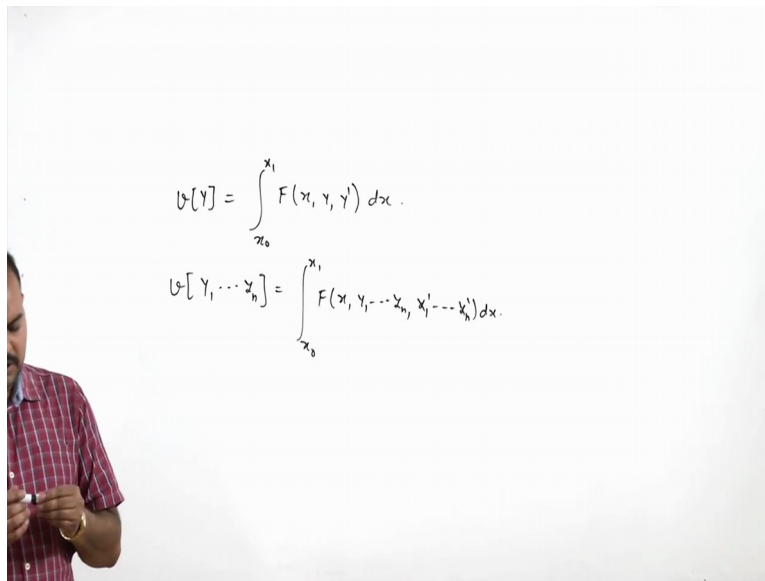


**Integral Equations, Calculus of Variations and their Applications**  
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**Lecture 53**  
**Variational Problem Involving a Conditional Extremum-1**

Hello friends welcome to today's lecture in today's lecture we will discuss the variational problem with the condition extremum.

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$$I[y] = \int_{x_0}^{x_1} F(x, y, y') dx.$$
$$I[y_1, \dots, y_n] = \int_{x_0}^{x_1} F(x, y_1, \dots, y_n, y_1', \dots, y_n') dx.$$

If we recall we have discussed the problem extremum problem for these kind of functional we have  $x$  not say  $x_1$  and we have  $f$  of  $x, y, y'$  and  $d$  of  $x$  or you can say that if we have more than 1 curve say  $y_1$  to  $y_n$  and it is  $x$  not to  $x_1$   $f$  of  $x, y_1$  to say  $y_n$  and  $y_1'$  to say  $y_n'$  and  $d$  of  $x$  provided some boundary condition defined at the point  $x$  not and  $x_1$ . So here these problems are known as unconditional extremum. So today we will discuss that what happen if we put certain condition on these functions these variable  $y$  and say  $y_1$  to  $y_n$ . So that is the today's topic, so let us discuss here.

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Variational problems involving a conditional extremum

Variational problems involving a conditional extremum are problems in which we find an extremum of a functional  $v$  such that certain constraints are imposed on the functions on which the functional  $v$  is dependent. For example, find the extremum of the functional

$$v[y_1, y_2, \dots, y_n] = \int_{x_1}^{x_2} f(x, y_1, y_2, \dots, y_n, y_1', y_2', \dots, y_n') dx$$

with the conditions

$$\phi_i[x, y_1, y_2, \dots, y_n] = 0 \quad (i = 1, 2, \dots, m; m < n).$$

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So we want to discuss here a is the variational problem involving a conditional extremum. So variational problem involving a conditional extremum are problems in which we find an extremum of a functional  $v$  such that the certain constant are imposed on the function on which the function  $v$  is dependent. So here if we consider this functional which is depending on  $y_1$  to  $y_n$  and define an  $x_1$  to  $x_2$   $f$  of  $x, y_1$  to  $y_n, y_1$  dash to  $y_n$  dash  $d$  of  $x$ . And the condition define on this variable  $y_1$  to  $y_n$  are given as  $\phi_i x, y_1$  to  $y_n$  equal to 0 for each  $i$  equal to 1 to  $m$  where  $m$  is some number which is strictly less than  $n$ .

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Recall the solution of a similar problem dealing with the investigation of the function  $z = f(x_1, x_2, \dots, x_n)$  for an extremum with the constraints

$$\phi_i[x_1, x_2, \dots, x_n] = 0 \quad (i = 1, 2, \dots, m; m < n).$$

The natural way is to solve the system

$$\phi_i[x_1, x_2, \dots, x_n] = 0 \quad (i = 1, 2, \dots, m).$$

the equations of which are independent with respect to some kind of  $m$  variables, say  $x_1, x_2, \dots, x_m$ .

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So to discuss this problem let us recall the similar problem and the similar problem is that we try to find out the extremum of the function  $z$  equal to  $f$  of  $x_1$  to  $x_n$  where  $x_1$  to  $x_n$  are

variable here and provided that certain constraints are given  $\phi_i(x_1, \dots, x_n) = 0$  where  $i$  is equal to 1 to  $m$  where  $m$  is strictly less than  $n$ . So this is the simple problem posed in calculus and to find out this problem to find out the extremum of this problem what we try to do here we try to look at this constraints system of constraint and we try to solve this system of constraint in terms of your  $x_1$  to  $x_n$  and try and to put that value of  $x_1$  to  $x_n$  here in the function  $z$  equal to  $f$  of  $x_1$  to  $x_n$  and this by doing this your function  $z$  is now reduced to a new function which is having a independent variable  $x_{m+1}$  to  $x_n$  and we can simply solve the condition of extremum with no constraint.

So how we can do this? Let us proceed here, so the natural way is to solve the system  $\phi_i(x_1, \dots, x_n) = 0$ , where  $i$  equal to 1 to  $m$  the equation of which are independent. So here we are already assuming that these system of a constraints are independent to each other it means that that we can solve this  $\phi_i$   $i$  equal to 1 to  $m$  in terms of  $x_1$  to  $x_m$ . So without laws of generality I am assuming that we can solve these constraints for  $x_1$  to  $x_m$ . So if it is not then we can change the relabel the variable and we can always relabel as  $x_1$  to  $x_m$ .

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$$x_1 = x_1(x_{m+1}, x_{m+2}, \dots, x_n);$$

$$x_2 = x_2(x_{m+1}, x_{m+2}, \dots, x_n);$$

$$\vdots$$

$$x_m = x_m(x_{m+1}, x_{m+2}, \dots, x_n);$$

and with respect to the substitution of  $x_1, x_2, \dots, x_m$  into  $f(x_1, x_2, \dots, x_n)$ . Then the functions  $f(x_1, x_2, \dots, x_n)$  becomes a function  $\phi(x_{m+1}, x_{m+2}, \dots, x_n)$  only of the  $n - m$  variables  $x_{m+1}, x_{m+2}, \dots, x_n$ , which are already independent, and so the problem has reduced to investigating the function  $\phi$  for an unconditional extremum. This approach can also be used to solve the above variational problem.



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So here if  $\phi_i$  are independent we can solve them as  $x_1$  to  $x_m$  as function of  $x_{m+1}$  to  $x_n$  and similarly  $x_{m+1}$  to  $x_n$  as a function of  $x_{m+1}$  to  $x_n$ . So by doing this this function  $f$  of  $x_1$  to  $x_n$  is reduced to a new function  $\phi$  which is depending now on only  $n$  minus  $m$  variable  $x_{m+1}, x_{m+2}, \dots, x_n$ . So now we can say that so the problem has reduced to investigating the function  $\phi$  for an unconditional extremum in the variable  $x_{m+1}$  to  $x_n$ . So we try to apply the same approach to solve the given variational problem.

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Solving the system

$$\phi_i(x, y_1, y_2, \dots, y_n) = 0, \quad (i = 1, 2, \dots, m)$$

for  $y_1, y_2, \dots, y_m$  and substituting their expressions into  $v[y_1, y_2, \dots, y_n]$ , we get the functional  $W[y_{m+1}, y_{m+2}, \dots, y_n]$  which depends only on  $n - m$  arguments that are already independent.

However, both for functions and functionals, we may apply a more convenient method known as method of undetermined coefficients.

For example, if we investigate the extremum of the function  $z = f(x_1, x_2, \dots, x_n)$  with the given constraints

$$\phi_i(x_1, x_2, \dots, x_n) = 0, \quad (i = 1, 2, \dots, m)$$

then using method of undetermined coefficients, we construct a new auxiliary function

$$\bar{z} = f + \sum_{i=1}^m \lambda_i \phi_i$$

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So how we can do that let us see that. So we have a constraint like this  $\phi_i(x, y_1$  to  $y_n$  equal to 0 where  $i$  is equal to running from 1 to  $m$ . So we try to solve this and substitute their expression into  $v$  functional. So we are solving this for  $y_1$  to  $y_m$  and after putting this expression  $y_1$  to  $y_m$  this is functional  $v$  which is depending  $y_1$  to  $y_n$  is now reduced to a new functional  $W$  which is now depending on only on  $y_{m+1}$  to  $y_n$  and so it is depending on now  $n$  minus  $m$  arguments that are already independent.

So this is the classical approach which we apply in calculus and we can apply for functional also. But here in this lecture we try to discuss a new approach or a more convenient approach that is the method of undetermined coefficient. So here to apply the method of undetermined coefficient let us first discuss the case of calculus and then we try to discuss the case for functional.

So here we want to investigate the extremum of the function  $z$  equal to  $f$  of  $x_1$  to  $x_n$  with the constraint  $\phi_i$   $i$  is from 1 to  $m$ . And using method of undetermined coefficient what we try to do here with the help of this function and the constraint we construct a new auxiliary function  $\bar{z}$  which is given as  $f$  plus summation  $i$  equal to 1 to  $m$   $\lambda_i \phi_i$ , where  $\lambda_i$  are some unknown parameters here which is known as undetermined coefficients and we try to find out  $\lambda_i$  in a way such that the extremum of this function satisfying this constraint is satisfying the r extremum of this  $\bar{z}$ .

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where the  $\lambda_i$  are certain constant factors and the function  $\bar{z}$  is now investigated for an unconditional extremum; i. e. we form a systems of equations  $\frac{\partial \bar{z}}{\partial x_j} = 0$  ( $j = 1, 2, \dots, n$ ) supplemented by the constraint equations  $\phi_i = 0$  ( $i = 1, 2, \dots, m$ ) from which all the  $n + m$  unknowns  $x_1, x_2, \dots, x_n$  and  $\lambda_1, \lambda_2, \dots, \lambda_m$  are determined.

Also, the problem involving a conditional extremum for functional is solved in similar fashion, namely if

$$v = \int_{x_0}^{x_1} F(x, y_1, y_2, \dots, y_n, y_1', y_2', \dots, y_n') dx$$

and

$$\phi_i(x, y_1, y_2, \dots, y_n) = 0 \quad (i = 1, 2, \dots, m)$$

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So where the lambda i are certain constant factor and the function z bar is now investigated for an unconditional extremum. So to find out say investigation for z bar for an unconditional extremum we simply say that let us take the partial derivative with respect to (( ))(7:22) and equate it to 0. So here deba z bar with respect to deba x j is equal to 0 where j is 1 to n, supplemented the constraint equation phi i equal to 0 i is from 1 to m.

So it is basically these are n equations and here we have m equations so we have total n plus m unknown n plus m equation which gives you say n plus m unknowns that is x 1 to x n these constraint lambda 1 to lambda m. So this the method known as Lagrange method of undetermined coefficient which we generally apply in calculus. Now we try to apply the similar method for our variational problem, okay.

So here consider this variational x not to x 1 F of x, y 1 to y n, y 1 dash to y n dash d of x and constraints are given as phi i x is depending on y 1 to y n equal to 0 for i equal to 1 to m. Here this small problem here it is phi i x, y 1 to y n equal to 0. So this bracket is here anyway.

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then the functional

$$\bar{v} = \int_{x_0}^{x_1} \left( F + \sum_{i=1}^m \lambda_i(x) \phi_i \right) dx$$


or

$$\bar{v} = \int_{x_0}^{x_1} \bar{F} dx$$

is constructed, where  $\bar{F} = F + \sum_{i=1}^m \lambda_i(x) \phi_i$  which is now investigated for an unconditional extremum, i.e. we solve the system of Euler's equations

$$\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0 \quad (j = 1, 2, \dots, n) \quad (1)$$

with the constraint equations

$$\phi_i = 0 \quad (i = 1, 2, \dots, m)$$



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where the  $\lambda_i$  are certain constant factors and the function  $\bar{z}$  is now investigated for an unconditional extremum; i. e. we form a systems of equations  $\frac{\partial \bar{z}}{\partial x_j} = 0$  ( $j = 1, 2, \dots, n$ ) supplemented by the constraint equations  $\phi_i = 0$  ( $i = 1, 2, \dots, m$ ) from which all the  $n + m$  unknowns  $x_1, x_2, \dots, x_n$  and  $\lambda_1, \lambda_2, \dots, \lambda_m$  are determined.

Also, the problem involving a conditional extremum for functional is solved in similar fashion, namely if

$$v = \int_{x_0}^{x_1} F(x, y_1, y_2, \dots, y_n, y_1', y_2', \dots, y_n') dx$$

and

$$\phi_j(x, y_1, y_2, \dots, y_n) = 0 \quad (j = 1, 2, \dots, m)$$


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Then the functional  $\bar{v}$  which we consider from this original functional along with the this constraint. So we consider this new functional  $\bar{v}$  is defined as  $\int_{x_0}^{x_1} F + \sum_{i=1}^m \lambda_i(x) \phi_i dx$  or if we denote this quantity as  $\bar{F}$  then we can rewrite this as  $\bar{v} = \int_{x_0}^{x_1} \bar{F} dx$ , where  $\bar{F}$  is denoted as  $F + \sum_{i=1}^m \lambda_i(x) \phi_i$ .

Now we investigate this  $\bar{F}$  for unconditional extremum it means that we try to solve the system of Euler's Equation for this functional  $\bar{F}$ . It means that  $\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0$  for each  $j = 1$  to  $n$  with the constraint equation that is  $\phi_i = 0$ ,  $i$  is from  $1$  to  $m$ . So here what we try to show here we try to show that the extremum curves extremum functions of this original function satisfying this constraint  $\phi_i = 0$  is

satisfying the Eulers Equation corresponding to new functional that is F bar, so that we wanted to prove here.

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the number of equations  $m + n$  is sufficient to determine the  $m + n$  unknown functions  $y_1, y_2, \dots, y_n$  and  $\lambda_1, \lambda_2, \dots, \lambda_m$  and the boundary conditions  $y_j(x_0) = y_{j_0}$  and  $y_j(x_1) = y_{j_1}$  ( $j = 1, 2, \dots, n$ ) which must not contradict the constraint equations, and will help to determine the  $2n$  arbitrary constants in the general solution of the system of Euler's equations.

It is obvious that the curves thus found on which a minimum or maximum of the functional  $\bar{v}$  is achieved will also be solutions of the original variational problem.

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then the functional

$$\bar{v} = \int_{x_0}^{x_1} \left( F + \sum_{i=1}^m \lambda_i(x) \phi_i \right) dx$$

or

$$\bar{v} = \int_{x_0}^{x_1} \bar{F} dx$$

is constructed, where  $\bar{F} = F + \sum_{i=1}^m \lambda_i(x) \phi_i$  which is now investigated for an unconditional extremum, i.e. we solve the system of Euler's equations

$$\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0 \quad (j = 1, 2, \dots, n) \quad (1)$$

with the constraint equations

$$\phi_i = 0 \quad (i = 1, 2, \dots, m)$$

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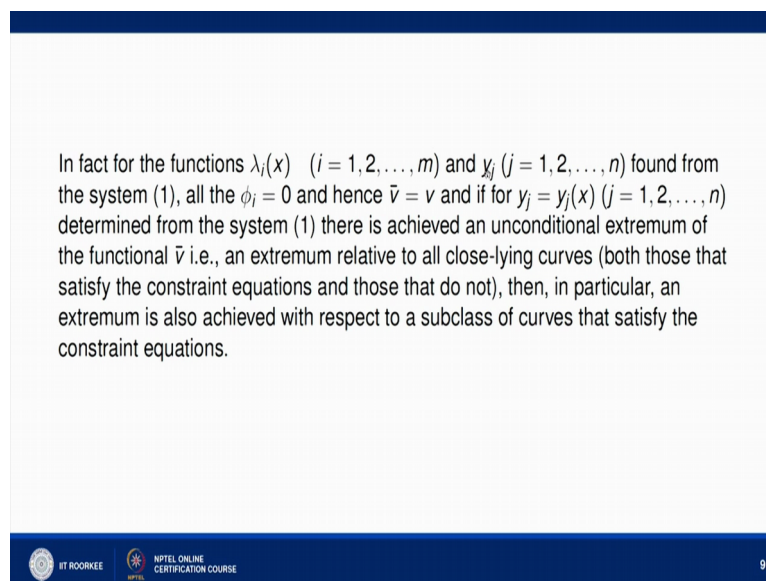
So to proof this we will consider a theorem but before that we here we see that the how many equations we have here we have n equations and here we have m equations given in terms of constraint. So here we have total n plus m equations. So the number of equation m plus n is sufficient to determine the m plus n unknowns that is y 1 to y n and lambda 1 to lambda m and the boundary condition which we which we already know at the point of say boundary point say x not and x 1 which is defined as y j x not equal to y j not and y j x 1 equal to y j 1 of course which must not contradict the constraint equation and will help to determine the 2n arbitrary constants in the general solution of the system of Eulers Equation.

It means that when you solve this system of Euler's Equation you will have generally a second order differential equation and when you solve this you have  $2n$  arbitrary constants which we try to fix with the help of boundary conditions. So now here we try to observe that it is obvious that the curves thus found on which a minimum or maximum of the functional  $\bar{V}$  is achieved will also be the solution of the original variational problem.

It means that what we are trying to do here we are considering the functional along with variational problem along with some constants. So it means that we are considering the variational problem with conditional extremum, what we try to do here with the help of method of undetermined coefficient? We try to convert this to a problem of say finding the unconditional extremum of a new functional say a new variational problem that we wanted to prove the equivalence of these two not equivalence of these two in fact we want to show.

So it is obvious that the curves thus found on which a minimum or maximum of the functional  $\bar{v}$  is achieved will also be solution of the original variational problem, how lwt us see this?

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In fact for the functions  $\lambda_i(x)$  ( $i = 1, 2, \dots, m$ ) and  $y_j$  ( $j = 1, 2, \dots, n$ ) found from the system (1), all the  $\phi_i = 0$  and hence  $\bar{v} = v$  and if for  $y_j = y_j(x)$  ( $j = 1, 2, \dots, n$ ) determined from the system (1) there is achieved an unconditional extremum of the functional  $\bar{v}$  i.e., an extremum relative to all close-lying curves (both those that satisfy the constraint equations and those that do not), then, in particular, an extremum is also achieved with respect to a subclass of curves that satisfy the constraint equations.

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then the functional

$$\bar{v} = \int_{x_0}^{x_1} \left( F + \sum_{i=1}^m \lambda_i(x) \phi_i \right) dx$$

or

$$\bar{v} = \int_{x_0}^{x_1} \bar{F} dx$$

is constructed, where  $\bar{F} = F + \sum_{i=1}^m \lambda_i(x) \phi_i$  which is now investigated for an unconditional extremum, i.e. we solve the system of Euler's equations

$$\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0 \quad (j = 1, 2, \dots, n) \quad (1)$$

with the constraint equations

$$\phi_i = 0 \quad (i = 1, 2, \dots, m)$$



In fact the function lambda i x and y j found from the system 1, system 1 is this let me system 1 is this basically it is system of Eulers Equation along with the constraint equation. So this will give you say lambda i and y i. So claim is that the functions lambda i and y j found from the system 1 all the phi i are 0 and if we take phi i are all 0 then v bar is reduced to v, basically v bar is basically what look at here v bar is defined as F plus summation i equal to 1 to m lambda i x phi i, so if phi i are all 0 then v bar is reduced to x not to x 1 F dx which is nothing but v.

So it means that for these functions lambda i and y j your v bar is reduced to v and if for y j, j is from 1 to n determined from the system 1 if we can have a unconditional extremum of the functional v bar it means that extremum related to all close-lying curves means all all curves satisfying the boundary condition they may not satisfy the constraint equation or they may satisfy the constraint equation then in particular an extremum is also achieved with respect to a subclass of curves that satisfy the constraint equation.

So it means that if we solve the system 1 and we can get a lambda i and y j and if y j say extremize the functional v bar then this v bar is reduced to v with this choice and we can say that the extremum extremal curve y j will also be extremal curve for v because if extremum is achieved for v bar which is on the class of all close-lying curves satisfy the constraint equation or may not satisfy the constraint equation then in particular it will then in particular an extremum is also achieved with respect to a subclass of curves that satisfy the constraint equation.

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**Theorem:** Given the conditions

$$\phi_i(x, y_1, y_2, \dots, y_n) = 0 \quad (i = 1, 2, \dots, m; m < n)$$

the functions  $y_1, y_2, \dots, y_n$  that extremize the functional

$$v = \int_{x_0}^{x_1} F(x, y_1, y_2, \dots, y_n, y_1', y_2', \dots, y_n') dx$$

satisfy the Euler's equations formed for the functional

$$\bar{v} = \int_{x_0}^{x_1} \left( F + \sum_{i=1}^m \lambda_i(x) \phi_i \right) dx = \int_{x_0}^{x_1} \bar{F} dx.$$

for given an appropriate choice of factors  $\lambda_i(x)$  ( $i = 1, 2, \dots, m$ ).



The functions  $\lambda_i(x)$  and  $y_j(x)$  are determined from Euler's equations

$$\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0 \quad (j = 1, 2, \dots, n)$$

and

$$\phi_i = 0 \quad (i = 1, 2, \dots, m)$$

The equations  $\phi_i(x, y_1, y_2, \dots, y_n) = 0$   $i = 1, 2, \dots, m$ , are assumed to be independent, i.e. one of the Jacobians of order  $m$  is different from zero,

$$\frac{D(\phi_1, \phi_2, \dots, \phi_m)}{D(y_1, y_2, \dots, y_m)} \neq 0.$$



So let us try to prove the just said statement. So here we say that given the condition  $\phi_i(x, y_1, y_2, \dots, y_n) = 0$ , where  $i$  is running from 1 to  $m$ ,  $m$  is strictly less than  $n$ . The functions  $y_1, y_2, \dots, y_n$  that extremizes the functional  $v$ , so this is the original functional  $v$  defined  $x$  not to  $x_1$   $F$  of  $x, y_1$  to  $y_n, y_1$  dash to  $y_n$  dash  $d$  of  $x$ . Then these these extremal function  $y_1$  to  $y_n$  satisfy the Eulers Equation formed for the functional  $v$  bar. So  $v$  bar is defined as  $x$  not to  $x_1$   $F$  plus  $i$  equal to 1 to  $m$   $\lambda_i(x) \phi_i$   $d$  of  $x$ , we can denote this  $F$  as  $\bar{F}$  bar  $dx$ . For given an appropriate choice of factors  $\lambda_i(x)$ ,  $i$  is from 1 to  $m$ .

So and here the factors  $\lambda_i(x)$  and these extremal curves functions  $y_1$  to  $y_n$  can be obtained by the Eulers Equation  $\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0$  for  $j$  equal to 1 to  $n$  and  $\phi_i = 0$  for  $i$  equal to 1 to  $m$ . In fact if we can consider this  $\bar{F}$  bar

which is defined as  $F$  plus  $i$  equal to 1 to  $m$   $\lambda_i \times \phi_i$  as a function of not only  $y_1$  to  $y_n$  but also a function of  $\lambda_1$  to  $\lambda_m$  then this system of  $m$  equation can be cooperated with the Eulers Equation in fact these set of equation is obtained by assuming that  $F$  bar is depending only on say  $y_1$  to  $y_n$ .

But if we assume that  $F$  bar is also depending on  $\lambda_1$  to  $\lambda_m$  then this equation can also be considered as part of Eulers Equation or otherwise you can simply write down that we have a that  $\lambda_i$  and  $y_i$  can be obtained by this Eulers Equation and the subsidiary equation  $\phi_i$  from  $i$  equal to 1 to  $m$ . So and this we can do the equation  $\phi_i$  from  $x, y_1$  to  $y_n$  equal to 0,  $i$  equal to 1 to  $m$  are assumed to be independent.

So here we assume that the constraints are independent constraint, so it means that none of the constraint can be written as in a combination of others. It means that this can be rewrite in the form of Jacobians we can say that Jacobian of  $\phi_1$  to  $\phi_m$  with respect to some variable  $y_1$  to  $y_m$  is not equal to 0. So here we are renumbering the variables such that we can assume like this, so without loss of generality I am assuming that the Jacobian of  $\phi_1$  to  $\phi_m$  with respect to  $y_1$  to  $y_m$  is non-zero.

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**Proof:** In this case, the condition for extremum  $\delta v = 0$  takes the form

$$\int_{x_0}^{x_1} \sum_{j=1}^n (F_{y_j} \delta y_j + F_{y_j'} \delta y_j') dx = 0.$$

On integration by parts and denoting  $(\delta y_j)' = \delta y_j'$  and  $(\delta y_j)_{x=x_0} = 0, (\delta y_j)_{x=x_1} = 0$ , we get

$$\int_{x_0}^{x_1} \sum_{j=1}^n \left( F_{y_j} - \frac{d}{dx} F_{y_j'} \right) \delta y_j dx = 0.$$

Since the functions  $y_1, y_2, \dots, y_n$  are subject to  $m$  independent constraints

$$\phi_i(x, y_1, y_2, \dots, y_n) = 0 \quad (i = 1, 2, \dots, m).$$



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So let us come to the proof here so in this case the condition for extremum  $\delta v$  equal to 0 takes the form  $\int_{x_0}^{x_1} \sum_{j=1}^n (F_{y_j} \delta y_j + F_{y_j'} \delta y_j') dx = 0$  and we try to handle this part so here we use integration by parts and denoting  $\delta y_j' = \delta y_j'$  and  $\delta y_j$  at  $x = x_0$  is equal to 0 and  $\delta y_j$

$x$  equal to  $x_1$  it equal to 0. So here we are assuming that these functionals are satisfying the boundary conditions, so these are obvious from that fact.

So here we can simplify this and we can write  $x$  not to  $x_1$ ,  $j$  equal to 1 to  $n$   $F$  of  $y_j$  minus  $d$  by  $dx$  of  $F$  of  $y_j$  dash  $\delta y_j$   $d$  of  $x$  equal to 0. So here if you recall the proof of the Eulers Equation their we have the similar kind of equation and we say that since  $\delta y_j$  are say arbitrary then we can keep this summation has to be 0. But here we cannot consider right now as  $\delta y_j$  are completely arbitrary because they are related by the the constraint  $\phi_i(x)$  from 1 to  $n$  equal to 0 for  $i$  equal to 1 to  $m$ . So here we cannot apply the fundamental lambda here to obtain the Eulers Equation for this.

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It follows that the variations  $\delta y_j$  are not arbitrary and the fundamental lemma cannot be applied in the present form. The variations  $\delta y_j$  must satisfy the following conditions obtained by means of varying the constraint equations  $\phi_i = 0$

$$\sum_{j=1}^n \frac{\partial \phi_i}{\partial y_j} \delta y_j = 0, \quad (i = 1, 2, \dots, m)$$

and, hence, only  $n - m$  of the variations  $\delta y_j$  may be considered arbitrary. Multiplying each of these equations term by term by  $\lambda_i(x)dx$  and integrating from  $x_0$  to  $x_1$ , we get

$$\int_{x_0}^{x_1} \lambda_i(x) \sum_{j=1}^n \frac{\partial \phi_i}{\partial y_j} \delta y_j dx = 0 \quad i = 1, 2, \dots, m.$$

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So here we can say that it follows that the variational  $\delta y_j$  are not arbitrary and the fundamental lambda cannot be apply in the present form. So the variation  $\delta y_j$  must satisfy the following condition obtained by means of varying the constraint equation  $\phi_i$  equal to 0. So when you discuss  $\phi_i = 0$  then it is reduced to this equation  $j$  equal to 1 to  $n$   $\frac{\partial \phi_i}{\partial y_j} \delta y_j$  equal to 0.

So here this  $\delta y_j$  satisfying these  $m$  equation and hence we cannot we can say that all  $\delta y_j$  are not arbitrary. So but here we have  $m$  equations so we can say that only  $n$  minus  $m$  of the variation  $\delta y_j$  may be considered arbitrary. So what we try to do here we multiply these equation by say  $\lambda_j$  and integrate from  $x_0$  to  $x_1$  we get this integral  $\int_{x_0}^{x_1} \lambda_j(x) \sum_{j=1}^n \frac{\partial \phi_i}{\partial y_j} \delta y_j dx = 0$ ,  $i$  equal to 1 to  $m$ .

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Adding termwise all these  $m$  equations, which are satisfied by the permissible variations  $\delta y_j$ , with the equation

$$\int_{x_0}^{x_1} \sum_{j=1}^n \left( F_{y_j} - \frac{d}{dx} F_{y_j'} \right) \delta y_j dx = 0$$

we will have

$$\int_{x_0}^{x_1} \sum_{j=1}^n \left[ \frac{\partial F}{\partial y_j} + \lambda_i(x) \frac{\partial \phi_i}{\partial y_j} - \frac{d}{dx} \frac{\partial F}{\partial y_j'} \right] \delta y_j dx = 0$$

or, if we introduce the notation

$$\bar{F} = F + \sum_{i=1}^m \lambda_i(x) \phi_i,$$



It follows that the variations  $\delta y_j$  are not arbitrary and the fundamental lemma cannot be applied in the present form. The variations  $\delta y_j$  must satisfy the following conditions obtained by means of varying the constraint equations  $\phi_i = 0$

$$\sum_{j=1}^n \frac{\partial \phi_i}{\partial y_j} \delta y_j = 0, \quad (i = 1, 2, \dots, m)$$

and, hence, only  $n - m$  of the variations  $\delta y_j$  may be considered arbitrary.

Multiplying each of these equations term by term by  $\lambda_i(x) dx$  and integrating from  $x_0$  to  $x_1$ , we get

$$\int_{x_0}^{x_1} \lambda_i(x) \sum_{j=1}^n \frac{\partial \phi_i}{\partial y_j} \delta y_j dx = 0 \quad i = 1, 2, \dots, m.$$



So here adding term wise all these  $m$  equations, which are satisfied by the permissible variation  $\delta y_j$  with the equation  $\int_{x_0}^{x_1} \sum_{j=1}^n \left( F_{y_j} - \frac{d}{dx} F_{y_j'} \right) \delta y_j dx = 0$ . So this we obtain by taking  $\delta v$  equal to 0. Now we have this equation which we multiply by  $\lambda_j$  and we are getting this we have new integral that is  $\int_{x_0}^{x_1} \sum_{j=1}^n \left[ \frac{\partial F}{\partial y_j} + \lambda_i(x) \frac{\partial \phi_i}{\partial y_j} - \frac{d}{dx} \frac{\partial F}{\partial y_j'} \right] \delta y_j dx = 0$  here. So here we introduce a new notation that is  $\bar{F}$  which is written as  $F + \sum_{i=1}^m \lambda_i(x) \phi_i$ .

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we get

$$\int_{x_0}^{x_1} \sum_{j=1}^n \left( \bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} \right) \delta y_j dx = 0.$$

Now, choose  $m$  factors  $\lambda_1(x), \lambda_2(x), \dots, \lambda_m(x)$ , so that they should satisfy the  $m$  equations

$$\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0 \quad j = 1, 2, \dots, m,$$

or

$$\frac{\partial F}{\partial y_j} + \sum_{i=1}^m \lambda_i(x) \frac{\partial \phi_i}{\partial y_j} - \frac{d}{dx} \frac{\partial F}{\partial y_j'} = 0 \quad j = 1, 2, \dots, m$$

These equations form a system that is linear in  $\lambda_i$  with a nonzero determinant

$$\frac{D(\phi_1, \phi_2, \dots, \phi_m)}{D(y_1, y_2, \dots, y_m)} \neq 0.$$

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Adding termwise all these  $m$  equations, which are satisfied by the permissible variations  $\delta y_j$ , with the equation

$$\int_{x_0}^{x_1} \sum_{j=1}^n \left( F_{y_j} - \frac{d}{dx} F_{y_j'} \right) \delta y_j dx = 0$$

we will have

$$\int_{x_0}^{x_1} \sum_{j=1}^n \left[ \frac{\partial F}{\partial y_j} + \sum_{i=1}^m \lambda_i(x) \frac{\partial \phi_i}{\partial y_j} - \frac{d}{dx} \frac{\partial F}{\partial y_j'} \right] \delta y_j dx = 0$$

or, if we introduce the notation

$$\bar{F} = F + \sum_{i=1}^m \lambda_i(x) \phi_i,$$

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So if we take this new notation that is F bar we can rewrite this condition into this form  $\int_{x_0}^{x_1} \sum_{j=1}^n (\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'}) \delta y_j dx = 0$ . So here in this this can be rewritten in terms of F bar as follows. So here we have incorporated our constraint as well as the condition that  $\delta v = 0$  into this integral that  $\int_{x_0}^{x_1} \sum_{j=1}^n (\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'}) \delta y_j dx = 0$ .

Now still we cannot apply the fundamental lemma because  $\delta y_j$  are not arbitrary so for this we have taken the factors  $\lambda_1$  to  $\lambda_m$  completely arbitrary but now let us assign some values of  $\lambda_1$  to  $\lambda_m$  so that this equation so  $\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0$  for  $j = 1$  to  $m$ . So we try to find out  $\lambda_1$  to  $\lambda_m$  such that these  $m$  equations is true and what is this if you simplify this if you

look at this is nothing but  $\delta F$  by  $\delta y_j$  plus summation  $i$  equal to 1 to  $m$   $\lambda_i \delta \phi_i$  by  $\delta y_j$  minus  $dF$  by  $dx$   $\delta y_j$  dash equal to 0.

If you look at this linear equation system of linear equation in terms of  $\lambda_i$  and we can find out the solution here solution of this system of linear equation in terms of  $\lambda_i$  because the coefficient matrix if you look at  $\delta \phi_i$  by  $\delta y_j$  this has a nonzero determinant because we have assumed that these  $\phi_i$  are independent constraint. So keeping this thing in mind we can always find out such factors  $\lambda_1$  to  $\lambda_m$  such that these equations are true for  $j$  equal to 1 to  $m$ . So if we have this equations true for  $j$  equal to 1 to  $m$  putting it into this equation.

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Hence, this system has the solution  $\lambda_1(x), \lambda_2(x), \dots, \lambda_m(x)$ . Given this choice of  $\lambda_1(x), \lambda_2(x), \dots, \lambda_m(x)$ , the basic necessary condition for an extremum

$$\int_{x_0}^{x_1} \sum_{j=1}^n \left( \bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} \right) \delta y_j dx = 0$$

takes the form

$$\int_{x_0}^{x_1} \sum_{j=m+1}^n \left( \bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} \right) \delta y_j dx = 0$$

Now, for the extremizing functions  $y_1, y_2, \dots, y_n$  of the functional  $v$ , this functional equation reduces to an identity for an arbitrary choice of  $\delta y_j, j = m + 1, \dots, n$ , it follows that the fundamental lemma is now applicable.

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We can have that we have this  $x$  not to  $x_1$ . Now summation is reduced to  $j$  equal to  $m + 1$  to  $n$  initially it is from 1 to  $n$  now it is reduced to  $m + 1$  to  $n$   $\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} \delta y_j dx$  equal to 0. So now this  $\delta y_j$  are arbitrary in some sense so we can say that for the extremizing function  $y_1$  to  $y_n$  of the function  $v$ , this functional equation reduce to an identity for an arbitrary choice of  $\delta y_j, j$  equal to  $m + 1$  to  $n$ . So now we try to apply the fundamental lemma, so what how we can apply by taking say all the variation as 0 except one.

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Putting all the  $\delta y_j$  equal to zero in turn, except one, and applying the lemma, we obtain

$$\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0 \quad j = m+1, \dots, n.$$

Taking into account the above obtained equations

$$\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0 \quad j = 1, \dots, m.$$

Finally, we find that the functions which achieve a conditional extremum of the functional  $v$ , and the factors  $\lambda_i(x)$  must satisfy the system of equations

$$\begin{aligned} \bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} &= 0 \quad j = 1, \dots, n \\ \phi_i(x, y_1, \dots, y_n) &= 0 \quad i = 1, \dots, m. \end{aligned}$$



we get

$$\int_{x_0}^{x_1} \sum_{j=1}^n \left( \bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} \right) \delta y_j dx = 0.$$

Now, choose  $m$  factors  $\lambda_1(x), \lambda_2(x), \dots, \lambda_m(x)$ , so that they should satisfy the  $m$  equations

$$\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0 \quad j = 1, 2, \dots, m,$$

or

$$\frac{\partial F}{\partial y_j} + \sum_{i=1}^m \lambda_i(x) \frac{\partial \phi_i}{\partial y_j} - \frac{d}{dx} \frac{\partial F}{\partial y_j'} = 0 \quad j = 1, 2, \dots, m$$

These equations form a system that is linear in  $\lambda_j$  with a nonzero determinant

$$\frac{D(\phi_1, \phi_2, \dots, \phi_m)}{D(y_1, y_2, \dots, y_m)} \neq 0.$$



So let us say that putting all the delta  $y_j$  equal to 0 in turn, except one, and applying the fundamental lemma we obtain this  $\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0$  for each  $j$  equal to  $m+1$  to  $n$  and if we so here we have  $n-m$  equation and if we remember we have these  $m$  equation which we have obtained by choosing the values of these factors  $\lambda_1$  to  $\lambda_m$ .

So this along with these  $n-m$  equation we can rewrite a set of equation as this that taking into account the above obtained equation we have  $\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0$  for each  $j$  equal to  $1$  to  $m$ , so  $1$  to  $m$  is earlier one and this  $m+1$  to  $n$  we have this equation  $\bar{F}_{y_j} - \frac{d}{dx} \bar{F}_{y_j'} = 0$  for each  $j$  equal to now



1 to n. So 1 to m is obtained by choosing lambda 1 to lambda m and this m plus 1 to n obtained by applying the fundamental lemma.

So we have now n such equation given here and m set of equation given by the constraint. So we have total n plus m equation and this n plus m equation we can find out the function y 1 to y n and the function lambda 1 to lambda m.

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**Example**

Find the shortest distance between two points  $A(x_0, y_0, z_0)$  and  $B(x_1, y_1, z_1)$  on the surface  $\phi(x, y, z) = 0$ .  
 The distance between two points on a surface is given by the formula

$$I = \int_{x_0}^{x_1} \sqrt{1 + y'^2 + z'^2} dx.$$

We will find the minimum of  $I$  provided  $\phi(x, y, z) = 0$ . Consider the auxiliary functional

$$\bar{I} = \int_{x_0}^{x_1} [\sqrt{1 + y'^2 + z'^2} + \lambda(x)\phi(x, y, z)] dx.$$



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So let us consider one example here and the example is that find the shortest distance between points A and B where the coordinates of A as x not, y not, z not and coordinates of B are x 1, y 1, z 1 on the surface phi of x, comma y, comma z equal to 0. So here shortest distance so the formula of distance is given here I as x not to x 1 under root 1 plus y dash square plus z dash square d of x.



And the condition that these two point lie on phi of x, comma y, comma z equal to 0 and we are measuring the distance only on this surface. So this is the condition we have to consider and now this we can solve by the theorem given just now. So here consider the auxiliary function I bar equal to x not to x 1 under root 1 plus y dash square plus z dash square plus lambda x phi of x, comma y, comma z dx. So here we have only one subsidiary equation or one condition so we consider only one function lambda x like this. Now here if we assume this as a new functional F bar then we can write down the Eulers Equation for this F bar.

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and the corresponding Euler equations

$$\lambda(x)\phi_y - \frac{d}{dx} \frac{y'}{\sqrt{1+y'^2+z'^2}} = 0,$$
$$\lambda(x)\phi_z - \frac{d}{dx} \frac{z'}{\sqrt{1+y'^2+z'^2}} = 0,$$
$$\phi(x, y, z) = 0.$$

From these three equations we determine the desired functions  $y = y(x)$  and  $z = z(x)$  on which a conditional minimum of the functional  $v$  can be achieved, and the factor  $\lambda(x)$ .



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And we can say that the corresponding Euler's equations are reduced to  $\lambda(x)\phi_y - \frac{d}{dx} \frac{y'}{\sqrt{1+y'^2+z'^2}} = 0$ . Similarly corresponding to  $z$ ,  $\lambda(x)\phi_z - \frac{d}{dx} \frac{z'}{\sqrt{1+y'^2+z'^2}} = 0$  and the condition that is  $\phi(x, y, z) = 0$ . So from these three equations we can find out the function  $y = y(x)$  and  $z = z(x)$  on which the conditional minimum of the functional can be achieved and we can also find out the function  $\lambda(x)$  from these three equations.

So here we have applied our theorem to find out the extremum of this functional in this variational problem  $I = \int_{x_0}^{x_1} \sqrt{1+y'^2+z'^2} dx$  provided the condition  $\phi(x, y, z) = 0$ .

So here we stop and in next class we will discuss when the condition is not a finite equation but it is a differential equation in place of this finite equation. So in next class we will discuss the similar kind of problem but the conditions are replaced by differential equations rather than this finite equation and consider and we will also consider certain applications of this said theory, okay so thank you for listening to us we will meet in next lecture, thank you.