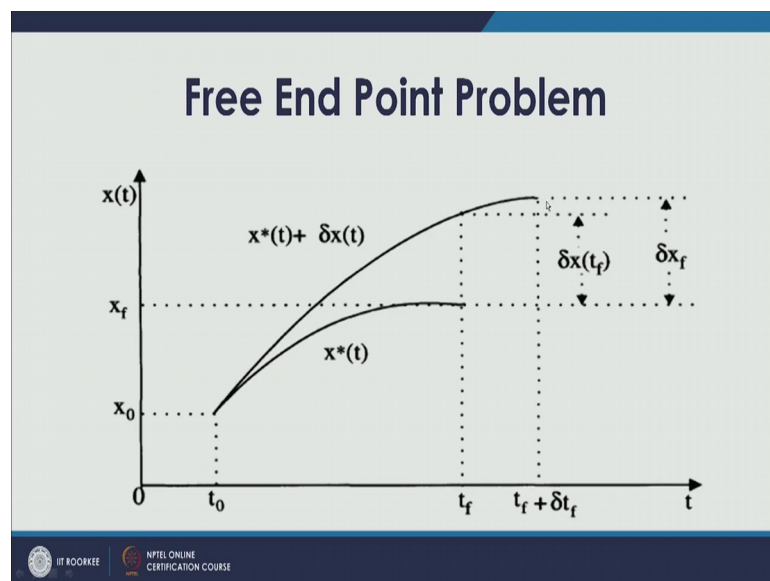


Optimal Control
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Lecture - 08
Free End Point Problem (Continued)

Welcome friends to this class which is the continuation of the previous class in which we are discussing about the free end point problem.

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In the free endpoint problem our final point can terminate to any of the point if there is a variation in the optimal value of the x .

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Free End Point Problem

$$\frac{\partial V(\cdot)}{\partial x} - \frac{d}{dt} \left(\frac{\partial V(\cdot)}{\partial \dot{x}} \right) = 0$$

$$\left[\frac{\partial V(\cdot)}{\partial \dot{x}} \Big|_{t=t_f} \right] \delta x_f + \left[V(\cdot) \Big|_{t=t_f} - \frac{\partial V(\cdot)}{\partial \dot{x}} \Big|_{t=t_f} \dot{x}(t_f) \right] \delta t_f = 0$$

where $V(\cdot) = V(x^*(t), \dot{x}^*(t), t)$

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So, our general condition appear as the first equation I can see it here which is $\frac{\partial V}{\partial x} - \frac{d}{dt} \frac{\partial V}{\partial \dot{x}} = 0$ this is nothing, but my Euler equation and the general boundary condition is given as $\left[\frac{\partial V}{\partial \dot{x}} \Big|_{t=t_f} \right] \delta x_f + \left[V(\cdot) \Big|_{t=t_f} - \frac{\partial V(\cdot)}{\partial \dot{x}} \Big|_{t=t_f} \dot{x}(t_f) \right] \delta t_f = 0$. So, this is the general condition.

For this general condition we have the different cases, like we can have the fixed endpoint problem in the fixed endpoint problem δx_f and δt_f both are 0. So, this means the second equation will not appear in that case and we have to solve the problem using the EL equation which will lead to a differential equation with given boundary conditions. So, in this case my boundary condition is the initial condition as well as my terminal condition. The second case we have considered that in which t_f was fixed. So, δt_f was 0 and the $x(t_f)$ was free. So, in that case if this, δx_f variation is arbitrary my $\frac{\partial V}{\partial \dot{x}}$ will be 0.

Third case we have taken that in which my t_f is free but $x(t_f)$ is fixed, if $x(t_f)$ is fixed this means my δx_f will be 0, if δx_f is 0 δt_f is arbitrary the coefficient of the δt_f that will also be 0. So, these three cases we already have been discussed in the previous classes. So, today we will take the case four in which my t_f and the $x(t_f)$ are free.

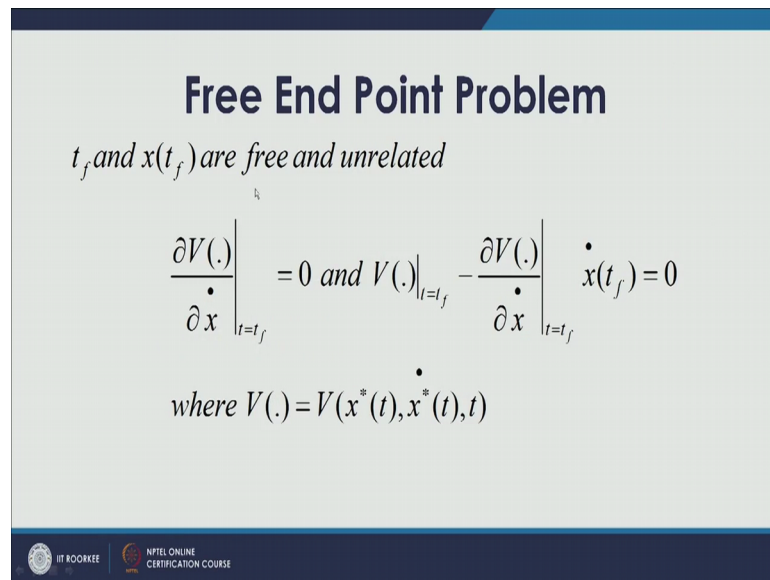
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Free End Point Problem

t_f and $x(t_f)$ are free and unrelated

$$\left. \frac{\partial V(\cdot)}{\partial \dot{x}} \right|_{t=t_f} = 0 \text{ and } V(\cdot) \Big|_{t=t_f} - \left. \frac{\partial V(\cdot)}{\partial \dot{x}} \right|_{t=t_f} \dot{x}(t_f) = 0$$

where $V(\cdot) = V(x^*(t), \dot{x}^*(t), t)$



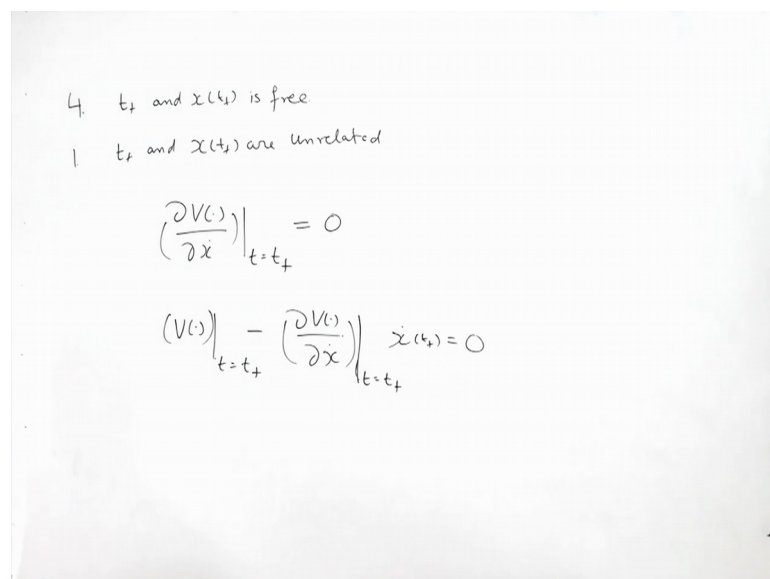
If t_f and the $x(t_f)$ are free, so we have my general condition which is given by these 2 equations. So, my first equation will appear in the similar manner which will my Euler equation and terminal condition will be given by second equation.

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4. t_f and $x(t_f)$ is free

1. t_f and $x(t_f)$ are unrelated

$$\left. \left(\frac{\partial V(\cdot)}{\partial \dot{x}} \right) \right|_{t=t_f} = 0$$

$$\left. V(\cdot) \right|_{t=t_f} - \left. \left(\frac{\partial V(\cdot)}{\partial \dot{x}} \right) \right|_{t=t_f} \dot{x}(t_f) = 0$$


So, we can say my fourth cases t_f and $x(t_f)$ is free this will further lead to the 2 sub cases the first one is if t_f and $x(t_f)$ are unrelated.

This means my t_f and the $x(t_f)$ both are the independent variable if both are independent. So, naturally in this case whatever be the coefficient of the $\delta x(t_f)$ that will be 0 and

what is the coefficient of the delta t f that will be 0 because both delta x f and the delta t f these will be arbitrary. So, in case of my first sub case in which t f and the x t f are unrelated, this means I can write delta V dot by delta x dot evaluated at t equal to t f point that will be 0 and V dot evaluated at t equal to t f point minus del V by del x dot again evaluated at t equal to t f point x dot t f that will be equal to 0. So, as we are seeing in this case my first term del V by del x dot this is nothing, but the coefficient of the delta x f and the second term is the coefficient of the delta t f, both delta x f and delta t f are arbitrary. So, their coefficient will be 0.

So, my first case in which the t f and the x t f are unrelated, my boundary condition will be governed by the del V by del x dot equal to 0 and the second equation is del V by sorry; V evaluated at equal to t f point minus del V by del x dot x dot t f that must be equal to 0. So, in this case my V dot is nothing but V evaluated at x star x star dot and t points. So, this is my first case.

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4. t_f and $x(t_f)$ is free

(ii) t_f and $x(t_f)$ are related

$$x(t_f) = \theta(t_f)$$

$$\delta x_f \approx \frac{d\theta(t_f)}{dt} \delta t_f$$

$$= \dot{\theta}(t_f) \delta t_f$$

Boundary Condition can be written as

$$\left[\left(\frac{\partial V(\cdot)}{\partial \dot{x}} \right) \Big|_{t=t_f} \dot{\theta}(t_f) + (V(\cdot)) \Big|_{t=t_f} - \left(\frac{\partial V(\cdot)}{\partial \dot{x}} \right) \Big|_{t=t_f} \dot{x}(t_f) \right] \delta t_f = 0$$

$$\left(\frac{\partial V(\cdot)}{\partial \dot{x}} \right) \Big|_{t=t_f} (\dot{\theta}(t_f) - \dot{x}(t_f)) + (V(\cdot)) \Big|_{t=t_f} = 0$$

In the second case if this 2 will be related. So, the second case we are saying if t f and the x t f are related means there may be the case that anyone of may be the dependent variable of the other. So, one if I am treating as a independent the other may be the dependent on the first variable.

Let us take an example in this case let say this is my x star, this is my general boundary condition and let say this is my another curve which is given as theta t. So, this is t 0 this

is nothing, but my \dot{x} . So, this is the same as we have discussed in the previous class \dot{x} plus Δt , this is my x star plus Δx the variation into this and this is my x of t_f . So, as we have seen \dot{x} and the x of t_f are related to each other let say my optimal trajectory terminate to a curve given by θ of t . So, in this case my \dot{x} of t_f nothing, but will be equal to $\dot{\theta}$ of t_f . So, my \dot{x} of t_f will be equal to $\dot{\theta}$ of t_f this means at the endpoint my trajectory is terminating at this given point.

So, if this is terminating then how we can relate this. So, Δx I can approximate as $\dot{\theta}$ at t_f point by dt into Δt . So, by this I can approximate or simply I can write this as $\dot{\theta}$ at t_f point Δt . So, Δx can be approximated in terms of the $\dot{\theta}$ if there is a relation between x and θ at any given condition. So, here we have the condition which we have considered as my trajectory is terminating to the θ of t curve. So, \dot{x} of t_f is equal to $\dot{\theta}$ of t_f . So, again if I will consider my general condition like given in this case, so this Δx I am trying to relate with the Δt .

So, if I will place the value of the Δx calculated on the board into this expression, so I will get is simple equation in Δt which will be. So, now, boundary condition can be written as. So, I am just simply placing the value of the Δx in my last equation, if I will place this value this is my equation will become $\frac{\partial V}{\partial x}$ dot by $\frac{\partial x}{\partial t}$ dot this value evaluated at t equal to t_f point $\dot{\theta}$ of t_f plus V evaluated at t equal to t_f point minus $\frac{\partial V}{\partial x}$ dot by $\frac{\partial x}{\partial t}$ dot at t equal to t_f point \dot{x} of t_f and the whole multiplied with Δt and this must be equal to 0.

So, by substituting the value of Δx in my last equation I get this value, so $\frac{\partial V}{\partial x}$ by $\frac{\partial x}{\partial t}$. So, I can combine this term and can write my boundary condition treating Δt to be the arbitrary, so the coefficient of the Δt will be 0. So, my final boundary condition will be $\frac{\partial V}{\partial x}$ dot which I am taking out from this expression sorry; this is at t equal to t_f point this whole multiplied with the $\dot{\theta}$ of t_f minus \dot{x} of t_f plus V dot at t equal to t_f point equals to 0. So, this will be my final boundary condition.

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Free End Point Problem

t_f and $x(t_f)$ are free and related

$$\frac{\partial V(\cdot)}{\partial \dot{x}} \Big|_{t=t_f} \left(\dot{\theta}(t_f) - \dot{x}(t_f) \right) + V(\cdot) \Big|_{t=t_f} = 0$$

where $V(\cdot) = V(x^*(t), \dot{x}^*(t), t)$

So, this we can say that if t_f and the $x(t_f)$ are free and related to each other by the curve $\theta(t)$ and my trajectory is terminating to the curve $\theta(t)$. So, my endpoint $x(t_f)$ will be equal to $\theta(t_f)$ then my final boundary condition will be $\frac{\partial V}{\partial \dot{x}} \Big|_{t=t_f} \dot{\theta}(t_f) - \dot{x}(t_f) + V \Big|_{t=t_f} = 0$. So, this is my fourth case, let us take an example to understand this more clearly.

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Find an extremal curve for the functional

$$J(x) = \int_{t_0}^{t_f} [1 + \dot{x}^2(t)]^{1/2} dt$$

The conditions are $t_0 = 0$, $x(t_0) = 0$ and t_f and $x(t_f)$ are free but $x(t_f)$ is required to lie on the line $\theta(t) = -5t + 15$

So, for this second sub case we will taken problem the statement of the problem is find an extremal curve for the functional $J(x)$ equal to the power half dt the boundary

conditions are t_0 equal to 0 and $x(t_0)$ equal to 0 and t_f and $x(t_f)$ is $x(t_f)$ are free, but $x(t_f)$ is required to lie on the line $\theta(t)$ equal to $-5t + 15$. So, my problem is we have to find an extremal curve for the given functional with the boundary condition given as t_0 equal to 0, $x(t_0)$ equal to 0 and t_f and the $x(t_f)$ are free, but here we are putting a condition - $x(t_f)$ is required to lie on the line $\theta(t)$ equal to $-5t + 15$.

So, now, if we will see what actually my problem is say I have to start with the origin t equal to 0 $x(t_0)$ this is my $\theta(t)$ line which is $-5t + 15$. So, t equal to 0. So, this value is 15 this is if $\theta(t)$ is 0. So, this will be nothing, but 3. So, this is my $\theta(t)$ line. So, we have to find; what will be my optimal curve for? So, this distance should be the minimal distance. So, this problem we have to solve. So, as you can see what is my functional this is nothing, but if you can recall our previous problem we are trying to find out the minimal curve which is joining the 2 points.

So, from there we have taken this functional. So, this we are directly treating at this point to solve this problem we will take first solve the EL equation and then we will apply our final condition to get out the sorry, to get the value of my constants.

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Solution

$$\frac{\partial V(x)}{\partial x} - \frac{d}{dt} \left(\frac{\partial V(x)}{\partial \dot{x}} \right) = 0 \quad \left| \quad V = [1 + \dot{x}^2(t)]^{1/2} \right.$$

$$0 - \frac{d}{dt} \left[\frac{\dot{x}(t)}{[1 + \dot{x}^2(t)]^{3/2}} \right] = 0 \quad \left| \quad \begin{aligned} \theta &= -5t + 15 \\ \dot{\theta}(t_f) &= -5 \end{aligned} \right.$$

$$\delta \mathcal{L}(t) = 0 \quad \left| \quad \begin{aligned} x(t_0) &= 0 \\ 0 &= C_2 \\ \Rightarrow C_2 &= 0 \end{aligned} \right.$$

$$x^*(t) = C_1 t + C_2$$

another boundary condition

$$\left(\frac{\partial V(x)}{\partial \dot{x}} \right) \Big|_{t=t_f} (\dot{\theta}(t_f) - \dot{x}(t_f)) + (V(x)) \Big|_{t=t_f} = 0$$

$$\frac{x(t_f)}{[1 + \dot{x}^2(t_f)]^{3/2}} [-5 - \dot{x}(t_f)] + [1 + \dot{x}^2(t_f)] = 0$$

So, the solution of this problem, naturally first we have to write δV by δx minus δt by δt .

So EL equation we will write first $\frac{\partial V}{\partial \dot{x}}$ that must be equal to 0. In this case my V is $1 + \dot{x}^2 t$ to the power half. So, $\frac{\partial V}{\partial \dot{x}}$ is 0, we already have been solve this problem $\frac{d}{dt} \dot{x} t$ by $1 + \dot{x}^2 t$ the power half that is equal to 0. So, this nothing but gives us $\ddot{x} t = 0$ and the solution of this which is nothing but my optimal $x^* t$ is $C_1 t + C_2$, and using the boundary condition my objective is to find out the constant C_1 and C_2 . So, my first condition is directly is $x_0 = 0$. So, if t is 0, so C_1 will be 0 nothing but C_2 this implies my C_2 value coming out to be 0. So, C_2 is 0 that we can find out from my initial conditions which is given $x_0 = 0$ and C_1 can be determined utilizing the end point condition which we have derived just now - $\frac{\partial V}{\partial \dot{x}}$ at $t = t_f$ point $\theta \dot{t}_f$ minus $\dot{x} t_f$ plus V at the point $t = t_f$ and equating it to 0.

So, let us see what we will get in this. My another boundary condition, so I have $\frac{\partial V}{\partial \dot{x}}$ will let just write here $\frac{\partial V}{\partial \dot{x}}$ at $t = t_f$ point $\theta \dot{t}_f$ minus $\dot{x} t_f$ plus V dot $t = t_f$ point that must be equal to 0. So, this is my another boundary condition. So, with the given V I will find out $\frac{\partial V}{\partial \dot{x}}$ which is nothing, but given by this equation at t_f point. So, I can write this is as $\dot{x} t_f + \sqrt{1 + \dot{x}^2 t_f}$, a square root of this; $\theta \dot{t}_f$ what was my θ ? My θ was $-5 t + 15$. So, $\theta \dot{t}_f$ is nothing, but -5 so this is $-5 - \dot{x} t_f$ and what is V at t_f point? $1 + \dot{x}^2 t_f$ and that must be equal to 0. So, we are given with my last condition.

So, if I will solve this. So, I am getting this $-5 - \dot{x} t_f + 1$ that must be equal to 0. What was my $\dot{x} t_f$? $\dot{x} t_f$ is $C_1 t + C_2$. So, $\dot{x} t_f$ is nothing, but my C_1 .

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Solution

$$\begin{array}{l}
 -5\dot{x}(t_f) + 1 = 0 \\
 -5C_1 + 1 = 0 \\
 C_1 = 1/5
 \end{array}
 \left| \begin{array}{l}
 x(t) = C_1 t + C_2 \\
 x(t_f) = C_1
 \end{array} \right.
 \begin{array}{l}
 V = [1 + \dot{x}^2(t)]^{1/2} \\
 \theta = -5t + 15 \\
 \dot{\theta}(t_f) = -5
 \end{array}$$

$x^*(t) = \frac{1}{5}t$

Find t_f $x(t_f) = \theta(t_f)$

$$\frac{1}{5}t_f = -5t_f + 15$$

$$t_f = \frac{75}{26} = 2.88$$

So, x dot of t_f you I will find that will be nothing, but my C_1 . So, this is minus 5 C_1 plus 1 equal to 0. So, C_1 nothing but is my 1 by 5. So, this means my optimal trajectory $x^* t$ which is $C_1 t$ nothing, but 1 by 5 t , C_2 is 0 so this will be my optimal value of the x . Similarly they can extend this now find t_f , and t_f we can find because we know my terminal condition $x(t_f) = \theta(t_f)$, $x(t_f)$ is 1 by 5 t_f because $x(t)$ is $x^* t$ is this 1 by 5 t_f and θ is minus 5 t_f plus 15 and this give you t_f equal to 75 by 26 which is equal to we can write as 2.88. So, using this, this will be my final solution. So, my final solution I can find out in the following manner.

So, in a free end point problem we will try to find out the different cases this means normally we are given with the initial point and where my terminal point is will be. So, the four cases we have discussed - the first one is the fixed end point problem, second is my $x(t_f)$ is free t_f is fixed, the third $x(t_f)$ is fixed t_f is free and when both are the free.

So, these four cases along with the example we have seen here. So, this is the free endpoint problem when we are simply trying to extremize a given functional without any condition. So, in this case we have not considered the considered any condition. In our next part we will consider the variational problem with the given condition. So, this lecture I stop it here and in the next lecture we will start our discussion on the extremization of the functional with condition. We will start with the function extremization and then we will lead to the functional extremization.

Thank you very much.