

Computational Fluid Dynamics for Incompressible Flows

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Module 3: Finite Difference Method

Lecture 1

Finite Difference by Taylor Series Expansion

Hello everyone, so today we will start module 3, finite difference method and in today's lecture we will learn, finite difference by Taylor Series Expansion. In last lecture, we have learned the classifications of partial differential equations and you have seen that in heat transfer and fluid mechanics problems there appears first derivative and second derivative of dependent variables.

The differential of dependent variables appearing in the partial differential equation must be expressed as approximate expression, so that a digital computer can be employed to obtain a solution.

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The image shows handwritten notes on a whiteboard or paper. At the top, it says "Finite Difference Method" in red. Below that, it lists $f(x)$, $\frac{\partial f}{\partial x}$, and $\frac{\partial^2 f}{\partial x^2}$. To the right is a small graph of a function $f(x)$ with points x_{i-1} , x_i , and x_{i+1} marked on the x-axis, and corresponding function values f_{i-1} , f_i , and f_{i+1} on the y-axis. The distance between x_{i-1} and x_i is labeled Δx , and the text "Δx - step size uniform grid" is written next to it. Below the graph, the Taylor series expansion is written: $f(x+\Delta x) = f(x) + \sum_{n=1}^{\infty} \frac{(\Delta x)^n}{n!} \frac{\partial^n f}{\partial x^n}$. This is then expanded to $f(x+\Delta x) = f(x) + \frac{\Delta x}{1!} \frac{\partial f}{\partial x} + \frac{(\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$. A box highlights the first two terms, and the text "Forward difference approximation" is written below it. The remaining terms are grouped and labeled "Truncation Error (TE)". Below this, a definition is given: "Truncation error is the difference between partial derivative and its finite difference representation." The equation for TE is $TE = -\frac{\Delta x}{2!} \frac{\partial^2 f}{\partial x^2} - \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} - \dots$. At the bottom, it says "Error of this approximation is termed as $O(\Delta x)$ " and " $\Delta x \gg (\Delta x)^2 \gg (\Delta x)^3$ ".

So, for that purpose let us take one function $f(x)$. So, we will use finite difference method. So, there are many ways to discretize this partial derivatives, but in today's lecture will use Taylor series expansion. So, let us consider any function $f(x)$, it is a continuous function. Now, we need to find its derivative $\frac{\partial f}{\partial x}$ and $\frac{\partial^2 f}{\partial x^2}$ using this finite difference approximation. So, before doing so, we need to have discrete points or we have to divide the domains into discrete points.

So, those points generally we represent by index i in x direction, and j in y direction. So, if we consider 1 Dimensional domain, so, if we discretize into discrete points, so these are known as grids. So, this is one point, this is one point, this is one point. So, these are the discrete points and separated by a distance, uniform distance Δx .

And, these index of these discrete points we are telling it is i , this is your $i + 1$ and this is $i - 1$. As you are considering only 1 Dimensional, we are using index i , but if it is 2 Dimensional then we will use index j in y direction, and if it is 3 Dimensional then index k in third direction.

So, these derivatives whatever we have written the $f(x)$ is a continuous function, then if we need to find these derivatives, at in the values of these discrete points, then let us say that these $f(x)$ varies like this. So, let us say that this point, let us say this is you're A , B and C and at this points you have the values known f_{i-1} , f_i and f_{i+1} . So, we will use now Taylor series expansion just to represent this derivative in some approximate values. So, what is Taylor series expansion. Let us write first, let us say that $f(x + \Delta x)$, we need to expand using Taylor series about the point x . So, if this is your x_i , so about the x_i we want to expand.

So, you will get $f(x + \Delta x)$, you can write $f(x + \Delta x) = \sum_{n=0}^{\infty} \frac{\Delta^n f}{n!} \Delta x^n$. So, this is the Taylor series expansion of $f(x + \Delta x)$ about x . So, we can expand it as $f(x + \Delta x) = f(x) + \Delta x \frac{df}{dx} + \frac{\Delta x^2}{2!} \frac{d^2 f}{dx^2} + \frac{\Delta x^3}{3!} \frac{d^3 f}{dx^3} + \dots$ and there will be other terms.

Now, if you want to represent this derivative $\frac{df}{dx}$ so, you can write $\frac{df}{dx}$ as so this if you take on the left hand side then you will get $f(x + \Delta x) - f(x)$. So, there Δx is there you divided, divided by Δx and other terms will be there. So, this side it will go so, it will be $-\Delta x \frac{d^2 f}{dx^2} + \dots$

So, we are dividing by Δx so, it will be $\frac{\Delta x^2}{2!} \frac{d^2 f}{dx^2} + \dots$ and so on. So, you can see that we have represented this first derivative of f with respect to x , about the point x as $f(x + \Delta x) - f(x)$ divided by Δx Δx is your step size and it is uniform.

So, it is uniform grid. So, these discrete points are known as grid, that we have approximated as the value at point $f(x + \Delta x) - f(x)$ divided by Δx and some other terms are

there. So, if you truncate it up to this point, so this is the finite difference approximation, of this first derivative $\frac{df}{dx}$. And as you are using one forward point, $f(x + \Delta x)$, it is known as forward difference approximation.

But we are neglecting the other terms. So, these terms are known as truncation error. So, truncation error, if this is your truncation error because you have truncated this after that you are neglecting this term. So, this is your truncation error. So, this is the truncation error, what is truncation error, so you can see that truncation error is the difference between the partial derivative and the finite difference approximation. Because finite difference approximation is this one, and this is your partial derivative. So, the truncation error is the difference between partial derivative and the finite difference approximation.

So, we can write it here, the truncation error is the difference between partial derivative and its finite difference representation. So now, you can see that so truncation error you can write in this case as, $-\frac{\Delta x^2}{2} \frac{d^2f}{dx^2} - \frac{\Delta x^3}{6} \frac{d^3f}{dx^3} + \dots$. So, in this case, you can see in the truncation error the leading term, first term is the leading term in this leading term the Δx order is one.

So, it is actually the error of this approximation is termed as, what type of approximation is $O(\Delta x)$. So, this is the notation, O . So, this is order of Δx . So, in the leading term, whatever you have this Δx or Δx^2 so, whatever is the highest order is there in the first term, so, that is known as order of Δx .

So, you can see, that if Δx is very small, then Δx will be much, much greater than Δx^2 and Δx^2 will be much, much greater than Δx^3 . So obviously, the first term or the leading term in the truncation error will contribute maximum error. So, that is why, the error of this approximation is termed as the order of whatever Δx is there in the leading term.

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$$\frac{\partial f}{\partial x}_i = \frac{f_{i+1} - f_i}{\Delta x} + O(\Delta x)$$

$$f(x - \Delta x) = f(x) + \sum_{n=1}^{\infty} \frac{(\Delta x)^n}{n!} \frac{\partial^n f}{\partial x^n} \quad \begin{matrix} + - n \text{ is even} \\ - - n \text{ is odd} \end{matrix}$$

$$f(x - \Delta x) = f(x) - \frac{\Delta x}{1!} \frac{\partial f}{\partial x} + \frac{(\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} - \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$$

$$\frac{\partial f}{\partial x} = \frac{f(x) - f(x - \Delta x)}{\Delta x} + \frac{\Delta x}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta x)^2}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$$

$$\frac{\partial f}{\partial x} = \frac{f(x) - f(x - \Delta x)}{\Delta x} + O[\Delta x]$$

Backward difference approximation

$$\frac{\partial f}{\partial x} = \frac{f_i - f_{i-1}}{\Delta x} + O(\Delta x)$$

Finite Difference Method

$$f(x) \quad \frac{\partial f}{\partial x} \quad \frac{\partial^2 f}{\partial x^2}$$

Taylor series expansion

$$f(x + \Delta x) = f(x) + \sum_{n=1}^{\infty} \frac{(\Delta x)^n}{n!} \frac{\partial^n f}{\partial x^n}$$

$$f(x + \Delta x) = f(x) + \frac{\Delta x}{1!} \frac{\partial f}{\partial x} + \frac{(\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$$

$$\frac{\partial f}{\partial x} = \frac{f(x + \Delta x) - f(x)}{\Delta x} = \frac{\Delta x}{2!} \frac{\partial^2 f}{\partial x^2} - \frac{(\Delta x)^2}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$$

Forward difference approximation

Truncation Error (TE)

Truncation error is the difference between partial derivative and its finite difference representation.

$$TE = - \frac{\Delta x}{2!} \frac{\partial^2 f}{\partial x^2} - \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} - \dots$$

Error of this approximation is termed as

$$O(\Delta x) \quad \Delta x \gg (\Delta x)^2 \gg (\Delta x)^3$$

So, now, if you write in terms of the index i , then you can write $\frac{\partial f}{\partial x}$ is equal to, at about point i as $f_{i+1} - f_i$ divided by Δx and what is the order of approximation, it is Δx . So, this is the finite difference approximation and it is forward difference approximation of the first derivative $\frac{\partial f}{\partial x}$.

Now, if you want to graphically represent it what does it mean? So, if you see in the previous graph so, about this point B actually you are writing this approximation. So, you are using the point C and B . So, the slope what it represent graphically, it is the slope if you join the points B and C . So, this is your forward difference and at point B if you want to exactly find the slope of this tangent what will have.

So, if you want to plot it so, it will be just tangent at this point B. So, this is your exact representation of the slope of this tangent. But when you are using forward difference and using a points B and C so, this is your approximation, forward difference approximation. Now, similarly, if we use $f(x - \Delta x)$ if you expand it using Taylor series about the point x , then you can write $f(x - \Delta x) = \sum_{n=0}^{\infty} \frac{(-1)^n \Delta x^n}{n!} f^{(n)}(x)$, where plus is if n is even and minus sign will come if n is odd.

So, if you expand it, you will get $f(x - \Delta x) = f(x) - \Delta x f'(x) + \frac{\Delta x^2}{2!} f''(x) - \frac{\Delta x^3}{3!} f'''(x) + \dots$

So here, now if you want to represent the first derivative $f'(x)$ so, you can write it as $f'(x) = \frac{f(x) - f(x - \Delta x)}{\Delta x} - \frac{\Delta x}{2} f''(x) + \frac{\Delta x^2}{6} f'''(x) - \dots$

So, if you truncate it up to this, then your finite difference approximation is $f'(x) \approx \frac{f(x) - f(x - \Delta x)}{\Delta x}$ and what is the order of this truncation error, it is the Δx . So, you can see that we are using 2 points $f(x)$ and 1 backward points, $f(x - \Delta x)$. So, as you are using a backward point it is known as backward difference approximation.

Now, if you want to represent in terms of the discrete points i , $i + 1$ and $i - 1$ you can write $f'(x) = \frac{f_i - f_{i-1}}{\Delta x} - \frac{\Delta x}{2} f''(x) + \frac{\Delta x^2}{6} f'''(x) - \dots$

So, you are using point A x_{i-1} , and point B x_i . So, it will be the graphical representation of this approximation. So, this is the slope using backward difference.

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$$f_{i+1} = f_i + \Delta x \frac{\partial f}{\partial x} + \frac{(\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \frac{(\Delta x)^4}{4!} \frac{\partial^4 f}{\partial x^4} + \dots \quad \dots (a)$$

$$f_{i-1} = f_i - \Delta x \frac{\partial f}{\partial x} + \frac{(\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} - \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \frac{(\Delta x)^4}{4!} \frac{\partial^4 f}{\partial x^4} - \dots \quad \dots (b)$$

Subtract Eq. (b) from Eq. (a)

$$f_{i+1} - f_{i-1} = 2\Delta x \frac{\partial f}{\partial x} + \frac{2(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$$

$$\frac{\partial f}{\partial x} \Big|_i = \frac{f_{i+1} - f_{i-1}}{2\Delta x} - \frac{(\Delta x)^2}{3!} \frac{\partial^3 f}{\partial x^3} - \dots$$

$$\frac{\partial f}{\partial x} \Big|_i = \frac{f_{i+1} - f_{i-1}}{2\Delta x} + O[(\Delta x)^2]$$

Central difference approximation

Adding Eq. (a) and Eq. (b)

$$f_{i+1} + f_{i-1} = 2f_i + \frac{2(\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{2(\Delta x)^4}{4!} \frac{\partial^4 f}{\partial x^4} + \dots$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{f_{i+1} - 2f_i + f_{i-1}}{(\Delta x)^2} + \frac{2(\Delta x)^2}{4!} \frac{\partial^4 f}{\partial x^4} + \dots$$

- Central difference approximation

Finite Difference Method

$$f(x) \quad \frac{\partial f}{\partial x} \quad \frac{\partial^2 f}{\partial x^2}$$

Taylor series expansion

$$f(x+\Delta x) = f(x) + \sum_{n=1}^{\infty} \frac{(\Delta x)^n}{n!} \frac{\partial^n f}{\partial x^n}$$

$$f(x+\Delta x) = f(x) + \frac{\Delta x}{1!} \frac{\partial f}{\partial x} + \frac{(\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$$

$$\frac{\partial f}{\partial x} = \frac{f(x+\Delta x) - f(x)}{\Delta x} - \frac{\Delta x}{2!} \frac{\partial^2 f}{\partial x^2} - \frac{(\Delta x)^2}{3!} \frac{\partial^3 f}{\partial x^3} - \dots$$

Forward difference approximation

Truncation Error (TE)

Truncation error is the difference between partial derivative and its finite difference representation.

$$TE = -\frac{\Delta x}{2!} \frac{\partial^2 f}{\partial x^2} - \frac{(\Delta x)^2}{3!} \frac{\partial^3 f}{\partial x^3} - \dots$$

Error of this approximation is termed as $O(\Delta x)$ as $\Delta x \gg (\Delta x)^2 \gg (\Delta x)^3$

Now, if you want to write f_{i+1} and f_{i-1} , you expand this two using Taylor series about point x_i , then you will get $f_i + \Delta x \frac{\partial f}{\partial x} + \frac{\Delta x^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{\Delta x^3}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$. So, there will be other terms. And similarly, you can write $f_i - \Delta x \frac{\partial f}{\partial x} + \frac{\Delta x^2}{2!} \frac{\partial^2 f}{\partial x^2} - \frac{\Delta x^3}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$. So, you just tried the other, another term $\frac{\Delta x^4}{4!} \frac{\partial^4 f}{\partial x^4} + \dots$ and here $\frac{\Delta x^4}{4!} \frac{\partial^4 f}{\partial x^4} - \dots$ so on.

So now, if you subtract the second one from the first one, so if we equation, let us say this is your a and this is equation b, then subtract equation b from equation a, so subtract equation b

from equation a. So, what you will get, so if you subtract it then it will be $f_{i+1} - f_i$ minus 1 in left hand side.

So, first term will get cancelled then you will get $2\Delta x \Delta f$ by Δx , this third time will get cancelled then fourth time you will get, plus $2\Delta x^3$ by factorial 3 $\Delta^3 f$ by Δx^3 and so on. So now, if you want to represent this derivative Δf by Δx about point i then you can write $f_{i+1} - f_{i-1}$ divided by $2\Delta x$ and the truncation error will be, minus so it will be Δx^2 because we have divided by $2\Delta x$ divided by factorial 3 $\Delta^3 f$ by Δx^3 and so on.

So, you can see if you truncated here, then you are actually using 2 points f_{i+1} and f_{i-1} while finding the derivatives at point i , and the leading order term is having Δx^2 , so the truncation error order is Δx^2 . So, you can write Δf by Δx is $f_{i+1} - f_{i-1}$ divided by $2\Delta x$ because these are separated or by distance $2\Delta x$. So, this is your i , this is your $i+1$, $i-1$, so $f_{i+1} - f_{i-1}$ divided by $2\Delta x$ and order of accuracy is Δx^2 .

So, graphical if you want to represent it, so you are using point x_{i-1} and x_{i+1} . So, that means A and C, so if you join these 2 points A and C, so it will give a slope using central difference because that approximation is known as central difference. So, you can see that central difference approximation is close to the exact solution of this Δf by Δx . So, this approximation is known as central difference approximation.

So, now if you want to find the second derivative approximation $\Delta^2 f$ by Δx^2 , so you can see from these two equations. So, if you add this equation a and b, then what you will get, so adding equation a and equation b, what you will get you just see, so it will be $f_{i+1} + f_{i-1}$ left hand side, right hand side first term to f_i . The second term will get cancelled, then you will get $2\Delta x^2$ divided by factorial 2 means $2\Delta^2 f$ by Δx^2 . And in this case, this 2, 2 will get cancelled out and then fourth term will get canceled, then the next term will be $2\Delta x^4$ by factorial 4 $\Delta^4 f$ by Δx^4 and other terms.

So, here you can see now if you represent this, second derivative of f with respect to x , so you can write $\Delta^2 f$ by Δx^2 . So, you can write $f_{i+1} - 2f_i + f_{i-1}$ now you divide by Δx^2 and the first term will be 2 as you are dividing by Δx^2

square, so it will be $2 \Delta x^2$ by factorial 4 f by Δx to the power 4 and other terms.

So, the leading order term in the truncation error is order of Δx^2 . So, you can see that this is the order of Δx^2 , so it is a second order accurate. So, $\Delta^2 f$ by Δx^2 you are representing using 3 discrete point values, one is f_i , f_{i+1} and f_{i-1} and this approximation also is known as central difference. So, central difference approximation of this second derivative.

In other way also you can also derive, the second order approximation so that let us see in the next slide.

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$$\begin{aligned} \frac{\partial^2 f}{\partial x^2} &= \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) \\ &= \frac{\partial f}{\partial x} \Big|_{i+\frac{1}{2}} - \frac{\partial f}{\partial x} \Big|_{i-\frac{1}{2}} + O[(\Delta x)^2] \\ &= \frac{f_{i+1} - f_i}{\Delta x} - \frac{f_i - f_{i-1}}{\Delta x} + O[(\Delta x)^2] \\ &= \frac{f_{i+1} - 2f_i + f_{i-1}}{(\Delta x)^2} + O[(\Delta x)^2] \end{aligned}$$

Say, you have this discrete points, this is your uniform grid. So, it is i this is your $i+1$ this is your $i-1$ and you have in between these 2, let us say this is your $i+1/2$ and this your $i-1/2$. So, if you want to represent this second derivatives. So, you can write $\Delta^2 f$ by Δx^2 . So, you can write Δ of Δx of Δf by Δx . So, you can write Δf by Δx you can use a central difference so, $i+1/2$ minus Δf by Δx $i-1/2$ So, it is your central difference about the point i divided by.

So, what is that distance, so if this is your Δx , this is the step size. This is your Δx and the distance between these 2 points are also, the distance between these 2 points is also Δx . So, this is the first derivative we are writing and, so you can write Δx and what is the

order of accuracy. So, we have seen that it is second order accurate, so it will be order of Δx square.

So, now, you can see that Δf by Δx now, you can again use central difference of this. So, you can write Δf by Δx at i plus half. So, this is your i plus half. So, this point is i plus half. So, this if you use the central difference then you will get f_{i+1} minus f_i divided by Δx . So, it is the central difference approximation of the first derivative. So, f_{i+1} minus f_i divided by Δx about the point i plus half.

So, what will be the order of accuracy, it is Δx square and minus Δf by Δx about point i minus half. So, about this point you take the central difference approximation. So, you will get f_i minus f_{i-1} divided by Δx and these 2 approximations also Δx square, earlier it was also Δx square. So, order of accuracy of this approximation will be Δx square.

So now, you can write it Δx square, so it will be f_{i+1} again minus twice f_i , so plus f_{i-1} and order of Δx square. So, this way also you can derive the finite difference approximation of the second derivative of f with respect to x .

Now, let us see that if you use more than 2 points for the first derivative then in forward difference and backward difference how you can write.

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$\frac{\partial f}{\partial x}$ f_i, f_{i+1}, f_{i+2}

Forward difference approximation

$f_{i+2} = f_i + 2\Delta x \frac{\partial f}{\partial x} + \frac{(2\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{(2\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \frac{(2\Delta x)^4}{4!} \frac{\partial^4 f}{\partial x^4} + \dots$ (c)

$f_{i+1} = f_i + \Delta x \frac{\partial f}{\partial x} + \frac{(\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \frac{(\Delta x)^4}{4!} \frac{\partial^4 f}{\partial x^4} + \dots$ (d)

$4 \times (d) - (c)$

$4 f_{i+1} - f_{i+2} = 3 f_i + 2 \Delta x \frac{\partial f}{\partial x} - \frac{4(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$

$\frac{\partial f}{\partial x} \Big|_i = \frac{-f_{i+2} + 4 f_{i+1} - 3 f_i}{2 \Delta x} + \frac{2(\Delta x)^2}{3!} \frac{\partial^3 f}{\partial x^3} + \dots$

$\frac{\partial f}{\partial x} \Big|_i = \frac{-f_{i+2} + 4 f_{i+1} - 3 f_i}{2 \Delta x} + O[(\Delta x)^2]$

Diagrams showing points f_i, f_{i+1}, f_{i+2} on a horizontal axis with spacing Δx .

So, for these, let us say that we will use 3 discrete points. So, we will find the value of Δf by Δx . So, this is the finite difference approximation of Δf by Δx using 3 discrete

points, and we will use f_i , f_{i+1} and f_{i+2} . So, using f_i , f_{i+1} , and f_{i+2} . So, we are using forward points $i+1$ and $i+2$. So, it is forward difference approximation.

So, we will use uniform grid, so the spacing between these points, i , $i+1$ and $i+2$, let us say. So, this is your i , this is your $i+1$ and this is your $i+2$ and it is uniform steps size so it is Δx and this is also Δx and the values at this point f_{i+1} this is f_{i+2} and this your f_i .

So, we need to represent this first derivative $\frac{df}{dx}$ using the values at discrete points i , $i+1$ and $i+2$. So, first we will use Taylor series expansion of f_{i+2} and f_{i+1} . So, if you write f_{i+2} , so it is $f(x+2\Delta x)$, so you can write $f_{i+2} = f(x) + 2\Delta x \frac{df}{dx} + \frac{(2\Delta x)^2}{2!} \frac{d^2f}{dx^2} + \frac{(2\Delta x)^3}{3!} \frac{d^3f}{dx^3} + \frac{(2\Delta x)^4}{4!} \frac{d^4f}{dx^4} + \dots$ and other higher order terms.

So, now let us expand f_{i+1} about the point x_i so, you will use $f_{i+1} = f(x+\Delta x) = f(x) + \Delta x \frac{df}{dx} + \frac{(\Delta x)^2}{2!} \frac{d^2f}{dx^2} + \frac{(\Delta x)^3}{3!} \frac{d^3f}{dx^3} + \frac{(\Delta x)^4}{4!} \frac{d^4f}{dx^4} + \dots$ and other higher order terms.

Now, what we will do we need to find the values of $\frac{df}{dx}$. So, what we will do, we will just write $4f_{i+1} - f_{i+2}$. So, we will do this algebra for $f_{i+1} - f_{i+2}$, so what you will get, so if you multiply, so if equation this as c and this is your d , then you write 4 into equation d and minus equation e .

So, if you do that, then what you will get, so for f_{i+1} , so it will be $3f_i$ then you will get, this is your $\frac{df}{dx}$ so it will be 4 into d so it will be 4 . So, $4 - 2$ so it will be 2 $\Delta x \frac{df}{dx}$. Then if you write these terms it will be multiplied by 4 , so it will be 4 and here 4 .

So, this term will become 0 because this is your 4 , and this is also your multiplied by 4 and if we have subtracted, so this term will get 0 . So, next term will be, so it will be plus 0 . So, next time you write, so it will be multiplied by 4 , so it will be 4 and this is your 8 , so you will get minus, so it will be $4 \Delta x^3 \frac{d^3f}{dx^3}$ and so on.

So, now you represent $\frac{df}{dx}$ so $\frac{df}{dx}$ about point i . So, $3f_i$ will come this side it will be minus. So, you can write $-\frac{2}{3} \Delta x^2 \frac{d^2f}{dx^2} + \frac{4}{3} \Delta x \frac{df}{dx} - f_i$ you divided

by $2\Delta x$ it will be $2\Delta x$ and minus. So, this will come in this right hand side, to show it will be plus. So, you divide by $2\Delta x$ it will be $2\Delta x$ square by factorial 3 del cube f by del x cube and other terms.

So, you can see that in this case, the truncation error order is Δx square. So, you have represented this first derivative del f by del x, using forward difference approximation f_{i+2} plus $4f_{i+1}$ minus $3f_i$ by $2\Delta x$ order up Δx square. So, it is a second order accurate. So, you have used 3 points f_i , f_{i+1} and f_{i+2} . So, you are getting the approximation, finite difference approximation of this derivative del f by del x as second order accurate.

So, this sometime it is required at the boundary points. So, if you have any boundary and you need to find the derivative or if you want to apply the boundary conditions in terms of derivative, if you want to have secondary accurate of this approximation, then you can use it. Because you will get these 3 points as this is your i , this is your $i+1$ and this your $i+2$.

So, if you require secondary approximation at the boundary points or first derivative, then you can use this approximation.

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$\frac{\partial f}{\partial x}$ f_i, f_{i-1}, f_{i-2} Backward difference approximation f_{i-2}, f_{i-1}, f_i

$$f_{i-2} = f_i - 2\Delta x \frac{\partial f}{\partial x} + \frac{(2\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} - \frac{(2\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \dots \quad (e)$$

$$f_{i-1} = f_i - \Delta x \frac{\partial f}{\partial x} + \frac{(\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} - \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + \dots \quad (f)$$

$$-4f_{i-1} + f_{i-2} = -3f_i + 2(\Delta x) \frac{\partial f}{\partial x} - \frac{4(\Delta x)^2}{3!} \frac{\partial^2 f}{\partial x^2} + \dots$$

$$\frac{\partial f}{\partial x} \Big|_i = \frac{3f_i - 4f_{i-1} + f_{i-2}}{2\Delta x} + \frac{2(\Delta x)^2}{3!} \frac{\partial^2 f}{\partial x^2} + \dots$$

$$\frac{\partial f}{\partial x} \Big|_i = \frac{3f_i - 4f_{i-1} + f_{i-2}}{2\Delta x} + O[(\Delta x)^2]$$

So, similarly if you want to use 3 backward points so, f_i , f_{i-1} and f_{i-2} , then similarly you can find this derivative del f by del x using 3 values f_i , f_{i-1} , and f_{i-2} . So similarly, if you use it, this Taylor series expansion for f_{i-2} so, you have 3 points.

So, this is your 3 points, discrete points separated by distance, uniform distance Δx . So, this is your i , this is your $i - 1$, and this your $i - 2$.

So, the values at this point is f_i , f_{i-1} , and f_{i-2} . So similarly, whatever way we have derived the forward difference approximation using 3 points, we can use the backward difference approximation, to find the Δf by Δx using 3 discrete point values f_i , f_{i-1} , and f_{i-2} .

So, here f_{i-2} you can write, $f_{i-2} \Delta x \Delta f$ by Δx plus $2 \Delta x^2$ by factorial 2 $\Delta^2 f$ by Δx^2 minus $2 \Delta x^3$ by factorial 3 $\Delta^3 f$ by Δx^3 and so on. Similarly, f_{i-1} you can expand using Taylor series about point x_i . So, you will get $f_{i-1} \Delta x \Delta f$ by Δx plus Δx^2 by factorial 2 $\Delta^2 f$ by Δx^2 minus Δx^3 by factorial 3 $\Delta^3 f$ by Δx^3 and other higher order terms.

So, if you do this algebra, let us say minus 4 f_{i-1} plus f_{i-2} . So, that means if it is your equation e, this is your equation f, then you multiply equation f with 4 and subtract it from c, so it will be c minus 4 into f. So, what you can write, 4 f_{i-1} , so 4 f_{i-2} minus 4 f_{i-1} , so if you multiply this f with 4, so you will get minus 3 f_i . Then you will get here, 4 and 4 so you will get 2, so you will get plus 2 $\Delta x \Delta f$ by Δx . You can see here, the third term in the right hand side will get cancelled because you are multiplying 4 with f when you are subtracting so, you will get 0.

Then the other term will be here, so it will be 8 minus 8 plus 4 so, it will be minus 4 Δx^3 by factorial 3 $\Delta^3 f$ by Δx^3 and other terms. So, now if we want to represent Δf by Δx so, you can write this 3 f_i you can take it in the right hand side. So, it will be 3 f_i minus 4 f_{i-1} plus f_{i-2} divided by so, 2 Δx . And this will be in the right hand side, so it will be, you are dividing by 2 Δx it will be 2 Δx^2 by factorial 3 $\Delta^3 f$ by Δx^3 and other higher order terms. So, you can see the leading term, in the truncation error is having the order of Δx^2 .

So, this approximation Δf by Δx , you are using backward difference approximation and you are using 3 discrete values f_{i-1} and f_{i-2} , which is having the order of accuracy Δx^2 . Similar way, so, you can actually use these for the boundary points to having these first derivative with this accuracy Δx^2 .

So, if you want to use or if you want to discretize any derivative, first derivative Δf by Δx at the boundary points and you need second order accuracy then you can use this, you can see

this is your boundary. So, this is your i, this is your i minus 1 and this is your i minus 2 and the distance is delta x and this is your delta x. So, till now we have found the derivatives of a single variable.

(Refer Slide Time: 39:48)

$f(x,y)$
 $\frac{\partial f}{\partial x \partial y} \Big|_{i,j}$
 Taylor series expansion for two variables
 $f(x+\Delta x, y+\Delta y) = f(x,y) + (\Delta x \frac{\partial}{\partial x} + \Delta y \frac{\partial}{\partial y}) f(x,y) + \frac{1}{2!} (\Delta x \frac{\partial}{\partial x} + \Delta y \frac{\partial}{\partial y})^2 f(x,y) + \dots$
 $= f(x,y) + \Delta x \frac{\partial f}{\partial x} + \Delta y \frac{\partial f}{\partial y} + \frac{(\Delta x)^2}{2} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta y)^2}{2} \frac{\partial^2 f}{\partial y^2} + \frac{2\Delta x \Delta y}{2} \frac{\partial^2 f}{\partial x \partial y} + \dots$
 $+ f_{i+1,j+1} = f_{i,j} + \Delta x \frac{\partial f}{\partial x} + \Delta y \frac{\partial f}{\partial y} + \frac{(\Delta x)^2}{2} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta y)^2}{2} \frac{\partial^2 f}{\partial y^2} + \Delta x \Delta y \frac{\partial^2 f}{\partial x \partial y} + O[(\Delta x)^3, (\Delta y)^3]$
 $+ f_{i-1,j-1} = f_{i,j} - \Delta x \frac{\partial f}{\partial x} - \Delta y \frac{\partial f}{\partial y} + \frac{(\Delta x)^2}{2} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta y)^2}{2} \frac{\partial^2 f}{\partial y^2} - \Delta x \Delta y \frac{\partial^2 f}{\partial x \partial y}$
 $- f_{i-1,j+1} = f_{i,j} - \Delta x \frac{\partial f}{\partial x} + \Delta y \frac{\partial f}{\partial y} + \frac{(\Delta x)^2}{2} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta y)^2}{2} \frac{\partial^2 f}{\partial y^2} - \Delta x \Delta y \frac{\partial^2 f}{\partial x \partial y}$
 $+ f_{i+1,j-1} = f_{i,j} + \Delta x \frac{\partial f}{\partial x} - \Delta y \frac{\partial f}{\partial y} + \frac{(\Delta x)^2}{2} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta y)^2}{2} \frac{\partial^2 f}{\partial y^2} - \Delta x \Delta y \frac{\partial^2 f}{\partial x \partial y}$
 $f_{i+1,j+1} - f_{i-1,j-1} - f_{i-1,j+1} + f_{i+1,j-1} = 4 \Delta x \Delta y \frac{\partial^2 f}{\partial x \partial y} + O[(\Delta x)^3, (\Delta y)^3]$
 $\frac{\partial^2 f}{\partial x \partial y} = \frac{f_{i+1,j+1} - f_{i-1,j-1} - f_{i-1,j+1} + f_{i+1,j-1}}{4 \Delta x \Delta y} + O[(\Delta x)^3, (\Delta y)^3]$

So, now if we want to find the mixed derivatives, so how we will find it? So, mixed derivative mean, say if f is function of x and y. So now, you want to find the mixed derivatives of it. So, you want to find del f by del x del y, about any point let us say i and j. So, i is the index notation in x direction, and j is the index in y direction. So, in this case now the grid points or discrete points, let us draw. So, it will be on uniform grid we are drawing.

So, this is your ij, this, so in right hand side so, it is i plus 1 j so, this is your i minus 1 j, this is your ij minus 1 and this is your ij plus 1. So, these are the discrete points and we want to find this mix derivative about this point ij with the neighboring values. And, the distance these are uniform step size. So, this is your delta x, this is your also delta x and this is your delta y and this is your delta y. So, delta y is also uniform and delta x is also uniform, but delta x may not be equal to delta y.

So, in this case, we will use Taylor series expansion of two variables. So, Taylor series expansion for two variables. So, if you write for two variables, you can write this way, f x plus delta x y plus delta y. So, this you want to expand about the point x y. So, it will be f x y plus delta x del of del x plus del y del of del y f x y plus del x del of del y, so it will be 1 by factorial 2, 1 by factorial 2 plus del y del of del y square f x y and so on.

So, if you expand it, so it will get $f_x y + \Delta x \Delta f_x y$ or you just write Δf by Δx plus $\Delta y \Delta f$ by Δy . So, this is your factorial 2, so 1 by factorial 2 is 2. So, 1 by 2 Δx square $\Delta^2 f$ by Δx square plus Δy square by factorial 2 $\Delta^2 f$ by Δy square and you have $\Delta x \Delta y$, y factorial 2 so it will be 2 here, here 2 $\Delta f \Delta x \Delta y$ and so on.

So, you will have now, these 2, 2 will get cancel out. So, if you now expand all this $f_{i+1, j} - f_{i, j+1} + f_{i, j} - f_{i-1, j+1}$, then you can write all these points. So, another points you write here, $i+1, j+1$ here another point $i+1, j-1$ this is your $i-1, j-1$ and this is your $i-1, j+1$.

So, if you write $f_{i+1, j+1}$, so you can expand it using this $f_{i, j} + \Delta x \Delta f$ by Δx plus $\Delta y \Delta f$ by Δy plus Δx square by 2 $\Delta^2 f$ by Δx square plus Δy square by factorial 2 $\Delta^2 f$ by Δy square plus $\Delta x \Delta y \Delta f \Delta x \Delta y$ and whatever you have neglected so, that will be order of accuracy as Δx cube Δy cube.

So, now if you write for $f_{i-1, j-1}$. Similarly, you can write $f_{i, j} - \Delta x \Delta f$ by Δx minus $\Delta y \Delta f$ by Δy . So, it will be plus Δx square by 2 $\Delta^2 f$ by Δx square then it will be plus Δy square by 2 $\Delta^2 f$ by Δy square and it will be minus, minus plus it will be $\Delta x \Delta y \Delta f \Delta x \Delta y$.

Similarly, you can write $f_{i-1, j+1}$. So, it will be $f_{i, j}$, so it will be minus $\Delta x \Delta f$ by Δx plus $\Delta y \Delta f$ by Δy and it will be Δx square by 2 $\Delta^2 f$ by Δx square. Then it will be, plus Δy square by 2 $\Delta^2 f$ by Δy square and $\Delta x \Delta y \Delta f \Delta x \Delta y$. And $f_{i+1, j-1}$ if you write then it will get $f_{i, j}$, so it will be plus $\Delta x \Delta f$ by Δx , this is x and this will be minus $\Delta y \Delta f$ by Δy plus Δx square by 2 $\Delta^2 f$ by Δx square plus Δy square by 2 $\Delta^2 f$ by Δy square plus $\Delta x \Delta y \Delta f \Delta x \Delta y$.

So, here it will be minus and this is will be also minus. So now, if you do this algebra, $f_{i+1, j+1} - f_{i+1, j-1} - f_{i-1, j+1} + f_{i-1, j-1}$. So, what you will get, so you can see so, $f_{i+1, j+1} - f_{i+1, j-1} - f_{i-1, j+1} + f_{i-1, j-1}$. So, then this is minus and this is plus. So, this is plus, this is plus and this is minus, this is minus.

So, if you do it you will see that these, these f will cancel out. So, if these are 2 plus and these are 2 minus of these will also cancel out, these will cancel out, these will cancel out, these will cancel out so, you will get only 4, so it is minus, minus plus, so 4 $\Delta x \Delta y \Delta f \Delta x \Delta y$. So, if you write it so, it will be order of Δx cube Δy cube. So now, if you

want to find the mix derivative, so, you can write del f by del x del y is nothing but $f_{i,j+1}$ plus 1 minus $f_{i,j-1}$ plus 1 minus $f_{i,j}$ plus 1 plus $f_{i,j}$ minus 1 minus 1.

So, you divide by 4 delta x delta y. So, what will be the order of accuracy, because the truncated term whatever we have seen that it is order of delta x cube and delta y cube. So, now we are dividing by delta x and delta y. So, obviously then order of accuracy will be delta x square and delta y square. So, you can write order of accuracy is delta x square and delta y square. So, this mix derivative we are found using the Taylor series expansion.

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$$\begin{aligned} \frac{\partial^2 f}{\partial x \partial y} \Big|_{i,j} &= \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \Big|_{i,j} \right) = \frac{\partial}{\partial x} \left(\frac{f_{i,j+1} - f_{i,j-1}}{2 \Delta y} \right) + O((\Delta y)^2) \\ &= \frac{1}{2 \Delta y} \left[\frac{\partial f}{\partial x} \Big|_{i,j+1} - \frac{\partial f}{\partial x} \Big|_{i,j-1} \right] + O((\Delta y)^2) \\ &= \frac{1}{2 \Delta y} \left[\frac{f_{i+1,j+1} - f_{i-1,j+1}}{2 \Delta x} - \frac{f_{i+1,j-1} - f_{i-1,j-1}}{2 \Delta x} \right] + O((\Delta x)^2, (\Delta y)^2) \\ &= \frac{f_{i+1,j+1} - f_{i-1,j+1} - f_{i+1,j-1} + f_{i-1,j-1}}{4 \Delta x \Delta y} + O((\Delta x)^2, (\Delta y)^2) \\ \frac{\partial^2 f}{\partial x \partial y} \Big|_{i,j} &= \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \Big|_{i,j} \right) = \frac{\partial}{\partial x} \left[\frac{f_{i,j+1} - f_{i,j-1}}{\Delta y} \right] + O((\Delta y)^2) \\ &= \frac{1}{\Delta y} \left[\frac{\partial f}{\partial x} \Big|_{i,j+1} - \frac{\partial f}{\partial x} \Big|_{i,j-1} \right] + O((\Delta y)^2) \\ &= \frac{1}{\Delta y} \left[\frac{f_{i+1,j+1} - f_{i-1,j+1}}{\Delta x} - \frac{f_{i+1,j-1} - f_{i-1,j-1}}{\Delta x} \right] + O((\Delta x)^2, (\Delta y)^2) \\ &= \frac{f_{i+1,j+1} - f_{i-1,j+1} - f_{i+1,j-1} + f_{i-1,j-1}}{2 \Delta x \Delta y} + O((\Delta x)^2, (\Delta y)^2) \end{aligned}$$

But you can also derive it using this way. So, you can write del2 f by del x del y, you can write it as a del of del x of del of del y. Now, you can use the central difference. So, if you use the central difference, then it will be order of accuracy delta x, y square. So, if del of del x, so now we are using del f by del y, so that we are using f, so it is at i, j. So, this we are writing, so at i, j. So, del f by del y you can write, $f_{i,j+1}$ minus $f_{i,j-1}$ divided by so 2 delta y.

So, what is the order of accuracy because we have a central difference of this first derivative, so you can write order of delta y square. Now, this we can write 1 by to delta y and now you can write del f by del x about i, j plus 1 minus del f by del x i, j minus 1 which is order of delta y square.

So, now again it is first derivative. So, now you can use central difference so, that it will be, order of accuracy will be delta x square so, you can write 1 by 2 delta y. So, for del f by del x

you can write at $i, j + 1$. So, if you use the central difference, you can write $f_{i+1, j+1} - f_{i-1, j+1}$ divided by $2\Delta x$. This is the central difference and obviously, the order of accuracy is Δx^2 .

And similarly, this you can write $\frac{\partial f}{\partial x}$ at $i, j - 1$. So, it will be $f_{i+1, j-1} - f_{i-1, j-1}$ divided by $2\Delta x$. So, this is also central difference of this first derivative about the point $i, j - 1$ and both are having the order of accuracy Δx^2 , so overall accuracy is $\Delta x^2 \Delta y^2$.

So, if it is so, so now you can write so, it will be $4\Delta x \Delta y$ it will be $f_{i+1, j+1} - f_{i-1, j+1} - f_{i+1, j-1} + f_{i-1, j-1}$ so it will be $f_{i+1, j+1} - f_{i-1, j+1} - f_{i+1, j-1} + f_{i-1, j-1}$ and this minus, minus plus, so it will be $f_{i-1, j-1}$ and order of accuracy second order in both x and y .

Now, let us use forward difference for this mix derivative. So, if you use the forward difference approximation, then similarly you can $(\frac{\partial^2 f}{\partial x \partial y})_{i, j}$ as $\frac{\partial}{\partial x} \frac{\partial f}{\partial y}$ at i, j . So, this you can write, if you use the forward difference of this first derivative. So, you can write $\frac{\partial}{\partial x} \frac{\partial f}{\partial y}$, so it will be $f_{i+1, j} - f_{i, j}$. So, this is your forward difference divided by the distance between this 2 points is Δx . What is the order of accuracy, this is the first order accuracy it will be the order of Δx .

So similarly, you can right now $\frac{\partial f}{\partial y}$ at $i, j + 1$ minus $\frac{\partial f}{\partial y}$ at i, j and order of accuracy is Δy . So, now you got the first derivative with respect to x . So now, you use again forward difference, for each derivative.

So, what you will get, $\frac{\partial^2 f}{\partial x \partial y}$. So, if you use this $\frac{\partial f}{\partial x}$ you will get $f_{i+1, j+1} - f_{i-1, j+1}$ divided by Δx . And what is the order of accuracy, obviously, order of Δx and you will get here $f_{i+1, j+1} - f_{i-1, j+1} - f_{i+1, j-1} + f_{i-1, j-1}$ this is also you have used forward difference, so Δx so order of accuracy is $\Delta x \Delta y$. So, you will get $\Delta x \Delta y$.

So, it will be $f_{i+1, j+1} - f_{i-1, j+1} - f_{i+1, j-1} + f_{i-1, j-1}$. So, this will be $f_{i+1, j+1} - f_{i-1, j+1} - f_{i+1, j-1} + f_{i-1, j-1}$ and order of accuracy is $\Delta x \Delta y$. So, today we have used Taylor series expansion to find the finite difference approximation of first derivative and second derivative. So, first we have learned the forward difference approximation, then backward difference approximation and central difference approximation of the first derivative. Then also, we have learned the central difference approximation of second

derivative. And also, at the last we have learned the finite difference approximation of mixed derivative. Thank you