

**Statistical Inference**  
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**Lecture - 06**  
**Basic Concepts of Point Estimations –IV**

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Efficiency of Estimators

$E|T - g(\theta)| \rightarrow$  Mean Absolute Error

$MSE(T) = E(T - g(\theta))^2 \rightarrow$  Mean Squared Error

$$= E \left[ \underbrace{T - E(T)} + \underbrace{E(T) - g(\theta)} \right]^2$$

$$= E\{T - E(T)\}^2 + E\{E(T) - g(\theta)\}^2 + 2E\{T - E(T)\}\{E(T) - g(\theta)\}$$

$$= V(T) + B^2(T) + 0$$

We can say that estimator  $T_1$  is better (more efficient) than  $T_2$  if

$$MSE(T_1) \leq MSE(T_2) \quad \forall \theta \in \mathbb{R}$$

Next we introduce the concept of efficiency. As we have seen that there can be situations where we have more than one consistent estimator, we may have more than one estimator which is unbiased as well as consistent. So, in that case, we introduce the concept of efficiency of estimators. For judging the efficiencies of the estimators we consider something called as expected error. We have seen unbiasedness; so, in unbiasedness we had expectation of  $T$  is equal to the given parametric function say  $g(\theta)$ .

So, if it is not unbiased expectation of  $T$  minus  $g(\theta)$  is a bias or you can say expected error. But in there is a danger in using one bias as a simple in a criteria for a goodness of an estimator, because sometimes the negative bias and the negative errors and the positive errors may cancel out each other. So, on the average the estimator may become unbiased, but actually it is not a good estimator.

We have seen the examples for example, in the estimation of  $e^{-\lambda}$  to the power minus 3 lambda we had an estimator minus 2 to the power  $x$  in Poisson distribution which was taking values always away from the range. But the errors were positive and negative both

very large errors and they were cancelling out each other. So, simply using expectation of  $x - g(\theta)$  that is bias as a measure is a dangerous thing.

So, one may look at other measures for example, why not consider absolute error and then take expectation. So, one may consider expectation of say  $|T - g(\theta)|$  absolute value. So, this is called the mean absolute error or one may consider expectation of  $(T - g(\theta))^2$  which is called the mean squared error.

So, I will pay some attention to this in the definitions. In the first case, we are simply looking at the amount or you can say magnitude of the error that we have committed in estimating  $g(\theta)$  by  $T$  and then we take the average of that. In the second one, we are considering the squares. So, if you think as a layman, then probably we feel that the first one is an appropriate measure for the error or you can say average error. However, in practice the evaluation of expectation of modulus  $T - g(\theta)$  is quite complex.

The second point is that if you look at mathematically, this function is not easy to handle. The main problem is that modulus function is not a smooth function, because it is having a corner that is at  $T = g(\theta)$  it is not smooth. Whereas, if you look at the mean squared error, it is easy to evaluate and it has a simple interpretation which is quite. So, what I do, I add and subtract expectation  $T$  here.

So, let us consider this as one term and this has one term. So, this becomes expectation of  $(T - g(\theta))^2$  plus expectation of  $(T - g(\theta))^2$  plus twice expectation  $(T - g(\theta))$  into expectation  $(T - g(\theta))$ . So, let us look at these terms. The first term is simply the variance of  $T$ . The second term is fixed terms so, expectation will be the same value because we have already taken expectation here. This term is nothing but the bias of the estimator  $T$ .

And if you look at the cross product term here, then this term is a constant. So, expectation applies to this, and this becomes 0. So, we have that mean squared error let me call it MSE of  $T$  that is equal to variance plus the bias. Now, this is quite significant interpretation. If I have to estimate a set  $T_1$  and  $T_2$  and we only say that variance of  $T_1$  is less than variance of  $T_2$ , then we are controlling only one quantity

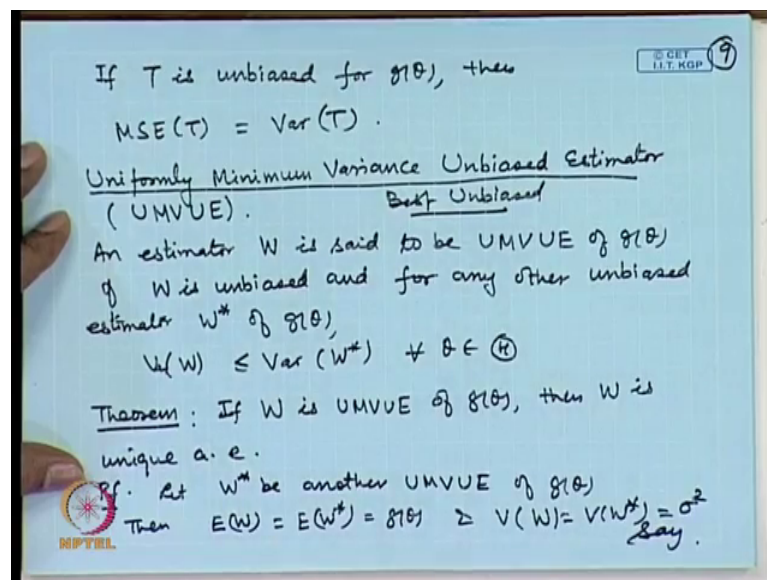
However, it may turn out that there is another estimator say  $T_3$ , which is which may be actually biased, but its variance is much less, so that the overall mean squared error is a

smaller. So, the average a squared error will be less. So, one can use mean squared error is as a good criteria for judging the goodness of an estimator.

So, we will say that we can say that estimator say T 1 is better which is actually a terminology for more efficient than T 2, if mean squared error of T 1 is less than or equal to mean squared error of T 2 for all theta. So, if the two mean squared errors are equal, then they will be same.

Now, in the context of unbiased estimation this concept of mean squared error being smaller is equivalent to variance being smaller. For example, if the estimator T is unbiased then bias will be 0 and this mean squared error will be equal to the variance.

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If T is unbiased for  $g(\theta)$ , then mean squared error of T is called to be variance of T. Now, we define Uniformly Minimum Variance Unbiased Estimators that is UMVUE. So, an estimator W is said to be UMVUE of say  $g(\theta)$  if W is unbiased and for any other unbiased estimator say  $W^*$  of  $g(\theta)$  variance of W will be less than or equal to variance of  $W^*$  that means, it will have the minimum variance throughout the parameter space. The first result in this direction is about the uniqueness of the UMVUE.

If so we also use the terminology best unbiased estimator etcetera. So, if W is UMVUE of say  $g(\theta)$ , then W is unique almost everywhere. So, let  $W^*$  be another

UMVUE. Then by definition expectation of  $W$  and expectation of  $W^*$  both are same as  $g(\theta)$  and variance of  $W$  and variance of  $W^*$  are also same let us call it say  $\sigma^2$ .

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Define  $W_1 = \frac{1}{2}(W + W^*)$ ,  $E(W) = g(\theta)$

$$\text{Var}(W_1) = \frac{1}{4} [\text{Var}(W) + \text{Var}(W^*) + 2 \text{Cov}(W, W^*)]$$

$$= \frac{1}{4} [2\sigma^2 + 2 \text{Cov}(W, W^*)]$$

$$\leq \frac{1}{4} [2\sigma^2 + 2\sqrt{\text{Var}(W)\text{Var}(W^*)}] = \sigma^2 = \text{Var}(W) \dots (1)$$

So inequality in (1) is not possible, so for equality to hold  $W^* = a(\theta)W + b(\theta)$  with  $\text{Pr} \approx 1$ .

$$\text{Cov}(W, W^*) = \text{Cov}(W, a(\theta)W + b(\theta)) = a(\theta)\sigma^2$$

$$\Rightarrow a(\theta) = 1, \quad b(\theta) = 0$$

So  $W = W^*$  w.p. 1. So  $W$  is unique a.e.

Now, let me define say  $W_1$  as half  $W$  plus  $W^*$ . Then what is the variance of  $W_1$ , we can apply the formula for a linear combination of variables. So, variance of a constant times that is that constant square times variance of  $W$  plus  $W^*$  which is becoming variance of  $W$  plus variance of  $W^*$  plus twice covariance between  $W$  and  $W^*$ .

Now, we are assuming variance of  $W$  and variance of  $W^*$  to be  $\sigma^2$ , so it becomes  $\frac{1}{4}(2\sigma^2 + 2\sigma^2 + 2\text{Cov}(W, W^*))$ . Now, covariance square is less than or equal to the product of the variances the well known Cauchy Schwarz inequality. So, this becomes  $\frac{1}{4}(2\sigma^2 + 2\sigma^2 + 2\sqrt{\sigma^2\sigma^2})$ , but these are both  $\sigma^2$ . So, this is simply becoming  $\sigma^2$ , so  $2\sigma^2 + 2\sigma^2$ , so it becomes  $\sigma^2$  which is the variance of  $W$  or  $W^*$ .

So, what we are proving? If  $W$  is UMVUE  $W^*$  is another UMVUE, then I am able to get another estimator  $W_1$  which is also unbiased because, if I take expectation of  $W_1$  here that is again  $g(\theta)$  as both  $W$  and  $W^*$  are unbiased and its variance is less than or equal to the variance of  $W$ . So, let me call this equation number 1. Inequality in 1 is not possible because our original claim is that  $W$  and  $W^*$  are UMVUE. So, another

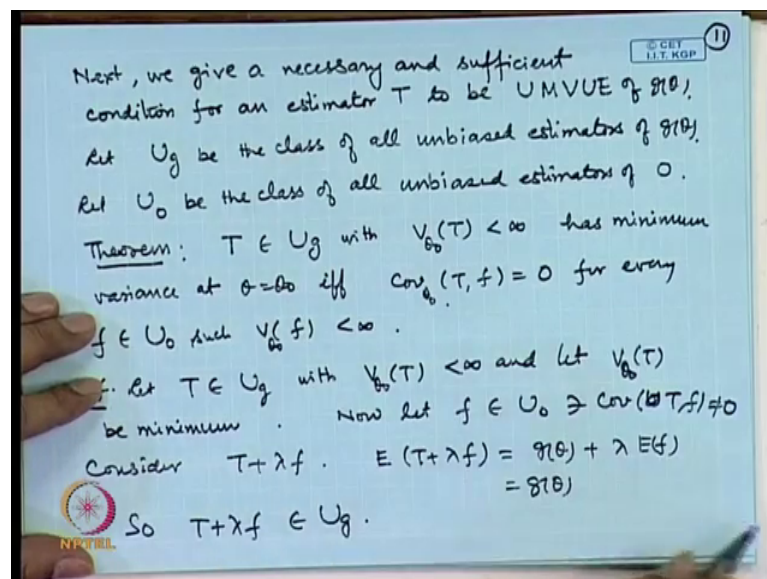
unbiased estimator cannot have variance less than them. So, at the most it can have equal, so that means, we should have equality.

Now, how this inequality came inequality came from this condition of the correlation between the  $W$  and  $W^*$  being less than 1, so that means, correlation must be one that is covariance is equal to the square root of the variances, that means,  $W$  and  $W^*$  are linearly related with probability 1. So, for equality to hold  $W^*$  must be linearly related to  $W$  with probability 1.

Now, once again you have unbiasedness, so if you are saying unbiasedness, then what should be the condition here. And also if I look at say covariance here between  $W$  and  $W^*$ , then that is equal to covariance between  $W$  and  $a\theta + b$ , so that is equal to  $a\theta$  into sigma square. So, that means, because this covariance between  $W$  and  $W^*$  is equal to variance  $W$  so,  $a$  is 1 and  $b$  will be 0, because unbiasedness is there because expectation  $W^*$  must be  $a\theta$ , so that is simply becoming  $a\theta + b$  so,  $b$  must be 0.

So, what we are concluding here that  $W$  is equal to  $W^*$  with probability 1, that means,  $W$  is unique almost everywhere. So, you cannot have two different unbiased MVUE's in if they are two different then they are equal almost everywhere.

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Now, next I give a necessary and sufficient condition for an estimator to be UMVUE. So, let us consider let  $U_g$  be the class of all unbiased estimators of  $g(\theta)$ . Let  $U_0$  be the class of all unbiased estimators of  $\theta$ . So, we have the following necessary and sufficient condition. So,  $T$  belongs to  $U_g$  with variance of  $T$  to be finite. So, this has minimum variance at  $\theta_0$  is equal to  $\text{Cov}_{\theta_0}(T, f)$ . If and only if covariance of  $T$  with say  $f$  is 0 for every  $f$  belonging to  $U_0$  for which variance of  $f$  is finite. That means, if an estimator is having covariance 0; that means, it is uncorrelated with every unbiased estimator of  $\theta$ , then this will be UMVUE of a function  $g$ .

Let me prove this here. So, let  $T$  the unbiased estimator of  $g$  and its variance be finite and let variance  $\text{Cov}_{\theta_0}(T, f)$  be minimum. Now, let us consider  $f$  belonging to  $U_0$ , such that covariance between  $T$  and  $f$  is not 0. So, I am assuming contrary to what we have to prove. So, we will arrive at a contradiction.

So, let us consider say  $T + \lambda f$  now if I take expectation of  $T + \lambda f$  then it is equal to expectation  $T$  that is  $g(\theta)$  plus  $\lambda$  times expectation  $f$  that is 0. So, it is equal to  $g(\theta)$  so, this new function which I have created  $T + \lambda f$  is also unbiased.

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$$V_{\theta_0}(T + \lambda f) = V_{\theta_0}(T) + \lambda^2 V_{\theta_0}(f) + 2\lambda \text{Cov}_{\theta_0}(T, f) \quad (1)$$

$$< V_{\theta_0}(T)$$

$$\Rightarrow \lambda (\lambda V_{\theta_0}(f) + 2 \text{Cov}_{\theta_0}(T, f)) < 0 \quad \dots (2)$$
 The condition (2) is satisfied for  

$$0 < \lambda < - \frac{2 \text{Cov}_{\theta_0}(T, f)}{V_{\theta_0}(f)} \quad \text{if } \text{Cov}_{\theta_0}(T, f) < 0$$

$$\text{or } - \frac{2 \text{Cov}_{\theta_0}(T, f)}{V_{\theta_0}(f)} < \lambda < 0 \quad \text{if } \text{Cov}_{\theta_0}(T, f) > 0$$
 This contradicts the fact that  $V_{\theta_0}(T)$  is minimum.  
 Hence  $\text{Cov}_{\theta_0}(T, f) = 0$ .

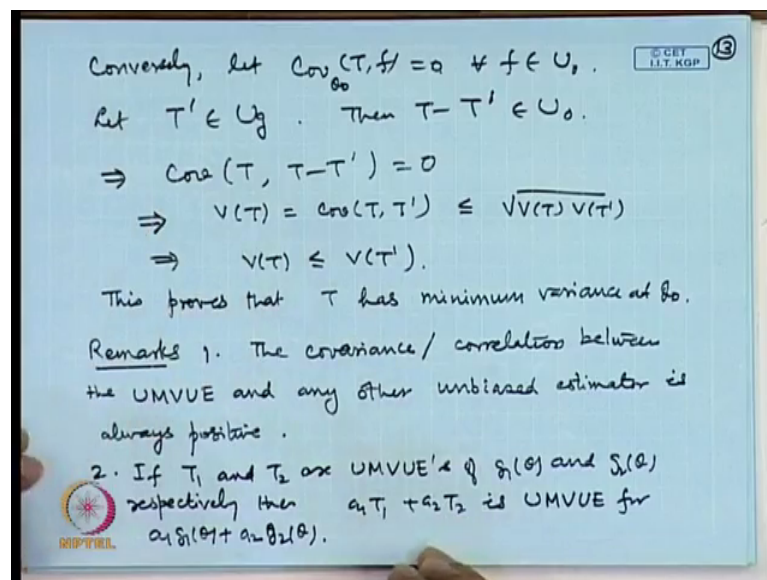
Now, let us take variance of  $T + \lambda f$ , so that is equal to variance of  $T$  plus  $\lambda^2$  times variance of  $f$  plus twice  $\lambda$  covariance between  $T$  and  $f$ . Now, if I put a condition here that this is less than variance of  $\text{Cov}_{\theta_0}(T, f)$ , then this thing

cancels out and it is reducing to a quadratic being less than 0, that means, this condition is equivalent to  $\lambda \text{Cov}(T, f) + \lambda^2 \text{Var}(f) < 0$ . So, this condition, obviously, can be satisfied.

The condition two is satisfied for  $0 < \lambda < -2 \text{Cov}(T, f) / \text{Var}(f)$ , of course, all these evaluations are at the point  $\theta_0$  if covariance of  $T$  and  $f$  is negative. And for  $-2 \text{Cov}(T, f) / \text{Var}(f) < \lambda < 0$  if this is positive. That means whatever be the value of covariance between  $T$  and  $f$  whether it is positive or negative, I am able to obtain a range of  $\lambda$  values such that the variance of  $T + \lambda f$  is less than variance of  $T$ . This is a contradiction to the fact that I assumed that variance of  $T$  is minimum at  $\theta_0$ .

So, where is the mistake? The mistake is that I am assuming that covariance between  $T$  and  $f$  is not 0. So, this is wrong. So, this contradicts the fact that variance  $\theta_0$  is minimum, hence we must have covariance between  $T$  and  $f$  equal to 0.

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Now, let us take the converse of this. Conversely let between  $T$  and in two variance of  $T$  prime. So, obviously, this is equivalent to saying that variance of  $T$  is less than or equal to variance of  $T$  prime. So, if I am taking covariance of  $T$  to be 0 with every unbiased estimator of  $\theta$  and I am taking another unbiased estimator  $T$  prime of  $g(\theta)$  then I am

getting that the unbiased the variance of T is less than or equal to variance of T prime. This proves that T has minimum variance at theta.

Another thing which you can conclude from here I have proved that if T is UMVUE, then covariance between T and T prime that is equal to variance of T; that means, this is always positive. So, we are also concluding from here that the covariance or you can say correlation between the UMVUE and any other unbiased estimator is always positive.

And other interesting property about the UMVUE is that if T 1 and T 2 are UMVUE's of g 1 theta and g 2 theta respectively, then a 1 T 1 plus a 2 T 2 is UMVUE for a 1 g 1 theta plus a 2 g 2 theta that means some sort of linearity property is also true for the UMVUE. Although it is true for the unbiased estimation, but it is not clear that it will be true for UMVUE's, but that is true here.

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$$\text{Cov}(a_1 T_1 + a_2 T_2, f) = a_1 \text{Cov}(T_1, f) + a_2 \text{Cov}(T_2, f) = 0$$

Example  $\underset{n \times 1}{Y} \sim N_n(\underset{n \times p}{X} \underset{p \times 1}{\beta}, \sigma^2 I)$   $Y = X\beta + \epsilon$

Let  $h(Y)$  be  $\Rightarrow E(h(Y)) = 0 \quad \forall \beta \in \mathbb{R}^p$

$$k \int h(y) e^{-\frac{1}{2\sigma^2} (y - X\beta)' (y - X\beta)} dy = 0 \quad \forall \beta \in \mathbb{R}^p$$

$$\Rightarrow \int h(y) e^{-\frac{1}{2\sigma^2} (y' y - 2y' X\beta)} dy = 0 \quad \forall \beta$$

diff w.r.t  $\beta$

$$\int h(y) X' y e^{-\frac{1}{2\sigma^2} (y' y - 2y' X\beta)} dy = 0$$

$$\Rightarrow E(h(Y) \sum X' Y) = 0 \quad \forall \lambda \in \mathbb{R}^p$$

So  $\sum X' Y$  is UMVUE of  $E(\sum X' Y) = \sum X' X \beta$

In fact, one can look at a very simple proof of this. If I consider say covariance of a 1 T 1 plus a 2 T 2 with an unbiased estimator of 0 then it is equal to a times covariance between T 1 and f plus a 2 times covariance between T 2 and f. Now, if T 1 and T 2 are UMVUE's, these are 0 so, this is simply 0. So, by the previous theorem this result follows.

As an application of this theorem let us consider linear model and try to obtain UMVUE. So, let us consider the Gauss-Markov linear model. So, y is an N by 1 vector with mean



$x\beta$  and variance covariance matrix as  $\sigma^2 y$ . So, actually it is the part of the Gauss-Markov linear model where we write it as  $\mu + \epsilon$  and  $\epsilon$  follows normal  $0, \sigma^2 I$ . So, let us consider say  $h(y)$  be a real valued function such that expectation of  $h(y)$  is say 0 for all  $\beta$ . This may be say  $N$  by  $p$  this may be  $p$  by 1 etcetera.

So, if you write this a statement expectation  $h(y) = 0$  it is equivalent to  $h(y)$  into the density function of  $y$  this is a multivariate normal distribution. So, it is  $e^{-\frac{1}{2\sigma^2}(y - x\beta)'(y - x\beta)}$ . And some coefficient will come which I am writing as a constant. This is equal to 0 for all  $\beta$  belonging to the  $R^p$ . This is a multivariate integral here.

Now, you differentiate both the sides with respect to  $\beta$ , then I will get  $h(y)$ , then derivative of this will give this term into the derivative of this with respect to  $y$  that gives me  $x' y e^{-\frac{1}{2\sigma^2}(y - x\beta)'(y - x\beta)}$ . In fact, here I can simplify beforehand I can write the term which is not involving  $y$  I can separate out and take to the other side. So, this is reducing to, so if you differentiate this, you will get  $x' y$  here, and the same term here.

So, this is equivalent to saying expectation of  $h(y)$  into some coefficient  $\lambda' x' y$  is equal to 0, for all  $\lambda$  belonging to  $R^p$ . So, what is this one this is a linear function. So, by the previous theorem, what we are saying is that  $\lambda' x' y$  is UMVUE of expectation of  $\lambda' x' y$  that is  $\lambda' x' \beta$ .

In the Gauss-Markov theory of linear models, we had proved that  $\lambda' x' y$  is the best linear unbiased estimator of  $\lambda' x' \beta$ . Here we are proving that it is not only best linear unbiased it is actually best unbiased that is it is the UMVUE for this. Although I have made a small mistake here, it is  $\lambda' x' x \beta$ . So, for this it is becoming best unbiased estimator.

In the forthcoming classes we will consider methods for finding out estimators. Just now in the previous two classes we have considered the properties of the estimator some desirable criteria. However, there must be some methods by which we can derive these estimators. So, we will do some well-known methods.