

Optimal Control
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Lecture – 07
Free End Point Problem (Continued)

Welcome friends, in this class we will continue our previous class discussion which was on the free end point problem.


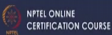
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Free End Point Problem

$$\frac{\partial V(.)}{\partial x} - \frac{d}{dt} \left(\frac{\partial V(.)}{\partial \dot{x}} \right) = 0$$

$$\left[\frac{\partial V(.)}{\partial \dot{x}} \Big|_{t=t_f} \right] \delta \dot{x}_f + \left[\frac{\partial V(.)}{\partial x} \Big|_{t=t_f} - \frac{\partial V(.)}{\partial \dot{x}} \Big|_{t=t_f} \dot{x}(t_f) \right] \delta t_f = 0$$

where $V(.) = V(x^*(t), \dot{x}^*(t), t)$

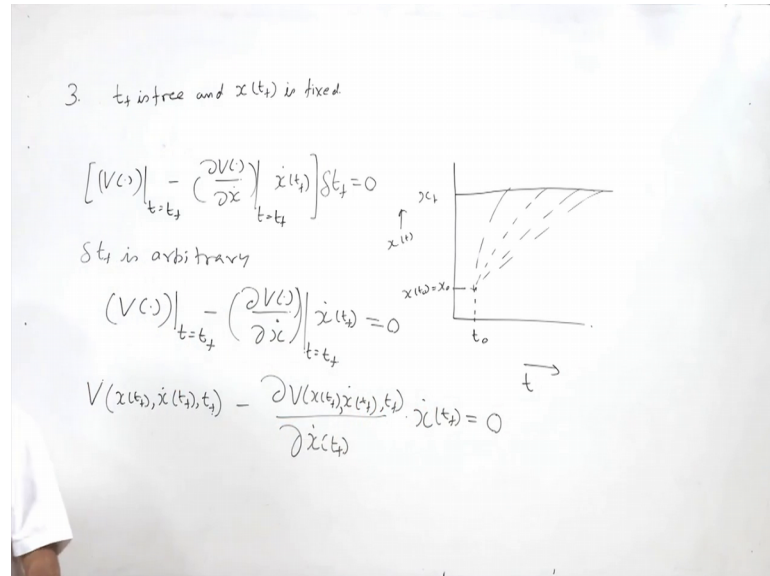



In the previous class we have derive the Euler equation plus the terminal condition, and any free end point problem is we can define as in the different cases bias for the variation of the delta x f and the delta t f the different cases can arise. The two cases we have seen in the previous classes one is the fixed end point problem in which both t f and the x of t f was fixed; initial point is also fixed terminal point is also fixed so, at terminal point delta x f and delta t f will be 0.

The second case we have seen that in which t f is fixed and the x t f is free. So, in that case my t f point 0 so this whole will become 0 and in solving a problem first we will solve the Euler equation, which will lead us to a differential equation whose solution will have the certain constants, and these constants we evaluate by using the initial point, initial condition as well as the terminal condition. In x t f free t f fixed point, my terminal condition was del V by del x dot by del x dot evaluated at t equal to t f point equal to 0.

So, in this class we will start our discussion with another case which will be our third case in which we are making t_f to be free and $x(t_f)$ is fixed.

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So, this is the case like means if this is my x_f , this is the x , this is t and let say this is my initial point t_0 , $x(t_0)$ is say x_0 . So, my final trajectory can terminate anywhere with this where $x(t_f)$ is fixed. So, this means in this case also my t_f is varying.

So, as we have discussed in the previously also once my $x(t_f)$ is fixed. So, δx_f will be 0; if δx_f is 0 so in this case my this first term will become 0, and my terminal condition will be V dot which we are evaluating at t equal to t_f point, minus $\frac{\partial V}{\partial \dot{x}}$ again evaluated at t equal to t_f point, $\dot{x}(t_f) \delta t_f = 0$. As δt_f is t_f is free. So, δt_f is arbitrary. So, we can simply write as V dot at t equal to t_f point minus $\frac{\partial V}{\partial \dot{x}}$ dot by \dot{x} again evaluated at t equal to t_f point, $\dot{x}(t_f)$ that must be equal to 0. In general if we will write $V(x(t_f), \dot{x}(t_f), t_f) - \frac{\partial V(x(t_f), \dot{x}(t_f), t_f)}{\partial \dot{x}(t_f)} \cdot \dot{x}(t_f) = 0$. So, we have the 2 conditions now one is if. So, the one is the initial point is given. So, I am given with the t_0 and $x(t_0)$ x_f is fixed is specified.

So, x_f is given t_f is free which will lead to my terminal condition V minus $\frac{\partial V}{\partial \dot{x}}$ by \dot{x} at t_f point, multiplied with the $\dot{x}(t_f)$ equal to 0. So, this we can use as my terminal condition. So, to explain it in explain it further again let us consider example for

this case which will give us the more insight how to use these conditions to solve a problem.

So, we take another example.

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Example Find an extremal for the functional

$$J(x) = \int_1^{t_f} [2x(t) + \frac{1}{2}\dot{x}^2(t)] dt$$

boundary conditions $x(1) = 4$
 $x(t_f) = 4 \quad t_f > 1$

$$V(t) = 2x(t) + \frac{1}{2}\dot{x}^2(t)$$

$$\frac{\partial V(t)}{\partial x} - \frac{d}{dt} \left(\frac{\partial V(t)}{\partial \dot{x}} \right) = 0$$

$$2 - \frac{d}{dt} (\dot{x}) = 0$$

$$\ddot{x}(t) = 2$$

This gives $x^*(t) = t^2 + C_1 t + C_2$

$x(1) = 4$
 $x(1) = 1 + C_1 + C_2 = 4$
 $C_1 + C_2 = 3$
 another boundary condition is
 $(V(t))|_{t=t_f} - \left[\left(\frac{\partial V(t)}{\partial \dot{x}} \right) |_{t=t_f} \right] \dot{x}(t_f) = 0$
 $2x(t_f) + \frac{1}{2}\dot{x}^2(t_f) - [\dot{x}(t_f)]\dot{x}(t_f) = 0$
 $2x(t_f) - \frac{1}{2}\dot{x}^2(t_f) = 0$

Find an extremal for the functional this is one to t f means the initial time is given as the 1, $2x(t) + \frac{1}{2}\dot{x}^2(t)$, d t. So, our objective is to find the extremal of the functional J x which is subjected to the boundary condition, boundary conditions are the initial point is given as $x(1) = 4$ and $x(t_f) = 4$ because t_f is unspecified this is also 4 and here $t_f > 1$; 1 is the initial point. So, t_f naturally will be greater than 1. So, this is my problem statement, we have to find out the extremal of the given functional J x with boundary condition $x(1) = 4$, $x(t_f) = 4$.

So, at the first step we have to solve the Euler equation given by the first equation here. So, in this case my V is $2x(t) + \frac{1}{2}\dot{x}^2(t)$. Euler equation is $\frac{\partial V}{\partial x} - \frac{d}{dt} \left(\frac{\partial V}{\partial \dot{x}} \right) = 0$. So, with this value of the V $\frac{\partial V}{\partial x} - \frac{d}{dt} \left(\frac{\partial V}{\partial \dot{x}} \right) = 0$ from here I can simply write that $2 - \frac{d}{dt} (\dot{x}) = 0$. So, this is nothing but giving you $\ddot{x} = 2$. So, my equation is $\ddot{x} = 2$.

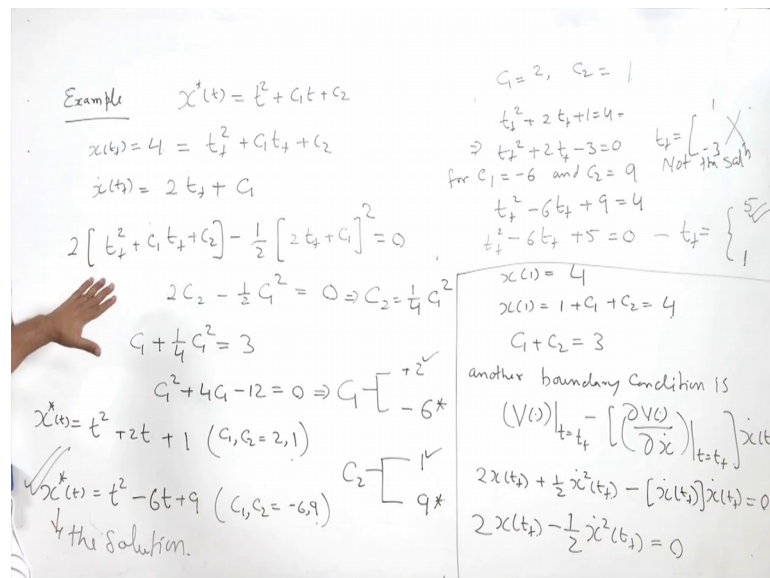
So, Euler equation give me the another differential equation which is nothing but $\ddot{x} = 2$ and the solution of this. So, this gives me x t which is $t^2 + C_1 t + C_2$

plus C_2 . So, if I will solve so, x dot is $2t$ further I will integrate this to get the x star t as t square plus $C_1 t$ plus C_2 . So, this is the solution of my x double dot t equal to 2 which am getting here. Now I can use my initial conditions I am given with the x_1 equal to 4 . So, x_1 in this case is 1 plus C_1 plus C_2 which is equal to 4 . So, my equation is C_1 plus C_2 equal to 3 . So, by the initial condition we can find out one equation in C_1 and C_2 which is giving me C_1 plus C_2 equal to 3 .

And the second condition or say the another equation to find out the C_1 C_2 variable we will get it from my terminal point, in this case t_f is free x_f is 0 . So, this term will be 0 and we are left only with this. So, what was my equation? So, my another boundary condition is V dot minus $\frac{d}{dt} V$ dot by $\frac{d}{dt} x$ dot x dot t_f equal to 0 .

So if, I will use the V as $2xt$ plus half, x dot square t I will get $2x$ of t_f plus 1 by $2x$ dot square of t_f minus. So, this is giving me the V at the t_f point, $2x$ of t_f plus half x dot square of t_f because my V is given me this value; minus if I will differentiate this with respect to x of t_f . So, that is nothing but x dot of t_f multiplied with x dot of t_f and this is equal to 0 . So, am simply getting as to x of t_f minus 1 by $2x$ dot square of t_f that is equal to 0 . So, what we can get by this.

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So, I have x t_f equal to 4 , x t_f is given to me as 4 and what was my x t and if you will see we have find the x star t as t square plus $C_1 t$ plus C_2 . So, we can write this as this is nothing but my t square plus $C_1 t$ plus C_2 . So, this is my x t f , and x dot t f if I will

write it from this; this is nothing but $2tf + C_1$. Now I have my x as this, x dot of t as this I can place this value in this equation, $2x$ of t minus 1 by $2x$ dot of t square equal to 0 . So, if I will place it. So, I have twice x of t is $t^2 + C_1$ plus C_2 minus 1 by 2 ; x dot of t is $2t + C_1$ square and that must be equal to 0 . So, if I will solve this we get $2C_2 - 1$ by $2C_1$ square equal to 0 .

So, all other factors will be cancelled out and this if we will solve we will get this value. So, either 2 equation in the C , one is $2C_2 - 1$ by $2C_1$ square equal to 0 and another this $C_1 + C_2$ equal to 3 . So, these 2 equations we have to solve to find the value of the C_1 and C_2 . As we can see my this equation is quadratic in nature, so naturally I will get the 2 values for C_1 and 2 values for C_2 . So, which value we will select that will be decided by the condition; which is given what is the t which is greater than one?

So, let us first see what the value is we are getting for C_1 and C_2 in this case. So, this gives me C_2 equal to 1 by 4 , C_1 square placing this value of C_2 in this equation $C_1 + C_2$. So, $C_1 + C_2$ in place of C_2 , I write 1 by $4C_1$ square and this is equal to 3 . So, this gives me equation C_1 square plus $4C_1 - 12$ equal to 0 , and this gives me the value of the C_1 as the 2 values of the C_1 , 1 is plus 2 and another is minus 6 . So, I get the 2 value of the C_1 by solving this equation plus 2 and minus 6 . Using the value of the C_1 I can find out what is the value of the C_2 ; so C_2 corresponding to 2 if C_1 equal to 2 . So, C_2 will be 1 with minus 6 C_2 will be nothing but 9 . So, I have I can take the value as 2 or 1 or 6 or 9 .

So, this means my optimal trajectory may be. So, has the 2 solutions, x star t as if I will take the 2 and one this is $t^2 + 2t + 1$ with C_1, C_2 as 2 and 1 . And another solution is x star t as, $t^2 - 6t + 9$ with the value of C_1, C_2 as minus 6 and 9 . So, which is my solution which solution I will select for this. So, this we can select by finding the value of the t . So, we can see from this equation if I know the C_1, C_2 for the different value of the C_1, C_2 .

This will satisfy let say C_1 equal to 2 , C_2 equal to what I am taking the C_2 ; C_2 is 1 . So, this equations give me $t^2 + 2t + 1$ equal to 4 , this implies $t^2 + 2t - 3$ equal to 0 . If I will solve this; this gives me t equal to 1 and minus 3 . For second solution for C_2 equal to sorry C_1 equal to minus 6 , and C_2 equal to 9 I have t

square plus $2t_f$ naturally this is the t_f , $2t_f$ sorry you to correct it. So, with C_1 is 6. So, this is $\text{minus } 6t_f \text{ plus } 9 \text{ equal to } 4$ or simply $t_f^2 \text{ minus } 6t_f \text{ plus } 5 \text{ equal to } 0$ and this gives me $t_f \text{ equal to } 5$ and 1. So, what was our condition my t_f should be greater than one. So, in this case my t_f is 1 and minus 3. So, this is not the solution in this case my $t_f \text{ equal to } 5$. So, I can select the second equation. So, this is the solution.

So, in such a problem we have to find out what are my constants and simultaneously we can also find out what is my t_f . So, in the solution my optimal trajectory here will be $t^2 \text{ minus } 6t \text{ plus } 9$ and the optimal time will be $t_f \text{ equal to } 5$. So, all the unknown parameter we can find out simply by solving using these 2 equations. So, in today lecture we have taken the three cases in which we have the fixed end point problem, the second case was our t_f was fixed and the $x(t_f)$ was free, and the third case was we have the $x(t_f)$ as fixed t_f as free.

So, in the next class we will discuss about when both are free then these 2 equations will exist and the different cases arises in that particular case that we will discuss in the next class. So, today we will stop here.

Thank you very much for your attention.