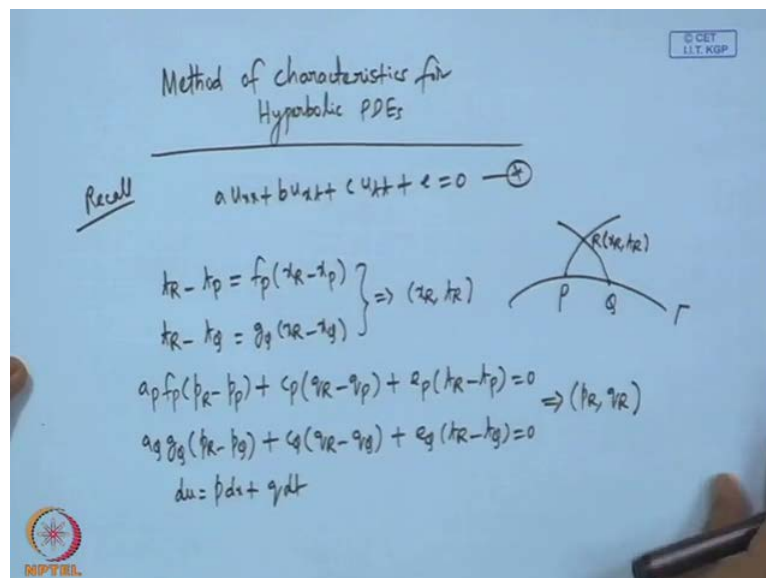


Numerical Solutions of Ordinary and Partial Differential Equations
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Lecture - 38
Method of Characteristics for Hyperbolic PDEs - II

Hello, good morning. So, in the last class we consider second order hyperbolic PDEs, and discussed method of characteristics. So, let us do some examples today and then also proceed to first order PDE. So, let us before we go for the examples, let us check quick recall on yesterday's thing.

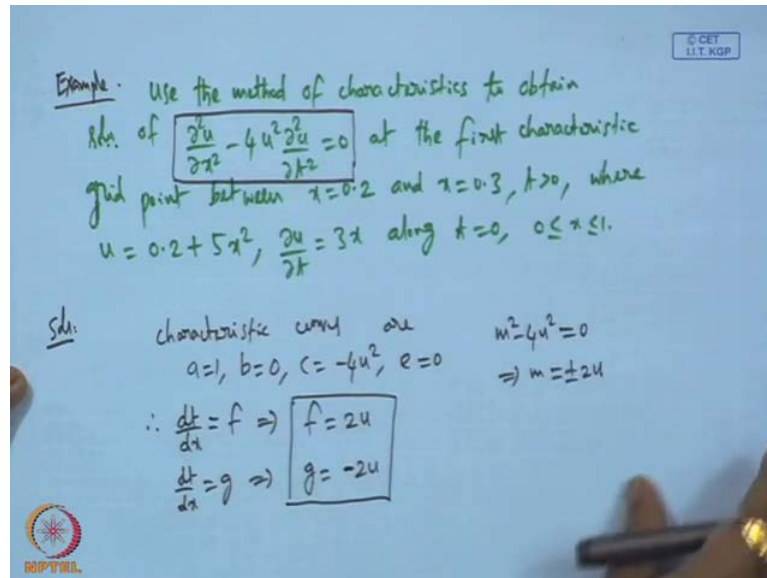
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So, the recall is we consider PDE of the form, so then if gamma is any non characteristic curve, if we take two points. So, they intersect the point R, now we have obtained. So,

these are the two equations and two unknowns. So, from here we get x R and t R then once we are done with this we go for, so these two would give p R and q R and then ultimately we use $d u$ equals; of course the discussed version and obtained, right? So with this let us proceed.

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So, example so use method of characteristics to obtain solution of at the first characteristic the point between x equals to 0.2 and x equals to 0.3, where u is $3x$ along p equals to 0. Suppose, this is a problem, so this is a given PDE and we are expect to get the solution between this two along the characteristic, so solution. So, what are the characteristic curves is so in this case a is 1, b is 0 c is minus 4 u square and e is 0 when we compare with the standard form. So, the characteristic curves are m is therefore, dt by dx equals to f implies f equals $2u$ dt by dx equals to g implies g equal to minus $2u$. So, these are required for us.

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we have $u = 0.2 + 5x^2$

$\frac{\partial u}{\partial x} = 10x = p$, given $\frac{\partial u}{\partial t} = 3x = q$ (along $t=0$)
 $0 \leq x \leq 1$.

$\therefore u_p = u(0.2, 0) = 0.2 + 5(0.2)^2 = 0.4$
 $u_q = u(0.3, 0) = 0.65$

$f_p = 2u_p = 0.8$ | $g_p = 0.6, g_q = 0.9$
 $g_q = -2u_q = -1.3$
 $c_p = -4u_p^2 = -0.64$
 $c_q = -4u_q^2 = -1.69$

Now, we have u equals to 0.2 plus $5x$ square therefore, $\frac{du}{dx} = 10x$ which is equals to p and by given $\frac{du}{dt} = 3x$, which is q . Of course, these are along $t=0$ and therefore, let us compute u_p u_p is u at 0.20 . So, this is than u_q , so this is than f_p is $2u_p$. So, this is 0.8 than g_q minus u_q , so this is minus 1.3 than c_p is u_p square. So, this is minus 0.64 . So, this is so having obtained also we need the corresponding data q_p . So, we have q which is $3x$ q_p is 0.6 and q_q is 0.9 . Now, let us first compute we would like to compute first the point.

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$t_R - t_P = f_P(t_R - t_P)$
 $t_R - t_Q = f_Q(t_R - t_Q)$
 $\Rightarrow t_R = 0.8(t_R - 0.2)$
 $t_R = -1.3(t_R - 0.3)$

$\Rightarrow t_R = 0.5278$
 $t_R = 0.0695$

$0.8(p_R - 2.0) - 0.64(q_R - 0.6) + 0 = 0$
 $-0.65(p_R - 3.1) - 1.69(q_R - 0.9) + 0 = 0$

$\Rightarrow p_R = -81.71$
 $q_R = -78.47$

$\therefore u_R = u_P + \frac{1}{2}(p_P + p_R)(t_R - t_P) + \frac{1}{2}(q_P + q_R)(t_R - t_P)$
 $= -13.29$

P (0.2, 1)
 Q (0.3, 0)
 R (x_R, t_R)

So this is P and this is Q now R, so we would like to compute this points therefore, we have to use. So, if we use this so t_P and t_Q are 0, so t_R is 0.8, so this implies x_R so you can solve the system. So, this is the point, so once we get this point what is our next task to compute the first derivatives at R. However the corresponding equation so I am referring these equations if you recall so e_P and e_Q . So far the further equation that we have considered, so I have already mentioned e is 0, so what would happen if e is 0 the corresponding equation to compute p_R and q_R from this system this is 0.

So, e_P is 0, e_Q is 0. So, there is no contribution from this term so the equation is simplified to so by simplifying solving the system, we get and we have approximately for u . So, this we approximate by taking the average of p and average of q , so accordingly we get u_R equals to u_P plus half p_P plus p_R . So, this if we compute by

substituting the corresponding values so this is the technique to compute. So, let us see one more example.

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Example

$$u_{xt} - u u_{xt} + (1-x^2) = 0$$

$$u(x,0) = x(1-x), \quad u_t(x,0) = 0$$

$$u(0,t) = 0, \quad u(1,t) = 0, \quad p(0.2,0), \quad q(0.4,0)$$

$$a=1, \quad b=0, \quad c=-u, \quad e=1-x^2$$

$$u_p = 0.2(1-0.2) = 0.16; \quad u_q = 0.4(1-0.4) = 0.24$$

$$p = \frac{\partial u}{\partial x} = 1-2x \Rightarrow p_p = 0.6; \quad p_q = 0.2$$

$$q = \frac{\partial u}{\partial t} = 0 \Rightarrow q_p = 0; \quad q_q = 0$$

Where e in this case e is 0 therefore, there is no contribution literally even though we have obtained this point that was not used to compute this. However to compute this u r we use. So, the next example then u t and the points p is this and q is now comparing with the standard form a is 1, b is 0, c is minus u, e is 1 minus x square, u P and u Q then p d u d x. So, this will be 1 minus 2 x this implies p P is 0.6 and p Q is 0.2 just you substitute the point p and q then q 0, so this implies q P is 0 q Q is 0.

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characteristic equation $am^2 - bm + c = 0$
 $\Rightarrow m^2 - u = 0 \Rightarrow m = \pm\sqrt{u}$
 $\therefore f = \sqrt{u}; g = -\sqrt{u}$
 $f_p = \sqrt{0.16} = 0.4; g_q = \sqrt{0.24} = 0.490$
 $g_q = -0.490$
to find (x_R, t_R)
 $t_R = f_p(x_R - p) = 0.4(x_R - 0.2)$
 $t_R = g_q(x_R - q) = -0.490(x_R - 0.4) \Rightarrow x_R = 0.310$
 $t_R = 0.044$

Now, let us go for the characteristics equation, so characteristic equation the equation we have so a is 1 b is 0 c is minus u. Therefore, so this implies m square minus u equals to 0. Therefore, f equals to root u and g is minus root u, now let us compute f P so this is then f Q, f Q is p is 0.2, q is 0.4. So, f Q is root then g Q is minus now we have to find x R t R because this is the next task to find R. So, t R is so this implies we get x R and t R so I have pre calculated by considering some random values so you must verify this.

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along the characteristics $a m dp + c dq + e dt = 0$

$$1(0.4)(p_R - 0.6) + (-0.16)(q_R - 0) + (1 - 0.04)(0.044) = 0$$

$$1(-0.49)(p_R - 0.2) + (-0.24)(q_R - 0) + (1 - 0.16)(0.044) = 0$$

$$\Rightarrow p_R = 0.399 ; q_R = -0.246$$

along p_R, u_R :

$$u_R = 0.16 + 0.399(0.710 - 0.2) + (-0.246)(0.044 - 0) \Rightarrow u_R = 0.2095$$

along q_R, u_R :

$$u_R = 0.24 + 0.299(0.310 - 0.4) + (-0.246)(0.044 - 0) \Rightarrow u_R = 0.2096$$

Now, along the characteristics we have the relations $a m dp$. So, the corresponding discretized versions if we use then we get a is 1. I am just substituting the corresponding values nothing else so we get p_R is q_R is, now the next task is to obtain along P_R, u_R . So, this will be u_R equals to 0.16 this is u_P plus so this implies u_R equals to zero point along q_R, u_R so along q_R so their close because u_R must be same they have to improve small error. So, this is the method of the characteristics for the second order PDE. Now, let us make use of the characteristics properties and then try to see the numerical solution of the first order PDE. So, the story is small as same.

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Quasi-linear I order

$$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = 0, \quad a - \text{constant}$$

general

$$\frac{\partial u_i}{\partial t} + \sum_{j=1}^m a_{ij}(x, t, u_1, \dots, u_m) \frac{\partial u_j}{\partial x} + b_i(x, t, u_1, \dots, u_m) = 0$$
$$\bar{U}_t + A \bar{U}_x + B = 0$$
$$A = \begin{pmatrix} a_{11} & \dots & a_{1m} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mm} \end{pmatrix}, \quad \bar{U} = \begin{pmatrix} u_1 \\ \vdots \\ u_m \end{pmatrix}, \quad B = \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix}$$

So, before we go to the numerical so these are nothing but Quasi-linear first order. So, we have to reduce a bit. So, this is the first order we considered yesterday as an example of conduction of with particle kind of, however there the scenario is different a is not constant. So, u is dependent on x and t and e are independent variables. Now, more general is something like this. So, this can be put it in a matrix form right where A is so we revisit this, and we saw discuss numerical method of system as well now in this.

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• if $a_{ij} = \text{constant}$, $b_i = \text{constant}$: linear - constant coefficients


$a_{ij} = a_{ij}(x,t)$, $b_i = b_i(x,t)$: linear - variable coefficients

B depends linearly on \bar{u} : linear

$A = A(\bar{u})$: quasi-linear

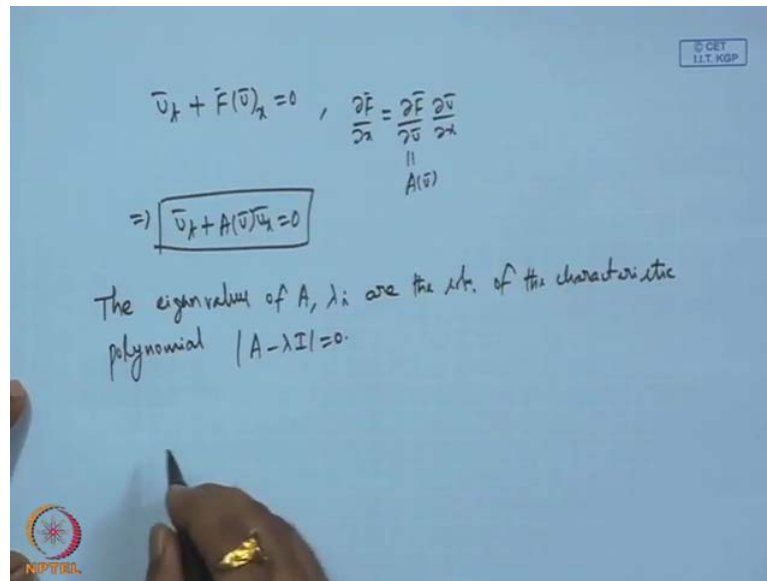
$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = 0$ linear advection

$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0$ inviscid Burgers equation



If a_{ij} is constant then b_i is constant then the equation is linear constant coefficients, or if a_{ij} is $a_{ij}(x,t)$, b_i is $b_i(x,t)$ then linear variable coefficients. If B depends linearly on u , so then linear depending on other coefficients variable, but it is linear if A is depending on u . So, then it is Quasi-linear, so examples. So, we discussed numerical solution of this little later, so this linear advection then so this is inviscid burgers equation.

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On the other hand more generally, so these are partial derivatives this notation, so where du f du x and this we call a of u the system reduces to, so this is more general. Now, the characteristic concept before we proceed, first order can also be classified depending on the characteristics, so we must discuss that so the Eigen values of A , λ_i are solution of the characteristic polynomial. Now, let us consider an example.

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example

$$\frac{\partial p}{\partial t} + \rho_0 \frac{\partial u}{\partial x} = 0$$

$$\frac{\partial u}{\partial t} + a^2 \frac{\partial p}{\partial x} = 0$$

$$\Rightarrow \bar{u}_t + A \bar{u}_x = 0 \quad (*)$$

$$A = \begin{pmatrix} 0 & \rho_0 \\ a^2 \rho_0 & 0 \end{pmatrix}, \quad \bar{u} = \begin{pmatrix} p \\ u \end{pmatrix}$$

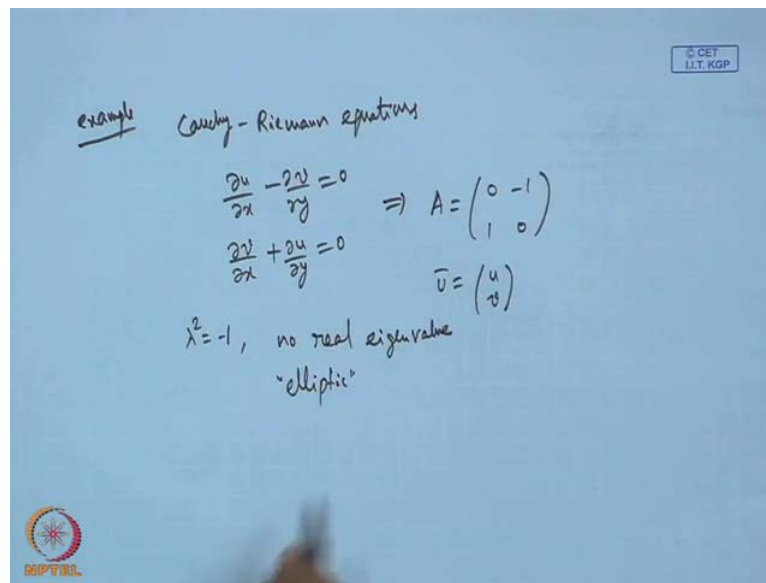
$$|A - \lambda I| = 0 \Rightarrow \lambda_1 = -a, \lambda_2 = a.$$

A system of the form (*) is said to be hyperbolic at (x, t) if A has m real eigenvalues $\lambda_1, \dots, \lambda_m$ and the corresponding set of m linearly independent eigenvectors k^1, \dots, k^m .
 strictly hyperbolic if λ_i are all real distinct

Suppose, the system is given by this and it must be coupled u naught is constant A is constant. So then this can be written as $u_t + A u_x = 0$, where A is given by $\begin{pmatrix} 0 & \rho_0 \\ a^2 \rho_0 & 0 \end{pmatrix}$ now, if you consider the Eigen values of this matrix, we get $\lambda_1 = -a$, $\lambda_2 = a$ now similar to second order one can define depending on the Eigen values.

So, the definition is as follows a system of the form (*) is said to be hyperbolic at x, t , if A has m real Eigen values and the corresponding set of m linearly independent Eigen vectors we can call k^1, \dots, k^m . So, this is said to be hyperbolic x, t if A has m real Eigen values. Now, the system is said to be strictly hyperbolic if λ_i are all real distinct. So, with respect to first order also one can classify then suppose you consider another example.

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example Cauchy-Riemann equations

$$\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} = 0 \Rightarrow A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$
$$\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = 0 \quad \bar{u} = \begin{pmatrix} u \\ v \end{pmatrix}$$

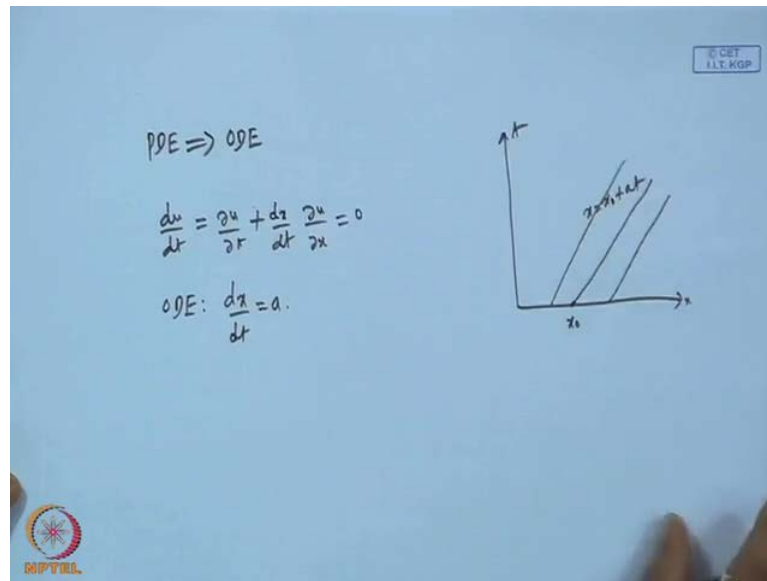
$\lambda^2 = -1$, no real eigenvalue
"elliptic"

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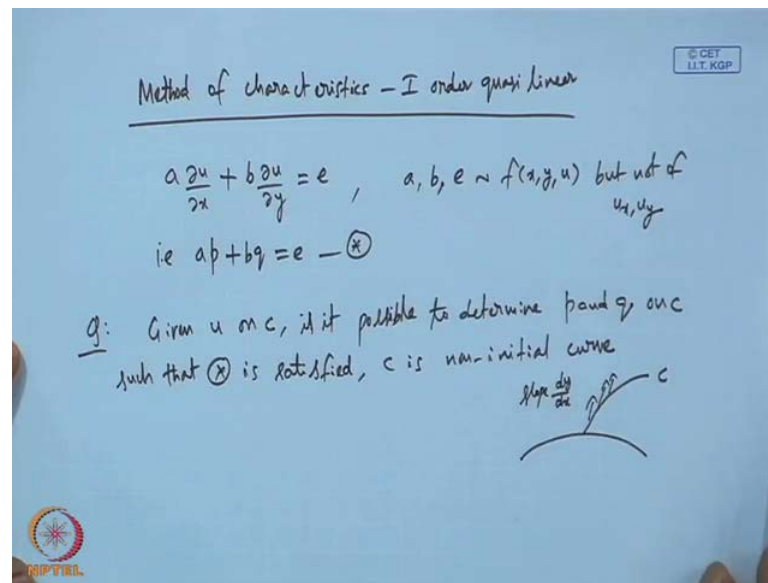
Which is quite popular, suppose you consider C R equations Cauchy Reimann then $u_x = v_y$, $u_y = -v_x$. So, this implies A is and u is v in this case λ^2 is minus 1. So, no real Eigen value hence this is elliptic, so we have extended the concept to the first order equation as well, now the characteristics of first order as I mentioned.

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What is the property of characteristic, so if you are taken an initial point. So characteristic curve is given by this so this is x naught this is x equals to x naught plus $a t$ where a is slope. So, these are the characteristic curves right, so what will happen? Characteristic curves in some sense they reduce PDE to Ode, so and then one can obtain along the characteristic curve. So, this is 0 and what is the ODE, the ODE is you see here a . So, the ODE is dx by dt equals to a now similar to second order, we would like to discuss briefly how do we proceed to compute solution along characteristics.

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So, method of characteristics first order Quasi-linear, so we consider $a \frac{du}{dx} + b \frac{du}{dy} = e$. So, as given a, b, e are functions of x, y, u , but a, b and e so they are functions of x, y, u , but not of u_x, u_y , but not of u_x, u_y . So, this equation is nothing but $a p + b q = e$, right? Now what is our aim, the question given u on c is it possible to determine p and q on c such that, star is satisfied where c is non initial curve. So, that means this is an initial curve, than this is c . So, if u is given on this is it possible to determine p and q on c such that star is so the answer is true like second order, so where in this case this slope of these tangents is denoted by $\frac{dy}{dx}$.

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$ap + bq = e \quad \text{--- (1)}$

$du = \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy = p dx + q dy \quad \text{--- (2)}$

eliminating p , $du = \frac{e - bq}{a} dx + q dy$

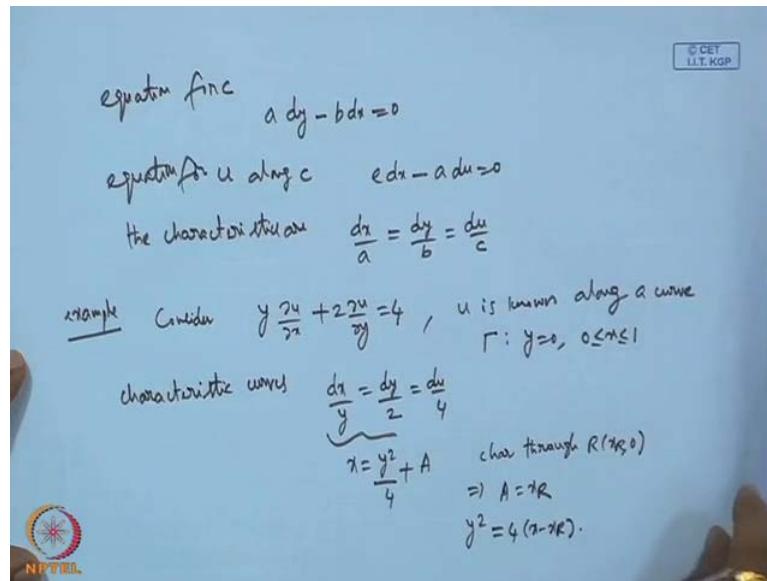
$\Rightarrow q(a dy - b dx) + (e dx - a du) = 0 \quad \text{--- (3)}$ independent of p

if $a dy - b dx = 0$ then (3) is independent of q as well.

curve c is having a slope $\frac{dy}{dx}$ such that
 $a dy - b dx = 0$ along which $e dx - a du = 0 \quad \text{--- (4)}$

So, we have the following scenario $ap + bq = e$ then $du = q dy$. So, then eliminating p , we have this implies, so this is independent of p this is independent of p . Now, this can be made independent of q , if 0 then this is independent of q as well. Therefore, curve c is having a slope $\frac{dy}{dx}$ such that $a dy - b dx = 0$ this is satisfied so this is.

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So, that means equation for c equation for c a d y minus b d x equals to 0 and equation for u along c so therefore, the characteristics are the curves. So, before we proceed analytically numerically, let us see a simple case. So, we consider y equals to 4 and say u is known along a curve gamma, which is y equals to 0. Now, the characteristics curves d x by y is dy by 2 is d u by 4. Now, let us consider these two. So, by considering these two we get x is y square by 4 plus A, then if the characteristics passes through R, characteristic through R. So, this if we substitute x R and y is 0 and we get a to be x R so this implies we have A is x R. Therefore we have y square equals to 4 into x minus x R. Now, along this characteristic.

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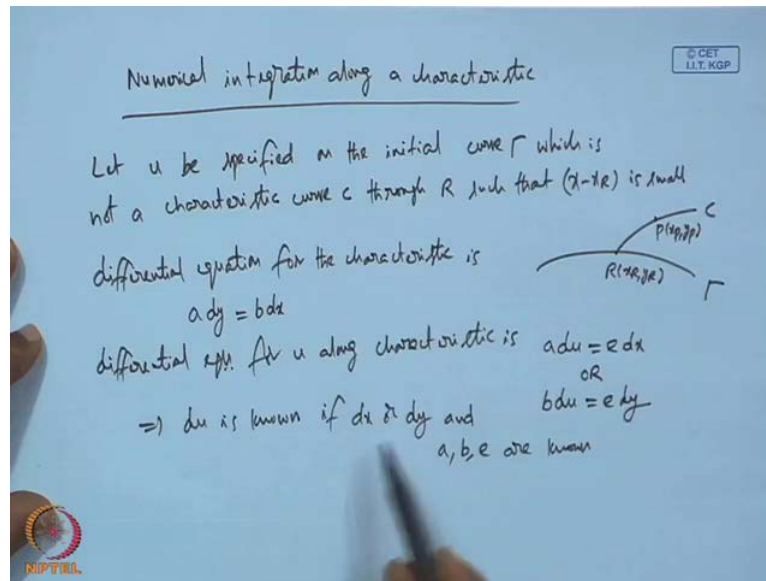
$y^2 = 4(x - x_R)$
along this char. this is $\frac{dy}{dx} = \frac{du}{dx}$
 $\Rightarrow u = 2y + B$, $u = u_R$ at $R(x_R, 0)$
 $\Rightarrow B = u_R$
 $\therefore u = 2y + u_R$

$y^2 = 2(x - x_R), u = 2y + u_R$

$R(x_R, 0)$

So, we have the characteristic y^2 is $4(x - x_R)$. Now, along this characteristic the solution is $u = u_R$, this implies now again $u = 2y + u_R$ at $x = x_R$ which is u_R . So, this will give us therefore, $u = 2y + u_R$, right? So, in this case the curves look like this, suppose this is the point so these are the curves $y^2 = 2(x - x_R)$ along which $u = 2y + u_R$. So, if u is known then one can compute so this is the analytical scenario.

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Now, we will like to consider numerical integration along a, so having obtained analytical. So, we want to make use of concept of characteristics then compute the solution numerical. So, this in some sense similar to second order, but let us have a look at it. So, let u be specified on the initial curve γ , which is not a characteristic curve c through r such that x minus x_r is small.

So, that this is the γ this is c and R and consider P , then the differential equation for the characteristic is $a dy = b dx$ that is what we have seen, then the difference equation for u along characteristic is $a du = e dx$ or $b du = e dy$. So, this implies du is known if dx or dy and a, b, e are known analytically also we have seen this. Now, how do we go for the numeric?

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first approximation

assume that x_p is known

then $a dy - b dx = 0$
 $e dx - a du = 0$

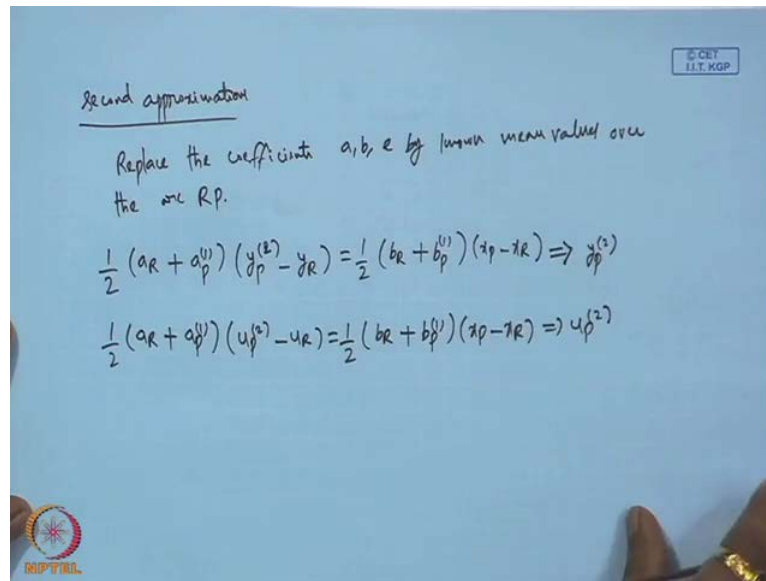
$\Rightarrow a_R (y_p^{(1)} - y_R) = b_R (x_p - x_R) \Rightarrow y_p^{(1)}$

$a_R (u_p^{(1)} - u_R) = e_R (x_p - x_R) \Rightarrow u_p^{(1)}$

The diagram shows a curve with a point P and a point $R(x_R, y_R)$ on the curve. A tangent line is drawn at point R . The curve is labeled C and the tangent line is labeled T . There is a small logo in the top right corner that says '© CET I.I.T. KGP' and a logo in the bottom left corner that says 'NPTEL'.

So, first approximation first approximation this is P assume that x_P is known then because we have to approximate $a dy - b dx = 0$, then $e dx - a du = 0$. So, this pair was alternately another pair could be, so this we are discussing a $R y_P$ first approximation equals $b_R x_P - x_R$. So, this would give if you know x_P the rest are all known y_P can be obtained than from this equation u_P can be obtained.

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Now, second approximation replace the coefficients a, b, e by non mean values or the arc RP . So, we consider these two equations and then we replace the mean values, so that would be so this goes like this so you can. So, this is first approximation what we have done we construct this equation than assuming x_P is known we can obtain y_P 1 than u_P 1. Now, we replace this coefficients by average you can see a_R and a_P 1 so then we get second approximation from here y_P 2. Similarly, from here we get u_P 2 so that is how we compute.

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example $\sqrt{x} u_x + u u_y = -u^2$
 $u = 2$ on $y = 0, 0 < x < \infty$

analytical $\frac{dx}{\sqrt{x}} = \frac{dy}{u} = \frac{du}{-u^2}$

$\Rightarrow y = -\log A u$
 $u = 2$ at $R(x_R, 0) \Rightarrow A = 2$
 $\therefore y = \log \frac{2}{u} \quad \text{--- (1)}$

$2\sqrt{x} = \frac{1}{u} + B \Rightarrow B = 2\sqrt{x} - \frac{1}{2}$

$\frac{1}{u} = 2\sqrt{x} + \frac{1}{2} - 2\sqrt{x} \quad \text{--- (2)}$

eliminating u , $y = \log 2 (2\sqrt{x} + \frac{1}{2} - 2\sqrt{x})$ char. through $(x_R, 0)$
 along char. $u = 2e^y$ or $u = (2\sqrt{x} + \frac{1}{2} - 2\sqrt{x})^{-1}$

So, let us have a quick look at example one consider this, suppose this is the example then analytical $d x$ by root x $d y$ by u $d u$ by minus u square. If you consider this y is minus $\log A u$ then u equals to 2 at $R \times R 0$ this implies A is to therefore, y is \log , so this is then we construct these two we get and again we can eliminate. Therefore, we have 1 by u right then eliminating u we get $\log 2$. So, this is the characteristic through, characteristic through $x R$ then along characteristic the solution is u equals to 2 or u equals to 2 root x plus half either from here or here.

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Numerical

I approx. $a = \sqrt{x}$, $b = u$, $e = -u^2$

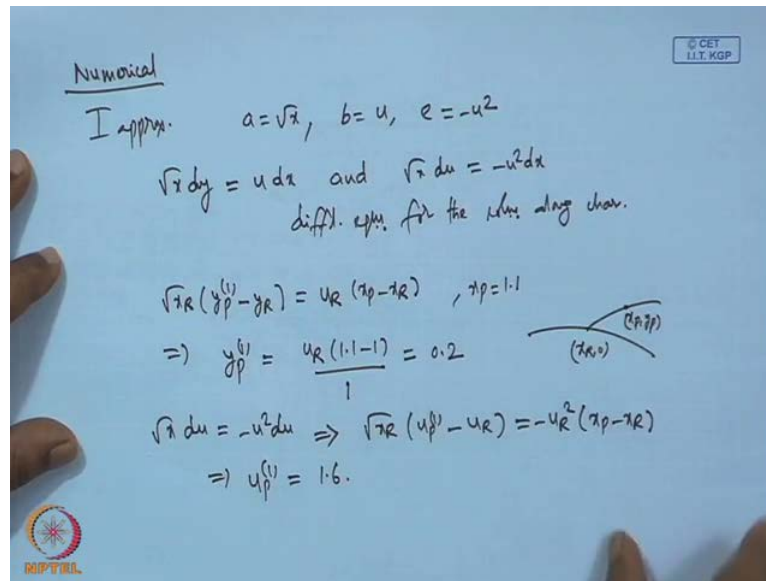
$\sqrt{x} dy = u dx$ and $\sqrt{x} du = -u^2 dx$
diff. eqns. for the solns. along char.

$\sqrt{x_R} (y_P^{(1)} - y_R) = u_R (x_P - x_R)$, $x_P = 1.1$

$\Rightarrow y_P^{(1)} = \frac{u_R (1.1 - 1)}{1} = 0.2$

$\sqrt{x} du = -u^2 dx \Rightarrow \sqrt{x_R} (u_P^{(1)} - u_R) = -u_R^2 (x_P - x_R)$

$\Rightarrow u_P^{(1)} = 1.6$



Now, let us see numerical first approximation a is this b is this. Then consider the characters solutions this, so these are the definitely equations for the solutions. So, the differential equations for the solutions along, I am using short forms. Now, if we approximate first approximations $u_R \times P$ minus x_R , so this implies $y_P^{(1)}$ is $u_R \times 1.1$ minus 1 by x_R is 1. So, we have considered x_P is 1.1. So, this is so this is $x_R = 0$ and this is $x_P = y_P$. So, our initial condition is x_R and x_P are close enough. So, the decrement is or increment 0.1, so this is now we consider this implies now from here we get $u_P^{(1)}$, so y_P and then we got this, right?

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II Approx

$$\frac{1}{2} (u_R + u_P^1) \Delta x = \frac{1}{2} (v_R + v_P) (y_P^2 - y_R).$$
$$\Rightarrow y_P^2 = 0.1757$$
$$(v_R + v_P) (u_P^2 - u_R) = -\frac{1}{2} (u_R^2 + u_P^1) \Delta x$$
$$\Rightarrow u_P^2 = 0.6559.$$

So second approximation, so we go for u_R plus u_P 1 d x x R x P y R. So, this will give y_P 2, so you can substitute the values than so this into u_P 2 minus u_R . So, this will give u_P 2, so this is the numerical procedure along the characteristics. So, the example is little I mean. Since I have a pre calculated I have done it you can verify. So, next lecture will talk about finite difference method and till then bye.