

# MECHANICS

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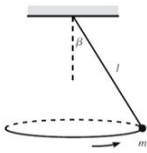
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Lecture: 36

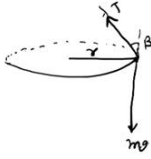
Equation of motion: examples

Hello everyone, welcome to the lecture again. In the last class, we look at the equation of motion in different coordinate systems and solve couple of examples for Cartesian coordinate.




Q.1  $\Rightarrow$  A mass hangs from a massless string of length  $l$ . Conditions have been setup so that the mass swings around in a horizontal circle, with the string making a constant angle  $\beta$  with the vertical. What is the angular frequency of this motion?

A  $\Rightarrow$


$$r = l \sin \beta \quad \text{--- ①}$$
$$T \cos \beta = mg \quad \text{--- ②}$$
$$Fr = T \sin \beta \quad \text{--- ③}$$
$$F_c = m r \omega^2 = m l \omega^2 \sin \beta$$
$$T \sin \beta = m l \sin \beta \cdot \omega^2$$
$$\omega = \sqrt{\frac{T}{m l}} = \sqrt{\frac{mg}{\cos \beta \cdot m l}}$$
$$\omega = \sqrt{\frac{g}{l \cos \beta}} \quad \blacktriangle$$

If  $\beta = 0$  then simple pendulum

$$\omega = \sqrt{\frac{g}{l}} \quad \blacktriangle$$


Today, we are going to look at examples in other coordinate systems. So, this is the first problem statement. A mass hangs from a massless string of length  $l$ . Condition have been set up so that the mass swings around in a horizontal circle with the string making a constant angle beta with the vertical. What is the angular frequency of this motion? So, let me make the free body diagram and look at the forces that are acting.

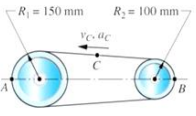
So, we have this mass which is going in a horizontal circle. Its mass is of course  $m$  and the tension  $T$  is going to act along the string and and it is making an angle beta from the vertical.

Now, the relation between the radius of the horizontal circle that it is making and the length of the string  $l$  can be found out from the geometry. So, you can see that  $r = l \sin \beta$ .

Let us call it equation number 1. The force balancing along the  $y$  direction gives you  $T \cos \beta = mg$ . And the force along the  $r$  direction,  $F_r$  is  $T \sin \beta$ . Now, let us look at equation of motion in the  $r$  direction. So, we have  $F_r = mr \dot{\theta}^2$ , which can be written as  $mr \omega^2$ .

And  $F_r$ , I already know, it is  $T \sin \beta = mr$  is  $l \sin \beta \omega^2$ . So,  $\sin \beta$  will get cancelled. You get  $\omega = \sqrt{\frac{T}{m}} l$ . Now, this I can rewrite because from equation number 2,  $T$  is  $\frac{mg}{\cos \beta}$ . So,  $T$  is  $\frac{mg}{\cos \beta \times m \times l}$  and  $m$  will get cancelled.

We get  $\omega = \sqrt{\frac{g}{l \cos \beta}}$ . Now, note that for a simple pendulum, we have  $\beta = 0$ . So, let us see what happens when  $\beta = 0$ . If  $\beta = 0$ , then let us put there  $\cos \beta$  will be 1. So, we have the condition of simple pendulum. So, we get  $\omega = \sqrt{\frac{g}{l}}$ . This is something that we already know.



**Q.2** ⇒ The flexible belt runs around two pulleys of different radii. At the instant shown, point C on the belt has a velocity of  $5 \text{ m/s}$  and an acceleration of  $50 \text{ m/s}^2$  in the direction indicated in the figure. Compute the magnitudes of the acceleration of point A & B on the belt at this instant.

**Ans.:** \* Every point on the belt has same speed  $\therefore v_A = v_B = v_C = 5 \text{ m/s}$ .


Tangential acc  $\Rightarrow (a_A)_t = (a_B)_t = a_C = 50 \text{ m/s}^2$ .

**Point A**  $\Rightarrow (a_A)_n = \frac{v_A^2}{R_1} = \frac{5^2}{.15} = 166.67 \text{ m/s}^2$

$\therefore a = \sqrt{(a_A)_n^2 + (a_A)_t^2} = \sqrt{(166.67)^2 + 50^2} = 174.0 \text{ m/s}^2$

**Point B**  $\Rightarrow (a_B)_n = \frac{v_B^2}{R_2} = \frac{5^2}{.1} = 250 \text{ m/s}^2$

$\therefore a_B = \sqrt{(a_B)_n^2 + (a_B)_t^2} = \sqrt{250^2 + 50^2} = 255 \text{ m/s}^2$



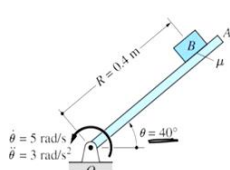
Now, let us look at another problem statement based on flexible belt. The question statement is following. The flexible belt runs around two pulleys of different radii. At the instant zone, point C on the belt has a velocity of  $5 \text{ m/s}$  and an acceleration of  $50 \text{ m/s}^2$  in the direction indicated in the figure. Compute the magnitudes of the acceleration of point A and B on the belt at this instant. Now, in this question, it is given that point C on the belt

has a velocity of  $5 \text{ m/s}$  and acceleration of  $50 \text{ m/s}^2$ . Therefore, the tangential component of the velocity and acceleration will be 5 and 50 throughout the belt.

So, every point on the belt has same speed. Therefore, velocity at point A, velocity at point B, and velocity at point C, its tangential component will be  $5 \text{ m/s}$ . Similarly, the tangential acceleration will let us say acceleration at point A, its tangential component, and acceleration at point B, its tangential component, or the acceleration at point C, it will be  $50 \text{ m/s}$ . So, this is again  $A_t$  and  $B_t$ .

Now, let us analyze point A. at point A, the normal acceleration will be velocity square divided by its radius. So, that will be  $5^2/0.15$ , which gives you  $166.67 \text{ m/s}^2$ . Therefore, total acceleration a will be a normal component square plus a tangential component square. That means it is  $166.67^2 + 50^2$  that gives you  $174 \text{ m/s}^2$ .

Now, let us look at point B. At point B, we have the normal component equal to  $v_B^2/R_2$ . So, that will be  $5^2/0.1$ , which will give you  $250 \text{ m/s}^2$ . Therefore, the total acceleration of point P will be square root  $a_B^2$  normal component plus  $a_B^2$  tangential component that will be  $\sqrt{250^2 + 50^2} = 255 \text{ m/s}^2$ .

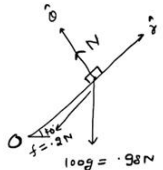


$R = 0.4 \text{ m}$   
 $\theta = 40^\circ$   
 $\dot{\theta} = 5 \text{ rad/s}$   
 $\ddot{\theta} = 3 \text{ rad/s}^2$


**Q3** → The 100-g block B slides along the rotating bar OA. The coefficient of kinetic friction b/w B & OA is  $\mu_k = 0.2$ . In the position shown  $\dot{r} = 1 \text{ m/sec}$ ,  $\dot{\theta} = 5 \text{ rad/sec}$  &  $\ddot{\theta} = 3 \text{ rad/sec}^2$ . For this position determine  $\ddot{r}$ , the acceleration of B relative to bar OA.

**Ans** →  $\Sigma F_\theta = m(R\ddot{\theta} + 2\dot{r}\dot{\theta})$  ✓  
 $N \cdot \sin 40^\circ + \mu N = -1 \cdot (4 \times 3 + 2 \times 1 \times 5)$   
 $N = 1.87 \text{ N}$  ✓

$\Sigma F_r = m(\ddot{r} - R\dot{\theta}^2)$   
 $2 \times 1.87 - 0.98 \sin 40^\circ = -1[\ddot{r} - 4 \times 5 \times 5]$   
 $\ddot{r} = -0.04 \text{ m/s}^2$  ✓  
 Acc. of B is directed toward point O.



$F_\theta = N \cdot \sin 40^\circ$   
 $f_r = 0.2 \times N = 0.38 \sin 40^\circ$



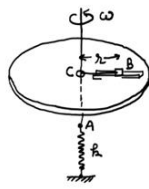
Now, let us look at another problem statement and it is following. The  $100 \text{ gm}$  block B slides along the rotating bar OA. The coefficient of kinetic friction between B and OA is  $\mu_k = 0.2$ .

In the position shown,  $\dot{R}$  is  $1 \text{ m/s}$ ,  $\dot{\theta}$  is  $5 \text{ radian/sec}$ . And  $\ddot{\theta}$  is  $3 \text{ radian/s}^2$ . For this position, determine  $\ddot{R}$ , the acceleration of B relative to bar OA. For  $R = 0.4 \text{ m}$ , the value of  $\dot{R}$ ,  $\dot{\theta}$ , and  $\ddot{\theta}$  is given, and we have to find out the value of  $\ddot{R}$ . Let us look at the free-body diagram of the block B. So, along the rod, let us take  $\hat{r}$  and  $\hat{\theta}$  therefore will be perpendicular to it.

The weight of the block which is  $100 \text{ gm}$ . Which is equal to  $0.98 \text{ N}$  is going to act downward, and the direction of the friction will be opposite to the motion. So, let us take it in this direction, and it will be  $\mu N$ ,  $\mu$  is given, and  $N$  is the normal reaction, which will, of course, act along the  $\hat{\theta}$  direction. So, let us write down the equation of motion along the  $\hat{r}$  direction and  $\hat{\theta}$  direction. So, we have  $F_{\theta} = m(R\ddot{\theta} + 2\dot{R}\dot{\theta})$  and we have  $\sum F_r = m\ddot{R} - R\dot{\theta}^2$ .

From the free body diagram, let us find out what are the forces in the  $F_{\theta}$  direction and what are the forces in the  $F_r$  direction. Now, you can see that the  $F_{\theta}$  or the force along the  $\hat{\theta}$  direction is  $N$  minus the component of the weight along the  $\hat{\theta}$  direction, which is  $0.98 \cos$ , and we have to determine all this at  $\theta$  equal to  $40^\circ$ . So, this angle is  $40^\circ$ ; therefore,  $\cos 40^\circ$  and  $F_r$ , the force along the  $R$  direction is the frictional force, which is  $0.2N$ , and  $N$  is something that we do not know right now. So, let us write it as  $N - 0.98 \sin 40^\circ$ . So, let us use this equation.

So, we have  $F_{\theta}$ , which is  $N - 0.98 \cos 40^\circ$  equal to  $m$  is  $100 \text{ gm}$ . So therefore  $0.1$ ,  $R$  is  $0.4$ , and  $\ddot{\theta}$  is given. It is  $3 \text{ radian/sec}$ . So, therefore, multiplied by  $3 + 2 \times 1 \times 5$ . So, this gives you  $N = 1.87 \text{ N}$ . And now, let us use the second equation. So, we have  $F_r$ , which is  $0.2 \text{ N}$ . So  $0.2 \times N$ .  $N$  is something that we know now. So, it is  $1.87 - 0.98 \sin 40^\circ$  equal to  $m$  is  $0.1$ .  $\ddot{R}$  Is a something that we have to find out  $-R$  is  $0.4\dot{\theta}^2$ . So,  $\dot{\theta}$  is  $5$ . And this gives you  $\ddot{R} = -0.04 \text{ m/s}^2$ . And the negative sign here indicate that the acceleration of B is directed towards point O.



Q 4 ⇒ A platform has a constant angular velocity  $\omega = 5 \text{ rad/sec}$ . A mass B of 2 kg slides in a frictionless chute attached to the platform. The mass is connected via a light inextensible cable to a linear spring of spring const.  $k = 20 \text{ N/m}$ . The spring is unstretched when the mass B is at the center C of the platform. If the mass B is released at  $r = 200 \text{ mm}$  from a stationary position relative to the platform, what is its speed relative to the platform when it has moved to  $r = 400 \text{ mm}$ ? What is the transverse force on the body B at this position?

Ans:  $\Sigma F_r = m(\ddot{r} - r\dot{\theta}^2)$   
 $\Rightarrow -20r = 2(\ddot{r} - 25r)$   
 $\ddot{r} = 15r$  — (1)

$\dot{\theta} = \omega = 5 \checkmark$

$F = -kx$

$\dot{r} = \frac{dv_r}{dt} = \frac{dv}{dr} \frac{dr}{dt} = v \frac{dv}{dr}$

$v_r \frac{dv_r}{dr} = 15r$

$\int v_r dv_r = \int 15r dr$

$\frac{v_r^2}{2} = \frac{15r^2}{2} + C_1$  — (2)

Initial case at  $r = 2 \text{ m}$ ,  $v_r = 0$

$\therefore 0 = \frac{15 \times 2 \times 2}{2} + C_1$

$C_1 = -30$

$\frac{v_r^2}{2} = \frac{15r^2}{2} - 30$

$v_r^2 = 15r^2 - 60$

but  $r = 4 \text{ m}$

$\therefore v_r = 1.342 \text{ m/sec}$  Ans ✓

for the transverse force

$F_\theta = m(r\ddot{\theta} + 2\dot{r}\dot{\theta})$

$= 2(0 + 2 \times 1.342 \times 5)$

$= 26.84 \text{ N}$  ↓



Now, let us look at another problem statement, question number 4. A plate form has a constant angular velocity  $\omega = 5 \text{ radians/second}$ , a mass B of 2 kg slides in a frictionless tube attached to the platform. The mass is connected via a light inextensible cable to a linear spring of a spring constant  $K = 20 \text{ N/m}$ . The spring is unstretched when the mass B is at the centre C of the platform. Now, it is given that if the mass B is released at  $r = 200 \text{ mm}$  from a stationary position relative to the platform. What is its speed relative to the platform when it has moved to  $r = 400 \text{ mm}$ ?

And we have been also asked what is the transverse force on the body B at this position. In this question, we have been asked to find out the speed and the transverse force. To find out the speed, let us look at the equation of motion along the  $r$  direction. So, we have  $\Sigma F_r = m\ddot{r} - r\dot{\theta}^2$ . Now, the force along the  $r$  direction is because of the spring.

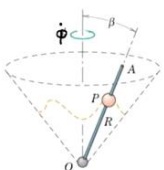
And the spring force  $F = -kx$  where  $x$  is the extension, which in this case is  $r$ , and  $k$  is given. Therefore,  $F_r$  will be  $-20r$ .  $m$  Is also given  $\ddot{r} - \dot{\theta}^2$  is also given.  $\dot{\theta} = \omega = 5$ . Therefore  $5^2r$ . And from here, we can get  $\ddot{r}$ .

So,  $\ddot{r}$  is  $15r$ . Now, this  $\ddot{r}$  is acceleration. So, it is  $dv_r/dt$  rate of change of velocity. And again, I can write down  $dv/dr$  and  $dr/dt$ , which I can rewrite as  $v dv/dr$ . Therefore, from this equation, we have  $v dv/dr$ , and everything is about the radial component equal to  $15r$  from equation number 1. Now, I can integrate it to find out what is  $v_r$ .

So  $v_r dv_r = 15r dr$ , let us integrate it. So, we have  $\frac{v_r^2}{2} = 15r^2/2$  plus constant. Now, this constant I can find out from the initial condition that were set up in the problem. So, the initial conditions is at  $r = 0.2 \text{ m}$   $v_r = 0$ , okay.

So, therefore,  $0 = 15 \times 0.2 \times \frac{0.2}{2} + C_1$  or  $C_1 = -0.3$ . I can put this in equation number 2. So, we have  $\frac{v_r^2}{2} = \frac{15r^2}{2} - 0.3$ . This I can rewrite as  $v_r^2 = 15r^2 - 0.6$  and let us put  $r = 0.4 \text{ m}$ .

So, we get  $v_r = 1.342 \text{ m/s}$  because we have been asked to find out the velocity at  $r = 0.4 \text{ m}$ . Now, let us look at the force for the transverse force. Because we have been asked to find out the transverse force, we know that  $F_\theta = mr\ddot{\theta} + 2\dot{r}\dot{\theta}$ . Now, all the values are given  $m$  is 2,  $r$  is 0.4,  $\ddot{\theta}$  because it is rotating with a constant velocity. Therefore,  $\ddot{\theta}$  will be 0 +  $2\dot{r}$ ,  $\dot{r}$  is 1.342 that is the velocity along the  $r$  direction which we have just find out multiplied by  $\dot{\theta}$ . So,  $\dot{\theta}$  is given 5 and this gives you 26.84 N.



**Q5** ⇒ The rod OA is held at the const. angle  $\beta=30^\circ$  while it rotates about the vertical with a const. angular rate  $\dot{\phi}=120 \text{ rev/min}$ . Simultaneously, the sliding ball P oscillates along the rod with its distance in mm from the fixed pivot O given by  $R=200+50\sin 2\pi nt$ , where, the frequency of oscillation along the rod is const = 2 cycle/sec. Calculate the magnitude of acceleration of P for an instant when its velocity along the rod from O towards A is max.

**Ans:**  $R = 200 + 50 \sin 2\pi nt$   $\therefore n=2$

$\therefore R = 200 + 50 \sin 4\pi t$   $\begin{matrix} \neq 200 \\ \neq 200\pi \\ \neq 0 \end{matrix}$

$\dot{R} = 200\pi \cos 4\pi t$   $\begin{matrix} \neq 200\pi \\ \neq 0 \end{matrix}$

$\ddot{R} = -800\pi^2 \sin 4\pi t$   $\begin{matrix} \neq 200\pi \\ \neq 0 \end{matrix}$

$\cos 4\pi t = 1$   
 $\therefore \sin 4\pi t = 0$

$\theta = \beta = 30^\circ$   $\dot{\phi} = 120 \cdot \frac{2\pi}{60} = 4\pi \text{ rad/sec}$

$\therefore \dot{\theta} = \ddot{\theta} = 0$   $\dot{\phi} = 0$


$a_r = \ddot{r} - r\dot{\theta}^2 - r\dot{\phi}^2 \sin^2 \theta$   
 $= 0 - 200 \times 0 - 200 \sin^2 30^\circ \times (4\pi)^2 = -800\pi^2 \text{ m/sec}^2$  ✓

$a_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta} - r\dot{\phi}^2 \cos \theta \sin \theta$   
 $= 0 + 0 - 200 \sin 30^\circ \cos 30^\circ (4\pi)^2 = -800\sqrt{3} \pi^2 \text{ m/sec}^2$  ✓

$a_\phi = 2\dot{r}\dot{\phi} \sin \theta + 2r\dot{\theta}\dot{\phi} \cos \theta + r\dot{\phi}^2 \sin \theta \cos \theta$   
 $= 2 \times 200\pi \times 4\pi \sin 30^\circ + 0 + 0 = 800\pi^2 \text{ m/sec}^2$  ✓

$a_r, a_\theta, a_\phi$

$a = \sqrt{a_r^2 + a_\theta^2 + a_\phi^2} = 17660 \text{ m/sec}^2$  !



Now, let us look at another problem statement. The rod OA is held at the constant angle  $\beta = 30^\circ$  while it rotates about the vertical with a constant angular rate  $\dot{\phi} = 120 \text{ revolution/minute}$  simultaneously the sliding ball. P oscillates along the rod with its distance in mm from the fixed pivot O given by  $R = 200 + 50\sin 2\pi nt$  where the frequency of oscillation along the is constant and it is equal to 2 cycle/second, and we have been asked to calculate the magnitude of the acceleration of P for an instant when its velocity along the rod from O towards A is maximum.

In this question, the rod O is rotating with a constant angular velocity about point O, and the ball P is making an oscillatory motion. We have to determine the acceleration of P. So, first of all, we have to identify the right coordinate system and for this problem, the right coordinate system is the spherical polar coordinate. Therefore, we can find out the acceleration if we know what is  $a_r$ , what is  $a_\theta$  and what is  $a_\phi$ . So, let us see the situation. In the question, we have been given that  $R = 200 + 50\sin 2\pi nt$  and  $n = 2$ .

$R$  becomes  $200 + 50\sin 4\pi t$ . And therefore,  $\dot{R}$  becomes  $200\pi\cos 4\pi t$ , and  $\ddot{R}$  is  $-800\pi^2\sin 4\pi t$ . Now, we have to find out the acceleration of point P. for an instant when the velocity is maxima. So, velocity maxima means  $\dot{R}$  has to be maxima and it can be maxima if  $\cos 4\pi t = 1$ . Therefore,  $\dot{R}$  will be  $200\pi$  and if  $\cos 4\pi t = 1$ , then  $\sin 4\pi t$  will be 0. Therefore,  $\ddot{R}$  will be 0 and  $R$  will be 200.

Now, in the question, we have been given  $\beta = 30^\circ$ . Now,  $\beta$  is the angle that it makes from the z axis and this angle in our formalism, we have taken it as  $\theta$ . So, therefore,  $\dot{\theta}$  and  $\ddot{\theta}$  will be 0 because  $\theta$  is constant. In the question, we have also given  $\dot{\phi} = 120 \text{ revolution/minute}$ . So  $\dot{\phi} = 120 \text{ revolution/minute}$ .

So, let us convert it into *radian/second*. So  $2\pi/60$ , which is  $4\pi \text{ radian/s}$ . Again, it is constant. Therefore,  $\ddot{\phi}$  will be 0. Now, we are in a situation to find out what is  $a_r$ , what is  $a_\theta$  and what is  $a_\phi$ .

So,  $a_r$  will be  $\ddot{r} - r\dot{\theta}^2 - r\sin^2\theta\dot{\phi}^2$ . Now, let us put these values. So,  $\ddot{r}$  is 0 –  $r$  is  $200\theta^2$ . So,  $\dot{\theta}$  is 0 –  $r$  is  $200\sin^2\theta$  is  $30^\circ$  and  $\dot{\phi}$  is  $4\pi$ . So,  $4\pi^2$  and this you can find out this is equal to  $-800\pi^2 \text{ m/s}^2$ .

Now, let us look at  $a_\theta$ .  $a_\theta$  is  $r\ddot{\theta} + 2\dot{r}\dot{\theta} - r\sin\theta\cos\theta\dot{\phi}^2$  and again  $r$  is 200 but  $\ddot{\theta}$  is 0 and  $\dot{\theta}$  is also 0. – $r$  is  $200\sin 30^\circ\cos 30^\circ\dot{\phi}^2$ .  $\dot{\phi}$  is  $4\pi^2$ , and this you can find out it is equal to  $-800\sqrt{3}\pi^2 \text{ m/s}^2$ . Now, let us look at  $a_\phi$ .

$A_\phi$  is  $2\dot{r}\dot{\phi}\sin\theta + 2r\dot{\theta}\dot{\phi}\cos\theta + r\sin\theta\ddot{\phi}$ . So, now let us put the values. This is equal to  $2\dot{r}$ .  $\dot{r}$  is  $200\pi$ .  $\dot{\phi}$  is  $4\pi$ . And  $\sin 30^\circ + 2r\dot{\theta}$ ,  $\dot{\theta}$  is 0 +  $r\sin\theta\ddot{\phi}$  is also 0. So, therefore, this comes out to be  $800\pi^2 \text{ m/s}^2$ . Now, total  $a$  will be  $\sqrt{a_r^2 + a_\theta^2 + a_\phi^2}$  plus which is equal to square root of this square plus this square plus that square and this is equal to  $17660 \text{ m/s}^2$ .

With this, let me stop here. See you in the next class. Thank you.