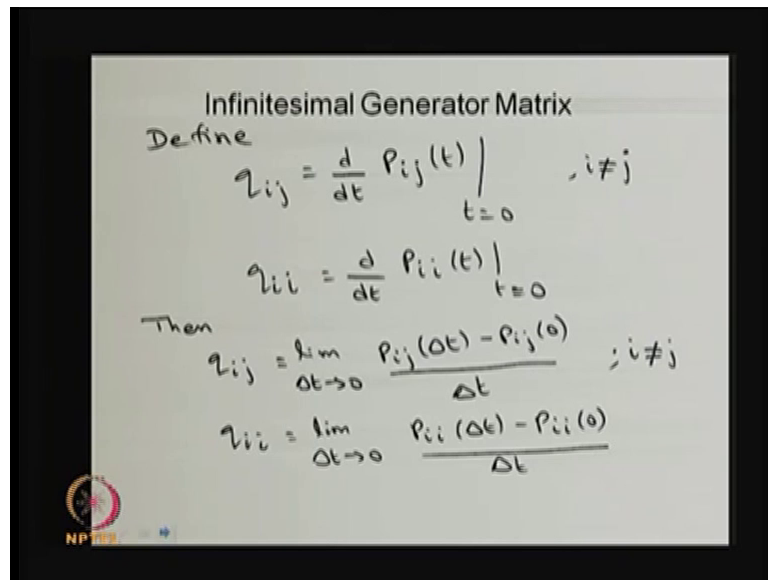


Introduction to Probability Theory and Stochastic Processes
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Lecture – 76

(Refer Slide Time: 00:01)



Infinitesimal Generator Matrix

Define

$$q_{ij} = \left. \frac{d}{dt} P_{ij}(t) \right|_{t=0}, \quad i \neq j$$
$$q_{ii} = \left. \frac{d}{dt} P_{ii}(t) \right|_{t=0}$$

Then

$$q_{ij} = \lim_{\Delta t \rightarrow 0} \frac{P_{ij}(\Delta t) - P_{ij}(0)}{\Delta t}, \quad i \neq j$$
$$q_{ii} = \lim_{\Delta t \rightarrow 0} \frac{P_{ii}(\Delta t) - P_{ii}(0)}{\Delta t}$$

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I am going to define the quantity called the q_{ij} , and later this is going to form a matrix that is going to be call it as a Infinitesimal Generator Matrix. So, let me start with the definition, q_{ij} that is nothing but take a derivative of P_{ij} of t . That is a function of t you can find out the derivative, it is a it is differentiable function only.

So, you take a derivative then substitute t equal to 0 for all i not equal to j . Then you define q_{ii} that is also in the same way separately, because the q_{ii} the diagonal element is going to be different from all other elements therefore, I am defining separately. You know how to find out the derivative, derivative of P_{ij} of t with respect to t that is, nothing but the limit Δt tends to 0 the difference divided by the Δt , since P_{ij} of t is a transition probability of system moving from i to j .

(Refer Slide Time: 01:09)

Use $P_{ij}(0) = 0, i \neq j, P_{ii}(0) = 1$
we get
 $P_{ij}(\Delta t) = q_{ij} \Delta t + o(\Delta t), i \neq j$
 $P_{ii}(\Delta t) = 1 + q_{ii} \Delta t + o(\Delta t)$
Since $\sum_j P_{ij}(\Delta t) = 1$, we get
(1) $\sum_j q_{ij} = 0$
(2) $q_{ij} \geq 0, i \neq j$
Hence, $q_{ii} = -\sum_{j \neq i} q_{ij}$

You can use P_{ij} of 0 is equal to 0 for i is not equal to j . For j is equal to i that is P_{ii} of 0 that is equal to 1; that means, the what is a transition probability of system moving from the state i to i in the interval 0 that is same as 1, that probability is 1. So, use this in the previous limit, in this P_{ij} of 0 is equal to 0 and p_i of 0 is equal to one you substitute.

Then the limit Δt tends to 0 therefore, the P_{ij} of Δt this will go to this side. So, q_{ij} times Δt therefore, this is going to be P_{ij} of Δt is nothing but the q_{ij} multiplied by Δt plus small o order of Δt ; that means, as Δt tends to 0 this whole quantity will tends to 0.

Similarly, you substitute P_{ii} a of 0 is equal to one here therefore, P_{ii} of Δt that is same as a this will come to this side so $1 + q_{ii} \Delta t + o(\Delta t)$. So, this order of Δt there is also tends to 0 as Δt tends to 0. You know that the summation of P_{ij} even at the time point Δt is small negligible time point to Δt .

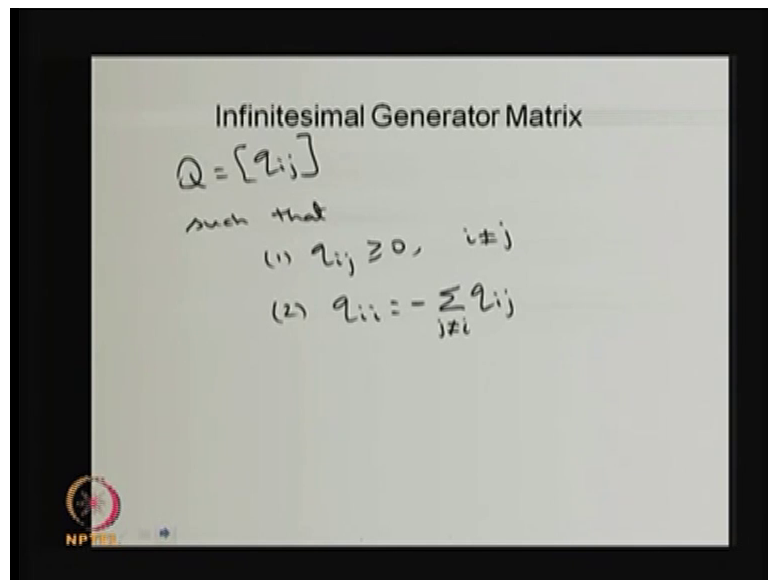
At the time also over the i that is equal to 1 therefore, if you sum it up, you can conclude the left hand side is the probability. Right hand side for i is not equal to j you have q_{ij} whereas, that second expression you have $1 + q_{ii}$ therefore, using the property of summation of P_{ij} is equal to 1, you will get the summation of q_{ij} for all i sorry, for all j that is going to be 0.

When you add both the equations say for all j you will get the summation over j q_{ij} is equal to 0, as well as all the q_{ij} quantities are going to be greater than or equal to 0 from the first one, because the left hand side is a probability and this is multiplied by the Δt or Δt is always greater than 0.

Therefore, the q_{ij} is going to be greater than 0 for all i not equal to j whereas, if I add over all the j that is going to be 0 therefore, you will get the q_{ii} , that is nothing but; you make the summation for all q_{ij} for r for all j except i , then you make a sum minus sign. So, that is going to be the q_{ii} ; that means, the diagonal element is nothing but, you make the row sum except that the diagonal term and put the minus sign that is going to be the diagonal term therefore, when you make a row sum that is going to be 0.

The details of the proof can be found in the reference books. So, the quantity q_{ij} that has the property the row sum is going to be 0. And other than the diagonal elements are greater than or equal to 0 therefore, the diagonally element is going to be summation of all the other terms with the minus sign.

(Refer Slide Time: 04:45)



So, using this we can make a matrix that is going to be Q matrix, with the entities q_{ij} such that; satisfies the property, q_{ij} is always greater than or equal to 0 for i is not equal to j whereas, the diagonal element is minus of summation therefore, it has the property the row sum is going to be 0.

So, the difference between this matrix and the one step transition probability matrix in the DTMC, that is a probability matrix ; so the entries are probability values from 0 to 1, and the summation row sum is 1 whereas, here because q_{ij} is are obtained by differentiating the P_{ij} , these are all the rates. And these rates are always great nor equal to 0, other than the diagonal elements and the diagonal elements are minus with the summation of all other row elements.

So, this matrix is called a infinitesimal generator matrix. Some books they use the word rate matrix also, and where as a here the rates are placed in the other than the diagonal elements. And the sum of the rates could be 0; that means, the probability of a system moving from that particular state to the that particular state is not possible; that probabilities 0 or there is a in a small interval of time there is the transition is not possible.

So, whenever the rates are greater than 0; that means, there is a positive probability that the system can have a transition of system moving from i to j.

(Refer Slide Time: 06:27)

Kolmogorov Differential Equations

Consider

$$P_{ij}(t+T) = \sum_{k \in S} P_{ik}(t) P_{kj}(T)$$

Differentiate w.r.t. T, $\frac{d}{dt}$

$$P'_{ij}(t+T) = \sum_{k \in S} P_{ik}(t) \frac{d}{dT} P_{kj}(T)$$

Put $T=0$,

$$P'_{ij}(t) = \sum_{k \in S} P_{ik}(t) q_{kj}$$

$$P'(t) = P(t)Q$$

So, we have defined the Q matrix, now using the Q matrix we are going to find out the P_{ij} of t. So, let me start with the Chapman Kolmogorov equation, now I am going to differentiate with respect to capital T; that means, I make the interval 0 to small t plus capital T as a 0 to t then I make a t to t plus capital T. Differentiate with respect to capital

T therefore, the left hand side is going to be I have written with a dash, so, the derivative comes inside the p_{kj} of T then I am substituting t equal to 0.

So, basically I am making a system to move from state 0 to small t, then there is a small interval of time from t to t plus capital T that is the interpretation of this. Then substituting t equal to 0, I will get the left hand side is going to be P_{ij} of dash t that is same as the summation over this whereas, this is nothing but the way we have defined the infinitesimal generator matrix entities. So, this is nothing but the q_{kj} , that is a rate in which the system is moving from the state k to j.

In a matrix form I can make it as a P_{ij} of t is going to form a matrix. So, the P dash of t that is same as a P of t times Q. So, this is a matrix and the P of t is also matrix, and this is the P dash of t means each entities are differentiated with respect to time t.

So, this is in the matrix form and this equation is called the forward Kolmogorov differential equation, because the derivation goes from 0 to t, then t to is t plus T, where considering as a very small interval of time. Therefore, this equation is called a forward Kolmogorov differential equation.

(Refer Slide Time: 08:46)

Kolmogorov Differential Equations

Similarly, $0 \xrightarrow{t} \xrightarrow{T} t+T$

$$P_{ij}'(t) = \sum_{k \in S} q_{ik} P_{kj}(t)$$

$$P'(t) = Q P(t)$$

Conclusion,

$$P'(t) = P(t)Q$$

$$P'(t) = Q P(t)$$

forward and backward kolmogorov equations

The same way if you do 0 to small t that has a small interval of time, and t to t plus capital T then you will get the P dash of t is equal to q times P of t, that is called the backward Kolmogorov differential equation. Whether you frame forward equation or a

backward Kolmogorov equation, if you solve that equation you will get the P_{ij} of t if you solve P dash of t is equal to P of t into q that is, a forward equation. P dash of t is equal to q times P of t that is a backward equation.

If you solve the equation with the initial condition because it is a differential equation. So, you need an initial condition, what is the probability, what is the transition probability of system moving from i to j a time 0 . If you know the initial condition by supplying that solving this equation you will get the P_{ij} of t . Once you know the P_{ij} of t then you can get the distribution of x of t .

(Refer Slide Time: 09:57)

Distribution of $X(t)$

$$\pi_j(t) \geq 0 ; \sum_{j \in S} \pi_j(t) = 1$$

Given $\pi_i(0)$ & $P_{ij}(t)$, we get

$$\begin{aligned} \pi_j(t) &= \text{Prob}[x(t)=j] \\ &= \sum_{i \in S} P[x(t)=j/x(0)=i] P[x(0)=i] \\ &= \sum_{i \in S} \pi_i(0) P_{ij}(t) \end{aligned}$$

So, once you know the P_{ij} of t , the given is p_i of 0 and by solving that forward or backward Kolmogorov differential equation you will get the p_i P_{ij} of t using these 2 you can get the P_{ij} of t . So, for given p_i of 0 and P_{ij} of t ; that means, the transition probability and the initial state probability vector, one can find out the distribution of x of t .

So, in this lecture I have started with the Markov process, then I have discussed the definition of a continuous time Markov chain. And also I have given what is the distribution of time spending in any state before moving into any other state, and also I explained the infinitesimal generator matrix, and using that how to find out the transition probability of P_{ij} from the Chapman Kolmogorov equation.

And we got a forward as well as the backward Kolmogorov differential equations by solving a forward or backward Kolmogorov differential equation, one can get the p_{ij} of t sorry one can get the P_{ij} of t that is a transition probability, using this equation you can get the p_{ij} of t that is nothing but the distribution of x of t . With this let me stop the this lecture and the next lecture, I will go for a simple example of a continuous time Markov chain as well as the stationary limiting distribution and the steady state distribution in the next lecture.