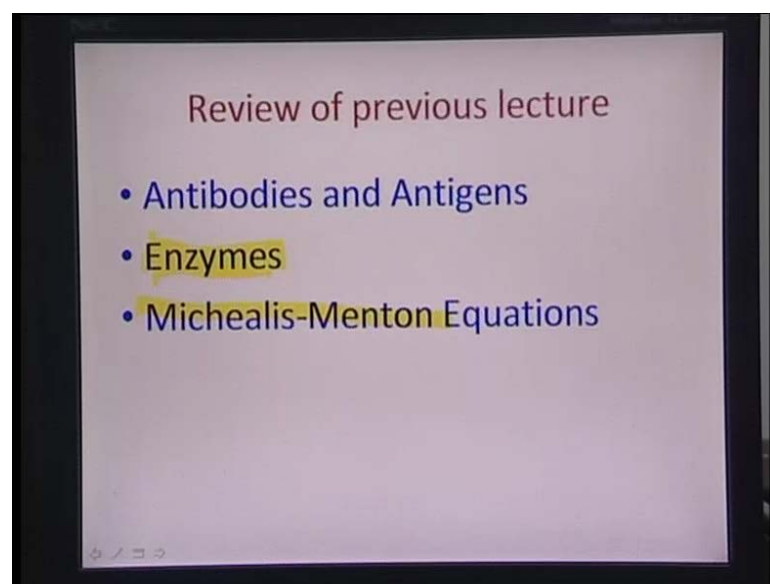


Bio-Microelectromechanical Systems
Prof. Shantanu Bhattacharya
Department of Mechanical Engineering
Indian Institute of Technology, Kanpur
Module No. # 01
Lecture No. # 25

Hello, welcome back to this 25th lecture on bio microelectromechanical systems. We will just quickly start with a brief review of what had been done in the last lecture.

(Refer Slide Time: 00:39)



We talked about antibodies, antigens and their kinetics of binding. We also mentioned about enzymes definitions and what they would do, and then we talked little bit about these wonderful set of rate kinetics equations called Michaelis-Menton equations for studying the properties of how an enzyme binds to a substrate producing an intermediate compound and then again breaks down into the product and the enzyme comes out as itself, essentially, how it catalyzes any process. We also talked a bit about the binding kinetics of antigens and antibodies and the way they would behave to changes in the ambient.

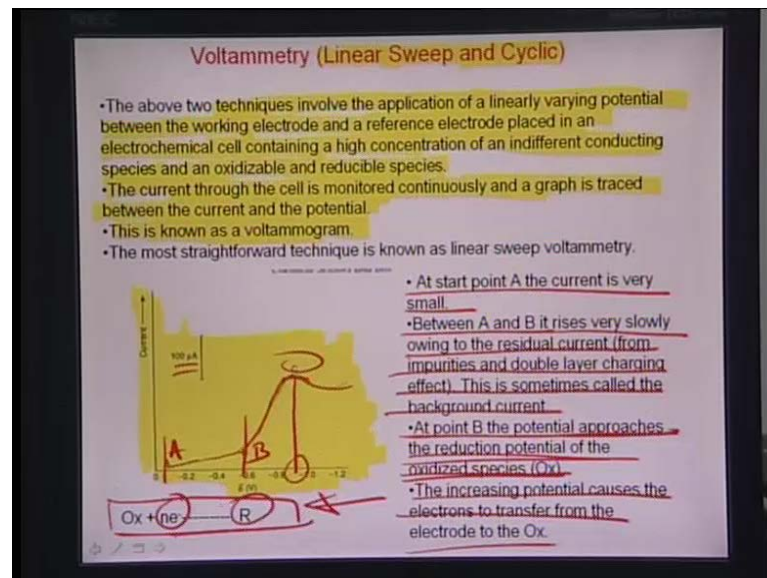
Today, we will try to address some issues. In last lecture, we also saw about some of the various ways and means of immobilization mechanisms of the biological entities onto the sensor surfaces side; in detail about adsorption phenomena also classified it into chemical and physical adsorptions. We also studied about micro encapsulation, about covalent bonding or direct covalent binding or the biological moiety onto the surface of

interest. We also talked about cross linking mechanisms and entrapments within gels or gel mattresses.

Why all the things are required is because, you have an entity and it causes an electrochemical change or a response. We had at the very outset defined that most of the sensing mechanisms which are commercially available **as on data electrochemical**. Therefore, with the mobilization of such biological entities onto the sensor surface, the obvious question which comes into this is, - how to measure the electronic response?

Therefore, a very important technique that we had touched upon earlier and I would like to detail it little bit today is Voltammetry. We had seen in detail, what potentiometry would mean in this. Essentially, it is the measurement of voltage with concentration at 0 current. In this case, in voltammetry is a plot between the current and voltage. It finds out redox reactions and tries to ascertain species by measuring its reduction and oxidation potential. So, let us look at this in little more detail, what voltammetry would involve typically?

(Refer Slide Time: 03:04)



There are 2 different kinds of voltammetric techniques: linear sweep and cyclic. Essentially, both these techniques involve the application of a linearly varying potential between the working electrode and the reference electrode placed in an electrochemical cell and in a manner that this cell actually contains the reduction oxidation species with a high concentration of indifferent species, which does not have any interfering ions with a particular electrode. So, the obvious thing to assume here is that as you pump in electrons inside the cell, there is a tendency of both the reduction and oxidation mechanisms to take place in the couple to formulate.

However, if you could have an electronic response of the system by measuring the current at different voltages, what you would see is a peak. The peak is more because, as a species is essentially oxidized and it suddenly liberates electrons. There is a tendency of all these electrons to shoot up one and all at a single potential point. Therefore, there is a huge rise in current at a certain potential and that is also known as the Oxidation potential of the particular species. So, species can be identified by its oxidation potential, the potential of the cell and to which the species get oxidized may vary as the oxidized agent or the agent which is getting oxidized varies in concentration as well as in type or nature.

Therefore, in such a case the current monitoring is very important through the cell and continuously a graph is traced between the current and the potential. We know this (Refer Slide Time: 04:38) is a voltammogram. Here, as you can see is nothing but a voltammogram. As you can see here, this measurement indicates the potential E_v on the x axis along with the current i on the x and the y axis. As you can see the curve here (Refer Slide Time: 05:00) is really something like an irregular shaped curve starting from the point A and there is a linear rise and then there is a sudden exponential rise, where **the reduction potential happens, the oxidation potential happens** and there is a shootout or burst of electrons, which increases the current. Therefore, this particular value here would also ascertain what species number 1 and what concentration of the species, which is getting oxidized number 2. So, these can be obviously concluded.

Let us look at the various parts of the curve - the start part of this curve between points A and B as you can see here (Refer Slide Time: 05:38) the current essentially is very small, because it is just an Ohmic response with the voltage. As the voltage increases, there is an increase in current V is equal to $I R$ and from the point B there is the potential suddenly approaches the reduction potential of the oxidized species. Therefore, there is a sudden shootout or burst of electrons, which increases the current. So, the increasing potential causes the electrons to transfer from the electrode to the oxidant Ox and so there is an increase in current, of course it is a reverse of electrons. If there is electron depletion, there will be an increase in current because of that. Here, the reaction which takes place is oxidation; Ox happens by combining with n electrons to formulate the reduction R in the process.

(Refer Slide Time: 07:03)

Voltammetry (Linear Sweep)

The increasing rate of reduction causes the cell current to increase. It can be shown that the net cell current in this region is given by the algebraic sum of a cathodic (reduction) current & an anodic current.

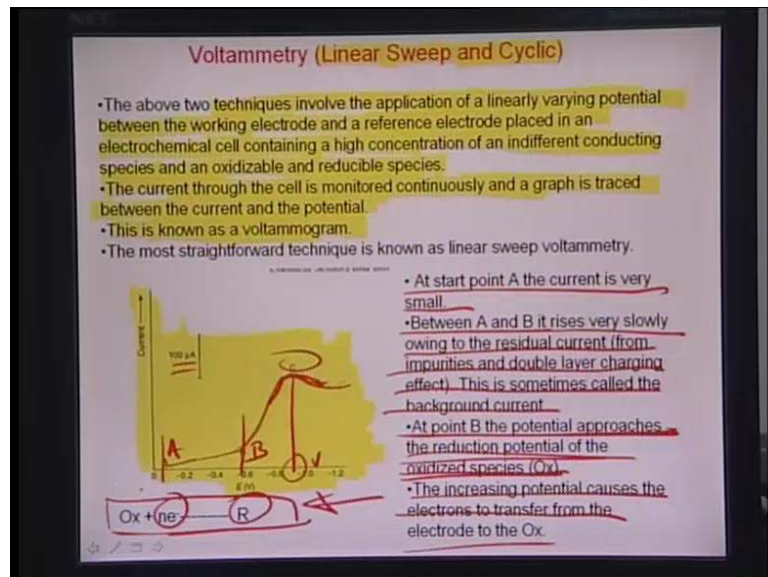
$$i_{net} = i_c + i_a$$

where, $i_c = n F i_c^0 \exp\left[-\alpha n F \left(\frac{E - E^0}{RT}\right)\right]$
 $i_a = -n F i_a^0 \exp\left[(1-\alpha) n F \left(\frac{E - E^0}{RT}\right)\right]$

As you see, some of the important conclusions here that the increasing rate of reduction causes the cell current to increase that are conclusion number 1. You can also be shown that the net current in the cell in this region is given by the algebraic sum of the cathodic and the anodic current and let us say i_{net} here as you can see in this particular illustration here (Refer Slide Time: 07:04) is given by i_c plus i_a , where i_c is the cathodic current due to the reduction and i_a is the anodic current. Although, the derivation of how i_c and i_a comes is beyond the scope of this course, I would like to just illustrate that the current i_c can also be measured as proportional to the number of the electrons transferred n the Faraday constant the equilibrium rate of the forward reaction to take place the concentration of the oxidant. Then, you have this exponential term here exponential to the power minus $\alpha n F E$ minus E^0 by $R T$, E^0 is the equilibrium potential and E is the potential at a particular point, T is temperature in Kelvin and R is the Rydberg's constant.

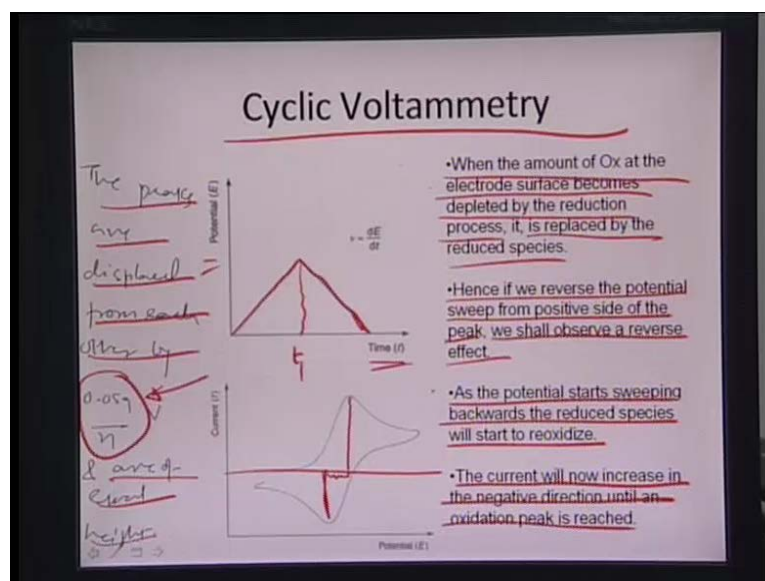
Here, the whole goal is that, as the E would increase you can see that there is automatically an increase in the cathodic current and simultaneously there is a fall in the anodic current. Therefore, the overall E net would really depend on position of E with respect to the E equilibrium, where this potential E of the current time point is located in comparison to the equilibrium potential of the particular reaction.

(Refer Slide Time: 08:34)



So, that is how you can ascertain the various the cathodic and anodic currents in a cyclic voltammogram. But, the whole idea is to be able to ascertain, what is the voltage v at which, this reduction status getting attained the species oxidized species Ox is suddenly accepting electrons and getting reduced. So, there is an increase in current because of that current, again is the loss of electrons, in the conventional sense. So, what would typically happen, if we take the EMF on the reverse side? That means towards the oxidant side, the reverse process should take place. Therefore, there should always be a tendency of the reduced species to get re oxidized and the current to go down, because there is a sudden burst or emission of electrons or availability of electrons. Therefore, this really is a set of 2 peaks and you can back and forth alter the potential into making it more reduction potential or oxidation potential. Correspondingly, plot a hysteresis curve because of that and that is typically what you call as Cyclic voltammetry. Cyclic, because you have species getting oxidized and simultaneously, a species getting reduced on the same system by just application of EMF and then you can characterize this by measuring the current all along and getting an increase as the species get reduced and simultaneous decrease as the species get oxidized.

(Refer Slide Time: 09:54)

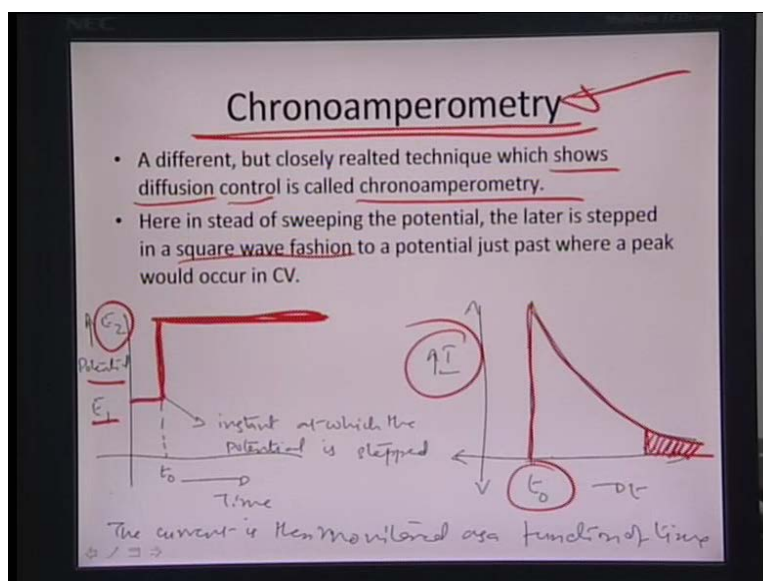


As you can see here, this illustrates what the cyclic voltammetry process really is. So, you get a potential or you give a potential with time as a triangular pulse, where you have an increased potential up to the time point let us say t_1 here and then beyond t_1 you have a reduction in the potential or the potential in the reverse direction. As you can see here, on the forward side you have an oxidized species suddenly getting reduced and losing electrons to the electrodes. Therefore, resulting in an increased current and reduced species getting oxidized here with a burst of electrons, which get a reduced current.

So, the amount of Ox at the electrode surface becomes depleted by the reduction process and is replaced by the reduced species in a nutshell. If you reverse the potential sweep from the positive side to the negative of the peak, we shall observe an exactly reverse effect that is an oxidation of the reduced species.

As the potential starts sweeping backwards, the reduced species will start to reoxidize again and the current will now increase in the negative direction until an oxidation peak is reached. What is more interesting here to observe is that, in an n electron transfer process, these 2 peaks are shifted exactly by 1 Nernstian slope 0.059 by n volts. They are typically of equal heights, because that indicates the equilibrium of concentration of the reduction and oxidation species inside the redox couple the redox reaction.

(Refer Slide Time: 11:39)

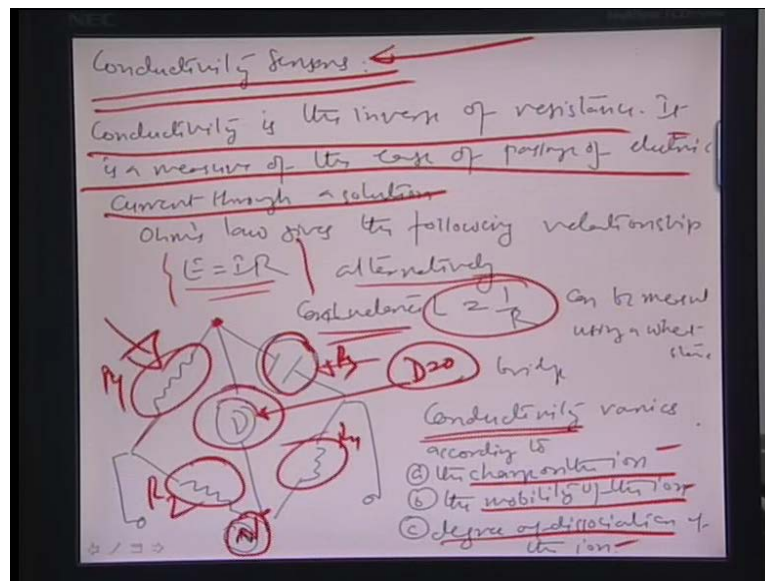


So, that is kind of all about cyclic voltammetry that one should know. Another very interesting technique apart from what we had done before is Potentiometry and Cyclic voltammetry is Chronoamperometry. As the name suggests, chrono indicates time and amperometry is the measurement of current. We are actually trying to measure the current by giving a sudden potential and creating an oxidation process to happen or a reduction process to happen. So, you give a square pulse here, as you are seeing here (Refer Slide Time: 12:08) the potential E in this particular figure, a time instance t_0 goes from E_1 to E_2 , there is a huge step or a square pulse that has been given thereby continuing the pulse at E_2 or the state to be at E_2 . What an essentially chronoamperometry show is, the diffusion control of such a case, where there is a square wave suddenly applied to a redox. So, if you measure the current with time, as you see here from time t_0 , there is a slow decrease in the current over time. If you monitor this, you can predict the type, nature and behavior of the redox species by monitoring how fast the current will decay with respect to time at a particular square pulse from E_1 to E_2 is generated.

The advantage here is that different slopes, different time aspects of decay of different species would be typically characteristic of the species type or nature and concentration and therefore can be used as a good technique to find out what is the active concentration of a certain species, which is electrochemically active in such a redox system or a redox couple.

So, we have by and large covered all the electrochemistry techniques; so far starting from potentiometry to cyclic voltammetry to chronoamperometry.

(Refer Slide Time: 13:44)



We now shift to briefly to another very interesting area, which is “Conductivity based sensors”. So, conductivity is the inverse of resistance, it is a measure of the ease of the passage of electric current through a solution. If you see all the solutions, they can obey Ohm’s law. Alternatively, the conductance relation would be a kind of E by L, where 1 by R is equal to the L. So, EL is equal to I, can be what the Ohm’s law can be written as in terms of conductivity.

Now, what conductivity does is that as is obvious, it would have changing behavior with the change in the ion concentration of the other particular medium. It would also depend on the mobility of the ion. If ion is mobile, the conductivity would be more the flow of currents through that kind of a medium would be much higher and then it would also depend on the degree of dissociation of a particular ion, especially in a redox system.

So, these are some of the factors, where the conductivity, typically you can get a Wheatstone bridge kind of configuration As you can see here, (Refer Slide Time: 14:52) there are resistances; which are known in nature and then there is a meter at the centre here and this is the flow cell, where the conductance typically has to be measured. The idea is that these four combinations can be varied in a manner that R 1 by R 2, typically becomes equal to R 3 by R 4 and that is an instance by the principle of Wheatstone bridge, typically the D here would show 0, there is no current here in between these 2 terminals at a fixed potential. Therefore, you can find out the conductance of such a medium or you can also apply an AC field here as you can see here and do similar calculations of an AC Wheatstone bridge to find out what the conductivity of this cell is.

But whatever it is the conductivity sensors essentially are used for measuring, the charge of a particular ion, the mobility of the ion and also the degree of dissociation of the ion and such electrochemical information found out by this technique is very useful for sensing or measurement.

We are kind of done now, with this whole electrochemistry business and also seen some of the interesting behaviors of surfaces or surface potentials. Now, what I would like to explore is a little bit of fluidics as applied to the micron scale and for that we have to do some basic theorizing of fluid mechanics and understand some of the basic concepts.

So, what I am going to do now is to dedicate kind of the remaining part of this lecture to more towards understanding of some basic fluidics and then go into active microfluidics, where we can design pumps valves, mixers, PCR reactors so on so forth. Let us look at this a little more closely now.

(Refer Slide Time: 16:45)

The slide is titled "Fluid Mechanics Theory (Microfluidics)". It contains two bullet points and two diagrams. The first bullet point defines a fluid as a substance that deforms continuously under shear stress. The second bullet point describes a thought experiment comparing a solid block and a liquid block under shear force. The left diagram shows a solid block being sheared and then returning to its original shape. The right diagram shows a liquid block being sheared and then deforming further when the force is reapplied.

Fluid Mechanics Theory (Microfluidics)

- Definition: Fluid is a substance that deforms continuously under the application of a shear stress, no matter how small the stress will be.[1]
- Consider a thought experiment wherein both a solid block of material and layer of fluid are subjected to a shear force.

Solid Block: If a shear force is exerted to a solid block this will return to its original position as the force is released.

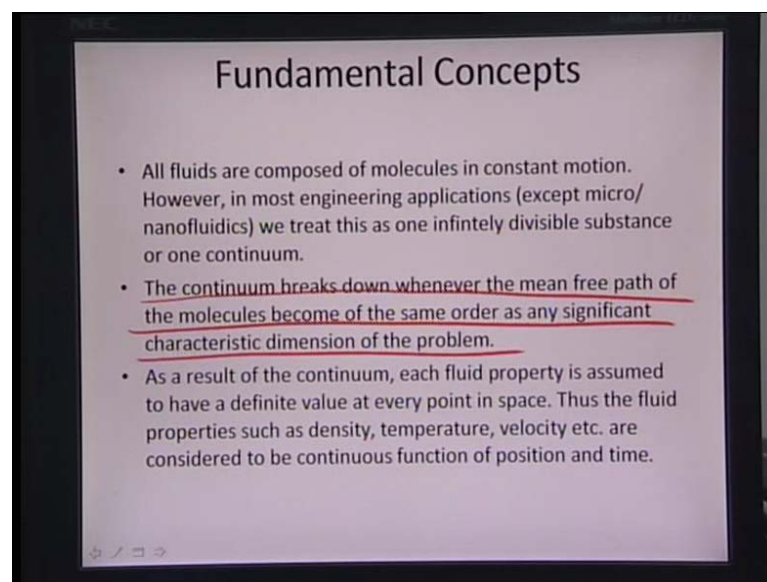
Liquid Block: If a shear force is exerted to a liquid block this will deform from its original position, to another new position as the force is released. If the force is reapplied the fluid will further deform.

So, to start with microfluidics, as we know is the movement of transport of fluids at the microscopic lens scale but what really fluidics is, first coming from the term fluid. So, what is a fluid? A fluid is a substance that deforms continuously under the application of the shear stress. So, what happens, suppose I take this particular solid object and try to hold it here at the base and try to deform it from the top. So, if I deform it by holding it continuously at the base, it would kind of get sheared or it would at least try to get deformed in its shape, the immediately after we release the load it should come back automatically or elastically, if it has not crossed it is elastic domain, back into its normal shape. However, in case of fluid is the reverse kind of effect.

Whenever you have, let us say an experiment as we can illustrate here again (Refer Slide Time: 17:50) wherein you have fluid layer as you can see here, held between a mobile plate on the top and a fixed plate at the bottom and then you try to move this fluid is a plug along with this plate by moving the plate forward in the forward direction. As you can see here, the fluid would kind of shear up without returning back. So, there is some molecular deformation something where this fluid will tend to remain in a sheared condition. If you apply some more force, it will shear to a different condition here. There is continuous shear process which is happening because of movement of the upper plate with respect to the lower plate.

So, I can summarize it by saying that, if a shear force is exerted in this case to a liquid block this will deform from its original position to another new position. As the force is released, this new position will be retained that is very important. The force is reapplied; the fluid will further deform along the same direction as that the force. However, in case of solid, it is the other way round the moment the force is released the block would tend to come exactly in the opposite direction and try to stabilize into its own shape. It will return to its original position, as the force is released in a particular solid. So that is essentially, what a fluid is it deforms on applying shear stress.

(Refer Slide Time: 19:15)

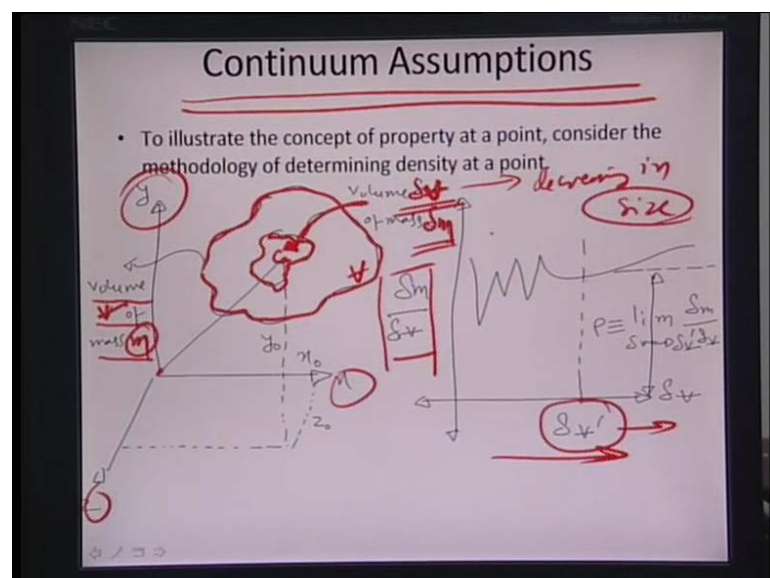


What is important to know that at a more fundamental molecular level? In a fluid, the molecules are not so firmly bound, they are having lesser forces and they are in constant motion with respect to one another. Whatever it is, we still treat the fluid as 1 continuum body, even if the molecules are moving around with respect to another, we still treat as one big continuum, especially in the scales in which we can do bio-sensing or diagnostic.

However, if you go to a certain different domain in the Nano scale, there the properties of the fluid itself vary with time because as, I am going to illustrate this concept in next slides. What happens if you scale down to smaller scale but, then essentially in most engineering applications related to sensing and diagnostics we still continue to believe the fluid as 1 big continuum, one indivisible substance be it that the molecules are moving in a certain motion with respect to one another. Still they are bound by a certain domain a bigger domain and that domain keeps on changing shapes and sizes, but it keeps on doing so continuously and the fluid continuity is maintained.

The continuum breaks down, whenever the mean free path of the molecules become of the same order as any significant characteristic dimension of the problem. So, if you are considering the volume element to be too small in comparison to the mean free path of individual molecule, the probability of the continuum to break down is more in that respect. So, as a result of the continuum each fluid property is assumed to have a definite value because you have one continuum the fluid is behaving as one medium and spatially or at every point in space these fluid properties would show a fixed value average value. If it is of a certain finite size where this problem of the mean free path to be equalized to one characteristic dimension that is no longer there. The mean free path is much smaller in comparison to one of the characteristic dimensions. So, properties such as density, temperature, viscosity etcetera are considered to be continuous function of position and time. In such instances where the continuum still exists, where the continuum breaks down the change with time, they become totally independent of the space as well as time. They keep on varying space to space, time to time etcetera.

(Refer Slide Time: 22:04)

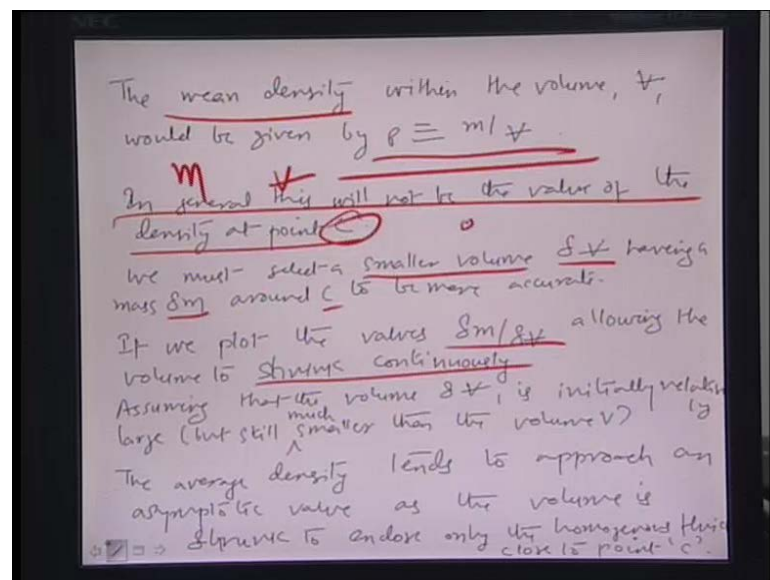


Let us illustrate this concept a little more in details suppose, we are talking about plotting the volume v of a mass of fluid m , as can be illustrated here with in this $x y z$ Cartesian coordinate system as you can see. Let us suppose, there is a point C in space, which is that radius vector r from the origin and you assume 1 big volume around v tilda; this whole thing is v cross. We assume the mass of such an element m . Now, around the point C , we also take a much smaller volume δv cross and take the mass of this particular element δm .

So, this volume here is much smaller around C in comparison to the overall volume, which is v cross with a mass m . This smaller volume has much **smaller volume, much** smaller volume δv cross and a much smaller mass δm . So, what I would like to do is, to go ahead and plot on the ratio mass per unit volume with respect to the volume change. So, this is essentially the variable volume, we are assuming that this δv is going on in decreasing in size to a certain extent. So, it is kind of closing on the point C and becoming more towards the point C that means it is becoming a point slowly from a finite volume and so it approaches continuously a smaller value.

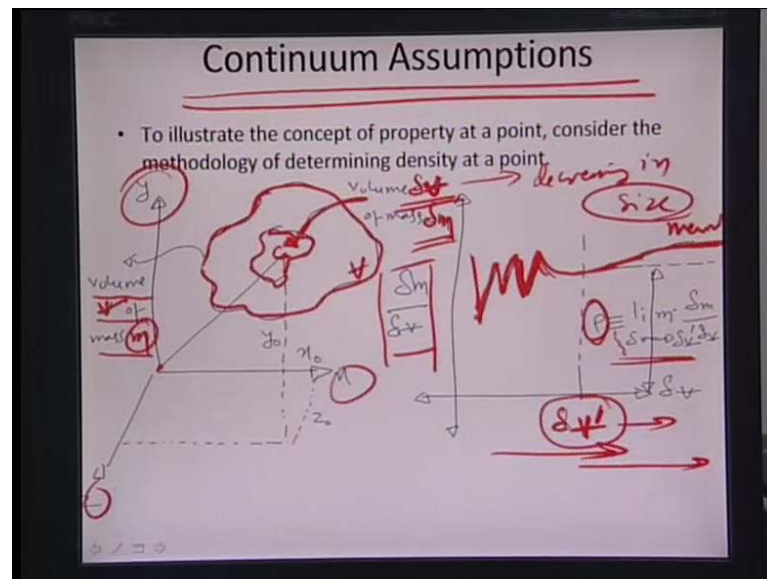
So, what would happen to properties like density that means mass per unit volume; in case it achieves this, let us have a look at what that would be.

(Refer Slide Time: 24:09)



So, the mean density of this bigger volume v , where the mass is given by mass per unit volume. In general, this will not be the value of the density at point C , though very close to C . If you are just having a point dimension of C , we have to select a smaller volume δv tilda. Let us assume, we have a mass δm around c . Now, you are plotting this, allowing the volume to shrink continuously.

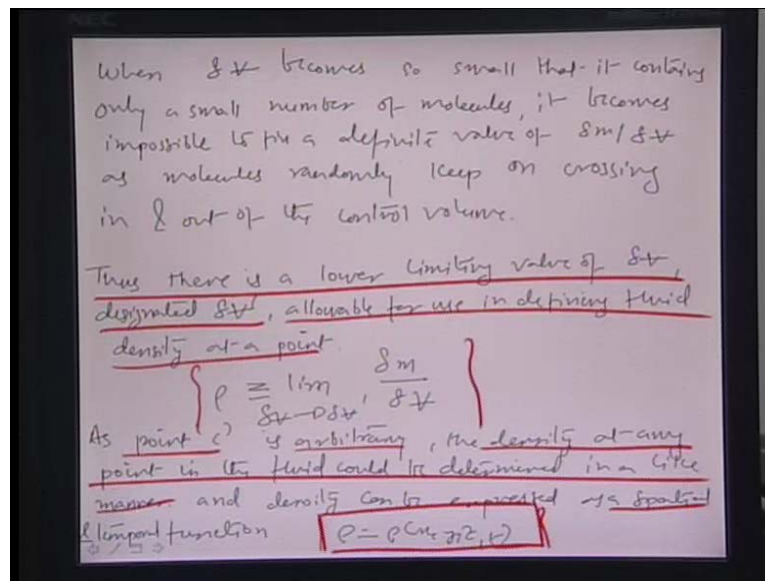
(Refer Slide Time: 24:48)



So, there is a certain volume here as you can see, let us say δv beyond which, the property density rapidly increases and asymptotes or becomes asymptotic to a fixed mean value, but below this you can assume that the dimension is so small that one of the characteristic dimensions is more like the dimension of individual mean free path of the molecules. So, the volume is small and the mean free path is greater; you never know there is an uncertainty or whether the molecule is within the volume or outside the volume. Thousands of these molecules, which are criss-crossing the surfaces of this small dimension and therefore, you are not 100 percent certain as to how much amount of a mass or how much amount of volume is there? Within the infinitesimally small point volume, that you are considering. Therefore, the density should be a function of time. So, δm by δv below a certain δv volume becomes very erratic, because of this motion of the molecules or continuous seeping of the molecules through its boundaries.

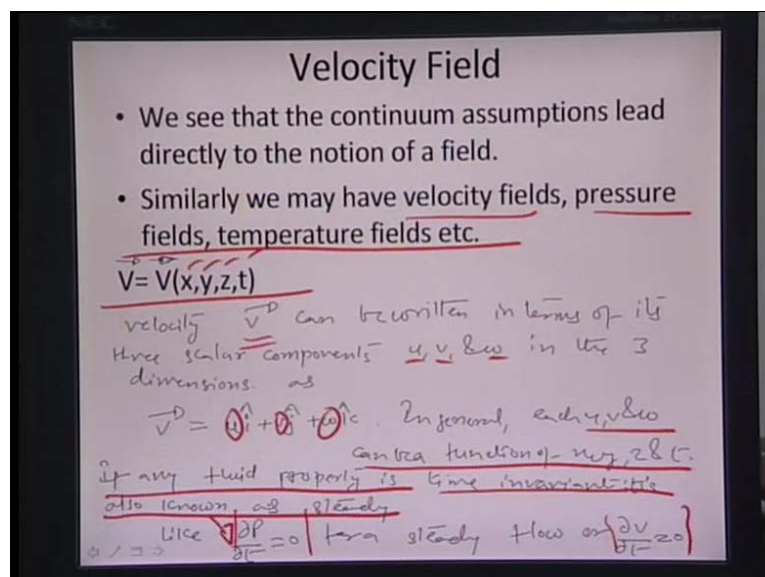
Let us say, you behave the density behaves like this; it is very erratic with time. So, really the continuum assumption is really valid beyond this δv value. Beyond which you can say that as the δv is approaching a limit δv , ρ becomes δm by δv , as a continuum property. But, less than δv , the ρ is really a function of ρt . So, function of time it keeps on varying.

(Refer Slide Time: 26:46)



So, that is what continuum essentially means in the real physical sense. In summary, there is a lower limiting value of δv cross designated at δv cross dash allowable for use defining fluid density at a point. So, at point c being arbitrary the density at any point in the fluid could not be or could be determined in a like manner. The density can be expressed as a spatial temporal function or spatio-temporal function as a function of x y z and t as you can see here in this particular equation (Refer Slide Time: 27:20). So, rho becomes a space time function.

(Refer Slide Time: 27:25)

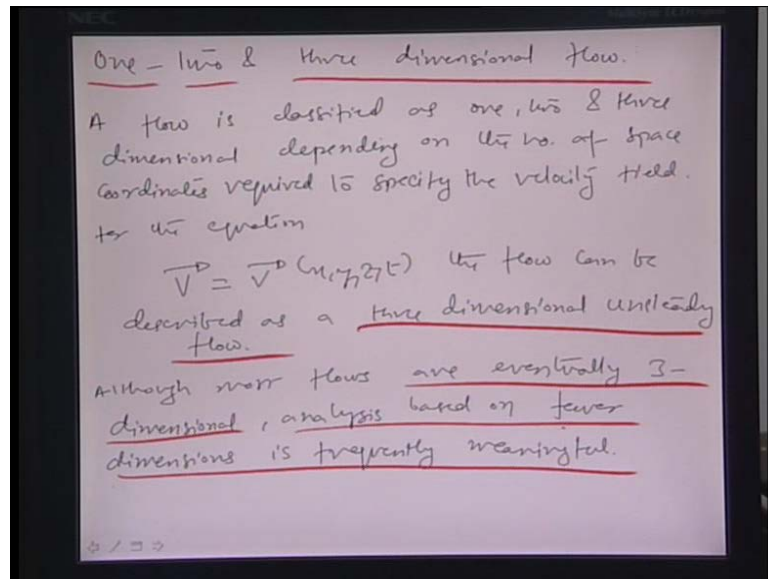


So, important concept to assume or to find out is what a velocity field would be? By the continuum assumption, we see directly there is some kind of a notion of a velocity field developing; that means if velocity really is a function of x y z and time, but it is

continuum property, it is an average velocity property. We should have a kind of trajectories along which these velocities meet a certain condition and they follow a certain space-time relationship. So, these trajectories can then act to define the flow paths of the various molecules, which are transporting through this fluidic medium. They could be timelines, they could be streak lines, they could be streamlines, and they could be path lines and all different kind of lines. So, we will like to have some illustration as to what this velocity field is and then go into these various aspects of various methods of defining the flow paths within the fluid.

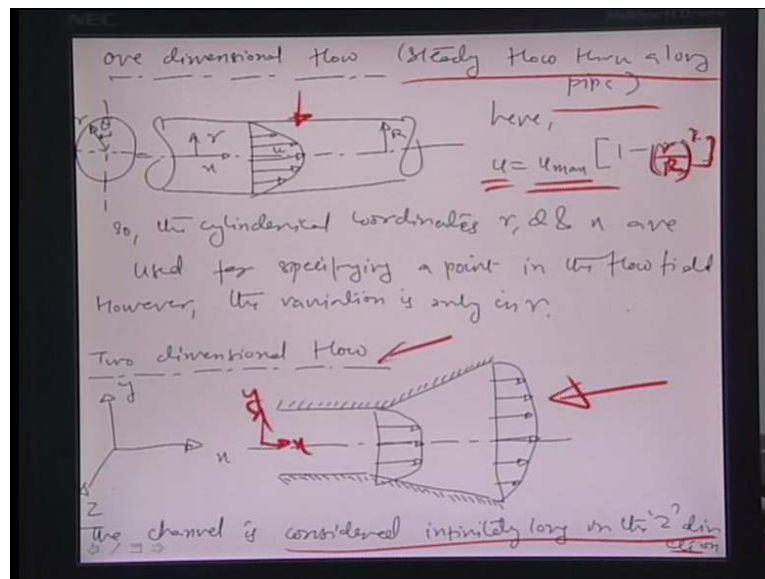
So, we may have similar equations as velocity fields, pressure fields, and temperature fields etcetera within this volume. Let us say, vector V is a function of x y z and time, that is typically the case because, V can be written as a summation of 3 components u v w in the x y z direction as $u \hat{i} + v \hat{j} + w \hat{k}$ and in general, each these u v and w can be a function of x y z and time. We can assume that a thing, if the fluid properties are time invariant, it is also known as Steady-state flow. So, the $\frac{d\rho}{dt}$ or as a matter of fact any other property like $\frac{dv}{dt}$ or $\frac{dP}{dt}$, P being the pressure; they are all equal to 0, there is no time variation of the particular flow. However, in flows which are heated up this may not be the case as because the density would keep on changing from the cold surface towards more towards the hot surface in touch with the fluid in question and. Therefore as we will see later on especially in micro scale fluidics we hardly need this component of heating and we can do away with the energy equation of the Navier Stokes just because of that reason. So, in microfluidic situations, mostly we use time invariant flows $\frac{dv}{dt}$ or $\frac{dP}{dt}$ or $\frac{d\rho}{dt}$ or any other property with respect to time, does not really vary at all within such domains.

(Refer Slide Time: 30:19)



So, flows can further be described as 1 2 and 3-dimensional. The name suggests, it really depends on the number of space-time coordinates that is needed to specify the velocity field for certain equation. So, if it is just dependent on x and not on y and z or time, then that is called a One-dimensional velocity field and which is steady-state and if it varying on time it can be also known as Unsteady one -dimensional. Therefore, it varies with all the 3 coordinates you can call a 3-dimensional unsteady flow system. Although, the flows are eventually 3-dimensional analysis almost has always helpful, if you can convert it somehow into a fewer dimensions 2 or 1 in most of the cases. Depending on the symmetry of the situation of the geometry through which the fluids are flowing, you could easily convert it into more 1-dimensional than 2 or 3. Although, the actual real-life it is more towards 3 dimensional. So, this is just for calculation simplicity sake, that you are eventually assuming all 3-dimensional flows or predicting all 3-dimensional flows on basis of analysis on one or more dimensions but fewer a than 3.

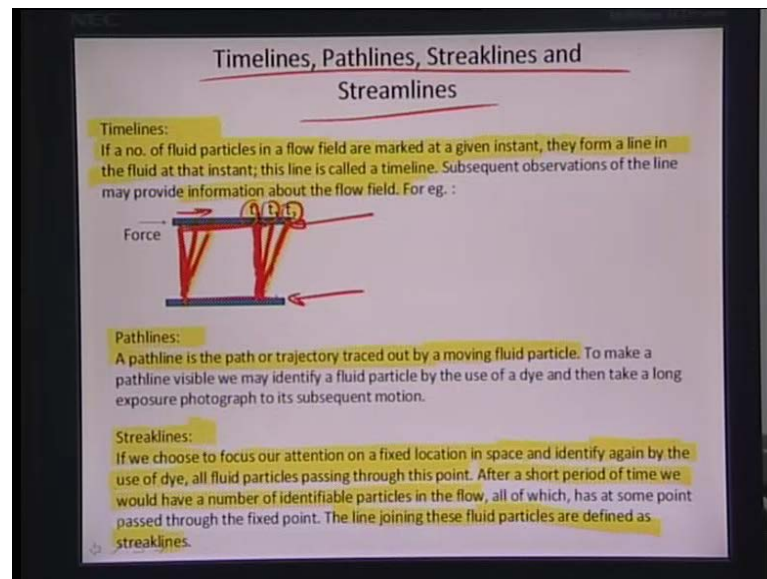
(Refer Slide Time: 31:40)



Let us discuss some examples of 1-dimensional flows, especially steady flows through long pipes. You can see here, this really is a variation of velocity profile with respect to the radius r . So, u here is actually equal to u_{max} , which is somewhere in the centre of the pipe, times of 1 minus small r by big radius R square. So, it is varying only on the radius vector. It is symmetric along the angle ϕ to describe the cylinder it is only varying along the radial direction.

So typically, this is the case in cylindrical coordinates or same is true for the z direction, z is too long in comparison to the width of the pipe, the radius of the pipe and so if you talking about micro-flows, where the dimensions of the pipe itself is very small in comparison to the length in which it is laid out. You typically can consider, it to be 1-dimensional flow problem, which is radially symmetric. If you assume that, the continuum assumptions or approximations hold true. Two-dimensional flows are represented here (Refer Slide Time: 32:54) in this particular figure. As you can see, the channel is considered infinitely long in the z direction that means in the plane of this particular illustration or in the board. Therefore, the variation though is mostly in the x and y if x and y are these dimensions here the flow velocity would be vary in only 2 dimensions in this particular case illustration.

(Refer Slide Time: 33:12)



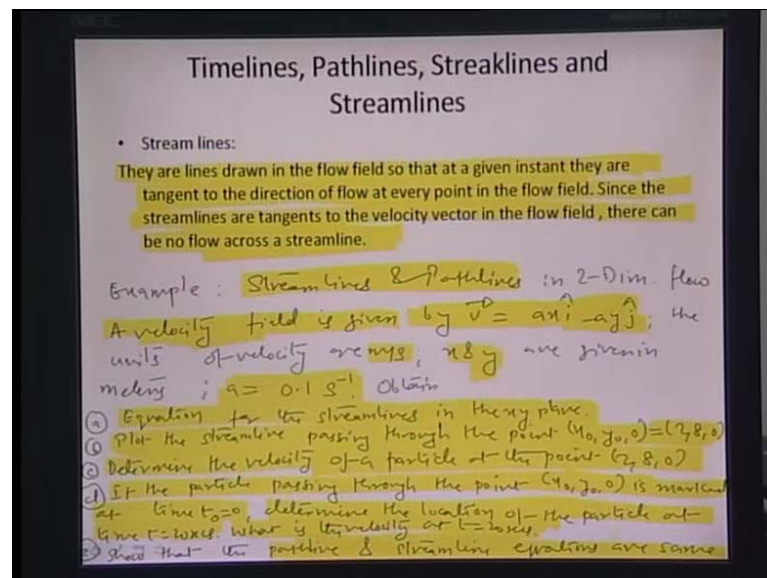
Let us talk, a little bit about these concepts of timeline, pathline, streaklines and streamlines. These are important for understanding of later on topics of microfluidics or micro flows. So, if you talk about timelines here- the timelines are these various instances t_0 t_1 and t_2 , what they are typically is that, if a number of fluid particles in a flow field are marked at a given instant of time at a certain point in space. Then, they form a certain line; it can be a straight line. This line is known as the Timeline and the variation of this line would provide information about the flow field like for example, in this particular case, as you can see the fluids at the very outset were held in a very symmetrical manner between the mobile plates here on the top and the fixed plate. The mobile plates starts moving and it being fluid and the property dictates it to be or take the shape of the relative displacement between the upper plate and the lower plate, which kind of varies with time and kind of increases with time. As you see here, from time t_0 to t_1 to t_2 , you have all these different lines which are getting formulated. So, this was a time t_0 all the particles which were here in this particular edge of the fluid over defined by this timeline at t_0 . Now, it moves to t_1 the timeline also changes to t_1 and t_2 . So, the flow field here would be defined by tracing these timelines that is what timeline means.

What are pathlines? A pathline is a path or trajectory traced out by a moving fluid particle. We can use identification techniques to make these timelines or these pathlines visible things like, we can introduce a small dye or an ink in water and we can see how this ink diffuses through or across. So, the ink particle moves in a path or trajectory traced out by moving the fluid around it or the ink itself with time. So, that is a pathline.

So, we can take a long exposure photograph of such a flow situation and see where this dye is slowly going into or diffusing into. So that is what the pathline of the dye would be in let us say, water.

The other important classification is streaklines and this is in little bit indirect way of describing flow fields. So, if you choose to focus our attention on a fixed location in space and identify again by the use of dye, all fluid particles passing through this point. After the short period of time, we would have a number of identifiable particles, which flow through that point in space in the flow field. All of these particles flow through that same fixed point as indicated before. Now, the lines that would typically join these fluid particles, once they are out of that small point and they are somewhere along the fluid after that points. The lines which would join all those particles, which came from this 1 spatial location is known as a streakline. So, we have already seen what a timeline pathline and streaklines would be and they have all different connotations. You could use these to explain fluid flow behavior or motion of molecules in a continuum fluid mechanics very easily.

(Refer Slide Time: 37:35)



The other very interesting factor is a streamline. So what are streamlines? **definitionally** They are lines drawn in the flow field, so that at a given instance they are tangent or they are tangential to the direction of flow at every point of the flow field. By drawing, let us say, you have a particle which moves along a certain trajectory and this trajectory's like curvilinear like this and there is a directional variation in the velocity. This variation in the velocity by virtue of the direction and that is a reason why the particle describes this trajectory. To combining all these tangents together would give you what you call the

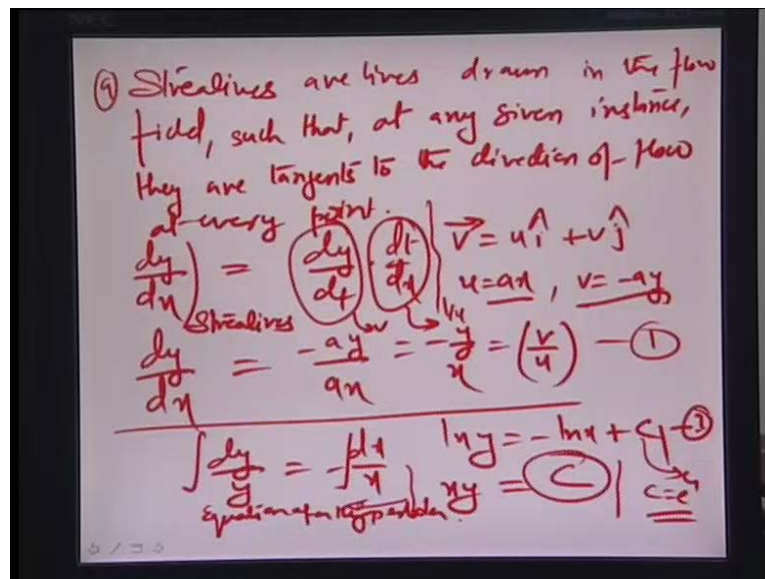
streamline or flow. Very interestingly, the streamlines do at a microscale, define at all possible scales, whether the flows are laminar or turbulence if they are very streamlined and they are very laminar in nature that indicates the less mixability between 2-3 different flows, which would have similar lines parallel to each other as they are going along in a small channel side by side. Since, the streamlines are tangents to the velocity vector in flow field, there can be no flow across a streamline.

So, what I would go ahead is to give you an example problem, to calculate how we can really estimate an equation on a 2-dimensional flow between the x and y coordinate to estimate, what we call a streamline.

This particular example of velocity field is given by the expression \mathbf{v} is equal to $a x \mathbf{i} - a y \mathbf{j}$, x and y are the position coordinates and a is some constant and \mathbf{i} and \mathbf{j} are unit vectors in the x and y direction, x and $-y$ direction and the units of velocity here are meters per second, a is given by the expression 0.1 second^{-1} . Just to be consistent on this equation and the dimensional aspect. So, we want to obtain the equation for streamlines in this particular case in the $x y$ plane. Basically, as in this example the velocity field is given by this equation \mathbf{v} vector is equal to $a x \mathbf{i} - a y \mathbf{j}$, \mathbf{i} and \mathbf{j} are the unit vectors in the x and y direction and a basically is having the units of second inverse. So, a is given as 0.1 second^{-1} , x and y are the $x y$ coordinates and basically the velocity \mathbf{v} is given meters per second in this particular expression.

So, the first problem here is to find equation for streamlines in the $x y$ plane, we also want to plot the streamlines passing through the point (x_0, y_0) , where x_0 and y_0 are 2 and 8 respectively. Essentially, these two things are something like a plot, that we would be able to define in terms of a geometrical relationship between x and y . We would also like to determine the velocity of the particle at a point $(2, 8)$ and also that if the particle passing through the point (x_0, y_0) is marked at time $t = 0$, we have to determine the location of the particle at time $t = 20$ seconds. So, typically it is almost everything related to streamlines and pathlines and how to plot them and also we need to ascertain the velocity at $t = 20$ seconds. So, one thing is determined the location another at that particular new location we have to also find out what the velocity of the particle at $t = 20$ second. Actually that is what we had approved also that the path and streamline equations are one and the same in this particular case. So, let us actually start this problem.

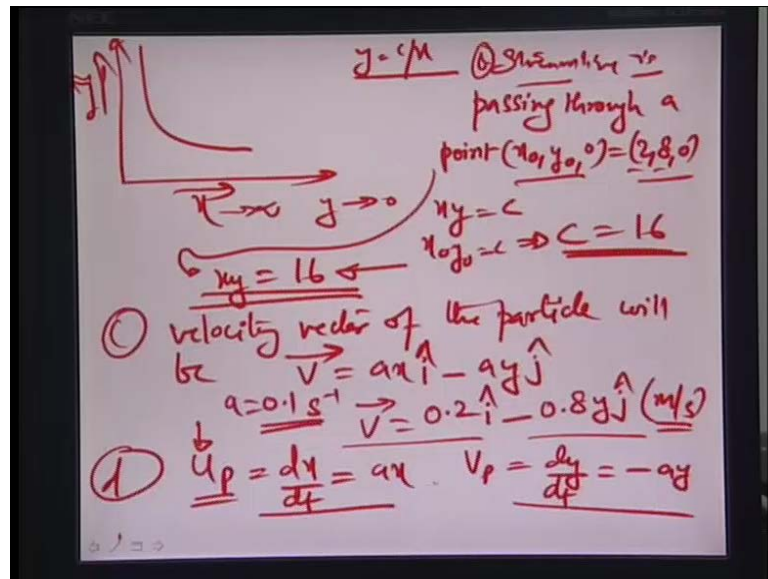
(Refer Slide Time: 41:48)



What are really streamlines? If we just go back to the definition of streamlines; streamlines are lines drawn in the flow field and such that at a given instant, they are tangent to the direction at every point of the flow field. So, in a flow field such that, at any given instance they are tangents to the direction of flow at every point. Here, we have to find out dy by dx , which is the tangent for the streamlines and this can also be represented as dy by dt times of dt by dx by using the Chain rule. As can be seen here in this equation, dt by dx ; what we really know the velocity relationship here has been given as $u\hat{i} + v\hat{j}$, where u is given as ax and v is given as $-ay$. That is how the velocity is defined really in the problem statement.

Therefore, the dy by dx for the streamline really is nothing but $-ay$ by ax . This is $-y$ by x or $-\frac{y}{x}$. Typically, it is $\frac{v}{u}$ that is exactly what this equation here says $\frac{dy}{dt}$ is v the rate of variation of y dimension in terms of time and $\frac{dt}{dx}$ is $\frac{1}{u}$ by dx by dt that is $\frac{1}{u}$, rate of variation of x with respect to time. Therefore, if we just solve this equation number 1 here, we are left with dy by y equals essentially $-dx$ by x with a minus sign and we can integrate this to obtain $\ln y$ on 1 side is equal to $-\ln x$ plus c . In the words, C 1 maybe and so in other words we have from this particular equation number 2 we can find out xy is equal to a constant maybe C and C is essentially e to the power of C 1 C 1 being a constant e to the power C 1 is also a constant.

(Refer Slide Time: 45:49)



This in fact represents the equation of a hyperbola. It is very convenient to plot all the x y points in a manner, whereas x tends to 0, the y value tends to infinity and vice versa, as y tends to 0 then again the same the x value tends to infinity. So, you can actually plot this equation normally as a set of streamlines. Let us say, this is y, this is x and so these equations would be typically something like this or of a parabola, where if x goes to infinity; let us say y would assume 0 value, y being equal to C by x and vice versa. If y goes to infinity x would assume a 0 value. They are asymptotic to both the x and y axis as can be seen here.

So, for a streamline, this is essentially the equation of the streamline. The part B of this problem statement says that, for a streamline passing through the point x₀ y₀ 0, where x₀ y₀ are 2 and 8 respectively. What would be the equation of the streamline? It is an interesting question. Let us say, in this particular case the streamline is passing through a point x₀ y₀ 0 equal to 2 8 0 respectively. Assuming that the streamline follows an equation x y equal to C. Therefore, x₀ y₀ should be also equal to C and hence, C becomes 16 in this particular case. Therefore, the equation of such a particular point here, would be typically x y equal to C equal to 16. So, this is the equation of the streamline passing through the point x₀ y₀ 0 2 8 0.

The third part of the question says or asks or determines, it tries to investigate the velocity of a particle, which passes through this point. So, you have to determine what the velocity vector of the particle will be, when it is on the particular streamline x y equal to 16. Therefore, in this particular case, a velocity V was given by a x i cap minus a y j cap, where a is 0.1 second inverse and velocity was given in meters per second.

Therefore, velocity here (Refer Slide Time: 48:50) would be represented as $0.2 \hat{i}$ minus $0.8 \hat{j}$ in meters per second assuming that 2 and 8 has the units of distance in meters. So, that is what essentially third parts of the question can be addressed as.

Now, the next part asks that, if the particle is passing through the point $x=0, y=0$ and it is marked at time $t=0$. Then, we had determine the location of the particle at time $t=20$ seconds and also we had to further determine what is the velocity at time $t=20$ seconds.

Let us suppose that you are actually trying to move from the point $x=y=16$ to a new trajectory. The velocity here from the earlier equation is given by this point $2\hat{i}$ minus $0.8\hat{j}$ and we have to see that at the new position, we have to first calculate what the new position really would be; if we assume this velocity. As we know, $u = \frac{dx}{dt} = ax$. So, this is u at a particular position or velocity or the x component of the velocity at a particular point P . Similarly, v of the particular particle will be $\frac{dy}{dt} = -ay$. From these 2 equations, what we really need to ascertain is, what the relationship between x, y and time t because, we need to find out what will happen at time $t=20$ seconds. Assuming that the initial curve here $x=y=16$ satisfies a streamline which is formulated at time $t=0$ seconds.

(Refer Slide Time: 51:25)

The image shows a whiteboard with handwritten mathematical work. At the top, two differential equations are written: $\int \frac{dx}{x} = \int a dt$ and $\int \frac{dy}{y} = -\int a dt$. Below these, the equations are integrated to give $\ln \frac{x}{x_0} = at$ and $\ln \frac{y}{y_0} = -at$. These are then exponentiated to yield $x = x_0 e^{at}$ and $y = y_0 e^{-at}$. The acceleration a is given as 0.1 s^{-1} and time t is 20 sec . A calculation for x is shown: $x = 2(e)^2 = 14.8 \text{ m}$. A calculation for y is shown: $y = 8e^{-2} = 1.08 \text{ m}$. The final velocity vector is given as $\vec{V}_{\text{new}} = 1.48 \hat{i} - 0.108 \hat{j}$ m/sec.

Therefore, if we integrate this particular equation, $\frac{dx}{x}$ on the left side and dt on the right side from 0 to time t , assuming the initial position to be x_0 and the final position to be x here. Similarly, this is for the velocity of the particle in the x direction and for the y direction, we do a similar thing as $\frac{dy}{y}$ from y_0 to y equal to minus a

t from time t equal to 0 to time t equal to t . Therefore, $\ln x$ by x naught here is equal to $a t$ and $\ln y$ upon y naught here equal to $-\ln a t$ and hence it is an exponential relationship. So, x becomes equal to $x_0 e^{a t}$ and y new coordinates become equal to $y_0 e^{-a t}$. We already know, the value of a to be 0.1 second inverse and the time here really is from 0 seconds to 20 seconds, which means the new x coordinate here assuming x_0 to be 2 and y_0 to be 8 as the two different points through which this earlier streamline would have passed from can be found. So, the new position x and y could be found out as 2 times of e to the power of 2 e square, which is about 14.8 meters and y similarly would be 8 times of e to the power of minus 2, which is about 1.08 meters; that is what the new $x y$ coordinates of this particular point is really. So, if the particle is moving at the velocity $a x \hat{i}$ minus $a y \hat{j}$ and it is supposed to be at time equal to 0 along the streamline or at a point $x_0 y_0$ at a particular point in the streamline $x y$ equal to 16. Then, from the relationship between $x y$ and t , we find out that the new positions x and y of the particles would be represented by 14.8 meters and 1.08 meters.

Therefore, the new streamline equation first of all, the new velocity that the particle will possess in this instance V new of the particle is equal to $1.48 \hat{i}$ minus $0.108 \hat{j}$. Velocity again relationship $a x \hat{i}$ minus $a y \hat{j}$ holds true, the only difference here is that the x and y are the new values of x and y , which are 14.8 meters and 1.08 meters respectively. So, these again is in meters per second, also we would like to determine the pathline equation for this particular example and for that, we also need to find out first the parametric equations, that means the relationship between x and t and y and t as we had done in the earlier example and then try to solve for time and from there we can find out what the pathlines are really.

So, **definitionally** again what are pathlines? Pathlines are typically lines, which are a kind of paths or trajectories traced out by a moving fluid particle. So, this is something that a particle at a particular point of time, when introduced into the fluid would follow temporarily as it goes ahead inside its domain.

(Refer Slide Time: 55:43)

② To determine the pathline we will first have to find out the parametric equations

$$x = x_0 e^{at}, \quad y = y_0 e^{-at}$$
$$e^{at} = \frac{x}{x_0} = \frac{y_0}{y}$$
$$\underline{x_0 y} = \underline{y_0 x_0} = \underline{16}$$

$\downarrow \quad \downarrow$
2 8

Let say, in order to determine this pathline, we will first have to find out the parametric equations x equal to $x_0 e^{at}$ and y equal to $y_0 e^{-at}$. So, from this expression what we get is a relationship between x and y ; let us say e^{at} in this case is x/x_0 and in this other case is y_0/y . Therefore, x and y really equal to $x_0 y_0$, which is again equal to 16 (x_0 being equal to 2 and y_0 being equal to 8 from the earlier example).

Therefore, what we find out here is that if suppose by definition what a pathline means really is, the location of the particular point at a certain time instance. You have to make, if you want to join all such points after all such particles, which have moved past a certain point. You have to make them independent of time and in order to make them independent of time, you find out the equation which has come out is same as the equation of the streamline as before. Therefore, the pathline equation derived here is same as the streamline equation in this example. This kind of led us to get a feel about all these different concepts of how to trace trajectory or lines of fluid particles within fluid flow systems. These will be immensely helpful later, for understanding of microflows because they are highly streamlined and laminar in nature.

So, with this I would like to close today's lecture and then start with derivation of the stress field and then correlation of all these parameters together, to derive something, which is very fundamental and unique to the fluid mechanics or the Navier Stokes equations. So, we will cover this in the next lecture. Thank you.