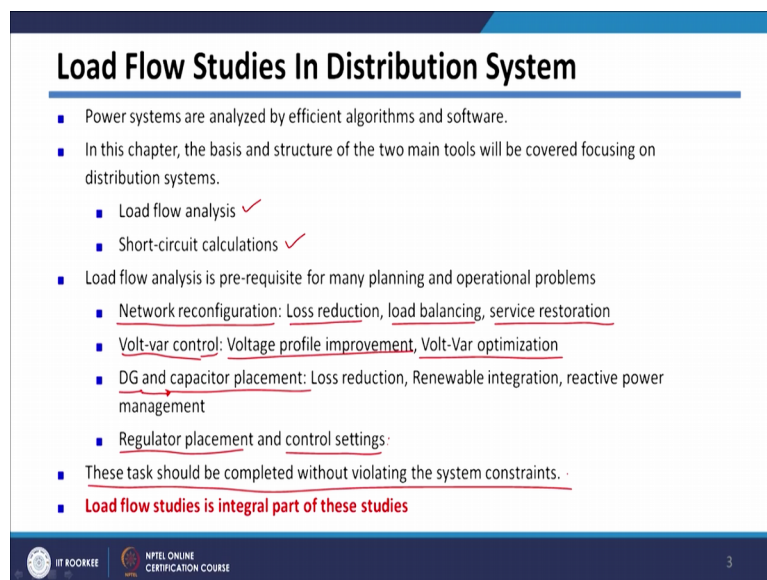


Electrical Distribution System Analysis
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Lecture – 27
Backward/Forward Sweep Load Flow Analysis Part I

In the last lecture, we have completed modeling of distribution system components. And, in this particular lecture we are going to start distribution system analysis. And, initially we will start with load flow analysis and then we will go to the short circuit analysis.

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Load Flow Studies In Distribution System

- Power systems are analyzed by efficient algorithms and software.
- In this chapter, the basis and structure of the two main tools will be covered focusing on distribution systems.
 - Load flow analysis ✓
 - Short-circuit calculations ✓
- Load flow analysis is pre-requisite for many planning and operational problems
 - Network reconfiguration: Loss reduction, load balancing, service restoration
 - Volt-var control: Voltage profile improvement, Volt-Var optimization
 - DG and capacitor placement: Loss reduction, Renewable integration, reactive power management
 - Regulator placement and control settings:
- These task should be completed without violating the system constraints.
- **Load flow studies is integral part of these studies**

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So, these tools are basically load flow analysis and short circuit calculations. So, we have seen load flow analysis and short circuit calculation in our B Tech course.

However, for distribution system the methods or algorithm used for load flow studies as well as short circuit calculation they are different. So, in this particular chapter we will see load flow analysis and short circuit analysis for basically distribution systems.

Now, if you go for load flow studies the load flow study is pre requisite for many planning as well as operational problems. So, these problems like network reconfiguration, need for loss reduction, load balancing, or service restoration. Ah. We need load flow studies before doing it, then for volt var control this is basically required for voltage profile improvement in a distribution system or volt var optimization. In this

case also you need load flow study results so, that we can arrive at proper volt var control in a distribution system.

Then, in a planning studies when you are placing DG or capacitor may be it for loss reduction or renewable integration or reactive power management or voltage profile improvement, we need load flow studies results. So, that we proper placement of DG are capacitor will be done.

Then, for placement of regulator or control setting of regulator we need load flow studies, we have seen that in case of placement of regulator or when you are setting when you are doing setting in this line drop compensator circuit, those are basically based on load flow studies. And, we have seen that all these stars should be completed without violating your system constraints.

So, while doing this load flow studies the we can also in cooperator your constraints of the system. So, that constraint's will not get violated. There for your load flow studies will always be integral part of when you your solving this kinds of issue. So, flow studies will be integral part of those studies.

Now, in your our b tech course you might have a studied methods like Newton Raphson or Gauss Seidel.

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Load Flow Studies In Distribution System

- Standard algorithms like of Newton-Raphson or Gauss-Seidel can be used for the solution of distribution systems.
- However, it is better to use programs designed for radial systems for two main reasons:
 - Programs designed for power systems normally assume a high X/R ratio.
 - A program developed specifically for distribution systems will be more efficient and simpler than those developed for high-voltage systems.
- Thus, It will lead to low memory requirement and good accuracy.
- Moreover, it is simple in implementation and has good convergence speed.
- Load flow analysis
 - Balanced and unbalanced system
 - Radial and weakly meshed system

$\begin{matrix} X & \uparrow & P & \leftarrow & \delta \\ R & \parallel & Q & \leftarrow & |V| \end{matrix}$

4

So, these methods like Newton Raphson or Gauss Seidel we can use it for distribution system also. However, the X/R ratio of distribution system is very poor, and because of this convergence of these methods is very poor means, they will converge very slow.

Because, in transmission system we know that X/R ratio is very high and because of this X/R ratio, which is very high. There will be decoupled effect means your P will be basically depend on angle of the voltage that is δ and Q will be mainly depend upon your voltage difference ΔV .

And, because of this decoupling effect your Jacobean metrics of Newton Raphson will be diagonal dominating, and because of this diagonal dominance it will converge fast.

However, in case of distribution system this X/R ratio is very poor. So, as I discussed program designed for power systems normally as in that X/R ratio is high. Therefore, program developed specifically for distribution system will be more efficient and simpler than those developed for high voltage.

So, we can develop some different algorithm for distribution system, which will be more efficient as well as they will be specifically for distribution system, thus it will lead to low memory requirement and good accuracy. So, this simple algorithm or specific algorithm for distribution system, they will lead to low memory requirement and good accuracy.

Moreover, they will be simple in implementation and has good convergence speed. So, as I told you whenever going using Newton Raphson or Gauss Seidel method for distribution system their convergences slow. So, we can develop some other methods, whose implementation will be simple and will give good convergence or it will converge fast.

So, load flow studies will be required for studying balanced as well as unbalanced system. So, generally we have seen that distribution systems are unbalanced. So, many cases we need to study unbalanced systems. Also, we need we can take the advantage of systems distribution system, which are radial mainly radial as well as weakly meshed. So, will develop the algorithm for radial system or sometimes weakly meshed systems.

Now, last let us start with one of classical algorithm used for distribution system analysis or load flow analysis of distribution system which is called as backward forward sweep load flow algorithm, which is class classical one of for distribution system analysis.

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Backward/Forward Sweep Load Flow

- Radial balanced distribution system

Backward Sweep:

$$I_2 = \frac{(P_{L2} + jQ_{L2})^*}{V_2 \angle 0^\circ}$$

$$I_3 = \frac{(P_{L3} + jQ_{L3})^*}{V_3 \angle 0^\circ}$$

$$I_{23} = I_3$$

$$I_{12} = I_{23} + I_2$$

Forward Sweep:

$$V_2 = V_1 \angle 0^\circ - Z_{12} I_{12}$$

$$V_3 = V_2 - Z_{23} I_{23}$$

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Let see how it works? So, in this case you are having say simple 2 base system; like this then there are 2 loads are connected say this load is PL 2 plus j QL 2 and this loads say PL 3 plus jQ L 3. And, this is bus number 2 bus number 3 and this is your bus number one source bus, the voltage at this bus is given and will remain constant on all iteration. So, we are keeping the bus of this voltage at this bus one will be constant at say V S angle 0 degree.

Now, this backward forward sweep algorithm will work like this initially, we assume that voltages at bus 2 as well as bus 3 which is equal to 2 voltage at source bus. So, V 2 we can say it will be V S angle 0 degree, as well as voltage V 3 will be equal to V S angle 0 degree.

So, this V 3 on putting bar on this it will be actually vector quantity, but for brevity many times I will not write this bar here. So, I will just write to V 2 V 2 will be your complex quantity or vector as well as your V 3 will be your vector.

So, in this case what we can do we can calculate the load currents at each buses. So, load current as bus number 2, which will basically I 2 current will be equal to PL 2 plus j Q L

2 divided by your V_S angle 0 degree, because we are assuming voltage at that bus is V_S angle 0 degree and we are taking complex conjugate of it. So, that will get current I_2 .

Similarly, will calculate current I_3 ; I_3 will be equal to $PL_3 + jQL_3$ divided by V_S angle 0 degree because, in this case also at bus 3 you are assuming voltage is V_S angle 0 degree so, complex conjugate of it.

So, current I_{23} will be equal to just load current at bus 3 which is I_3 , and then current I_{12} will be equal to I_{23} as it is, if you apply case will at this point. So, I_{23} plus current, which is flowing at this load current flowing at this bus number 2, which is we have calculated which is I_2 . So, I_{12} will be equal to I_{23} plus I_2 .

So, this is called as backward sweep. So, all the line currents we are calculating by going backward from your n nodes, and if you are reaching till your first node or source node.

And, then voltages will be calculated starting from source node. So, I can calculate write the equation for V_2 will be equal to V_1 , which is basically V_S angle 0 degree minus drop, which is happening across this particular line which is impedance say Z_{12} and current flowing through this is I_{12} .

Similarly, I can calculate voltage V_3 will be equal to V_2 minus Z_{23} into I_{23} . And, this is called as forward sweep forward sweep.

And, in this case we have calculating voltages in forward direction starting from your source node and we are reaching to the n node. So, that we can get the voltages at say from V_2 than from V_3 and then you can use this V_3 updated voltage V_3 into when your calculating voltage V_3 here.

Then, now and remember that here these V_3 as well as V_2 they are complex numbers as well as we can say their phrases, for brevity I am not given bar one it.

So, using this I can calculate again current I_2 . So, current I_2 will be equal to again loads I am considering constant power loads. So, if they loads are not constant power loads or if they are mixed load, this load also need to be updated in each iteration.

However, in this case since I am considering constant power load the const loads will remain constant. So, it will be $PL_2 + j QL_2$ divided by your new voltage, which you have got is V_2 and in you have to take star of it.

So, V_2 will be having some angle that I have not written it here, and then similarly I can get I_3 , which will be equal to $PL_3 + j QL_3$ divided by your V_3 star.

Now, to differentiate between these I_2 and I_3 , I can say this these are I_2 and I_3 at first iteration, this I_2 and I_3 at first iteration and these voltages, which you have got is at the end of first iteration.

Now, here we have started second iteration. So, at the second iteration this is say current has second iteration, this is current at second iteration. And, then I_2 and I_3 at second iteration will be equal to again I_3 at second iteration.

So, this first I_3 at second iteration and then I_1 and I_2 at second iteration will be equal to I_2 and I_3 at second iteration plus I_1 at second iteration, which you have got it here, and then again voltages will be updated. So, V_2 at second iteration will be equal to V_S this voltage we are keeping constant so, it will not never change.

So, V_S angle 0 degree minus Z_{12} into I_1 and I_2 at second iteration this was this first iteration. So, I just I have to write first iteration here and this V_S it we also at first iteration and then V_3 at second iteration will be equal to V_2 at second iteration minus Z_{23} and $2 I_2$ and I_3 at second iteration. And, we have to keep it repeating this pattern till we converge so, how to check the convergence.

(Refer Slide Time: 13:31)

Backward/Forward Sweep Load Flow

- Radial balanced distribution system

$$\begin{aligned}
 & V_2^k \quad V_3^k \\
 & V_2^{k-1} \quad V_3^{k-1} \\
 \checkmark e_2^k &= |V_2^k - V_2^{k-1}| \checkmark \\
 \checkmark e_3^k &= |V_3^k - V_3^{k-1}| \checkmark \\
 e_{\max}^k &= \max(e_2^k, e_3^k) \\
 e_{\max}^k &\leq \epsilon \text{ (tolerance)} \\
 &\text{print results}
 \end{aligned}$$

Let us see. So, we have got values of V_2 at say k th iteration and then we have got V_3 at k th iteration, by doing many iterations. And, we know the values of V_2 at k minus 1th iteration also and V_3 at k minus 1 iteration also.

Then, error of voltages at node 2 at k th iteration will be equal to mode of V_2 which you have got at k th iteration, minus V_2 which we have got at k minus 1 iteration. And, then error in 3 voltage at node 3 will be at k th iteration will be equal to V_3 at k th iteration minus V_3 at k minus 1th iteration and it is mode.

And, then you have seen. So, in k th iteration where getting this 2 errors here then to get maximum error. So, maximum error at k th iteration I can say a max, which will be equal to maximum of e_2^k . And, e_3^k means we have to get the maximum value of errors you have to from all the errors.

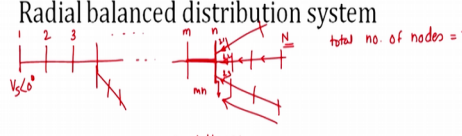
So, in this case there are 2 buses. So, you have to get the maximum value from these 2 buses which is e_{\max} . Now, then you can compare this e_{\max} with your threshold value if this e_{\max} is less than or equal to your tolerance limit which said epsilon. So, whatever tolerance limit we you said, if it is less than this then we can actually print your results.

Now, let us see the steps in this particular algorithm that is backward forward sweep load flow algorithm.

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Backward/Forward Sweep Load Flow

- Radial balanced distribution system



Step 1: Initialization of voltages
 $V_j^{(0)} = V_S \angle 0^\circ$ for $j = 2, 3, \dots, N$

Step 2: Iteration count initialization $K = 1$

Step 3: $I_j^{(K)} = \frac{(P_L + jQ_L)^*}{V_j^{(K-1)}}$ for $j = 2, 3, \dots, N$ load current computation ✓

Step 4: Backward sweep:
 $I_{mn}^{(K)} = I_n^{(K)} + \sum \text{of all the currents of branches emanated from bus } n$ ✓
 for, m branches

M

7

So, for any general type of distribution system, say your distribution system is something like this you are having some buses. And, then some are they have some branches say here also there are some branches.

Let us this is first node second node third node, and then there are many number of node say this node, node is m this node is n and say there are N number of nodes into the system. So, total number of nodes say equal to N .

Now, let us see is the steps. So, voltage at the first is I am assuming it is $V_S \angle 0^\circ$ degree as per our philosophy algorithm and which will never change in during the iteration it will remain constant. So, step one is initialization of voltages.

So, in this case will initializes voltages of all the buses. So, I can say V_j at zeroth iteration will be equal to $V_S \angle 0^\circ$ degree, and this will be defined for all j is starting from 2 3 and which will go to up to N .

So, basically we are assigning all the nodes which are j which is changing from 2 2 N , we are assuming the voltages should be $V_S \angle 0^\circ$ degree that is your step 1. So, this is your step first then step 2 initial initialize your iteration count.

So, iteration count initialization. So, here I am taking K is equal to one. So, it is first iteration then step 3, step 3 we have seen we have to calculate your load currents. So, load current equation we have seen I_j load current at any Z th bus at say K th iteration.

Now, in this case since if it is iteration number 1 it will k will be equal to 1 will be equal to P_{Lj} , which is basically real part of the load and then Q_{Lj} imaginary part sorry imaginary part of the load at k th bus, divided by V_j voltage at Z th bus, but that is calculated at k minus 1, because we do not know that voltage here. So, that is calculated at k minus 1 iteration so, earlier iteration.

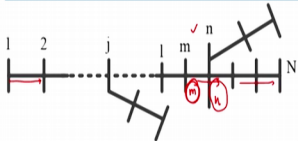
So, in this case when you are calculating for say k is equal to 1. So, this first iteration and then you have to use the voltage is which are basically at k is equal to 0 that is V_j^0 , which is we already initialized and then you have to take the complex conjugate of it. And, this we have to do it for all the j ranging from 2 3 up to N .

So, load currents at each bus will be calculated by this equation which is basically step 3. So, step 3 is basically load current calculation, and then your step 4 is basically you have seen it is backward sweep, where we are calculating the branch current.

So, when I am calculation say I_{mn} , which is basically branch current which is flowing between branch connected between bus m and n , will be equal to at k th iteration, will be equal to I_n which is basically load current at m th dash, which is calculated at k th iteration we already calculated it in step 2 plus summation of so, this summation of all the currents of branches emanated from bus N .

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Backward/Forward Sweep Load Flow



✓ Step 5: forward sweep:

$$V_n^{(k)} = V_m^{(k)} - Z_{mn} I_{mn}^{(k)} \quad \leftarrow \text{for all } n = 2, 3, \dots, N$$


✓ Step 6:


$$e_j^{(k)} = |V_j^{(k)} - V_j^{(k-1)}| \quad \text{for } j = 2, 3, \dots, N$$

✓ Step 7:

$$e_{\max}^{(k)} = \max(e_2^{(k)}, e_3^{(k)}, e_4^{(k)}, \dots, e_N^{(k)})$$

step 8, If $e_{\max}^{(k)} \leq \epsilon$ (tolerance) print results
 else update iteration count $k = k + 1$ and go to step ③



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8

Then, in step 5 we have seen it is forward sweep and in forward sweep we are calculating voltages at each bus. So, voltage at any n th bus at k th iteration will be equal to. So, when I am calculating voltage at n th bus voltage if m th bus m th bus will already be calculated. So, which will be known because we are actually starting from source node and we are going towards leaf nodes or n nodes.

So, before going to the n th node we already calculated the voltage of m th node. So, voltage then voltage of m th node which is already known minus impedance of this branch say Z_m and current flowing through this branch is I_{mn} , this you have at k th iteration which we already calculated in step 4.

So, this will be available from step 4 and this V_m if voltage of bus m , we already calculated in same step, but before calculating voltage at n th node.

So, this how we can get the voltages at each bus using your forward sweep and then in step 6 we are calculating error. So, error at any j th bus. So, this will be again repeated for all j , which is going from or all n s which are going from 2 3 up to N .

So, we basically using this we are calculating voltages of each bus and then e_j error in voltages of j th bus, in k th iteration will be equal to mode of V_j bus voltage of j th bus at k th iteration minus voltage of same bus at earlier iteration k minus one iteration, and we are taking the mode of it.

So, here also this will be repeated for your j going from 2 3 up to N . And so, after getting errors of voltages in each of the bus you can get the maximum error. So, in step 7 will get maximum error. So, e_{\max} of your k th iteration will be equal to maximum of all the errors.

So, here we are getting all the errors like we are getting error in 2 of k th iteration, error at bus 3 at k th iteration, error at bus fourth at k th iteration, we have to error at n th bus and k th iteration and when we get maximum error.

So, these are the error nothing, but the error at each bus and when we get maximum error in step 8, we compare that maximum error with respect to your tolerance value which you have selected. So, this if this e_{\max} at k th iteration will be less than or equal to

epsilon, which is basically tolerance value, which is selected if this condition we getting satisfied.

So, I can write if statement here if this condition is getting satisfied your converge with result. So, print results which are correct else if this condition is not getting satisfied update the iteration count update iteration counts. So, we can make k is equal to $k + 1$.

So, now, you have got next index iteration and then you have to go to and go to step 3. So, step 3 we have seen step 3 is here. So, again will calculate using the voltages at k minus oneth iteration earlier iteration will calculate your currents, at each bus load current at each bus. And, then we will calculate branch currents by going backward towards the source node will calculate currents in each branch by adding this one. So, this will be run for all m branches in the system.

And, then we have seen we have to use forward sweep to get the voltages. So, will go to step 5 to get the voltages and then get the error in each bus voltage maximum error from all the errors in all the buses. And, this maximum value will be become compare with tolerance value, if it is lesser than tolerance value, you have to print the result if error is more than tolerance value; you have to still keep iterating. So, you have to iterate the update your iteration count to k is equal to $k + 1$ and you have to go step 3. So, you will be in this loop till this condition get satisfied.

So, this is your backward forward sweep algorithm of load flow. In next class we will see one example of this and then we will go for 3 phase backward forward load flow algorithms.

Thank you.