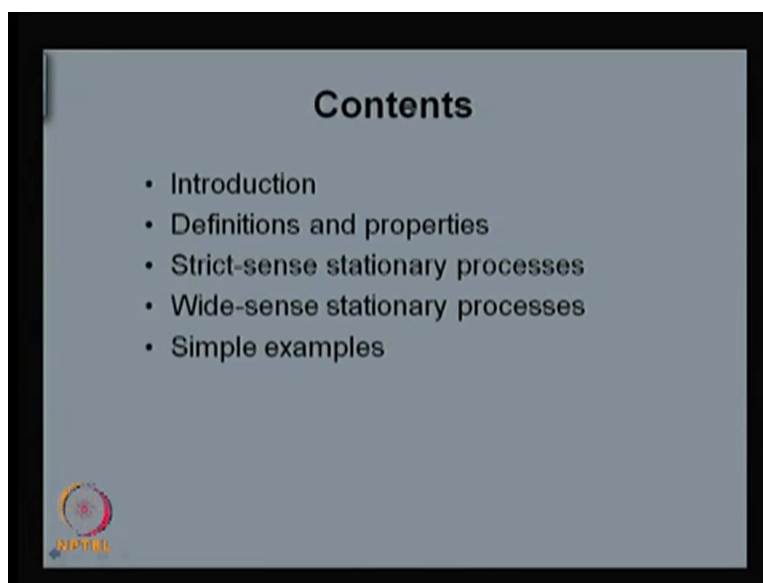


Introduction to Probability Theory and Stochastic Processes
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Lecture – 56

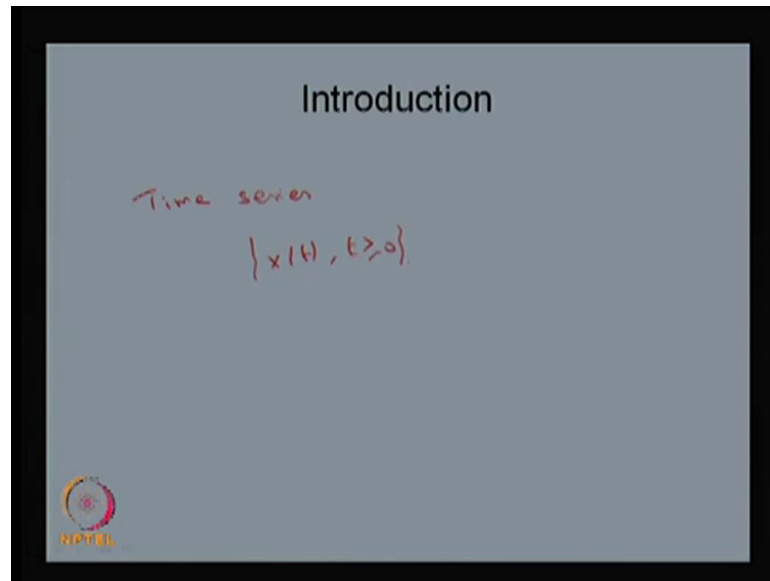
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In this talk I am going to cover the introduction of the stationary process, and the few definitions and the properties of the stationary process. Then there is a two important stationary processes; one is the strict sense stationary process, the second one is the wide sense stationary process. After this I am going to give few simple examples of stationary process. Introduction, a stationary process is a stochastic process whose probable strict or laws remain unchanged through shifting times or in space.

Stationarity is a key concept in the time series analysis as it allows powerful techniques for modelling and forecasting to be developed. What is the meaning of time series? Time series is a set of data ordered in time usually recorded at regular interval of regular in time interval. In probability theory a time series if you make out the, a time series is a collection of random variable index by time series is a special case of stochastic processes.

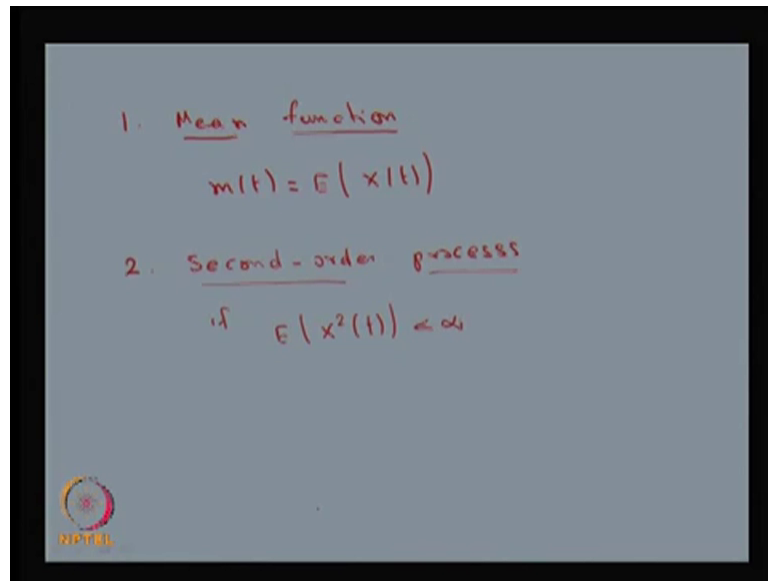
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One of the main features of time series is the inter dependency of observation over time. This interdependency needs to be countered in the time series data modelling to improve temporal behavior and forecast of future movement. So, basically the stationary is used as a tool in time series analysis. When the raw data are often transformed to become stationary; that means, if you collect the raw data and that raw data need not be satisfying the times.

It need not satisfies a stationary property, but using the stationarity property the time series of that raw data is a transformed so that you can model as well as you can forecast for the future moment by using the stationarity property. There are different forms of a stationarity depending on which of the statistical properties of the time series are restricted. The most widely used form of stationarity or strict sense stationarity and weak sense stationarity. So, basically before we go to the 2 types of two important types of stationary property that is a weak sense stationary property. And strict sense stationarity property we will just see few definitions followed by these two important stationarity property.

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The first one is the mean function. Mean function is defined as the with the notation m of t , that is nothing but expectation of the random variable X of t . So, here the stochastic process is the collection of a random variable X of t over the t belonging to capital T and you are defining the mean function as the function of t that is expectation of random variable X of t . Sometimes this is going to be a function of t , sometimes it is going to be a independent of t , according to the function of a t or independent of t we can classify the stochastic process later.

So, this definition is going to be very important, that is mean function. The second one it is a second order stochastic process. When we say a stochastic process is going to be a second order stochastic process, if it satisfies the condition the second order moment it is going to be finite for all t , if this condition is satisfied; that means, if a random variables with the finite second order moment then that corresponding stochastic process is called a second order stochastic process; that means, there is a possibility the stochastic process may not satisfy the second order moment may be infinite or it would not exist. In that case, it is not going to be call it as a second order process.

So, whenever you collect the random variables from a stochastic process and satisfying the second order moments are going to be finite for all t , then we see that stochastic process is going to be a second order process.

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3. Covariance function

$$c(s, t) = \text{cov}(X(s), X(t))$$
$$= E[X(s)X(t)] - E[X(s)]E[X(t)]$$

It satisfies

(1) $c(s, t) = c(t, s) \quad \forall t, s \in T$

(2) Using Schwarz inequality

$$c(s, t) \leq \sqrt{c(s, s)c(t, t)}$$

The third definition, is a covariance function how to define the covariance function covariance function in notation it is c of s comma t , that is nothing but covariance of 2 random variables X of s comma X of t . Since it is a collection of random variable, so, for each t you will have one random variable so; that means, you have here you have taken 2 s and t and you got the corresponding random variable, and you are finding the covariance of these 2 random variables.

That is nothing but the expectation of X of s X of t minus expectation of X of s and the expectation of X of t ; obviously, since you are finding the covariance of any 2 random variable; obviously, this stochastic process must be a second order stochastic process so that are the second order moments exist. And you are able to find out the covariance of this one; that means, the existence of the second order moment is going to be finite that is assume it to be that is assumed. And therefore, you are getting the covariance of these 2 random variables. So, using that you are defining c of s comma t , that is a covariance.

Since it is nothing it is a expectation of the product minus expectation of the individual one, it is going to satisfy it satisfies the first condition the c of s comma t is same as c of t comma s for all t comma s belonging to capital T . Where capital T is a parameter space from the parameter space if you take any 2 t and s , then if you find out the covariance function of a s comma t is same as a t comma s .

The second property using Schwarz inequality, you can now always able to say the upper bound is going to be c of s comma s and c of t comma t . This is going to be exist because the second order moments was finite therefore, c of s comma s , that is nothing but that is nothing but the variance of X of s and this is going to be the variance of X of t . And therefore, this is nothing but the product of the variance and the square root; so, this is going to be a finite quantity. Therefore, this has the upper bound of c of s comma t has the upper bound the square root of product of variance of X of s and X of t .

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(3) It is non-neg. definite
 For a_1, a_2, \dots, a_n is a set of real numbers and $t_i \in T$

$$\sum_{j=1}^n \sum_{k=1}^n a_j a_k c(t_j, t_k) = E \left[\left(\sum_{j=1}^n a_j X(t_j) \right)^2 \right] \geq 0$$

(4) Sum & product also covariance functions.

The third property it is the covariance matrix, non-negative definite also; that means, for a_1, a_2, \dots, a_n that is a set of a set of real numbers, and if you take t_i is belonging to capital T and if we find this double summation of j running from 1 to n , and k running from 1 to n a_j and a_k these are all the real numbers with covariance functions of t_j comma t_k the double summation is nothing but the expectation of summation of a_j 's X of t_j 's whole square this expectation quantity is always going to be greater or equal to 0 since it is a whole square.

So, the expectation of whole square quantity is always greater or equal to 0 for all the set of all real numbers a_1, a_2, \dots, a_n and the t s are belonging to, and this is nothing but the expectation of this quantity. And that quantity is always going to be greater or equal to 0; so, you can conclude the covariance of function is going to be a non-negative definite.

The 4th property is the sum as well as the product of any 2 covariance functions, also covariance functions. The sum and products also going to be the covariance function this property needs elaboration. However, we assume these for this course. So, this 4 property is going to be used later whenever you would like to cross check whether the covariance function is going to be satisfied or how to find out the covariance function so these properties will be used.