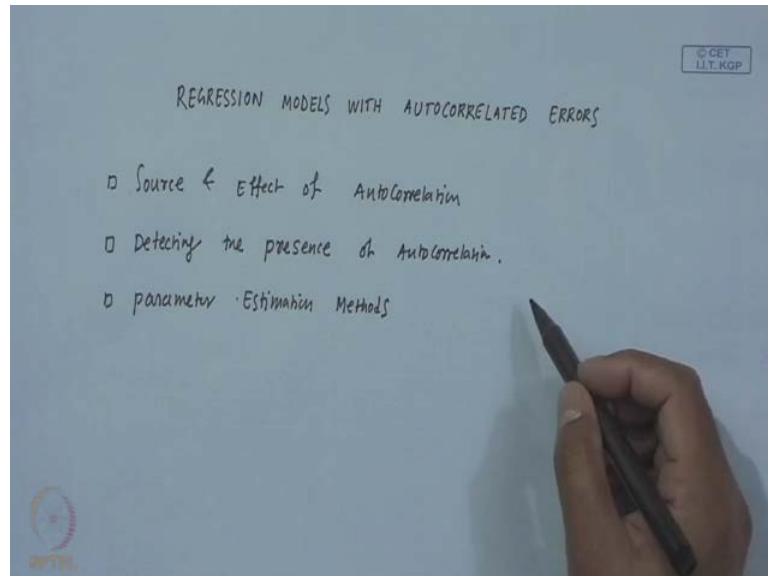


Regression Analysis
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Lecture - 33
Regression Models with Autocorrelated Errors

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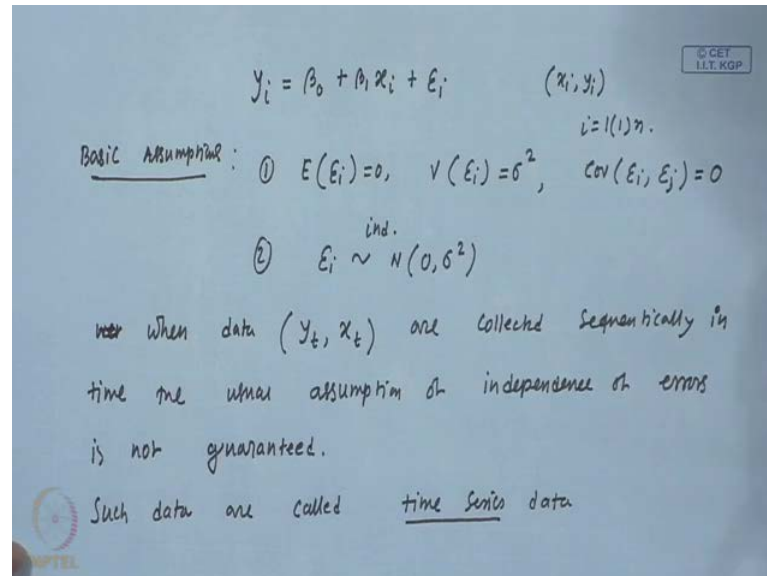


Today, we will start a new topic called a Regression Models with Auto Correlated Errors, here is the content of this module source and effect of autocorrelation and detecting the presence of autocorrelation. And then you know if you have autocorrelation in the model, I will explain what is this autocorrelation, and how to parameter, how to estimate the parameter of the model. So, let me give the idea what is the objective of this module given a set of data say x_i, y_i , while fitting a simple linear regression model say y equal to β_0 plus $\beta_1 x$ plus ϵ . So, we make several assumption on the error term, we assume that expectation of e equal to expectation of ϵ is equal to 0, variance of ϵ is equal to σ^2 .

We assume that the errors are uncorrelated, and also we make a normality assumption on the error to for the testing of hypothesis, and you know for confidence and interval of a parameter. Now, if the data set let say x_i and y_i is a collected sequentially over time, then the assumption of this independent error is not guaranteed, so in that situation I mean when the data are collected over time, those type of data called you know time

series data. And then how to deal with such situation, when the errors are correlated, let me you know write down the objective of this module clearly.

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So, I am talking about model say very simple linear regression model y_i equal to beta naught plus beta 1 x_i plus epsilon i , and you are given the data set say $x_i y_i$, so i is from 1 to n . And the assumption we make that basic assumptions are we assume that expectation of epsilon i is equal to 0, variance of epsilon i is equal to sigma square, the constant variance and also we assume that you know the errors are uncorrelated. So, I can write in this form that covariance of epsilon i epsilon j is equal to 0, because the expectation is also 0.

Well, and also we make the assumptions this is the first one, second one is that we assume that this epsilon i follows normal 0 sigma square, and they are independent. Now, what I said is that now, when this data say I will write y_t instead of y_i $y_t x_t$ are collected sequentially in time the usual assumption of independence of errors is not guaranteed, anyway such data are called time series data. Let me just you know to make this part clear, what I mean by that data are collected sequentially in time, let me just give one example to clear your doubt.

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SOFT DRINK CONCENTRATE DATA

YEAR	SALES (Y)	EXPENDITURES (X) (1,000 \$)
1	3083	75
2	3149	78
3	3216	80
4	3239	82
5	3296	84
6	3374	88
7	3475	93
8	3569	104
9	3697	109
10	3725	115
11	3794	120
12	3959	127
13	4083	135
14	4193	144
15	4318	153
16	4488	161
17	4683	170
18	4880	178
19	5083	188
20	5283	198

This is called you know soft drink concentrate data and this one is the regressor variable, this is the regressor variable x and this is the sales amount y, and this is the sales amount and this one is the x is expenditure on advertisement, so this is in 1000 dollar unit. And so we have data on the amount of money, you know used for the advertisement and sales amount for 20 years, so this data you know this is a let me call this is $x_t y_t$, so this x_t and y_t are collected over 20 years.

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$y_i = \beta_0 + \beta_1 x_i + \epsilon_i \quad (x_i, y_i)$

$i=1(1)n.$

Basic Assumptions: ① $E(\epsilon_i) = 0, \quad V(\epsilon_i) = \sigma^2, \quad \text{Cov}(\epsilon_i, \epsilon_j) = 0$

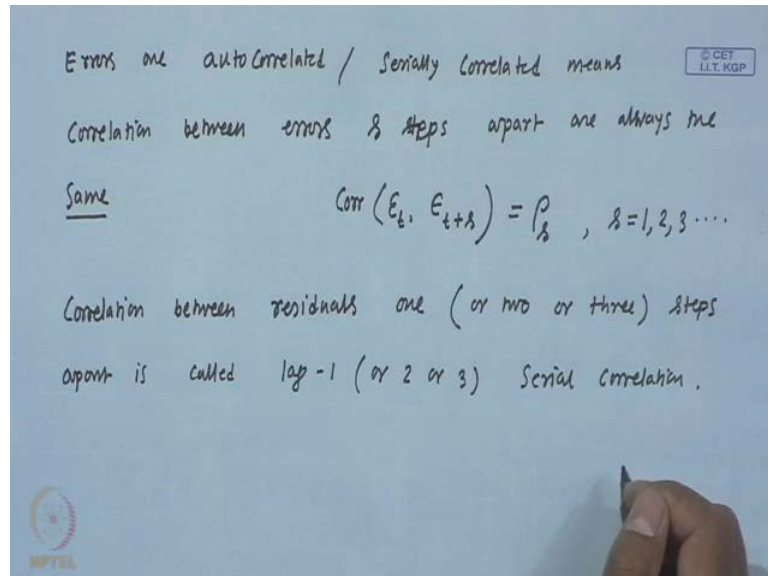
② $\epsilon_i \overset{\text{ind.}}{\sim} N(0, \sigma^2)$

When data (y_t, x_t) are collected sequentially in time the usual assumption of independence of errors is not guaranteed.

Such data are called time series data.

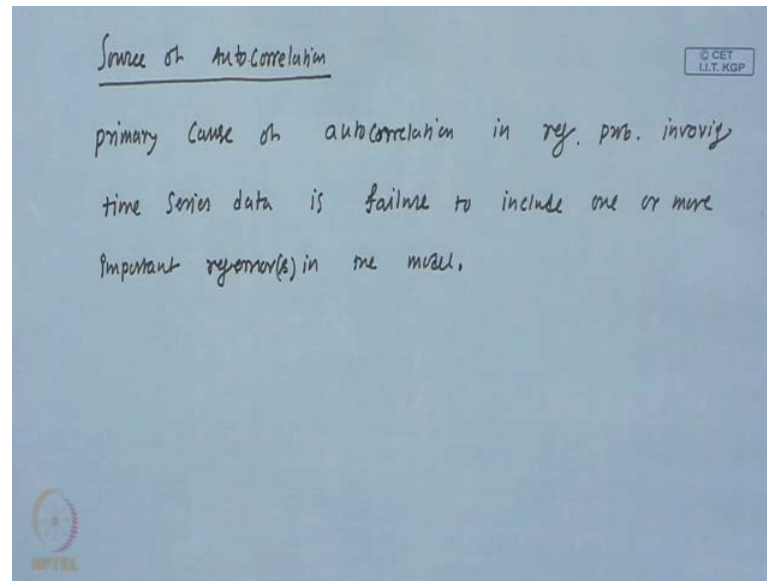
So, this is a time series data, so when the data are collected sequentially in time the usual assumption of independence of error is not guaranteed.

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So, here we say that errors are autocorrelated or also you called a serially correlated, so that means, that errors are correlated or serially correlated means correlation between errors s steps apart are always the same. So, I am talking about the correlation between epsilon i or say epsilon t and epsilon t plus s , this is same for all t , and we usually this denote by ρ_s , for s equal to 1, 2, 3 like this. So, as the correlation between residuals say 1 or 2 or 3 steps apart is called a lag 1 or 2 or 3 serial correlation. So, if the s is equal to 1; that means, when you are constraint in the correlation between the errors, one step apart that is called lag one autocorrelation or serial correlation.

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So, what is the source of this autocorrelation, so the primary source cause of autocorrelation in regression problem, involving a time series data is failure to include 1 or more important regressors in the model. So, what we mean by this one is that let me consider the example, of a soft drink concentrate data. So, there we are trying to regress the sales amount on the amount of expenditure for advertisement, but you know the growth, I mean the population increases over time and this growth in population has you know influence in the sales amount.

So, the population size is another important variable, which has influence on sales amount, so if you do not include the population size or increase in the population size you know that variable in the model, then you can expect autocorrelation in the time series data. So, the it says that the primary cause of autocorrelation in regression problem, involving time series data is you know is failure to include important regressor variable in the model, so we understood the source of autocorrelation, why it happens.

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Effect on Autocorrelation

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① $Y = X\beta + E$


LSE $\hat{\beta} = (X'X)^{-1} X'Y$

Errors are correlated

$\hat{\beta}$ is unbiased but $\hat{\beta}$ is not min variance

$\hat{\beta}$ is not BLUE

$V(E) = \sigma^2 V \neq \sigma^2 I$



And then now let me talk about the effect of autocorrelation, so if effect of autocorrelation, so if autocorrelation is there in the model; that means, what is the meaning of this that epsilon i and epsilon j the correlation between them is not equal to 0. So, if this happen, if the errors are correlated and what is the effect of that while fitting a simple, say simple multiple linear regression model, so if you are fitting a multiple linear regression models, say y equal to x beta plus epsilon.

Then we know that the least square estimate is beta hat which is equal to x prime x inverse x prime y, so this is obtained using a least square estimate. And now, if you consider the basic assumptions on the model that you know this epsilon i follow normal distribution with mean 0, variance sigma square in the independent. Then the condition of the Gus Markov theorems are satisfied and so the beta hat, we get the beta hat is equal to x prime x inverse in x prime y that is the best linear unbiased estimate.

So, but here, once the condition that you know, here the errors are correlated, so here that condition is not true, so errors are correlated here, so because of the violence of this violation of this condition that you know errors are uncorrelated. Here, beta hat is unbiased, but beta hat is not minimum variance, so because of this problem like you know errors are correlated in this case, so the least square estimate beta hat is not the best linear unbiased estimator. Of course, you know if the variance of epsilon is equal to say

sigma square v , where v can be written as sigma square I , then we know how to get the best linear unbiased estimator using the generalized least square technique.

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2. When the errors are positively autocorrelated, the MS_{Res} may seriously under estimate σ^2

$\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x$ $V(\hat{\beta}_1) = \frac{MS_{Res}}{S_{xx}}$

$se(\hat{\beta}_1) = \sqrt{\frac{MS_{Res}}{S_{xx}}}$ Small.

Confidence interval is short. β_1 may be

$H_0: \beta_1 = 0$ vs $H_1: \beta_1 \neq 0$, $t = \frac{\hat{\beta}_1}{se(\hat{\beta}_1)} = \text{large}$. Significant when it is really not.

The second effect is when the errors are positively auto correlated I will say what is mean by this one, then the M S residual may seriously under estimate sigma square, because we know that M S residual is a unbiased estimator for sigma square. So, what is the consequence of this one that you know M S residual underestimate sigma square, the consequence of this one is that the variance of suppose you are fitting the model y hat a simple linear regression model β_0 hat plus β_1 hat x is the fitted model.

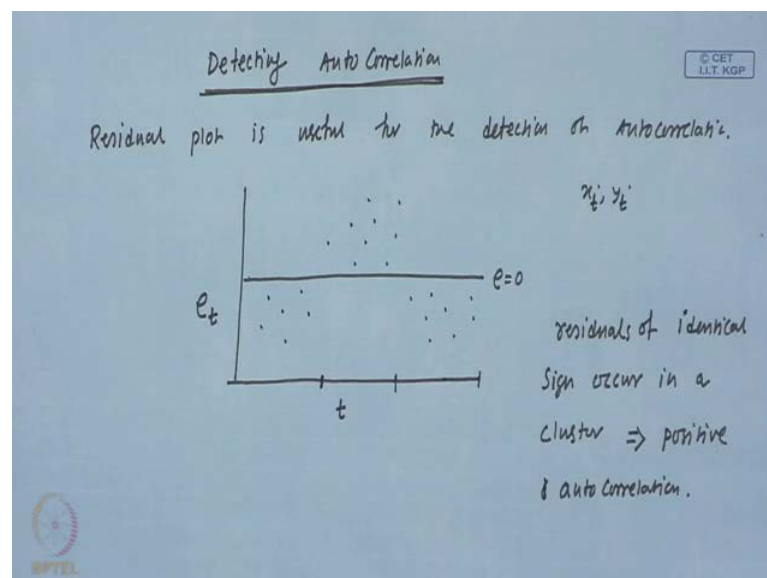
And so we know that variance of β_1 hat is equal to M S residual by S_{xx} , so the standard error of β_1 hat is equal to square root of this quantity M S residual by S_{xx} . Now, since this one is small the standard error is going to be small, and the consequence of this one is that when we compute the confidence interval for say β_1 hat. So, the confidence interval, if you refer my first module the confidence interval for β_1 is β_1 hat plus $t_{\alpha/2, n-2}$ degree of freedom into standard error of β_1 hat. And the lower boundaries β_1 hat minus $t_{\alpha/2, n-2}$ standard error of β_1 hat.

Since, this one is small then this confidence interval is short, so you will get a narrow interval for the parameter, and which might not be the true interval for the parameter β_1 . And also in the regression of model, we test a hypothesis like to check the significance of β_1 or to or the significance of the model or the linear term, we check the

hypothesis like H_0 is say $\beta_1 = 0$ against the H_1 that a β_1 is not equal to 0. And you know that the test statistic to test one is $t = \hat{\beta}_1 / \text{standard error of } \hat{\beta}_1$.

So, see when there exist positive autocorrelation in error the M S residual underestimate sigma square, and the consequence of that is that the standard error of $\hat{\beta}_1$ is small. So, this one is small, so t is large, so; that means, that β_1 may be significant, so you will get a result that β_1 is significant, when it is really not, because of the positive autocorrelation in the data, these are the effect of autocorrelation.

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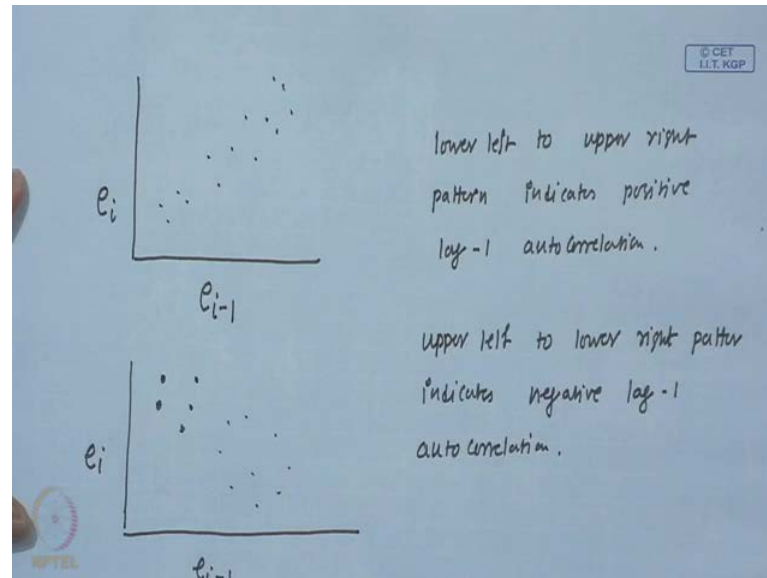


Now, let me talk about how to detect a autocorrelation, so detecting autocorrelation. So, the first technique is you know the residual plot is useful for the detection of autocorrelation. So, what we plot is that you plot, so given the data said x_i, y_i or x_t, y_t you fit a simple linear regression model, so once you have a fitted you can compute the residuals.

And then you plot let me call it x_t, y_t and you plot residual e_t against t , and if you see that your plot is like this say for example, this is the residual plot e_t against t , here what happen is that till this point you see all the residuals, so this is the line $e = 0$. So, till this time point all the residuals are negative and from here to here you can see all the residuals are positive, and again the residuals are negative in this segment. So, residual of identical sign occur in a cluster, then this indicate the positive autocorrelation maybe I

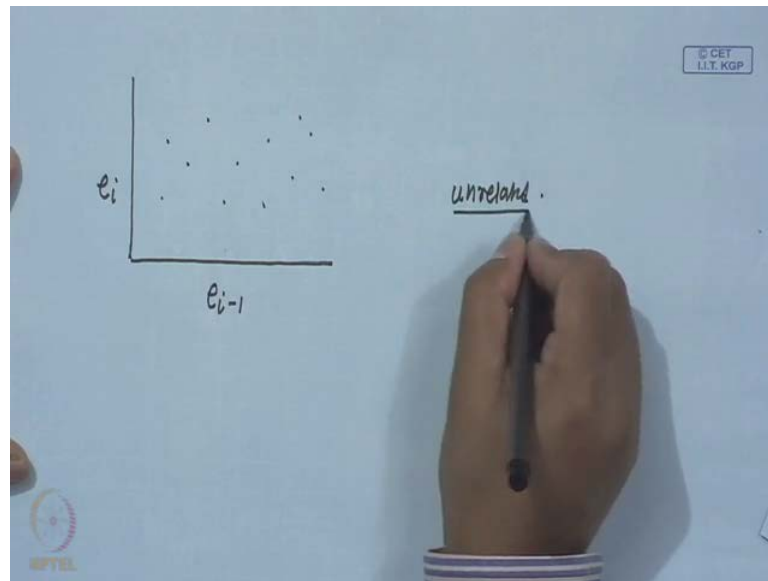
will explain why this is true, before that you know let me give some more residual plots of like you know.

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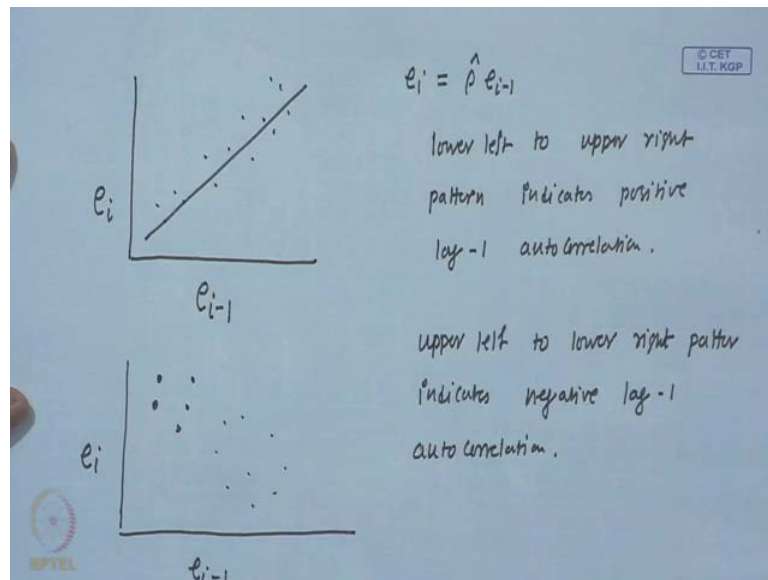
If the this residual plot is e_i well e_t against e_{i-1} , so here we are short of trying to find the relation between e_i and e_{i-1} ; that means, a lag one correlation. So, if you see the plot is like this see for example, then this one is sort of lower left to upper right pattern indicates positive lag one autocorrelation. And if you see the scatter plot of e_i against e_{i-1} is like this say e_i , e_{i-1} it is say for example, like this; that means, this is upper left to lower right pattern, this indicates negative lag one autocorrelation.

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And other one is, so this plots are like to detect a lag 1 autocorrelation, similarly for lag 2, you have to plot e_i against e_{i-2} and see how they are related. So, e_i vs e_{i-1} if you see the pattern is like this, then this indicates that errors are uncorrelated or unrelated.

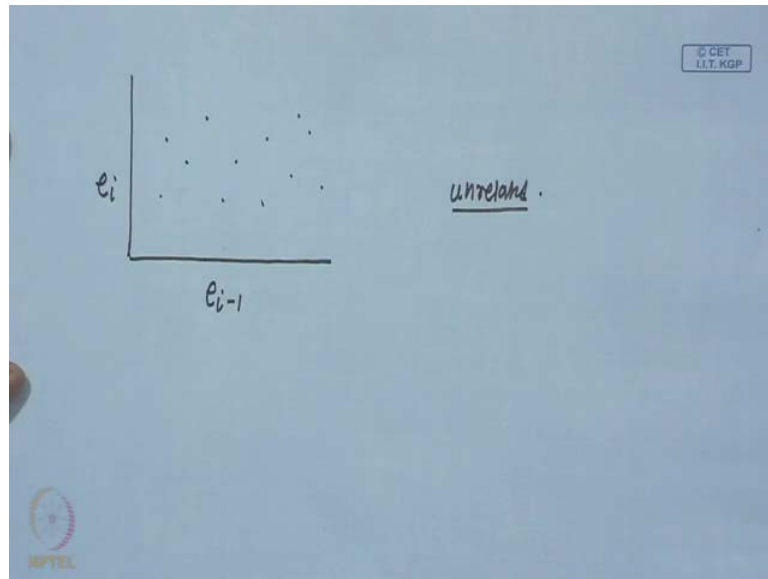
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So, these are the graphical technique to identify the existence of autocorrelation and specially for lag one autocorrelation, you have to plot this is basically we are trying to find the relation between e_i and the previous residual. And also you see you know e_i

now this sort of you know if you fit a straight line, if you fit a model between few regress e_i on e_{i-1} . You will get a straight line model like e_i is equal to some ρ into e_{i-1} , and this clearly says here ρ is positive and e_i increases sort of as e_{i-1} increases, so they are very similar in magnitude. So, this is what the positive lag one autocorrelation, and negative lag one this indicates negative lag one autocorrelation.

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And this one says that there are there is no correlation between e_i and e_{i-1} ; that means, the errors are uncorrelated. Now, we will talk about one statistical test to test the presence of autocorrelation.

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The Durbin - Watson Test

Suppose we wish to fit the model

$$y_u = \beta_0 + \sum \beta_i x_{iu} + \epsilon_u, \quad u = 1(1)n$$

by LS to observation $(y_u, x_{1u}, x_{2u}, \dots, x_{ku})$

we usually assume $\epsilon_u \stackrel{iid}{\sim} N(0, \sigma^2)$; $\rho_{\epsilon} = 0$

we want to see if this assumption is justified

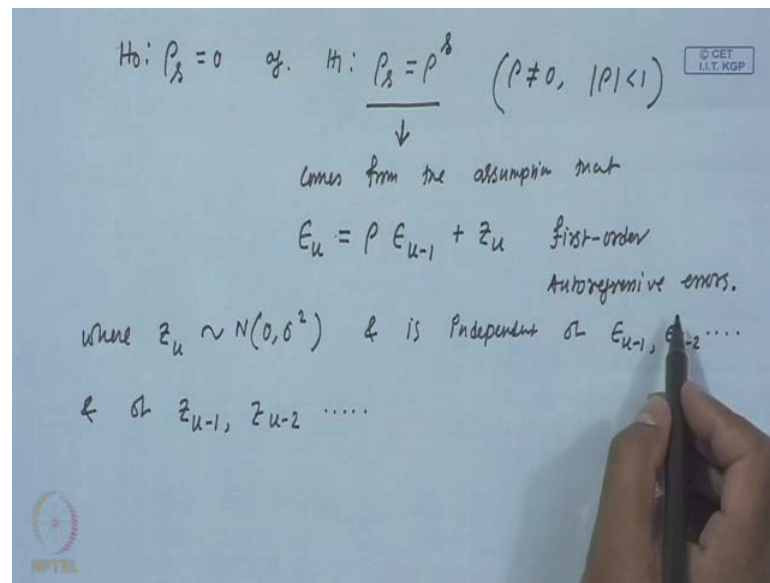
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The test is called The Durbin Watson Test, suppose we wish to fit the model say y_u equal to β_0 plus $\beta_i x_{iu}$ plus ϵ_u , u is from 1 to n by least square technique, to observation say y_u . And then I am talking about multiple linear regression model x_{1u} x_{2u} and something x_{ku} , so what we do is that we usually assume that this ϵ_u follows normal distribution with 0 sigma square, and there IID. That is what; that means, that we are assuming that the lag is autocorrelation is equal to 0; that means, correlation between the errors s step apart that is equal to 0.

So, if you want to use least square technique to fit this model you have to assume this; that means, we are assuming this. Now, we want to what we want to do is that, we want to see if this assumption is justified for the given data, for that what we will do is that we will test hypothesis.

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It is against the null hypothesis that ρ_s is equal to 0, against the alternative hypothesis H_1 that ρ_s is equal to ρ to the power of s , this ρ is not equal to 0 and its modulus value is less than 1. Now, what I will do is that you know why particular, you are considering this alternative hypothesis, how this alternative hypothesis comes, we will talk about that little bit. So, if the null hypothesis is accepted here in our test we will be talking about one test procedure using the Durbin Watson test, and if the null hypothesis is accepted here that is ρ_s is equal to 0; that means, there is no autocorrelation in the error.

And here we wrote the alternative hypothesis ρ_s is equal to ρ to the power of s . Now, what I will do is, I will try to justify the choice of this alternative hypothesis. So, this alternative hypothesis comes from the assumption that the errors follow this model, $\epsilon_u = \rho \epsilon_{u-1} + z_u$; that means, the errors are first order autoregressive errors. Where, this z_u first order autoregressive means, there is a linear relation between ϵ_u and ϵ_{u-1} , where z_u follows normal $0, \sigma^2$. And this z_u is independent of $\epsilon_{u-1}, \epsilon_{u-2}$ and of z_{u-1}, z_{u-2} like this. So, if the errors are first order autoregressive error, then I can write this ϵ_u in this form.

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$$\begin{aligned} \epsilon_u &= \rho \epsilon_{u-1} + z_u \\ &= \rho (\rho \epsilon_{u-2} + z_{u-1}) + z_u \\ &= \rho^2 \epsilon_{u-2} + \rho z_{u-1} + z_u \\ &= \rho^2 (\rho \epsilon_{u-3} + z_{u-2}) + \rho z_{u-1} + z_u \\ &= \rho^3 \epsilon_{u-3} + \rho^2 z_{u-2} + \rho z_{u-1} + z_u = \sum_{k=0}^u \rho^k z_{u-k} \end{aligned}$$

Under $H_0: \rho = 0$
 $\epsilon_u \stackrel{\text{ind}}{\sim} N(0, \sigma^2)$

$E(\epsilon_u) = 0$ $V(\epsilon_u) = (1 + \rho^2 + \rho^4 + \dots) \sigma^2$
 $= \frac{\sigma^2}{1 - \rho^2}$, $\text{cov}(\epsilon_u, \epsilon_{s+u}) = \rho^{|s|} \sigma^2 \frac{1}{1 - \rho^2}$
 $\text{cov}(\epsilon_u, \epsilon_{s+u}) = \rho^{|s|}$

$\epsilon_u \sim N\left(0, \frac{\sigma^2}{1 - \rho^2}\right)$

So, my epsilon u, I took this epsilon u is equal to rho epsilon u minus 1 plus z u I took. Now, I can write this one as rho rho epsilon u minus 2 plus z u minus 1, I am just replacing epsilon u minus 1 by this 1 plus z u. So, this can be written as rho square plus rho square epsilon u minus 2 plus rho z u minus 1 plus z u, this again if you replace this epsilon u minus 1 by this quantity as rho epsilon u minus 3 plus z u minus 2 plus rho z u minus 1 plus z u.

So, what we will get is that, you will get rho to the power of three epsilon u minus 3 plus rho square z u minus 2 plus rho z u minus 1 plus z u. So, ultimately, you can write this as again, you replace epsilon u 3 using this formula you can write this as rho to the power of k z u minus k, k is from 0 to u you can check that. So, this is what the epsilon u in terms of z u z, so expectation of epsilon u is equal to 0, because expectation of z is equal to 0, what about the variance of epsilon u, now the variance of they all are independent, z i is the independent.

So, you can write this the variance, this one as 1 plus rho square plus rho to the power of 4 like this into sigma square, because the variance of z u minus k is sigma square and they are independent. So, you can write in this form, and this can be written as sigma square by 1 minus rho square, and similarly you know you can check that the covariance of epsilon u and epsilon s plus u.

So, I am trying to find the correlation between if the errors are you know first order autoregressive, what is the correlation between epsilon u and epsilon s plus u. So, you can check the covariance is equal to rho to the power of s sigma square, 1 by 1 minus rho square, so this is the covariance. And since, this is the covariance, and then it is clearly the correlation between epsilon u and epsilon s plus u is equal to rho to the power of s. And here as you see now the epsilon u, which is first order autoregressive, they follow normal distribution with mean 0, and variance sigma square by 1 minus rho square and under the null hypothesis.

The null hypothesis is under H naught that rho equal to 0, under this null hypothesis this sigma epsilon u, they follow normal 0 sigma square, you put rho equal to 0 here normal sigma square. And correlation also become 0 because rho equal to 0 the correlation between them is 0, so they independent, so the under null hypothesis, epsilon u follow normal sigma square and they are independent.

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$H_0: \rho_s = 0$ vs. $H_1: \rho_s = \rho^{|s|}$

To test H_0 vs. H_1 , we fit the model $Y = X\beta + \epsilon$ &

Compute the residuals e_i . We then form the

Durbin - Watson test statistic

$$d = \frac{\sum_{u=2}^n (e_u - e_{u-1})^2}{\sum_{u=1}^n e_u^2}$$

The distribution of d lies between 0 & 4 &

Symmetric about 2.

So, you understood the significance of this alternative hypothesis now, so we are testing the hypothesis that H naught is a rho s is equal to 0 against the alternative hypothesis H 1 that rho s is equal to rho to the power of s. So, and we have checked that this alternative hypothesis in on the assumption that the errors are first order autoregressive, then rho s is equal to rho to the power of s.

This is the correlation between σ_u and ϵ_u , now to test this hypothesis to test H_0 against H_1 , so what we do is that we fit the model $y = x\beta + \epsilon$. Assuming, that all the basic assumptions are true and using the least square technique, and then once you have the fitted model you can compute the residual, and compute the residual e_i , and then once you have the e_i does not matter whether the basic assumptions are true or not.

Now, you can check whether there is a autocorrelation in the error term or not by using the test, we then form the Durbin Watson test statistic that $d = \frac{\sum_{i=2}^n (e_i - e_{i-1})^2}{\sum_{i=1}^n e_i^2}$. So, given a set of data you fit the model you find the residual, and then you compute the Durbin Watson test statistic, and then based on this test statistic, we will now test this hypothesis whether there exist autocorrelation in the data or not. So, the distribution of d lies between 0 and 4 and the distribution is symmetric about 2, so we know the test statistic to test this hypothesis, and now we will be talking about you know what are the critical reasons when to reject and accept.

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① one sided test against the alternative
 $H_0: \rho = 0$ $H_1: \rho > 0$

if $d < d_L$ reject H_0
 if $d > d_U$ accept H_0
 if $d_L < d < d_U$, test is inconclusive.

positive autocorrelation indicates successive error terms are of similar magnitude \leftarrow the diff in residuals $e_i - e_{i-1}$ will be small.

Say first case, one sided test against the alternative that ρ is greater than 0, so basically we are testing here of for a lag one that $H_0: \rho = 0$ against $H_1: \rho > 0$, so you compute the test statistic d . And then if d is less than d_L , I will say what is this d_L you reject H_0 , so there is a table for this Durbin Watson test statistic.

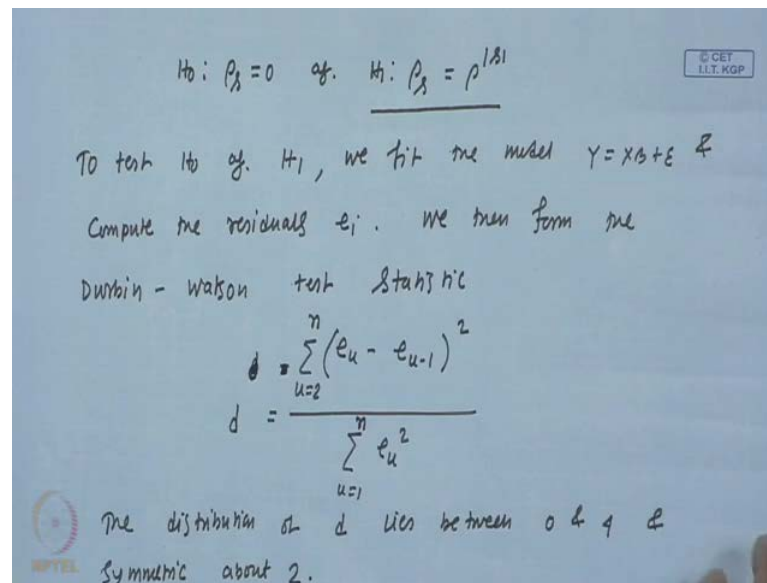
So, the table is given for it is only it requires the number of observations you have, so for that soft drink concentrate data, there we had 20 observations, and then from the table you have to see the d_L and d_U value corresponds to n equal to 20.

So, if d is less than d_L , we reject a H_0 , if d is greater than d_U , we accept a H_0 , I will explain you know why suddenly this a critical reason, and if d_L is less than d and less than d_U the test is inconclusive. Now, what happen is that, if the d is small if, so given a data you fit a model using the ordinary least square technique, and you get e_i and once you have the residual you can compute the Durbin Watson test statistic.

So, small value of d implies ρ is equal to 0; that means, small value of d indicates, there is no you reject this one; that means, you accept this 1, so small value of d indicates that auto autocorrelation exist in the model. So, if the d is small you are rejecting this; that means, you are accepting this, acceptance of ρ is greater than 0 means the data has positive or the error has a positive autocorrelation, so let me just explain this part why this is true. So, the positive autocorrelation, when it is positive autocorrelation, you just recall the graph you are plotting e_i against e_{i-1} , so this is the case when it has positive autocorrelation.

The positive autocorrelation indicates successive error terms are of similar magnitude, and the difference in residuals e_i minus e_{i-1} will be small, so this is the case when it indicates the existence of positive autocorrelation. So, here you can see you take a point and this is the e_{i-1} value and this is, so the e_{i-1} and e_i they are almost of similar magnitude, that is why you get a you know all the points are centered about the line x equal to y or the line this is centered about e_i equal to e_{i-1} . So, points are centered about this line means e_i and e_{i-1} are very similar, and since they are similar the difference is small.

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$H_0: \rho = 0$ vs. $H_1: \rho = \rho^{1st}$

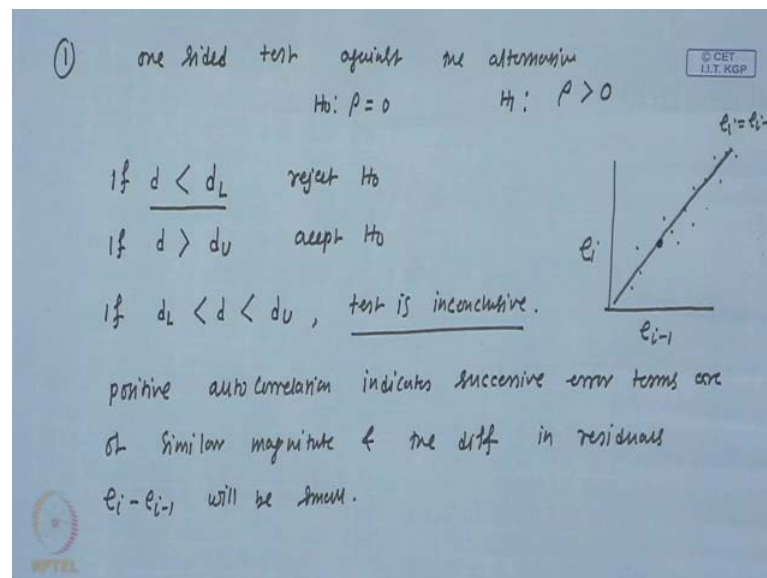
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Compute the residuals e_i . We then form the
Durbin - Watson test statistic

$$d = \frac{\sum_{u=2}^n (e_u - e_{u-1})^2}{\sum_{u=1}^n e_u^2}$$

The distribution of d lies between 0 & 4 &
Symmetric about 2.

So, once the difference is small you now recall the Durbin Watson test statistic d , that involve the difference, so if the difference is small the d is going to be small.

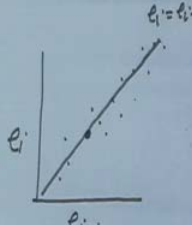
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① one sided test against the alternative
 $H_0: \rho = 0$ vs. $H_1: \rho > 0$

If $d < d_L$ reject H_0
If $d > d_U$ accept H_0
If $d_L < d < d_U$, test is inconclusive.

positive auto correlation indicates successive error terms are of similar magnitude & the diff in residuals $e_i - e_{i-1}$ will be small.



The plot shows a positive linear trend in the residuals, with the y-axis labeled e_i and the x-axis labeled e_{i-1} . A diagonal line represents $e_i = e_{i-1}$.

And once d is small that implies the existence of positive lag one autocorrelation, and that is why we reject the null hypothesis and accept the alternative hypothesis, so I hope you know this will make clear, why this is a critical reason. As, I told you there is a table I will talk in the next class, this is a table for d_L and d_U value for different n and for different α , and I will talk about other cases also in the next class. So, we need to

stop now, we will continue with the Durbin Watson test with the some example, to illustrate the Durbin Watsons test in the next class.

Thank you.