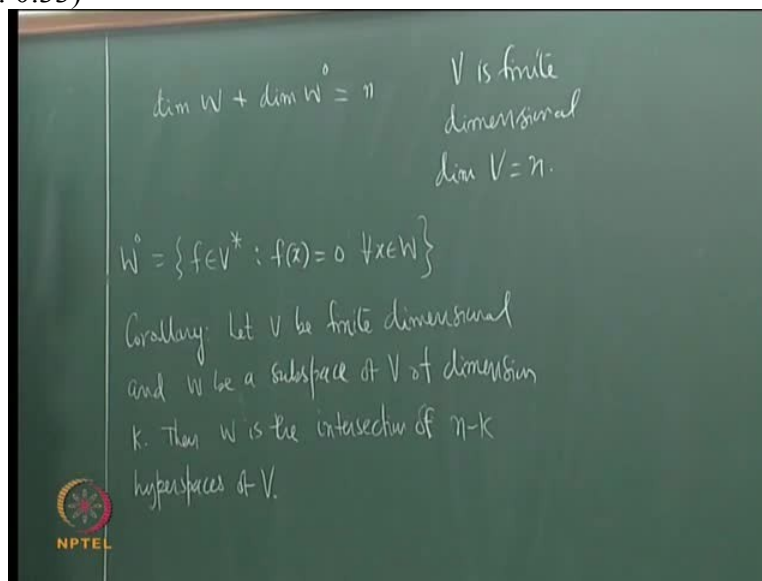


Linear Algebra
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Module no 06
Lecture no 23
Subspace Annihilators II

So we are discussing the notions of dual basis, dual spaces annihilators. Later we will discuss the double dual, the transpose of a linear transformation, okay?

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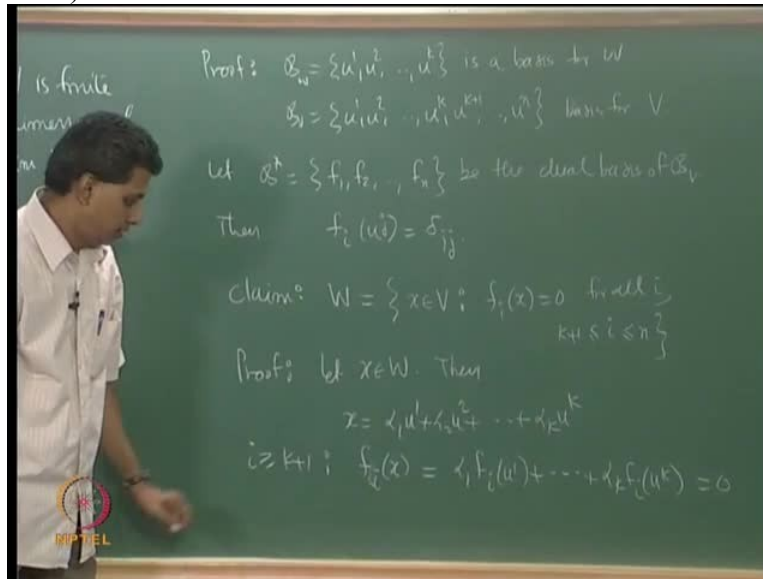


Last time, we had proved the following result that dimension of $W +$ dimension W not equals N . We are assuming that V is finite dimensional. Okay, V is finite dimensional and W space of V . Then this holds where W not is the annihilator of W . So I am just recalling the definition. W not is the set of all set of all functionals, set of all linear functionals on V that take each X and W to 0. This is W not, called the annihilator of W . And I was going to state two consequences, the 1st one, 1st one is the following. Let V be finite dimensional and W be a subspace of V of dimension K .

Then W is the intersection of $N - K$ hyperspaces. W is the intersection of $N - K$ hyperspace of V . What is a hyperspace of a vector space? Any subspace of thy mention one less than the dimension of the space V . That is called a hyperspace. So one of the consequences of really not

this result but the proof of this result okay. So let me only take the 1st few steps of the proof of the previous theorem. From that, we will derive the fact that this W is the intersection of $N - K$ hyperspaces. Okay.

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So recall the proof. The 1st few lines is the proof of the previous theorem. Dimension W + dimension W not equal to N . Let us say, W is, W has this as a basis. V equals U_1, U_2 , et cetera, U_K . This is a basis for W and what we did was to extend this to a basis for V . I will call this B_W B_V . B_V is U_1, U_2 , et cetera, U_K, U_{K+1} et cetera U_N . The dimension of V is taken to be N . This is the basis for V and then what we did was to construct a dual basis for this. Let B^* equals f_1, f_2 , et cetera, f_N be the dual basis of B_V . Then how are these functional and these vectors related? By definition, we must have $f_i(u^j)$ equals Δ_{ij} . Okay? In this notation, I will make the following claim.

So let us look at the following. The claim that I am making here is that the subspace W is the set of all X and V such that $f_i(X)$ equal to 0 for all $i, K + 1$ less than or equal to i less than or equal to N . Remember, this W is a subspace of V of dimension K . I am trying to describe this W in terms of V . Linear functionals f_{K+1}, f_{K+2} , et cetera, f_N okay? Suppose, let us say I have proved this claim. Then can you see that this is okay what is this again? This is the set of all X for that $f_{K+1}(X)$ equal to 0, $f_{K+2}(X)$ equal to 0 et cetera, $f_N(X)$ equal to 0.

This is a set of all X that lie in the intersection, F_{K+1} , null space of F_{K+2} , et cetera, null space of F_N . That is, if I had proved this, then it would follow that W is intersection null space F_I , I equals $K+1$ to N . Intersection of null spaces of linear functionals. Each linear functional has a property that the null space is one-dimensional. Okay? Null space is $N-1$ dimensional. Range is 1 dimensional, null space is $N-1$ dimensional. So each linear functional has a property that the null space is the hyperspace. I have written this as a intersection.

Actually $N-K$ sub $K+1$ to N . $N-K$ intersection of $N-K$ hyperspace is. Okay? So we need to only prove this. Is that clear? Suppose we prove this, then it follows that W is the intersection of $N-K$ hyperspaces. It is clear that it is the intersection of $N-K$ subspace is but each subspace is null space of a linear functional. Each is a subspace of a null space each subspace is a null space of a nonzero linear functional. Null space of a nonzero linear functional is $N-1$ dimensional. And so it follows that this W is the intersection of $N-K$ hyperspaces.

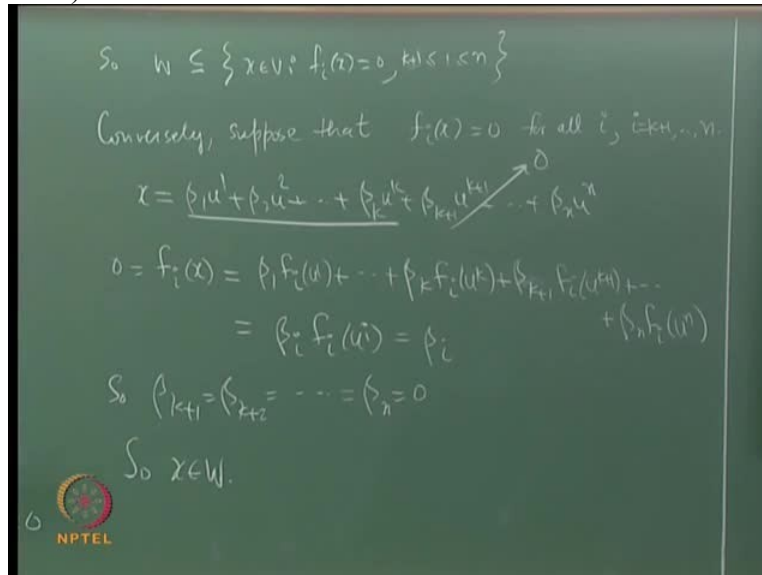
So we need to only demonstrate this. Okay. So let us prove this. One is obvious but I will prove both. I have 2 sets, A equals B . Imus so A contained in B and B contained in A . Okay, let us start with, so we need to prove this claim now. So let me take X and W . I must show that this X has the property that whenever I is greater than or equal to $K+1$, F_I of X is 0. Let X element of W . Then for W , I have taken this as a basis. So this X can be written as $\alpha_1 U_1 + \alpha_2 U_2$, et cetera $+ \alpha_K U_K$. Look at I greater than or equal to $K+1$ and then F_I of X . I greater than or equal to $K+1$ F_I of X .

Remember, I need to show that F_I of X is whenever I want to show left-hand side containing the right-hand side, I must show that if X belongs to W , then $F_{K+1} X$ is 0, $F_{K+2} X$ is 0, et cetera, F_N of X is 0. So I take I to be greater than or equal to $K+1$. I must or, this is 0 okay but F_I of X , F is, F_I is linear. So this is $\alpha_1 F_I$ of U_1 , et cetera $+ \alpha_K F_I$ of U_K . I have just used linearity of F_I okay but remember that this is a F_1, F_2 , et cetera, F_N is a dual basis and so whenever I is greater than or equal to $K+1$ each of this is 0 because look at this indices. You get from U_1 , et cetera up to U_K .

So when I is equal to $K+1$ or more, I is not equal to J . So each term is 0. So this is 0. I is greater than or equal to $K+1$. So F_I for any U_J when J is less than or equal to K is 0. That is the

definition. So FI of X is 0. So what we have shown is that the left-hand side, W is contained in this subset.

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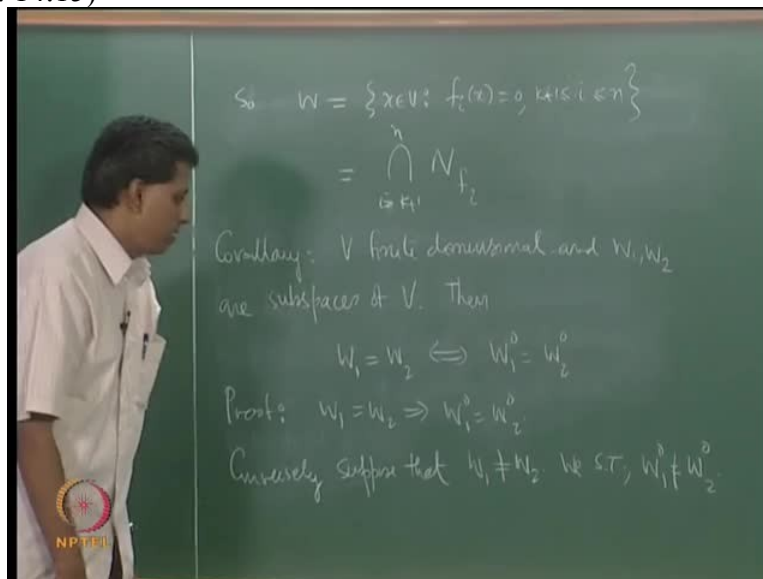
So W is contained in set of all X and V such that FI of X equal to 0 for all I satisfying we need to show the converse. Conversely suppose that FI of X is equal to 0 for all I, I running from K + 1 to N, suppose X is a vector that belongs to the right-hand side subset right-hand side subspace, I must show that X belongs to the left-hand side W. Now X is an arbitrary element. So I can write X using this basis. So let me use some other scalars. X is a linear combination of U1, et cetera, UN. So X is beta 1 U1 + beta 2 U2, et cetera + beta K UK + beta K + 1 UK + 1, etc, beta N UN. U1, U2, et cetera, UN is the basis for V and so I can write X in this manner.

FI of X is 0. So I start with 0, that is FI of X. FI of X, FI is linear. Beta 1, FI of U1, et cetera + beta K FI of UK + et cetera. Okay let me write the next term also. Beta K + 1 FI of UK + 1 + et cetera + beta N FI of UN. After applying FI, I get this. For each I running from K + 1 to N, X must satisfy FI of X is equal to 0. But look at what we have on the right-hand side. On the right-hand side, there is only one term that remains because FI of UJ is that the IT. What is that term? see, I runs from K + 1 to N, I is fixed okay. And so, this is FI of UI, all other terms are 0, all other terms are 0. Beta I FI UI but FI UI is 1.

So this is beta I. So what have we shown? We have shown that if $f_i(x)$ is equal to 0 then beta I is equal to 0 but what are the values that I can take? I takes, I runs from $K + 1$ to N which is beta $K + 1$ is 0, beta $K + 2$ is 0, et cetera. So what we have shown is that beta $K + 1$ equals beta $K + 2$, et cetera equals beta N equal to 0. So go back and look at the representation for X . Look at the representation for X . X is beta 1 U_1 , et cetera. From $K + 1$ th term onwards, they are all 0. So X is just this. This term is 0. The representation of X . The scale is corresponding to $B_{K + 1}$ et cetera, they are all 0.

That is what we have shown because see this $f_i(x)$ is equal to 0 for all i running from $K + 1$ to N . So the scale is beta i bring from $K + 1$ to N R^0 . So X is a linear combination of U_1 , et cetera U_K but then that is U_1, U_2 , et cetera, U_K is a basis for W . So this X must belong to W . So I have started with an arbitrary vector on the right-hand side subset. I have shown that that belongs to W . So right-hand side subspace is contained in the left-hand side subspace. So W is equal to this and hence the theorem, corollary. Let me just write one more step to make the final part transparent.

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Let me write that here. So what we have done is W is the set of all X and V such that $f_i(x)$ is 0 for all i running from $K + 1$ to N . Now you see that this is the intersection of the null space of f_i for i running from $K + 1$ to N . Anything on the right-hand side must be in the null space of f_i for each i running from $K + 1$ to N . So this is, and there are $N - K$, this intersection has $N - K$ terms.

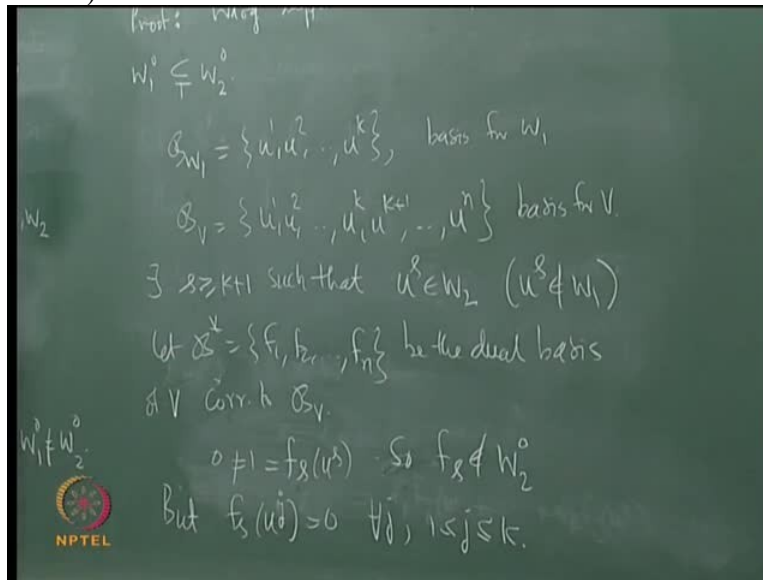
So there are $N - K$ subspaces. Each is a subspace of non-zero linear functional. So each subspace is dimension $N - 1$, null space of F , that is $N - 1$.

So I have written W as an intersection of $N - K$ hyperspaces okay. That is the complete proof of this corollary. There is another corollary which talks about the relationship of 2 subspaces and their annihilators really. So 2nd corollary V is finite dimensional and W_1, W_2 are subspaces of V , then W_1 is equal to W_2 if and only if their annihilators are equal. $W_1^\perp = W_2^\perp$. 2 subspaces are equal if and only if their annihilators coincide. This again uses the proof of the previous theorem out of which one part is easy. If S is equal to P , then annihilator of S is equal to annihilator of P .

That is easy to see. So $W_1 = W_2$ implies $W_1^\perp = W_2^\perp$. Annihilators must be the same okay. It is a converse that is nontrivial here. To prove the converse, to prove the converse what we will do is assume that W_1 is not equal to W_2 , show that $W_1^\perp \neq W_2^\perp$. Conversely let us suppose that $W_1^\perp \neq W_2^\perp$. We will show that we show that $W_1 \neq W_2$. This is really the converse because what is the meaning of this? $W_1^\perp \neq W_2^\perp$ implies $W_1 \neq W_2$. This is the same as saying $W_1^\perp = W_2^\perp$ implies $W_1 = W_2$. That is a converse. If A implies B then not B implies not A .

That is what we are using. The statement A implies statement B . The negation of statement B implies negation of statement A . So if we demonstrate $W_1^\perp \neq W_2^\perp$ implies this, then it follows that if this statement is not true, then negation of this statement is true. So it follows that if this is not true, that is $W_1^\perp = W_2^\perp$ implies $W_1 = W_2$ which is really the converse okay. So let us prove this. Now W_1 is not equal to W_2 . They are subspaces. So as sets, they are not equal. So one is not contained in the, at least one of them is not contained in the other. For the sake of using this notation, let me assume that W_2 is not contained in W_1 okay. Okay.

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I am saying without loss of generality. So this is what I am going to prove. I am going to prove that $W_1 \not\subseteq W_2$ implies $W_1^0 \not\subseteq W_2^0$. Without loss of generality, let us assume that W_2 is not contained in W_1 . Okay? We show that W_1^0 is not contained in W_2^0 . Okay. If W_1 were not contained in W_2 , one could show that W_2^0 is not contained in W_1^0 by a similar argument. So there is no loss of generality in assuming W_2 is not contained in W_1 . Now I will have to go back to the previous notation. For W_1 , let me take u_1, u_2, \dots, u_k as a basis. I am calling that B_{W_1} . This is the basis for W_1 .

This can be extended to a basis for V . Okay, as before, I am assuming that V is N dimensional. So there are N vectors here. This basis has been extended to a basis for V . If W_2 is not contained in W_1 , what means is that there is a vector in W_2 which is not in W_1 okay. Is it clear then that there exists s greater than or equal to $k + 1$ such that u_s belongs to W_2 , obviously u_s does not belong to W_1 . Do you agree with this? W_2 is not contained in W_1 . W_1 has u_1, u_2, \dots, u_k as the basis. So anything in W_1 is spanned by these vectors.

Now you take u_s where s is not 1 to k . So s is greater than or equal to $k + 1$. If all of these vectors belong to W_1 , then W_1 is the whole of V in which case this cannot happen. W_2 is a subspace. So there is at least one s for which u_s does not belong to W_1 but those u_i that belong to W_1 are indexed by 1 to k . So if there exists a u_s that does not belong to W_1 , it must be corresponding to an index that is greater than or equal to $k + 1$. So there exists u_s where s is,

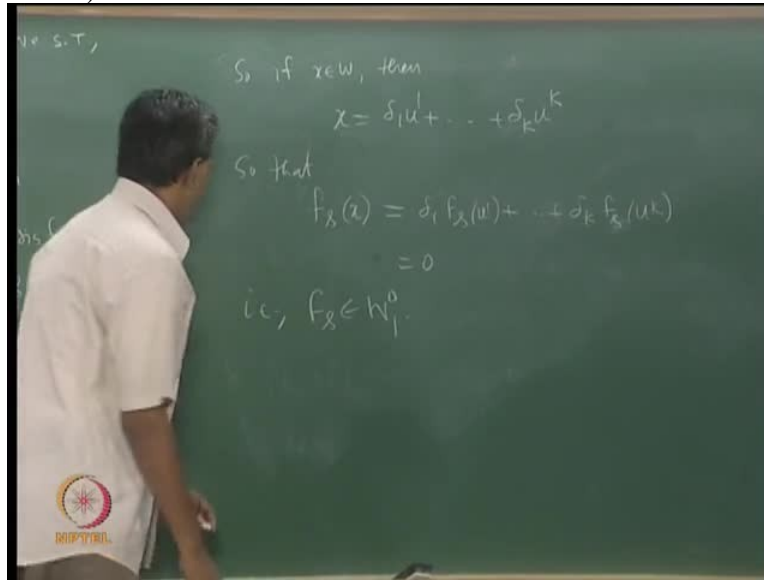
there exists S greater than or equal to $K + 1$ such that U_S does not, sorry U_S does not obviously belong to W_1 but it belongs to W_2 okay.

Now look at the functional f_S . That will do what we require here. Look at the functional f_S . I have now constructed dual basis. Let B^* equals f_1, f_2, \dots be the dual basis of V corresponding to the dual basis B corresponding to B . Then as before, f_i of U_j equals δ_{ij} . I am just calling your attention to f_S . Look at f_S . f_S of U_S we know by definition must be equal to 1. Okay. And that is not 0. It means f_S cannot belong to, see U_S belongs to W_2 . And f_S is the functional that takes U_S to a nonzero value. So f_S cannot belong to W_2 .

f_S does not belong to W_2^0 . W_2^0 is the set of all functionals that takes all elements in W_2 to 0. I have produced one element in W_2 which is taken to a nonzero value by the functional f_S . So f_S does not belong to W_2^0 but obviously f_S belongs to W_1 . Why? But f_S of U_j , I will use J . f_S of U_j equals 0 for all J such that $1 \leq J \leq K$ by the definition of the dual basis because J runs from 1 to K , S is greater than or equal to $K + 1$, so J can never be equal to S . J runs from 1 to K , S is greater than or equal to $K + 1$. So S is never equal to J .

So this is 0. In other words, f_S of U_1, f_S of U_2, \dots they are all 0 which means f_S belongs to W_1^0 because anything in W_1^0 is a linear combination of these and so if I apply the linear functional f_S to that vector, that will take the value 0. Should I elaborate?

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Okay, let me do that quickly. So if X belongs to W , then X is some linear combination of these UKs so that FS of X is what I want. FS of X is Δ_1 FS of U_1 , et cetera Δ_k FS of U_k . Each term is 0. So this is 0. That is FS belongs to W_1^0 . So remember I, that is what I wanted to show. If W_2 is not contained in W_1 , I wanted to show W_1^0 not contained in W_2^0 . I have a functional that belongs to W_1^0 . I have a vector or a functional that belongs to W_1^0 but that is not in W_2^0 . FS is not in W_2^0 . And so this holds and so the converse holds.

Okay. So W_1^0 equals W_2^0 implies W_1 must be equal to W_2 . If the annihilators coincide then the corresponding subspaces, only for subspaces, the subspaces must coincide. By the way, this formula does not hold if you take arbitrary subsets. If W_1 is a subset, W_2 is a subspace. Then W_1^0 could be equal to W_2^0 without W_1 being equal to W_2 . The underlying subsets must be subspaces. Okay? Okay. To consolidate, let us look out to example. To consolidate the ideas of dual base annihilators and then determining elements in annual basis.

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are the annihilators

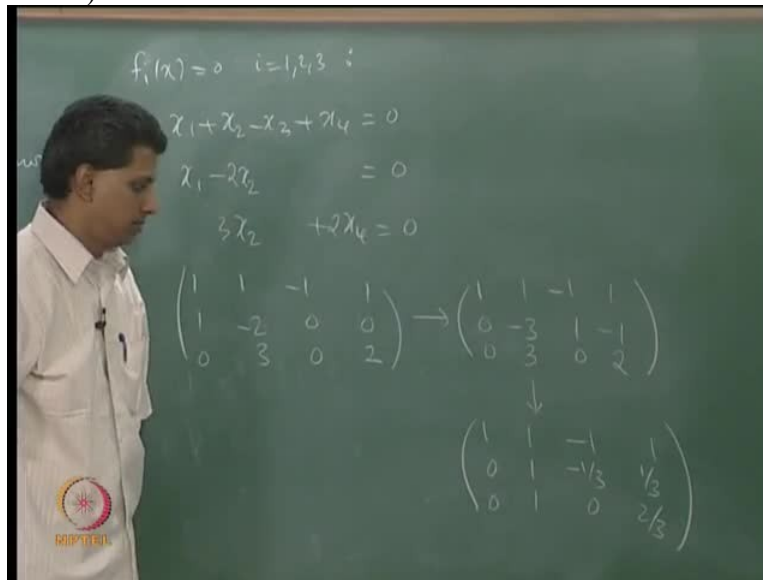
$$f_1(x) = x_1 + x_2 - x_3 + x_4$$
$$f_2(x) = x_1 - 2x_2$$
$$f_3(x) = 3x_2 + 2x_4, \quad x \in \mathbb{R}^4$$
$$\text{So } W = \{x \in \mathbb{R}^4 : f_1(x) = f_2(x) = f_3(x) = 0\}$$

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So let us consider the following examples. Let us say I have 1st one, determine the subspace of W , let us say I take \mathbb{R}^4 , determining the subspace W of \mathbb{R}^4 for which the functionals given below are the annihilators. Okay. I am given let us say 3 annihilators. I will call F_1 of X , X is in \mathbb{R}^4 . So let us say I have $X_1 + X_2 - X_3 + X_4$. F_2 of X is $X_1 - 2X_2$, F_3 of X is $3X_2 + 2X_4$. The question is, you are given functionals. These functionals annihilate a certain subspace, what is that subspace? Okay. Remember, a subspace, just now we have seen. W is equal to set of all X elements of V , I said $F_i X = 0$ for all i running from $K + 1$ to N .

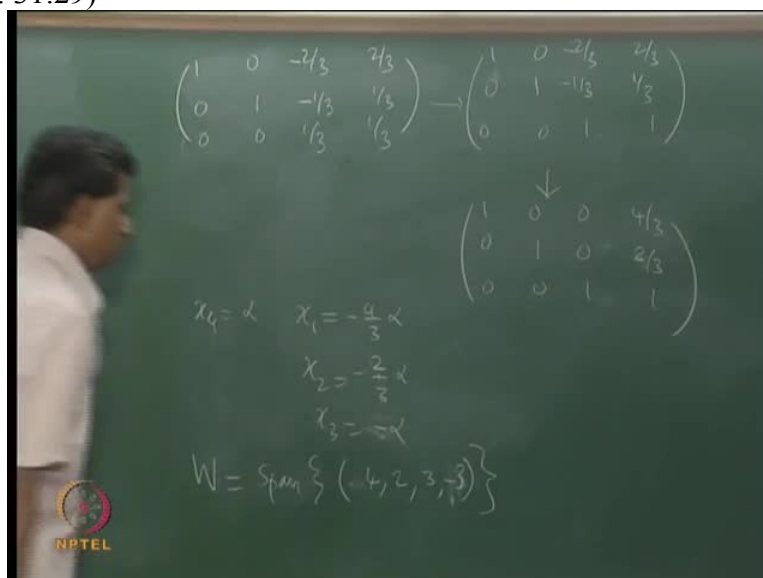
Subspaces can be given by the set of annihilators of that space. Okay. Subspace can be given using the annihilating functionals also. Okay. So we need to solve this problem. So what is the definition of W ? W is the set of all X and \mathbb{R}^4 in this case such that F_1 of X equals F_2 of X equals F_3 of X equals 0. Now what you will see is that again it is elementary row operation. Write down these 3 equations. These are homogeneous equations.

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These 3 systems give me the following. Sorry, there is only one system. $X_1 + X_2 - X_3 + X_4$ equals 0. $X_1 - 2X_2$ because 0. $3X_2 + 2X_4$ equals 0. Elementary row operations. So I have the matrix $1 \ 1 \ -1 \ 1, \ 1 \ -2, \ 0 \ 3 \ 0 \ 2$. I will apply elementary row operations to determine the set of all solutions. I will keep this as a pivot and then straightaway make this 0. Okay. Let me do it like this. I have $0 \ 1 \ -1 \ 3$ by 3 . I can divide this also by 1 . $0 \ 1 \ 0$ divide by 3 , 2 by 3 .

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$x_4 = \alpha$ $x_1 = -\frac{4}{3}\alpha$
 $x_2 = -\frac{2}{3}\alpha$
 $x_3 = -\alpha$
 $W = \text{Span} \left\{ \begin{pmatrix} -4 \\ 2 \\ 3 \\ -3 \end{pmatrix} \right\}$

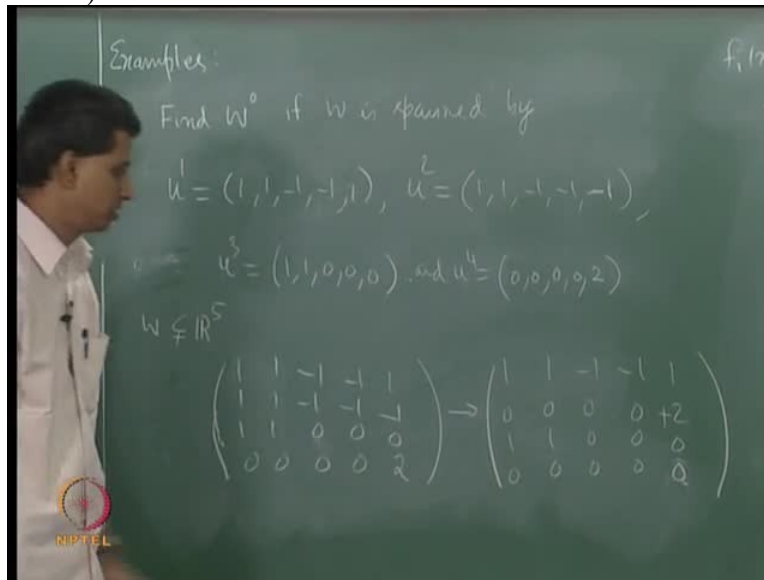
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Then keeping the 2nd, next operation will be to okay multiply this by 3. So that was unnecessary. I have 0 0 1 1. 0 1 - 1 by 3 1 by 3 1 0 - 2 by 3 2. Ya, obviously I am not doing it very efficiently but let us look at the solution. Okay so now I have a 3 by 4 system where this 3 by 3 part is the identity part. So what follows is that, remember that this came from this set. There are 4 variables. What this tells me is that I must fix the last variable, X4. So let us say X4 is Alpha, then X1 is - 4 by 3 Alpha, X2 is also - 4 by 3 Alpha, X3 is - Alpha. There is a problem with the solution.

From this step to this step, it is correct. From here to here, see, I am keeping this as the pivot row. Then 1 by 3 times this + this. So these entries, this becomes 0. 1 by 3 times this + this 2 by 3. Let me look at it once again. After this step, it is correct. Okay. So I am keeping this as fixed. Okay. Then multiply this by 2 by 3 or cancel this. 1 0 2 by 3. 2 by 3 + 2 by 3, 4 by 3. That is okay. So this entry is - 2 by 3 Alpha. Please check the calculations. So what is W then? W is one-dimensional. W is one-dimensional because it is any multiple of, so let me just say W is span of this vector. Let me multiply throughout by 3. X1 is - 4, X2 is - 2.

So let us say 4 2, X3 is multiplying throughout by 3 and - 1. I am multiplying by 3. I am multiplying by - 3. - 3, okay. 6, - 3, - 3. X1 - 2X2. So this is the subspace W which is the annihilated by these 3 functionals okay. Again, it is only solving homogeneous systems. One more problem where we will determine the annihilator.

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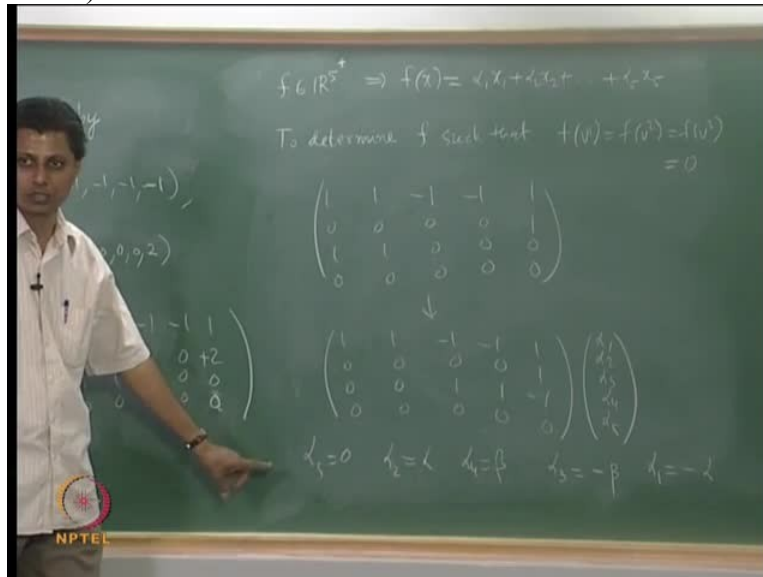
2nd example, find W^0 . Find W^0 if W is spanned by these vectors. Let us say U_1 is let me take one more. W is a subspace spanned by these 4 vectors. I am not claiming that these vectors form a basis for W . W is spanned by these set of vectors. What is W^0 , the annihilator of W ? Okay. Remember that W is a subspace of \mathbb{R}^5 . Not the whole of \mathbb{R}^5 . There are only 4 vectors here. So W is a subspace of \mathbb{R}^5 . I must find the functionals that generate W^0 . Okay. So I will determine a dual basis for a basis corresponding to, for a basis containing more for a basis contained in this set.

These 4 may not be dependent. Okay. So let us know what do we need to find? We need to find W^0 okay. So let us look at the functional F . If F belongs to W^0 , what is the condition that F must satisfy? Okay? But before that, let us look at these 4. I will again write it in the matrix form okay. $\begin{pmatrix} 1 & 1 & -1 & -1 & 1 \\ 1 & 1 & -1 & -1 & -1 \\ 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{pmatrix}$. And apply elementary row operations. W is the subspace which is the row space of this matrix. W^0 is the subspace corresponding to the row space of this matrix. Okay? Row space does not change if we do elementary row operations.

So I want to do just probably one operation. I have not reduced it to the row reduced echelon form. I will just do one of these. So $-$ this, $+$ this. I will keep this one also as it is and then observe the last one is $0 \ 0 \ 0 \ 0 \ 2$. In the next step, what could be done is these 2 could be made 0. So I will make that here itself. This could be made $+2$, does not make a difference. So this, so what is

clear is that the 4 vectors are independent, only 3 of them are independent. Dimension of W is 3. Dimension of W is 3. We need to determine W⁰. Okay.

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What we need to determine is that any functional F in R⁵ any functional on R⁵. If F belongs to R⁵ star, then F can be written as Alpha 1 X1 + Alpha 2 X2 alpha 5 X5. Any function on RN can be written as A1X1 + et cetera ANXN. So FX is of this form. I need to determine, okay I do not know how many are there. I will just keep I need to determine F such that F of, these 2 vectors, I will call them V1, V2, V3. I will call these row vectors, V1, V2,V3. I must determine all X that satisfy these 3 equations. Again, homogenous equations, okay. So let us write this. It is almost in the row reduced echelon form. So I want 1 1 - 1 - 1 1 into X1, X2, X3, X4, X5 equal to 0.

We will have to interchange. Let us say I make, I keep this as it is. So from here, I get 0. I do not really have to do it but I get a 1 here. This is not the row reduced echelon form. So let me not get into the details there. From this, I can right away tell you what these functions are. See, from this what follows is that remember, I need to determine F. So I need to determine the 5 unknowns here, alpha 1, alpha 2,et cetera alpha 5. Is that clear? I need to determine W not. F belongs to W not if satisfies this equation. These equations give me this into alpha 1, alpha 2, et cetera, alpha 5, that is equal to 0.

Now what is clear is that from this alpha 5 is 0. Is that okay? Alpha 5 is 0. Okay let me write down. 2nd equation tells me, alpha 5 is 0, 3rd equation, okay, so from this I have 3 equations in 5 unknowns. So I need to fix 2 of them. Which one do I fix? It cannot be the 3rd one, it cannot be the 1st one. And so it is the 2nd and 4th. It is the 2nd and the 4th which you get by the row reduced echelon matrix. So let me say I fix alpha 2 equals alpha. See this diagonal entry, this is 1, 2, this is 3. So these 3, these 2 will not be fixed. Alpha 5 is already 0. 1 and 3, so 2 and 4.

Alpha 4 is beta. Then determine the others. In particular, the 3rd equation gives me Alpha 3. Alpha 3 is alpha 5 - alpha 4 - beta. The 1st one should give me alpha 1. This is gone. Alpha 4 + Alpha 3. Beta + Alpha - sorry alpha 5 is 0. Alpha 4 + Alpha 3, that is 0. So Alpha 1 + Alpha 2 is 0. So alpha 1 is - Alpha okay. So can you see that the basis consists of just 2 functionals because there are just 2 variables, Alpha, beta. All the others are in terms of these.

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The chalkboard shows the following derivation:

$$f \in W^0 \Rightarrow f(x) = -\alpha x_1 + \alpha x_2 - \beta x_3 + \beta x_4$$

$$= \alpha(x_2 - x_1) + \beta(x_4 - x_3)$$

$$= \alpha f_1(x) + \beta f_2(x)$$

$$f_1(x) = x_2 - x_1$$

$$f_2(x) = x_4 - x_3$$

$$W^0 = \text{span} \{ f_1, f_2 \}$$

An NPTEL logo is visible in the bottom left corner of the chalkboard image.

Let me summarise. F belongs to W not implies F is of the form this is what I have.- Alpha X1
 Alpha 2 is alpha.+ Alpha X2. Alpha 3 is - beta. Alpha 4 is beta. Alpha 5 is 0. Alpha 5 does not figure here. Now I can write alpha and beta are, can take arbitrary values. In particular, alpha 0 beta 1, alpha 1 beta 0. So I can write this as alpha times X2 - X1 + beta times X4 - X3 which means I can write this as alpha times F1 of X + beta times F2 of X. F1 and F2 are independent functionals. F1 of X is X2, let us say - X1 + X2. F2 of X is the 2nd term, X4 - X3.

Sorry. $X_4 - X_3$. F_1 is this, F_2 is this. Any F and W not is a linear combination of these 2. These 2 are independent. These 2 are independent because you can think of F_1 as the vector $-1 \ 0$, sorry $-1 \ 1$, all other entries 0. F_2 is $0 \ 0 - 1 \ 1 \ 0$. So these 2 are independent. Okay. Okay finally W not is span of $F_1 \ F_2$. So please verify the calculations. Essentially it is solving homogeneous equations. Even remember the 1st problem when we determined the dual basis. That was solving homogenous equations. Okay. Let me stop here. Next time, let us discuss the notion is of the double dual.

Once we have done one go from V to V^* , can we go from V^* to V^{**} ? So this can be done and when we discuss the notion of double dual, we will also consider the following question which we have not dealt with before. What we know is that given a basis for V , finite dimensional case. Given a basis for V , there is a dual basis for V^* . So there is a basis for V^* where there is a natural correspondence between the basis for V that we started with and the basis for V^* that we constructed.

The other question is, given a basis for V^* , is there a basis for V such that the basis for V^* is the dual for the basis of V ? That we would consider. The answer is yes. For finite dimensional spaces, the answer is yes. For infinite dimensional spaces, the answer is no. Infinite dimensional spaces will be discussed in functional analysis. For finite dimensional spaces, we will show that the answer is yes. Okay, this is one of the main results that we will prove in the next lecture. Okay. Let me stop here.