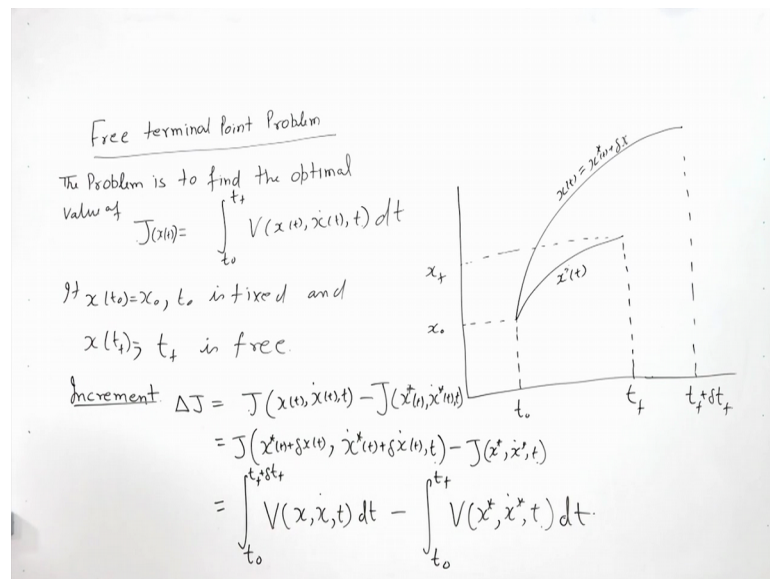


**Optimal Control**  
**Dr. Barjeev Tyagi**  
**Department of Electrical Engineering**  
**Indian Institute of Technology, Roorkee**

**Lecture – 05**  
**Free End Point Problem**

Welcome friends in this class. In the previous class we have discussed about the fixed end point problem. We are trying to find out the optimal value of a given functional subjected to the end points are fixed. Today we will see the another problem which we can say the free terminal point problem in which  $t_0$  is fixed or the initial point is fixed, but the final point is free, free with respect to the time and with respect to the  $x$ . So, both  $x$  and  $t$  we will consider to be the free then we will see the different cases which can arise in such a problem.

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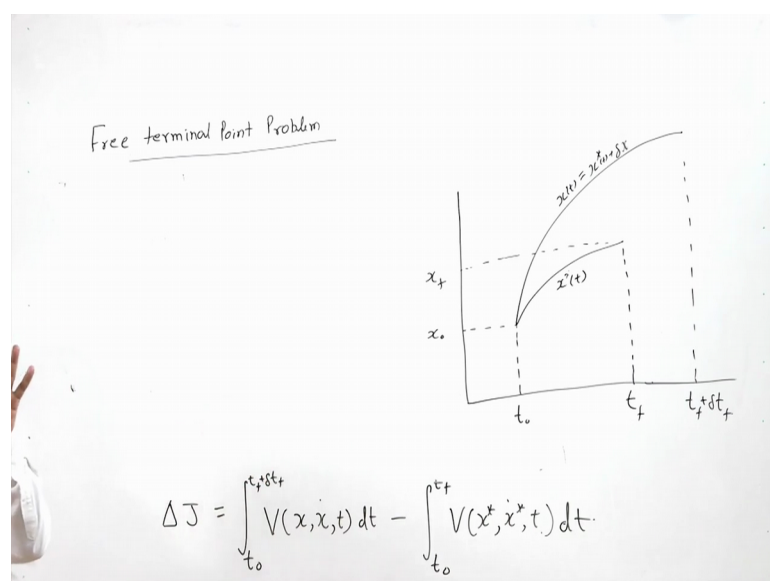
So, we will have a free terminal point problem. So, we can define  $t_0$  and  $x(t_0)$  value of  $x$  at the  $t_0$  is fixed, I define this by optimal trajectory  $x^*$  and this is the variation  $x(t)$  can be simply written as  $x^*(t) + \delta x(t)$ . My optimal trajectory is terminating it at  $t_f$  point and see the trajectory will go beyond the  $t_f$  point  $t_f + \delta t_f$  at  $t_f$  point let by optimal trajectory will have value  $x_f$ . So, the problem is to find the optimal value of  $J$  my performance index which is simply defined as  $t_0$  to  $t_f$   $V(x, \dot{x}, t) dt$  or in more general form we can write it as like  $J(x(t), V(x(t), \dot{x}(t), t) dt$ , if  $x(t_0) = x_0$  and  $t_0$  is fixed and  $x(t_f)$

$t_f$  is free. So, this is our problem, we have to find the optimal value of the  $J$  if by boundary conditions  $x(t_0) = x_0$  and  $t_0$  is fixed  $x(t_f)$  is free.

So, basic approach to solve this problem is same as we have discussed for the fixed end point problem means first of all we have to find the increment, from this increment we will write the first variation as for the fundamental theorem first variation must be equal to 0, from there we will get the conditions for this  $V$  to be optimal for the given boundary conditions.

So, our first step is to find out the increment, how we define the increment?  $\Delta J$  is nothing, but the value of the  $J$  at  $x(t), \dot{x}(t)$  minus value of the  $J$  at  $x^*(t), \dot{x}^*(t)$ . What is  $x(t)$  in this case? This is  $x^* + \delta x$  or in other way I can also write this as  $x^* + \delta x$   $\dot{x}$  is  $\dot{x}^* + \delta \dot{x}$ , at  $\delta x$  is there. So, my  $t$  is nothing but  $t$  minus  $J$  I am dropping the  $x^* \dot{x}^*$ . So, this  $J^*$  is I can directly write because in this case my  $t$  is varying from  $t_0$  to  $t_f$ , but once am writing  $J$  for  $x^* + \delta x$  my time is varying from  $t_0$  to  $t_f + \delta t_f$ . So, this can be written as  $\int_{t_0}^{t_f + \delta t_f} V(x, \dot{x}, t) dt$  here  $x$  is  $x^* + \delta x$ . So, I am simply writing the  $V$  this into  $dt$  minus for  $J^*$  this is  $\int_{t_0}^{t_f} V(x^*, \dot{x}^*, t) dt$ . So, this equation gives me the increment in  $J$  which we can find. So, my increment is  $\Delta J$  is given by this equation.

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So, now in the next what we are doing. Here we have the integral limit from  $t_0$  to  $t_f$  plus  $\Delta t_f$ ; this will break in  $t_0$  to  $t_f$  and then  $t_f$  to  $t_f$  plus  $\Delta t_f$ .

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Free terminal point Problem  $\Delta J_1$

$$\Delta J = \int_{t_0}^{t_f} (V(x, \dot{x}, t) - V(x^*, \dot{x}^*, t)) dt + \int_{t_f}^{t_f + \Delta t_f} V(x, \dot{x}, t) dt$$

$$= \Delta J_1 + \Delta J_2$$

$$\Delta J_1 = \int_{t_0}^{t_f} (V(x^* + \delta x, \dot{x}^* + \delta \dot{x}, t) - V(x^*, \dot{x}^*, t)) dt$$

Expanding using Taylor Series

$$\Delta J_1 = \int_{t_0}^{t_f} \left[ V(x^*, \dot{x}^*, t) + \left( \frac{\partial V(x, \dot{x}, t)}{\partial x} \right)_x \delta x + \left( \frac{\partial V(x, \dot{x}, t)}{\partial \dot{x}} \right) \delta \dot{x} + h.o.t - V(x^*, \dot{x}^*, t) \right] dt$$

$$= \int_{t_0}^{t_f} \left[ \left( \frac{\partial V(x, \dot{x}, t)}{\partial x} \right)_x \delta x + \left( \frac{\partial V(x, \dot{x}, t)}{\partial \dot{x}} \right) \delta \dot{x} + h.o.t \right] dt$$

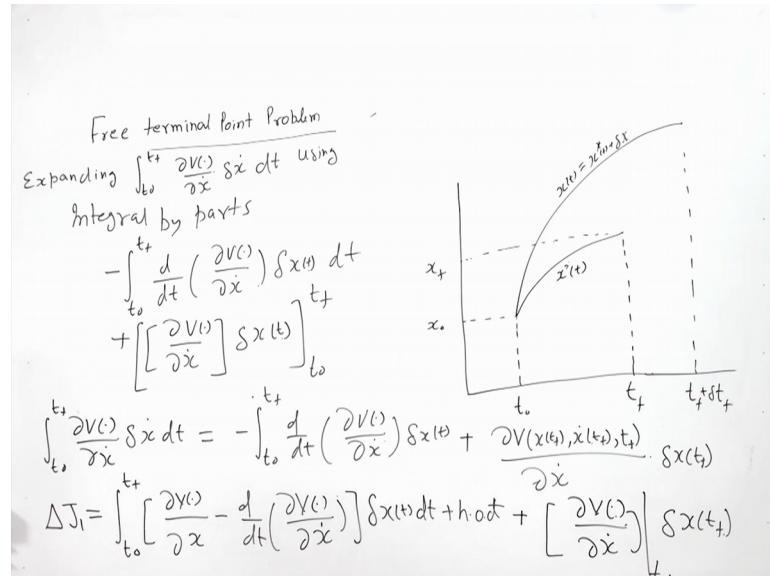
So, this integral we are breaking into the 2 integral - the first integral we can plug with the second one because both will be from  $t_0$  to  $t_f$  or I can write my  $\Delta J$  as  $t_0$  to  $t_f$ ,  $V(x, \dot{x}, t) - V(x^*, \dot{x}^*, t) dt$  plus the breakup of this from  $t_f$  to  $t_f$  plus  $\Delta t_f$   $V(x, \dot{x}, t) dt$ . Now if we will see this is the first integral is similar to what we will have in our the fixed end point problem. So, this we will say let say by first integral give me the  $\Delta J_1$  and the second integral give me the  $\Delta J_2$ .

So, first we will take. So, my  $\Delta J$  I am simply writing is  $\Delta J_1$  plus  $\Delta J_2$ . So, I will we will each term independently let us say  $\Delta J_1$  is given as my  $t_0$  to  $t_f$ . So, this  $V(x, \dot{x}, t) - V(x^*, \dot{x}^*, t) dt$  because this  $x$  is nothing, but my  $x^* + \delta x$ . So, expanding this term using Taylor Series, Taylor Series what we will get. So,  $\Delta J_1$   $t_0$  to  $t_f$  we are simply going to get  $V(x^*, \dot{x}^*, t) + V$  is the function of  $x^* + \delta x$  by  $\frac{\partial V}{\partial x}$  obtained at optimal point into  $\delta x$  plus  $\frac{\partial V}{\partial \dot{x}}$  I am writing the dot here the simply because I have the same value into  $\delta \dot{x}$  plus higher order term minus  $V(x^*, \dot{x}^*, t) dt$ .

So, these 2 term will get cancelled out and we are left with  $\frac{\partial V}{\partial x} \delta x$  plus  $\frac{\partial V}{\partial \dot{x}} \delta \dot{x}$  plus some higher order terms into  $dt$ . So, if we will see for  $\Delta J_1$  I will get the same expression as we are getting in the fixed end point problem. So,  $\Delta J$

1 I can represent it by this. So, now, in this case I will expand this term using integration by part.

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Expanding  $\int_{t_0}^{t_f} \frac{\partial V}{\partial \dot{x}} \delta \dot{x} dt$  by  $\frac{\partial V}{\partial \dot{x}} \delta \dot{x} dt$  using integral by parts. So, the second term gives us. So, we will get plus  $\frac{\partial V}{\partial \dot{x}}$  by  $\delta x$  at  $t_f$ , as my initial point  $t_0$  is fixed. So,  $\delta x(t_0)$  will be 0 and this term means I have to evaluate only at the point  $t_f$ . So, my this second term  $\int_{t_0}^{t_f} \frac{\partial V}{\partial \dot{x}} \delta \dot{x} dt$  can be written as minus  $\int_{t_0}^{t_f} \frac{d}{dt} \left( \frac{\partial V}{\partial \dot{x}} \right) \delta x dt$  plus  $\frac{\partial V}{\partial \dot{x}}$  at  $x$  of  $t_f$   $\delta x$  of  $t_f$ .

So, this will be the second term which we are expanding. So, in  $J_1$  expression if I will club this, so the total  $J_1$  expression I can write is. So,  $\Delta J_1$  can be written as  $\int_{t_0}^{t_f} \left[ \frac{\partial V}{\partial x} - \frac{d}{dt} \left( \frac{\partial V}{\partial \dot{x}} \right) \right] \delta x dt$  plus higher order terms plus  $\frac{\partial V}{\partial \dot{x}}$ . So, this, the value of the  $\frac{\partial V}{\partial \dot{x}}$  and this whole is evaluated at  $t_f$  point multiply  $\delta x$  of  $t_f$ . So, the first  $\Delta J$  we have divided into the 2 terms  $J_1$  and  $J_2$ . So,  $\Delta J_1$  can be written as given by this last expression. So, the  $J_1$  we have written by this.

Now next we will see how we can write the second integral this we will keep with us the last part.

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Free terminal point Problem

$$\Delta J_2 = \int_{t_f}^{t_f + \delta t_f} V(x, \dot{x}, t) dt$$

$$= V(x(t_f), \dot{x}(t_f), t_f) \cdot \delta t_f + h \delta t_f$$

$$= V(x^*(t_f) + \delta x(t_f), \dot{x}^*(t_f) + \delta \dot{x}(t_f), t_f) \cdot \delta t_f$$

expand this with Taylor series

$$\Delta J_2 = V(x^*(t_f), \dot{x}^*(t_f), t_f) \cdot \delta t_f$$

$$+ \left. \frac{\partial V(\cdot)}{\partial x} \right|_{t_f} \delta x(t_f) \delta t_f + \left. \frac{\partial V(\cdot)}{\partial \dot{x}} \right|_{t_f} \delta \dot{x}(t_f) \delta t_f + (h \cdot \delta t_f) \delta t_f$$

$$\Delta J_2 = V(x^*(t_f), \dot{x}^*(t_f), t_f)$$

So, what we have taken as the  $J_2$ ? So,  $\Delta J_2$  is considered as this is my integral from  $t_f$  to  $t_f + \delta t_f$  of  $V(x, \dot{x}, t) dt$ . What actual this integral represent here? Say to find this value let us see this, we are integrating from the time  $t_f$  to  $t_f + \delta t_f$  and  $V$  is  $x$  plus  $\delta x$ . So, this means  $x$  plus  $\delta x$  at  $t_f$  point is this  $t_f + \delta t_f$  point is this. So, I can say this is nothing, but area under this curve.

So, we can recall that the  $\Delta J_2$  we are representing as  $t_f$  to  $t_f + \delta t_f$  of  $V$  of  $x, \dot{x}, t dt$ . So, what this integral represent here? My limit is from  $t_f$  to  $t_f + \delta t_f$  and the  $V$  value which is dependent on the  $x$  which is  $x(t_f), \dot{x}(t_f)$  to this. So, at this point the value of the  $x$  will be the value  $x^*(t_f)$ . So, this integral is nothing but the area under this curve and area under this curve can be simply represented as  $V(x^*(t_f), \dot{x}^*(t_f), t_f) \delta t_f$  plus some higher order terms, sorry. So, this is  $x(t_f), \dot{x}(t_f), \delta x(t_f)$  at  $t_f$  point we will have the variation into this. So, this can be approximated as  $V(x^*(t_f), \dot{x}^*(t_f), t_f) \delta t_f$  plus what is my higher order terms and multiplied with  $\delta t_f$ .

Now expanding this with Taylor Series what we can write for the  $J_2$  this is  $V(x^*(t_f), \dot{x}^*(t_f), t_f) \delta t_f$  which I have missed here  $\delta t_f$ . This is the first term plus  $\frac{\partial V}{\partial x}$  evaluated at the  $t_f$  point into  $\delta x(t_f), \delta \dot{x}(t_f)$  multiplied with  $\delta t_f$  plus  $\frac{\partial V}{\partial \dot{x}}$  evaluated at the  $t_f$  point,  $\delta \dot{x}(t_f) \delta t_f$  plus what is my higher order terms and multiplied with  $\delta t_f$ .

So, if we will see in this  $\delta V$  multiplied with the  $\delta t f$  is the only first order term here, all other terms are the second order and the higher. So, this can be approximated to 0 this can be approximated 0 or we can neglect this, this can be approximated to 0. So,  $\delta J^2$  simply can be represented as  $V \times \delta t f$ ,  $\dot{x} \delta t f$  and  $t f$ . So, we are evaluated the  $\delta J^1$  and  $\delta J^2$ .

Today, in this lecture we stop here. In the next lecture we will derive the complete expression for the  $J$  and complete our free end point problem in the next class.