

Computational Fluid Dynamics for Incompressible Flows
Professor Amaresh Dalal
Department of Mechanical Engineering
Indian Institute of Technology, Guwahati
Lecture 01
Solution of Navier-Stokes Equations using FVM

Hello everyone, so, till now, we have discretized the convection diffusion equation using finite volume method. So, now you are in a position to discretize the Navier-Stokes equation using Finite Volume Method. So, in the Navier-Stokes equation pressure gradient term appears. First let us discretize this pressure gradient term using finite volume method.

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Solution of Navier-Stokes Equations using FVM

Steady Navier-Stokes Equations
 $\nabla \cdot (\rho \vec{u} \vec{u}) = -\nabla p + \nabla \cdot (\mu \nabla \vec{u}) + \vec{b}$

$S_{u_x}|_p = - \int_V \nabla p \cdot \hat{n}_i dV$

$\hat{n}_i = \text{the direction unit normal in which the component of } \vec{u} \text{ being computed.}$
 $\nabla p \cdot \hat{n}_i = \frac{\partial p}{\partial x} \hat{i}_1 + \frac{\partial p}{\partial y} \hat{i}_2$

x-mom eqn. $\hat{n}_i = \hat{i}_1 \quad \frac{\partial p}{\partial x}$
y-mom eqn. $\hat{n}_i = \hat{i}_2 \quad \frac{\partial p}{\partial y}$

$S_{u_x}|_p = - \int_A \nabla p \cdot \hat{n}_i \cdot d\vec{S}$
 $= - \sum_i p_i A_{j_i}$

For x-momentum eqn
 $S_{u_x}|_p = - (p_e A_e - p_w A_w) = - (p_e - p_w) \Delta y$

For y-momentum eqn
 $S_{u_y}|_p = - (p_n A_n - p_s A_s) = - (p_n - p_s) \Delta x$

Grid diagram showing a central cell with faces labeled e, w, n, s and a shaded control volume. Dimensions Δx and Δy are indicated. Faces are labeled with $(\delta x)_e, (\delta x)_w, (\delta y)_n, (\delta y)_s$. Area calculations are shown: $A_e = A_w = \Delta y$ and $A_n = A_s = \Delta x$.

So, consider first the co-located grid where u, b, w, pressure and all the scalars are defined at the cell centre p. So, that is known as co-located grid, you have learned while learning the Mac algorithm. So, first let us write the Navier-Stokes equation. So, we will write for steady Navier-Stokes equations. So, in vector form if you write then it is divergence of rho u, u is equal to minus grad p plus divergence of mu grad u.

So you can see this is your convection term, this is your diffusion term. So, if you do not have this pressure gradient term, then this represents the steady convection diffusion equation. So, you know how to discretize this convection diffusion equation. Now, here pressure gradient term appears in the Navier-Stokes equation. So, we will integrate this pressure gradient term using finite volume method. Here also you can write the general source term b.

So, now this pressure gradient term let us discretize using finite volume method over this main control volume p . So, at this cell centre p , we are defining u , v and pressure p . So, if you write S_{ui} , i is the direction in which you are taking the momentum equation, whether x momentum or y momentum equation, so it will come u or v for the pressure.

So this is the source term. So you can integrate over the control volume $\int \text{grad } p \cdot n_i dV$. So, what is n_i ? n_i is the direction unit normal in which the component of u being computed. So if you consider u momentum equations, so this will be only i , okay. So, if you consider u momentum equation or x momentum equation, okay, so, you will consider only u .

So, for that you will get n_i as i okay and for y momentum equation you will get n_i as j . So what you are going to get? So $\text{grad } p \cdot n_i$, so if you take this obviously, you are going to get minus $\frac{\partial p}{\partial x}$. So, if you consider only $\text{grad } p \cdot n_i$, so, what you are going to get in the x momentum equation? So, you are going to make the dot product with $\text{grad } p$ with i . So, $\text{grad } p$ is for two dimensional case it is $\frac{\partial p}{\partial x} i + \frac{\partial p}{\partial y} j$.

So, now if you make the dot product with $\text{grad } p$ with the unit normal in the x direction i then you are going to get minus $\frac{\partial p}{\partial x}$. And similarly, when you are making dot product with $\text{grad } P$ and j , j is the unit normal in the y direction then you are going to get minus $\frac{\partial p}{\partial y}$ and those are the pressure gradient terms in x momentum and y momentum respectively.

So, it is $\frac{\partial p}{\partial x}$ and this is your minus $\frac{\partial p}{\partial y}$ and this is the pressure gradient term right, in x momentum equation and this is y momentum equation. So, now, this let us integrate over this control volume now use Gauss divergence theorem, then convert it to surface integral okay. So, if it is surface integral then you can write it as $\int p n_i \cdot ds$.

So using Gauss divergence theorem this volume integral we are converting to the surface integral and you know p is the pressure, pressure is the scalar. So, now this you can write minus summation of P_f , all the faces A_{fi} . Again A_{fi} okay, A_{fi} is the area, magnitude of the area in particular direction.

So, if you are considering this two dimensional grid, so, if you are considering the x momentum equation then in the i direction what is the area? So, you can see this is Δy okay. So, this is your Δy . So, in this case A_e is equal to A_w is equal to Δy okay. So, i is in the direction which you are actually considering the momentum equation.

Similarly if you consider the momentum equation, then your normal will be in the j direction and you can see this is your surface area. So that will be Δx . So, e_n is equal to A_s is equal to Δx . So, if you write these ways pressure gradient source term for the u momentum equation, let us write what you are going to get.

So, now we are going to write this source term if you are considering the u momentum equation or x momentum equation. So, for x momentum equation, this is u okay the pressure gradient term. So how many faces are there? So it is two. So you are going to get $\text{minus } P_e A_e \text{ minus } P_w A_w$. So, this $P_e A_e \text{ minus } P_w A_w$.

So, if you are considering a uniform mesh, then A is equal to A_w is equal to Δy . So, you can write $\text{minus } P_e A_e \text{ minus } P_w$ into Δy . So, this is the pressure gradient term after integrating over this control volume P . Similarly, for y momentum equation this is V , so V , Y momentum equation, so, we are writing v , so $\text{minus } P_n A_n \text{ minus } P_s A_s$. So, what you are going to get?

So, if we will consider uniform mesh, then A_n is equal to A_s is equal to Δx . So, this will get $\text{minus } P_n \text{ minus } P_s$ into Δx . So, we have integrated this pressure gradient term over the control volume on a co-located grid or non-staggered grid. So, now, you know the discretization of convection diffusion equation using finite volume method in $A_p \phi_p$ form. So, that let us write the discretized Navier-Stokes equation on this using this control volume, using this finite volume method.

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Solution of Navier-Stokes Equations using FVM

Non-staggered/Collocated Grid Staggered Grid

Discretized Navier-Stokes equations

$$a_p u_p = \sum_{nb} a_{nb} u_{nb} - (P_E - P_W) \Delta y + b_u$$

$$a_p v_p = \sum_{nb} a_{nb} v_{nb} - (P_N - P_S) \Delta x + b_v$$

$$\Rightarrow S_u|_p = -(P_E - P_W) \Delta y = - \left(\frac{P_E + P_p}{2} - \frac{P_p + P_W}{2} \right) \Delta y = -(P_E - P_W) \frac{\Delta y}{2}$$

$$S_v|_p = -(P_N - P_S) \Delta x = - \left(\frac{P_N + P_p}{2} - \frac{P_p + P_S}{2} \right) \Delta x = -(P_N - P_S) \frac{\Delta x}{2}$$

The momentum equation will contain the pressure difference between two adjacent grid points and not between adjacent ones.

Okay so, what we are going to write? $a_p u_p$, okay $a_p \phi_p$ form we are writing. So discretized Navier-Stokes equation. So x momentum equation, this is $a_p u_p$ summation of all the neighbor u_{nb} . Now we have the pressure gradient term. So, now we will write as P_E minus P_W , so P_E minus P_W .

So, this is your I forgot to mention here, so P_E , so face at East and this is the west okay, this is the face centre. So, here we are writing P_E minus P_W into Δy and the source term associated with x momentum equation b_u . Similarly, you write b_v momentum equation $a_p v_p$ is equal to summation of all the neighbor v_{nb} minus now the pressure gradient term in y momentum equation, that is P_N minus P_S into Δx plus the source term associated with y momentum equation.

So, this looks like the earlier discretized equation for convection diffusion equation for general variable ϕ . Only additional terms are for this pressure gradient to come. So, now, you see these are the discretized equation, but the pressure at East face and pressure at West face, if you see the co-located grid, so, we have discretized this equation in co-located grid.

So, if you have, this is your u , v and pressure, all you have defined at the cell centre p and this is your p and this is your small e , this is your small W and this is your small n and this is your small S and it is the neighbor in East side, N , W and South. Now, you see when you are solving this x momentum and y momentum equation in this control volume p then you need to find the pressure at this East face, West face, North face and South face.

Now, if you see that pressure, you have pressure is available only in the main control volume p . So, obviously you have to use some interpolation scheme to find the value of pressure at the face centre. So, if you use the linear interpolation assuming the uniform mesh, then what we are going to get, let us see. So, if you see this term that is your $S_u P$ is minus P_e minus P_w into Δy .

And this P_e is not available at this face centre E . So we will take the linear average between these two points, East and P where the value of pressure is available. So we will average it out like P_e plus P_p divided by 2. And in the West face, we will take P_w plus P_p divided by 2. Now you see this P_p by 2, it is plus and this is P_p by 2 minus, so these will get cancelled and you are going to get minus P_e minus P_w into Δy by 2.

Similarly for $S_v p$, you can write minus P_n minus P_s into Δx . So, at this point, North and at this face centre South, the pressure values are not available. So, you are going to interpolate it from the values from north and P for this P_n . So, it is P_n plus P_p divided by 2 minus for the South face enter, it is P_s plus P_p divided by 2 into Δx .

Now, you can see, so this is P_p by 2 and this is minus P_p by 2 so, it will get cancel and you are going to get P_n minus P_s into Δx by 2. Now look it carefully. When we are calculating this pressure gradient term for the u momentum equation you are taking the pressure gradient from the alternate grid points because you are solving the u momentum equation for this point p , but you are taking the pressure from the alternate point, capital E and capital W which is far away from this point P .

So, the momentum equation will contain the pressure difference between two alternate grid points and not between adjacent one. So, now you can see that you are taking from alternate grid points. That means, when you are calculating the pressure gradient term for the u momentum equation you are taking the pressure values far away from the main control volume p at East and West control volume.

Now, you can see that when you are calculating this pressure gradient term, you are calculating in a kosher mesh. You have the grid size of Δx and Δy , but you are calculating the pressure gradient term which is $2 \Delta x$ apart. So, that means you are calculating the pressure gradient term from the kosher mesh. So, obviously it is not desirable because you are actually calculating the pressure gradient term in a kosher mesh and obviously, this would diminish the accuracy of the solution.

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Solution of Navier-Stokes Equations using FVM

Zigzag pressure field

$S_{u1} = -(P_e - P_w) \Delta y$

Representation of the continuity Equation:

$$\nabla \cdot \vec{u} = 0$$

$$\int \nabla \cdot \vec{u} dV = 0$$

Use Gauss-divergence theorem

$$\int \vec{u} \cdot d\vec{S} = 0$$

$$\sum \vec{u}_f \cdot \vec{S}_f = 0$$

$$\sum (u_e A_e - u_w A_w) + (\sum v_n A_n - \sum v_s A_s) = 0$$

$$(u_e - u_w) \Delta y + (v_n - v_s) \Delta x = 0$$

$$\left(\frac{u_e + u_w}{2} - \frac{u_e + u_w}{2} \right) \Delta y + \left(\frac{v_n + v_s}{2} - \frac{v_n + v_s}{2} \right) \Delta x = 0$$

$$\left(\frac{u_e - u_w}{2} \right) \Delta y + (v_n - v_s) \Delta x = 0$$

Staggered grid

Now, another implication is that if you have somehow the wave pressure field, then what will happen? Let us say that for the x direction, the pressure field you have zigzag pressure field. So what will happen? So, these are the main control volume okay and this is your face s, if let us say this is your p, this is your small E and this your small W.

One dimensional case we are considering and in the x momentum equation you need the pressure at Pe and Pw but you are taking from the east and west and let us say somehow you have a zigzag pressure field due to the flow field. So, now if you have zigzag like 100, 200, okay 100, 200, 100, okay this is 200 and this is also 100.

So, now you can see that you have a pressure field which is zigzag and it is varying between the grid points as 100, 200, 100, 200, like that. Now, if you want to take the average of this pressure field at the East face, so you want to calculate this East because you have the pressure gradient term, su, you have minus Pe minus Pw into delta y.

So, now Pe minus Pw, so Pe, you will calculate. So, it will be average of these two, so it is 150, okay 100 plus 200 divided by 2, it is 150 and the west face where you have 100 plus 200 divided by 2, it is 150. So, now you can see that you have Pe is equal to 150 and Pw is equal to 150 and Pe minus Pw essentially will become 0.

So, that means in every cell if you calculate this pressure gradient term, it will become 0. So it will feel like a uniform pressure field. So uniform pressure field that means there will be no pressure gradient. But for the flow to take place you need the pressure gradient. So, this is the another problem using co-located grid.

So, one problem is that you are calculating the pressure gradient term in the staggered mesh which will actually diminish the accuracy of the solution and also you can see that if we have a zigzag pressure field then it will feel like a uniform pressure field where there will be no pressure gradient.

So, now, let us see, if you consider the continuity equation and satisfy in the co-located grid in the main control volume u , then what are the implications we will have? So, now let us say that it is your co-located grid and u , v and p , you are solving in this main control volume p and this is your east face, north, west and south.

So, what is your continuity equation? Representation of the continuity equation, so, if you consider incompressible flow then it is just divergence of u , density if you consider constants in then you can take it outside and divergence of u is equal to 0. So for these now if you integrate this continuity equation over this main control volume p , so what you are going to get?

You are integrating over this control volume dV is equal to 0. Now you convert it to surface integral. So, use Gauss divergence theorem. So we are converting this volume integral to surface integral, $u \cdot ds$ is equal to 0, where u is u_i plus v_j for the two dimensional case.

So now you can write it, summation of $\int U_f \cdot S_f$ is equal to 0. So, we are going to get $U_e A_e$, and now $U_f U_e \cdot S_e$, so, S_e is your A_{ei} , and S_w is what is that? Minus A_{wi} because you can see, the normal is in the outside normal is, sorry outward normal is in the negative x direction. So, we are considering x this direction and y this way. So, minus, similarly S_n is your A_{nj} and S_s is your minus A_{sj} , minus is because the outward normal in the negative y direction.

So, you are going to get $U_e A_e$. So, we will write now minus sign because it is minus A_w . So, $U_w A_w$ plus $V_n A_n$ minus $V_s A_s$ because the velocity at North is V_n is equal to 0. And you know that A_e is equal to A_w is equal to Δy , that is the surface area and A_n is equal to A_s is equal to Δx .

So, if you write on the uniform grid, then you can write u_e minus U_w into Δy plus V_n minus V_s into Δx is equal to 0. So, when we are actually satisfying the continuity equation in the main control volume p , so, the velocities we have written in terms of the face velocity, east, west, north and south.

But you can see that we are evaluating the velocities at the cell centre p or at the cell centres, we have the velocities available, not at the face centre. So, now we need to interpolate the velocity at the face centre and on the uniform grid if you use the linear interpolation, then at East face, U_e , you can write as U_e plus U_p divided by 2.

So, similarly, you can write U_e is equal to U_e plus U_p divided by 2 minus now U_w . So at this west face, you can see U_p plus U_w divided by 2, U_p plus U_w divided by 2 into Δy . Now, you can see V_n minus v_s , so, you can write it as V_n . So here at North face you want to calculate the V_n . So it will be, V_n plus V_p divided by 2 minus at the south face, so V_s will be V_s plus V_p divided by 2.

So it will be V_p plus V_s divided by 2 into Δx is equal to 0. Here it will be x . So now, you see this is U_p by 2 and this is minus U_p by 2. So you are going to get U_e minus U_w Δy by 2 plus, it will be V_n minus V_s into Δx by 2 is equal to 0. So this is the discretized equation for this continuity equation.

Now you can see, where do we need to satisfy the continuity equation? We need to satisfy the continuity equation in the main control volume P and the velocities it should contain at least the velocity at the cell centre p , but while discretizing this continuity equation using finite volume method in the main control volume p on co-located grid, what we got?

We got the velocities from the neighbor cell. So, you can see that when we are satisfying the continuity equation at the cell centre p , the discretized continuity equation does not contain the velocity at cell centre p , rather it contains from the neighbor velocities like U_e , U_w , U_n and U_s .

So, obviously you can see that it is not desirable because when are satisfying the continuity equation it should contain the velocity at pressure, at the main control volume p . So, now to and also similarly if you have the wavy velocity field, similarly if you have wavy velocity field then again what is the problem, let us discuss.

Let us say for the u velocity you have, for u velocity let us have the velocity distribution like this. So, these are the main control volume and these are the face centre. So, if it is p then it is east, this is your west, this is your capital E and this is your capital W . So, this is your wavy velocity field. And you have now let us say similar way you have some velocities here 100, this is your 200 this is your 100, this is your 200 and this is your 100.

So if you want to calculate the velocity as East face, so, you will get 150 and this is also 150. So, you can see this is your U_e is 150 and U_w is on 50 Okay, but when you are actually satisfying the continuity equation, although it satisfied the continuity equation, you can see 150 minus 150 but there is no pressure field exist because in the pressure gradient term, you can see it is becoming 0, right. So, this is not realistic.

So, to overcome this problem, Harlow and Welch, they first propose the staggered grid where the velocities are computed in a staggered manner. So, that already we discussed when we discussed the Mac algorithm, but let us see again.

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Solution of Navier-Stokes Equations using FVM

Harlow and Welch (1965) - MAC : FDM

Mass flow rates across the control volume faces can be calculated without any interpolation for the relevant velocity component.

Two-fold advantages:

- 1) For a typical CV, it is easy to see that the discretized continuity equation would contain the differences of adjacent velocity components.
 - this would prevent a wavy velocity field
- 2) Pressure difference between two adjacent grid points now becomes the natural driving force for the velocity component located between the grid points.

The diagram illustrates a staggered grid. A central square cell is labeled 'Main control volume' and is hatched. It is surrounded by four smaller square cells, each representing a velocity control volume: 'U-control volume' (top), 'V-control volume' (right), 'W-control volume' (bottom), and 'U-control volume' (left). The grid is labeled 'Staggered grid'. A coordinate system with x and y axes is shown in the top right corner.

So, to overcome this problem Harlow and Welch in 1965, they proposed the Mac algorithm for finite difference method where the pressure is computed in the main control volume P and all other scalar but the velocities are computed at the staggered manner.

So at the East face okay of this main control volume, here U is computed and if you consider the North Face, the velocity V is computed or you can do also in other ways. You can compute the velocities U_{ij} at west face or V velocity at the south face. So, you can see this is the main control volume, hatched like this, where you are solving the pressure but velocities U , you are computing in this control volume.

So, in this control volume we are solving and the V control volume is this one. So, here it is the V where you are computing the V_{ij} . So, you can see that the velocities are computed in

staggered ways, and this grid is known as a staggered grid. And using this staggered grid whatever problem we discussed for the co-located grid that can be overcome.

So, mass flow rates across the control volume faces can be calculated without any interpolation for the relevant velocity component. So, whatever problem we face while solving the pressure gradient term for the u momentum equation it contains U_e minus U_w . So, but you see that you are actually calculating U_e in the staggered grid at the face centres.

Similarly, b at the face centres, north and south. While calculating the pressure gradient terms, so, you can directly use the velocities, u and v without the interpolation okay and when you are satisfying the continuity equation for this main control volume p then you can use the U_e minus U_w and U_n minus U_s which actually for the main control volume p .

So, that way you can overcome those problems using staggered grid. So, there are two fold advantages, let us write down. So, for a typical control volume, it is easy to see that the discretized continuity equation would contain the differences of adjacent velocity components.

So, this would prevent a wavy velocity field and pressure difference between two adjacent grid points now becomes the natural driving force for the velocity component located between the grid points. So, you can see that when you are solving the u momentum equation, so, for solving u momentum equation you need the pressure at the face centre of this u control volume.

That means P_e and P_p , but P_e and P_p now it is available at the cell centre of P and E . So that means you do not need an interpolation for pressure as well. Similarly, when you are solving the V momentum equation, you need the pressure at the North face and this main control volume p . So, obviously, these are already available, so you do not need any interpolation and this is the driving force for the velocity V and this is the driving force for velocity U .

So, in today's lecture, we discretized the pressure gradient term of the Navier-Stokes equation using finite volume method and we have shown that if you use co-located grids, there are some problems because you are actually taking the pressure from a faraway grid points. And when we discretize the continuity equation using finite volume method, there also we have seen that the when you are satisfying the continuity equation in the main control volume, it does not contain the velocity of this main control volume.

So, to overcome those problems, you can use staggered grid where the pressure is solved in the main control volume P and the velocities are solved in staggered way. And you can see that when you are solving the u momentum equation, the natural driving force is P_e minus P_p and those pressures are available at East and P point. Similarly for V momentum equation the pressure driving force is P_n minus P_p and those are also available in the main control volume of pressure.

And when you are satisfying the continuity equation in the main control volume, then you need to get the velocities at the faces like U_e minus U_w and V_n minus V_s and those are actually computed in the staggered grid at those face centre. So, that is the advantage but obviously, there are some disadvantage of the staggered grid because we have already discussed while learning the Mac algorithm that you need different indexing for velocities and pressure. Thank you.