

Mathematical methods and its applications
Dr. P. N. Agrawal
Department of Mathematics
Indian Institute of Technology, Roorkee

Lecture – 14
Solution of higher-order homogenous
linear differential equation with constant coefficients

Hello friends. Welcome to my lecture on Solution of Higher-order Homogenous Linear Differential Equations with Constant Coefficients. So far we considered second order homogenous linear differential equation with constant coefficients. Now we shall generalize the idea to higher-order homogenous linear differential equation with constant coefficients.

(Refer Slide Time: 00:47)

**Higher-order homogeneous linear differential equations
with constant coefficients**

Let us consider the n th order homogeneous linear differential equation with constant coefficients

$$a_0 y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y^{(1)} + a_n y = 0, \quad \dots(1)$$



Let us put $y = e^{mx}$, we have

$$(a_0 m^n + a_1 m^{n-1} + \dots + a_{n-1} m + a_n) e^{mx} = 0.$$

Since $e^{mx} \neq 0$, for every x , we get

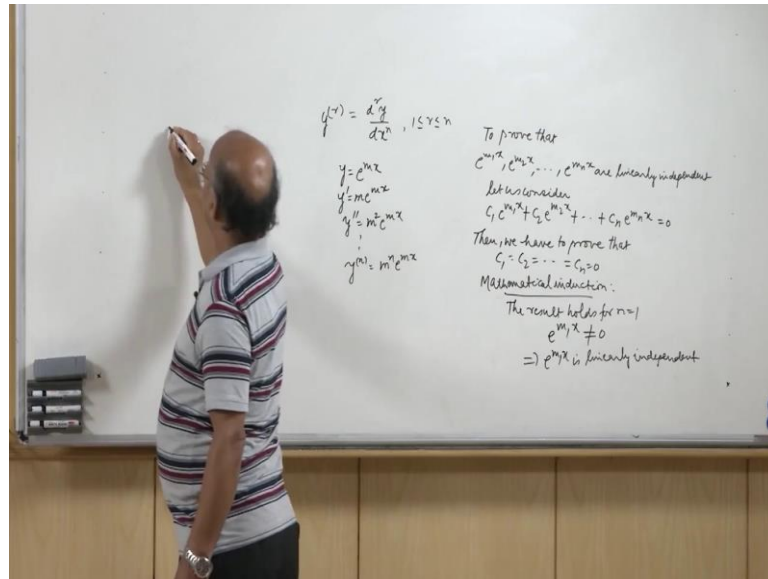
$$a_0 m^n + a_1 m^{n-1} + \dots + a_{n-1} m + a_n = 0 \quad \dots(2)$$

which is known as the auxiliary equation or the characteristic equation.

2

So, let us consider the n th order homogenous linear differential equation with constant coefficients $a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_1 y^{(1)} + a_0 y = 0$. Where $a_n, a_{n-1}, a_{n-2}, \dots, a_1, a_0$ are constant coefficients and $y^{(r)}$ denotes the r th derivative of y with respect to x .

(Refer Slide Time: 01: 10)



So, one less than or equal to r less than or equal to n , this denotation for the derivatives of y with respect to x ; now, let us put y equal to e to the power $m x$. We have seen in the case of the second order linear differential equation with constant coefficients that in the case of first order linear differential equation it turned out that exponential solution is a solution of that homogenous linear differential equation of first order. So, we tried why not let us see for exponential solutions of second order. And it indeed turned out that the second order linear differential equation have exponential functions as solutions.

So, let us put y equal to e to the power $m x$ in equation 1. So, then what do we have if you y equal to e to the power $m x$ then y dash is m times e to the power $m x$, y double dash is m square times e to the power $m x$ and so on n th derivative of y gives you m to the power n e to the power $m x$. So, when you put y equal to e to the power $m x$ in equation 1, but you get is a naught m to the power n plus a 1 y m to the power n minus 1 and so on, n minus 1 m plus a n times e to the power $m x$ is equal to 0 .

Now, it is very well known that e to the power $m x$ is never 0 for $1 \leq x$ belonging to r . So, we will get a naught m to the power n plus a 1 m to the power n minus 1 and so on n minus 1 m plus n equal to 0 which is known as the auxiliary equation or the characteristic equation. So, this equation will have n roots counting the multiplicity. So, those n roots if those n roots are all real and distinct. So, there are 3 possibilities, the n roots of the equation auxiliary equations are all real and distinct. Then there is the second

case where the some of the roots may be equal and then the third possibility where some of the roots may be complex. So, let us discuss each case one by one.

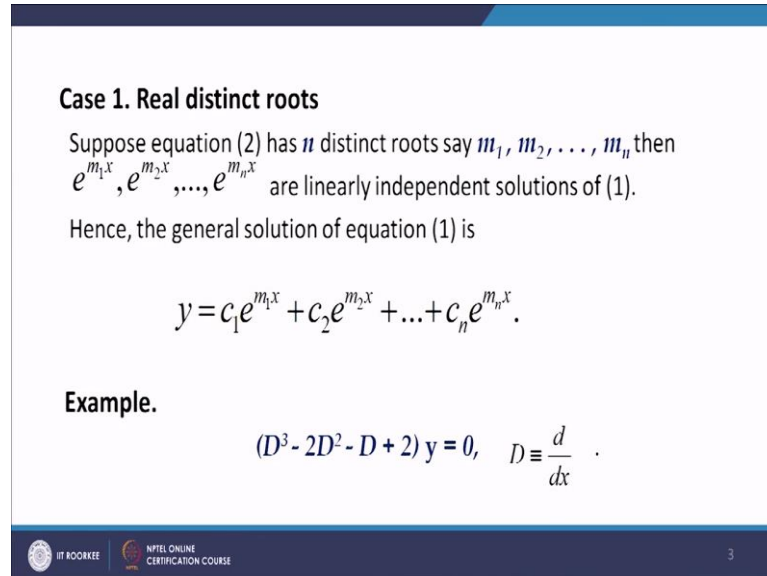
(Refer Slide Time: 03:31)

Case 1. Real distinct roots

Suppose equation (2) has n distinct roots say m_1, m_2, \dots, m_n then $e^{m_1 x}, e^{m_2 x}, \dots, e^{m_n x}$ are linearly independent solutions of (1).
Hence, the general solution of equation (1) is

$$y = c_1 e^{m_1 x} + c_2 e^{m_2 x} + \dots + c_n e^{m_n x}.$$

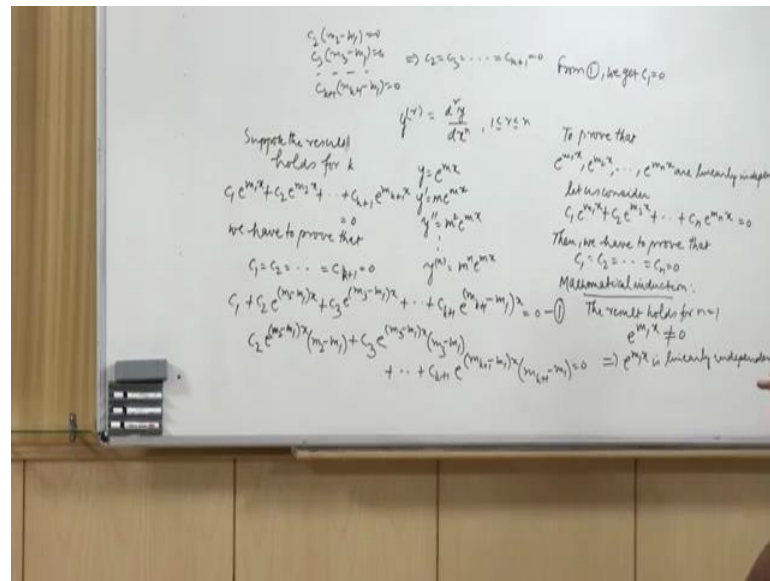
Example.

$$(D^3 - 2D^2 - D + 2)y = 0, \quad D \equiv \frac{d}{dx}.$$


So, suppose the n roots of the auxiliary equation are m_1, m_2, \dots, m_n and they are all distinct. Then the corresponding solutions of the equation (1) will be $e^{m_1 x}, e^{m_2 x}, \dots, e^{m_n x}$ and they are all linearly independent because if you take to prove that these n solutions $e^{m_1 x}, e^{m_2 x}, \dots, e^{m_n x}$ are linearly independent, they are linearly independent I.I.

Let us consider $c_1 e^{m_1 x} + c_2 e^{m_2 x} + \dots + c_n e^{m_n x} = 0$. Then we have to prove that $c_1 = c_2 = \dots = c_n = 0$. We can prove this by mathematical induction. Suppose if we can prove this by mathematical induction. So, the result clearly holds for n equal to 1, result holds for n equal to 1, because when n is equal to 1 $e^{m_1 x}$ is never 0. So, the result holds for n equal to 1. So, this implies that $e^{m_1 x}$ is linearly independent.

(Refer Slide Time: 05:48)



So, suppose the result holds for k functions that are then we have to show that the result holds for k plus 1 function. So, $c_1 e^{m_1 x} + c_2 e^{m_2 x} + \dots + c_{k+1} e^{m_{k+1} x} = 0$ and so on $c_k e^{m_k x} + c_{k+1} e^{m_{k+1} x} = 0$, we have to prove that $c_1 = c_2 = \dots = c_{k+1} = 0$.

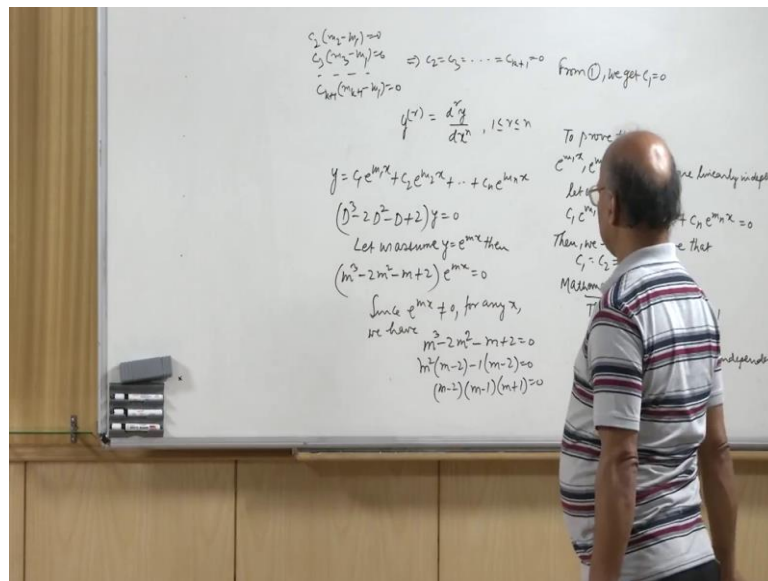
Now, since $e^{m_1 x}$ is never 0, we can divide this equation by $e^{m_1 x}$. So, dividing we have $c_1 + c_2 e^{(m_2 - m_1)x} + c_3 e^{(m_3 - m_1)x} + \dots + c_{k+1} e^{(m_{k+1} - m_1)x} = 0$. Now the result holds for $c_1 = c_2 = \dots = c_k = 0$. So, whenever and the k functions is equal to 0. Now we can differentiate this with respect to x , let us differentiate this with respect to x , then we will get $c_2 m_2 e^{m_2 x} + c_3 m_3 e^{m_3 x} + \dots + c_{k+1} m_{k+1} e^{m_{k+1} x} = 0$ plus $c_3 e^{(m_3 - m_1)x} + c_4 e^{(m_4 - m_1)x} + \dots + c_{k+1} e^{(m_{k+1} - m_1)x} = 0$.

So, $e^{(m_2 - m_1)x} + e^{(m_3 - m_1)x} + \dots + e^{(m_{k+1} - m_1)x}$ are functions, where these $m_2 - m_1, m_3 - m_1, \dots, m_{k+1} - m_1$ they are all distinct, and we have assumed the result for k functions. So, these are k functions. So, they are linearly independent. So, their coefficients must be 0. So, $c_2 m_2 + c_3 m_3 + \dots + c_{k+1} m_{k+1} = 0$, $c_3 m_3 + c_4 m_4 + \dots + c_{k+1} m_{k+1} = 0$, and so on. $c_k m_k + c_{k+1} m_{k+1} = 0$. Since $m_2 > m_1, m_3 > m_1, \dots, m_{k+1} > m_1$ and so on $m_k > m_1$

are all distinct, this implies that c_2, c_3 and so on c_{k+1} are all 0s, and from this equation when you put c_2, c_3, c_{k+1} equal to 0, we get So, this equation let us call it as 1. So, from one we get c_1 equal to 0.

So, c_1, c_2, c_3 and so on c_{k+1} equal to 0. So, the result holds for k by mathematical induction it holds for all k .

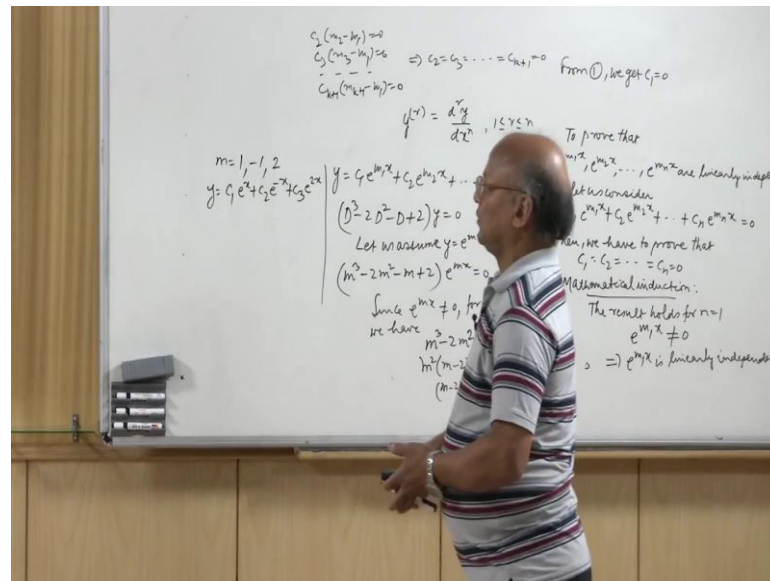
(Refer Slide Time: 10:37)



Here the n functions e to the power $m_1 x$, e to the power $m_2 x$ and for e to the power $m_1 x$ are linearly independent. And therefore, the general solution we can write as, So, general solution can be written as y equal to $c_1 e$ to the power $m_1 x$ plus $c_2 e$ to the $m_2 x$ and so on, $c_n e$ to the power $m_n x$ when the roots of the auxiliary equation are all real and distinct. So, let us say for example, $D^3 - 2D^2 - D + 2$ y equal to 0, D here represents D over $D x$. So, it is a third order linear differential equation with constant coefficients. So, let us assume y equal to e to the power $m x$, then we get $m^3 - 2m^2 - m + 2$ e to the power $m x$ equal to 0.

Since e to the power $m x$ is not 0, for any x , we have the auxiliary equation $m^3 - 2m^2 - m + 2$ equal to 0. Now we can easily factorize this equation. So, $m^3 - 2m^2 - m + 2$ is $m^2(m-2) - 1(m-2)$. So, the factors are $m-2$ and $m^2 - 1$.

(Refer Slide Time: 12:19)



So, we can write $m - 1$ into $m + 1$ equal to 0. The 3 roots of the auxiliary equation are 1 minus 1, 1 minus and 2. So, these are the auxiliary equation as real and distinct roots. So, with general solution will be y equal to $c_1 e$ to the power x $c_2 e$ to the power minus x plus $c_3 e$ to the power $2x$ in this case. Now let us move to second possibility in the second case, we have real multiple roots, when certain root occurs more than one.

(Refer Slide Time: 12:53)



Case 2. Real multiple roots:

Let r be the multiplicity of the root m_1 . Let the remaining $n - r$ roots be real and distinct.

Substituting $m = m_1$, we obtain $y_1(x) = e^{m_1 x}$ as one of the solutions.

We shall now show that the remaining $(r - 1)$ linearly independent solutions corresponding to the multiple root $m = m_1$, are given by

$$x y_1, x^2 y_1, \dots, x^{r-1} y_1, \text{ where } y_1 = e^{m_1 x}.$$

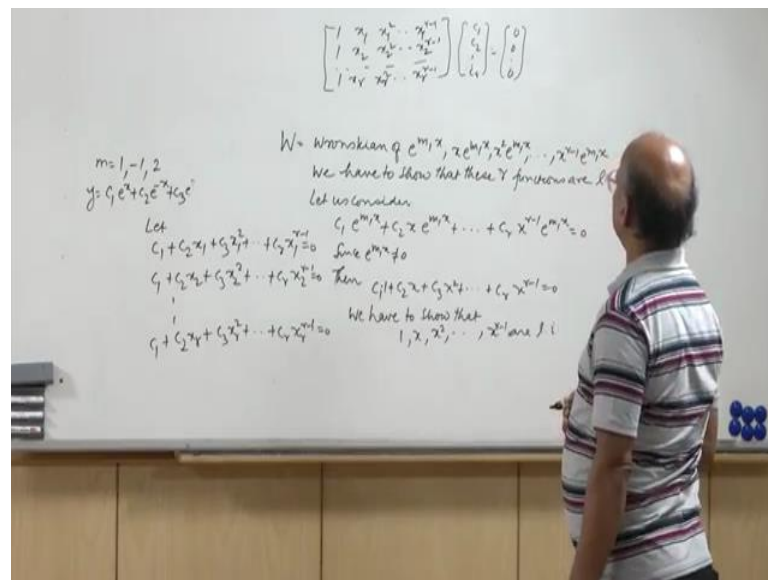


4

So, let us let r be the multiplicity of a root say m equal to $m - 1$ and let us assume that the remaining n minus r roots be real and distinct.

So, corresponding to the distinct roots n minus r , n minus r roots the corresponding n minus r real and distinct roots we can write the corresponding part of the complementary function like we wrote in the case of case 1. So, when we have r roots which are equal how we will find the corresponding part of the complementary function let us see that here. So, assume that m equal to $m - 1$ occurs r times m equal to $m - 1$ occurs r times. So, one solution of the auxiliary equation is one solution of the equation 1 will be $y_1 = x$ equal to e to the $m - 1$ x let us try to find the other r minus 1 linearly independent solutions of the equation 1.

So, we shall now show that the remaining r minus 1 linearly independent solutions corresponding to the multiple root m equal to $m - 1$ are given by x into y_1 , that is x into e to the power $m - 1$ x square into y_1 that is x square into e to the power $m - 1$ x and so on, x to the power r minus 1 e to the power $m - 1$ x .

(Refer Slide Time: 14:22)



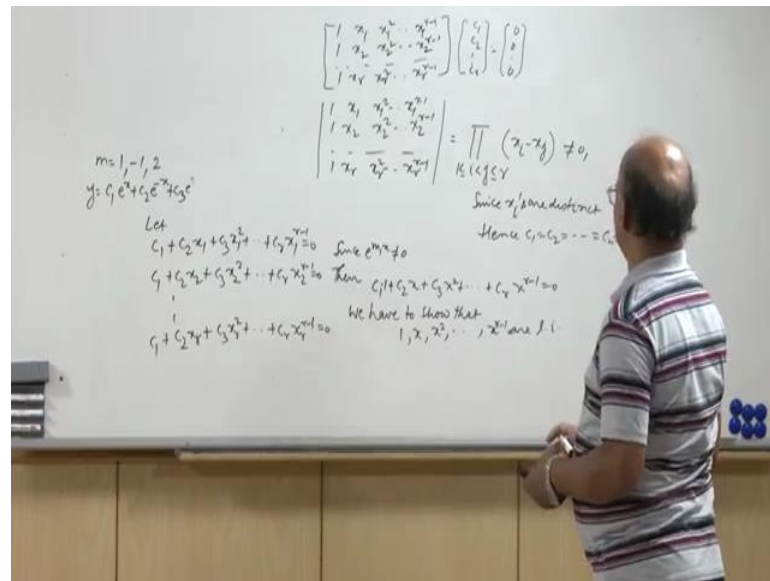
Now, let us note that the Wronskian of these solutions letter W , W is the Wronskian of e to the $m - 1$ x x e to the power $m - 1$ x x square e to the power $m - 1$ x and so on x to the power r minus 1 e to the power $m - 1$ x . So, let us first note that the Wronskian of these r functions is not equal to 0. So, they are linearly independent. Let us see how we will prove this; we have to show that these n r functions are linearly

independent. So, let us consider their combination $c_1 e^{m_1 x} + c_2 e^{m_2 x} + \dots + c_r e^{m_r x} = 0$. We have to prove that c_1, c_2, \dots, c_r are all 0s. Since $e^{m_1 x}$ is never 0, let us divide this equation by $e^{m_1 x}$. So, we get then $c_1 + c_2 e^{(m_2 - m_1)x} + c_3 e^{(m_3 - m_1)x} + \dots + c_r e^{(m_r - m_1)x} = 0$. So, we get this equation.

Now, we have to prove that this equation gives us $c_1 = c_2 = c_3 = \dots = c_r = 0$. Now, in other words we have to show that the functions $1, x, x^2, \dots, x^{r-1}$ are linearly independent. We have to show that $1, x, x^2, \dots, x^{r-1}$ are linearly independent. So, this is a polynomial in x of degree $r-1$. So, and we need to find these r coefficients. So, let us take r points x_1, x_2, \dots, x_r which satisfy this equation. So, then we shall have let us say let $c_1 + c_2 x_1 + c_3 x_1^2 + \dots + c_r x_1^{r-1} = 0$. We have r distinct point let us take r distinct points x_1, x_2, \dots, x_r , these satisfy this equation. So, then $c_1 + c_2 x_2 + c_3 x_2^2 + \dots + c_r x_2^{r-1} = 0$ and so on, $c_1 + c_2 x_r + c_3 x_r^2 + \dots + c_r x_r^{r-1} = 0$, and so on $c_1 + c_2 x_1 + c_3 x_1^2 + \dots + c_r x_1^{r-1} = 0$.

So this can this is a homogenous system of linear equations, we can write it as $1, x, x^2, \dots, x^{r-1}$ and so on, $1, x_2, x_2^2, \dots, x_2^{r-1}$ and so on, $1, x_r, x_r^2, \dots, x_r^{r-1}$ and so on $c_1 + c_2$ and so on $c_r = 0$. Now these homogenous system linear differential equations, so this will have trivial solution provided the determinant of this matrix is nonzero, and the determinant of this matrix is actually nonzero, because it is Vandermonde determinant whose value is equal to determinant of this matrix $1, x, x^2, \dots, x^{r-1}$.

(Refer Slide Time: 19:02)



This is equal to product of 1 less than or equal to i less than or equal to $r \times i$ minus x_j . So, since x_i 's are all distinct; since x_i 's are all distinct the value of it is value is nonzero.

Since x_i are distinct. So, this determinant of this nonzero and therefore, $c_1 = c_2 = \dots = c_n = 0$, hence these n functions $1, x, x^2, \dots, x^{r-1}$ are linearly independent. And So, the n functions here they are linearly independent, $y_1 = c_1 x + c_2 x^2 + \dots + c_n x^{r-1}$. So, the proof of $W \neq 0$ is rather difficult. So, we have proved it by the other method.

(Refer Slide Time: 20:34)

Since the Wronskian of these solutions $W \neq 0$, they are linearly independent.


If $L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y^{(1)} + a_n y$,

then, substituting $y = e^{mx}$ in this equation, we get

$$L[e^{mx}] = (a_0 m^n + a_1 m^{n-1} + \dots + a_{n-1} m + a_n) e^{mx}$$

$$= (m - m_1)^r g(m) e^{mx}, \quad g(m_1) \neq 0. \quad \dots(3)$$

Consider now m as a parameter.




Now, let us see if we let us substitute by if you if you define this as y . If you define the left hand side of equation 1 by $L[y]$, then what we will have if you put y equal to e^{mx} in this then $L[e^{mx}]$ will be equal to $a_0 m^n + a_1 m^{n-1} + \dots + a_{n-1} m + a_n$ into e^{mx} . And since m_1 occurs r times as a root of this characteristic equation we have m this can be written as $(m - m_1)^r$ into $g(m)$, into e^{mx} where $g(m)$ is not $g(m_1)$ is not equal to 0 e^{mx} is never 0. So, m_1 occurs r times means the remaining expression $g(m)$ into e^{mx} must not be 0. So, $g(m_1)$ is not equal to 0.

(Refer Slide Time: 21:27)

$$\frac{d}{dm} L[e^{mx}] = r(m - m_1)^{r-1} g(m) e^{mx} + (m - m_1)^r \frac{d}{dm} [g(m) e^{mx}].$$

Since L is a linear differentiable operator with respect to the independent variable x and m , x are independent, we obtain

$$\frac{d}{dm} L[e^{mx}] = L\left[\frac{d}{dm} e^{mx}\right] = L[x e^{mx}]$$

$$= r(m - m_1)^{r-1} g(m) e^{mx} + (m - m_1)^r \frac{d}{dm} [g(m) e^{mx}]. \quad \dots(4)$$


Now, let us consider m as a parameter. So, then $D^m l e^m x$ let us differentiate this equation with respect to m . When we differentiate this equation with respect to m what we get is $D^m l e^m x$ equal to r times m minus $m - 1$ to the power $r - 1$ $g m e$ to the power $m x$ minus $m - 1$ to the power r D^m of $g m e$ to the power $m x$. Now since l is a linear differentiable operator, we have taken l s this l s this. So, it is a linear differentiable operator. So, with respect to the independent variable x and m and x are independent to each other.

Therefore, $D^m l e^m x$ can also be written as $l D^m e^m x$. And when we differentiate $e^m x$ with respect to m we get $x e^m x$. So, $l x e^m x$ is equal to this. And this when it says at x^m equal to $m - 1$ this when it says that m equal to $m - 1$. So, $x e^m x$ is also a solution of the equation 1. So, since the right hand side vanishes at m equal to $m - 1$ $x e^m x$ is also solution of the differential equation 1.

Again differentiating question 4 with respect to m this equation you again differentiate with respect to m then we will have r into $r - 1$ m minus $m - 1$ to the power $r - 2$ $g m e$ to the power $m x$ and the other terms will be these ones, $2 r m$ minus $m - 1$ to the power $r - 1$ D^m of $g m e$ to the power $m x$ and then m minus $m - 1$ to the power r D^2 over D^m square $g m e$ to the power $m - 1 x$ again we put $r m$ equal to $m - 1$. So, this vanishes because r is greater than 2. So, this vanishes, and this also vanishes and this also vanishes. So, $x^2 e^m x$ is also a solution of equation 1. So, in this manner we continue and when we differentiate $r - 1$ times after $r - 1$ times we differentiate.

(Refer Slide Time: 23:30)

The right hand side of equation (5) vanishes at $m = m_1$ again.
Hence, $x^2 e^{m_1 x}$ is also a solution. After $r - 1$ differentiations, the first term on the right hand side is obtained as $r! (m - m_1) g(m) e^{mx}$ which vanishes for $m = m_1$.
The other terms also vanish for $m = m_1$.
Therefore, $x^{r-1} e^{m_1 x}$ is also a solution.
If we differentiate one more time, that is r times, the first term on the right hand side becomes
 $r! g(m) e^{mx}$, which does not vanish at $m = m_1$.

IT ROORKEE | NPTEL ONLINE CERTIFICATION COURSE 8

The first term on the right hand side is obtained as first term here. If you differentiate it, if you differentiate this here we have differentiated, when we see here if you differentiate r minus 1 times m minus m_1 to the power are this expression m minus r minus 1 times. Then the first term on the right side will be obtained as r factorial m minus m_1 $D g m$ into e to the power $m x$, which vanishes at m equal to m_1 the other terms will also vanish because their powers of m minus m_1 will be more than or 1, and here. So, x to the power r minus 1 e to the power $m_1 x$ will also be solution.

Now, if we differentiate one more time with respect to m , that is r times the first term on the right hand side will be now, r factorial $g m e$ to the power $m x$ which does not vanish at m equal to m_1 . Since $g m_1$ is nonzero. So, it shows that x to the power $r e$ to the power $m_1 x$ is not a solution. And thus we find that e to the power $m_1 x$, $x e$ to the power $m_1 x$ and so on, x to the power r minus 1 e to the power $m_1 x$ are linearly independent solutions corresponding to the multiple root m equal to m_1 ,

(Refer Slide Time: 24:52)

showing that $x^r e^{m_1 x}$ is not a solution.
Hence, we find that

$$e^{m_1 x}, x e^{m_1 x}, x^2 e^{m_1 x}, \dots, x^{r-1} e^{m_1 x},$$
are the linearly independent solutions corresponding to the multiple root $m = m_1$.

Example.

$$(8D^3 - 12D^2 + 6D - 1)y = 0.$$

IT ROORKEE NITEL ONLINE CERTIFICATION COURSE 9

Let us show in the case of r multiple roots, r roots of the equal, we this is how we will find the independent solutions.

(Refer Slide Time: 25:02)

$$y = (c_1 + c_2 x + c_3 x^2) e^{\frac{1}{2}x}$$

$$(8D^3 - 12D^2 + 6D - 1)y = 0$$

$$8m^3 - 12m^2 + 6m - 1 = 0$$
 If we take $m = \frac{1}{2}$

$$8 \cdot \frac{1}{8} - 12 \cdot \frac{1}{4} + 6 \cdot \frac{1}{2} - 1 = 1 - 3 + 3 - 1 = 0$$

$$4m^2(2m-1) - 4m(2m-1) + 1(2m-1) = (2m-1)(4m^2 - 4m + 1) = (2m-1)^3$$
 Hence $m = \frac{1}{2}$ is a root of multiplicity 3.

$$\begin{bmatrix} 1 & x_1 & x_1^2 & \dots & x_1^{r-1} \\ 1 & x_2 & x_2^2 & \dots & x_2^{r-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_r & x_r^2 & \dots & x_r^{r-1} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_r \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$\begin{vmatrix} x_1 & x_1^2 & \dots & x_1^{r-1} \\ x_2 & x_2^2 & \dots & x_2^{r-1} \\ \vdots & \vdots & \ddots & \vdots \\ x_r & x_r^2 & \dots & x_r^{r-1} \end{vmatrix} = \prod_{1 \leq i < j \leq r} (x_i - x_j) \neq 0$$
 Since x_i are distinct
 Hence $c_1 = c_2 = \dots = c_r = 0$

So, let us consider the equation at 8 D cube, 8 D cube minus 12 D square, and then we have 6 D minus 1, y equal to 0. So, the auxiliary equation will be 8 m cube minus 12 m square plus 6 m minus 1 equal to 0. 8 m cube minus 12 m square plus 6 m minus 1 equal to 0.

Let us find; solve this cubic equation. So, here we notice that if we take m equal to half, then we get 8 into 1 by 8 minus 1^2 into 1 by 4 plus 6 into 1 by 2 minus 1 equal to 1 minus 3 plus to plus 3 minus 1 equal to 0 . So, m equal to half is a root of this equation. So, we can put m let us put $2m - 1$ $2m - 1$ is a factor of this equation, $2m - 1$. So, we can write $4m^2 - 4m + 1$ $4m^2 - 4m + 1$ means $8m^2 - 8m + 2$ $8m^2 - 8m + 2$ cube minus $4m^2 - 4m + 1$. And then we will take $4m^2 - 4m + 1$ $8m^2 - 8m + 2$ into $2m - 1$. So, we get minus $8m^2 + 8m - 2$ $8m^2 - 8m + 2$ minus 1^2 $8m^2 - 8m + 2$ minus plus $4m$. So, we get how much we require $8m^2 - 8m + 2$ $8m^2 - 8m + 2$ minus $8m^2 - 8m + 2$ plus $4m$ plus $4m$ is minus $4m$; so $2m - 1$.

So, this is equal to this, how we have factorized this. So, this is $2m - 1$ into $4m^2 - 4m + 1$. These are the 2 factors and this can be this is square of $2m - 1$. So, this is $2m - 1$ whole cube. So, here m equal to half is a root of multiplicity 3. And, general solution is y equal to $c_1 + c_2 x + c_3 x^2$ e to the power half x in this case.

(Refer Slide Time: 28:04)



Case 3. Multiple complex roots:

This case is the combination of the two earlier cases of real multiple roots and simple complex roots.

Now, if $p + iq$ is a multiple root of order m , then $p - iq$ is also a multiple root of order m .

For example, if $p_1 + iq_1$ is a double root then $p_1 - iq_1$ is also a double root. The corresponding linearly independent solutions are

$$e^{p_1 x} \cos q_1 x, e^{p_1 x} \sin q_1 x, x e^{p_1 x} \cos q_1 x, x e^{p_1 x} \sin q_1 x .$$



10

Let us now consider the third case multiple complex roots. This case is a combination of the 2 earlier cases. Suppose the $p + iq$ is a multiple root of order m then since the coefficients of the given differential equation in 1 are real the $p - iq$ will also be a multiple root of order m . So, for example, if $p_1 + iq_1$ is a double root then $p_1 - iq_1$ is also a double root.

Now, we have earlier seen that if $p + iq$ and $p - iq$ are roots of the auxiliary equation, then the corresponding independent solutions are $e^{(p+iq)x}$ and $e^{(p-iq)x}$. Now $p + iq$ is a double root, and $p - iq$ is a double root. So therefore, if y_1 is $e^{(p+iq)x}$ and y_2 is $e^{(p-iq)x}$, then y_1 and y_2 are solutions. Also, $y_1 x$ and $y_2 x$ are solutions. Then $y_1 + y_2$ and $y_1 - y_2$ are also solutions. So, if $p + iq$ is a double root and $p - iq$ is a double root then $e^{(p+iq)x}$ and $e^{(p-iq)x}$ are solutions, and $x e^{(p+iq)x}$ and $x e^{(p-iq)x}$ are also solutions. So, if $p + iq$ is a double root and $p - iq$ is a double root then $e^{(p+iq)x}$, $e^{(p-iq)x}$, $x e^{(p+iq)x}$, and $x e^{(p-iq)x}$ are solutions.

(Refer Slide Time: 29:36)

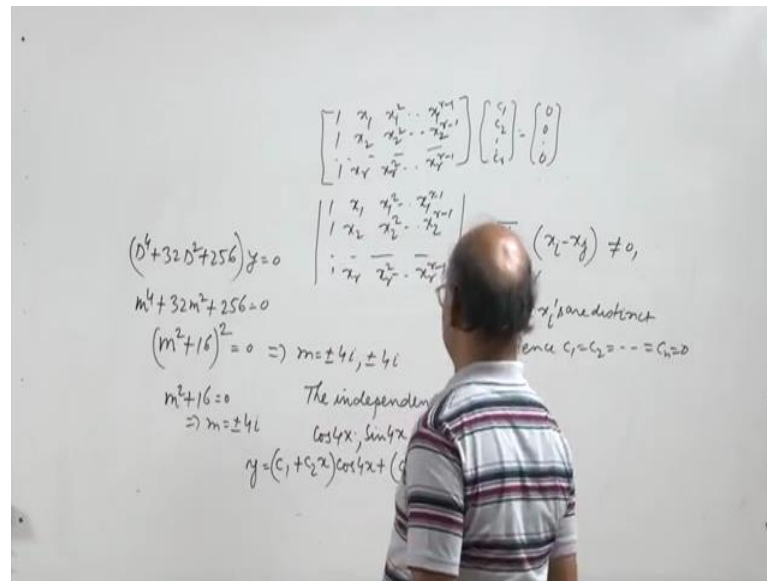
Example.

$$(D^2 + 32D + 256)y = 0.$$

IIT ROORKEE NPTEL ONLINE CERTIFICATION COURSE 11

They will also be double roots, and therefore, the corresponding independent solutions will be $e^{(p+iq)x}$, $x e^{(p+iq)x}$, $e^{(p-iq)x}$, and $x e^{(p-iq)x}$.

(Refer Slide Time: 30:02)



So, we will write the general solution in this case as follows. So, $D^4 + 32D^2 + 256$ suppose this is equal to 0 $D^4 + 32D^2 + 256 y = 0$. So, the auxiliary equation will be $m^4 + 32m^2 + 256 = 0$ let us this is equal to $m^4 + 6m^2 + 16$ whole square equal to 0. If you square this, we get $m^4 + 32m^2 + 256 = 0$.

So, we have here m^2 now, $m^2 + 16 = 0$ gives you $m = \pm 4i$. So, $\pm 4i$ occur twice, because here we have $m^2 + 16$ square. So, this gives you $m = \pm 4i$ and $\pm 4i$. So, 4 occur twice and $\pm 4i$ also occur twice. So, here we will have the independent solutions will be $e^{(p+iq)x}$ if $p+iq$ is a root and $p-iq$ is a root. Then we have $e^{(p+iq)x} \cos qx$ and $e^{(p+iq)x} \sin qx$. So, we have here $p=0$. So, $\cos 4x$ and $\sin 4x$ means $\cos 4x$ is a root $\sin 4x$ is a root $\cos 4x$ is a solution $\sin 4x$ is a solution. And the other linearly independent solutions are $x \cos 4x$ and $x \sin 4x$.

So, we will write the general solution as $y = c_1 \cos 4x + c_2 x \cos 4x + c_3 \sin 4x + c_4 x \sin 4x$ in this case, where c_1, c_2, c_3, c_4 are arbitrary constants. So, with that we conclude this lecture on solution of homogenous linear differential equations of higher-order.

I thank you for your attention.