress theory that is the green one, the irregular hexagon with the principle stress theory. By comparing the maximum shear stress theory with maximum principle stress theory for stresses of same nature, sigma 1 equal sigma 2 is equal sigma y p which is as same as principle stress theory. For unlike nature, the variation is significant, that is in quadrant two and four, see here. They are significant. The third inference, can I rub this, are you able to follow my hand writing.

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The third inference is the total strain energy theory indicates failure at sigma 1 not equal to sigma y p even in first and third quadrants, that is very dangerous. It is only

87 percent; 0.87 it yields. 0.87 it yields, what does it mean? When your point at the stress state lies above this boundary or outside this boundary somewhere here, according to the total strain energy theory, which is shown in blue color here, failure has occurred. But according to principle stress theory, according to St. Venant's theory failure has not occurred. So that is a discrepancy, one theory says failure occurred, others theory says it has not occurred, it is much below  $\sigma_y$ .

So, what does it mean? If you send plastic analysis, you take the stress till  $\sigma_y$  and then only the failure starts, if your assumption is that, this is not holding good or valid as far as this theory is concerned. Because this theory says when the stresses are alike  $\sigma_1$   $\sigma_2$  are same nature and magnitude equal, failure will occur even at 87 percent of  $\sigma_y$  itself. So, that is a dangerous interpretation. Our results of  $\sigma_y$  occurring causing failure for plastic analysis and design could be over conservative, could be dangerous as far as this theory is concerned.

Now let us see the second and fourth quadrant more in detail. The variations of  $\sigma_y$  for unlike stresses, so I am focusing on quadrant two and four. Between total strain energy theory, the blue one, between the total strain energy theory and, the orange one, maximum distortion theory is minimum; they closely agree. What does it mean? This information can be interpreted as change of shape in the body will not cause serious deviation in failure. Maximum strain energy includes volumetric as well as distortion, maximum distortion talks only about change of shape. They agree in unlike stresses two and four.

So if the stresses are unlike in nature, one in compression, one is tension, same magnitude change of shape of the body will not significantly influence the failure stress or yield stress but in comparison to principle stress theory, there is a significant variation. Why? This theory says at 60 percent of yield, failure has started whereas principle stress theory says only at yield, failure will start. What does it mean? This is for ductile material, this is for brittle material. So, that is yielding, this is fracture. Though both of them talk about yield point only, remember this is also  $\sigma_y$ , this is  $\sigma_y$  percentage. Both of them are talking about  $\sigma_y$  multiplied only but this is for ductile, this is for brittle.

This is what the failure theories are, and this is what the discrepancies are. This we must understand very clearly before we really understand what we do for plastic analysis and

design. So in the next class, we will take about it as an example and then we will talk about very important part in marine structures where we talk about shear center. Shear center is a very important aspect of calculation. It is one of the design aspects to be computed and very important because this induces torsional moment in the members in marine structures. When this kind of torsional moment will occur what is the shear center, how to compute it for geometric sections we will see. We will also do couple of problems on using the design examples of this principle, I mean this failure theories, couple of example, then we will move on to shear center in the next class. Do we have any questions or any more important information or interpretation which I left by comparing these theories.

The most important and eye-catching information which you must not miss out is the comparison of the focus of St. Venant's compared to principle stress and the focus of total strain energy theory in quadrant one and three compared to principle stress. These are the two important eye-catching, say, predominantly or significance seen variations in your comparison of failure theory. So, the necessity of understanding failure theories, the necessity of appreciating the deviations of the failure theories in unlike stress regions and like stress regions is important. As a prerequisite for us to really know what we really mean by yielding for plastic analysis and design which we said or which we discussed in the earlier lectures.

So, this lecture terminates the discussions on theories of failure. This is only just a curtain raiser. If you want really you can look into them in biaxial and triaxial stress state in detail, I think you should refer to some of the fracture mechanics lectures in detail for the materials. So, we have just as a prerequisite, we must understand, we must know this but still for the completion of the viewer's interest, we have discussed this in detail as far as far as possible applicable to plastic design alone. Of course we will apply this into examples and show how these theories actually give me numerically a different meaning and as a designer how I am, let us say, influenced by these results, we will see that in next class.