

Advanced Engineering Mathematics

Lecture 47

Application to Mechanics

Curve in space: A curve is an aggregate of points where coordinates are function of a single variable. Thus the equations

$$x = x(t), \quad y = y(t), \quad z = z(t)$$

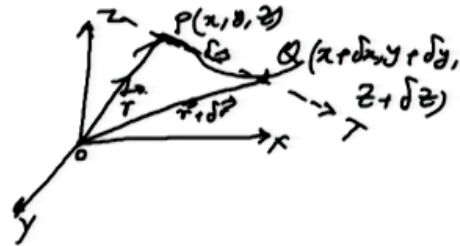
represents a curve in space and the variable “ t ” is called the parameter. For each value of $t \in \mathbb{R}$ (i.e., $a \leq t \leq b \in \mathbb{R}$), there corresponds a definite point $P(x, y, z)$ of the curve.

Example 1.

- (i) In xy -plane: $x^2 + y^2 = 25$ is a circle. $x = 5 \cos t$, and $y = 5 \sin t$ where $0 \leq t \leq 2\pi$.
- (ii) In xyz -plane: $x^2 + y^2 + z^2 = 25$ is a sphere. $x = 5 \cos \theta \cos \phi$, $y = 5 \cos \theta \sin \phi$, and $z = 5 \sin \theta$ where $0 \leq \phi \leq 2\pi$ and $0 \leq \theta \leq \pi$.

Let $\vec{r} = \vec{f}(t)$ represent the equation of a curve.
Now,

$$\begin{aligned} \vec{r} &= x \hat{i} + y \hat{j} + z \hat{k} \\ &= x(t) \hat{i} + y(t) \hat{j} + z(t) \hat{k}, \quad t \in \mathbb{R}. \end{aligned}$$



From here, we take $x = x(t)$, $y = y(t)$, and $z = z(t)$. The tangent line PT at a point P of a curve is the limiting position of the secant PQ joining P to a neighboring point Q , i.e., when Q approaches P along the curve.

$$\begin{aligned} \vec{PQ} &= \vec{OQ} - \vec{OP} = \vec{r} + \delta \vec{r} - \vec{r} = \vec{f}(t + \delta t) - \vec{f}(t) \\ \lim_{\delta t \rightarrow 0} \frac{\vec{PQ}}{\delta t} &= \lim_{\delta t \rightarrow 0} \frac{\delta \vec{r}}{\delta t} = \lim_{\delta t \rightarrow 0} \frac{\vec{f}(t + \delta t) - \vec{f}(t)}{\delta t} \\ \frac{d\vec{r}}{dt} &= \vec{f}'(t) \end{aligned}$$

That is, $\frac{d\vec{r}}{dt} = \vec{f}'(t)$ is parallel to the tangent PT of the curve $\vec{r} = \vec{f}(t)$ at P . Therefore,

$$\begin{aligned} \vec{R} &= \vec{r} + \lambda \frac{d\vec{r}}{dt} \\ \vec{R} - \vec{r} &= \lambda \frac{d\vec{r}}{dt}, \quad (\text{Equation of the tangent line}) \\ \text{or, } (\vec{R} - \vec{r}) \times \frac{d\vec{r}}{dt} &= \vec{0}. \end{aligned}$$

where λ is any arbitrary constant, \vec{r} is the position vector of the P and \vec{R} is the position of any point on the tangent line.

Example 2. Find the equation of a tangent line to the space curve $x = t$, $y = t^2$, and $z = \frac{2}{3}t^3$ at $t = 1$.

Solution: We can write $\vec{r}(t) = t\hat{i} + t^2\hat{j} + \frac{2}{3}t^3\hat{k}$. Therefore, the position of the point at $t = 1$ is $\vec{P} = \hat{i} + \hat{j} + \frac{2}{3}\hat{k}$.

$$\begin{aligned}\frac{d\vec{r}}{dt} &= \hat{i} + 2t\hat{j} + 2t^2\hat{k} \\ \left.\frac{d\vec{r}}{dt}\right|_{t=1} &= \hat{i} + 2\hat{j} + 2\hat{k}.\end{aligned}$$

Hence, the equation of the tangent line

$$\begin{aligned}((X\hat{i} + Y\hat{j} + Z\hat{k}) - (\hat{i} + \hat{j} + \frac{2}{3}\hat{k})) \times (\hat{i} + 2\hat{j} + 2\hat{k}) &= \vec{0} \\ \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ X-1 & Y-1 & Z-\frac{2}{3} \\ 1 & 2 & 2 \end{vmatrix} &= \vec{0} \\ (2Y - 2Z - \frac{2}{3})\hat{i} + (Z - 2X + \frac{4}{3})\hat{j} + (2X - Y - 1)\hat{k} &= \vec{0}\end{aligned}$$