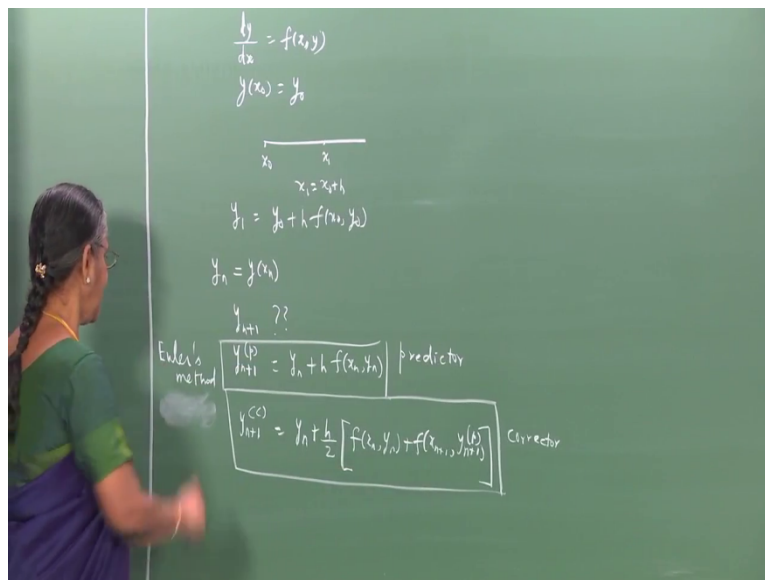


Numerical Analysis
Prof R Usha
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Lecture 23
Numerical Solution of Ordinary Differential Equations-6
Predictor- Corrector Methods
(Adam - Moulton)

In the last class we studied about the Predictor- Corrector Method by Euler's Method which solves the initial value problem $\frac{dy}{dx}$ is equal to $f(x, y)$ and an initial condition is given at x_0 as $y(x_0)$ equal to y_0 . If you want to obtain the solution say at a point x_1 which is x_0 plus h then Euler's Method says y_1 is y_0 plus h into $f(x_0, y_0)$. So typically if the information is given at x_n as $y(x_n)$ and that is equal to y_n and you are asked to compute what y_{n+1} is?

Then Euler's Method says y_{n+1} is y_n plus h into $f(x_n, y_n)$. Then we also saw a modified form of Euler's Method in which the curve solution curve in an interval x_n to x_{n+1} is approximated by a straight line passing through x_n, y_n and having its slope to be the average of the slopes at the point x_n, y_n and x_{n+1}, y_{n+1} .

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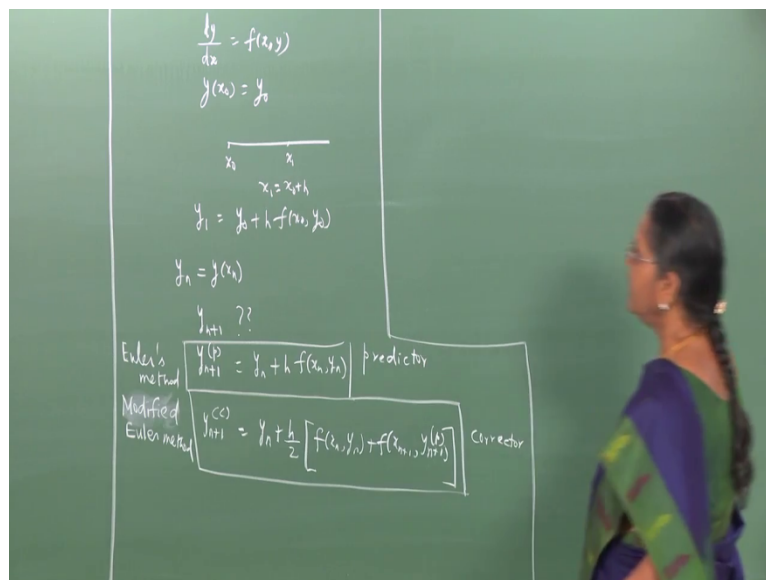
And so we obtained modified Euler's Method given by y_{n+1} equal to y_n plus h by 2 into $f(x_n, y_n)$ plus $f(x_{n+1}, y_{n+1})$. And we observed when we derived this formula that the unknown y_{n+1} appears not only on the left side but it also appears here and we need

the value of the function at x_{n+1} y_{n+1} . But our goal in deriving the method was to obtain what y_{n+1} is.

So this suggest that we can use the value of y_{n+1} here as that is predicted by the Euler's Method. So I call Euler's Method as a predictor and I use this predicted value of y_{n+1} and find what is $f(x_{n+1}, y_{n+1})$ predicted which is the value of the function at x_{n+1} y_{n+1} because of we know what is x, y .

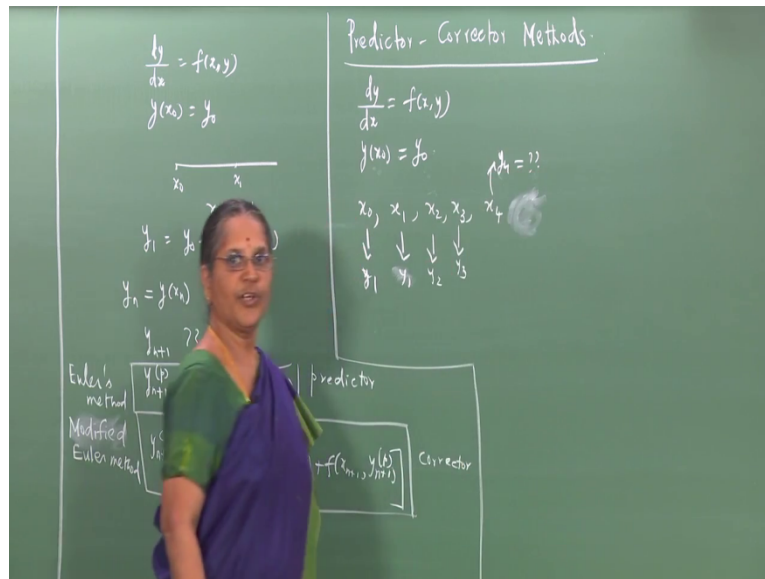
So once we know what the function here is I can evaluate y_{n+1} that is going to be a value that I get for y_{n+1} which is obtained using the predicted value of y_{n+1} . So I have essentially corrected the value of y_{n+1} , so I call this as a corrected value. So I now have two methods with the help of which I am able to predict y_{n+1} . So I call that as a predictor method and using that predicted value here I am able to correct it and so I call this as a corrector method.

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Euler's Method and corrected Euler's Method serve as a Predictor- Corrector pair for computing the solution of the initial value problem of the form $dy/dx = f(x,y)$ and $y(x_0) = y_0$ and one will be able to obtain the solution at the next point knowing the information at a previous point. So this suggest that more efficient methods can be devised by employing Predictor- Corrector Methods so that whatever that is predicted can be corrected and successively recorrected till the desired degree of accuracy is attained.

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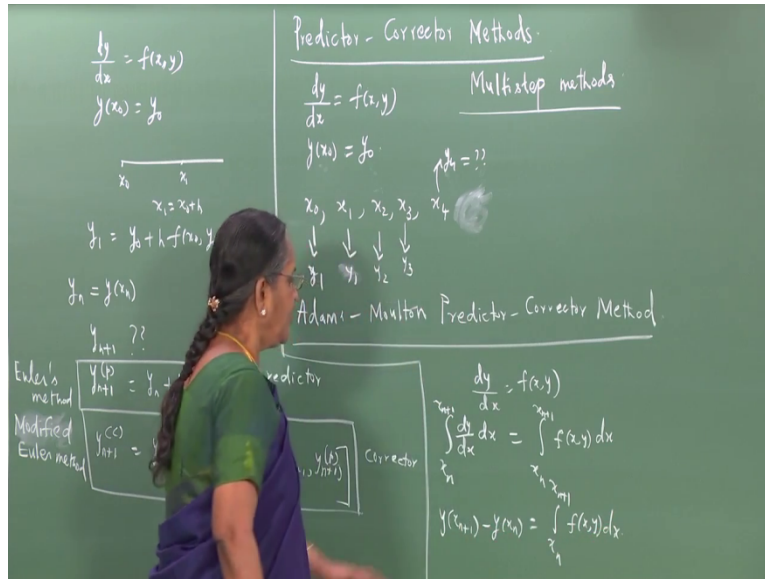


So in this class we shall look for some more Predictor- Corrector Methods. So we shall look into so we will derive some Predictor- Corrector Methods in this class which help us to solve $\frac{dy}{dx}$ is equal to $f(x,y)$ given that $y(x_0)$ is equal to y_0 . If suppose we have information about the solution of this problem at points say x_0 which is given by this initial condition at x_1, x_2, x_3 and if we are asked to compute the solution at say x_4 which means the solution at the point x_4 makes use of the information at the previous 4 points. Namely the solution at x_4 is y_4 and that is what is needed by us.

So the solution at x_3, x_2, x_1 and x_0 are given to us, with this information we should find out what y_4 is. So the computation of solution at y_4 involves the knowledge of the solution at the previous points. So the methods that we derive by requiring that information is needed at a set of previous points in order to obtain solution at this point then such methods are called multi step methods.

So essentially we will be deriving what are referred to as Multi step methods. Once we derive them we can conveniently use these methods Predictor- Corrector Methods and obtain the solution of the given problem correct to the desired degree of accuracy.

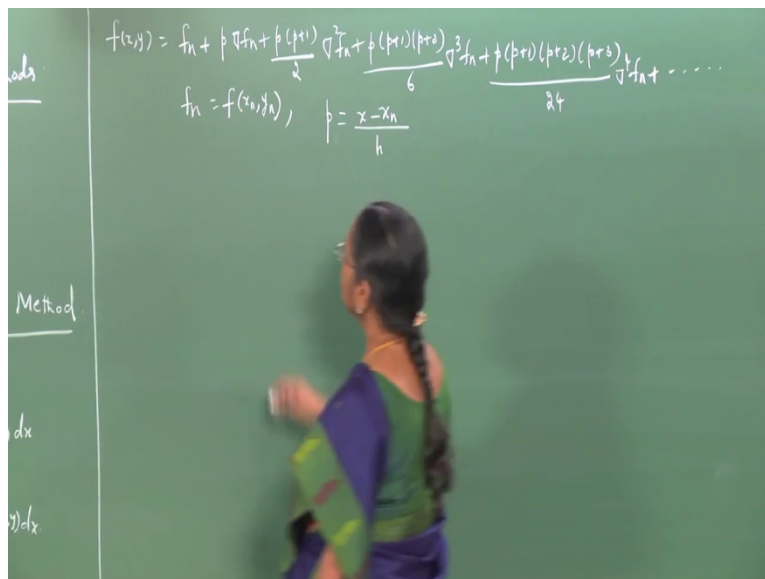
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So let us first derive what is known as Adam's - Moulton Predictor- Corrector Method. So it solves a differential equation $\frac{dy}{dx}$ is equal to $f(x, y)$. Let me integrate both sides with respect to x from x_n to x_{n+1} . So $\frac{dy}{dx}$ into dx will be integral x_n to x_{n+1} $f(x,y)$ integration with respect to dx . So this tells you $y(x_{n+1}) - y(x_n)$ is integral x_n to x_{n+1} $f(x,y) dx$.

So at this stage I shall approximate the function $f(x,y)$ using Newton's backward interpolation polynomial.

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So $f(x,y)$ is $f_n + p \Delta f_n + \frac{p(p+1)}{2} \Delta^2 f_n + \frac{p(p+1)(p+2)}{6} \Delta^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \Delta^4 f_n + \dots$. So by f_n I mean the value of the function at (x_n, y_n) and by p I mean $x - x_n$ divided by h .

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The chalkboard shows the following derivations:

$$f(x,y) = f_n + p \Delta f_n + \frac{p(p+1)}{2} \Delta^2 f_n + \frac{p(p+1)(p+2)}{6} \Delta^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \Delta^4 f_n + \dots$$

$$f_n = f(x_n, y_n), \quad p = \frac{x - x_n}{h}, \quad x - x_n = hp, \quad \frac{dx}{dx} = h \frac{dp}{dp}, \quad x_n - x_n = hp \Rightarrow p = 0, \quad x_{n+1} - x_n = hp \Rightarrow h = hp \Rightarrow p = 1$$

$$y(x_{n+1}) - y(x_n) = \int_{x_n}^{x_{n+1}} \left[f_n + p \Delta f_n + \frac{p(p+1)}{2} \Delta^2 f_n + \frac{p(p+1)(p+2)}{6} \Delta^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \Delta^4 f_n + \dots \right] dx$$

$$= h \int_0^1 \left[f_n + p \Delta f_n + \frac{p(p+1)}{2} \Delta^2 f_n + \frac{p(p+1)(p+2)}{6} \Delta^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \Delta^4 f_n + \dots \right] dp$$

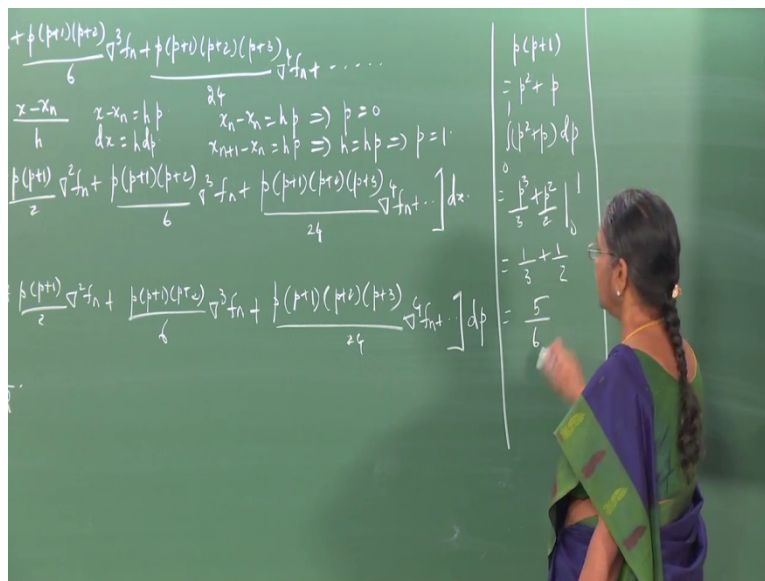
$$= h \left[f_n + \frac{1}{2} \Delta f_n + \frac{1}{6} \Delta^2 f_n + \dots \right]$$

So I substitute for $f(x,y)$ here So I get $y(x_{n+1}) - y(x_n)$ is integral x_n to x_{n+1} of $f(x,y)$ so $f_n + p \Delta f_n + \frac{p(p+1)}{2} \Delta^2 f_n + \frac{p(p+1)(p+2)}{6} \Delta^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \Delta^4 f_n + \dots$ integration with respect to x .

Now I observe that the variable here is p and the integration is with respect to x so I use this transformation so I have $x - x_n$ to be h into p , so dx will be equal to $h dp$. Further when x is equal to x_n then this tells that p is 0 and where x is equal to x_{n+1} then we have h to be equal to hp which gives you p to be equal to 1.

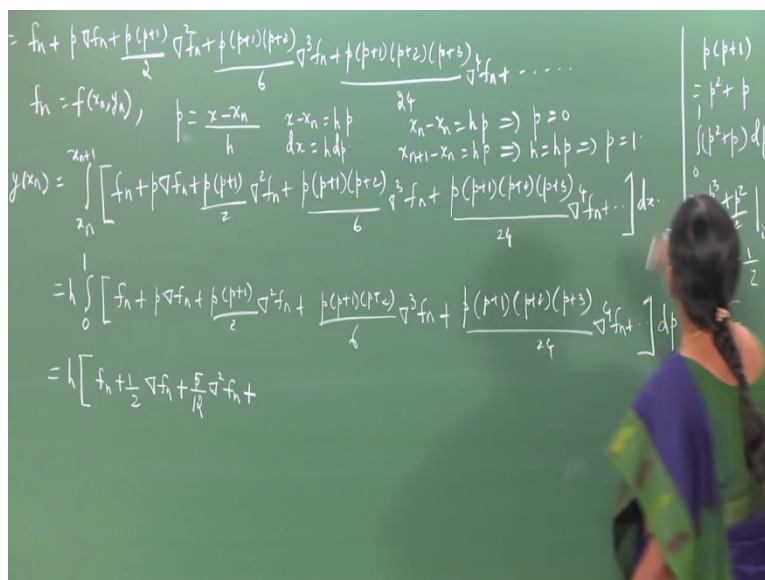
So the integration is h times integral 0 to 1 $f_n + p \Delta f_n + \frac{p(p+1)}{2} \Delta^2 f_n + \dots$ del square f_n , So I write down all these terms as they are and then perform the integration. Integration is now with respect to p . So the first term will give you h into $f_n dp$ integrated with respect to p from 0 to 1 so it is f_n into p between 0 and 1. So it is simply f_n , the second term $p dp$ so p^2 by 2 between 0 and 1 so half of Δf_n then plus half of p into $(p+1)$.

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So that will give you p square plus p and that has to be integrated with respect to p, so that will give you p cube by 3 plus p square by 2 between 0 and 1. So this will give you 5 divided by 6.

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So this term will give you 5 by 12 into del square f n.

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$f(x) = f(x_n) + \frac{p(p+1)}{2} \nabla^2 f_n + \frac{p(p+1)(p+2)}{6} \nabla^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \nabla^4 f_n + \dots$
 $f_n = f(x_n), \quad p = \frac{x-x_n}{h}, \quad x-x_n = hp, \quad \frac{dx}{dx} = h \frac{dp}{dp}$
 $x_n - x_n = hp \Rightarrow p=0, \quad x_{n+1} - x_n = hp \Rightarrow h = hp \Rightarrow p=1$
 $f_n = \int_0^1 \left[f_n + p \nabla f_n + \frac{p(p+1)}{2} \nabla^2 f_n + \frac{p(p+1)(p+2)}{6} \nabla^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \nabla^4 f_n + \dots \right] dp$
 $= h \int_0^1 \left[f_n + p \nabla f_n + \frac{p(p+1)}{2} \nabla^2 f_n + \frac{p(p+1)(p+2)}{6} \nabla^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \nabla^4 f_n + \dots \right] dp$
 $= h \left[f_n + \frac{1}{2} \nabla f_n + \frac{5}{12} \nabla^2 f_n + \dots \right]$

$p(p+1) = p^2 + p$
 $\int_0^1 (p^2 + p) dp = \left[\frac{p^3}{3} + \frac{p^2}{2} \right]_0^1 = \frac{1}{3} + \frac{1}{2} = \frac{5}{6}$
 $\int_0^1 (p^2 + p)(p+2) dp = \int_0^1 (p^3 + 3p^2 + 2p) dp = \left[\frac{p^4}{4} + p^3 + p^2 \right]_0^1 = \frac{1}{4} + 1 + 1 = \frac{9}{4}$

Then the next term p into p plus 1) is p square plus p and that has to be multiplied by p plus 2 so that will give you p cube plus p square plus $2p$ square so this will become $3p$ square plus $2p$. So I have to integrate this between 0 and 1 with respect to p . So that will give you p power 4 by 4 plus $3 p$ cube by 3 plus p square by 2 between 0 and 1 . So this gives you 1 by 4 plus 1 plus 1 , so we have 9 by 4 .

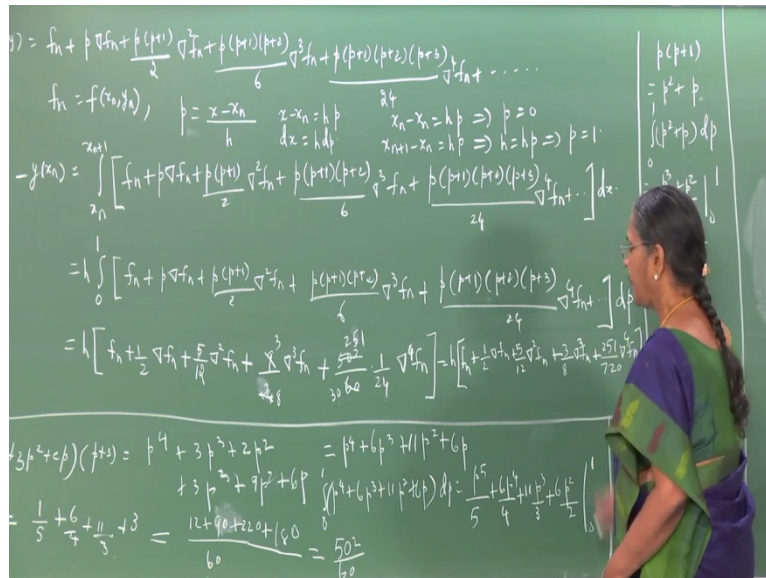
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$f_n + \frac{p(p+1)}{2} \nabla^2 f_n + \frac{p(p+1)(p+2)}{6} \nabla^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \nabla^4 f_n + \dots$
 $f_n = f(x_n), \quad p = \frac{x-x_n}{h}, \quad x-x_n = hp, \quad \frac{dx}{dx} = h \frac{dp}{dp}$
 $x_n - x_n = hp \Rightarrow p=0, \quad x_{n+1} - x_n = hp \Rightarrow h = hp \Rightarrow p=1$
 $f_n = \int_0^1 \left[f_n + p \nabla f_n + \frac{p(p+1)}{2} \nabla^2 f_n + \frac{p(p+1)(p+2)}{6} \nabla^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \nabla^4 f_n + \dots \right] dp$
 $= h \int_0^1 \left[f_n + p \nabla f_n + \frac{p(p+1)}{2} \nabla^2 f_n + \frac{p(p+1)(p+2)}{6} \nabla^3 f_n + \frac{p(p+1)(p+2)(p+3)}{24} \nabla^4 f_n + \dots \right] dp$
 $= h \left[f_n + \frac{1}{2} \nabla f_n + \frac{5}{12} \nabla^2 f_n + \dots \right]$

$p(p+1) = p^2 + p$
 $\int_0^1 (p^2 + p) dp = \left[\frac{p^3}{3} + \frac{p^2}{2} \right]_0^1 = \frac{1}{3} + \frac{1}{2} = \frac{5}{6}$
 $\int_0^1 (p^2 + p)(p+2) dp = \int_0^1 (p^3 + 3p^2 + 2p) dp = \left[\frac{p^4}{4} + p^3 + p^2 \right]_0^1 = \frac{1}{4} + 1 + 1 = \frac{9}{4}$

So I have already 6 here so 9 by 24 into del cube f n and then I have to perform integration of this term. So let us work out the details. So I have p plus 1 p plus 2 given by p cube plus 3p , p square plus 2p.

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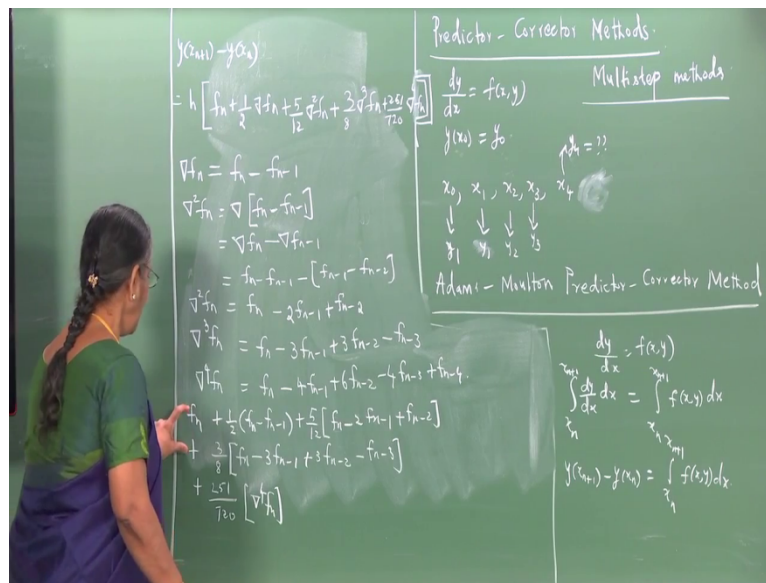


So we have p cube plus p square plus 2p now that has to be multiplied by p plus 3 so and that will give you p to the power of 4 plus 3 p cube 2 p square and then plus 3 p cube plus 9 p square plus 6 p which will give you p power 4 plus 6 p cube plus 11 p square plus 6 p. Now I have to integrate this with respect to p. And that gives you p power 5 by 5 plus 6 p power 4 by 4 plus 11 p cube by 3 plus 6 p square by 2 between 0 and 1.

So let us substitute for p the upper and the lower limit that gives you 1 by 5 plus 6 by 4 plus 11 by 3 plus 6 by 2. So if you evaluate this then you get 502 by 60 so I substitute here that will give you 502 by 60 into 1 by 24 into del power 4 f n. So I shall truncate this terms here at this stage so y (x n plus 1) minus y (x n) which is this when the integration is performed it gives you this result which can be simplified and it is given by h into f n plus half delta f n plus 5 by 12 del square f n then the next term 3 by 8 into del cube f n plus this gives you 251 by 30 into 24 so that is 251 by 720 into del power 4 f n.

So let us now substitute for the backward differences delta f n del square f n etc and then express this in terms of the function values.

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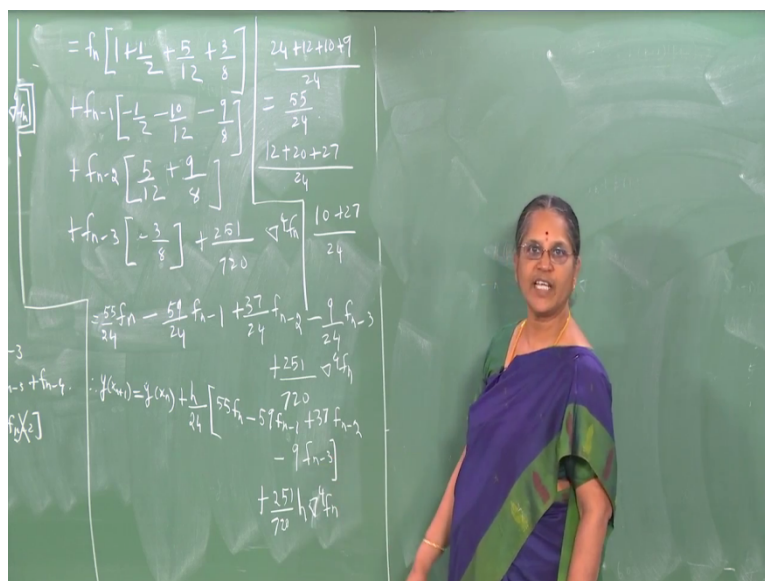


So we obtain $y(x_{n+1}) - y(x_n)$ is given by h , let me rewrite that expression once again that will be easier for me to make the computations So $[f_n + \frac{1}{2} \Delta f_n + \frac{5}{12} \Delta^2 f_n + \frac{3}{8} \Delta^3 f_n + \frac{251}{720} \Delta^4 f_n]$. So we use the definition of the backward difference operator on f_n so that gives you $f_n - f_{n-1}$. So what is $\Delta^2 f_n$ it is the backward difference operator operating on $f_n - f_{n-1}$ so it is $\Delta f_n - \Delta f_{n-1}$.

And that is $f_n - f_{n-1} - [f_{n-1} - f_{n-2}]$. So that will give you $f_n - 2f_{n-1} + f_{n-2}$ that is what is $\Delta^2 f_n$. We require $\Delta^3 f_n$ so that will be $f_n - 3f_{n-1} + 3f_{n-2} - f_{n-3}$ and finally we have $\Delta^4 f_n$ and that will be $f_n - 4f_{n-1} + 6f_{n-2} - 4f_{n-3} + f_{n-4}$. So we have obtained the backward differences on f_n which appear here and express them in terms of the function values of different points.

So now we have to substitute these here and collect the like terms and then write down the result finally so we have the first term to be f_n the second term is half of Δf_n which is $f_n - f_{n-1}$ then the next term is $\frac{5}{12} \Delta^2 f_n$ that is $f_n - 2f_{n-1} + f_{n-2}$. Then I have $\frac{3}{8} \Delta^3 f_n$ so that gives you $f_n - 3f_{n-1} + 3f_{n-2} - f_{n-3}$. And finally this term $\frac{251}{720}$.

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So we shall retain that term as it is as del power 4 into f n I do not want to substitute that in terms of the function values. Let us simplify these terms. So I shall collect the terms involving f n so the first term has coefficient 1 then we have half 5 by 12 then 3 by 8 that is the coefficient of f n. And then the next term is f n minus 1 [minus half which comes from this then minus 10 by 12 from this term then minus 9 by 8]. Then I will collect the terms involving f n minus 2 that is 5 by 12 from there and then 9 by 8 from the next term and we have f n minus 3 whose coefficient is minus 3 by 8.

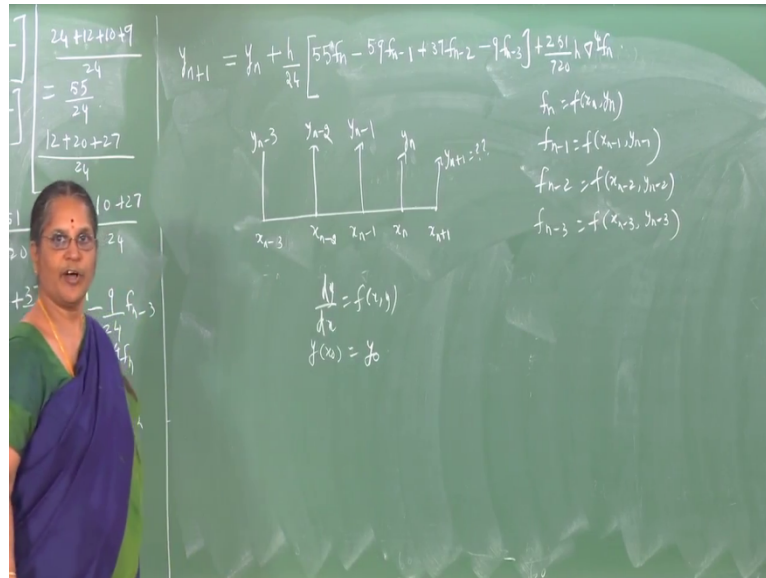
And I have the next term which is 258 by 720 into del power 4 f n. So we have to simplify these so I shall take say 24, 24 plus 12 plus 10 plus 9. So 36 , 46 so 55 by 24. So coefficient of f n is 55 by 24 then I have minus f n minus 1 into so I shall now take 24 as common denominator so I have 12 plus 20 plus 27 47, 49 so 59 by 24 into f n minus 1.

Then this term again 24 so 10 27 so plus 37 by 24 f n minus 2. And then if I take 24 here then it will become 9 by 24 f n minus 3 and then the last term 251 by 720 into del power 4 f n. So we have simplified the right hand side so we write down the result therefore y (x n plus 1) is equal to y (x n) plus I have h as a coefficient here so h by 24 into [55 f n minus 59 f n minus 1 plus 37 f n minus 2 minus 9 f n minus 3 plus 251 by 720 into h into del power 4 f n.

Thus we have y(x n plus 1) to be given by y(x n) plus h by 24 into a linear combination of the function values f(x,y) at x n y n this is at x n minus 1 y n minus 1 x n minus 2 y n minus 2

and this is at x_{n-3} y_{n-3} . And this is obtained by approximating the function $f(x,y)$ by means of backward interpolation polynomial for equally spaced points.

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The result that we get is an approximation value to $y(x_{n+1})$ so we denote it by y_{n+1} and that is $y_n + h/24 [55f_n - 59f_{n-1} + 37f_{n-2} - 9f_{n-3}] + 251/720 h^2 \delta^2 f_n$. So what does this method indicate? Suppose you require a solution at this point x_{n+1} namely y_{n+1} is what you have to find. Then you require the knowledge of the value at x_n which is y_n and what about this f_n is $f(x_n, y_n)$.

So when you know what is y_n at x_n then you can compute what is $f(x_n, y_n)$ so this term is known what is f_{n-1} it is $f(x_{n-1}, y_{n-1})$. So the information at the previous point namely x_{n-1} should also be available to you and you call that as y_{n-1} . And once you have this you find what f_{n-1} is.

Similarly you compute the values of f_{n-2} which is $f(x_{n-2}, y_{n-2})$ and f_{n-3} which is $f(x_{n-3}, y_{n-3})$. So that is going to be attained by using the information at x_{n-3} where the solution is y_{n-3} . So in order to get the solution at x_{n+1} you require information about y_n at a previous four points.

So essentially what is it that you have done? You have approximated that function $f(x,y)$ by a polynomial passing through these 5 points x_i, y_i such that this will be a fourth degree polynomial and hence the fourth order backward difference is constant and the fifth and the

higher order backward differences are all 0. And that is why you truncated your Newton Backward interpolation polynomial at the term which contained $h^4 \nabla^4 f_n$.

The Question now is , how do you get these values? because your problem is $\frac{dy}{dx} = f(x, y)$. And you will be given information at some initial point (x_0, y_0) .

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You are asked to compute the solution at x_{n+1} . So you require the knowledge of the solution at the previous four points $x_n, x_{n-1}, x_{n-2}, x_{n-3}$. Divide the interval x_0 to x_{n+1} into four equal parts and name those points as x_i and then try to obtain the solution at other three points using single step method which you have already learnt . Namely you can use Euler's method or Taylor series method or Runge Kutta method of order 2 or order 4 and compute the solution at the points at which you require the information.

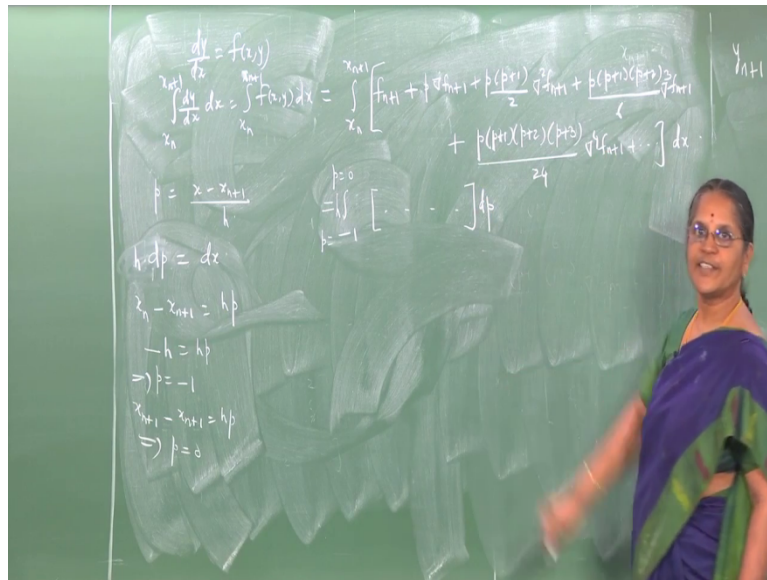
So step 1 would be to collect information at a set of previous four points once you have that information now use this method to obtain the value of $y(x_{n+1})$ which is denoted by y_{n+1} because you know every value with the help of the information that you have computed and hence you can compute y_{n+1} .

So this is a multi step method because the value at x_{n+1} which is y_{n+1} is obtained by having information or knowledge about the solution at the previous points which can either be given to you a priori or you will have to compute using the single step methods which you have already learned. And using those information at the previous points you can

use this method and compute what y_{n+1} which is the value of y at x_{n+1} and it is an approximation to the value of y at x_{n+1} . So it is a multistep method.

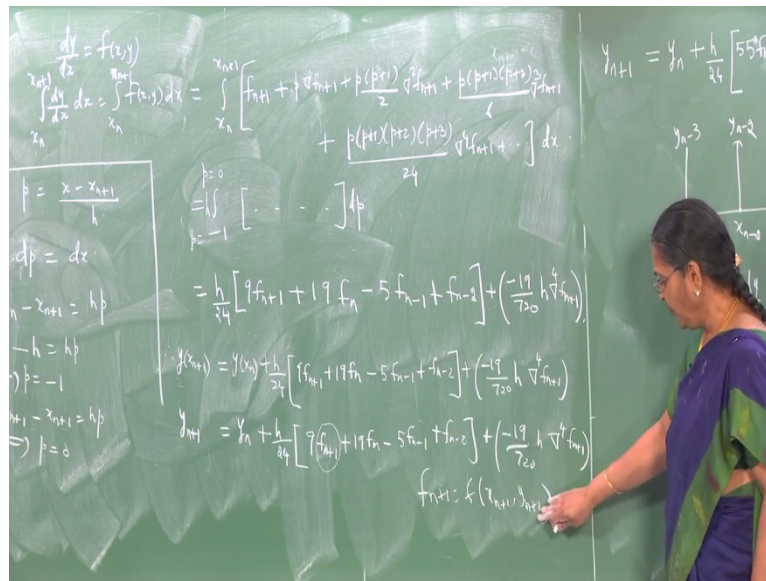
So now we shall derive another multi step method which the calculations the arguments and the discussions are analogous to this so I will not be doing in detail these calculations I will just indicate the method and present what finally the method is and then tell you how we can use the method that we have derived now and the one that we are going to derive now can be used as a Predictor Corrector pair and solution to a particular problem can be obtained correct to the desired degree of accuracy.

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Here p is x minus x_{n+1} by h this derives you dp into h is dx . So when x is x_n you have $x_n - x_{n+1}$ to be hp . So minus h is hp so p is minus 1, then x is x_{n+1} then this gives you p equal to 0. So the limits of integration are p is equal to minus 1 to p is equal to 0 of the terms within this bracket and integration is now with respect to p . So you have to work out the details of this integration we shall give you the result.

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So we have $y(x_{n+1})$ will be equal to $y(x_n)$ plus h by 24 into $[9f_{n+1} + 19f_n - 5f_{n-1} + f_{n-2}]$ plus $(\text{minus } 19 \text{ by } 720 \text{ times } h \text{ into } \nabla^4 f_n \text{ plus } 1)$. And since we have approximated the function $f(x,y)$ by means of backward interpolation polynomial about x_{n+1} we obtain an approximation to the value of $y(x_{n+1})$. So we have y_{n+1} to be given by $y_n + h$ by 24 into the terms which are written here.

So let us look at this method that we have derived. Again we observe that it is a multi step method it requires the knowledge of the solution at x_n which is y_n at x_{n+1} which will be y_{n+1} only then we can compute what f_{n+1} is namely f_{n+1} is $f(x_{n+1}, y_{n+1})$ and we already have seen f_n is $f(x_n, y_n)$ f_{n-1} is $f(x_{n-1}, y_{n-1})$ and f_{n-2} is $f(x_{n-2}, y_{n-2})$.

Now we see that the left hand side gives you y_{n+1} and on the right hand side we have f_{n+1} which requires the knowledge of what y_{n+1} is. We are only trying to get what y_{n+1} is but that involves the knowledge of y_{n+1} in getting f_{n+1} .

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From where do we get it we make use of the y_{n+1} that we already derived in the earlier method. Recall this is the method that we had derived earlier. Where we are able to write down what y_{n+1} is when we have information at a set of previous points. So we use this y_{n+1} obtained using this method in evaluating at f_{n+1} is, then we know what f_{n+1} is of course the other values can be computed with the available information.

So we obtain the value of y_{n+1} this is the second time that we get y_{n+1} at x_{n+1} for the same problem governed by the differential equation. We used the method which we derived earlier to get y_{n+1} that is used here and in turn f_{n+1} is used here and that gives you a new value of y_{n+1} , so we say that we have corrected the value of y_{n+1} by the new method that we have derived and this was done by using the y_{n+1} obtained by the earlier method as a Predicted value.

So I call this as a predictor and the method that we have obtained now as a corrector. So how do I get f_{n+1} ? It is $f(x_{n+1}, y_{n+1})$ is nothing but the predicted value obtained from the predictor. So thus we have a predictor corrector pair for solving an initial value problem dy/dx is equal to $f(x,y)$.

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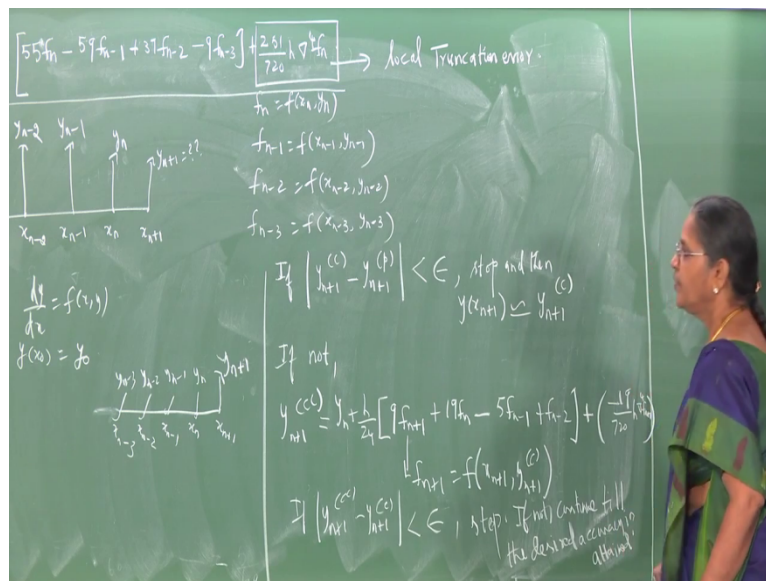


So let us write down what the corrector is. This is given by y_{n+1} corrector is this expression. So my predictor is this and my corrector is going to be this again I observe that the last term gives me the local truncation error in this multi step method. Another observation just look at the local truncation errors in both the methods, right?

So you observe that the local truncation error in the predictor method is several times that in the corrector method and therefore the error that is incurred by using this method in predicting the value of y_{n+1} is corrected using the corrector method. In addition the corrector method can be used successively to re-correct our solution till the desired degree of accuracy is attained.

How do we do it? We are given a problem dy/dx and we are given enough information that is required to compute y_{n+1} using the predictor. Once the predictor is obtained we use it here and correct it. At this stage we check whether the difference in absolute value between the corrected value and the predicted value is less than Epsilon which is the desired degree of accuracy.

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So let us write down the details. So what do we do at this stage? At this stage we check whether y_{n+1} obtained using the corrector minus y_{n+1} obtained using the predictor is less than Epsilon. If so then we stop and then take this y_{n+1} corrected value as approximating $y(x_{n+1})$. Stop and take the solution as approximating $y(x_{n+1})$ which is given by y_{n+1} corrector value.

If suppose this does not happen then what do you do? you use the corrector once again and get the second corrected value how do you use it? The second corrected value is going to be $y_{n+1} + h/24 [9f_{n+1} + 19f_n - 5f_{n-1} + f_{n-2}] + (-h^4/720) f_{n+1}^{(4)}$.

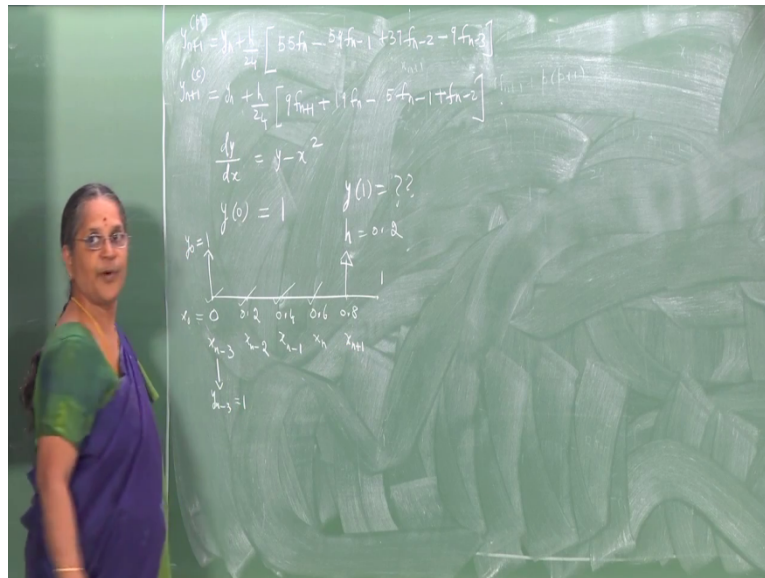
Here the f_{n+1} is going to be $f(x_{n+1}, y_{n+1})$ but which (y_{n+1}) will you use? You have the first corrector value there that is what you are re-correcting so you compute y_{n+1} double corrector value by evaluating f_{n+1} making use of the first corrected value of y_{n+1} . The rest of terms will be the same there wont be any change the only change that will occur in this will be at f_{n+1} which is now $f(x_{n+1}, y_{n+1}^{(c)})$ first corrector value.

What you do now? You check wheter y_{n+1} double corrected value minus y_{n+1} first corrector value is less than Epsilon if then stop if not continue this process if not continue re-correcting your solution every time computing what is f_{n+1} by making use of the value of y_{n+1} obtained at that corrected step and then evaluate the new y_{n+1} which is the

corrected value till the desired degree of accuracy is attained if not continue till the desired accuracy is attained.

So the Predictor Corrector method helps you to obtain the solution of dy by dx is equal to $f(x,y)$ correct to the desired degree of accuracy by using the Predictor to predict the value and then you can successively recompute using the corrector till accuracy is attained. So I am sure you have been able to understand the details in the derivation of this Predictor Corrector Method this pair the Predictor and the Corrector together is known by Adam Moulton Predictor Corrector Method or it is also called a Predictor Corrector pair.

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Let us illustrate Adam Moulton Predictor Corrector Method for solving a differential equation. So consider differential equation dy by dx which is equal to y minus x square. And the information given to you is $y(0)$ equal to 1. The question is find the solution of this initial value problem at x is equal to 1 by taking step size as 0.2

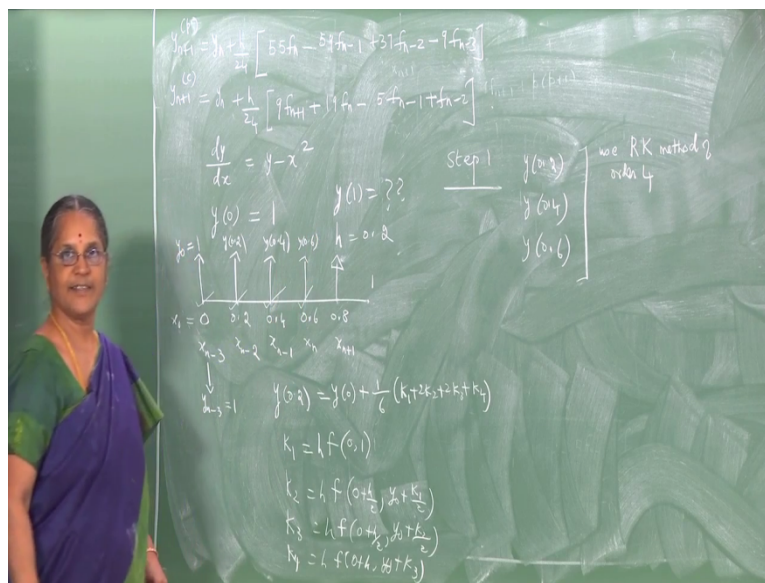
So we are given a solution at zero in the form an initial condition. So this is x if I call this as say x_0 $y(x_0)$ is y_0 and that is given to be 1. And I require the solution at 1 and I am asked to go in steps of h which is 0.2. So let us mark these points 0.2 0.4 0.6 0.8 and 1. And I am asked to use Adams Predictor Corrector method.

So I can compute the solution y_{n+1} and predict it if I know information at x_n , x_{n-1} , x_{n-2} , x_{n-3} . So I require information at 4 points. So I have information given here, so if I know information at these four points then I can evaluate the value at this point

using the Predictor. So instead I shall denote this y_{x_n+1} so 0.6 will be x_{n+1} 0.4 will be x_{n-1} 0.2 is x_{n-2} and 0 will be x_{n-3} .

And therefore what is the corresponding value of y it is y_{n-3} since x_{n-3} is 0 y_{n-3} is 1 that is already given to me. So I need to now get the solution at these points 0.2 0.4 and 0.6. Only when I have information at all the 4 points I can use the predictor and get the solution at these point and then use the corrector to correct it. So my goal now would be to compute the solution at 0.2 0.4 and 0.6 .

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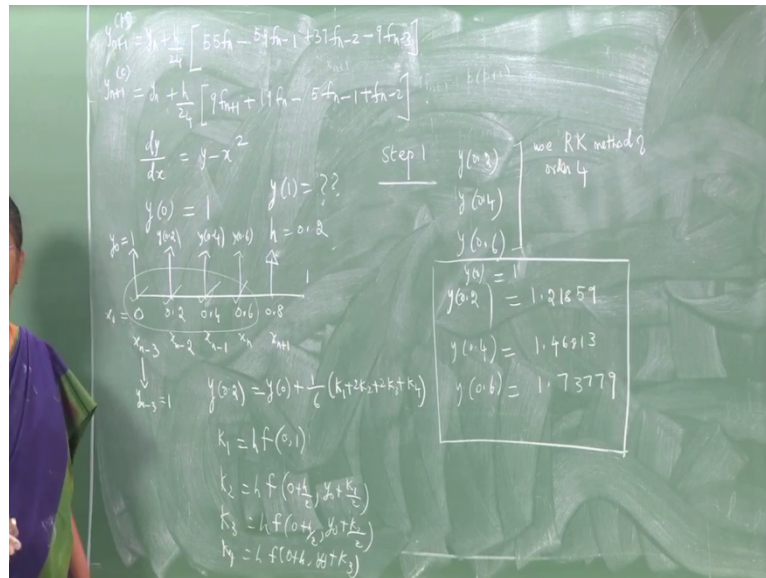
So step 1 so given a problem write down what are all the information that you gather from the given problem and what is it that we require? That is your first step. And then continue in your first step the computation of whatever is required so we require solution at 0.2 solution at 0.4 and at 0.6. So how do you get this? These solutions can be obtained using say Runge Kutta Method of order 4. How do you do it ? You know the solution at this point so I march one step ahead and compute the solution by Runge Kutta method at this point isn't it?

What is it/ So I require y at 0.2 What does Runge Kutta method of order 4 says? It says it is $y(0)$ plus $1/6$ into $(k_1 + 4k_2 + k_3 + k_4)$. What is k_1 ? k_1 is h into $f(x_0, y_0)$. So 0 what y_0 ? It is 1 and what is k_2 ? k_2 is h into $x_0 + h/2, y_0 + k_1/2$ and k_3 is h into $x_0 + h/2, y_0 + k_2/2$ and finally k_4 is h into $(x_0 + h, y_0 + k_3)$.

So I know what the function is given to me, what are x_0, y_0 which are 0 and 1 so I can compute k_1, k_2, k_3, k_4 substitute here and arrive at what $y(0.2)$ is? So once $y(0.2)$ is

obtained then again I use Runge Kutta Method of order 4 I march one step ahead and find the solution at 0.4 and that is $y(0.4)$, I do the same thing and obtain the solution at 0.6. So please carry out the details of these computations I will give you the results namely the values of these points and then we move on with using the Predictor corrector method to obtain the solution at 0.8.

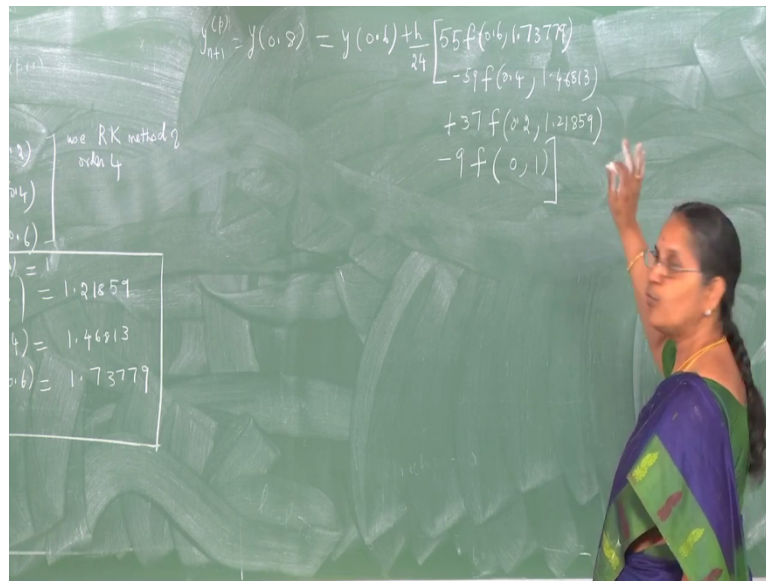
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When we do it by Runge Kutta method we get $y(0.2)$ to be given by 1.21859 $y(0.4)$ is given by 1.46813 $y(0.6)$ is 1.73779 and we already know that $y(0)$ is 1. So we have the solution obtained using Runge Kutta method of order 4 at these three points and this is an initial condition that is given in the problem.

So we have information at all these four points which is needed to obtain the solution at the point 0.8 using Predictor Method. What does the Predictor method say this is a Predictor. That is y_{n+1} so I have called this as y_{n+1} so the value of y at this point is what is denoted by y_{n+1} .

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So y_{n+1} Predicted will give me $y(0.8)$ according to minution and that is equal to $y(n)$ what is y_n it is going to be $y(0.6)$ and then plus h by 24 into 55 times f of what is f_n it is $f(x_n, y_n)$ x_n is 0.6 what is y_n ? We have just now obtained its value that is 1.73779.

Then the next term minus 59 into f of what is f_{n-1} it is x_{n-1} y_{n-1} so it is $f(0.4)$ what is y_{n-1} we have computed it to be 1.46813 then the next term is 37 f_n minus 2 and f_{n-2} is $f(x_{n-2}, y_{n-2})$ so it is $f(0.2)$, What is the value at 0.2? 1.21859 and the last term minus 9 times f_{n-3} . Our $n-3$ is 0 and value there is 1 so it is $f(0, 1)$ so it is always better to write down using the formula what is it that you want and then evaluate these functions at these points and then simplify to get the answer.

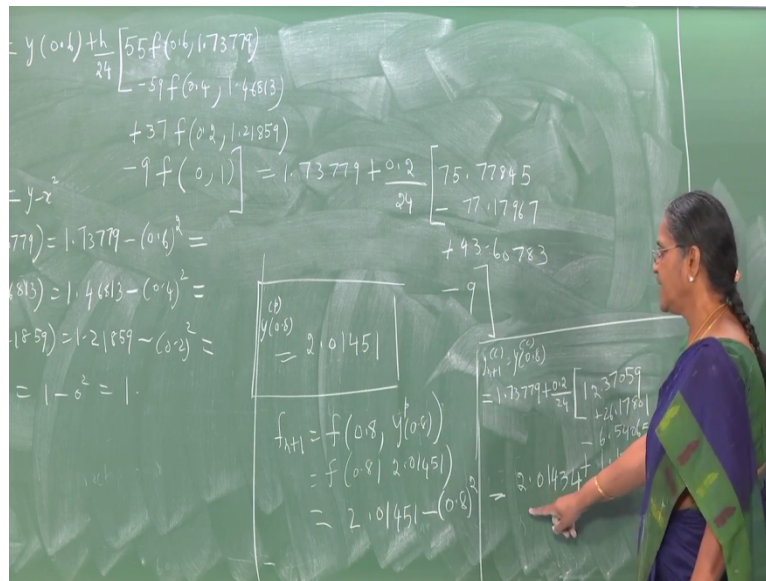
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$$y_{n+1} = y(0.6) + \frac{h}{24} \left[55f(0.6, 1.73779) \right. \\
\left. - 57f(0.4, 1.46813) \right. \\
\left. + 37f(0.2, 1.21859) \right. \\
\left. - 9f(0, 1) \right] = 1.73779 + \frac{0.2}{24} \left[75.77845 \right. \\
\left. - 77.17967 \right. \\
\left. + 43.60783 \right. \\
\left. - 9 \right] \\
f(x,y) = y - x^2 \\
f(0.6, 1.73779) = 1.73779 - (0.6)^2 = \\
f(0.4, 1.46813) = 1.46813 - (0.4)^2 = \\
f(0.2, 1.21859) = 1.21859 - (0.2)^2 = \\
f(0, 1) = 1 - 0^2 = 1 \\
\boxed{y(0.8) = 2.01451}$$

So let us find out what is $f(x,y)$ a problem tells you that $f(x,y)$ is y minus x square so you require $f(0.6)$ 1.73779 so it is 1.73779 minus x square so (0.6) square then $f(0.4)$ 1.46813 so it is 1.46813 minus (0.4) square; $f(0.2)$ 1.21859 so 1.21859 minus (0.2) the whole square and $f(0)$ 1 and that will be 1 minus 0.

I substitute these values in this formula and that gives me $y(0.6)$ which is 1.73779 h is 0.2 by 24 into 55 times $f(0.6)$ 1.73779 which is this value I have to take 55 times this value and that turns out to be 75.77845 the next value is 77.17967 and 43.60783 and finally we have minus 9. And if you simplify this further it turns out to be 2.01451 this is your $y(0.8)$ and that is what is predicted. Having predicted the value at 0.8 we would like to correct it using the corrector.

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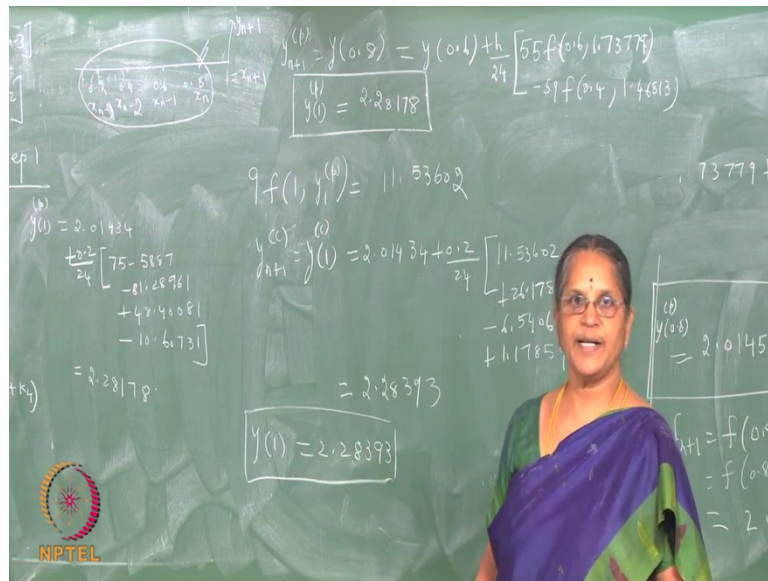


So before using the formula just find out what is this f_{n+1} . What is f_{n+1} ? Here is f_{n+1} is going to be f evaluated at x, y what is x it is 0.8 what is y ; y is $y(0.8)$ that is predicted. So it is $f(0.8)$ 2.01451, but $f(x,y)$ is y minus x square so 2.01451 minus (0.8) the whole square. So compute that f_{n+1} first.

Let us now use the corrector and write down the corrected value so y_{n+1} corrected is $y(0.8)$ corrected value and that is equal to y_n which is 1.73779 plus 0.2 by 24 into f_{n+1} which is this and that turns out to be 12.37059; then the next term is 19 times f_n which is 26.17801; then the third term minus 5 f_n that is 6.54065 and finally plus 1.17859 which is f_n minus 2 and that turns out to be 2.01434 this is the corrected value of $y(0.8)$ the predicted value is 2.01451 and the corrected value is 2.01434.

If I require that my solution is correct to two decimal places I observed the predicted value is 2.01 and the corrected value is also 2.01 so the desired degree of accuracy is attained at this step that is not the end of the problem. What is it that we want? We require the solution at 1 the question is compute the solution at 1. So what does that mean?

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We require the solution at 1 so I should call this as x_n plus 1. In order to obtain solution at x_n plus 1 which is 1 we require information at the previous 4 points and they are available. The value at this point was just now computed using the Predictor Corrector Method and so we again work out the details as before. Use the predictor and predict this value and then successively use the corrector and obtain the solution correct to the desired degree of accuracy.

So I leave this as an exercise I will give you the answers you can work out the details yourself. The Predicted value turns out to be $y(1)$ predicted turns out to be 2.28178 I can give you the step just before the final answer so that you can check the details your self. y_1 predicted value is 2.01434 plus 0.2 by 24 into [75 plus 0.5887 minus 81.28961 plus 48.40081 minus 10.60731] and that turns out to be 2.28178 that is what I have given.

Now I would like to correct this value using the corrector that requires information of f at this point so $f(x_n$ plus 1) (y_n plus 1) that is $y(1)$ predicted is required and I also have to multiply it by 9 in the formula. So I take 9 times this and the value turns out to be 11.53602. Once I have the f_n plus 1 value I use the corrector so y_n plus 1 corrected is $y(1)$ corrected and that turns out to be 2.01434 plus 0.2 by 24 into 11.53602 plus 26.17801 minus 6.54065 plus 1.17859 and the result is 2.28393.

So this is the corrected value at 1 and the Predicted value at 1 is 2.28178 and we observe that if we demand two decimal place accuracy then the difference between the solution of the

corrected value and the predicted value is less than the prescribed tolerance and so we have been able to obtain the solution correct to the desired degree of accuracy namely 2.28.

So in the next class we shall derive another predictor corrector method which is known as Milne's Predictor Corrector Method and the computation details are analogous to what we have done here in this case in deriving Adam Moulton Predictor Corrector method we approximated $f(x,y)$ by using backward interpolation polynomial by Newton, whereas in Milne's Predictor Corrector method we shall approximate $f(x,y)$ say by using forward interpolation polynomial by Newton and obtain a Predictor Corrector pair known as Milnes Predictor Corrector pair.

So we shall continue our discussion about this Predictor Corrector method in the next class.