

**Course on Integral Equations, Calculus of Variations and their Applications**  
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**Lecture 19**  
**Fredholm alternative Theorem - 2**

Hello friends, let us continue our discussion for Fredholm integral equation of second kind when kernel is given as separable kernel.

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The image shows handwritten mathematical derivations for Fredholm integral equations with separable kernels. The equations are as follows:

$$y(x) = f(x) + \lambda \int_a^b K(x,t) y(t) dt$$

$$y(x) = f(x) + \lambda \int_a^b \overline{K(x,t;\lambda)} f(t) dt$$

$$\overline{K(x,t;\lambda)} = \frac{D(x,t;\lambda)}{D(\lambda)}, \quad D(\lambda) \neq 0$$

$$D(\lambda) = 0$$

$$y(x) = f(x) + \lambda \int_a^b K^*(t,x) y(t) dt \Rightarrow \int_a^b g(x) K^*(x) dx = \int_a^b \int_a^b K(x,t) y(t) dt dx$$

$$y(x) = \lambda \int_a^b K^*(t,x) y(t) dt = \lambda \int_a^b K^*(x) \int_a^b K(x,t) g(t) dt dx$$

So there we have seen that if the determinant of the coefficient matrix denoted as  $D(\lambda)$  is non-zero then the equation  $y(x) = f(x) + \lambda \int_a^b K(x,t) y(t) dt$  has a unique solution and it is given as  $y(x) = f(x) + \lambda \int_a^b \overline{K(x,t;\lambda)} f(t) dt$  where  $\overline{K(x,t;\lambda)}$  is given as  $\frac{D(x,t;\lambda)}{D(\lambda)}$  and  $D(\lambda)$  is the coefficient matrix here.

And here we have assumed that  $D(\lambda)$  is non-zero. Now the problem is that if  $D(\lambda) = 0$  then this value of  $\lambda$  happens to be the root of this coefficient matrix  $D(\lambda)$  then this solution is not defined then we have to find out say conditions on  $f$  such that we may have solution. So in general we do not have any solution of this, right? But there are certain conditions when this  $f$  is having certain feature for which we have still have a solution of this particular problem.

So in case of  $\lambda = 0$  to find out the solution we consider the transpose equation of the original equation the given equation, so how we define transpose equation? We define transpose equation like this  $y(x) = f(x) + \lambda \int_a^b K(x,t) y(t) dt$  here  $K^*$  is the conjugate transpose of  $K(x,t)$ . So here this is the known as transpose equation or some time people call it adjoint equation of the first one.

So here we say that we try to find out the condition so here before starting with anything we try to discuss certain properties here, so first property we want to discuss is that the eigen function corresponding to distinct eigen values of transpose equation and the given equation are orthogonal to each other means what that suppose we have a eigen value like here let me write it here that use some other notation let me write it say here we write it say  $g(x) = \lambda \int_a^b K(x,t) g(t) dt$  and here we have  $K(x,t)$  and let me use this  $K(x,t)$ .

So here we have  $g(x) = \lambda \int_a^b K(x,t) g(t) dt$ , so this implies what? That  $g$  is the eigen function of the equation of this Fredholm integral equation corresponding to  $\lambda$  and let us say that we have  $h(x) = \lambda \int_a^b K^*(x,t) h(t) dt$  and we here we have a transpose of this  $K^*(x,t) = \overline{K(t,x)}$ . Now my claim is that this  $g$  and  $h$  which is eigen function corresponding to  $\lambda$  of the problem and  $h$  is the eigen function corresponding to  $\lambda$ , here  $\lambda$  is non-equal to  $\lambda$  and eigen function of the transpose equation.

And we are claiming that this  $g(x)$  and  $h(x)$  is orthogonal to each other, what do you mean by this? It means that  $\int_a^b g(x) \overline{h(x)} dx = 0$ , so this we want to prove. So to prove this what we do here we simply multiply by  $\overline{h(x)}$  here and integrate and we do the same thing here. So what you will get here let me write it here so here we have  $\int_a^b g(x) \overline{h(x)} dx = \lambda \int_a^b \int_a^b K(x,t) g(t) \overline{h(x)} dx dt$  and here I am writing a to b and this is what I am writing this, okay so here it is what multiplying this as  $\overline{h(x)}$  let me write  $\overline{h(x)}$  here and then  $dx$ , right?

So now this I can write it here  $\int_a^b \int_a^b K(x,t) g(t) \overline{h(x)} dx dt = \lambda \int_a^b \int_a^b K(x,t) \overline{h(x)} g(t) dx dt$  and  $dx$ . Now here we want to find out say expression of this so here we can find out  $\int_a^b \int_a^b K(x,t) \overline{h(x)} g(t) dx dt$  is basically what you can take the transpose of this and

we can put it here value and then we can simplify what should be the value here, okay. So here or you can say that we can change the order here, so when you change the order what you will get?

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$D(L) = 0 \quad ?? \quad f(t)$   
 $\int_a^b g(x) h^*(x) dx$   
 $= \lambda_1 \int_a^b \int_a^b K(x,t) h^*(x) g(t) dx dt$   
 $= \lambda_1 \int_a^b g(t) \left( \int_a^b K(x,t) h^*(x) dx \right) dt$   
 $= \lambda_1 \int_a^b g(t) \frac{h^*(t)}{\lambda_2} dt$   
 $\Rightarrow \frac{\lambda_1}{\lambda_2} \int_a^b g(t) h^*(t) dt$   
 $= \frac{\lambda_1}{\lambda_2} \int_a^b g(x) h^*(x) dx = 0$

$g(x) = \lambda_1 \int_a^b K(x,t) g(t) dt \quad \checkmark$   
 $h(x) = \lambda_2 \int_a^b K^*(t,x) h(t) dt$   
 $\lambda_2 \neq \lambda_1$   
 $\int_a^b g(x) h^*(x) dx = 0$   
 $\Rightarrow \int_a^b g(x) h^*(x) dx = \int_a^b \int_a^b K(x,t) g(t) h^*(x) dt dx$   
 $= \int_a^b h^*(x) \left( \int_a^b K(x,t) g(t) dt \right) dx$

So here we have this is what? This is a to b g of x h star of x d of x is equal to lambda 1 now I am just changing the order here then we have a to b and this is what you will get K of x, t I am writing h star x and g of t and we have dx here and dt here then I can take gt out.

So we have lambda 1 a to b and then it is g of t a to b K x, t h star x and we have d of x. So this I can write lambda 1 a to b g of t, now here what I can write here this I can write this as what? So from here look at this how I can write it this, this I can write here I want to so here this is what I can write this transpose of this so dt I have missed. So I can take this as transpose here and then it is, okay so this I can write it here, okay so this I can write it here so transpose of this so it will go to this I can write it like this.

Now this is what? This is a to b K star x, t h x dx is basically what? It is giving you this, so here I can write gt and I can write this as h star t dt, is it okay? Divided by say lambda 2, right? So I am using this expression and we are writing the value of this so it is a to b K star t, x ht dt is nothing but hx divided by lambda 2 and conjugate transpose of this. So this is what lambda 1 divided by lambda 2 a to b g of t h star t dt here and this is nothing but a to b and g of x h star x d of x.

So  $t$  is just a dummy variable so I can replace it by  $x$  so this I can write  $1 - \lambda_1$  upon  $\lambda_2$ , and here we have what? We have  $a$  to  $b$   $\int_a^b g(x) h^*(x) dx = 0$ . Now  $\lambda_1$  is not equal to  $\lambda_2$  so this implies that  $g(x)$  is orthogonal to  $h^*(x)$ . So here we can say that the eigen function corresponding to  $\lambda_1$  of this equation and the eigen function corresponding to distinct eigen value of the transpose equation are orthogonal to each other, right?

Now with the help of this we try to find out the condition that what happened if  $d\lambda = 0$  then what should be condition on your  $f$  of  $t$  so that we have a solution here.

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The whiteboard contains the following handwritten notes and equations:

- At the top left:  $D(\lambda) = 0 \quad ?? \quad f(t)$
- Below that:  $\lambda = \lambda_0$  and  $\phi_{i_0}, \dots, \phi_{k_0}$  are the solutions of  $\lambda(x) = \lambda_0 \int_a^b K(t, x) \phi(t) dt$ .
- On the right:  $\lambda(x) = \lambda_0 \int_a^b K(t, x) \phi(t) dt$  and  $\int_a^b K(t, s) g(s) \phi_{i_0}^*(t) dt ds$ .
- Under "Claim":  $\int_a^b f(t) \phi_{i_0}^*(t) dt = 0$ .
- Below the claim:  $f(t) = g(t) - \lambda_0 \int_a^b K(t, s) g(s) ds$ .
- Equation:  $\Rightarrow g(x) = f(x) + \lambda_0 \int_a^b K(t, x) g(t) dt$ .
- Equation:  $\int_a^b f(t) \phi_{i_0}^*(t) dt = \int_a^b \left[ g(t) - \lambda_0 \int_a^b K(t, s) g(s) ds \right] \phi_{i_0}^*(t) dt$ .
- Equation:  $= \int_a^b g(t) \phi_{i_0}^*(t) dt - \lambda_0 \int_a^b \left( \int_a^b K(t, s) g(s) ds \right) \phi_{i_0}^*(t) dt$ .
- Equation:  $= 0$ .
- Equation:  $\Rightarrow \int_a^b g(s) \phi_{i_0}^*(s) ds = \int_a^b f(t) \phi_{i_0}^*(t) dt = 0$ .
- At the bottom right:  $i=1, 2, \dots, k$ .

So for that so we want to know that when  $d\lambda = 0$  what should be the condition on  $f$  of  $t$  so that our equation has a solution. So here if you take that  $d\lambda$  is equal to 0 let us say that  $\lambda$  is equal to  $\lambda_0$  where  $\lambda_0$  is the solution of this root of this determinant  $d\lambda$ , then we can call this as eigen value and let us say that the corresponding to this  $\lambda_0$  we have an eigen function say let us say we have say  $\phi_1$  corresponding to  $\phi_1$  not say  $\phi_1$  not to say  $\phi_1$  say let us say  $\phi_k$  not.

So we let us say that corresponding to this  $\lambda_0$  we have these many eigen function of the equation this  $y$  of  $x$  equal to  $\lambda_0 \int_a^b K(x, t) y(t) dt$ . So it means that this  $\phi_1$  not to  $\phi_k$  not satisfy this homogeneous integral equation. Now we claim that we want to claim that

if  $f(t)$  is orthogonal to all  $\phi_i(t)$  then and then only we have say we have some solutions of this equation  $y'' + \lambda y = f(t)$ .

So for that let us say that how we can write this so here let us say that let us say that we have a solution of the problem, so let us say that  $g(x)$  has a solution of what of the non-homogeneous condition that  $g'' + \lambda g = f(x)$ , right? So let  $g$  is one of the solution of this and then our claim is that if  $f$  satisfy this condition then we have a solution. So to show this let us say this so  $\int_a^b f(t) \phi_i(t) dt$  and this I can write as, so this I can write here as  $\int_a^b f(t) dt$  and I am writing the value of  $f(t)$ .

So  $f(t)$  is basically I can get is from this so here we have this  $g(t) + \lambda g(t) = f(t)$  we are considering for  $\lambda$  is equal to  $\lambda$  not so let us say  $\lambda$ . So  $\int_a^b f(t) dt$  and we have what  $\int_a^b g(t) dt$ , right? So this is what we are writing here. So let us use some other symbol otherwise so here let us use some let us say  $s$  you are using so  $g(s)$  and this I am writing as so here it is  $t$  and  $dt$  here.

So what I am doing I am just writing the value of  $f(t)$  so how we are getting the value of  $f(t)$  from this I am getting value of  $f(t)$  when I am writing  $f(t)$  then I have to use some other dummy variable for this integration. So here I am using dummy variable as  $s$  and then I am writing here, so I am writing the value of  $f(t)$  so how I can write so I can write  $f(t)$  as  $g(s) + \lambda g(s) = f(s)$  and here I am writing  $g(s)$  and this is  $s$ , so integration variable is  $s$  and  $ds$ , right?

So I am just using the value of  $f(t)$  so which I am writing here  $g(s) + \lambda g(s) = f(s)$  and then I am writing  $\int_a^b f(t) \phi_i(t) dt$ , right? And then we try to get some kind of condition on  $f(t)$ . So this I can write it simplify  $\int_a^b g(s) ds$  and then when we have this then we have  $\int_a^b f(t) \phi_i(t) dt - \lambda \int_a^b g(s) \phi_i(s) ds$ , is it okay?

Now what we want to show is that  $f(t)$  is orthogonal to this means I have to take the conjugate of this, so please orthogonal  $t$  means this is the conjugate. So here please correct this and then we have this and then we have this and then we have this, is it okay? So here once we have this then what we do here we simply change the order of this integration. So when you change the order of

this integration I am just looking at this particular part, so here I am writing here as  $a$  to  $b$  and  $a$  to  $b$  now if you change the order then  $t$  will come inside and  $ds$  will come out.

So it will be what  $K$ ,  $t$ ,  $s$  and  $g$  of  $s$  and  $\phi_i$  not star  $t$  then I am taking  $dt$  inside and  $ds$  outside, is it okay? So this is what this implies that  $a$  to  $b$  and I am having  $g$  of  $s$  here and then what is inside is  $a$  to  $b$   $K$ ,  $t$ ,  $s$  and  $\phi_i$  not star  $t$   $dt$  and then  $d$  of  $s$ . So this I can write as you can write it transpose here then inside it will be transpose here, right? So this I can write it like this. Now, we have what? This is  $\phi_i$  not  $t$   $dt$  is a solution of what? It is eigen function corresponding to this  $\lambda$  not, so  $\lambda$  not of the transpose equation.

So here I am we have assumed here that corresponding to  $\lambda$  equal to  $\lambda$  not  $\phi_i$  not to  $\phi_k$  not are the solutions of transpose equation that is  $y$  of  $x$  equal to  $\lambda$  not  $a$  to  $b$   $K$  star  $t$  of  $x$   $y$   $t$   $dt$ . So if we take the assumption on these then this is what? This I can write as  $a$  to  $b$  and this is nothing but what this I can write as the  $g$  of  $s$  as it is divided by  $\lambda$  not and this is going to be  $\phi_i$  star and we have  $s$  and then  $d$  of  $s$ , is it okay? Now if you this is  $\lambda$  time, yeah  $y$   $x$  upon  $\lambda$ . So this value is coming out to be this provided that  $\phi_i$   $\phi_1$   $0$  to  $\phi_k$   $0$  are the solutions of this the transpose equation or you can say that when  $\lambda$  equal to  $\lambda$  not if we have say eigen function corresponding to transpose equation corresponding to this  $\lambda$  not then this value is equal to this and if you put this value then what we will have then this value is coming out to be  $0$ , right?

So it means what, so this implies what? That  $a$  to  $b$  your  $f$  of  $t$  your  $\phi_i$   $0$   $t$   $dt$  star is coming out to be  $0$  for since I have taken any  $i$  so I can write it that it is for  $i$  equal to  $1, 2$  and up to  $k$ . So it means that that we have a solution that here we have assumed that  $g$  is a solution of this particular problem. So if  $g$  is a solution then we must have that  $f$   $t$  is orthogonal to the eigen function corresponding to the transpose equation, is it okay?

So that is the necessary condition, yeah there is  $a$  and we can prove that this is also a sufficient condition but I am not going into detail of that that is easily available that you can do you can prove it, okay or you can see the book of R.P Kanwal linear integral equation but we can show here that if  $g$  is the solution of the given problem that is Fredholm integral equation of second kind then the necessary condition that your  $f$   $t$  has to be orthogonal to the eigen function corresponding to the transpose equation, is it okay?

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Fredholm Alternative Theorem

Either the integral equation

$$y(x) = f(x) + \lambda \int K(x, t)y(t)dt$$

with fixed  $\lambda$  possesses one and only one solution  $y(x)$  for arbitrary  $L_2$ -functions  $f(x)$  and  $K(x, t)$ , in particular the solution  $y = 0$  for  $f = 0$ ; or the homogeneous equation

$$y(x) = \lambda \int K(x, t)y(t)dt$$

possesses a finite number  $n$  of linearly independent solutions  $y_j, j = 1, 2, \dots, n$ .

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So if we summarize all this thing then we can write one theorem the theorem which is going to be stated in next slide that is this Fredholm alternative theorem it says that either this integral equation this equation  $y(x) = f(x) + \lambda \int K(x, t)y(t)dt$  with fixed  $\lambda$  possess one and only one solution  $y(x)$  for arbitrary  $L_2$  functions  $f(x)$  and  $K(x, t)$  in particular the solution  $y = 0$  for  $f = 0$ .

So this portion this first portion is corresponding to when  $\lambda$  is not equal to 0. So when  $\lambda$  is not equal to 0 you can find out your  $y(x)$  unique way and you can get unique solution of this non-homogeneous first Fredholm integral equation of the first kind or you can say that if your  $f(x)$  is equal to 0 then that case all those constant is simply vanished and in that case you have only trivial solution. So this first portion is corresponding to the fact that  $\lambda$  is not equal to 0 but if  $\lambda$  is equal to 0 then we have to look at the homogeneous equation  $y(x) = \lambda \int K(x, t)y(t)dt$  possess a finite number of linearly independent solution this we are one possibility corresponding to  $\lambda$  not equal to 0 other possibility is corresponding to  $\lambda$  equal to 0.

And this theorem is known as Fredholm alternative theorem, what we try to do here, here we have consider this particular theorem for kernel which is separable. Now what we try to do here we want to generalize the theory developed for separable kernel for kernel which is not separable or we can generalize this theory for a general kind of kernel.

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Example

Show that the integral equation

$$y(x) = f(x) + \frac{1}{\pi} \int_0^{2\pi} \sin(x+t)y(t)dt \quad (12)$$

possess no solution for  $f(x) = x$  and possess infinitely many solutions when  $f(x) = 1$ .  
Here

$$K(x, t) = \sin(x+t) = \sin x \cos t + \cos x \sin t$$
$$= a_1(x)b_1(t) + a_2(x)b_2(t)$$

and

$$a_{ik} = \int_0^{2\pi} b_i(t)a_k(t)dt, \quad i, k = 1, 2$$

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So that is before this we can consider a simple example here that is based on Fredholm alternative theorem and once we discussed this example later on then we will discuss how to generalize the discussion which we have presented in this lecture or in the previous lecture to the general kind of kernel. So one with just one quick look to this particular example, so here we have equation given here  $y$  of  $x$  equal to  $f$  of  $x$  plus  $\frac{1}{\pi}$  upon  $\pi$   $\int_0^{2\pi} \sin(x+t)y(t)dt$ . So here question is that if  $f$  of  $x$  is  $x$  then we do not have any solution but if  $f$  of  $x$  is equal to 1 then we have (( ))(21:59) solutions here, right?

So for that since look at here the kernel is  $\sin$  of  $x$  plus  $t$  and if you simplify this is nothing but a kind of separable kernel. So when you write it separable kernel which is written as  $a_1(x)b_1(t) + a_2(x)b_2(t)$  then we can write down the  $a_{ik}$  as this.



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$$a_{11} = \int_0^{2\pi} b_1(t)a_1(t)dt = \int_0^{2\pi} \cos t \sin t dt = 0.$$

$$a_{12} = \int_0^{2\pi} b_1(t)a_2(t)dt = \int_0^{2\pi} \cos t \cos t dt = \pi,$$

$$a_{21} = \int_0^{2\pi} b_2(t)a_1(t)dt = \int_0^{2\pi} \sin t \sin t dt = \pi.$$

$$a_{22} = \int_0^{2\pi} b_2(t)a_2(t)dt = \int_0^{2\pi} \sin t \cos t dt = 0.$$

Therefore

$$D(\lambda) = \begin{vmatrix} 1 - \lambda a_{11} & -\lambda a_{12} \\ -\lambda a_{21} & 1 - \lambda a_{22} \end{vmatrix} = \begin{vmatrix} 1 & -\lambda\pi \\ -\lambda\pi & 1 \end{vmatrix} = 1 - \lambda^2\pi^2$$

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So here we can calculate all these  $a_{11}$ ,  $a_{12}$ ,  $a_{21}$ ,  $a_{22}$  and which by which we can form the matrix  $d$  lambda coefficient matrix  $d$  lambda and determinant of  $d$  lambda is given as  $1 - \lambda^2\pi^2$ .

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Example

Show that the integral equation

$$y(x) = f(x) + \frac{1}{\pi} \int_0^{2\pi} \sin(x+t)y(t)dt \quad (12)$$

possess no solution for  $f(x) = x$  and possess infinitely many solutions when  $f(x) = 1$ .  
Here

$$K(x, t) = \sin(x+t) = \sin x \cos t + \cos x \sin t$$

$$= a_1(x)b_1(t) + a_2(x)b_2(t)$$

and

$$a_{ik} = \int_0^{2\pi} b_i(t)a_k(t)dt. \quad i, k = 1, 2$$

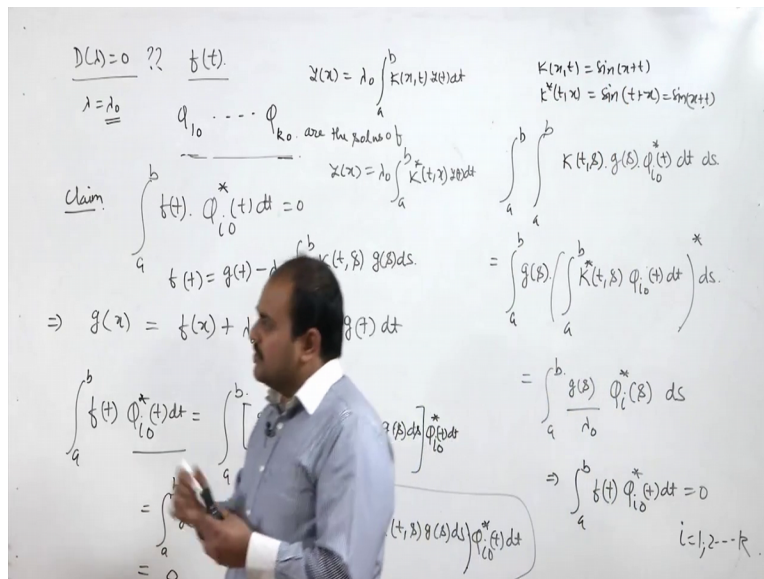
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So we may we know that if  $d$  lambda is non-zero then we have a unique solution here, okay. And unique solution is given as  $y$  of  $x$  equal to  $f$  of  $x$  plus  $\lambda$  times resolvent integral of resolvent kernel  $ft dt$ , right? The resolvent kernel means  $\gamma x, t, \lambda ft dt$  which is given as this equation number 11. So when  $d$  lambda is non-zero we have a solution like this but if you look at

in this particular problem your lambda is 1 by pi and for which this d lambda is coming out to be 0.

So it means that we do not have a unique solution for this then we need to find out the situation when we have say no solution or more than one solution. So for that we have to look at the eigen values and eigen function of the transpose equation. By the way here your kernel is sin of x plus t so transpose kernel is nothing but the same as sin of x plus t.

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So here this K x, t is what? K x, t is sin of x plus t so this is real so K star t, x is going to be a sin of t plus x which is same as sin x plus t.

So here we have transpose problem is same as the same problem, right? So here when we want to discuss the eigen value eigen function of the transpose problem it is same as the considering the eigen value and eigen function of the same problem homogeneous problem.

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The eigenvalues are given by

$$D(\lambda) = 0 \quad \text{i.e.} \quad 1 - \lambda^2 \pi^2 = 0$$

which gives  $\lambda_1 = 1/\pi$  and  $\lambda_2 = -1/\pi$ .  
Here  $\lambda = \lambda_1 = 1/\pi$ . Thus  $D(\lambda) = 0$ , hence (12) will either have no solution or have infinitely many solutions.  
Now find the eigenfunction of the homogeneous integral equation

$$y(x) = \frac{1}{\pi} \int_0^{2\pi} \sin(x+t)y(t)dt \quad (13)$$

The algebraic system corresponding to (13) is

$$(1 - \lambda a_{11})C_1 - \lambda a_{12}C_2 = 0 \quad \text{i.e.} \quad C_1 - \lambda\pi C_2 = 0$$
$$\text{and } \lambda a_{21}C_1 + (1 - \lambda a_{22})C_2 = 0 \quad \text{i.e.} \quad -\lambda\pi C_1 + C_2 = 0.$$


9

So here we are looking at that eigen function of the problem which is  $y$  of  $x$  equal to  $\frac{1}{\pi} \int_0^{2\pi} \sin(x+t)y(t)dt$  and we want to find out say solution of this.

So when you find out the solution of this we have already discussed how to do it so here we simply expand it using the formula of  $\sin$  of  $x$  plus  $t$  and assume that  $C_1$  and  $C_2$  where  $C_1$  and  $C_2$  is what you write  $\sin$  of  $x$   $\cos$  of  $t$   $y(t)dt$ , so you assume  $C_1$  as  $\int_0^{2\pi} \cos t y(t)dt$  and write as  $C_1$ . Similarly you can write  $C_2$  as  $\int_0^{2\pi} \sin t y(t)dt$  and using the expression of  $C_1$  and  $C_2$  we can simply solve our algebraic system like this.

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When  $\lambda = 1/\pi$ , we obtain  $C_1 = C_2$ . Then the corresponding eigenfunction  $y_1(x)$  is given by

$$y_1(x) = \lambda \sum_{i=1}^2 C_i a_i(x) = \frac{1}{\pi} (C_1 a_1(x) + C_2 a_2(x))$$
$$= \frac{1}{\pi} (C_1 \sin x + C_1 \cos x) = C_1 (\sin x + \cos x).$$

When  $\lambda = -1/\pi$ , we obtain  $C_1 = -C_2$ . Then the corresponding eigenfunction  $y_2(x)$  is given by

$$y_2(x) = \lambda \sum_{i=1}^2 C_i a_i(x) = \frac{1}{\pi} (C_1 a_1(x) + C_2 a_2(x))$$
$$= \frac{1}{\pi} (C_1 \sin x - C_1 \cos x) = C_1 (\sin x - \cos x).$$

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So here we have  $C_1 - \lambda \pi C_2 = 0$  and  $-\lambda \pi C_1 + C_2 = 0$ . So we want to find out say eigen value corresponding to  $\lambda = 1/\pi$ . So for this  $\lambda = 1/\pi$  means this is what this I can solve as  $C_1 = C_2$ , so when you put  $\lambda = 1/\pi$  you can solve and you can get  $C_1 = C_2$  and corresponding solution corresponding eigen function is given by  $y(x)$  where  $\lambda = 1/\pi$  now and  $C_1 = C_2$  I can write this as  $\frac{1}{\pi} C_1 a_1(x) + C_2 a_2(x)$  where  $C_2$  is nothing but  $C_1$ .

So this I can write as  $C_1 (\sin x + \cos x)$  I am just writing  $\frac{1}{\pi}$  is merged with this so or you can take any constant now this is this you can write as  $C_1$  telda you can say like this. So I can say that eigen function corresponding to  $\lambda = 1/\pi$  is given as constant multiple of  $\sin x + \cos x$ . Similarly we can find out the eigen function corresponding to  $\lambda = -1/\pi$  so go back here and here we put  $\lambda = -1/\pi$  and we can solve that it is nothing but  $C_1 = -C_2$  and again we can simplify and your solution is constant multiple of  $\sin x - \cos x$ , right?

So we have  $y_1(x)$  as  $\sin x + \cos x$  into some constant multiple of this and  $y_2(x)$  which is eigen function corresponding to  $\lambda = -1/\pi$  and it is like this.

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When  $f(x) = x$ , we have

$$\int_0^{2\pi} f(x)y_1(x)dx = \int_0^{2\pi} C_1 x(\sin x + \cos x)dx \neq 0,$$
$$\text{and } \int_0^{2\pi} f(x)y_2(x)dx = \int_0^{2\pi} C_1 x(\sin x - \cos x)dx \neq 0,$$

which gives that  $f(x)$  is not orthogonal to  $y_1(x), y_2(x)$  and so (12) will possess no solution.

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So here when we have  $f$  of  $x$  equal to  $x$  then we can calculate  $\int_0^{2\pi} f(x)y_1(x)dx$  and  $\int_0^{2\pi} f(x)y_2(x)dx$  and if you put  $y_1$  here then it is equal to this and when you calculate this you please calculate this and it is coming out to be 0.

So it means that it is not satisfying the condition stated here, right? So it means that we do not have so this implies that we cannot have a solution of the this non-homogeneous problem.

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Example

Show that the integral equation

$$y(x) = f(x) + \frac{1}{\pi} \int_0^{2\pi} \sin(x+t)y(t)dt \quad (12)$$

possess no solution for  $f(x) = x$  and possess infinitely many solutions when  $f(x) = 1$ .

Here

$$K(x, t) = \sin(x+t) = \sin x \cos t + \cos x \sin t$$
$$= a_1(x)b_1(t) + a_2(x)b_2(t)$$

and

$$a_{ik} = \int_0^{2\pi} b_i(t)a_k(t)dt, \quad i, k = 1, 2$$

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When  $f(x) = 1$ , we have

$$\int_0^{2\pi} f(x)y_1(x)dx = \int_0^{2\pi} C_1(\sin x + \cos x)dx = 0.$$

Then (12) will possess infinitely many solutions given by

$$\begin{aligned} y(x) &= f(x) + C'y_1(x) + C''y_2(x) \\ &= 1 + C'C_1(\sin x + \cos x) + C''C_1(\sin x - \cos x) \\ &= 1 + A\cos x + B\sin x. \end{aligned}$$

where  $A$  and  $B$  are arbitrary constants.

So it means that in this case our problem when  $f(x)$  equal to  $x$  our original problem  $y$  of  $x$  equal to  $x$  plus  $1$  upon  $\pi$   $0$  to  $2\pi$   $\sin x$  plus  $t$   $yt$   $dt$  will not have any solution but if I look at  $f$  of  $x$  equal to  $1$  and find out the value  $0$  to  $2\pi$   $\int_0^{2\pi} f(x)y_1(x)dx$  equal to it is coming out to be  $0$  you can put the value of  $y_1(x)$  and similarly you can say that it is  $0$  to  $2\pi$   $\int_0^{2\pi} C_1$  similarly you can check for  $0$  to  $2\pi$   $\int_0^{2\pi} f(x)y_2(x)dx$ .

And you can check that both are coming out to be  $0$  here we have done only for  $y_1(x)$  you can check for  $y_2(x)$  and it is also coming as  $0$ . And in this case this condition is satisfied, right? And it means that your non-homogeneous problem will have a  $(0)$ (28:14) solution so which we can write it here  $y$  of  $x$  equal to  $f$  of  $x$  plus say any constant multiple of  $y_1(x)$  plus some constant multiple of  $y_2(x)$ .

So when you write it then we can write that  $y$  of  $x$  is equal to  $x$  plus  $a$   $\cos$  of  $x$  plus  $b$  of  $\sin$  of  $x$ . So in this case when  $f$  of  $x$  equal to  $1$  we have this condition that this  $1$  is orthogonal to eigen functions corresponding to transpose equation here transpose equation is the same equation. So here the this condition is satisfied and we have a solution  $y$  of  $x$  given as  $x$  plus  $a$   $\cos x$  plus  $b$   $\sin x$  or you can say that we have  $(0)$ (28:55) solution.

So that we have discussed, now in next lecture we try to generalize the concept discuss in this lecture and the previous lecture to general kind of kernels, thank you very much.