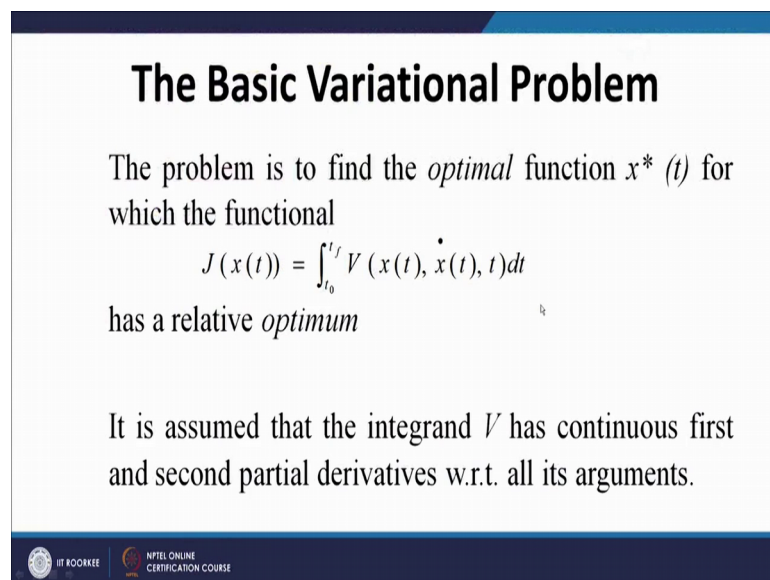


Optimal Control
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Lecture – 04
The Fixed End Point Problem

Welcome friends to this session of our discussion which we are extending to our basic variational problem, in the basic variational problem we are trying to find out the optimal value of a functional.

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The Basic Variational Problem

The problem is to find the *optimal* function $x^*(t)$ for which the functional

$$J(x(t)) = \int_{t_0}^{t_f} V(x(t), \dot{x}(t), t) dt$$

has a relative *optimum*

It is assumed that the integrand V has continuous first and second partial derivatives w.r.t. all its arguments.

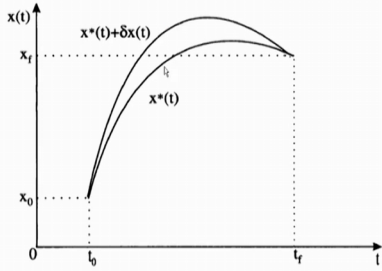
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And we have consider the functional is $J(x, t, V(x, \dot{x}, t))$.

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The Basic Variational Problem

Let us assume that $x^*(t)$ is the optimum attained for the function $x(t)$.



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We start our solution with assuming that we will have the optimal value and the variation.

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The Basic Variational Problem

The increment in J

$$\begin{aligned}\Delta J(x^*(t), \delta x(t)) &= J(x^*(t) + \delta x(t), \dot{x}^*(t) + \delta \dot{x}(t), t) - J(x^*(t), \dot{x}^*(t), t) \\ &= \int_{t_0}^{t_f} V(x^*(t) + \delta x(t), \dot{x}^*(t) + \delta \dot{x}(t), t) dt - \int_{t_0}^{t_f} V(x^*(t), \dot{x}^*(t), t) dt \\ &= \int_{t_0}^{t_f} [V(x^*(t) + \delta x(t), \dot{x}^*(t) + \delta \dot{x}(t), t) - V(x^*(t), \dot{x}^*(t), t)] dt\end{aligned}$$

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The Basic Variational Problem

The first variation

$$\delta J(x^*(t), \delta x(t)) = \int_{t_0}^{t_f} \left[\frac{\partial V(\dot{x}^*(t), x^*(t), t)}{\partial x} \delta x(t) + \frac{\partial V(x^*(t), \dot{x}^*(t), t)}{\partial \dot{x}} \delta \dot{x}(t) \right] dt$$

Considering

$$\begin{aligned} \int_{t_0}^{t_f} \left(\frac{\partial V}{\partial \dot{x}} \right)_* \delta \dot{x}(t) dt &= \int_{t_0}^{t_f} \left(\frac{\partial V}{\partial \dot{x}} \right)_* \frac{d}{dt}(\delta x(t)) dt = \int_{t_0}^{t_f} \left(\frac{\partial V}{\partial \dot{x}} \right)_* d(\delta x(t)) \\ &= \left[\left(\frac{\partial V}{\partial \dot{x}} \right)_* \delta x(t) \right]_{t_0}^{t_f} - \int_{t_0}^{t_f} \delta x(t) \frac{d}{dt} \left(\frac{\partial V}{\partial \dot{x}} \right)_* dt \end{aligned}$$



In this for this we will find out the increment J and write down the first variation as del V by del x, delta x t del V by del x dot delta x dot of t.

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The Basic Variational Problem

The first variation

$$\begin{aligned} \delta J(x^*(t), \delta x(t)) &= \int_{t_0}^{t_f} \left(\frac{\partial V}{\partial x} \right)_* \delta x(t) dt + \left[\left(\frac{\partial V}{\partial \dot{x}} \right)_* \delta x(t) \right]_{t_0}^{t_f} - \int_{t_0}^{t_f} \frac{d}{dt} \left(\frac{\partial V}{\partial \dot{x}} \right)_* \delta x(t) dt \\ &= \int_{t_0}^{t_f} \left[\left(\frac{\partial V}{\partial x} \right)_* - \frac{d}{dt} \left(\frac{\partial V}{\partial \dot{x}} \right)_* \right] \delta x(t) dt + \left[\left(\frac{\partial V}{\partial \dot{x}} \right)_* \delta x(t) \right]_{t_0}^{t_f} \end{aligned}$$

Using boundary conditions

$$\delta J(x^*(t), \delta x(t)) = \int_{t_0}^{t_f} \left[\left(\frac{\partial V}{\partial x} \right)_* - \frac{d}{dt} \left(\frac{\partial V}{\partial \dot{x}} \right)_* \right] \delta x(t) dt$$



We expand the second term using the integration by parts to get the final value as del V by del x minus d by d t del V by del x dot delta x t first integral term and the boundary value terms. In this case my boundary values are fixed, we got t 0 and x t 0 is given t f and x t f is given. So, this means delta x of t 0 is 0 delta x of t f is 0. So, this term will not appear in the first variation, and that particularly again to remind for a two point

boundary value problem, where initial and the final points are is specified and we write the first variation as δJ equal to integral of this term.

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The Basic Variational Problem

For the optimum $x^*(t)$ to exist,

$$\delta J(x^*(t), \delta x(t)) = 0$$
$$\int_{t_0}^{t_f} \left[\left(\frac{\partial V}{\partial x} \right)_* - \frac{d}{dt} \left(\frac{\partial V}{\partial \dot{x}} \right)_* \right] \delta x(t) dt = 0$$

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Then we use the fundamental theorem as δJ to be equal to 0. So, my this term will be 0 we apply the fundamental lemma.

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The Basic Variational Problem

LEMMA

If for every function $g(t)$ which is continuous,

$$\int_{t_0}^{t_f} g(t) \delta x(t) dt = 0$$

where the function $\delta x(t)$ is continuous in the interval $[t_0, t_f]$, then the function $g(t)$ must be zero everywhere throughout the interval $[t_0, t_f]$.

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The Basic Variational Problem

Using lemma to fundamental theorem, a necessary condition for $x^*(t)$ to be an optimal of the functional J

$$\left(\frac{\partial V(x^*(t), \dot{x}^*(t), t)}{\partial x} \right)_* - \frac{d}{dt} \left(\frac{\partial V(x^*(t), \dot{x}^*(t), t)}{\partial \dot{x}} \right)_* = 0$$

$$\left(\frac{\partial V}{\partial x} \right)_* - \frac{d}{dt} \left(\frac{\partial V}{\partial \dot{x}} \right)_* = 0$$

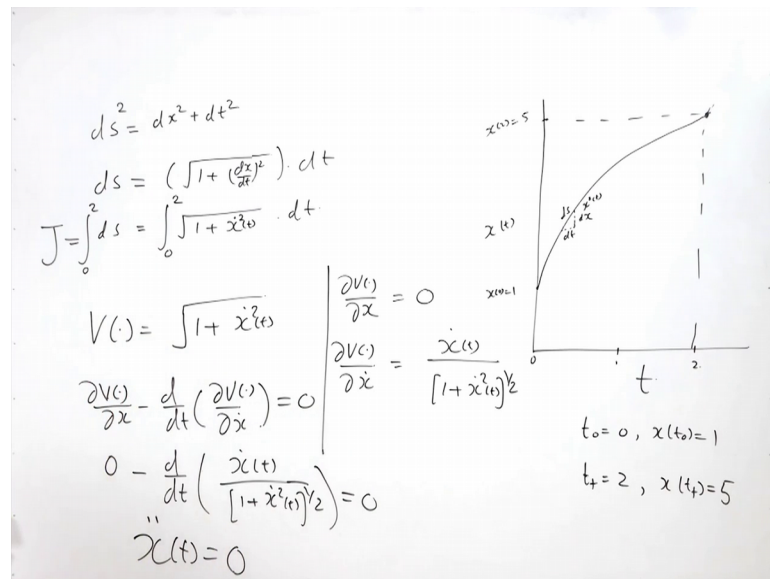
for all $t \in [t_0, t_f]$.

This equation is called the Euler equation



To get my Euler equation as $\frac{\partial V}{\partial x} - \frac{d}{dt} \frac{\partial V}{\partial \dot{x}} = 0$.
So, how to solve a problem based on this.

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Let us take us an example and see how we can solve a two point boundary value problem. Our problem is very simple my objective is to determine the is smallest distance between two points, my points are as t_0 equal to 0, and x_{t_0} equal to 1 and t_f equal to 2, and x_{t_f} equal to let say 5.

So, my first point lie at t equal to 0 is this point. So, my let say first point lie here, this is x_0 equal to 1, and my second point let us a lie here this is 0 let us a 1, this is 2 and this

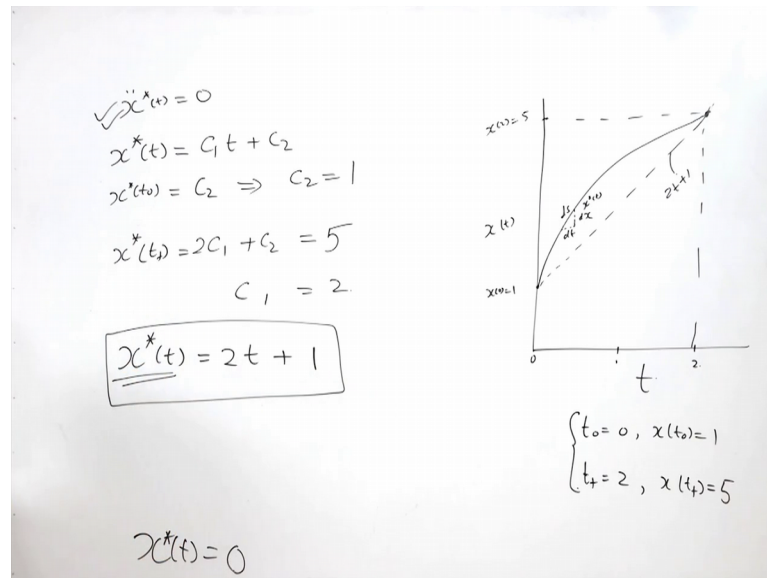
value say 5 and this is my second point which is I can say this is my x^2 which is equal to 5 So, I have to find the minimum distance between these two point, to get this distance let us consider a slope. So, what we say let this is my optimal value which I am saying this is my x^* of t . So, at this let say this is my d_s , this is d_t , this is d_x . So, this means my this d_s from 0 to 2. So, I can write d_s as d_s^2 , d_x^2 plus d_t^2 or simply d_s I can write as $1 + d_x$ by d_t is square into d_t ; for I will simply writing this $1 + x$ dot of t its square into d_t , this is my d_s . So, to find out the complete length I can integrate this from 0 to 2, 0 to 2, 0 is by $t = 0$ point and 2 is by $t = 2$ point.

So, in this way I can say this is my functional s or this is my objective function. So, my objective is to optimize the s for optimal value for a given x which will be my optimal value. So, this I can treat as, we have taken s I can take as say in place of s we can write this is my J . So, if I will equate it with my objective function. So, I can say my V is nothing but is square root of $1 + x$ dot is square t , this is my V . So, if for this functional my e_l equation must satisfy and what is my equation is this means $\frac{\partial V}{\partial x} - \frac{d}{dt} \frac{\partial V}{\partial \dot{x}}$ that must be equal to 0.

So, for this V if I will write what is my $\frac{\partial V}{\partial x}$. So, I can see this V is not a function of x . So, this will be nothing but 0 and $\frac{\partial V}{\partial \dot{x}}$ if I will find. So, I have to differentiate this with respect to \dot{x} . So, what actually we will get. So, this is \dot{x} dot of t , $1 + x$ dot of t square whole to the power half. So, these two values I will place here. So, this is $0 - \frac{d}{dt} \left(\dot{x} \cdot \frac{1}{2} (1 + \dot{x}^2)^{-1/2} \right)$ and this whole must be equal to 0. So, if I will solve this I will get nothing but due to this $\frac{d}{dt}$ this is the x double dot of t equal 0.

And naturally if I am the solving this, this x is nothing but my optimal value of the x .

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So, my differential equation is x double dot of t must be equal to 0, and to get the optimal value of the x I have to solve this differential equation subjected to the given boundary conditions. So, the solution of this is simple and I can directly write the solution as $C_1 t$ plus C_2 ; where C_1 and C_2 are my constants constant of integration, and value of the C_1 and C_2 I can simplifying by using my boundary conditions. So, if boundary conditions will change naturally my C_1 and C_2 value will change.

So, for the given problem at t_0 I have x of t_0 as nothing but C_2 . So, this implies and t_0 my x t_0 is 1. So, C_2 is nothing but 1 and at x star of t_f , t_f is 2. So, twice C_1 plus C_2 this is equal to by x t_f is 5. So, this give me C_1 equal to 2. So, what is my optimal x ? C_1 means $2t$ plus 1. So, this is my optimal trajectory, and as we can see this is nothing but the equation of a straight line as I have assume. So, nothing but I will directly get this is $2t$ plus 1line. So, in this way we can solve a 2 point boundary value problem, we are given with the boundary conditions we know this is my Euler equations I have to solve this equation.

So, first I will identify what is my I take $\frac{\partial V}{\partial x} - \frac{d}{dt} \frac{\partial V}{\partial \dot{x}}$ and the solution of this e l equation nothing but gives me a differential equation in terms of my x , and I have to solve this x subject to the boundary condition to get the optimal value of the x . So, this is the general approach to determine the optimal value of a functional, but till now we got only the optimal value, our objective was to find out the


minimum distance. So, whether this optimal value is my minimum value or not I have to check the sufficient condition.

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The Basic Variational Problem

$$\Delta J = \int_{t_0}^{t_f} \left[\frac{\partial V(x^*(t), \dot{x}^*(t), t)}{\partial x} \delta x(t) + \frac{\partial V(x^*(t), \dot{x}^*(t), t)}{\partial \dot{x}} \delta \dot{x}(t) + \frac{1}{2!} \left[\frac{\partial^2 V(\dots)}{\partial x^2} (\delta x(t))^2 + \frac{\partial^2 V(\dots)}{\partial \dot{x}^2} (\delta \dot{x}(t))^2 + 2 \frac{\partial^2 V(\dots)}{\partial x \partial \dot{x}} \delta x(t) \delta \dot{x}(t) \right] + \dots \right] dt$$

\dot{x}



As you can recall the increment we have written as the first variation and the second variation; and what is the definition of the optimal of a functional says at optimum point my first variation will be 0 and the sufficient condition says the second variation should be positive and my second variation is nothing but my this complete term is defining nothing but the second variation.


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The Basic Variational Problem

The second variation can be written as

$$\delta^2 J = \int_{t_0}^{t_f} \frac{1}{2!} \left[\left(\frac{\partial^2 V}{\partial x^2} \right) (\delta x(t))^2 + \left(\frac{\partial^2 V}{\partial \dot{x}^2} \right) (\delta \dot{x}(t))^2 + 2 \left(\frac{\partial^2 V}{\partial x \partial \dot{x}} \right) \delta x(t) \delta \dot{x}(t) \right] dt$$

Expand the last term using integration by parts

$$\delta^2 J = \frac{1}{2} \int_{t_0}^{t_f} \left[\left\{ \left(\frac{\partial^2 V}{\partial x^2} \right) - \frac{d}{dt} \left(\frac{\partial^2 V}{\partial x \partial \dot{x}} \right) \right\} (\delta x(t))^2 + \left(\frac{\partial^2 V}{\partial \dot{x}^2} \right) (\delta \dot{x}(t))^2 \right] dt$$


So, I can write this second variation as $\frac{1}{2} \delta^2 V$ by δx square δx t square $\delta^2 V$ by δx dot square, δx dot t square plus twice $\delta^2 V$ by δx δx dot δx t δx dot of t. Now in this I can write the last term which is δx δx dot in terms of the sorry, I can explain this term using the integration by parts, considering $\delta^2 V$ by δx δx dot δx t this term as my u and δx dot t as my V with as the two point boundary value condition we are problem we are taking. So, my initial and the final point will be given.

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$$\int_{t_0}^{t_f} \left[\frac{\partial^2 V(\cdot)}{\partial x \partial \dot{x}} \delta x(t) \delta \dot{x}(t) \right] dt$$

$$= \int_{t_0}^{t_f} \underbrace{\left[\frac{\partial^2 V(\cdot)}{\partial x \partial \dot{x}} \delta x(t) \right]}_u d(\underbrace{\delta x(t)}_v)$$

$$= - \int_{t_0}^{t_f} \delta x(t) \frac{d}{dt} \left(\frac{\partial^2 V(\cdot)}{\partial \dot{x}} \delta x(t) \right) dt + \left[\right] \delta x(t) \Big|_{t_0}^{t_f}$$

$\delta x(t_0) = 0$
 $\delta x(t_f) = 0$

So, if I will write this value $\delta^2 V$ by δx , δx dot, $\delta^2 V$ by δx δx dot multiplied with δx t, δx dot of t. δx t δx dot of t dt what we are saying we are and this is nothing but t_0 to t_f . So, t_0 to t_f that we can write as $\delta^2 V$ by δx δx dot δx of t and this we will write $d \delta x$ t by dt into dt .

So this dt , dt will be canceled out. So, I can simply write this as δx t and this whole I am taking as u and this a I am taking as v . So, this is $u dv$ and $u dv$ is integral t_0 to t_f minus $v du$. So, v is δx of t into $d u$ I will write $\delta^2 V$ by δx dot δx of t sorry there is no dt . So, if I will divide this by dt . So, this will be dt here this is cancelled out plus $u v$. So, u is I can directly write here, and V is δx of t t_0 to t_f . So, if I will place this value δx of t_0 will be 0, δx of t_f will be 0. So, my this term will not appear only this term will appear and this term will be nothing but my d by dt $\delta^2 V$ by δx δx dot δx t square. So, because these two δx t I can have as a square.

So, the whole term I can write as half of $\delta^2 V$ by δx square, d by dt $\delta^2 V$ by δx δx dot δx t square, $\delta^2 V$ by δx dot square δx dot t is square. So, to be this whole term to be positive because this is a square term, this is a square term this will be positive. So, to make the whole term positive this means my first term should be greater than 0.

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The Basic Variational Problem



The sufficient condition for a *minimum* is

$$\delta^2 J > 0$$

This gives

$$\left(\frac{\partial^2 V}{\partial x^2}\right)_* - \frac{d}{dt} \left(\frac{\partial^2 V}{\partial x \partial \dot{x}}\right)_* > 0$$

$$\left(\frac{\partial^2 V}{\partial \dot{x}^2}\right)_* > 0$$

Simultaneously $\delta^2 V$ by δx square must be greater than 0. So, this means if $\delta^2 J$ is greater than 0, my first term $\delta^2 V$ by δx square minus d by dt $\delta^2 V$ by δx δx dot must be greater than 0, and $\delta^2 V$ by δx dot is square this term also must be greater than 0. So, this two term must be greater than 0 then I can say this $\delta^2 J$ will be greater than 0, and the similar is applied if this is less than 0.

So, if $\delta^2 J$ is greater than 0 my condition will be for minima, if this is less than 0 my condition will be for maxima. The same as we are getting here the this particular equation I can also write in the form of δx , δx dot, $\delta^2 V$, δx square $\delta^2 V$ by δx , δx dot, $\delta^2 V$ by δx , δx dot, $\delta^2 V$ by δx dot square in terms of this say δx , δx dot, x x dot.

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The Basic Variational Problem

$$\delta^2 J = \frac{1}{2} \int_{t_0}^{t_f} [\delta x(t) \ \delta \dot{x}(t)] \begin{bmatrix} \frac{\partial^2 V}{\partial x^2} & \frac{\partial^2 V}{\partial x \partial \dot{x}} \\ \frac{\partial^2 V}{\partial x \partial \dot{x}} & \frac{\partial^2 V}{\partial \dot{x}^2} \end{bmatrix} \begin{bmatrix} \delta x(t) \\ \delta \dot{x}(t) \end{bmatrix} dt$$

$$\delta^2 J = \frac{1}{2} \int_{t_0}^{t_f} [\delta x(t) \ \delta \dot{x}(t)] \Pi \begin{bmatrix} \delta x(t) \\ \delta \dot{x}(t) \end{bmatrix} dt$$

$$\Pi = \begin{bmatrix} \frac{\partial^2 V}{\partial x^2} & \frac{\partial^2 V}{\partial x \partial \dot{x}} \\ \frac{\partial^2 V}{\partial x \partial \dot{x}} & \frac{\partial^2 V}{\partial \dot{x}^2} \end{bmatrix}$$

If the matrix Π is positive (negative) definite, we establish a minimum (maximum).

So, they always give me the square term. So, whether whatever be the variation in delta x and delta x dot, that always in del 2 J will be positive. So, the whole sign of del 2 J will depend upon what actually is the sign of my matrix given as pi. So, I can write this matrix pi. So, the definiteness of this matrix will decide whether my sufficient condition is for minima or for maxima. If this matrix is positive definite or greater than 0 then this is the condition for my minima and if this is sorry this is less than 0 or this is negative definite then this is the condition for my maxima.

So, in this way we can apply both necessary and the sufficient condition to get what actually will be my maxima or minima. So, what is the condition of my optimum point that we can decide by using the second variation. So, you can apply the second variational to the problem which we have discussed just now and you will find my second variation is nothing but positive. So, what the optimum x we have selected that is giving us the minimum value for the J or minimum so that particular length will be minimum.

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$$\int_{t_0}^{t_1} \left[\frac{\partial^2 V(\cdot)}{\partial x \partial \dot{x}} \delta x(t) \cdot \delta \dot{x}(t) \right] dt$$

$$= \int_{t_0}^{t_1} \underbrace{\left[\frac{\partial^2 V(\cdot)}{\partial x \partial \dot{x}} \delta x(t) \right]}_u d(\delta x(t))$$

$$= - \int_{t_0}^{t_1} \delta x(t) \cdot \frac{d}{dt} \left(\frac{\partial^2 V(\cdot)}{\partial x \partial \dot{x}} \right) dt + \left[\delta x(t) \right]_{t_0}^{t_1}$$

$\text{Specified} \rightarrow \delta x(t_0) = 0$
 $\text{Unknown} \rightarrow \delta x(t_1) \neq 0$

So, I stop my discussion here for this session and in the next session we will start our discussion on the free end point problem. In that problem we normally keep this is specified and delta x t f and t f are may be unknown. So, they are the different condition will appear on x of t f and t f. So, the different cases we will consider in the next class to discuss the free end point problem.

Thank you very much.