

Ordinary and Partial Differential Equations and Applications
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Lecture - 11

Solution of Homogeneous Linear System with Constant Coefficients-III

Hello friends, welcome to my lecture on solution of homogeneous linear system with constant coefficients. We shall discuss the case of equal roots of the characteristic equation in this lecture. So if the characteristic polynomial of a matrix A does not have n distinct roots then A may not have n linearly independent eigen vectors, for example let us consider the matrix $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$.

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Equal roots: If the characteristic polynomial of a matrix A does not have n distinct roots then A may not have n linearly independent eigen vectors.
 For example,

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

has eigen values $\lambda=1,1,2$ and two linearly independent eigen vectors

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Handwritten notes on the slide:

$$(A-I)v = 0$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$v_2 = 0$
 $v_3 = 0$
 Thus $v = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} v_1 \\ 0 \\ 0 \end{bmatrix} = v_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

Then you can see that it is an upper triangular matrix, its diagonal elements are therefore its eigen values so the diagonal elements are 1, 1, 2 and therefore it has eigen values 1, 1, 2 okay. Now corresponding to eigen value $\lambda = 1$ if you find the eigen vector then what you get. $(A - I)v = 0$ so you subtract identity matrix from A and what you get is $\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ and then $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$. So this is v_1, v_2, v_3 and you get $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ here and what you get is okay.

So $v_1 \cdot 0 + v_2 \cdot 1 + v_3 \cdot 0 = 0$ so you get $v_2 = 0$ and then second equation is $0 = 0$, third equation gives you $v_3 = 0$ and thus $v = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$ reduces to $\begin{bmatrix} v_1 \\ 0 \\ 0 \end{bmatrix}$ okay, or we can write it as v_1 times $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, so taking $v_1 = 1$ you have an eigen vector $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ corresponding to eigen value $\lambda = 1$ and for $\lambda = 2$ similarly you can find an eigen vector $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$. So you see here that we do not have 3 linearly independent eigen vectors corresponding to the eigen value.

Eigen values 112 only 2 linearly independent eigen vectors we have so how to find n linearly independent solutions of the vector differential equation $\dot{x} = Ax$ that is the question, okay. So thus if you consider the vector differential equation $\dot{x} = Ax$ it will have only 2 linearly independent solutions of the form $e^{\lambda t}$ corresponding to $\lambda = 1$ we got one vector which is 100.

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Thus, $\dot{x} = Ax$ (1)

has only two linearly independent solutions of the form $e^{\lambda t} v$. Therefore, we need to find a third linearly independent solution.

In general, suppose that the $n \times n$ matrix A has only $k < n$ linearly independent eigen vectors. Then the differential equation (1) has only k linearly independent solutions of the form $e^{\lambda t} v$. Therefore we need to find $(n-k)$ linearly independent solutions.

We know that if $\dot{x} = ax$, where a and x are scalars then $x(t) = e^{at} c$ is a solution of this equation. Analogously, $x(t) = e^{\lambda t} v$ is a solution of the vector differential equation for constant vector v .

Handwritten notes:
 $\frac{dx}{dt} = a \cdot x \Rightarrow \frac{dx}{x} = a dt$
 $\ln x = a t + \ln c$
 $x = c e^{at}$

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So one solution you get and then corresponding to $\lambda = 2$ you got one eigen vector 001, so you get another linearly independent solution of the form $e^{\lambda t} v$. Now therefore we need to find a third linearly independent solution because in order to write the general solution of the vector differential equation $\dot{x} = Ax$ we need to have n linearly independent solutions of this equation.

And here A is the 3×3 matrix so we need 3 linearly independent solutions. Now in general suppose that the $n \times n$ matrix A has only $k < n$ linearly independent eigen vectors then the differential equation $\dot{x} = Ax$ has only k linearly independent solutions of the form $e^{\lambda t} v$. Therefore, we need to find $n - k$ linearly independent solutions in order to write the general solutions of the vector differential equation $\dot{x} = Ax$.

We know that if you take these scalar first order differential equation $\dot{x} = Ax$ where A and x are scalars then $x(t) = c e^{At}$ is the solution of this equation that you can see it easily, you have $\frac{dx}{dt} = Ax$, so that gives you $\frac{dx}{x} = A dt$ and so when you integrate we

get $\ln x = \ln t A \text{ times } At + \text{constant}$ let us take $\ln c$ then you get $x = c$ times you have, so $\ln x = At + \ln c$ so $x = c$ times e to the power At .

So $x = c$ times e to the power At is the solution of this equation. Analogously $x \dot{=} Ax$ for a constant vector v . Let us see how it is the solution of this vector differential equation. First of all let us see the definition of e to the power At .

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e^{At} is defined as

$$e^{At} = I + At + \frac{A^2 t^2}{2!} + \dots + \frac{A^n t^n}{n!} + \dots$$

It can be shown that the infinite series converges for all t and can be differentiated term by term. Since

$$\frac{d}{dt}(e^{At} v) = A e^{At} v = A(e^{At} v)$$

$\Rightarrow e^{At} v$ is a solution of (1) for every constant vector v .

Handwritten notes in red ink:

- $\frac{d}{dt} x = Ax$
- $\frac{d}{dt}(e^{At} v) = A e^{At} v$
- $\frac{d}{dt}(e^{At} v) = \frac{d}{dt} \left[I + At + \frac{A^2 t^2}{2!} + \dots + \frac{A^n t^n}{n!} + \dots \right] v$
- $= \left[A + \frac{A^2 (2t)}{2!} + \dots + \frac{A^n n t^{n-1}}{n!} + \dots \right] v$
- $= A \left[I + At + \frac{A t^2}{2!} + \dots \right] v$

e to the power At where A is $n \times n$ matrix, is defined as $I + At + \frac{A^2 t^2}{2!} + \dots + \frac{A^n t^n}{n!} + \dots$ and so on and A to the power n t to the power $n \times n$ factorial and so on where I is an identity matrix of the same order as A that is I is the identity matrix of order n . Now it can be shown that the infinite series which is giving e to the power At it converges for all t and can be differentiated term by term.

Now if you find d/dt of e to the power $At \times v$ what you get you see d/dt of e to the power $At \times v$ so this is $= d/dt$ of e to the power At means $I + At + \frac{A^2 t^2}{2!} + \dots + \frac{A^n t^n}{n!} + \dots$ A to the power n , t to the power n/n factorial and so on $\times v$ where v is the constant vector. So when we differentiate with respect to t what we get? This is independent of t so this will be 0 .

So we get At when we differentiate this with respect to t we get $A + \frac{A^2 \times 2t}{2!} + \dots + \frac{A^n n t^{n-1}}{n!} + \dots$ okay, or I can write it as $A \times I +$ here we have At then we have A to the power $n-1$, t to the

power $n-1/n-1$ factorial and so on v , okay, so this is e to the power At . So we get $A * e$ to the power $At * v$ that is the derivative of e to the power $At * v$.

So d/dt of e to the power $At * v$ is A times e to the power $At * v$ and since we can write it as e to the power At okay $* Av$ so what we get, we have to write it as this is $A e$ to the power $At * v$. So what we have d/dt of e to the power $At * v$ is $A * e$ to the power $A2 * v$ and therefore our differential equation is $dx/dt = Ax$. So in this if we replace x by e to the power $At * v$ what we get is d/dt of e to the power $At * v = A$ times e to the power $At * v$ that is what we get here.

So e to the power $At * v$ is the solution of the vector differential equation 1 for every constant vector v .

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Remark: $(e^{At})^{-1} = e^{-At}$, $e^{A(t+s)} = e^{At} \cdot e^{As}$
 and $e^{At+Bt} = e^{At} \cdot e^{Bt}$ if $AB = BA$.

Since $(A - \lambda I)(\lambda I) = (\lambda I)(A - \lambda I)$, where λ is constant, we have

$$e^{At} v = e^{(A-\lambda I)t} e^{\lambda t} v.$$

Moreover, $e^{\lambda t} v = e^{\lambda t} v$
 Hence $e^{At} v = e^{(A-\lambda I)t} e^{\lambda t} v$
 $= e^{\lambda t} e^{(A-\lambda I)t} v,$

because $e^{\lambda t}$ is a scalar.

Handwritten notes:
 $(e^{At})^{-1} = e^{-At}$
 $e^{At} = e^{(A-\lambda I)t + \lambda I t} = e^{(A-\lambda I)t} \cdot e^{\lambda I t}$
 $e^{At} e^{-At} = I$
 $e^{At} = [I + At + \frac{A^2 t^2}{2!} + \dots] [I - At + \frac{A^2 t^2}{2!} - \dots]$
 $= I + At + \frac{A^2 t^2}{2!} + \dots - At - A^2 t^2 - \frac{A^3 t^3}{3!} + \dots + \frac{A^2 t^2}{2!} - \frac{A^3 t^3}{3!} + \dots$
 $= I$
 $\lambda A - \lambda I \quad \lambda A - \lambda I$
 $= I + \lambda t + \frac{\lambda^2 t^2}{2!} + \dots = e^{\lambda t} v$

Now we can easily show that e to the power At inverse = e to the power $-At$ and e to the power $At + s = e$ to the power $At * e$ to the power As , e to the power $At + Bt = e$ to the power $At * e$ to the power Bt if $AB = BA$. This we can see very easily. See e to the power $At * e$ to the power $-At$ if you write what we get $I + At + A$ square t square/2 factorial and so on and then we multiply by e to the power $-At$ so on $I - At + A$ square, t square/2 factorial $- A$ cube t cube /3 factorial and so on, okay.

So we multiply by I first so $I + I At + A$ square, t square/2 factorial and so on then $-At$. So we get $-At$ then we multiply $-At$ here so $-A$ square t square then we multiply $-At$ here so $-A$ cube t cube/2 factorial and so on then you multiply by A square t square/2 factorial so you get

A square $t^2/2!$ factorial okay, then A cube $t^3/2!$ factorial and then you multiply by A square t^2 so $A^4 t^4/2!$ factorial square and so on and you get like this.

So $A^2 t^2$ will cancel with $A^2 t^2/2!$ factorial + $A^2 t^2/2!$ factorial is $A^2 t^2$, so it will cancel with $A^2 t^2$. Similarly, $A^3 t^3/3!$ factorial okay $-A^3 t^3/2!$ factorial and then $-A^3 t^3/3!$ factorial so what we will get all the terms will cancel except I and what we get is $e^{At} * e^{-At} = I$. So we can say that e^{At} inverse is e^{-At} .

And similarly if you multiply the series for e^{At} and then the series for e^{Bt} you will get the series for $e^{(A+B)t}$, but here when you multiply $e^{At} * e^{Bt}$ then you need $AB = BA$ in order to get $e^{(A+B)t}$. So $e^{(A+B)t}$ is true only if $AB = BA$, so $e^{(A+B)t}$ is $e^{At} * e^{Bt}$ provided $AB = BA$.

Now let us look at these 2 matrixes $A - \lambda I$ and λI same as λI and $A - \lambda I$ because $A - \lambda I$ is λA okay and then $-\lambda * \lambda$ is $-\lambda^2 I$ so we get $\lambda^2 I$ so lefthand side is this and righthand side is what, $\lambda * I A$ that is $\lambda * A$ and then $\lambda I * \lambda I$ is $-\lambda^2 I$ so $\lambda^2 I$ so lefthand side and righthand side are same.

So $A - \lambda I$ and λI commute, so $A - \lambda I$ and λI commute okay where λI is constant. Now using this property $e^{(A - \lambda I)t} * e^{\lambda I t}$ is $e^{(A - \lambda I)t + \lambda I t}$, okay, $e^{(A - \lambda I)t} = e^{(A - \lambda I)t + \lambda I t}$. Now use this property, $A - \lambda I$ and λI since they commute okay, we can write it as $e^{(A - \lambda I)t} * e^{\lambda I t}$.

So e^{At} can be written as $e^{(A - \lambda I)t} * e^{\lambda I t}$ because $A - \lambda I$ and λI commute and we are using this property $e^{(A - \lambda I)t + \lambda I t} = e^{(A - \lambda I)t} * e^{\lambda I t}$. Now $e^{(A - \lambda I)t} = e^{(A - \lambda I)t + \lambda I t}$ this we can see very easily $e^{(A - \lambda I)t}$.

Let us write $e^{\lambda I t}$ this is equal to we have $I + \lambda I t + \lambda^2 I t^2/2!$ and so on $* e^{\lambda I t}$. So what you get is so this is $v + \lambda I v = v$

and then $\lambda t * v I v = v$ again then $\lambda^2 I^2 t^2$ here okay, so $\lambda^2 t^2 I^2 * v$ is v so $\lambda^2 t^2 / 2!$ * v and so on or I can write it as scalar $1 + \lambda t + \lambda^2 t^2 / 2!$ and so on * v .

Which is $= e$ to the power $\lambda t * v$, okay. So e to the power $\lambda I t * v$ is e to the power $\lambda t * v$ and therefore e to the power $Atv = e$ to the power $A - \lambda I t * e$ to the power $\lambda t * v$. Now e to the power λt is a scalar quantity so we can write it outside this matrix, e to the power $\lambda t * e$ to the power $A - \lambda I t v$ okay. So ultimately what we have e to the power $Atv = e$ to the power $\lambda t * e$ to the power $A - \lambda I t * v$, okay.

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Suppose v satisfies $(A - \lambda I)^m v = 0$, for some integer m then

$$e^{At} v = e^{\lambda t} \left(v + t(A - \lambda I)v + \dots + \frac{t^{m-1} (A - \lambda I)^{m-1} v}{(m-1)!} \right) \checkmark$$

we have $e^{At} v = e^{\lambda t} e^{(A - \lambda I)t} v$

$$= e^{\lambda t} \left[I + (A - \lambda I)t + \frac{(A - \lambda I)^2 t^2}{2!} + \frac{(A - \lambda I)^3 t^3}{3!} + \dots + \frac{t^{m-1} (A - \lambda I)^{m-1}}{(m-1)!} \right] v$$

$$+ \frac{t^m (A - \lambda I)^m}{m!} + \frac{t^{m+1} (A - \lambda I)^{m+1}}{(m+1)!} + \dots$$

$(A - \lambda I)^n v = 0$ for $n \geq m+1$

$$= e^{\lambda t} \left[v + t(A - \lambda I)v + \frac{t^2 (A - \lambda I)^2 v}{2!} + \dots + \frac{t^{m-1} (A - \lambda I)^{m-1} v}{(m-1)!} + \frac{t^m (A - \lambda I)^m v}{m!} \right]$$

Now suppose $(A - \lambda I)^m v = 0$ for some integer m then e to the power $Atv = e$ to the power $\lambda t * v + t$ times $(A - \lambda I)v +$ and so on t to the power $m - 1 (A - \lambda I)^{m-1} v$ and then $m-1$ factorial, this we can see from the previous equation we have e to the power $At * v =$ this okay, so we have e to the power $A - \lambda I t * v$. This is what we have, e to the power $At * v = e$ to the power $\lambda t * e$ to the power $A - \lambda I t * v$ operating on v .

So this equal to e to the power λt and let us write the expansion series for this, so $I + (A - \lambda I)t + (A - \lambda I)^2 t^2 / 2!$ $(A - \lambda I)^3 t^3 / 3!$ factorial and so on, okay, t to the power $m (A - \lambda I)^m v$ upon $m-1$ factorial and then we have t to the power $m (A - \lambda I)^m v$ upon m factorial

and then so on, t to the power $m+1$ $A - \lambda I$ to the power $m+1$ v upon $m+1$ factorial and so on.

So here I should not have written v , v we can write outside here, okay. So then what happens is when this series operates on v , you get $v + t$ times $A - \lambda I * v$ you get e to the power λt $v + t$ times $A - \lambda I$ $v + t^2/2$ factorial $A - \lambda I$ whole square v and so on. We get t to the power $m-1$ $A - \lambda I$ to the power $m-1$ v upon $m-1$ factorial and then we have t to the power m $A - \lambda I$ to the power m v upon m factorial and so on.

Now if v satisfies $A - \lambda I$ $m v = 0$ for some m for some positive integer m then what will happen this term will be 0, t to the power $m * A - \lambda I$ to the power mv/m factorial = 0 and after this we will have t to the power $m+1$ $A - \lambda I$ to the power $m+1v$ upon $m+1$ factorial that term will also be 0 because you can operate on this equation by $A - \lambda I$ so that you get $A - \lambda I$ to the power $m+1$ $v = 0$.

So if $A - \lambda I$ to the power $n * v = 0$ for all $n \geq m+1$, so this $A - \lambda I$ to the power $m * v = 0$ implies this = 0 for all $n \geq m+1$ so this series will then reduce to this series okay. All terms starting with the power of t as m and more will vanish and we will have e to the power λt $v = e$ to the power λt $v + t$ times $A - \lambda I * v$ and so on t to the power $m-1$ $A - \lambda I$ to the power $n-1$ $v/m-1$ factorial.

So there will be only m terms inside the bracket. Now let us see how we can find n linearly independent solutions of the vector differential equation $\dot{x} = Ax$.

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Algorithm for finding n linearly independent solutions of (1):

Thus, in order to find additional solutions we pick an eigen value λ of A and find all vectors v for which $(A - \lambda I)^2 v = 0$ but $(A - \lambda I)v \neq 0$. For each such vector $e^{At} v = e^{\lambda t} e^{(A-\lambda I)t} v = e^{\lambda t} \left[v + t(A - \lambda I)v \right]$ is an additional solution of (1).

We do this for all eigen values λ of A.

If we still do not have enough solutions, then we find all vectors v for which $(A - \lambda I)^3 v = 0$ but $(A - \lambda I)^2 v \neq 0$. for such vector v

$$e^{At} v = e^{\lambda t} \left[v + t(A - \lambda I)v + \frac{t^2}{2!} (A - \lambda I)^2 v \right]$$

is an additional solution of (1).



So in order to find additional solutions suppose we have k solutions in linearly independent solutions in order to find n-k solutions we pick an eigen value λ of A and find all vectors v for which $(A - \lambda I)^2 v = 0$, but $(A - \lambda I)v \neq 0$ okay. So for each such vector $e^{At} v = e^{\lambda t} e^{(A-\lambda I)t} v$ we have seen just now $e^{At} v = e^{\lambda t} \left[v + t(A - \lambda I)v + \frac{t^2}{2!} (A - \lambda I)^2 v \right]$ will reduce to $e^{\lambda t} \left[v + t(A - \lambda I)v \right]$.

Because we are assuming that $(A - \lambda I)^2 v = 0$ so here $m = 2$ and this means that only $v + t(A - \lambda I)v$ will remain inside the bracket all other terms will vanish, So we will have $e^{At} v = e^{\lambda t} \left[v + t(A - \lambda I)v \right]$ this will give us an additional solution of $\dot{x} = Ax$. Now we do this for all eigen values λ of A.

If we still do not have enough solutions that is we do not get all n solution then we find all vectors v for which $(A - \lambda I)^3 v = 0$, but $(A - \lambda I)^2 v \neq 0$. For such vector v , $e^{At} v = e^{\lambda t} \left[v + t(A - \lambda I)v + \frac{t^2}{2!} (A - \lambda I)^2 v \right]$ which will reduce to this okay, so this $e^{\lambda t} \left[v + t(A - \lambda I)v + \frac{t^2}{2!} (A - \lambda I)^2 v \right]$ will give you this expression inside the bracket.

All other terms will vanish so $e^{At} v = e^{\lambda t} \left[v + t(A - \lambda I)v + \frac{t^2}{2!} (A - \lambda I)^2 v \right]$ will give us an additional solution of $\dot{x} = Ax$.

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Proceeding in this manner, we obtain n linearly independent solutions.

Example: Consider

$$\dot{x} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} x$$

$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ = upper triangular matrix
 diagonal elements of A are 1, 1, 2 | The diagonal elements of A are 1, 1, 2

$$(A-I)v = 0$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$v_2 = 0, v_3 = 0$

$$v = \begin{bmatrix} v_1 \\ 0 \\ 0 \end{bmatrix} = v_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$(A-I)^2 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Then the eigen values of A are 1, 1, 2.

Now proceeding in this manner we obtain n linearly independent solutions of the equation $\dot{x} = Ax$. So let us now take an example where $\dot{x} = Ax$ is given, A is a 3 x 3 matrix, so our aim will be to determine 3 linearly independent solutions of this vector differential equation, so here $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$, okay. Let us note that A is an upper triangular matrix so the Eigen values of A are the diagonal elements of A.

The diagonal elements of A are 1, 1, 2 these are the diagonal elements and this is an upper triangular matrix. So the diagonal elements are the eigen values of A okay. The diagonal elements of an upper triangular or lower triangular matrix are its eigen values. The diagonal elements of A are 1, 1, 2 so we have the eigen values of A 1, 1, 2. Now let us find the eigen vector for $\lambda = 1$ so we have to consider $(A-I)v = 0$.

We have this $\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$, let us find $(A-I)v = 0$ so what we will get this will give you $\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ and then $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$. So here you can see $v_2 = 0$ and $v_3 = 0$ so we get the eigen vector v as $v_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ and you can take it as $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ so we get corresponding to eigen value $\lambda = 1$ we get an eigen vector $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.

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Eigen vector for $\lambda = 1$: $(A - I)v = 0$
 $\Rightarrow \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^T$ is an eigen vector for $\lambda = 1$.

then $x^1(t) = e^t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ is a solution of given problem.

To find the other linearly independent solution we find those vectors v for which $(A - \lambda I)^2 v = 0$ such that $(A - \lambda I)v \neq 0$.

$(A - I)^2 v = 0 \Rightarrow \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow v_3 = 0$ So $v = \begin{bmatrix} v_1 \\ v_2 \\ 0 \end{bmatrix}$
 $= v_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + v_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

$x(t) = e^{\lambda t} v$
 $x^1(t) = e^t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
 $(A - I) \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = 0$
 let us take $v = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

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And therefore we can have one solution of the equation $\dot{x} = Ax$ we know that $x(t) = e^{\lambda t} v$ is the solution of $\dot{x} = Ax$ if λ is an eigen value and v is the corresponding eigen vector of the matrix A then $x(t) = e^{\lambda t} v$ is the solution of $\dot{x} = Ax$. So one solution $x(t)$ will be $e^t v$ where $\lambda = 1$ here so e^t and the eigen vector we have taken as $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ so we have 1 solution $e^t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.

Now to find the other linearly independent solution, you know one solution we shall get corresponding to $\lambda = 2$ okay, but corresponding to $\lambda = 1$ we have got only one linearly independent solution so let us find one more solution corresponding to $\lambda = 1$. So what we do is to find the other linearly independent solution. We find those vectors v for which $(A - \lambda I)^2 v = 0$ so that $(A - \lambda I)v \neq 0$ where $\lambda = 1$.

This we are doing for $\lambda = 1$. So what we will do is let us find $(A - \lambda I)^2 v = 0$. $(A - I)^2 v = 0$ gives you if you write $(A - I)^2$ matrix so $(A - I)^2$ will be $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ and you multiply $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$ so what you get when you multiply $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$ here what you get is v_3 . When you multiply $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$ you get v_3 so $v_3 = 0$ and v_1, v_2 are free variables. So $v = v_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + v_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$.

And then $v_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ you multiply $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ so we get 0 and then $v_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ when we multiply we get 0 here and $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ we multiply here we get 0 and here we multiply we get 0. So $(A - I)^2 v = 0$, this is $(A - I)^2 v = 0$ but we need $(A - I)v \neq 0$, so $(A - I)v = v_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + v_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ so let us see what it is. First column is $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, so when you

multiply to the all rows here you will get the first column as 000 and then 100 you multiply so 100 will give 0 here, 100 will give 0 here, 100 will give here again 0.

And 001 you multiply you get 0 here you multiply you get 0 and here you multiply you get 1, okay, so we get this matrix. So $(A - \lambda I)^2 v = 0$ gives you 000, 000, 001 $v_1, v_2, v_3 =$ so what we get $v_3 = 0$ and so $v = v_1, v_2, v_3$. So v_1, v_2 are arbitrary and we get $v_3 = 0$ here, okay, now I can write it as v_1 times 100 + v_2 times 010, so one solution for $(A - \lambda I)^2 v = 0$ can be taken as 100.

The other solution can be taken as 010, but if you take 100 then we have seen $(A - \lambda I) 100 = 0$ because $(A - \lambda I)v = 0$ gives a solution 100, so $(A - \lambda I) 100 = 0$ so this condition will be not valid if we choose 100, so let us choose 010, okay, so let us take solution of $(A - \lambda I)^2 v = 0$ such that $(A - \lambda I)v \neq 0$ as 010, okay.

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Hence

$$v = \begin{bmatrix} v_1 \\ v_2 \\ 0 \end{bmatrix} = v_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + v_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

If we take $v = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^T$ then $(A - \lambda I)v = (A - I)v = 0$. So we take $v = \begin{bmatrix} 0 & 1 & 0 \end{bmatrix}^T$, then $(A - \lambda I)v = (A - I)v \neq 0$.



So we take the solution and yeah this is what I have written $v =$ linear combination of these 2 vectors and if we take this 100 transpose then $(A - \lambda I)v = 0$ so we take 001 transpose and then $(A - \lambda I)v$ which is $(A - \lambda I)v \neq 0$ this you can check $(A - \lambda I)v \neq 0$ if you take v to be 001 vector, okay.


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Thus, $x^2(t) = e^t \begin{bmatrix} t \\ 1 \\ 0 \end{bmatrix}$ is another solution of the given equation.

Eigen vector for $\lambda = 2$: $(A - 2I)v = 0$
Hence $v = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ ✓

Consequently, $x^3(t) = e^{2t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ is the third solution of given problem.

Handwritten derivation:
 $x^2(t) = e^t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = e^t \left[\frac{(A-I)t}{1!} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \frac{(A-I)^2 t^2}{2!} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \dots \right]$
 $= e^t \left[\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t(A-I) \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right] = e^t \left[\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right] = e^t \begin{bmatrix} 0 \\ 1+t \\ 0 \end{bmatrix}$



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Thus $x_2(t) = e^t$ is a solution of the given equation, and then what you have okay, $x_2(t)$ let us find, so $x_2(t)$ we have to find, okay, so in order to find $x_2(t)$ what we have e^t to the power λ that is e^t to the power t * we have taken 010 okay, so 010 now e^t to the power t we can write as e^t to the power t , e^t to the power $A-I$ * t , we have $x_2(t) = e^t$ to the power t * e^t to the power $A-I$ - okay, so this is e^t to the power At .

Because $x_2(t)$ is e^t to the power At * 010 this is a solution of this, so x to the power $A-I$ * t this is e^t to the power t so $I + A - \lambda I$ * 010 also we have to write so $A - \lambda I$ * t and then $A - I$ whole square, this is v here and this is t here, so $t^2 (A - I)^2 / 2!$ factorial v and so on this reduces to e^t to the power t $I + t(A - I) * v$ and here also v , here also v , okay, so what we get, e^t to the power t then we have v is 010 so $010 + t$ times.

So you put the value of $A - I$ here t times $A - I$ * v , $v = 010$, what we get is e^t to the power t times $t10$. So e^t to the power t * $t10$ is another solution of the equation and for $\lambda = 2$ we have the equation $A - 2I v = 0$ if we solve this we will get $v = 001$ transpose, so third solution is $x_3(t) = e^{2t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ so thus we have 3 linearly independent solutions.

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$x^1(t), x^2(t), x^3(t)$ are L.I. because

$$x^1(0) = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^T, x^2(0) = \begin{bmatrix} 0 & 1 & 0 \end{bmatrix}^T, x^3(0) = \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}^T$$

are L.I. vectors in \mathbb{R}^3 .

Hence the general solution is given by

$$x(t) = \begin{bmatrix} (c_1 + c_2 t)e^t \\ c_2 e^t \\ c_3 e^{2t} \end{bmatrix} \checkmark$$

$$x(t) = c_1 x^1(t) + c_2 x^2(t) + c_3 x^3(t)$$

How they are linearly independent see $x_1(t), x_2(t), x_3(t)$ are linearly independent because $x_1(0)$ is 100, $x_2(0)$ is 010 and $x_3(0)$ is 001, you can see, $x_3(0)$ is 001, $x_2(0)$ is 010 and $x_1(0)$ is 100. So these 3 vectors are linearly independent vectors in \mathbb{R}^3 and therefore $x_1(t), x_2(t), x_3(t)$ are linearly independent. Now so the general solution we can write $x(t) = c_1 x_1(t) + c_2 x_2(t) + c_3 x_3(t)$ and when you add the 3 column vectors what you get is this column vector, okay.

So this is the general solution of the given vector differential equation. Now in the case of this initial value problem $\dot{x} = Ax, x(0) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$ you can see that $\lambda = 2$ is an eigen value of A with multiplicity 3.

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Example: Consider the initial value problem

$$\dot{x} = \begin{bmatrix} 2 & 1 & 3 \\ 0 & 2 & -1 \\ 0 & 0 & 2 \end{bmatrix} x, \quad x(0) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$A = \begin{pmatrix} 2 & 1 & 3 \\ 0 & 2 & -1 \\ 0 & 0 & 2 \end{pmatrix}$ = upper triangular matrix
 $(A - \lambda I)^3 = \begin{bmatrix} 0 & 1 & 3 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 3 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$
 $(A - 2I)^2 = \begin{bmatrix} 0 & 1 & 3 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 3 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$
 $(A - 2I) = \begin{bmatrix} 0 & 1 & 3 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$
 $v = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ or $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$
 $(A - 2I)v = 0$
 $v = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$
then $(A - 2I)v \neq 0$
 $(A - 2I)^2 v = 0$
 $(A - 2I)v = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$
 $v_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

Then the eigen value of A is $\lambda = 2$ with multiplicity three.

$A = \begin{bmatrix} 2 & 1 & 3 \\ 0 & 2 & -1 \\ 0 & 0 & 2 \end{bmatrix}$ it is an upper triangular matrix so its eigen values are its diagonal elements and which are 2, 2, 2 so eigen values of A are 2, 2, 2, okay that is $\lambda = 2$ occurs with multiplicity 3.

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Eigen vector for $\lambda=2$: $v = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}^T$

$$x^1(t) = e^{2t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \checkmark$$

Since A has only one linearly independent eigen vector.
 To find the other linearly independent solution we find those vectors v for which $(A - \lambda I)^2 v = 0$ such that $(A - \lambda I)v \neq 0$. $\lambda = 2$

Now consider $(A - 2I)^2 v = 0$, then we find

Handwritten notes:
 $(A - 2I)v = 0 \Rightarrow v = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
 $= e^{2t} [I + (A - 2I)t] \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
 $= e^{2t} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
 $= e^{2t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
 $= e^{2t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = e^{2t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
 $x^2(t) = e^{At} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = e^{2t} e^{(A-2I)t} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

Now eigen vector for $\lambda = 2$ if you find then you will see that $(A - 2I)v = 0$ gives you solution by $v = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, so $e^{2t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ is 1 linearly independent solution of $\dot{x} = Ax$. Since A has only one linearly independent eigen vector we get one solution, to find other linearly independent solution we find those vectors v for which $(A - \lambda I)^2 v = 0$ such that $(A - \lambda I)v \neq 0$, $\lambda = 2$ here.

So now consider $(A - 2I)^2 v = 0$ then we find, so $(A - 2I)$ is this $\begin{bmatrix} 0 & 1 & 3 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$ okay, so $(A - 2I)$ will give you what, $(A - 2I)$ will give you $\begin{bmatrix} 0 & 1 & 3 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$ and when we multiply $\begin{bmatrix} 0 & 1 & 3 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$ what we get. So this will give you $\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ first column is $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ when it is multiplied 2 rows will give you first column as $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ will also give $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ and then $3 \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ is -1 and then $3 \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ will multiply to this.

This is $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$, this is $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$, this is $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ and this is also $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ so what we get $(A - 2I)^2 v = 0$ this is, okay. So $(A - 2I)^2 v = 0$ if you do then what you will get? So we get $v_3 = 0$ that means v_1 and v_2 are arbitrary okay. So v_1 and v_2 are arbitrary means we can take v as $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ or we can take v as $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ okay. Now corresponding to $\lambda = 2$ the one solution that we have got is what $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. So if you choose $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ here then $(A - 2I)v$ will be $= 0$.

Okay, because we have already seen that so let us choose 010 okay, corresponding to lambda A-2I square v = 0 and A-2I v != 0 so if you choose v as 010 then A-2I v will not be = 0 so we can consider this vector okay, and when you do this then what will be x2t, so x2t will be = e to the power At * v, v is 010 we are taking okay, so e to the power 2t and then e to the power A-2t * A-2I t 010 so this gives you what?

E to the power 2t times I + A-2I t and then 010, okay, so we get e to the power 2t 010 okay + A-2I, A-2I is the matrix 013 and then we have 00-1 and then we have 000 * 010 * t, okay so this is what we get. So e to the power 2t 010 and then 010 when you multiply here what you get 010 you multiply so you get 01 here and 010 when you multiply here you get 0, 010 you multiply here you get 0 and you get t here.

So what you get e to the power 2t t10, so one solution is this we have got okay.

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$v = \begin{bmatrix} 0 & 1 & 0 \end{bmatrix}^T$ satisfies $(A - 2I)^2 v = 0$ but $(A - 2I)v \neq 0$.
 then $x^2(t) = e^{2t} \begin{bmatrix} t \\ 1 \\ 0 \end{bmatrix}$. ✓

$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = v_1 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + v_2 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + v_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ ✓

Since $(A - 2I)^2 v = 0$ has only two linearly independent solutions. To find the other linearly independent solution we find those vectors v for which $(A - 2I)^3 v = 0$ such that $(A - 2I)^2 v \neq 0$.

Now consider $(A - 2I)^3 v = 0$, then we find $v = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

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Now so we have x2t = e to the power 2t t10 this is one another solution. Now we have to still get one more solution because A-2I whole square v has given only 2 linearly independent solutions so let us consider A-2I whole cube v = 0. So when you consider A-2I whole cube v = 0 such that A-2I square v is != 0 then A-2I whole cube v = 0 gives you what? A-2I whole square is this.

If you multiply again A-2I what you get 00-1, 000 and 000 and we multiply to this 013 and we multiply 00-1, 000 okay so this is A-lambda I whole cube. So what do you get first column vector is 0 so vector, so we get 0. Second 100 gives you 0 and third 3-10, 3-10 when

you multiply here you get this okay, so $A - \lambda I$ whole cube $v = 0$ okay, $A - 2I$ whole cube $v = 0$ when we do what we get $000, 000, 000$ and then $v_1, v_2, v_3 = 0$.

Okay, so v_1, v_2, v_3 are arbitrary vectors here okay, so now we can consider then v_1, v_2, v_3 is the linear combination of $100, 010$ and 001 , okay, so 100 we already have got 100 vs solution of $A - 2I * v = 0, 010$ we got as a solution of $A - 2I$ whole square $v = 0$ so here we want that vector for which $A - 2I$ whole square v is $\neq 0$ okay, but $A - 2I$ v cube $= 0$ so this we cannot take because for this vector $A - 2I v = 0$.

So $A - 2I$ whole cube v will be $= 0, A$ and $A - 2I$ whole square v will also be 0 and this vector also we cannot take so let us take 001 , so we take here $v = 001$ and for this we then find the solution, third solution $x_3(t) = e^{At} * v$.

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$$\begin{aligned}
 x_3(t) &= e^{At} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \\
 &= e^{2t} e^{(A-2I)t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \\
 &= e^{2t} \left[I + (A-2I)t + \frac{(A-2I)^2}{2!} t^2 \right] \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}
 \end{aligned}$$



So we get 001 and we write it as e^{2t} , $e^{(A-2I)t} * 001$ and then we write $e^{2t} \left[I + (A-2I)t + \frac{(A-2I)^2}{2!} t^2 \right] * 001$ other terms will vanish operating on 001 . So you know the value of the matrix $A - 2I$, you also know $A - 2I$ whole square so substitute here this I is identity matrix when you take this product of these 2 matrixes this matrix $* 001$ what we get is this $x_3(t)$ as $e^{2t} \left[3t - \frac{1}{2} t^3 \right] * 001$.

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$v = \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}^T$ satisfies $(A - 2I)^3 v = 0$ but $(A - 2I)^2 v \neq 0$.

then $x^3(t) = e^{2t} \begin{bmatrix} 3t - \frac{1}{2}t^2 \\ -t \\ 1 \end{bmatrix}$ ✓

$x(t) = c_1 x^1(t) + c_2 x^2(t) + c_3 x^3(t)$
 $\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$
 $= \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} \Rightarrow c_1 = 1$ ✓
 $c_2 = 2$
 $c_3 = 1$

So what we get $x(t)$ now is the linear combination of these 3 linearly independent solutions $x^1(t)$, $x^2(t)$, $x^3(t)$. Now we use the initial condition, the initial condition is $x(0) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$, so when we use $x(0) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$ we will have $c_1 x^1(0) + c_2 x^2(0) + c_3 x^3(0)$, okay, c_1 times. Now $x^1(0)$ is what, you put $t = 0$ here, so we get $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ and here you put $t = 0$ then but you get $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ and here you put $t = 0$ then you get $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$.

So we get $\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$, so what we get is $c_1 c_2 c_3$, so then $c_1 = 1$, $c_2 = 2$, $c_3 = 1$, so put these values of c_1, c_2, c_3 here okay, you get the solution of the initial value problem.

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Hence the solution of the IVP is given by

$$x(t) = e^{2t} \begin{bmatrix} 1 + 5t - \frac{1}{2}t^2 \\ 2 - t \\ 1 \end{bmatrix}$$
 ✓

So the solution of the initial value problem is $x(t) = e^{2t} \begin{bmatrix} 1 + 5t - \frac{1}{2}t^2 \\ 2 - t \\ 1 \end{bmatrix}$, so this is how we solve the homogeneous vector differential equation with constant coefficients in the case where the characteristic equation has equal

roots, so in the next lecture we shall discuss nonhomogeneous vector differential equation with constant coefficient. Thank you very much for your attention.