Linear Programming and its Extensions Prof. Prabha Sharma Department of Mathematics and Statistics Indian Institute of Technology, Kanpur

> Lecture No. # 29 Min-Cost Flow Problem

(Refer Slide Time: 00:24)



So, let us continue with our miss minimum cost flow problem; I will quickly revise the whole thing. So, we said that we will have starting solution as a structured (T, L, U), where T is the, a spanning tree; yes, spanning tree consisting of basic arcs.

Now, these arcs, the flow may be, some of the flows may at their upper bounds, but we will call these the basic arcs. So, the spanning tree is the spanning tree consisting of basic arcs. Then L is the set of non-basic arcs at their lower bound, which is zero in our case right now.

So you can see, the, you can guess that they can be situations, where the lower bounds are not necessarily zeros, we will just mention them in at the end of the... And that this thing over, then U is the set of non-basic arcs at their upper bounds. So, we have the

structure given to us starting thing and we also need to discuss later on how to get a starting spanning tree structure like this; we will do that, so anyway then given this, the compute the dual solution, so I was mentioning the last time also compute the dual solutions. So, this we do by select to or put w 1 as 0; so, we are always do that and so, we call this the, we also call this the root node.

And therefore, the spanning tree is also called a rooted tree and the significance of this comes in later on but anyway right now we had saying that w 1 is 0; so, then you can compute the remaining w I n minus 1, w i is uniquely.

So, you can do that, because you will have for the basic tree, you have n minus 1 arcs and once you fix one of the w i's, you have n minus 1 w variables to decide given n minus 1 equations and so, because the relative prices for the basic arcs must be zeros, so we get the remaining this thing.

(Refer Slide Time: 03:53)



And the process is not difficult, because you see it is a spanning tree, so it is a connected tree with n minus 1 arcs; so, once you have your arc 1 and here you have put the dual variable as 0, then there will be at least 1 arc incident on it correspondingly for this let say it is j1, then you will fix, you say that w 1 minus w j 1 is equal to c 1 j 1, so that is

tell you that w j 1 is minus c 1 j 1, similarly, because it is a connected thing they will may an arc like this or like this.

So, you just move on because the tree structure is given to you, so you can and given as we mention that the basis is triangular; so, backward substitution you are essentially doing and the backward substitution, you are starting from node 1 onwards. So, you can accordingly fix as you go along the tree, you can fix all the dual variables also, so we do that and then...

So, after that, compute c i j bars right and we said that if c i j bar is greater than 0 or x i j 0 right for non-basic variable which is at its lower bound, then you cannot, because increasing the value here would also increase the objective function value; so, this is the so, this is optimality criteria for x i j 0 and if c i j bar is less than 0, for a basic non-basic variables at its upper bound, then also we cannot improve the value of the objective function, because if you want to reduce this value then c i j bar negative, the product will become again positive and it will be a positive increase in the value of the objective function right. If this, then the current solution is optimal. So, therefore, we will look for, we will always at the end of, once we have obtained a basic feasible solution; we will very check for optimality, if we find some arcs violating the optimality condition, then we will consider them for entering into the basis. So, now, here as I said, right now I will follow Danzig's pivot rule which says that you select the arc which violates optimality criterion the most, that means, it may either be c i j bar negative.

So, that means, you will have to compute all the c i j bars for the non-basic arcs and then select the one which violets the optimality condition the most. So, then it is rule and **I** as, I told you that the other pivot rule could be that, you the moment, you find one arc which is violating the optimality condition, you enter it.

And of course, there can be (()), so these are the two extremes, you first compute all c i j bars and then find the best one to induct, best one in Danzig cells or you just the moment, you find one arc which is violating the optimality condition you try to enter it. So, there are also in between rules and you know one can, I will give you some more references later on, see you can go through them, so that is it. So, once we, then

therefore, we use Danzig's pivot rule, so we decide on an arc to enter the basis and now what happens when an arc enters the basis.



(Refer Slide Time: 08:05)

So, that means, you will add. So, suppose, consider now let us say that c i j bar is less than 0 and currently x i j is 0; so, that means, this is a non-basic variable at its lower bound and the corresponding c i j bar is less than 0. So, improve increasing the value of x i j will improve the objective function value. So, in that case, if you consider T union i j has a cycle, see I went through all this in detail for the transportation problem, where I demonstrated to you, how a theta loop could be available and the same kind of thing happens here. So, we will not spend time on rigorously establishing that this will have a cycle but, anyway because this will be now n arcs and so they must be linearly dependent, because the rank of the matrix is n minus 1.

So, this will have a (()) cycle, we showed you is a minimal in his concept minimal dependent set; so, that means, it will be the set of columns which have a two entries, each column of the set consisting of the cycle will have two entries one plus 1 minus 1 and so, when you add up, you can add up, all the rows will be 0, anyway so this has a cycle.

So, now let us consider a configuration; suppose this is i and this is j and then you may have j 1 and then you may j 2 and this may be j 3 and then this. So, this is your cycle and

now what we talk about I have already mentioned all these things, so I am just going through them; so that, you have a, you can recall all these things, so the thing is that, we want to increase the flow along this direction right, on the arc i j because the c i j bar is less than 0.

So, then we give an orientation to the cycle which is the same as the orientation of the arc, because you want to increase the flow in this direction; so, that means, a, now the ideas to determine by what level you can raise up this value; so, suppose I want to increase the flow by delta here, then this arc also has the same orientation as the cycle or as the arc I j; therefore, also here also the flow will increase.

But now, this arc has an orientation which is opposite to the orientation of the cycle therefore, this will the flow here will decrease and so we indicate that by minus delta, because see the arc is in this direction; see, if I try to flow something which means I am actually reducing the flow on this arc right, then here this also has the same orientation, so this will be plus delta and this will be delta.

So, all these arcs will have, now what are the considerations as usual again the same, see the, it is a same simplex algorithm, I first showed it to you, how it can be implemented on a transportation array, you saw the simplifications tremendously its tremendous simplification. Now, I am just trying to show you how to implement the simplex algorithm on the on a graph on a network; this is the difference, otherwise the theory and everything remains the same.

So, in any case you want to just quickly recall, so here you see you will have three values; delta 1 will be the smallest value for which a basic arc; so, that means, I am considering, see here you have this kind of thing and you may already have a flow here j j 1; so, then you do not want and here this would be the flow, now, will go up to plus delta. So, then we do not want the flow on this arc to go beyond its upper bound, so we saying smallest value for which a basic arc reaches its upper bound. So, that means, you are going to say that this is u j j 1, so which implies the delta isless than or equal to u j j 1 minus x j j 1 delta is this. So, then among all such deltas, that means, among all the positive deltas, so here for example, this would be your delta would be less than or equal to u j 3 i minus at whatever the flow here x j 3 i and so on, so far, all positive deltas you will compute the smallest one, because none of these constraint should get violated; so,

delta 1 is the smallest value for which a basic arc delta 1 is smallest value of delta for which basic arc reaches its upper bound.

Similarly, delta 2 would be, now here you see that for they once for which is negative, see here the new value is x j 2 j 1 minus delta, I am trying to flow delta units among this, which means that, the you actually reducing the flow on this arc by delta; so, this is, this now this should remain greater than 0, which implies that delta has to be less than or equal to x j 2 j 1.

So, whatever the flow on the arc j 2 j 1, your delta cannot exceed that for all the minus 1. So, delta 2 is the smallest value for which no basic variable, no basic arc has negative flow, so you want to make sure that. When you increase the flow on a basic non-basic arc none of the basic arcs has become, has a flow less than 0 and what is your delta 3, I am increasing the flow here.

So, delta 3 is actually your, here it will be u i j or in other words, delta 3 is the upper bound constraint for the incoming arc you would increasing the flow here. So, in a, I can say that this is going to enter the basis, it is going to become basic depends on how what the choice is right. And now let us quickly write down, so how and similarly, you can write down these values, when so I have considered the case or maybe I will draw it again for you here.

(Refer Slide Time: 15:34)



And will quickly revise the considerations; so, now you can also have a situation when the arc has a flow like this, then may be let us consider the same situation j 2 has this one and now in this case when c i j bar is greater than 0 and the flow x i j is u i j; so, that means, this is saturated on. And **if part**, if the c i j bar is greater than 0, producing this value will give a decrease in the value of the objective function.

So, therefore, now your orientation will be reversed, I will do it this way and so, this will be minus delta, here again this will be minus delta and this is also opposite, but this will become plus now and this will be minus delta. So, I want to decrease the flow on or arc i j, then I will use this device; so that, I, so that, the orientation or becomes opposite to the direction of i j because I want to give flow into a cycle in this direction anyways and you can you self-observe just like theta loop that, because I am changing the flow along a cycleat a every node conservation is there and so your constraints will not be violated the constraints will remain entire. So, here also what we are doing is, we are saying that this has to be like this and which means that the flow here will go down by delta. And so, again when you want to determined you will have the three numbers, again see here, delta cannot, so here delta cannot be greater than u i j, because otherwise the flow here will become negative and then for all these minus arcs, see here the flow.

(Refer Slide Time: 17:52)



So, therefore, here the delta will be governed by the amount of flow that you have in this direction, because the same consideration as you had for the arc j 2, j 1 see here we said

that delta has to be less than or equal to x j to is, so wherever there is a minus sign, the delta will be governed by the amount of flow, that is there already in the arc.

(Refer Slide Time: 18:06)

So, in our case, this one, the flow is here u i is equal to u i j and on this just x j 3 i and so on so for, minus 1, the value of the delta has to be governed by the amount of flow, that is already there in network; for plus 1, here your consideration will be that, this arc should notagain exceed its upper bound. So, here you will have the that delta must be less than or equal to u j 2 j 1; in other words, your whatever the flow j 2 j 1, this is the flow plus delta should be less than or equal to u j 1 j 2 and so, once you understand because the theta loop part was very welldone with you.

So, you understand that this everything, so once, that means, depending on what kind of a arc we are entering into the basis, we will compute these things and decide. And so, now once you have decided the value of delta, so then you update, that means, update the flow in the network; so, you, this is the next step update the flow in the network.

Now, you have to recompute the dual solution, so just has in the case of the transportation problem. I showed you a, show shortcut, so here also there is a shortcut we do not need to compute the dual solution from scratch, we can take advantage of the our earlier calculation; so, for example, what we are saying is that, if suppose you have

something like this, suppose this is a tree solution and suppose this arc is a candidate for entering the basis.



(Refer Slide Time: 20:30)

So, then and I should have told you that wherever, the say for example, out of these three, I should have mention this also, see the (())of example, if delta is equal to delta 1, that means, the minimum of the three, so I should have written that down. So, final choice of delta is minimum of delta 1, delta 2, I hope you can read it, this is delta 3, so out of these, when once you compute these three numbers, then choose its smallest one of the three and that will be the a value of delta, at which this variable will enter, the this arc will become a basic arc and the flow will get determined.

So, here for example, if delta is delta 1, then what is happening if delta is delta 1, that means, one of the arcs is reaching its upper bound, before any of these two things is happening, so what will be do, once this happens so again I will not right it down, because the same steps for the as we did for the transportation.

So, once an arc reaches its upper bound, we will rename it as a non-basic variable and drop it from the basis; so that means, suppose it is this arc which is reaching its upper which for this minimum is attained; so, then this will reach its upper bound, when I update the flow so this will become a basic arc and this would become non-basic. So, again I will have to recomputed my, so that means, this is my incoming variable, this is my exiting arc from the basis; if the minima occurs for delta 2 out of these 3, delta 2 is a smallest number, that means, some arc is going to become 0 when I have the flow at level delta in the cycle.

So, that means, one arc will become and so you can say that for example, here smallest variable for which the basic arc has negative flow will become negative; so, that means, before that happens, so here that means this arc therefore, becomes non-basic and this arc becomes basic the usual pivot, because this will become 0 and this has become positive and if delta is minimum for delta 3, then this has reached its upper bound, before anything else has happens.

So, that means, I do not have to change the status of i j, the arc i j remains non-basic, but now it reaches its upper bound, so it is there is a positive flow on the arc which is equal to its upper bound, but I do not change the status of the arc it remains non-basic. So, these are the three things, that to so you have this is, this describes your pivot rule completely and accordingly you can also manage the pivot rule here.



(Refer Slide Time: 23:14)

So, now you have to recomputed; so, how do you recomputed the dual solution; so, idea is that, I will give you the simple rule here, try to write it in this much space. So, this is suppose, arc i j is entering the basis and arc p q is leaving the basis and I have, you have

seen that it can be in two different ways, either the flow is becoming 0 or it is reaching its upper bound two things can happen.

So, its leaving the basis, now what you do is, before you do this, actually arc i j is entering and this arc p q is, so drop p q from the current tree, which I mean is that, before you have done the pivot, before the pivoting, drop p q form the tree before the privet; so, you are dropping this in that and then this, this will decompose the tree into two trees T1 and T2, where one node, one belongs to T1, so your root node

Node 1 belongs to so we will call that sub tree T1, in which T1 lies so and the other one is T2; so, that will always happen, you see because it is a minimally connected tree sub graph; so, let say example, if I drop this arc from the tree, then I will have this portion and I will have this portion, look at I drop this arc I drop this arc, then I will have T 2 will be just simply this node and T1 will be this because one belongs to T1; so, you will always have 2 sub trees, a moment you drop the exiting arc from the basis.

(Refer Slide Time: 25:38)



So, then and now you have two cases, q belongs to T 2, see so therefore, before I say that so wi's for I belonging to T1 do not change why because this remains 0. So, since T1 all these arcs are connected to node 1; so, therefore, your dual equations remain intact and so these dual variables will not change.

(Refer Slide Time: 26:24)

So, wi's for i belonging to T1 do not change, because my value here of the dual variable corresponding to the root node does not change. Now, if q belongs to T 2 for the two possibilities, if the arc is like this, so for example, and let me say that this is the exiting arc, so let us say 35 is the exiting arc and this is coming in, in this one; so, what we are saying is that, here either so what is it, if this is leaving the if you are dropping this, then what is your T 1, see I have drop this, see your T1 is this these three arcs and your T 2 will be simply this one T 2consists of the arc 56.

So, now, you if the arc is in this direction, then your node 6 belongs to T 2 and if the arc will be in this direction, then what we will say is that, see if I call it p q, then p will be in T 2, so that depends on the notation, if q belongs to T 2, then what is happening, so then you see, because p is not in T 2; so, the value of the p has not change, then you have the equation . So, then let me write it this way, then c p q minus w p plus w q is c p q bar and which is less than 0, because that is why we decided that p q will enter the basis that was at 0 level; so, then this is this, and if w q prime is the new value w q, then what is the equation that needs to be satisfied, then we want that w p minus w q prime should be equal to c p q now because p q is going to become a basic arc this is it; so, which implies that your w q prime is equal to q w p minus c p q and from here w p if you take it to this side is equal to w q minus c p q bar. So, that means, that the new value of w q prime is w q minus c p q bar. So, the value of w a lready discuss; this again in the

transportation problem, that now in this T 2, if for example, this value has change, then this value will also change because they are connected by the same amount; so, that means, what is our rule, now for all nodes in T 2 the dual solution.

(Refer Slide Time: 29:49)

(Refer Slide Time: 30:20)

0 (1

So, when we are re computing the a dual solution, so what comes out is that, wi's for i belonging T 1 do not change; so, you do not have to spend time computing them and for and w i goes to w i minus c p q bar for i belonging to T 2, where we know the p q is the exiting, sorry, what did I say here, yes it has been clear is i j is entering, so I should have

and the basic we drop pq and I should have, I should have said, if I say that, it is i j which is entering, then if j belongs to T 2, then I have to recomputed.

(Refer Slide Time: 30:40)

So, maybe it will be easier to I will keep it has q T 2 I have read this; so, here we will say that i j is the, is the exiting is leaving the basis n r p q is entering; so, make it the other way, so then drop i j from the tree before the pivot; this will decompose the tree into two trees and we will call T1, that tree for in which one lies and the other sub tree would be T2 and then we are discussing like this.

(Refer Slide Time: 31:30)

(Refer Slide Time: 31:33)

So, if q is T2, so therefore, we have to, so then the these values will change by c bar p q, so we said that you see when the arc p q is entering the basis and i j is leaving the basis, then why by dropping arc i j from the tree; you see it will get disconnected into two parts, we said. And then, so T1 and T2 will be the two parts of the tree and note we call T1 that subset of the tree in which node 1 the root node lies; so, therefore, T1 will be that particular tree and T2 is the other one. Now, the wi's, so recomputed the dual solution I

am giving you a simple formula; so, this is wi's and T1 will not change, it is only the wi's for the nodes in T2 which will change.

(Refer Slide Time: 32:12)

(Refer Slide Time: 32:36)

Recompter the due solution. and (i, i) is leaving the boris and and (p. q) is orthough the baris 4

And so here I am saying that see for i in T 2, the calculation I have already shown you the w i will change will reduce by c p q bar; so, that means, the new w i would be w i minus c p q bar and then of course, we will continue with the algorithm, but in case p belongs to T 2, that means, the arc p q that is coming into the basis, so, either the node p belongs to T2 or the node q.

(Refer Slide Time: 32:44)

So, in case, node q belongs to T 2, then we update the corresponding dual value by w i minus c p q bar and in case, p belongs to T2, then w prime p minus w q, you see well the calculation is simple, the new w p prime the value of this w p prime minus w q is c p q because the arc is coming into the basis, so, the new dual values should satisfy this particular dual constraint as equality.

So, therefore, it follow the w prime is w q plus c p q, now when you substitute for c p q bar, then the w q will cancel and you will have w p plus c p q bar; so, that means, w p has gone up by c bar p q. So, if p belongs to T2 then the dual variable will, the value will go up by c bar p q and since the, your T2 is connected, that means, that all nodes in T2 the, the dual variables will go up by c p q bar.

(Refer Slide Time: 34:05)

So, this is how if you can remember the simple formula, then you do not have to re compute the dual variables for all the nodes; you only have to re compute them by for the nodes in T 2 and that also the formula is simple, that if p belongs to T 2, then the values go up by c bar p q and i f q belongs to T 2, then they reduce by c bar p q or i belonging to T 2. So, once therefore, a real shortcut to re computing your dual solution, here again we are taking advantage of the structure of the problem; so, we are exploiting the structure and simplifying our computations.

(Refer Slide Time: 34:32)

(Refer Slide Time: 34:36)

(5.10)

So, now this happens, so then we continue, so then continue with the, I have already said that you update your flow in the network to re compute the dual solutions and then continue with the algorithm. Now, there are two issues that we need to look at and so I will first work out an example for you quickly, I will show you one or two iterations of the algorithm and then we need to look at how to compute the starting dual feasible

solution; that means, I must get a starting structure T, L, U and given a problem to solve and secondly, we have to tackle degeneracy.

(Refer Slide Time: 35:35)

And again is nothing different adjust, that here again people take advantage of the structure and try to come up with the simpler rule, for you know (()), so they take up this example, now here the numbers are c i j u i j; so, the first number is the cost, the second number indicates the upper bound on the flow, that can take place on that arc, then these numbers are the di's; so, here for node 1, it is 25 units, that is only source the other, so these 3 do not have anything available, then 5 and 6 are in our sense markets or the demand points.

(Refer Slide Time: 36:20)

So, then they add up so sigma b i is 0 and you are told that, this is the initial solution; so T is this and U contains these three arcs which the flow is are at their upper bounds and this is the arc which has 0 flow; 3, 4 so I have try to draw the thing here and let us see so 1, 2 and what we will do is, we will indicate the, I find it convenient to represent this as a broken line and so there 1, 2, for example, so you had 20 units this upper bound; so, that means, the flow here is 15.

So, then this flow is 10 and so the round circles indicate your basic arcs and the square ones indicate the non-basic arc at their upper bounds, the flow is at their upper bound, then you have 2, 4, the flow is at its upper bound which is again 15. So, I can fill up this and then you have 4, 6, the flow is 10, which is so we will again denote this by broken line and this is also a broken line.

So, then you have a 10, so 10 go up this way because this only thing; so, 10 going this way, then 2, 5 you have how much, now this is 15, this is going 15, so this much have 10 units of flow remember conservation; so, if 25 units are coming in here then 25 units have to go out. So, this just becoming familiar with the, you know when you trying to do the algorithm on a on a network. Now, here 5 units for required and so you have 25 then,

you have 4, 5 and 5, 6; so, 45you have 10 units coming here, then you need 10 more here; so, this will be 10.

And so 10 going out, so you must have 5 units coming here, because 5 units are demanded here; so, 10 are coming, so this way you have 5 more units, so 15 are coming, then 5 get absorbed here and 10, go on this way. So, this is your starting feasible solution and 3, 4 is 0 and in fact 3, 4 and 3, 5 both I have not, may I should have included 35 also, both these arcs are at their lower bounds which is 0. Now, and we to compute the dual solution, we will quickly do this and then you see that here, I will just write it out; so, the cost is 3, so that means, 3 minus 0 plus w 3 is 0, the basic arc which says that w 3 is minus 3.

So, it is minus, so for these arcs, it is so, I will write this is minus 3; so, same thing we were doing that on transportation array, now we have to do it on the network. So, here again this were this cost is how much 3 into 2, 6, so you want that the c i j value, that means, the c i j value 6 is equal to essentially u i minus 3 plus w 2; so, w 2 becomes 9, but then it should be minus 9; I think according to me, this is 6, so we want the relative price to be so 6 plus 3 plus w, sorry this is minus.

So, therefore, so your w 2 is minus 9 and I will tell you, why I could realize that, this is not correct, the plus 9 was not correct, I will get back to you in it; similarly, let us quickly do this, so this is a because for the transportation problem, it all sub plus we had got rid of the negative sign, but here the negative sign is intact, therefore, so for 25 what is the calculation, so 2 should be equal to minus 9 minus w 5 so minus w 5 is or w 5 is 11 minus 11. And for this one, again you will have to right out 7 is equal to minus 11 minus w 4, so that gives you w 4 as something wrong, because so w 4 is minus 18 let us see that; let me right it again, see what we are saying c 4 5 minus w 4, again I was not writing it correctly.

So, this is because arc is 4, 5, so minus w 4 plus w 5 is 0; so, therefore, this implies that w 4 is equal to c 4 5 which is 7 and this is minus 11, so this is minus 4, w 4 is minus 4 we will check this in a minute. Now, the values, fine, so then this for 5,6 what is the, what is happening the cost is 1; so, one should be equal to minus 11 minus w 6; therefore, w 6 is equal to minus 12.

(Refer Slide Time: 42:11)

So, given this basic feasible solution, I compute the relative prices and you see that from here for 3, 4 that is positive, so that will not be candidate c 35 bar is minus 3, so this can be a candidate for entering the basis and c bar 24 or is 9 and since this is at is upper bound; the positive number here implies that, when I reduce the flow, the cost will also come down; so, these are the, where 4,6 is as its upper bound and minus 5 does not help.

(Refer Slide Time: 42:53)

-wi=distance of mode i ferm anis(3, 5) + (2,4) condi dates prenter anin, chara (2,4) ke reduced

So, therefore, the arcs that are candidate for coming into the basis, that means, arcs 3, 5 and 2, 4 are candidates for entering the basis and so we will choose arc 2, 4, that means, I

will reduce the flow but, before I continue with the algorithm I just want to make a note here that you that is a nice interpretation for the dual variables for the network flow problem; so, here you see minus w i will be the distance of node i from node 1.

(Refer Slide Time: 43:30)

(Refer Slide Time: 43:35)

-wi=distance of mode i ferm nodel while the the T. how on mac (2,4) here to ke reduced 120 reaches

That means, suppose I take the numbers which are the cos I can treat them as distances, so whether I call this as a distance of node i from node 1 or the cost of reaching node i

from node 1, whichever way you want to interpret the numbers here the c i j's, then you see for any basic feasible solution with respect to the given tree minus w i should measure up to the distance of node i from node 1 with respect to the tree.

(Refer Slide Time: 43:50)

So, for example, in the, in the solution here you see 1, 3, so here this is and we start with w 1 as 0, so then this is minus of this is 3, which is the distance of node 3 from node 1. Then you can go up so to reach to node 2 from node 1, this is the path, you will take so you add up the cos which is three plus 6, 9.

So, minus 9 is here w 2. Then similarly, when you come to node 5, this is the path; so, here this would be 3 plus 6, 9 plus 2, 11, so minus 11 is your w 5. Now, when you go to node 4, you see this arc, you travel from the opposite direction; so, that means, here, **I** will, when I want to compute w 4, the distance or w 4 is minus 4; so maybe I should write here minus 4, now this is or whichever way you want to do it fine, whichever way you want to do it fine. This will be minus 3 or minus 11, I have already come up to here minus 11, then this is travels in the opposite direction; so, I will have to write plus 7 here and so, this will be minus 4 or you want to do it, this way that 3 plus 5, so this is 11, so if 11 and then minus 7, so that is 4, so minus 4, so the distance or the cost of reaching node 4 from node 1 is a 4 in our term. And similarly, this is 12, that means, the currently so every time, when you re compute your dual solution, this will be a very good check, because you have small networks you can do it by hand.

So, therefore, you will know immediately, that given the tree solution with respect to the tree, we find out the path for each node from node 1 and then add up the cos of the arcs that make up that path and it should measure up to so minus of that some should measure up to the dual value, the current dual value; so, this was just I wanted to show you that the dual solution has a very meaningful interpretation here.

(Refer Slide Time: 45:55)

(Refer Slide Time: 46:15)

So, now, we continue with the algorithm, so I decide to choose 2, 4 because now I am using the Danzig rule, which says that you bring the most profitable arc; remembered it

is common you would bring in the most profitable arc into the basis. So, since c bar 2 4 is 9, so here the rate of reduction in the cost would be at 9 units this thing and c bar 35, c bar 35 is minus 3.

(Refer Slide Time: 46:34)

So, therefore, we will choose c bar 24 has to be reduced and so the cycle formed here would be this and I consider this and the orientation has to be this, because I am reducing the flow one 2, 4; so, then an arc 2, 4 the flow will go up and an arc 4, 5 again the flow will go down and delta here comes out to be 5, because remember we have to make show that the flow here should not become negative, the flow here should not exceed its upper bound and similarly, here also the flow should not become negative.

(Refer Slide Time: 47:31)

(Refer Slide Time: 47:42)

So, the numbers are 5, 5 is 10 and you take the minimum of the three numbers, then 25, so when your delta is 5, 25 will reach its upper bound, because the currently, the flow is 10 and if I add 5 more units 15, the upper bound will be reached. Now, I have three

choices here and 24 becomes basic because flow here has now come down from its upper bound and 4,5 what is happening for 4,5, what is the current flow the current flow is 5; so, if I reduce the flow, then this become 0. So, you see, you have, either you have a choice of allowing making 25 and a non-basic variable ordropping 45 which is a non-basic variable at 0 level.

(Refer Slide Time: 48:10)

So, we decide to, and this is where you see the problem in the simplex algorithm can come, because your choice of exiting variable is not unique. So, here drop arc 4, 5 and similarly, for the incoming variable also, we decide to drop arc 4, 5, is it and I have shown you the updated solution here, now this is 15, I am keeping it as basic 4,5 has been dropped this arc the flow has come down by 5 units.

(Refer Slide Time: 48:35)

So, this is it, now remember the shortcut that we have used; so, what is happening is that, when you see the drop in the arc, which is being dropped is 4, 5, so when you drop this from this tree, see you are dropping arc 4, 5 from here, then in the current tree, this remains intact it is only node 4; so, node 4 now becomes your T 2 and this is your T 1, because 1 belongs to this part of the tree; so, T 2 simply contains node 4 and since you are the incoming arc is 2, 4, remember it was non-basic; now, we are making it basic, so the incoming arc is 2, 4, so that means, q belongs to T 2.

(Refer Slide Time: 49:04)

And so, that means that the corresponding value for w 4 prime will go down by c 2 4 bar and this is c 2 4 bar is 9, so minus 4 minus 9 is minus 13 and this is your updated dual solution nothing else changes, because all the other nodes are in T 1, so there the w i is remain intact and this is the only one which changes and now you can again just do it exercise, that the distance from here to here should measure up to 13 and other distances remain the same, because that the only change you have made, we have made 4,5 has been dropped.

So, now, that means, we, I, you re compute my dual see relative prices and here you see that 3, 4 is a non-basic variable, the value is minus 7 c bar 3, 4; therefore, this is a candidate for coming into the basis and again we are using the most negative here, I am I mean absolute value in the largest value; so this minus 7. So, therefore, arc 3,4 enters the basis fine and now when you compute the delta, so I will let you do the computations

yourself, but I have giving you the number; so, delta is minimum, so all the three numbers are the same and here again you have you see lot of choices, your choice of deciding on the exiting variable is not unique; we let arc 3,4 remain and of course, because see here what is happening is that, when you allow 3,4 to enter at level 10, then 3,4 it reaches, its upper bound and all others also either become flow becomes 0 or attends its upper bound, whatever you can check out, what are the choices here.

So, in any case, see we will have to do least work, when we decide not to make not to change the status of 3, 4, it is just that the flow on 3, 4 becomes equal to 10, that means, it is equal to its upper bound. And so, we will not have to change anything, we will not have to change our dual solution, because no arc is leaving the basis; the basis remains intact. So, and then, but then what will happen is will remember if you allow 3, 4 to enter, maybe I can just show you here, see this your allowing to enter. So, your orientation will be this way; so, this becomes this and this comes down like this and so what is happening, that both of them or a 10 so since you are increasing the flow on this arc by 10 units, this flow become 0, this flow becomes 0.

So, you will have to, then decide on one of the variables, because you have to maintain 5 arcs in the basis; so, that you have connectivity; therefore, I will increase the flow by 10 here, so 3, 4. And so, this will remain non-basic at its upper bound, but here the flow will become, will not disturb this one; next table, I, the next diagram I will make, but I will keep 3, 4 and 3, 2 at 0 level but in the basis; so, this is what we are doing. So, therefore, we do not have to do any calculations it just that this number; now, the flow an arc 3,4 is also equal to 10 and both these flows come down to 10.

(Refer Slide Time: 52:30)

So, now, I have updated the solution here, remember these two became non-basic but at 0 level. So, this is the solution, now without because my dual solution did not change; so, I have from earlier calculation, your c bar 46 is equal to 4; 4, 6 is at its upper bound, so this would help in reducing the cost. And now, you see when you want to reduce the cost, your orientation of the cycle would be this; so, this would be minus delta, minus delta, this would be plus delta and plus delta, but you see that here delta would be 0, because this is already at its upper bound here, that is node flow on arc 2,4; so, I cannot reduce by the flow by any amount, therefore, delta by here is also 0; therefore, this is the d j, so that means, delta is actually minimum of 0,0,0.

I hope this point is clear, because the orientation has to be this, I want to reduce the flow on 4, 6. So, here also it will be minus delta, there is no flow on 2, 4, then when you want to come down this way, the delta has to be positive, so plus delta, but the flow is already at its upper bound.

So, therefore, the, a value of delta is 0, 0, 0, the minimum value which is equal to 0. Therefore, this is the degenerate pivot, but we, it will help us to change the status of certain arcs, so that, we get a new basic feasible solution; in the new, the sense we get a new tree, so let arc 2, 4 exist, we are saying that because at its upper bound, so I can make it non-basic and arc 4, 6 enter the basis. So, there not changing the flow, it all, it is just that now I am calling this arc as non-basic and this arc 46 as basic, because trying

out a new basis and this so I wanted to show you the step also. Now, here when arc 4, 6 enters and you are dropping arc 2, 5, so just see from here arc 2, 5 is being dropped, then you see your tree T1 remains 1, 3, 2, 4 and only 5, 6 are the this is the arc which make your T 2, I mean the, T 2 is your 5 and then arc 5, 6 and node 6, so these are the and what is your entering arc 4, 6.

(Refer Slide Time: 55:21).

So, again q belongs to T 2 and therefore, as I am saying here that incoming arc is 46 and 6 belongs to T2therefore, w 5 and w 6 will decrease by c bar 46 which is 4 so I have done that earlier value was minus 11 it has become minus 15 and this was minus 12 so this is minus 16 now.

(Refer Slide Time: 55:49)

So, I think I have shown you enough iterations, how to update your dual solution, how to update the flow and so on and so, try to demonstrate to you the shortcut in computing your dual values, then I just, I would like you to may be 1 or 2 more iterations, I think 2 more iterations from here to reach the optimal solution and I have given an optimal solution here, but of course, it need not be unique, because remember the choice of exiting and entering variables has not been unique and all the iterations, but you can try out and see.

So, anyway, this is one of the optimal solutions and if you should try to complete the, this thing; so, basically, I have try to just translate the simplex algorithm to the network flow problem, in-cost flow problem and try to show you that because of the simple structure, you can take advantage of the calculations just as we exploited the structure of the transportation problem, because there the under laying graph or the network goes simply bipartite here, of course, it is not bipartite, but still we could explode the structure and make shortcuts in your computations.

So, I think the algorithm should be quite here, how we go about it; so, as I said that two considerations degeneracy has to be tackled and also a starting feasible solution and we will use here phase 1 just as I showed you for the transportation problem we can use phase 1 and that is not difficult I, but later on, I will give you as I said for the bounded

variable transportation problem also. I will give you this max flow method of computing the starting feasible solution, which will hold for this one also.

(Refer Slide Time: 57:26).

(Refer Slide Time: 57:38).

Because the only difference between a bounded variable transportation problem and mincost problem, means, that for the transportation problem, it is bipartite graph just the computations become little different, otherwise this almost the something. So, that the idea of including this, in the prose was I could have simple said that, you just apply the algorithm as a quite a bounded, as for the transportation problem to this one also, but I wanted to show you how you can work on networks directly and see the implementation of the algorithm.