

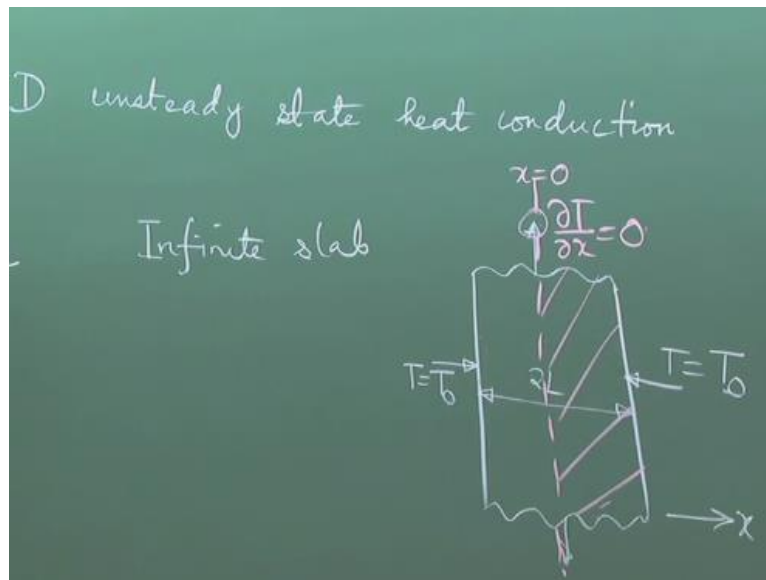
Conduction and Convection Heat Transfer
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Lecture - 16
One Dimensional Unsteady State Heat Conduction - I

In the previous class, we were discussing about the Lambda parameter approach of solving the unsteady state heat conduction problems. Now the Lambda approach, essentially neglects the special variation of temperature within the system. But there are certain problems where the special variation of temperature within the system is important and there you have to solve the temperature distribution as a combined function of position and time not just time but also a function of position and time.

So, we will discuss about such problems today. So, we will discuss about first, one dimensional unsteady state heat conduction.

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Now, it is a general broad topic and we will try to understand this particular issue with the help of some problems. So, we will first consider one problem of something called Infinite slab. So, what is this? Let us say we have slab which has a thickness of $2L$ and the direction in which it has a thickness of $2L$ is x direction. The other directions like these directions and the direction

perpendicular to the plane of the figure are infinitely large.

Because they are infinitely large the gradients along those directions are very small and therefore the corresponding second order derivative terms are neglected in the corresponding heat conduction equation. So, if we do that we will come up with the simplified equation. But because we are working with a problem let us keep the boundary conditions and then we will solve the problem. So, let us say that the temperature here is T equal to T zero.

We will first work out, a problem when both the temperatures are same. If the temperatures are different, I will not work out that problem. But I will give you some idea that based on what consideration you can solve the problem even if the temperatures are not the same. But to begin with let us consider that these two temperatures are equal which is T equal to T zero. So, considering that all the thermophysical properties are constant.

So, let us first write the energy equation, plus let us say we put a term for heat generation Now, let us try to see that which term of these equations are negligible as compared to the other terms let us look into that.

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The image shows a handwritten derivation of the heat conduction equation for a slab. The top equation is the general energy equation:

$$\rho C \frac{\partial T}{\partial t} = \frac{\partial}{\partial x} \left(k_x \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k_y \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k_z \frac{\partial T}{\partial z} \right) + \dot{q}$$

Arrows point from the $\frac{\partial}{\partial y}$ and $\frac{\partial}{\partial z}$ terms to the word "neglected". The equation is then simplified to:

$$\rho C \frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial x^2}$$

Below this, the governing equation is written as:

$$\text{gde: } \frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial x^2}$$

Boundary and initial conditions are listed on the right:

- ic At $t=0$, $T=T_i$ for all x
- bc At $x=0$, $\frac{\partial T}{\partial x} = 0$
- At $x=L$, $T=T_0$

So, this slab is much wider and much longer in height as compared to the thickness. So, the gradients along y and z directions are neglected. This is also neglected. If these are neglected and

also, we don't have any heat generation so this term is zero. Then how do we solve this problem? We solve this problem, by considering that K_x is a constant. If K_x is a variable it is not so easy to solve it analytically. This is our governing differential equation.

See, there is a very interesting thing when we solve this problem we say that we are assuming all thermophysical properties as constant. But you can see that actually taking K as constant is good enough it does not matter whether ρ C_p are constant or whatever because anyway ρ C_p come out of the derivative, right. So, ρ C_p or for a solid C_p become C ρ into C comes out the derivative not because ρ and C are constant.

But because of some other simplifications which we have already taken care of when we derive the energy equation. So, equation has the assumption that K is constant but it does not have an assumption that ρ C is constants, right. So, this is very illusive because ρ C out of the derivative may create an illusion that as if ρ and C are constants but these are not constants. So, this is the governing differential equation.

Now, this is a time dependent problem. So, this kind of problem in the theory of differential equation, are called as initial boundary value problems. So, you require initial conditions to specify that at time equal to zero what is the situation? So initial condition, at t equal to zero, temperature is equal to T_i for all x . This is let us say initial temperature and boundary condition.

Now, you can play a little bit of trick by reducing the size of the domain you can see that this problem is symmetrical on this side on this end whatever is the temperature at this end also the same temperature is there. So, it is symmetrical with respect to the central axis. So, also when we say symmetry we have to keep in mind that we are taking about symmetry in geometry and symmetry in boundary condition.

So here we have both symmetry in geometry and symmetry in boundary condition. So now because of symmetry you can solve half of the domain. Let us put, the origin here as x equal to zero whatever is the solution that we get for half of the domain the remaining this half will be symmetrical solution.

So, we can reduce the size of the problem. For analytical solution, it does not matter that much but if you are solving the problem computationally or numerically I mean reducing the total domain size will reduce your computational cost that is you will require less number of grid points to solve the problem and so on.

Computational time and computational cost will be less. So now can you tell what will be the boundary condition here? It should be partial derivative of T with respect to x equal to zero. So, at x equal to zero you have this and at x equal to L , T equal to T_0 . See you can make this problem very nicely tractable by method of separation of variables by transforming even both the boundary conditions to be homogeneous.

Right, if you define θ equal to T minus T_0 then this will give you θ equal to zero at x equal to zero.

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The image shows a chalkboard with handwritten mathematical derivations. On the left, it defines $\theta = T - T_0$ and lists boundary conditions: (1) At $x=0$, $\frac{\partial \theta}{\partial x} = 0$ and (2) At $x=L$, $\theta = 0$. On the right, it shows the governing partial differential equation $\frac{\partial \theta}{\partial t} = \alpha \frac{\partial^2 \theta}{\partial x^2}$ and the separation of variables assumption $\theta = f(x)g(t)$. This leads to the ordinary differential equations $fg' = \alpha f''g$ and $\frac{f''}{f} = \frac{g'}{g} = \text{each} = \text{const} = -\lambda^2$.

So, let us recast the problem by writing θ is equal to T minus T_0 . So, boundary condition at x equal to zero, At x equal to L , θ equal to zero. And the governing differential equation now, we will use the method of separation of variables. So, θ equal to let us say that θ is a product of a function of x and a function of time. So, you have $fg' = \alpha f''g$ from this. So, $\frac{f''}{f} = \frac{g'}{g} = \text{const} = -\lambda^2$.

Now when you write this equation, this is a function of x only, right. This is a function of T only. So, function of x only is equal to a function of T only. That means each must be a constant. Now the question is whether the constant is a positive constant or a negative constant. That we have to carefully figure out. Again, if you make a mistake as I told you that there are two ways of figuring it out one way is the hard way.

That let us say, you make a mistake you will see that it will not eventually satisfy your initial or boundary conditions. But there is a simple physical way of figuring it out. See, this is dg/dt , right. So, dg by g if you integrate it will be \ln of g . So, that will be equal to this α into the constant into T . So, what is g ? G is the time dependence of the problem eventually as you allow the time as T tends to infinity what will happen?

The time dependent part of the solution will vanish because it will attain a steady state in the limit as time tends to infinity this problem will attain a steady state. Because this problem will attain a steady state what it will mean? It will mean that the unsteady part of the solution will decay with time, right. Because it will decay with time and g will an exponential function of T a negative constant will imply an exponential decay.

Otherwise it will be an exponential rise. So, therefore we can say that this is equal to minus λ^2 . So, now let us apply the boundary conditions before applying the boundary conditions let us see the solution.

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$$\begin{aligned}
 \frac{1}{\alpha g} \frac{dg}{dt} &= -\lambda^2 \\
 \ln g &= -\alpha \lambda^2 t + \ln C_1 \\
 g &= C_1 e^{-\alpha \lambda^2 t} \\
 f'' + \lambda^2 f &= 0 \leftarrow \\
 f &= C_2 \cos \lambda x + C_3 \sin \lambda x \\
 0 &= \sum C_n e^{-\alpha \lambda_n^2 t} \cos \lambda_n x
 \end{aligned}$$

So, dg by dt , $1/\alpha g$, dg by g is what? \ln of g is equal to minus $\alpha \lambda^2 t$ plus \ln of some constant C_1 . So, g is equal to C_1 into the power minus $\alpha \lambda^2 t$. Now what is the solution for f ? \cos and \sin , right. So, $C_2 \cos \lambda x + C_3 \sin \lambda x$. The solution is related to the product of f and g . Now let us apply the boundary conditions. Boundary condition number one at x equal to zero, $\delta \theta / \delta x$ equal to zero this boundary condition.

That means basically dx will be equal to zero. So, if you make df/dx \cos will become \sin and \sin will become \cos , of course plus minus. I am not bothering. So, \cos will become \sin so at x equal to zero that term is automatically equal to zero and the derivative of this will be \cos . So, at x equal to zero you have C_3 , x equal to zero if f has to be zero then C_3 must be equal to zero, right.

Because if C_3 is not equal to zero then the entire solution is a trivial solution that is if f equal to zero solution itself is zero.

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Handwritten mathematical derivations on a chalkboard:

$$bc: (1) \Rightarrow C_3 = 0$$

$$(2) \Rightarrow \cos \lambda L = 0$$

$$\lambda L = (2n+1) \frac{\pi}{2}$$

$$\lambda_n = \frac{(2n+1)\pi}{2L}$$

$$\theta = \sum C_2 \cos \lambda x \cdot C_1 e^{-\alpha \lambda^2 t}$$

$$= \sum C_n e^{-\alpha \lambda_n^2 t} \cos \lambda_n x$$

The next is at x equal to L , θ equal to zero means you have $C_2 \cos \lambda L$ equal to zero again here C_2 cannot be zero because if both C_1 and C_2 are zero then what happens? Then it results in a trivial solution. So, only possibility is that $\cos \lambda L$ equal to zero. That means λL is $(2n+1)\pi/2$. Because there are infinite such possible values of n you have infinite such possible values of λ .

so, each λ is denoted by λ_n . So, λ_n equal to $(2n+1)\pi/2L$. This is the λ . This is the so called IN value of that problem. Now, the solution θ is you have C_3 equal to zero $C_2 \cos \lambda x$ into $C_1 e^{-\alpha \lambda^2 t}$. This is the solution but we have to keep in mind that there are n such possible values of λ for each value of λ this is the solution.

So, for n such possible values you have summation of these for over n that should be the solution. That is because of the linearity of the governing differential equation. So, the total solution is a sum total of the solution for each possible value of λ and λ will have infinite number of possible values. So, now in place of C_1 into C_2 let us write this as C_n into the power minus $\alpha \lambda_n^2 t$ into \cos .

So, the only part of the problems that remains is to calculate what is C_n ? If we find out what is C_n then that completes the solution of the problem. So, how do we calculate C_n ? To calculate C_n

we will refer to this equation.

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The image shows a chalkboard with handwritten mathematical derivations. The first equation is:

$$\int_{x=0}^{x=L} \frac{d^2 f_n}{dx^2} f_m dx + \lambda_n^2 \int_{x=0}^{x=L} f_n f_m dx = 0$$

The second equation is:

$$\left[f_m \frac{df_n}{dx} \right]_0^L - \int_0^L \frac{df_m}{dx} \frac{df_n}{dx} dx + \lambda_n^2 \int_0^L f_n f_m dx = 0$$

The third equation is:

$$\text{Swap } n \text{ \& } m \Rightarrow - \int_0^L \frac{df_n}{dx} \frac{df_m}{dx} dx + \lambda_m^2 \int_0^L f_n f_m dx = 0$$

The final equation, after subtraction, is:

$$\text{Subtract } (\lambda_n^2 - \lambda_m^2) \int_0^L f_n f_m dx = 0$$

So, we write, now we basically need to derive an orthogonality condition in the context of two-dimensional steady state problem we discussed what is an orthogonality condition. And similar orthogonality condition will be derivable here so how do we proceed towards deriving the derivable remember the objective of deriving the orthogonality condition is we can isolate C_n and we can figure out that for one value of m equal to n only that is none zero.

And for other cases the coefficient of C_n becomes zero. So that out of the summation you can isolate the C_n from the summation. So, now what we did we multiplied it by f_m and integrated by parts. The same thing we will do here. So dx then this is a higher order derivative so this we will put a second function and this we will put as first function. So, first function, this is second function.

So, first function into integral of the second minus integral of derivative of first into integral of the second. Now there are certain simplifications we can make see this boundary term at x equal to zero (()) (27:13) df_n/dx equal to zero. Because $\delta\theta/\delta x$ equal to zero and at x equal to L you have θ equal to zero that means f equal to zero. So that brings this entire boundary term equal to zero.

And that is why we actually had to use the homogenous boundary conditions. So that homogenous boundary condition clean up this boundary term either this equal to zero or this equal to zero either of this. These are homogenous boundary conditions. So that leads to products equal to zero and this term goes away. Now next what we do we write the same equation but swap n and m.

So, swap n and m and then subtract. If we subtract then what will happen these terms will be zero. I mean they will get cancelled and you will have lambda n square minus lambda m square integral of $f_n f_m dx$ from zero to L equal to zero.

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The image shows a chalkboard with the following handwritten text:

$$\int_0^L f_n f_m dx = 0 \text{ if } m \neq n$$

$$\neq 0 \text{ if } m = n$$

ic

$$\text{At } t=0, \theta = \theta_i = T_i - T_0$$

$$\theta_i = \sum C_n \cos \lambda_n x$$

$$\int_0^L \theta_i \cos \lambda_m x dx = \int_0^L \sum C_n \cos \lambda_n x \cos \lambda_m x dx$$

$$\Rightarrow C_m \int_0^L \cos^2 \lambda_m x dx = \int_0^L \theta_i \cos \lambda_m x dx \Rightarrow C_m = ?$$

So, this leads to integral of $f_n f_m dx$ zero to L equal to zero if m is not equal to n and is not equal to zero if m equal to n. which is the so-called orthogonality condition. Where f_n is what? f_n is $\cos \lambda_n x$, right. And λ_n is given by this equation. So, we can now attempt to find out what is C_n by applying the initial condition so far as our solution is concerned we have used only the boundary condition. We have not yet used the initial condition.

So, at initial condition at time equal to zero, theta equal to say theta i which is T_i minus T_0 . So, theta i is equal to summation of $C_m \cos \lambda_m x$. So, what we will do we will multiply both sides by $\cos \lambda_m x$, f_n into f_m and then integrate so theta i $\cos \lambda_m x dx$. Now by the orthogonality condition this product integral of this product is zero if m is not equal to n.

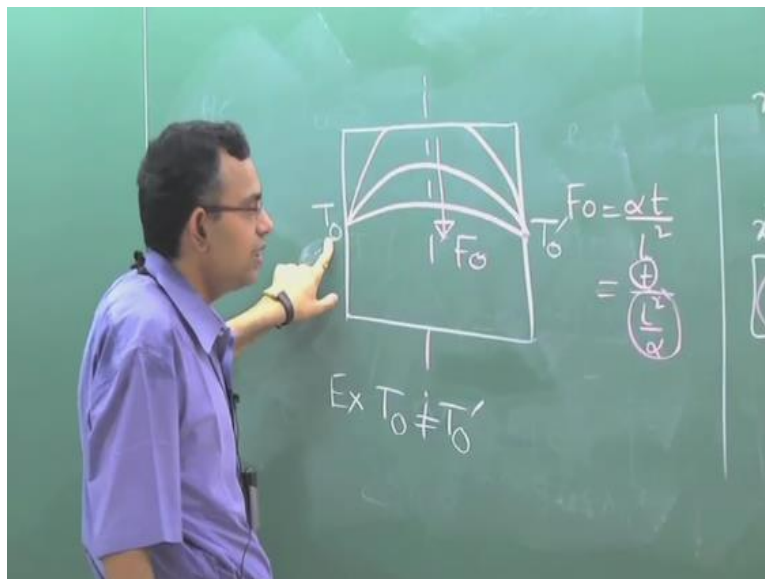
Only in one case it is non-zero when m is equal n .

So, this series will eventually be only one term, one non-zero term so that non-zero term. So that non-zero term if you isolate that means you can write $C_n \int_0^L \cos^2 \lambda_n x \, dx$, zero to L equal to integral of $\theta_i \cos \lambda_n x \, dx$. So, this will tell you what is C_n that completes the solution of the problem because once you know C_n you can substitute that here to get θ and see this solution is very general.

Because if the initial temperature is a function of position then also you can solve this problem. If initial temperature is constant then you just need to take this out of the integral otherwise if this a function of x you just put it as a function of x I am not going into the integration of sin, cos, sin and these terms. These are all high school level stuff and we should not waste time here we should better use the time to develop physical insight now into the solution, right.

So, let us try to do that. Now let us try to see that if you want to plot the solution of this problem how will the solution look?

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Let us say this is the domain. Of course, this is infinitely long but I have just truncated it and drawn it like this. So, if you consider the central line first of all it is the solution is symmetric with respect to the central line. So, at very early times the solution may be something like this,

right. At very early times then the solution becomes this as you progress with time and eventually if you go for time tends to infinity what will be the solution?

It will be uniform throughout, right. Because there is no heat source so as time tends to infinity then the steady state solution will be what? A constant so this is progressing time. Initially there will be a difference between see the slab has an initial temperature and you are subjected into a boundary condition so what will happen? There will be a difference between these two and that difference will trigger some heat transfer but that difference will be slowly nullified as you are proceeding with time.

In the limit as time tends to infinity the time dependent solution goes away. So, when you have the time dependent solution gone then you will be basically having just the special dependence of temperature. Now this you can blot also in terms of none dimensional number we have discussed about this which is Fourier number. So sometimes to make a none dimensional representation instead of T you plot it as a function of αT by l square.

We discussed that αT by l square which is the Fourier number, this is t by L square by α . So, this is the time divided by diffusion time, heat diffusion time. In fact, the entire solution the time dependent solution you can write as a function of two none-dimensional numbers the Biot number and the Fourier number. You should try to make an attempt to write the solution in terms of the none dimensional numbers Biot number and Fourier number.

We have defined both of these numbers in our previous lecture. The next point is that what will be the change in solution if we change the boundary condition. For example, we have considered both the ends to be at the same temperature T zero but let us say this end is at a different temperature then this. Then you cannot directly use the method of superposition of variables. So, what we have to do is basically you divide the problem into two problems.

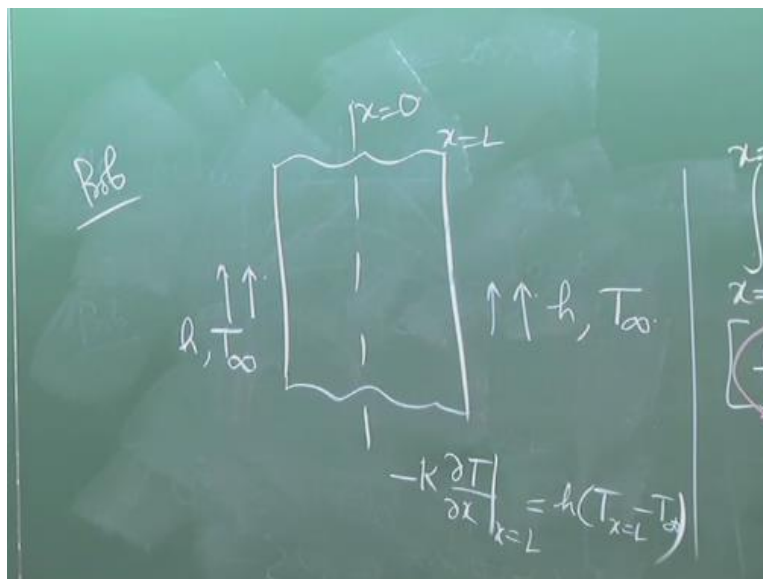
One problem is when both the ends are at the same temperature then you solve in this way and with that super imposed another problem when there is a differential of the temperature of the two ends and steady state solution of that. So, let us say that end is T zero and this end is T zero

dash so one problem is that you solve our steady state problem when this T zero let us say an example with T zero not equal to T zero dash.

So, you can solve a steady state problem by considering this radiant and there you do not consider any unsteadiness the entire unsteady as you dump on other problem where you have both ends at the same temperature and then that total solution is a linear superposition of that two solutions where for the second problem where you show the unsteady problem you can use this method. For the steady problem, it is a simple one-dimensional steady state heat conduction.

So net solution is the sum total of the two solutions you have to be a little bit careful of how to give initial condition for the unsteady problem but that I leave on you as an exercise. Let us say that instead of having a given temperature boundary condition we have another problem where we use the given convective heat transfer coefficient boundary condition.

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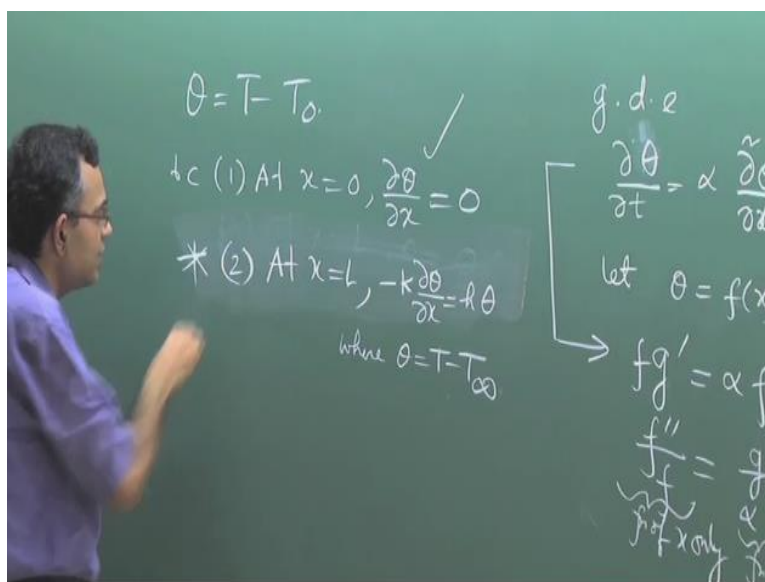
Let us say same infinite slab. Let us say that some fluid is flowing outside the slab with heat transfer coefficient h , and temperature T infinity. So, the only difference from the previous problem is that there is a different boundary condition. Previous problem what type of boundary condition it was? It was a Dirichlet type of boundary condition where the temperature was specified. What type of boundary condition is not there for this problem?

What is the boundary condition here? What is the boundary condition at this surface? So, physically what is the boundary condition? Whatever is the rate at which heat is transferred here at the same rate heat is transferred from here to the surroundings. Let us say that the system is at a greater temperature than the surroundings. So that means minus this is x equal to L , this is x equal to zero, minus $K \Delta T \Delta x$, at x equal to L is equal to h into T at x equal to L minus T infinity.

Now again the confusion always remains is that we are assuming that it is an unsteady state problem still we are assuming that the rate at which heat is transferred is the same rate at which heat gets transferred to the surroundings. So is there any kind of inconsistency between this and the consideration of unsteady state. There is no inconsistency because a surface cannot store thermal energy does not matter whether it is steady or unsteady surface cannot store thermal energy.

So, at whatever rate heat is transferred to the surface at that instance at the same rate heat will be transferred from that surface. So, this boundary condition is the only difference between the previous problem and this problem. So, let us work out that let us try to follow the solution of the previous problem and then see what are the changes? So, at x equal to zero $\Delta \theta \Delta x$ here we can also solve half of the domain and at x equal to L .

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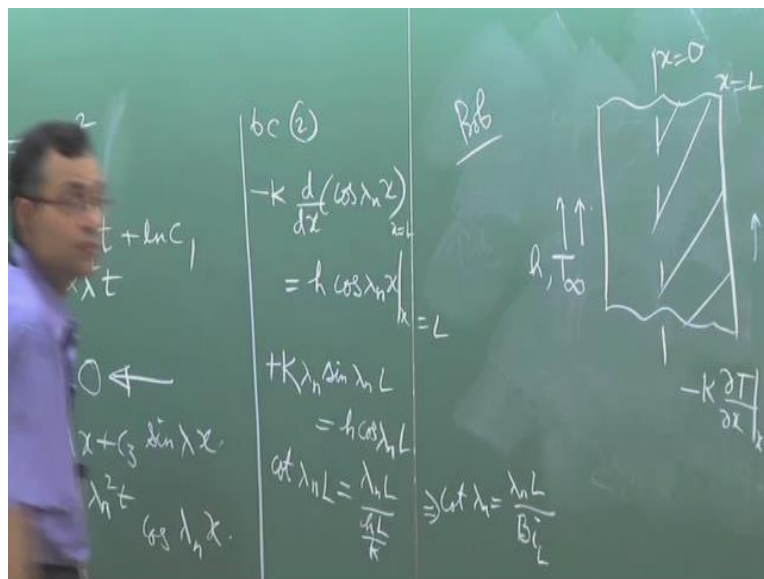


Here, we define as $T - T_\infty$, right. Minus $k \delta \theta$, δx equal to h into θ , θ is $T - T_\infty$. This At x equal to L . So, this is the only change and let us quickly see how this change is reflected in the solution. So, this part of the solution remains the same because this is before applying the boundary conditions. So before applying the boundary conditions whatever was the solution general solution is the same.

So ultimately your general solution is when you apply the boundary condition so θ is summation of $C_n e^{-\alpha \lambda_n^2 t} \cos \lambda_n x$. How did we get this solution we get this solution by substituting this boundary condition, right and this boundary condition does not change from the previous problem to this problem so this form is fine but λ_n is different?

So how do you get λ_n ? You have to use the second boundary condition.

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Minus k remember when you are differentiating with respect to x only f is important not g because g is not function of x , right. So minus k this will be basically df and dx , df and dx is d of $\cos \lambda x$ and this is h into θ , θ will eventually be f , g gets cancelled from both sides. So minus k minus will get cancelled so $k \lambda \sin \lambda L$ is equal to $h \cos \lambda L$. So, you can write $\cot \lambda L$ equal to λL by hL by K , right.

So, what we have done is we have multiplied by L because we want to use the non-dimensional number the Biot number. Biot number is hL by k . So, $\cot \lambda_n L$ is equal to $\lambda_n L$ by Biot number based on L . So, this is the iL value. See the iL value determination is not very straightforward because this is a transcendental equation. If you want to get a graphical feel of the solution then we can draw it here. So, this is $\lambda_n L$.

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$$\frac{1}{\alpha g} \frac{dg}{dt} = -\lambda^2$$

$$\ln g = -\alpha \lambda^2 t + \ln C_1$$

$$g = C_1 e^{-\alpha \lambda^2 t}$$

$$f'' + \lambda^2 f = 0$$

$$f = C_1 \cos \lambda x + C_2 \sin \lambda x$$

$$bc(2) \quad -k \frac{d(\cos \lambda_n x)}{dx} \bigg|_{x=L} = 0$$

$$= h \cos \lambda_n L$$

$$+ k \lambda_n \sin \lambda_n L = 0$$

$$\lambda_n L = L$$

Pi two Pi like that we can sketch. So, $\cot \lambda_n L$ will be something like this, right. In this way, you will have infinite number of such segments and the other part of the solution is this is $\lambda_n L$ by Biot number. This is y equal to mx , a straight line passing through the origin. So, this point of intersection are the iL values. So, if you are familiar with Met lab what you can do, in Met lab.

You can draw the graph of $\cot \lambda L$ and you may or say $\cot x$ and you may draw the graph of $x / \text{Biot number}$ and find out the points of intersection. Those points of intersections are the Eigen values of this problem. For the previous problem this was like straight forward two in plus one into Pi by two. For this problem, it has to be obtained from this. Now what about the constant SC ?

So, we will quickly see how to get constant C_n because we have got λ_n see all these problems are Eigen value problems just like in Linear algebra you require, in Eigen Value

problems you require to find out the Eigen Value problems and vector. Similarly, differential equation you require to find out the Eigen Value and Eigen Value function. So, Eigen Value we have already determined now the Eigen functions are related by orthogonality condition.

And we have to derive the orthogonality condition here.

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$$\int_{x=0}^{x=L} \frac{d^2 f_n}{dx^2} f_m dx + \lambda_n^2 \int_{x=0}^{x=L} f_n f_m dx = 0$$

$$\left[f_m \frac{df_n}{dx} \right]_0^L - \int_0^L \frac{df_m}{dx} \frac{df_n}{dx} dx + \lambda_n^2 \int_0^L f_n f_m dx = 0$$

at $x=L$, $-k \frac{df_n}{dx} = h f_n$

$$\left[\frac{h}{k} f_n f_m \right]_{x=L}$$

So, we will use this f_m into df_n/dx . Why I am separately here? Because here the boundary condition is different so we have to make sure that we derive the orthogonality condition freshly from the boundary condition of this problem. So, what is the boundary condition of this problem at x equal to zero it is the same. So, at x equal to zero this term is zero. But x equal to L this term is not zero, right. At x equal to L what is this term? Minus k df_n/dx equal to h into f_n .

This is minus k df_n/dx equal to h into f_n . This is at x equal to L . So, what will this become in place of df_n/dx we will have minus h/k f_n f_m , right. Because at x equal to zero any way df/dx is zero at x equal to L it is not zero but df_n/dx is related to f_n . So, we have written this now what we will do we will swap n and m and subtract and you can see because of the symmetry in f_n f_m these terms will be cancelled.

So, that is why see eventually sometimes the ignorance is a blessing if you do formula based study then you need not go through it you eventually know orthogonality condition will come

some way or the other. So, you eventually write only the orthogonality condition but there may be a tricky boundary condition when orthogonality condition itself is not satisfied and then you cannot use the separation of variable method to solve that problem.

So, for every typical boundary condition you have to look for the orthogonality condition. Here fortunately the orthogonality condition can be obtained because when you swap f_n and f_m and subtract this term will be zero. So, eventually you will get this. So, although you get the same final answer for the orthogonality condition so far as the orthogonality condition is concerned but the root of getting that orthogonality condition is different for different problems.

Then the remaining solution is very similar to the previous one so you can get C_m from here just λ will be different from the previous problem. So, only difference with the previous problem is Eigen value otherwise the structure of the problem is very, very similar. So, to summarize what we have discussed today some unsteady state problems where you have problem solved by the method of separation of variables.

So, we have addressed the method of separation of variables with the help of some examples of infinite slabs. We will later on consider some of examples which we call as semi-infinite problems and we will take it up in the next lecture. Thank you very much.