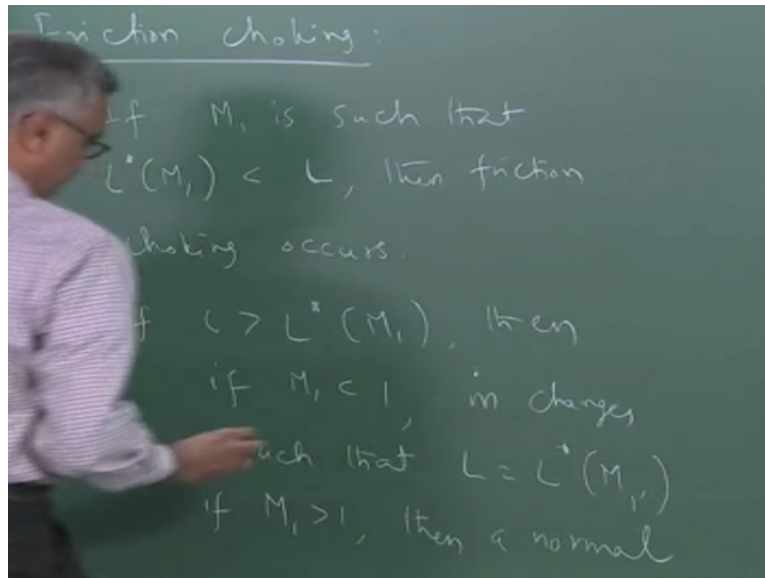


Gas Dynamics and Propulsion
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Lecture - 12
Fanno Flow

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In the previous class we looked at friction choking and its consequences. So in the subsonic and the supersonic case, if the Mach number M_1 is such that the L^* corresponding to that M_1 is $<$ the length of the duct L , then friction choking occurs and we said that if friction choking occurs depending upon the length of the duct in comparison to L^* , in the subsonic case, the mass flow rate is adjusted.

So if for example L is $> L^*$ corresponding to the given inlet Mach number. Then if the Mach number M_1 is < 1 , M dot changes. So we saw that in the subsonic case, the mass flow rate through the duct changes to accommodate the new length. So M dot changes such that the L^* corresponding to the new one for $L = L^*$ corresponding to the new operating condition.

And if the Mach number initial, the inlet Mach number is supersonic, if $M_1 > 1$, then a normal shock occurs in the duct.

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shock stands in the duct.

Calculation procedure:

$$P_1 u_1 = P_2 u_2$$

$$\frac{P_1}{RT_1} M_1 \sqrt{\gamma RT_1} = \frac{P_2}{RT_2} M_2 \sqrt{\gamma RT_2}$$

$$\frac{P_2}{P_1} = \frac{M_1}{M_2} \sqrt{\frac{T_2}{T_1}}$$

Since $T_0 = T_1 \left(1 + \frac{\gamma-1}{2} M_1^2\right)$
 $= T_2 \left(1 + \frac{\gamma-1}{2} M_2^2\right)$

So the location of the normal shock has to be determined iteratively. We will work out numerical example that illustrates how this iterative process works. We will look at both the cases through worked examples. So now we take a look at calculation procedure. How do we do practical calculations using the theory that we have developed so far. So calculation procedure here is the same as what we did for Fanno flow.

So if you remember from our governing equations we have written down $\rho_1 U_1 = \rho_2 U_2$ and if I substitute for ρ_1 in terms of P_1 , so I can write this as P_1/RT_1 and for U_1 I can substitute in terms of Mach number and the speed of sound, so this is $M_1 \sqrt{\gamma RT_1}$ that is $= P_2/RT_2$ times $M_2 \sqrt{\gamma RT_2}$. And if I rearrange this, I get $P_2/P_1 = M_1/M_2 \sqrt{\gamma T_2/T_1}$.

Now in this particular flow there is no heat addition, so stagnation temperature remains constant. So we can write this as since $T_0 = T_1 \left(1 + \frac{\gamma-1}{2} M_1^2\right)$ and this is also $= T_2 \left(1 + \frac{\gamma-1}{2} M_2^2\right)$.

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$$\frac{T_2}{T_1} = \frac{1 + \frac{\gamma-1}{2} M_1^2}{1 + \frac{\gamma-1}{2} M_2^2}$$

$$\frac{P_2}{P_1} = \frac{M_1}{M_2} \sqrt{\frac{1 + \frac{\gamma-1}{2} M_1^2}{1 + \frac{\gamma-1}{2} M_2^2}}$$

$$\frac{P_{02}}{P_{01}} = \frac{P_2}{P_1} \cdot \frac{P_1}{P_01} = \left(1 + \frac{\gamma-1}{2} M_2^2\right)^{\gamma/\gamma-1} \cdot \frac{M_1}{M_2} \sqrt{\frac{1 + \frac{\gamma-1}{2} M_1^2}{1 + \frac{\gamma-1}{2} M_2^2}} \cdot \frac{1}{\left(1 + \frac{\gamma-1}{2} M_1^2\right)^{\gamma/\gamma-1}}$$

So I can write T_2/T_1 as follows. $T_2/T_1 = 1 + \gamma - 1/2 * M_1$ square divided by $1 + \gamma - 1/2 * M_2$ square. And I can actually substitute for T_2/T_1 from here into this equation. So I still have T_2/T_1 in the right hand side. So if you substitute from there, I can get P_2/P_1 to be = $M_1/M_2 * \text{square root of } 1 + \gamma - 1/2 * M_1 \text{ square} / 1 + \gamma - 1/2 * M_2 \text{ square}$. And I can write P_{02}/P_{01} in the same way as we did earlier.

So P_{02}/P_{01} , remember this is a flow with friction which is an irreversibility, so the entropy increases and there is a loss of stagnation pressure as a result of the increase of entropy. So P_{02}/P_{01} can be written as $P_{02}/P_2 * P_2/P_1 * P_1/P_{01}$. And you know that P_{02}/P_2 is nothing but $1 + \gamma - 1/2 * M_2$ square raise to the power $\gamma/\gamma - 1$ and P_2/P_1 is given from here. So this can be written as $M_1/M_2 * \text{square root of } 1 + \gamma - 1/2 * M_1 \text{ square} / 1 + \gamma - 1/2 * M_2 \text{ square}$.

And P_{01}/P_1 is going to be $1 / 1 + \gamma - 1/2 * M_1$ square raise to the power $\gamma - 1$. So now we have all the quantities that we are looking for. M_1 is known, so if you look at these four expressions, M_1 is known, that is the Mach number at the inlet. If I know M_2 then all the quantities that I need are known. So we calculate M_2 from the momentum equation. So we will do something like this. So we will start with the differential form of the momentum equation.

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$$dP + \rho u du + \frac{4}{D_h} \cdot \frac{1}{2} \rho u^2 \cdot f dx = 0.$$

$$dP + \frac{P}{RT} M^2 \gamma \frac{du}{u} + \frac{4}{D_h} \cdot \frac{1}{2} \cdot \frac{P}{RT} M^2 \gamma f dx = 0.$$

$$\frac{dP}{P} + \gamma M^2 \frac{du}{u} + \frac{4f}{D_h} \cdot \frac{\gamma M^2}{2} dx = 0.$$

Eliminate $\frac{dP}{P}$ and $\frac{du}{u}$ in favor of $\frac{dM}{M}$ to get

$$\frac{M^2 - 1}{\gamma M^2} \cdot \frac{1}{1 + \frac{\gamma - 1}{2} M^2} \frac{dM^2}{M^2} = -\frac{4f}{D_h} dx.$$

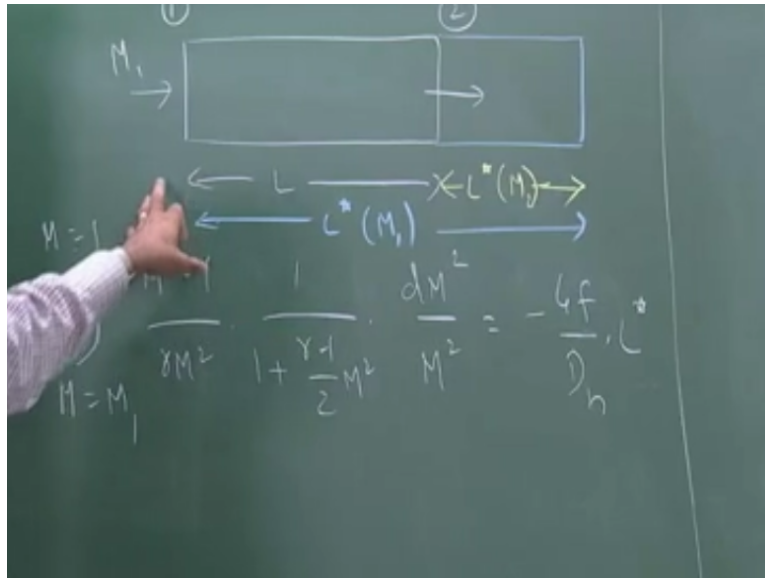
So we can write the momentum equation in differential form like this. If you take a small control volume and write the differential form of the momentum equation, it looks like this. f is the friction factor, remember f is the Darcy friction factor. Please remember that. And if I make use of the equation of state and the definition of Mach number I can write this as $dP + P/RT * M^2 * \gamma * dU/U$.

Notice that I have multiplied and divided this term by U . So I get a U square here and a dU/U . So U square can be written as $M^2 * \gamma * RT$. And I have done the same thing, here $4/DH * 1/2 * P/RT * \gamma * U^2 * f dx = 0$. Oh, I am sorry, this is $M^2 * \gamma * RT$. The square root disappears, so there is no square root here.

So we can easily see that the RT cancels out in both these terms and the P can be brought to the denominator. So I end up with an equation that looks like this, $dP/P + \gamma M^2 * dU/U + 4f/Dh * \gamma M^2 / 2 * dx = 0$. And we derive relationships earlier for dP/P and dU/U in terms of dM/M . So if you use those relationships, so eliminate dP/P and dU/U in favor of dM/M so we can get relationship which looks like this.

So, I am going to leave the algebra to you. So I will just write down the final expression. It is $\frac{M^2 - 1}{\gamma M^2} * \frac{1}{1 + \frac{\gamma - 1}{2} M^2} * \frac{dM^2}{M^2} = -\frac{4f}{Dh} dx$. So this equation that we have written down, finally gives me an expression involving duct length and change of Mach number.

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So I have two ways in which I can proceed now, just like we discussed earlier if I have a duct of length let us say L , and this is state 1, this is state 2. M_1 is known here, I can integrate this equation, left hand side from M_1 to some M_2 which is not known and the right hand side can be integrated from 0 to L . So that will give me L . So right hand side when integrated from 0 to L will give me L .

So I will have a highly non linear equation involving M_2 from the left hand side. I can solve that and get M_2 . Now this means I have to solve a non linear equation every time. So I need to have very complex tables. The other problem is such non linear equations also have multiple solutions. So we avoid this by using the same trick that we used before. So what I am going to do is I am going to take a certain value of M_1 and integrate from that M_1 to $M = 1$.

So the right hand side if I do that will give me L^* corresponding to that Mach number, right? So let me write this down and then we will see. So the left hand side, I am going to integrate from sum $M = M_1$ to $M = 1$. So this is $M^2 - 1/\gamma M^2 * 1/1 + dM^2/M^2 = -4f/Dh$ times, in this case this becomes the L^* corresponding to L_1 . Notice that we are assuming that the friction factor f is constant along the length of the duct.

In fact we are not accounting for variations in the friction factor usually for this problems you will notice that for the kind of Reynolds number that we are operating at, friction factors will not vary significantly. So this is a very good engineering assumption. So this is L^*

corresponding to M_1 . Notice that now I am not solving any equation. I am just obtaining this integral this can actually be evaluated in close form.

So what I do is, I take M_1 to be point 1, point 2, point 3, point 4, so I tabulate this for all values of subsonic Mach numbers. I do the same thing for supersonic Mach numbers also, right? I can start from 1.1, 1.2, so I tabulate this and then I don't have to solve the equation. So if I know M_1 , I calculate L^* corresponding to that M_1 . So L^* corresponding to that M_1 maybe something like this, right?

So this maybe L^* corresponding to M_1 . But because we are operating on the same branch of the Fanno curve, this is nothing but L^* corresponding to M_2 . So with the known value of M_1 , I calculate L^* from this tabulation, I know L^* corresponding to M_1 . I subtract the length of the duct; I get L^* corresponding to M_2 . So I go to the table again and see what is the value of M_2 which corresponds to this value of L^* .

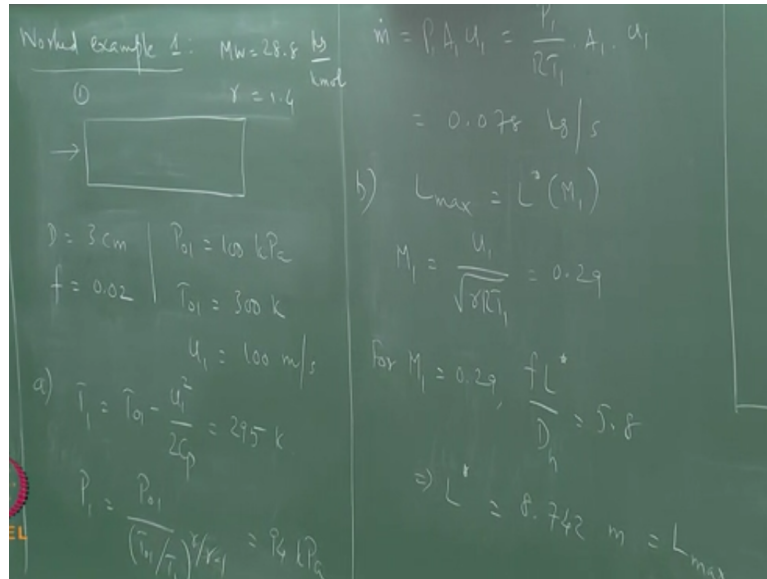
That is the basis of the calculation procedure. Same is what we did for Rayleigh flow also, okay? So if this is tabulated, we don't have to solve any equations at all. It is a very effective way of doing calculation and that is what we are going to do. We are going to use this table to do these calculations. Any questions before we do that? **“Professor - student conversation starts”** (()) (15:48).

The friction coefficient depends upon, primarily upon or only upon the Reynolds number, the friction stress depends up on the hydraulic diameter. But the friction factor depends only the Reynolds number. And you will notice that for the kind of speeds with which we are working, the Reynolds number based on hydraulic diameter will be so high that you are essentially operating in a region where the friction factors are constant.

So in fact you are far to the right on the Moody's chart where you notice that the friction factor is independent of Reynolds number, that is the kind of region that we are operating in. So that is a very good engineering approximation to use. **“Professor - student conversation ends”**. So let us do a worked example. Next we will do two of the examples in this module, one for a subsonic entry Mach number, another one for a supersonic Mach number.

And in both cases, we will look at situations when L is $< L^*$ and L is also $> L^*$. So the first example that we are going to do reads like this. Air enters 3 cm diameter pipe with a stagnation pressure and temperature of 100 K pascal and 300K and a velocity of 100 m/s/. Compute A, the mass flow rate, B, the maximum pipe length for this mass flow rate and C mass flow rate for a pipelength of 14.5 m. Take f to be 0.02 for the calculation.

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So let us write down the information here. So this is, let us call the worked example 1. So are given a pipe. The diameter of the pipe is given to be 3 cm. Friction factor f is given to be 0.02, remember this is Darcy friction factor and at entry to the duct, so this is state 1, we have been given, $P_{01} = 100$, $T_{01} = 300$ kelvin and U_1 is given to be 100 m/s. So we are asked to calculate first the mass flow rate, \dot{M} through the pipe.

So to calculate mass flow rate we need to know the static condition, stagnation conditions are given here. So let us start with the static conditions. So T_1 is going to be T_{01} minus U_1 square/ $2C_p$ and if you substitute the numbers that are given here for T_{01} and U_1 and you will also say that molecular weight, we will use molecular weight for air to be 28.8 kg per kmol and γ for air to be 1.4.

So if you substitute these numbers we will get static temperature to be 295 kelvin. And this static pressure P_1 is nothing but P_{01} divided by $(T_{01}/T_1)^{\gamma/(\gamma-1)}$, I am sorry, $\gamma/(\gamma-1)$. And so the static pressure comes out to be 94

kilo pascal. So the mass flow rate, \dot{M} is $\rho_1 A_1 U_1$ and ρ_1 is nothing but P_1/RT_1 times $A_1 U_1$.

So all the quantities are known in this. A_1 is nothing but $\pi d^2/4$ where d is the diameter of the duct. So if you plug in the numbers, you get the mass flow rate to be 0.078 kg per second for part A. Now part B asks us to determine the maximum length of the pipe that I can have for this mass flow rate. So the maximum length is going to be $= L^*$ corresponding to the inlet Mach number, so let us look at part B.

So part B for the mass flow rate to remain the same, the maximum length that I can have is L^* corresponding to M_1 . And M_1 we can calculate like this, $M_1 = U_1/\text{square root of } \gamma RT_1$ and this comes out to be roughly 0.29. So we have to use the tables for this.

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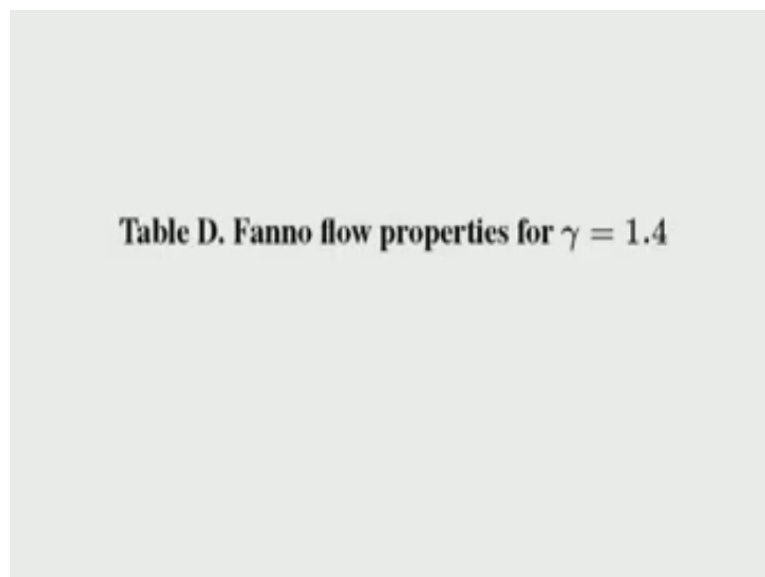


Table D. Fanno flow properties for $\gamma = 1.4$

So let us look at the tables. So we are now using table B which corresponds to Fanno flow and you will notice that the table lists data like this Mach number.

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M	$\frac{P}{P^*}$	$\frac{T}{T^*}$	$\frac{\rho}{\rho^*}$	$\frac{P_0}{P_0^*}$	$\frac{fL^*}{Dh}$
0.01	1.09543E+02	1.19998E+00	9.12880E+01	5.78738E+01	7.13440E+03
0.02	5.47701E+01	1.19990E+00	4.56454E+01	2.89421E+01	1.77845E+03
0.03	3.65116E+01	1.19978E+00	3.04318E+01	1.93005E+01	7.87081E+02
0.04	2.73817E+01	1.19962E+00	2.28254E+01	1.44815E+01	4.40352E+02
0.05	2.19034E+01	1.19940E+00	1.82620E+01	1.15914E+01	2.80020E+02
0.06	1.82508E+01	1.19914E+00	1.52200E+01	9.66591E+00	1.93031E+02
0.07	1.56416E+01	1.19883E+00	1.30474E+01	8.29153E+00	1.40655E+02
0.08	1.36843E+01	1.19847E+00	1.14182E+01	7.26161E+00	1.06718E+02
0.09	1.21618E+01	1.19806E+00	1.01512E+01	6.46134E+00	8.34961E+01
0.10	1.09435E+01	1.19760E+00	9.13783E+00	5.82183E+00	6.69216E+01
0.11	9.94656E+00	1.19710E+00	8.30886E+00	5.29923E+00	5.46879E+01
0.12	9.11559E+00	1.19655E+00	7.61820E+00	4.86432E+00	4.54080E+01
0.13	8.41230E+00	1.19596E+00	7.03394E+00	4.49686E+00	3.82070E+01
0.14	7.80932E+00	1.19531E+00	6.53327E+00	4.18240E+00	3.25113E+01
0.15	7.28659E+00	1.19462E+00	6.09948E+00	3.91034E+00	2.79320E+01
0.16	6.82907E+00	1.19389E+00	5.72003E+00	3.67274E+00	2.41978E+01
0.17	6.42525E+00	1.19310E+00	5.38533E+00	3.46351E+00	2.11152E+01
0.18	6.06618E+00	1.19227E+00	5.08791E+00	3.27793E+00	1.85427E+01
0.19	5.74480E+00	1.19140E+00	4.82190E+00	3.11226E+00	1.63752E+01
0.20	5.45545E+00	1.19048E+00	4.58258E+00	2.96352E+00	1.45333E+01
0.21	5.19355E+00	1.18951E+00	4.36613E+00	2.82929E+00	1.29560E+01
0.22	4.95537E+00	1.18850E+00	4.16945E+00	2.70760E+00	1.15961E+01
0.23	4.73781E+00	1.18744E+00	3.98994E+00	2.59681E+00	1.04161E+01
0.24	4.53829E+00	1.18633E+00	3.82548E+00	2.49556E+00	9.38648E+00
0.25	4.35465E+00	1.18519E+00	3.67423E+00	2.40271E+00	8.48341E+00
0.26	4.18505E+00	1.18399E+00	3.53470E+00	2.31729E+00	7.68757E+00
0.27	4.02795E+00	1.18276E+00	3.40556E+00	2.23847E+00	6.98317E+00
0.28	3.88199E+00	1.18147E+00	3.28571E+00	2.16555E+00	6.35721E+00
0.29	3.74602E+00	1.18015E+00	3.17419E+00	2.09793E+00	5.79891E+00

For each Mach number you get all the quantities that you want, P/P^* , T/T^* , ρ/ρ^* , P_0/P_0^* and fL^*/Dh . So now our Mach number is 0.29, so let us see, so corresponding to 0.29 which is over here, fL^*/Dh is 5.79891, right? Let us write this down. So corresponding to so for $M1 = 0.29$, fL^*/Dh comes out to be approximately 5.8. Let us use 5.8 for this. So from which I can calculate my L^* corresponding to this smart number to be about 8.742 meters.

“Professor - student conversation starts” Sir when do we use whole fL square by Df ? I have consistently said throughout that we are using the Darcy friction factor. Now, in the aerospace community they use a friction factor called manning friction factor which is actually off from this number by a factor of 4. The Darcy friction factor is the most widely used friction factor in connection with flow through pipes and ducts and so on.

So that is what we are using, that is why you don't see the $4f$ there. So the manning friction factor for the same case instead of f being 0.02, the manning friction factor for this case would have been 0.005. So the 4 times that is equal to this. But Darcy friction factor is the most widely used, all the correlation gives only this which is why we are using this, okay?

“Professor - student conversation ends”.

Please note that when you are using the Darcy friction factor we should not use tables that have the last column as $4 fL^*/Dh$, if you see $4 fL^*/Dh$ in the last column, notice that the last column in the table that we are using is fL^* over Dh , the last column is $4 fL^*$ over Dh , that would usually mean that the f that is being used that is the manning friction factor and not the Darcy friction factor.

So this tells me that the maximum length that I can have for this mass flow rate is 8.742 meters. So if I use a 3 cm diameter pipe, so I have my experimental set up for some other device set up over here and my compressed air tank is let us say further down, if the pipe length that I am using is more than 8 meters then I will not get this mass flow rate, it has to be below 8.7 meters for me to get the same mass flow rate that I am looking for, okay?

Part C of the question says, what would be the mass flow rate if the length of the pipe is 14.5 meters more than this maximum value that is part C.

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$\dot{m} = ?$, if $L = 14.5$ m.
 Since $L > L^*(M_1)$, we expect the inlet static state to change to a new state $1'$ such that $L^*(M_{1'}) = L$
 $\frac{fL}{D_h} = \frac{0.02 \times 14.5}{0.03} \Rightarrow M_{1'} = 0.29$ from the table
 $T_{1'} = \frac{T_{01}}{\left(1 + \frac{\gamma-1}{2} M_{1'}^2\right)} = 297$ K ; $P_{1'} = \frac{P_{01}}{\left(1 + \frac{\gamma-1}{2} M_{1'}^2\right)^{\frac{\gamma}{\gamma-1}}} = 96.1$ kPa

So part C $\dot{m} = 1$ if $L = 14.5$ meters. So now since L is $> L^*$, is $> L^*$ corresponding to M_1 which is 0.29, we expect the mass flow rate to decrease and the inlet conditions to be different. Since $L > L^*$, we expect being at static state to change to a new state which we are going to call let us say $1'$ such that L^* corresponding to $M_{1'} = L$.

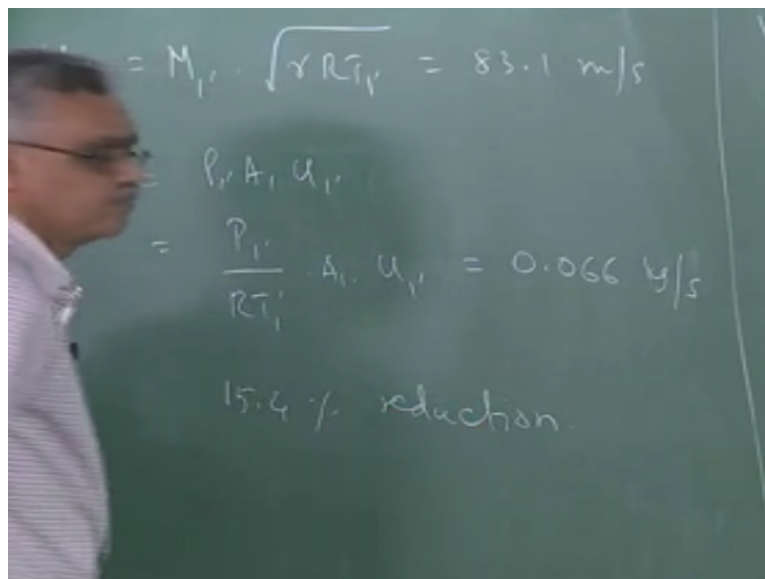
And again we have not been given any information about the exit pressure. If exit pressure is specified, then we need to determine an inlet static state which is such that the pressure at the exit of the duct matches the exit ambient pressure. Since nothing has been given, we will assume that it comes out at the sonic state, okay? So from the given length of 14.5, then let us calculate fL/D_h .

For this value comes out to be 0.02 times 14.5 centimeters divided by this is a pipe, so you know that hydraulic diameter of the pipe is same as the diameter of the pipe. So that is 14.5

meters, so this is 0.03 meters. So if I go to the tables with this value, so this corresponds to M_1 prime which is = 0.24 from the table. So the inlet Mach number changes from 0.29 to 0.24.

But the stagnation conditions remain the same, so T_1 prime = T_01 divided by $1 + \frac{\gamma - 1}{2} M_1^2$ and T_01 remains the same, so this comes out to be 297 kelvin. And P_1 prime can be calculated in the same manner (()) (29:16) $P_01 / (1 + \frac{\gamma - 1}{2} M_1^2)^{\frac{\gamma}{\gamma - 1}}$ and this comes out to be 96.1 kilopascal.

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Now the velocity U_1 prime is nothing but M_1 prime * square root of $\gamma R T_1$ prime and if you substitute the numbers the velocity comes out to be 83.1 meter per second, slightly different from what we had before, earlier we had 100 m/s, now we have 83 meter per second. So the new \dot{m} is called the \dot{m} prime, is once again ρ_1 prime A_1 U_1 prime and that is nothing but P_1 prime divided by $R T_1$ prime * A_1 * U_1 prime.

And this works out to 0.066 kilogram per second which is 15.4% reduction. So if you design compressible equipment expecting certain inlet conditions and if your pipe is let us say longer than, if you don't know the design and you just simply use a very long pipe then the mass flow rate as you can see is going to be substantially different from what you are hoping to get. Okay, that is the reason why it is very important to study Fanno flow.

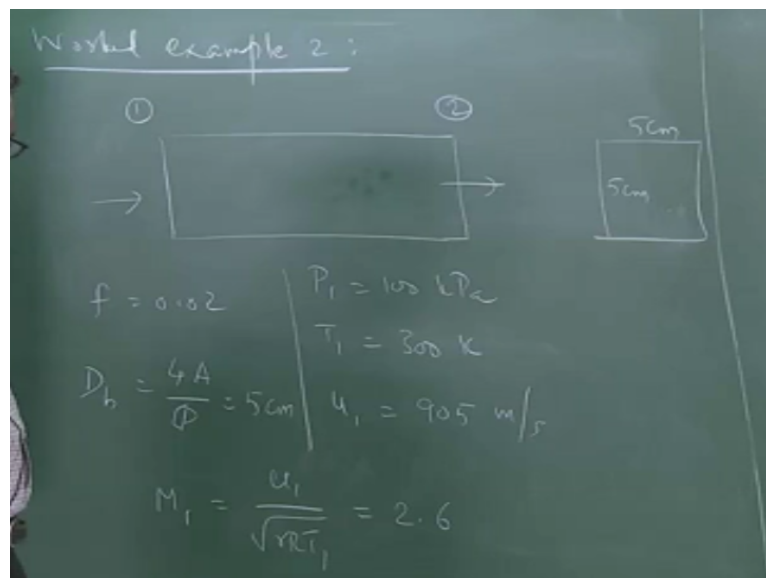
The effective of friction can be quite significant and the change in inlet condition is also quite significant. Notice that at the exit state now, which you are using a 15-meter-long pipe the

exit side Mach number is one. Whereas you might have designed the equipment for some other inlet Mach number, the equipment which is connected to the end of the pipe, you may be expecting some Mach number and some mass flow rate whereas the conditions are totally changed now.

So if you want to use a longer pipeline then what you need to do to avoid friction choking is to increase the diameter of the pipe, is the larger diameter and then design the pipes properly so that you get the conditions that you are looking for, okay? So that is the big example where we looked at the inlet state, subsonic inlet state, the next example that we are going to do will use a supersonic inlet state and will see how the changes takes place.

The next worked example reads as follows, air enters 5 cm x 5 cm square duct at 300 kelvin, 100 kilopascal and a velocity of 905 meter per second. If the duct length is 2 meters find the flow properties at the exit, take f to be = 0.02. So here we are given a square duct, so the cross section of the duct is square. 5 cm x 5 cm, f is given to be 0.02.

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The inlet state we are given the let us assume these to be static conditions since nothing is said, so we take P_1 to be 100 Kpa and T_1 to be 300 kelvin and U_1 is given to be 905 meter per second and the hydraulic diameter the cross section is given, so the hydraulic diameter, so you remember is 4 times the area divided by the perimeter. So 4 times the cross sectional area divided by the perimeter.

For this case gives me the hydraulic diameter to be 5 centimeters again, coincidentally, okay? Now you may wonder how this can possibly happen in real life. Why would I want to have a flow that is entering at velocity of 905 meter per second into a duct. This can very easily happen if for example you are doing let us say supersonic flow experiments in a wind tunnel, right, so we may have a nozzle which is connected to this.

This maybe your test section where you are going to keep some objects and other things that you want to test let us say in a supersonic stream. So in such cases you will definitely get this type of flow situation. So it is very important that you study this type of flow, so they do occur in real life. So let us start this, since the static conditions are already given we can calculate the initial Mach number M_1 as $U_1/\text{square root of } \gamma R T_1$ and this I get to be 2.6.

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For $M_1 = 2.6$, $\frac{fL}{D_h} = 0.4526$
 from the Fanno table
 $L^*(M_1) = \frac{0.4526 \times D_h}{f} = 1.1315 \text{ m}$
 Since $L > L^*(M_1)$ and $M_1 > 1$,
 a normal shock stands in the duct.

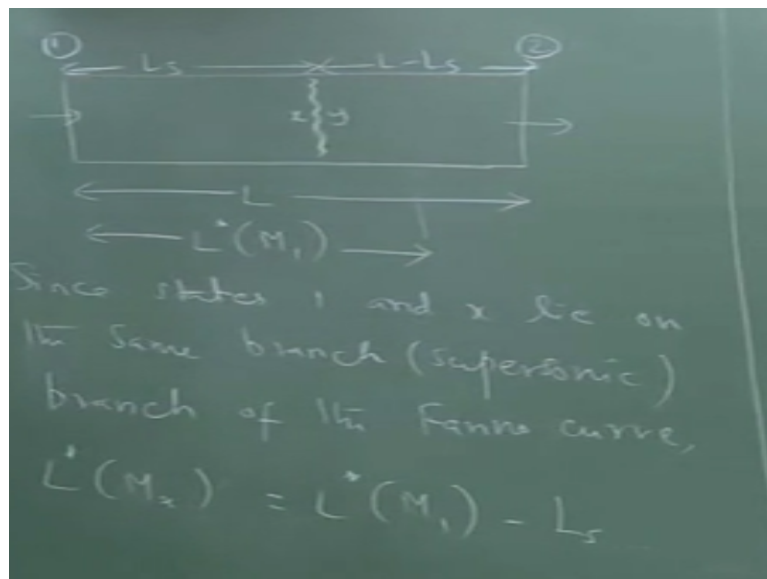
So for $M_1 = 2.6$, fL^*/D_h comes out from the table as, I am sorry, fL^*/D from the table it can get to be 0.4526 from the Fanno table. So this gives me L^* , corresponding to the Mach number M_1 to be $0.4526 \times D_h / f$ which comes out to be 1.1315 meter. And the problem statement stated that the length of the duct was 2 meters. Okay? Questions? **“Professor - student conversation starts”**

Sir that thing, using (()) (38:48) is 1.3 likely. Please look in the supersonic (()) (38:58) 2.6 Mach number over (()) (39:02) 1.4., so 1.3/3. No, what I have is correct. That maybe $4 FL^*$ but we are not using that, we have to use a table with is FL^* . Using Darcy friction factor, not Fanno friction factor. Okay, 1.1315 meters, that is what we have used, okay? So notice that

what we have done here is we have gone to the Fanno table corresponding to $2.6 fL^*$ comes out to be 0.4526, that is what we have used, okay?

“Professor - student conversation ends”. So since the given length L is $>$ the L^* corresponding to M_1 and M_1 is > 1 , the inlet is supersonic, there is going to be a stance in the duct. So we have to locate where the normal shock is and then determine the exit properties. We discussed this scenario in the previous class. Let us recap this scenario before we proceed with our calculations, okay?

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So we have a duct, so this is state 1, this is state 2, this is L , okay, now let's say this is L^* corresponding to M_1 , right, remember for this example L was 2, but L^* corresponding to M_1 was $<$ L . So let us say this is L^* corresponding to M_1 . So normal shock stands somewhere in the duct like this. Let us say that the state 1 before the normal shock let us call that y , okay?

That is further state that the shock stands let us say at a distance L_s from the entrance of the duct, okay? Now state point 1 and state point x lie on the same branch of the Fanno curve, correct? So since states 1 and x lie on the same branch and that is the supersonic branch of the Fanno curve L^* corresponding to M_x is going to be L^* corresponding to M_1 minus L_s , okay? So that is one relationship that we have.

Now if no information about the exit is given, then we assume the exit states to be the sonic state.

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If we assume the exit state to be the sonic state, then

$$L^*(M_y) = L - L_s$$

If you assume, then notice that L^* corresponding to M_y is nothing but total length minus L_s , that is the remaining length, right, so this is $L - L_s$ and that has become $= L^*$ now, so if you assume the exit state to be sonic state then L^* corresponding to M_y is $L - L_s$. So the calculation has to proceed iteratively now. We assume the shock to be at some location. That is L_s is not, so then corresponding to M_1 we calculate L^* .

Then since we have assumed the value for L_s , I can get L^* of M_x . Corresponding to L^* of M_x from the supersonic part of the Fanno table I calculate M_x . With the value of M_x , I go to normal shock table to get my M_y . With the value of M_y , I go to the subsonic part of the Fanno table to calculate my L^* corresponding to M_y . I checked to see whether this value is equal to this value.

If they are not equal, then I adjust the shock location, I use a different value for L_s and repeat the same thing. That is the procedure that we are going to use. So we will write a table and then do these calculations in the next class.