

Matrix Computation and its applications
Dr. Vivek Aggarwal
Prof. Mani Mehra
Department of Mathematics
Indian Institute of Technology, Delhi

Lecture - 33
Rank-nullity theorem

Hello viewers. So, welcome back to the course on Matrix Computation and its application. So, in the previous lecture, we have discussed a few examples about how we can find the rank and the nullity of a linear transformation. So, today we are continuing with that one.

(Refer Slide Time: 00:37)

Lecture - 33

$T: U \rightarrow V$ be a L.T then $\begin{cases} \dim(R(T)) = \text{rank } T = r(T) \\ \dim(N(T)) = \text{Nullity}(T) = n(T) \end{cases}$

Ex $T: V_4 \rightarrow V_3$
 $T(x, y, z, t) = (x - y + z + t, x + z - t, x + y + z - 2t)$ find rank, nullity of T .

Sol
 $T(x, y, z, t) = (x - y + z + t, x + z - t, x + y + z - 2t) = x(1, 1, 1) + y(-1, 0, 1) + z(1, 2, 2) + t(1, -1, -2)$

$T(x, y, z, t) = \begin{bmatrix} 1 & -1 & 1 & 1 \\ 1 & 0 & 2 & -1 \\ 1 & 1 & 3 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} + t(1, -1, -2)$

$R(T) = [(1, 1, 1), (-1, 0, 1), (1, 2, 2), (1, -1, -2)]$

So, I know that if I have the linear transformation $T: U \rightarrow V$. So, suppose this is a linear transformation then, the $\dim(R(T))$ is called the rank of T . And also, sometimes we are represented by $R(T)$. And the $\dim(N(T))$ is called the nullity of T that sometimes you represent by a small $n(T)$.

So, this one we have discussed. So, let us take one example. Suppose, I take a linear transformation $T: V_4 \rightarrow V_3$. In the previous case, we have taken a transformation from V_3 to

V_4 . Now, we are taking from V_4 to V_3 by the transformation T . So, we are representing it as (x, y, z, t) .

Suppose, $T(x, y, z, t) = (x - y + z + t, x + 2z - t, x + y + 3z - 3t)$. So, this is my linear transformation. Now, we need to find the rank and nullity of T . So, this one we need to find. Now, from here, I know that the range space is made up of this type of element. So, now, I can write from here.

$$T(x, y, z, t) = (x - y + z + t, x + 2z - t, x + y + 3z - 3t) = x(1,1,1) + y(-1,0,1) + z(1,2,3) + t(1,-1,-2) \dots \dots (1)$$

$$T(x, y, z, t) = \begin{bmatrix} 1 & -1 & 1 & 1 \\ 1 & 0 & 2 & -1 \\ 1 & 1 & 3 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix}$$

So, now from here, you can say see that this T the transformation basically, we can represent this T with this matrix, and this matrix is of order $3 * 4$, and T is a linear transformation from V_4 to V_3 . So, we can represent this transformation in terms of this matrix. Now, from here, I know that. So, this is my equation number 1. Now, from here I can say that my $R(T)$ range space is spanned by these vectors

$$R(T) = [(1,1,1), (-1,0,1), (1,2,3), (1,-1,-3)]$$

But the range space I know is a subspace of V_3 . Since $R(T)$ is a subspace of V_3 . So, it has a 4 vector in its span. So, it cannot be linearly independent, and also, it belongs to V_3 .

(Refer Slide Time: 06:11)

The image shows a handwritten solution in a Notepad window. At the top, it says "Since R(T) is a Subspace of V_3 ". Below this, matrix A is given as $A = \begin{bmatrix} 1 & -1 & 1 & 1 \\ 1 & 0 & 2 & -1 \\ 1 & 1 & 3 & -3 \end{bmatrix}$. The work shows row operations: $-R_1 + R_2$ and $-R_1 + R_3$ leading to $\begin{bmatrix} 1 & -1 & 1 & 1 \\ 0 & 1 & 1 & -2 \\ 0 & 2 & 2 & -4 \end{bmatrix}$, and then $-2R_2 + R_3$ leading to $\begin{bmatrix} 1 & -1 & 1 & 1 \\ 0 & 1 & 1 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$. The first two columns are circled and labeled "basic columns". The rank is determined to be 2, and a basis for R(T) is given as $\{(1,1), (-1,0,1)\}$. The null space is found by solving $x - y + z + t = 0$, $x + 2z - t = 0$, and $x + y + 3z - 2t = 0$. The second equation is used to express $y = z - 2t$. Substituting into the first equation gives $x = -z + t$. The free variable is $z = 2$. The final basis vectors are $(1,0) = 2(1,0,0) + (-1,1,0)$ and $(1,-2,0) = -(1,0,0) - 2(-1,1,0)$.

So, from here I know that. So, now, I need to check how many vectors are linearly independent in this case. So, I will take this matrix.

$$A = \begin{bmatrix} 1 & -1 & 1 & 1 \\ 1 & 0 & 2 & -1 \\ 1 & 1 & 3 & -3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & 1 & 1 \\ 0 & 1 & 1 & -2 \\ 0 & 2 & 2 & -4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & 1 & 1 \\ 0 & 1 & 1 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

So, using these operations R_1 as $-R_1 + R_2$ and R_2 as $-R_1 + R_3, -2R_2 + R_3$ we get the above matrix. So, I can get this as my pivot element. So, I know that these two vectors (first two columns) are basic columns and this is a non-basic column.

So, from here I can see the rank of this matrix. So, let me call it A. So, the $\text{rank}(A) = 2$ that we can check from here. Also, I can write this non-basic column this and this. So, I can write this

$$(1 \ 1 \ 0) = 2(1 \ 1 \ 0) + (-1 \ 1 \ 0)$$

$$(1, -2, 0) = -(1, 0, 0) - 2(-1, 1, 0)$$

So, it is -1 and it is 2. So, it will be 1 and then it is -2. 0. So, this non-basic column can be written as a linear combination of the basic columns. So, from here, I can find that in the set $(1 \ 1 \ 1)$ the first and the next $(-1 \ 0 \ 1)$. So, the whole this one they span the whole $R(T)$ and

they are linearly independent. So, from here I can say that the rank of my linear transformation is 2.

Now, I want to find the nullity. So, for nullity, this is my image. So, I will put this image equal to 0. So, now, I need to put the image. So, that image is $x - y + z + t = 0$ and $y + z - 2t = 0$. So, these are the conditions. I am putting this element equal to 0 and this one.

Now, from here I have 4 variables and 2 equations and I know that the rank is 2. So, now, from here they no need to convert this one into the echelon form, because we can use this matrix here. So, I will use this matrix and from there, I will get that we can have $x - y + z + t = 0$ and I can have $y + z - 2t = 0$. So, with the Gauss elimination, I can convert this into this form, because the rank is 2. So, this is the way we can find out.

$$y = 2t - z,$$

$$x - 2t + z + z + t = 0 \Rightarrow x = t - 2z$$

(Refer Slide Time: 14:13)

The image shows a handwritten solution in a Windows Journal window. At the top, it says "Since $R(T)$ is a Subspace of V_3 ". Below this, a matrix A is given as $\begin{bmatrix} 1 & -1 & 1 & 1 \\ 1 & 0 & 2 & -1 \\ 1 & 1 & 3 & -2 \end{bmatrix}$. Row operations are shown: $-R_1 + R_2$ and $-R_1 + R_3$ lead to $\begin{bmatrix} 1 & -1 & 1 & 1 \\ 0 & 1 & 1 & -2 \\ 0 & 2 & 2 & -4 \end{bmatrix}$. Then $-2R_2 + R_3$ leads to $\begin{bmatrix} 1 & -1 & 1 & 1 \\ 0 & 1 & 1 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$. The first two columns are circled and labeled "basic Columns". The rank is stated as $\text{rank}(A) = 2$. The range of T is given as $\text{Range}(T) = \mathbb{R}^2$. A basis for the range is shown as $\{(1, 1), (-1, 0, 1)\} = R(T)$. Another basis is shown as $\{(1, 0) = 2(1, 0, 0) + (-1, 1, 0), (1, -2, 0) = -(1, 0, 0) - 2(-1, 1, 0)\}$. The nullity is calculated by solving the system $\begin{cases} x - y + z + t = 0 \\ x + 2z - t = 0 \\ x + y + 3z - 2t = 0 \end{cases}$. The second equation is used to solve for y : $y = x + z + t = x + z + \frac{x + 2z}{2} = \frac{2x + 3z}{2}$. The free variables are identified as x and z , with $\text{free variables} = 2$.

I can take my $y = x + z + t$. So, that is ok. So, I can write $x + z + t$ is $x + z$ by 2, and that gives me. So, $2x + x + 3z$ and $2z + z + 3z$ by 2. So, this is the way we can write our variables.

(Refer Slide Time: 14:43)

$$\Rightarrow \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = \begin{bmatrix} x \\ \frac{3x+3z}{2} \\ z \\ \frac{x+z}{2} \end{bmatrix} = x \begin{bmatrix} 1 \\ 3/2 \\ 0 \\ 1/2 \end{bmatrix} + z \begin{bmatrix} 0 \\ 3/2 \\ 1 \\ 1/2 \end{bmatrix}$$

$$\Rightarrow \text{Nullity}(T) = 2 \quad N(T) = \left[\left(1, \frac{3}{2}, 0, \frac{1}{2}\right), \left(0, \frac{3}{2}, 1, \frac{1}{2}\right) \right] \in V_4$$

$$\Rightarrow \boxed{\text{rank} + \text{nullity} = 2 + 2 = \dim V_4 = 4}$$

So, now from here $x, y, z,$ and t . So, this is my vector. It can be written

$$\begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = \begin{bmatrix} t - 2z \\ 2t - z \\ z \\ t \end{bmatrix}$$

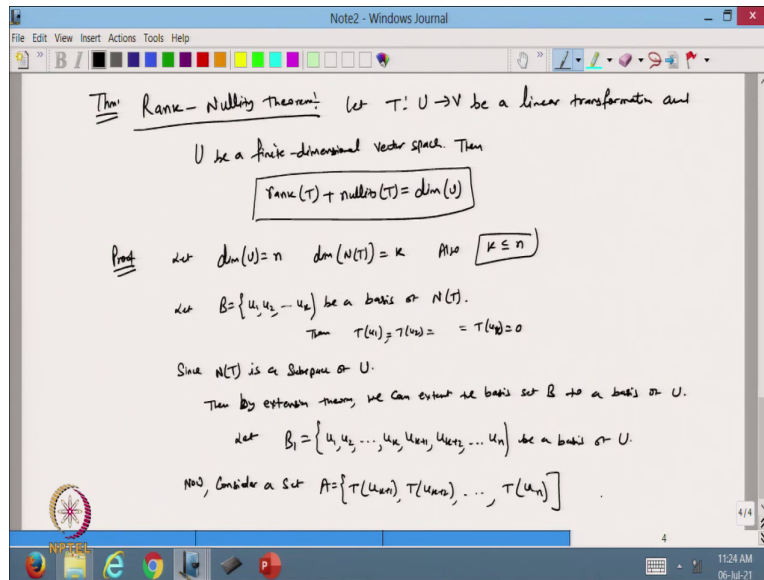
$$t \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix} + z \begin{bmatrix} -2 \\ -1 \\ 1 \\ 0 \end{bmatrix}$$

So, and also, I know that from here, these 2 vectors are linearly independent, because here, it is the 0 element, and here is the 0 limit. So, I cannot make this element 0 by a scalar multiple.

So, from here, I can write that the null space is spanned by. So, from here just I can write that the nullity of T is 2 and the null space is spanned by this vector. So, I can write that $N(T) = [(1, 2, 0, 1), (-2, -1, 1, 0)]$. And this belongs to definitely, we know that this is a subspace of V_3 . So, it belongs to V_4 sorry, because we have a linear transformation from V_4 to V_3 . So, from here also we can check that the rank plus nullity that is $2 + 2$ is equal to the dimension of V_4 that is 4.

So, based on this one. Now, we are going to introduce a very important theorem and that is called the rank nullity theorem.

(Refer Slide Time: 17:23)



So, we are going to introduce a rank nullity theorem. So, what is this rank nullity theorem? Now, let I have a linear transformation from U to V be a linear transformation and U be a finite-dimensional vector space. Then, the rank(t)+nullity (T)= dimension(U). So, this is called the rank-nullity theorem. You can check whether although the range page is a subspace of v, the rank plus nullity satisfies this condition.

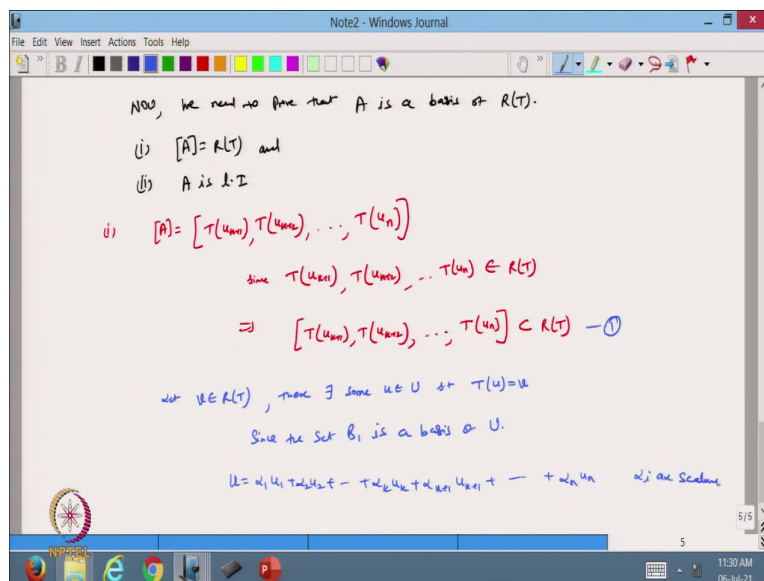
So, this is a very important theorem. We can prove this one. So, let I assume that the left dimension of U is maybe n let this one. Also, the dimension of N (T) is the nullity that it is equal to K. So, this is what we have decided. And also, we know that the K will be less than equal to n, because null space is a subspace of U. So, definitely the dimension of N T is always less than equal to the dimension of U. So, that is true. Now, it is given to me that null space is having the dimension K that is the null t is K. So, let us take a base B {u₁, u₂, ..., u_k}.

So, let be a basis of null space T. So, if it is the basis of this, then we know that T(u₁), T(u₂), ..., T(u_k) = 0, because this belongs to the null space now. Since, N(T) is a subspace of

vector space U then, by extension theorem, we can extend the basis set B . So, this is the basis of $N(T)$ to a basis of U . So, that we can do.

So, let me just take B_1 as the basis. So, that will contain $(u_1, u_2, \dots, u_{k+1}, u_{k+2}, \dots, u_n)$ because this is equal to u_n . So, let B_1 be the basis of U now. So, this we have shown. Now, consider a set. So, I consider a set A . What is this set? This set is I am taking $T(u_{k+1}), T(u_{k+2}), \dots, T(u_n)$. So, this contains $n - k$ elements ok. So, I consider set A .

(Refer Slide Time: 22:51)



Now, we need to prove that A is a basis of range space $R(T)$. So, to prove this one, what do I need to do? First, I need to show that A this A basically yeah. So, that is, I need to show that the span of A is equal to $R(T)$, and the second one I need to check that it is linearly independent.

So, if this set of A I is taken is linearly independent and it spans $R(T)$, then we can say that this is the basis of $R(T)$. So, how can we do that one? So, let us prove two things. So, the first one. So, this I need to prove now. So, what am I going to do? So, let now A span means the span of $T(u_{k+1}), T(u_{k+2}), \dots, T(u_n)$ this is. Now, since $T(u_{k+1}), T(u_{k+2}), \dots, T(u_n)$. And all these $T(u_n)$ belong to the range space T and the range space of T is a subspace of the vector space V .

Then from here, we know that the linear combination $T(u_{k+1}), T(u_{k+2}), \dots, T(u_n)$ So, if I take their linear combination that is contained in the range space of T because their linear

combination also belongs to $R(T)$. So, if I take this set of all the linear combinations that are spanned, this is contained in $R(T)$ now. So, after doing this one. So, this is the one way I have done it.

Another way I can say is that let some V belong to $R(T)$. So, this I can write as 1. So, let me take V from $R(T)$. Then, there exists some u belonging to U ; such that $T(u)$ is V . Now, V belongs to $R(T)$. Now. So, what I need to show is that. I want to show that for any V_1 have taken from $R(T)$, there is u from the U . So, that $T(u) = V$. Now, I want to show that V belongs to the span of this one. So, this one I need to show. So, if u belong to U .

Since set B_1 is a basis of U , then I can write my u as a linear combination of $u = \alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_k u_k + \alpha_{k+1} u_{k+1} + \dots + \alpha_n u_n$. So, I can write like this one. And this is linearly independent. So, all alpha I s are uniquely determined, because they are linearly independent. So, this is the unique representation of u . I can write from here, and all alpha is are scalars.

(Refer Slide Time: 28:13)

The screenshot shows a Windows Journal window with the following handwritten content:

$$T(u) = T(\alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_k u_k + \alpha_{k+1} u_{k+1} + \dots + \alpha_n u_n)$$

$$= \alpha_1 T(u_1) + \alpha_2 T(u_2) + \dots + \alpha_k T(u_k) + \alpha_{k+1} T(u_{k+1}) + \dots + \alpha_n T(u_n)$$

$$\Rightarrow T(u) \in \text{span}\{T(u_1), T(u_2), \dots, T(u_n)\}$$

$$\Rightarrow R(T) \subset [T(u_1), T(u_2), \dots, T(u_n)] \quad \text{--- (3)}$$

from (1) & (2)

$$\Rightarrow R(T) = [A]$$

(ii) A is $k \times I$

$$\alpha_{k+1} T(u_{k+1}) + \alpha_{k+2} T(u_{k+2}) + \dots + \alpha_n T(u_n) = 0$$

Now, from here, I can write my $T(u)$. So,

$$T(u) = T(\alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_k u_k + \alpha_{k+1} u_{k+1} + \dots + \alpha_n u_n)$$

$$\alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_k u_k - \alpha_{k+1} u_{k+1} - \dots - \alpha_n u_n = 0_u$$

$$B_1 = \{u_1, u_2, \dots, u_k, u_{k+1}, \dots, u_n\}$$

$$\alpha_1 = \alpha_2 = \dots = \alpha_k = \alpha_{k+1} = \dots = \alpha_n = 0$$

$$\begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = \begin{bmatrix} t - 2z \\ 2t - z \\ z \\ t \end{bmatrix}$$

$$t \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix} + z \begin{bmatrix} -2 \\ -1 \\ 1 \\ 0 \end{bmatrix}$$

$$T(u) = \alpha_1 T(u_1) + \alpha_2 T(u_2) + \dots + \alpha_k T(u_k) + \alpha_{k+1} T(u_{k+1}) + \dots + \alpha_n T(u_n)$$

So, I can write like this one. Now, from here, you see that this is equal to 0, because I know that u_1 up to u_k are the basis of $N(T)$. So, its image will be 0.

So, this will be 0. So, from here, I can write that this is $v = T(u) = \alpha_{k+1} T(u_{k+1}) + \dots + \alpha_n T(u_n)$

It means that the $T(u)$ and that is my v can be written as a linear combination of this one. So, from here, I can say that the v belongs to the span of $T(u_{k+1}), T(u_{k+2}), \dots, T(u_n)$. And from here, I can say that my $R(T)$ is a subset of this $T(u_n)$. So, from 1 and 2, we can say that the range space of T is equal to the span of A because this is A this one. So, we can show.

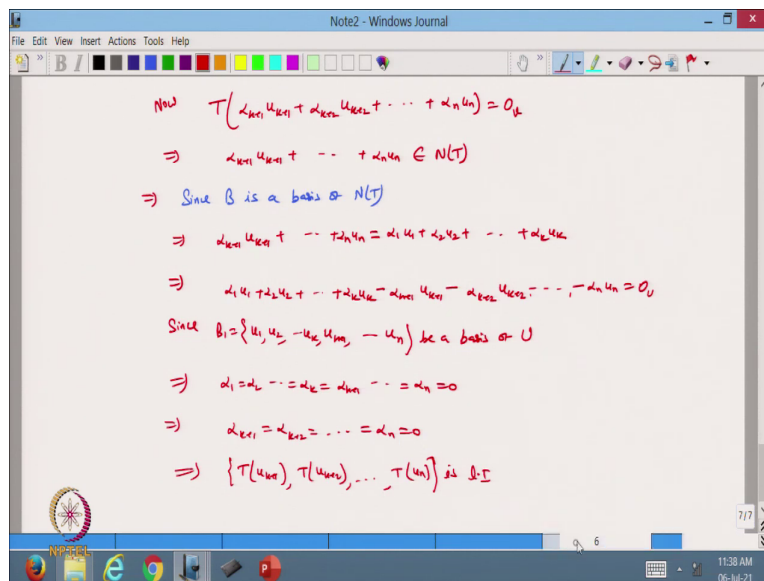
Now, we need to show the second one that A is linearly independent. So, that we need to show. So, for this one, let me take a linear combination. So, I just take linear combination as

$$\alpha_{k+1} T(u_{k+1}) + \dots + \alpha_n T(u_n) = 0$$

So, this linear combination I take and put equal to 0 now. So, I need to show that this A is

linearly independent. It means we need to show that all this $\alpha_{k+1} T(u_{k+1}) + \dots + \alpha_n T(u_n) = 0$

(Refer Slide Time: 31:39)



Now, from here I can write that $T(\alpha_{k+1}u_{k+1} + \dots + \alpha_n u_n) = 0_k$. So, if it is equal to 0, which implies that $\alpha_{k+1}u_{k+1} + \dots + \alpha_n u_n \in N(T)$, because their image is going to 0 and this 0 is a 0 of v. So, we already know that this belongs to the 0 of v.

Now, I know that if it belongs to $N(T)$ then, the null space has the basis B. So, from here that since B is a basis of $N(T)$. So, now, we can write that

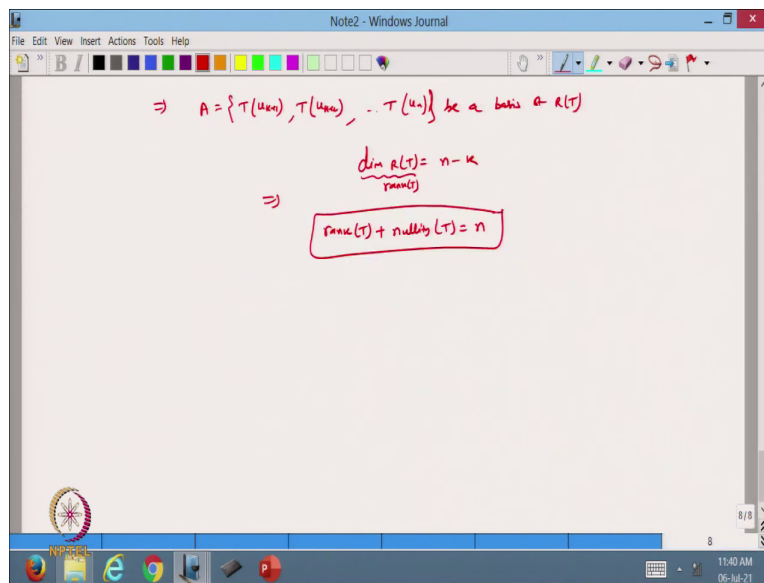
$$\alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_k u_k = \alpha_{k+1} u_{k+1} + \dots + \alpha_n u_n$$

$$\alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_k u_k - \alpha_{k+1} u_{k+1} - \dots - \alpha_n u_n = 0_u$$

So, if you check from here, then this is a basis of u. Now, since $B_1 = \{u_1, u_2, \dots, u_k, u_{k+1}, \dots, u_n\}$ be the basis of U. So, now from here, which implies that $\alpha_1 = \alpha_2 = \dots = \alpha_k = \alpha_{k+1} = \dots = \alpha_n = 0$. So, this is all 0, because these are the basic elements.

And from here, which implies that $\alpha_{k+1} = \dots = \alpha_n = 0$ and from here, I can say that the set $\{T(u_{k+1}), T(u_{k+2}), \dots, T(u_n)\}$ is linearly independent. So, now we can show that this is linearly independent and it spans $R(T)$.

(Refer Slide Time: 36:07)



So, from here, I can say that A that is $\{T(u_{k+1}), T(u_{k+2}), \dots, T(u_n)\}$ be a basis of $R(T)$, because this is what I wanted to show that this set A is the basis of $R(T)$. And now, from here, you can say that the basis of $R(T)$.

So, the dimension of $R(T)$ will be $n - K$ and from here. So, the dimension of $R(T)$ is the rank of T . So, from here, I can write that $\text{rank of } T + K$ is the nullity of T and that is equal to n , where n we have taken that n is the basis of the dimension of u . So, that is equal to this one.

So, from here we are able to show that the rank plus nullity is equal to the dimension of the space U whenever we have a linear transformation from U to V . So, this is a very important theorem in the case of rank nullity. So, we stop here now. So, in today's lecture, we have discussed a very important theorem that is the rank nullity theorem. So, that shows that if we have a linear transformation T from any vector space finite-dimensional vector space U to V .

Then, the rank of T plus the nullity of T is always equal to the dimension of the vector space U and it is a very useful theorem. We can use this theorem in the future to solve many problems. So, I hope that you have enjoyed this lecture thanks for watching.

Thanks very much.