

Networks and Systems
Prof. V. G. K. Murti
Department of Electrical Engineering
Indian Institution of Technology, Madras

Lecture - 32
Network Function (3)
2-port networks: Symmetry
Equivalent networks Examples

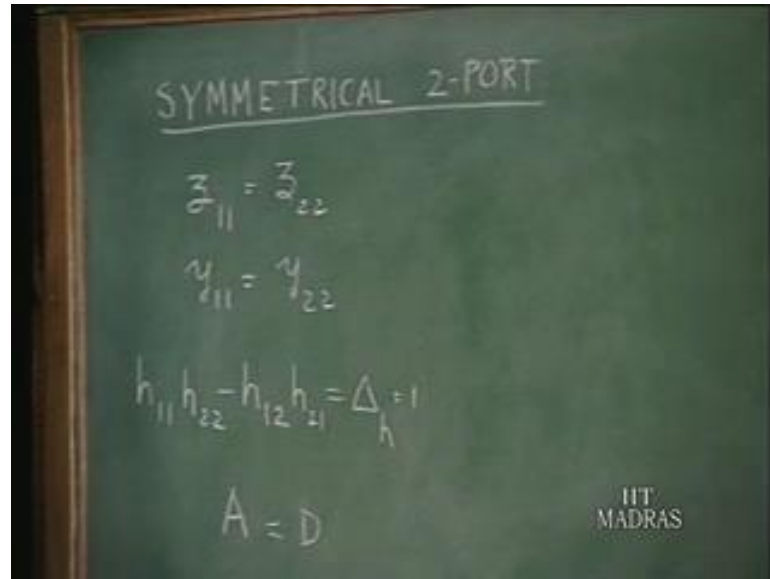
In the last lecture, we acquainted ourselves with the concept of a network function in general way and looked at the network functions pertaining to 1 port and 2 port networks. As far as 1 port network is concerned we have 2 network functions to deal with, the driving point impedance and the driving point admittance functions. These are functions of s , but I said we refer to them simply as impedances.

As far as 2 port networks are concerned there are 4 variables terminal variables V_1, V_2, I_1 and I_2 any two of them can be expressed in terms of the other two. And, we have several sets of parameters which characterize a 2 port network as far the terminal behavior is concerned. These are the z parameters, the open circuit impedance parameters. The short circuit admittance parameters or the y parameters, the h parameters, the hybrid parameters and the transmission parameters and the ABCD parameters.

We saw the definition of each one of these sets of parameters. And we also saw the consequences on the parameters, arising out the reciprocity theorem. That is if the network contains purely bilateral and reciprocal 2-terminal pair elements, what are the restrictions on this? We saw that z_{12} equals z_{21} y_{12} is equal to y_{21} h_{12} equals minus h_{21} and the determinant of the ABCD matrix equals 1. Therefore, for a reciprocal 2 port only three of these four parameters in each set are independent. So once, we know 3, the fourth one can be obtained easily.

Now on the other hand, there are some 2 port networks, which provide identical behavior whether you view it from port 1 or port 2. Then, such 2 port networks are called symmetrical 2 port networks. That means the networks have a kind of symmetry with reference to ports 1 and 2.

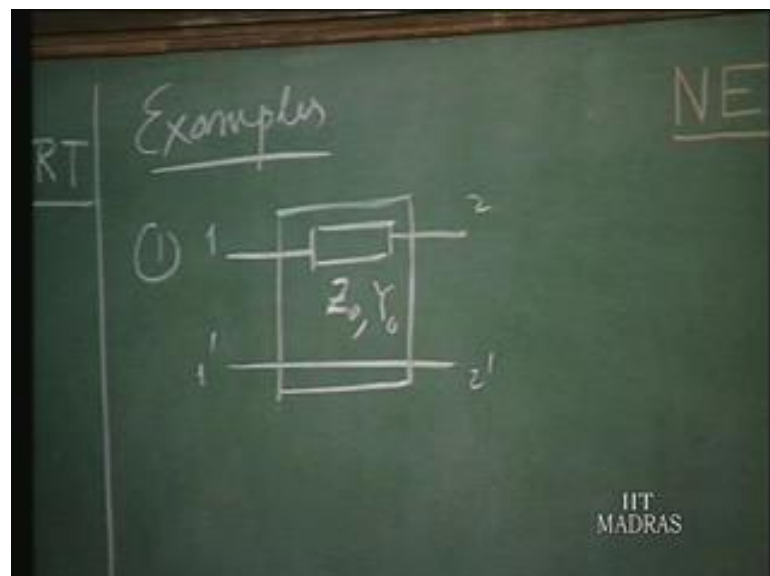
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Now if you have a symmetrical 2 port network. The consequence is that the driving point impedance, whether you look at port 1 or port 2 is the same z_{11} equals z_{22} y_{11} equals y_{22} . And likewise in terms of h parameters, the determinant of the h parameter matrix $h_{11}h_{22} - h_{12}h_{21}$ that is the determinant equals 1 and A equals D .

So, if a network is symmetrical and reciprocal then two restrictions on these parameters are valid. Therefore, for a symmetrical reciprocal network we have only two of these parameters in each set are independent the other two follow from that.

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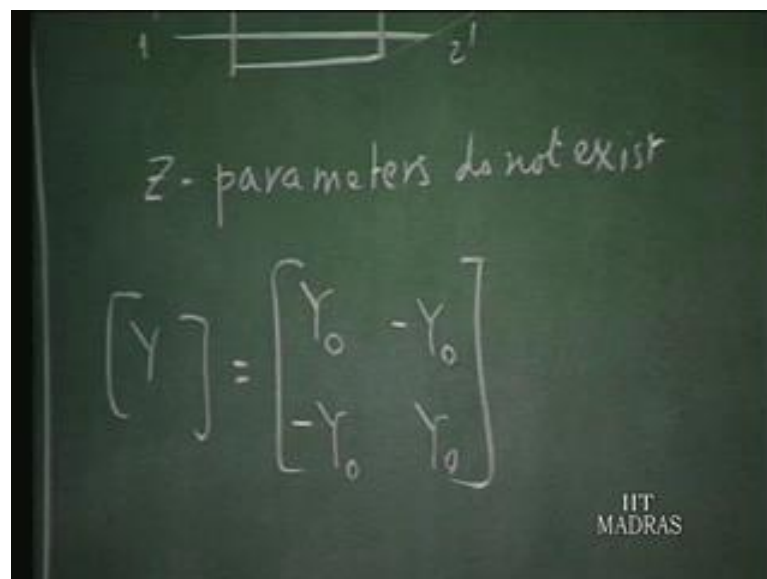


Now, based on these definitions of the various network parameters let us work out a series of examples to illustrate the meaning of these various terms. Examples, suppose I have a very simple network 2 port network which consist of just one series element. Let us, say the impedance of this is Z not or the admittance of this is Y not. So, one is the reciprocal of the other a 1 port here with a impedance function Z not of s or it is reciprocal of s the admittance function $1/Z$.

Now, if you try to find out Z_{11} for this. You keep this open circuited and try to measure the input impedance that is infinity. Because, once you keep this open circuited then input impedance is infinity. Z_{21} also turns out to be infinity, because if you want to drive a current I_1 here. That I_1 must go through infinite impedance. And therefore, consequent large infinite voltage will be developed here at a terminal across port 2.

So, Z_{11} Z_{21} will be infinite. Similarly, it can be shown that Z_{12} and Z_{22} are infinity. So, all the four parameters are infinite themselves no useful purpose for us.

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So, simply we say Z parameters do not exist, what about Y parameters, the Y matrix. (Refer Slide Time 04:01) Now, if you short circuit port 2 to port 2 and try to measure the input admittance here that is equal to Y not. Because, after all the total impedance in is that of the 1port network only. Therefore, admittance is the impedance is Z not the admittance is Y not, therefore Y_{11} is equal to Y not.

So, if you apply voltage V_1 here, the current that flows here is Y_{11} times V_1 that is the current that flows here that is I_1 . The same current flows here also; that means, you have depression I_2 is this current, this is I_1 this is I_2 . So, I_2 happens to be minus Y_{12} times V_1 . So, the depression of V_2 is I_2 divided by V_1 , when V_2 is short circuited or the port 2 is short circuited, therefore Y_{21} equals minus Y_{12} .

And since, this is a symmetrical network; you find the same type of element arrangement whether use port 1 or port 2. Y_{22} is also the same, this is also a reciprocal element, because this is a bilateral type of impedance. Therefore, this is minus Y_{12} . So, series element constituting a 2 port network we have a short circuit admittance matrix given in this fashion.

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Z-parameters do not exist

$$[Y] = \begin{bmatrix} Y_0 & -Y_0 \\ -Y_0 & Y_0 \end{bmatrix}; [H] = \begin{bmatrix} Z_0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$[T] = \begin{bmatrix} 1 & Z_0 \\ 0 & 1 \end{bmatrix}$$

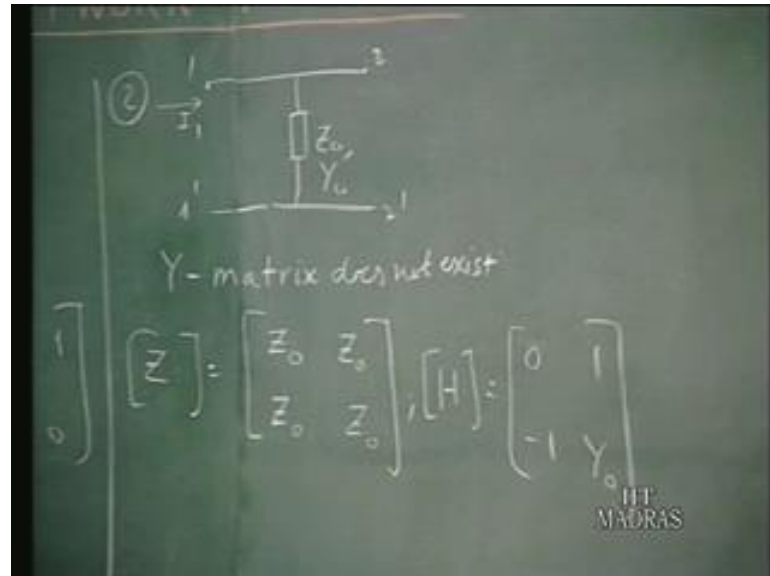
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You can calculate the by similar reasoning the hybrid parameter matrix, the H matrix for this turns out to be $1/Y_{11}$ or Z_{11} minus $1/0$. Again, this is a symmetrical network you have $1/Y_{11}$ H_{12} is equal to minus H_{21} . The determinant of this is Z_{11} times 0 minus of product of one and minus 1. The determinant of h matrix is equal to 1 and that is a consequence of symmetry as we have already explained therefore, it all adds up.

The transmission matrix the ABCD matrix for this can be computed from the definitions of the ABCD elements. This turns out to be $1 \ 0 \ Z_{11} \ 1$. All these, Y_{11} 's and Z_{11} 's are function of s of course in a general case. So in this simple example, we have Z

parameters do not exist Z matrix does not exist. But, the other type versus other parameters exist and these are the values.

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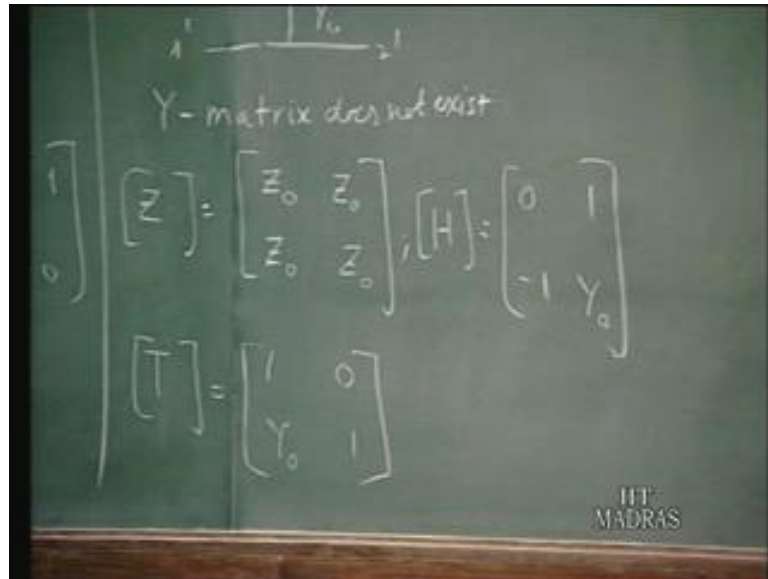


Now let us, take another simple case, where we have a shunt element Z_{02} or Y_{02} . Now, if you short circuit this and measure the input admittance that is going to be infinity and so it turns out that all the Y parameter elements Y parameters are going to be infinity. Therefore, we can say Y matrix do not exists, what about Z matrix? If you keep the port 2 open and measure the input admittance that is equal to the impedance of this element.

So, let us say this is Z not or it is admittance Y not. So, the input impedance when port 2 is open is Z not. Keeping port 2 open if you drive a current I_1 here, the voltage that is developed across port 2 is the same as the voltage that is developed across this impedance which is I_1 times Z not. Therefore, V_2 divided by I_1 when I_2 is 0 that is the value of Z_{21} and it happens to be equal to Z not. Therefore, this is also Z not.

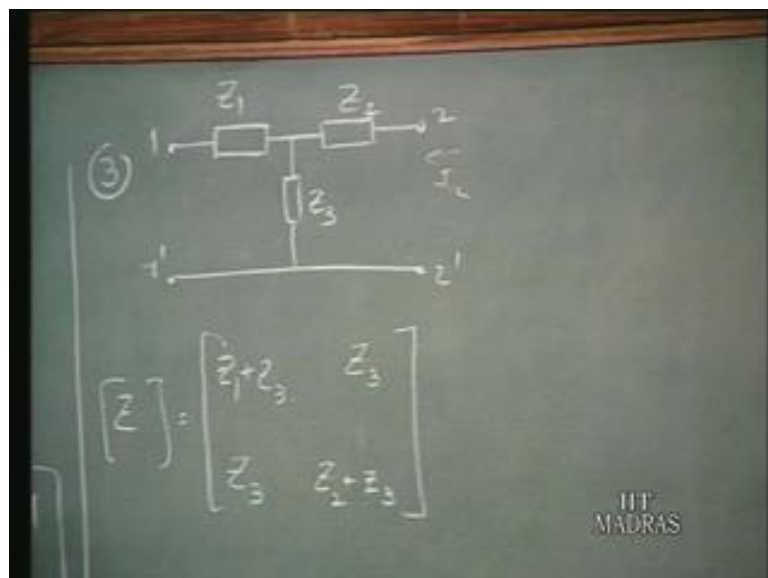
And again, this is a symmetrical reciprocal network. You if you calculate Z_{22} and Z_{12} they will also be the same. So, for a simple 2 port network constituted by 1 shunt impedance this is the Z matrix for this.

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The H matrix for this still likewise can be computed $0 \ 1 \ \text{minus} \ 1 \ Y \ \text{not}$. Again, it is a symmetrical network its determinant is going to be 1 and H_{12} is equal to minus of H_{21} which is a consequence of reciprocity. The transmission matrix for this will be $1 \ 0$, we will also have a very simple form $1 \ 0 \ Y \ \text{not} \ \text{and} \ 1$. And again, you see the determinant of the transmission matrix $AD - BC$ is equal to 1 that comes as a result of the reciprocity of this network.

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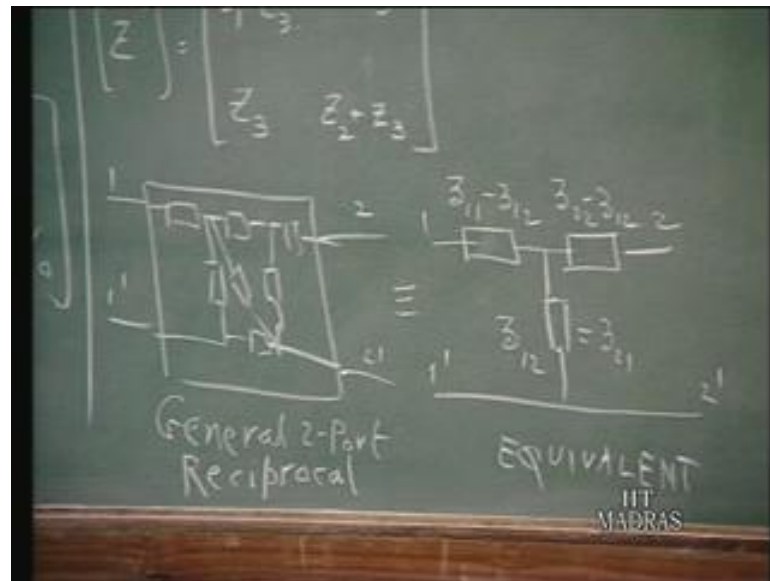
Let us, now take a third example here, we complicate this a little bit let us consider a T network consisting of 3 impedances, impedance function that is $Z_1 Z_2 Z_3$. These are all functions of s . So, 3 port networks connected in a T formation, this is called a T network. Because, 3 impedances have the configurations corresponding to a T letter T. Therefore, this is a T network and if $Z_1 Z_2 Z_3$ are functions of s .

If you want this particular configuration enables us to determine Z matrix of this 2 port network very conveniently. Z_{11} is the impedance seen at port 1 keeping port 2 open. So, if you drive a current I_1 through this 1 port terminals that current passes through these two impedances. Because, port 2 is open and it develops a voltage Z_3 times I_1 across port 2 and across port 1 it develops Z_1 plus Z_3 times I_1 . Therefore, the Z matrix for this shall have Z_{11} is Z_1 plus Z_3 Z_{21} is simply Z_3 .

Because, a current I_1 flowing through this will develop a voltage Z_3 times I_1 across this shunt network shunted branch which is also the voltage across port 2. So, Z_3 will be the Z_{21} element and when you do the same operation connecting a current source here have I_2 and keeping this open the voltage that is developed across port 1 is Z_3 times I_2 . Therefore, Z_{12} which is V_1 divided by I_2 when I_1 is 0 it happens to be Z_3 . Therefore, this is Z_3 .

And the looking in impedance here, when port 1 is open is this sum of this 2 which is Z_2 plus Z_3 . So, you observe that in the case of a T connected configuration in a 2 port network the values of the Z parameters can be computed by surprising is very simple.

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In a converse fashion, suppose we have a complicated 2 port network. Let us, say highly complicated 2 port network may be like this a general 2 port. Now, this general 2 port will have some Z parameters. You can compute them using various methods of network analysis that are available to you.

But, if that general 2 port network has got a Z matrix which is equal to Z_{11} it is given by $Z_{11} - Z_{12} Z_{22}^{-1} Z_{12}$ and Z_{12} and $Z_{22} - Z_{12} Z_{11}^{-1} Z_{12}$ in our general configuration. We can form an equivalent T network for this in this form. So, this is an equivalent network which has identical terminal behavior as the original network. So, what is meant by an equivalent network at that if you have 2 network equivalent then the terminal behavior of the two networks are identical? So in the case of, a 2 port network the relation between V_1, V_2, I_1 and I_2 will be identical in both cases.

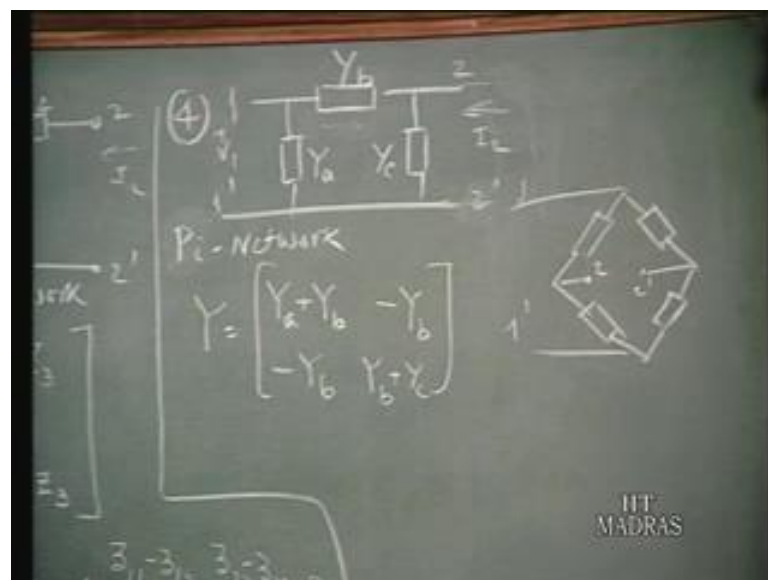
So, if I have this general 2 port described by a Z matrix, I can describe the terminal relations of the general 2 port by means of this equivalent network by writing this as $Z_{11} - Z_{12} Z_{22}^{-1} Z_{12}$. This as Z_{12} and this as $Z_{22} - Z_{12} Z_{11}^{-1} Z_{12}$, so; that means, when you look from this side the total impedance when keeping port 2 open is $Z_{11} - Z_{12} Z_{22}^{-1} Z_{12}$.

Therefore, Z_{11} which is the driving point impedance of this network I use that value here I; that means, all this parameters are those which relate to the general network, if I calculate them and then incorporate three impedances having these values. This

particular network will have the same terminal relations as this original network. All this is just on the basis that this is the reciprocal 2 port network in which Z_{12} is the same as Z_{21} ; that means, general 2 port network which is reciprocal this is very important.

If this is not reciprocal that equivalent will not be valid. So, we have a general reciprocal 2 port network which follows the reciprocity theorem which means Z_{12} is equal to Z_{21} . And there in that case this is an equivalent configuration for this general 2 port networks. So, instead of dealing with this complicated 2 port network, we can always replace this by its equivalent and use this for in the analysis problem.

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In a similar fashion, if I have a, what is called a pi network. Suppose, I have a configuration like this with three elements, let us say this is Y_a this is Y_b this is Y_c . Then, for such a network calculation of the Y parameters turns out to be very convenient. So this is the port 1, 1 prime 2 2 prime the Y parameters for this is very convenient to calculate.

Because, when you short circuit this and measure the admittance at port 1 that is the parallel combination of Y_a and Y_b . Because, one position is shorted Y_a and Y_b come in parallel and that is the total admittance seen at port 1. Therefore, Y_{11} equals Y_a plus Y_b . Now, what is the current in port 2, when this is shorted what is I_2 in terms of V_1 . When you have applied voltage V_1 and short circuit these terminals this entire V_1 appears across Y_b .

So, the current in this direction is V_1 times Y_b . But, our reference direction for current I_2 is in the opposite direction. Therefore, I_2 divided by V_1 turns out to be minus Y_b . Therefore, this will be minus Y_b . And similar arguments by applied when you short circuit port 1 and may apply a voltage across port 2 will lead to just to the result that Y_{12} is equal to minus Y_b and this is Y_b plus Y_c .

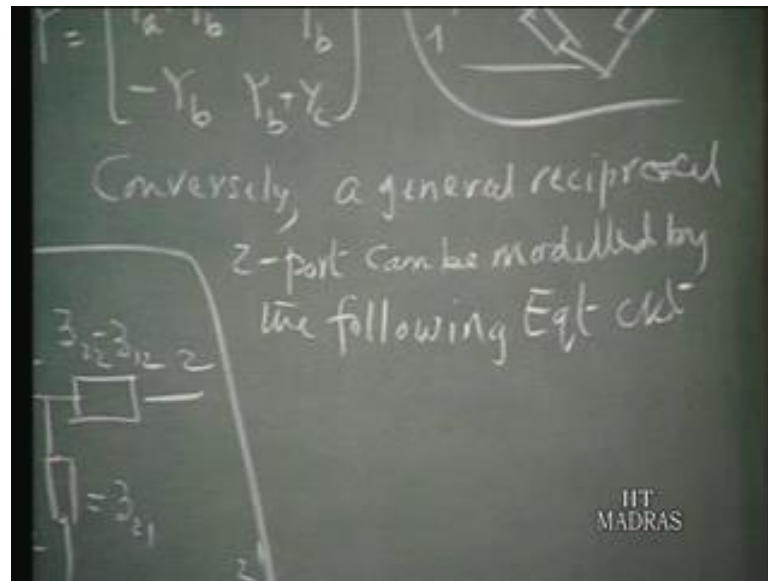
So, when you have a pi network this is called this; obviously, a part of the form of the pi. The letter pi symbol pi here and this is called a pi network. So, when you have a pi network usually referred to as pi network. This is called a tee network. So, when you have a pi network the calculation of the Y parameters turns out to be very convenient.

And we have a negative sign here that is important to note. Because, we have taken the reference direction in this fashion and therefore, when you apply a voltage V_1 current actually flows in this direction. Suppose, you have few resistance the current will go in this direction. If this is a DC source and resistance the current will flow in this direction. But since, our reference direction is opposite sense it turns out as far as the transfer admittance are Y matrix is concerned.

You will have lot of negative coefficients. So that has to be taken kept in mind. That as far as the network of a 3-terminal configuration; that means, there is a common ground between port 1 and 2 it turns out that the coefficients in the transfer admittances will turn out to be negative. It may or may not be. So, when you have a four terminal type of 2 port network.

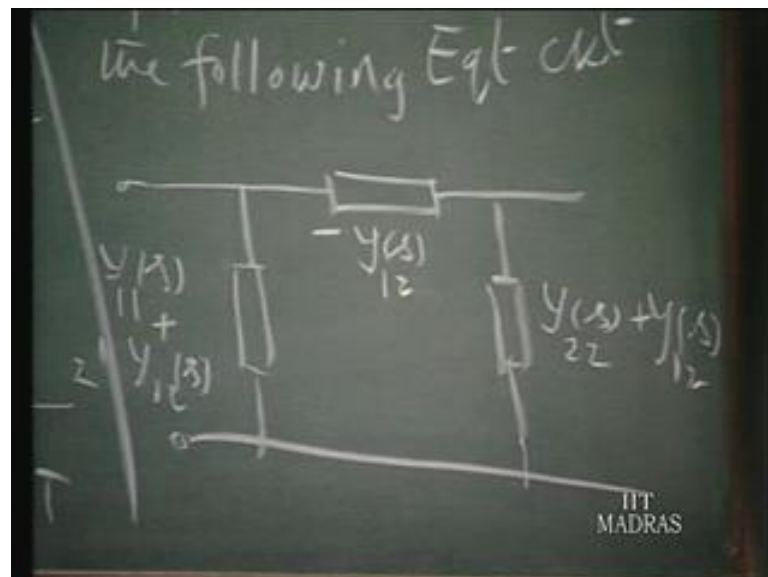
For example, if I have a 2 port network in this like in this fashion suppose this is port 1 1 prime and this is port 2 2 2 prime. There is no common connection between 1 prime and 2 prime in such cases the transfer admittances may have positive coefficients or negative coefficients or both. But on the other hand, if it is a 3-terminal 2 port you have negative coefficients like this. So, this is.

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So, conversely a general reciprocal 2 port can be modeled by the following equivalent circuit. That is just as we have found out an equivalent circuit for a reciprocal general 2 port networks here. You found out that an equivalent circuit in this form similarly when you have a general reciprocal 2 port network.

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We can find out the equivalent circuit in terms of the Y parameters in this fashion. You have seen (Refer Slide Time 15:43) you observe that this shunt element here is minus of I mean the series element series impedance is branch here as an admittance equal to

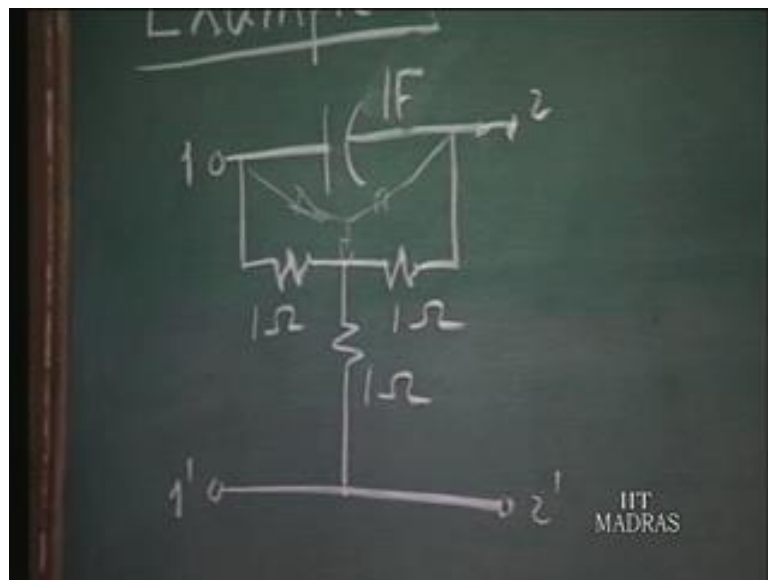
negative of Y_{12} or Y_{21} . Therefore, I can write this as minus Y_{12} of s and when you short circuit this.

The total admittance seen from port 1 must be Y_{11} . Therefore, this must be whatever you are having here is equal to Y_{11} of s plus Y_{12} of s . So, this 1 port network must have total admittance Y_{11} of s plus Y_{12} of s . So, this plus this when you short circuit this will provide a total admittance at port 1 which is equal to Y_{11} of s . Likewise this admittance will be Y_{22} of s plus Y_{12} of s . So that is the configuration.

So, we have seen from these two examples that there is a duality between them. If we have a t network you can find out the open circuit impedance parameters quite conveniently or in a general 2 port reciprocal network it can be modeled in terms of the Z parameters by an equivalent T network quite conveniently.

Similarly, if you have a π network the Y parameters are easy to compute or conversely a general reciprocal 2 port network can be modeled by a convenient equivalent circuit in the form of a π network using the Y parameters as shown here.

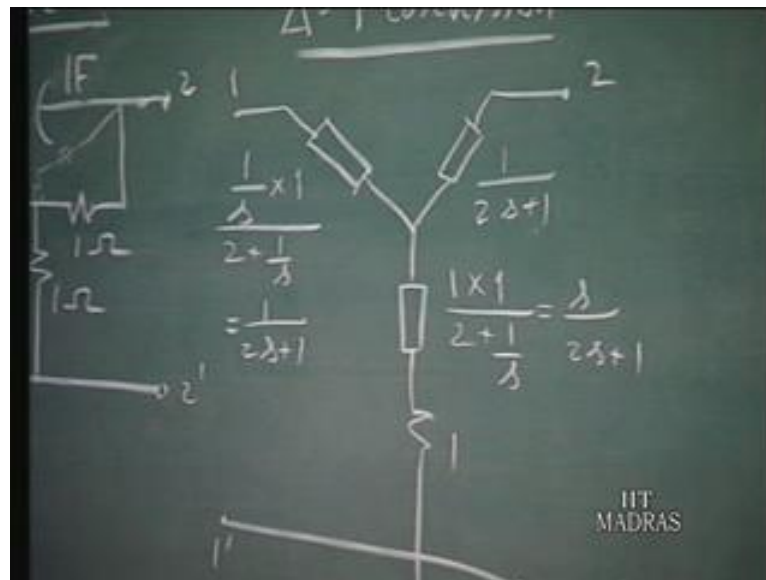
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This is a slightly more complicated example. Let us say that we are interested in finding out the Z parameters of this 2 port network. We have seen earlier that if the network is in the form of a T network then the evaluation of the Z parameters is quite convenient. How are this configuration is not in the form of a T .

On the other hand if you convert this delta configuration of a 1 farad capacitor and 2 1ohm resistors by means of convert this into a star like this. Then, the whole network falls out into the form of a T network. So, let us try to do that convert this delta into an equivalent star.

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So, delta to star conversion now the rules for this convention follow exactly the same lines as we have in the case of resistive networks or in the case of impedances under AC fed circuit analysis. So, however we have to use the generalized impedances in this case. So, this delta if it has to be converted into a star, we have three generalized impedances like this.

And of course, we have this 1ohm resistance here, so this will be 1 prime 2 2 prime. So, this delta will be converted into this equivalent star and we are can find out the open circuit impedance parameters of this altered configuration the terminal conditions will remain the same, because whatever changes have been brought about are internal to the 2 port.

The impedance of this is obtained by the product of these two impedances divided by the sum of three impedances. Therefore, the impedance of this will be one upon s that is generalized impedance of this times 1 divided by the sum of the three impedances which is 2 plus 1 over s which will be of course, 1 upon 2 s plus 1.

By symmetry this will also be $1 \text{ upon } 2s + 1$ that is the impedance of this box. The impedance of this box; however, is the product of these two impedances divided by the sum of impedances. So, this $1 \text{ times } 1 \text{ divided by } 2s + 1$ over s this will be $s \text{ upon } 2s + 1$. And of course, this 1 ohm resistance will remain. So now, the entire network now is in the form of a T network and we can find out the open circuit impedance matrix of this port 2 with without further I do.

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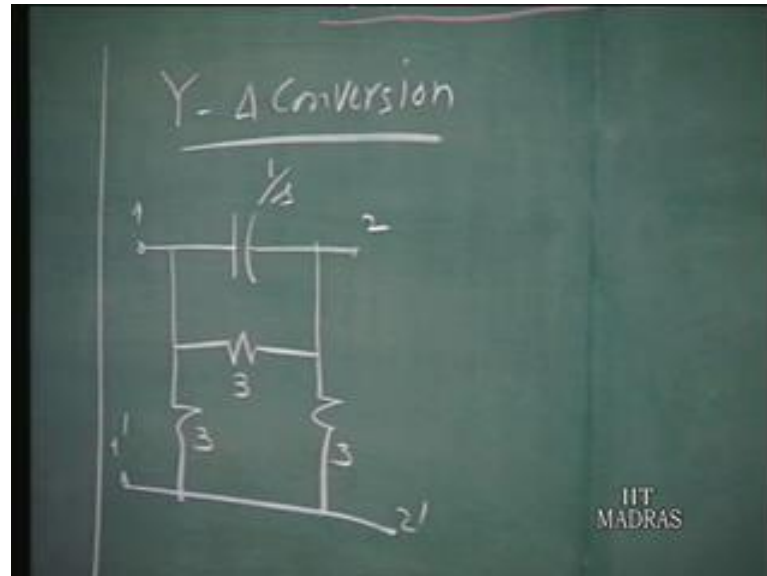
$$Z_{oc}(s) = \begin{bmatrix} \frac{s+1}{2s+1} + \frac{1}{s} + \frac{3s+1}{2s+1} & \frac{s}{2s+1} \\ \frac{s}{2s+1} & \frac{3s+2}{2s+1} \end{bmatrix}$$

So, Z_{oc} of s of this would be the driving point impedance at port 1 is the sum of this impedance plus this impedance plus this impedance. This is $1 \text{ over } 2s + 1$ this is $s \text{ over } 2s + 1$. Therefore, $s \text{ plus } 1 \text{ over } 2s + 1$ plus 1 of course, which will be of course, $3s + 2 \text{ over } 2s + 1$ that is Z_{11} . By symmetry Z_{22} is also $3s + 2 \text{ over } 2s + 1$. Z_{12} and Z_{21} given by this impedance of this shunt branch $s \text{ over } 2s + 1$ plus 1 that will be $3s + 1 \text{ over } 2s + 1$ that one will be the open circuit impedance matrix of this 2 port network.

On the other hand let us imagine that we are interest in finding out the Y parameters of that. To find out the Y parameters its most convenient if the network is in the form of a pi. So, how can you convert this into an equivalent pi? The answer is quite straightforward, we have three resistors connected in star if you convert them into an equivalent delta we have one branch coming in parallel with 1 farad capacitor.

Another branch coming in parallel with first port, a third branch coming in parallel with second port the whole configuration will be in the form of a pi.

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So, let us do that. So, star to delta conversion if you do that. We retain the identity of the 1 farad capacitance, which has got generalized impedance $1/s$. In addition to these three resistors are connected into an equivalent delta. So that will be the altered configuration. The impedance of this 3 ohms and star as equivalent to 3 ohms in delta, so these are all the generalized impedances are 3 ohms each. So that will be the configuration that we have for the pi network that is obtained by converting the star in to an equivalent delta.

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$$Y = \begin{bmatrix} \frac{2s+8}{3} & -\frac{(3s+1)}{3} \\ -\left(\frac{1}{3}+s\right) & \frac{3s+2}{3} \end{bmatrix}$$

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So, what are the Y parameters for this? In the short circuit admittance matrix from this now, (Refer Slide Time 26:49) the driving point impedance at port 1 is obtained by short circuiting second port and looking at the impedance as seen from port 1, which will be this is 3 ohm resistor its admittance is one-third. The admittance of this is one-third and that is in parallel with the capacitor of admittance s .

So, all these three elements come in parallel because port 2 is effectively short circuited. So, port 1 is an admittance which is the sum of this impedance plus this admittance this admittance plus this admittance plus this admittance that will be $\frac{2}{3} + s$ which is $\frac{2 + 3s}{3}$. And by symmetry the impedance seen from port 2 as well will be $\frac{3s + 2}{3}$.

Now, what about the transfer admittance? Suppose you short circuit this drive apply voltage here. The current that flows in port 2 is limited by the admittance of this parallel branch. Because, this is ineffective because you have short circuited and the current here we do not care what it is we are interested in only the current flowing in this. So, the current flowing in this will be the applied voltage times the admittance of this parallel combination. That will be $\frac{1}{3}$ by $\frac{1}{3}$ is the admittance of this and s is the admittance of this.

So, $\frac{1}{3} + s$ times V_1 will be the current flowing in this direction. But, our port difference is in this direction the current which is measured always with this reference

side. Therefore, we must put a negative sign out in front. So, Y_{21} will be minus of one-third plus s . That will be minus of $3s + 1$ over 3 and Y_{12} likewise will be minus $3s + 1$ upon 3 . That will be the admittance transferred short circuit transfer admittance of Y_{12} .

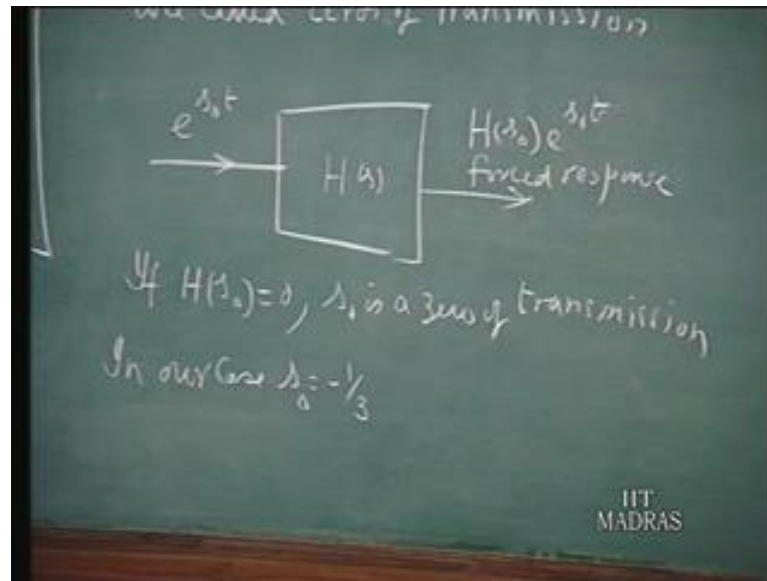
(Refer Slide Time 25:00) Now we observe here, that Z_{12} Z_{21} Y_{12} Y_{21} or all of them having the same $0, s$ equals minus one-third makes this 0 this also zero. And so, does it make the transfer impedances Z_{21} and Z_{12} 0 .

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Zeros of transfer function are called are called zeros of transmission. Essentially, they are the values of the complex frequency for which if you apply the signal as an input with that complex frequency the output turns out to be 0 . Therefore, they are called zeros of transmission.

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And the zeros of transmission are inherent for a particular network. So, if you are having a system function H of s a generalized system function general transfer function. If you apply a exponential input signal e power s e power s not T and the forced response is of course, H s not times e to the power s not t is the forced response. Then, if H s not is 0 , then s not is said to 0 of transmission.

And this zero of transmission is inherent for a particular system. So, with minor exceptions here and there if there is a particular zero transmission associated with transfer admittance that will also be the zero of transmission with the transfer impedance transfer voltage ratio transfer current ratio and so on and so forth. So, H of s can be any type of transfer function for a signal flow of input from port 1 to port 2.

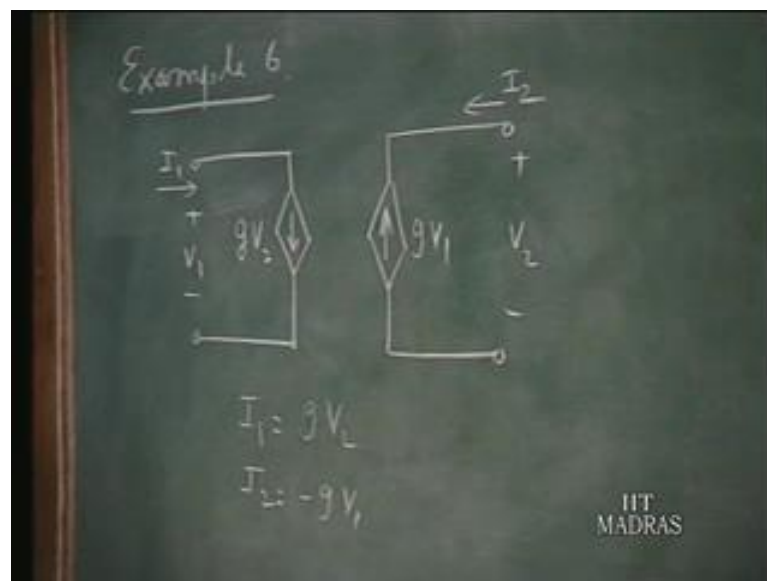
In this case in our case there is only 1 zero of transmission that s not happens to be minus one-third. So, if you drive this 2 port network at port 1 with an exponential signal e power s not T where s not is minus one-third. Then, the forced response at the output is zero, a word about this zero of transmission or zeros of transfer function.

We know that the poles and zeros of driving point functions have certain restrictions as far as their natural response is concerned. The g from the point of your stability of a passive network we already observed that the poles and zeros of passive transfer driving point functions of passive networks must be in the left of plane. And if they are in the imaginary axis they should be simple.

So, from the point of view of stability of passive networks the poles and zeros of driving point functions have got certain restrictions. Same restrictions also are valid for the poles of transfer functions. For example, this transfer function has a pole at s equals minus half. So, poles and zeros of transfer functions the poles of transfer functions must have the same restrictions as poles and zeros of driving point functions as far as passive networks are concerned.

But as far as zeros of transfer functions are concerned, there is no such restriction. Even for passive networks you may find the zeros of transmission anywhere in the complex s plane. They need not be restricted to left of plane. They can be in the imaginary axis they can be in the right side of plane and so on and so forth. So, absolutely no restrictions and zeros of location of zeros of transmission are the zeros of transfer function.

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The poles of transfer function; however, are restricted in the same way as the poles and zeros of driving point functions. So far, we have been considering only reciprocal networks. So, let us consider a 2 port network constituted by dependent sources. We have two dependent current sources, the current here depends upon this voltage the current here depends upon this voltage.

So, we have for this network I_1 equals g times V_2 , I_1 of s is g times V_2 of s and I_2 which is a current in this direction is minus of g g V_1 . So, minus g V_1 , so these are the two conditions on the terminal variables.

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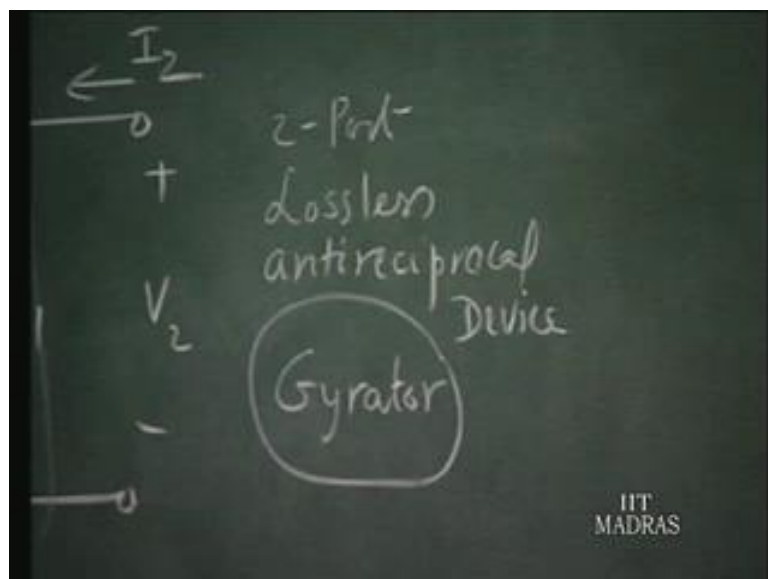
Handwritten equations on a chalkboard:

$$I_1 = gV_2$$
$$I_2 = -gV_1$$
$$[Y] = \begin{bmatrix} 0 & g \\ -g & 0 \end{bmatrix}$$
$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} 0 & g \\ -g & 0 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

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Therefore, the Y matrix for this will be I_1 equals g times V_2 and I_2 equals minus g times V_1 so; that means, I_1 I_2 are given by this matrix 0 g minus g 0 multiplying V_1 and V_2 . So, you observe that this Y matrix is not the of diagonal elements or not in the same; that means, this is not reciprocal. So, V_1 we have dependent sources in the 2 port network the reciprocity relationship may not be valid.

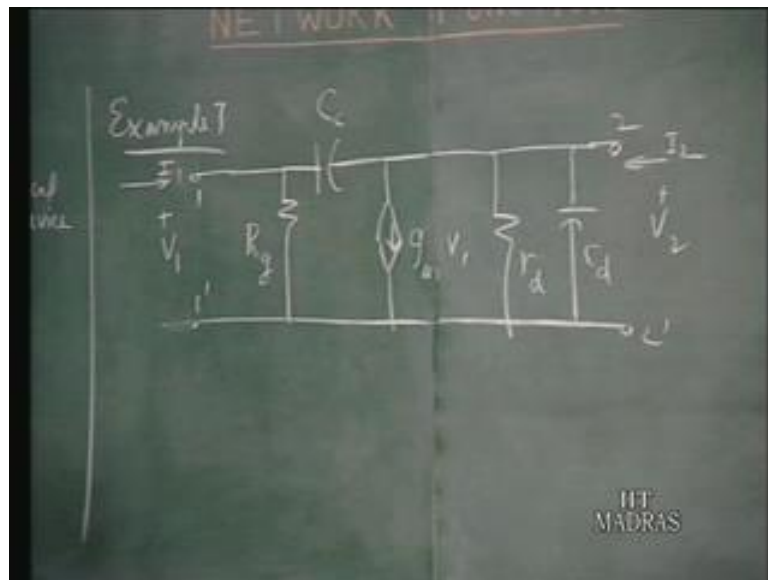
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In fact, this is what is called anti reciprocal if this if the network is a reciprocal we expect these 2 to be equal is exactly the negative of this. So, this is called anti reciprocal such a

2 port network constitutes, what is called a gyrator? This is a 2 terminal pair 2 port lossless anti reciprocal device which can be constructed with active elements this is a one element this is used in active networks and it is a design of active filters. But, we will just note the terminal relations and leave it at that.

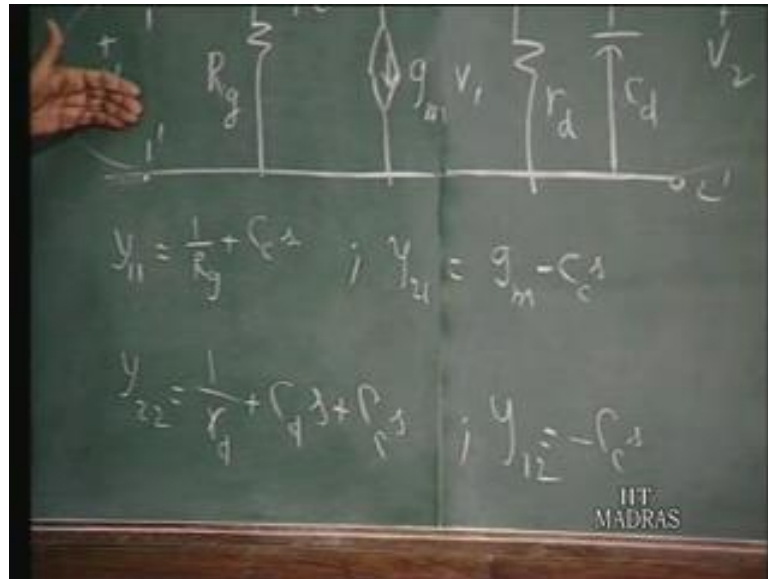
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Let us, take another example slightly more complicated. Suppose we have, this is a model of some active circuits, we have g_m times V_1 . We have resistance r_d and finally, you kept capacitance c_d . So, this is I_1 prime 2 prime V_1 I_1 V_2 and I_2 . We can calculate the Y parameters for this quite conveniently. So, let us do that Y 11 you short circuit V_2 and measure the driving point admittance. Once you short circuit V_2 there will be low currents in r_d and c_d .

You can forget about that and the impedance the admittance as seen from port 1 is the admittance of this plus the admittance of this. Because, these two are now coming in parallel and that what constitutes the current here and whatever current is generated in this dependent source will flow through a short circuit $g_m V_1$, because that is the path with the least impedance.

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So, Y_{11} will be the admittance of this plus the admittance of this. So, $1/R_g$ plus C_c that is Y_{11} , Y_{21} the current in this I_2 short circuited current in the short circuited terminals when applied voltage V_1 is there. V_1 drives a current through C_c like this therefore, there is a current C_c times V_1 . In addition we have a current through this dependent source $g_m V_1$ going like this.

And since the direction positive reference direction for current I_2 is in this direction. So, you have that current divided by V_1 will turn out to be g_m minus C_c of s that is Y_{21} g_m minus C_c of s that is Y_{21} . Y_{22} , if you short circuit the port 1 apply voltage V_2 and measure the current in the driving terminals that current will be constituted by the current flowing in r_d C_d .

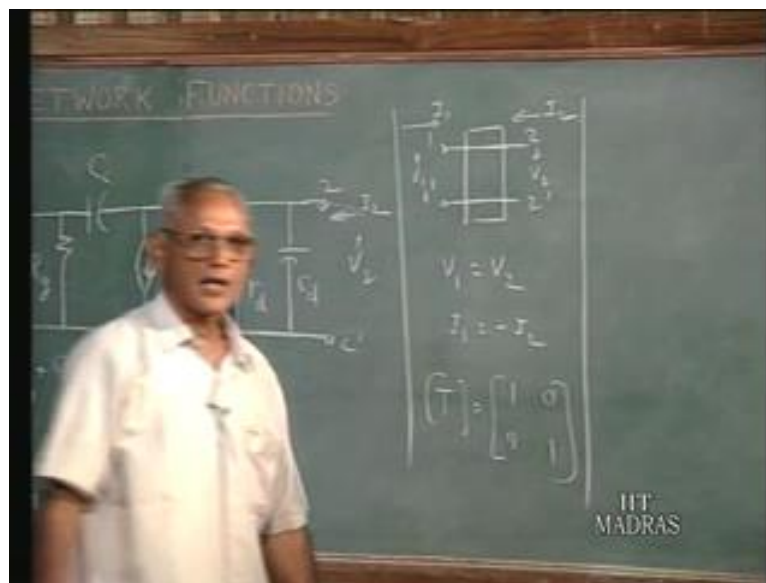
Since, V_1 is shorted the current source strength is 0. Therefore, this is open circuited you have a current passing through the cap coupling capacitor C_c through these terminals. Therefore, the parallel combination of this this and this constitute the total admittance. So, you have $1/R_d$ plus C_d plus C_c that is your Y_{22} . Y_{12} is the ratio of current flowing through the shorted terminals in this direction divided by V_2 . So, V_2 drives a current through C_c in this direction which is C_c times V_2 .

So, the current in the direction reference direction for I_1 is minus C_c times V_2 therefore, Y_{12} is minus C_c . Notice here, once again Y_{12} is not the same as the Y_{21} . This is because this is not a reciprocal 2 port network, because of the presence of the

control source $g_m V_1$. So, when you have control sources present can reciprocity relations will not be valid this is an active 2 port and reciprocal this reciprocity is not valid.

We have seen in these examples and some of the earlier examples that for a 2 port network one set of parameters make exist another set may not exist. We have seen that in the case of a pure series branch Z parameters do not exist, but other parameters may exist. In general it may be that 1set of parameters may exist others may not.

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So for a very simple case, suppose I have 2 port constituted by two line like this these are two lines going right through from port 1 to port 2. You will find that all parameters except the ABCD parameters exist. So in this case, we have V_1 equals V_2 and I_1 equals minus I_2 . Therefore, the chain parameters are ABCD parameters are exist which is equal to $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$. Other parameters do not exist. You would not have x you would not have Z parameters you will not have Y parameters you do not have H parameters for this 2 port network.

Now, we have constructed an equivalent circuit of a 2 port network in terms of Z parameters and Y parameters. And we said those 2 equivalent circuits in terms of T T I T configuration and pi configuration are valid for a reciprocal 2 port. Now, what happens if you have a general 2 port of this with a lot of active elements present? And if you want

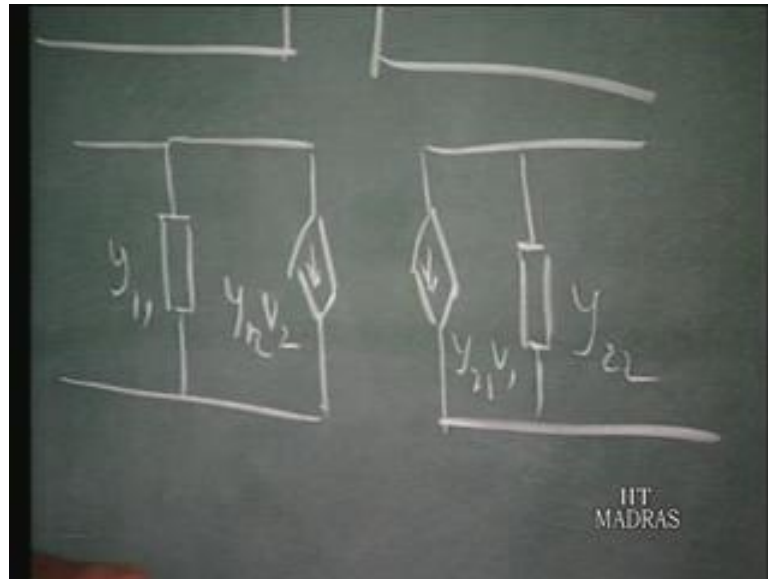
to find out the equivalent circuit for such situations, then we will have to model the equivalent circuits in terms of active elements.

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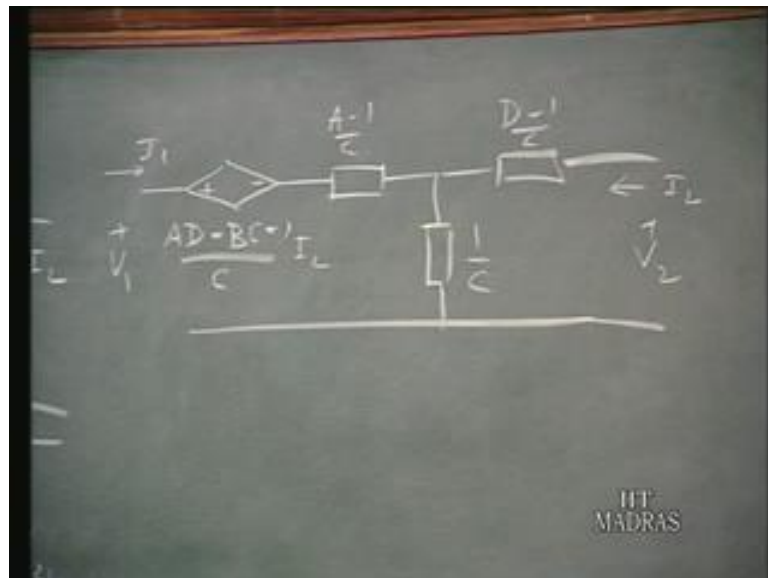
So, the general equivalent 2 port networks general equivalent circuits in terms of active elements can now be given. We can say for Z parameters we can write Z_{11} plus a voltage source which is equal to $Z_{12} I_2$ V_1 . And likewise, you have $Z_{22} I_2$ plus any equivalent a source here which is a dependent voltage source which is $Z_{21} I_1$. That is an equivalent circuit in terms of Z parameters for a general not only the reciprocal network.

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In terms of Y you have $Y_{11} V_1$ plus a current source which is equal to $Y_{12} V_2$ and this is the port. And for port 2, we have $Y_{22} V_2$ that is the current here and you have $Y_{21} V_1$. That is the a port network which will be an equivalent circuit in terms of Y parameters for a general 2 port network.

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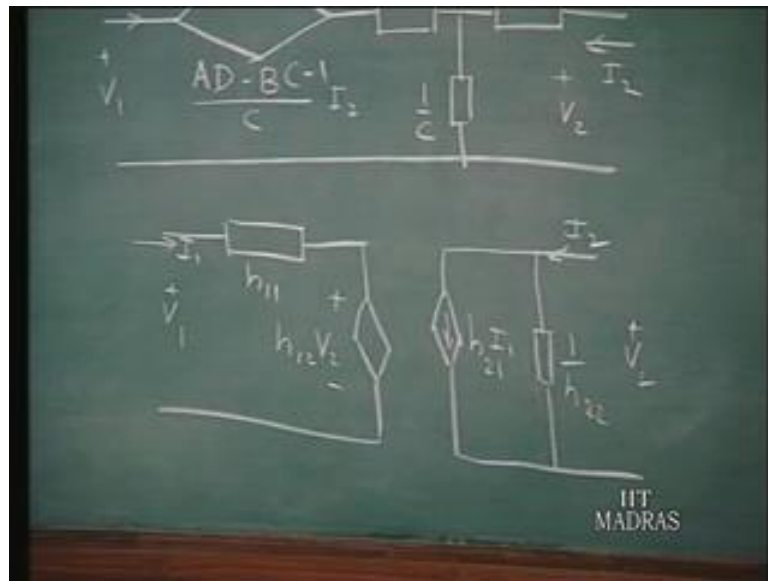


Current in terms of the ABCD matrices, you have you can write this in the form have A minus 1 upon C this is an impedance of this. This is D minus 1 upon C that is also

impedance $\frac{1}{C}$ is an impedance. And in addition, you can have a dependent source which is $\frac{AD - BC - 1}{C}$ times I_2 .

So, if you analyze this network you will find out that it will also determine relations of a 2 port in terms of ABCD term parameters V_1 equals A times V_2 minus B times I_2 etcetera. And for a reciprocal network this becomes 0, because $AD - BC$ equals 1 therefore, this dependent source will vanish.

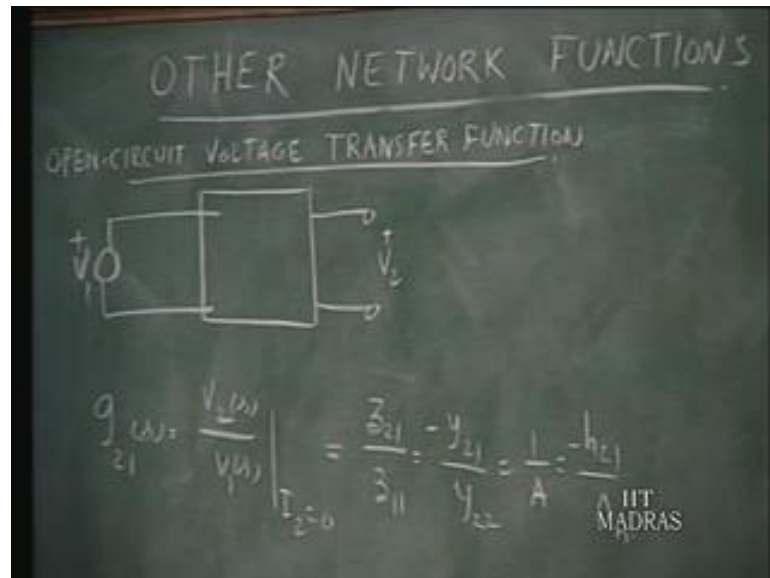
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In the case of h parameters the equivalent circuit would be like this we have V_1 equals I_1 times h_{11} that is an impedance plus h_{12} times V_2 . So, it is a voltage source dependent voltage source which depends on the value V_2 and h_{12} is a dimensionless factor. On the other hand, the current I_2 will be h_{21} times I_1 . So, this is a current source of value h_{21} times I_1 in parallel with an element whose impedance is $1/h_{22}$. So, if this is V_2 the current here is V_2 times h_{22} .

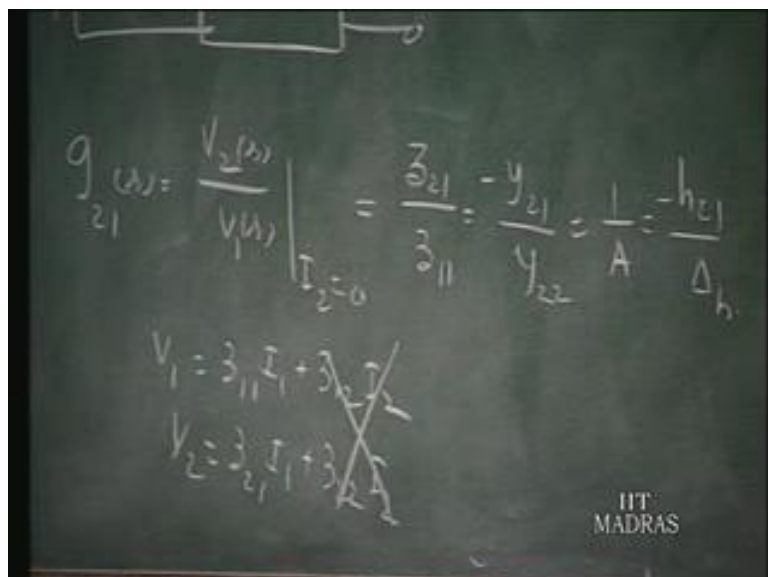
Therefore, the total current is $h_{21} I_1 + h_{22} V_2$ plus $h_{21} I_1$. So, this is a current source whose current ratio is h_{21} . And this is a voltage controlled voltage source whose value is $h_{12} V_2$. So that is the configuration which gives an equivalent circuit of the 2 port network in terms of h parameters. So, these are the general equivalent circuits which can be made use of for analyzing the 2 port network, instead either you can use the equations or this equivalent circuit.

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When dealing with 2 port network, we often use network functions other than those which have already we discussed in this particular example. We have port 2 open, we apply an input voltage V_1 . The ratio of V_2 of s to V_1 of s under open circuit conditions is called the open circuit voltage transfer function in the forward direction that is if the signal is going from port 1 to port 2.

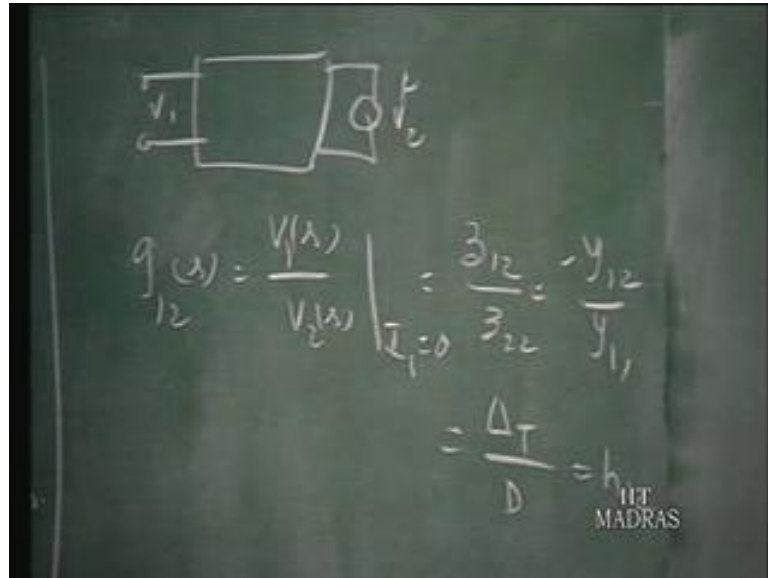
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And it can be shown that this Z_{21} by Z_{11} for example, you have V_1 equals $Z_{11} I_1$ plus $Z_{12} I_2$ and V_2 equals $Z_{21} I_1$ plus $Z_{22} I_2$ and when I_2 is 0. These two terms

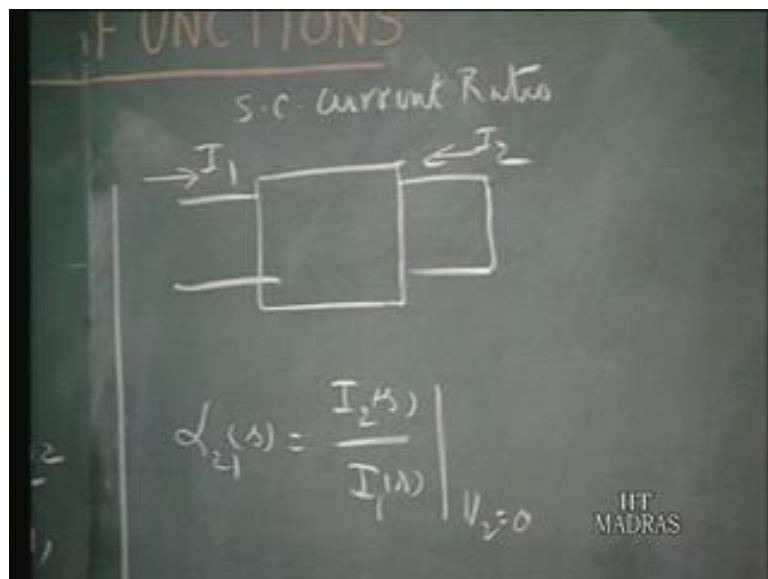
get cancelled out. The ratio of V_2 to V_1 is Z_{21} over Z_{11} likewise you can show that this is also equal to $-Y_{21}$ over Y_{22} , this can also be shown to be $1/A$ or $-h_{21}$ by Δ_T .

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Similarly, if we have kept port 1 open and apply a voltage to the port 2. So, V_1 this is g_{12} of V_1 of s over V_2 of s when I_1 is 0 that can be written as Z_{12} over Z_{22} minus Y_{12} over Y_{11} is the Δ_T over D , where this determinant this is the determinant of the transmission matrix is also equal to h_{12} . So, this can be we can work this out yes.

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Often we may also be interested in finding out the short circuit current ratio; that means, you apply a certain current I_1 here and measure the current I_2 under a short circuit conditions. So, you write this α_{21} of s is I_2 of s over I_1 of s when V_2 is 0 that is this is called the short circuit current ratio.

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The image shows a chalkboard with the following handwritten equations:

$$\alpha_{21}(s) = \frac{I_2(s)}{I_1(s)} \Big|_{V_2=0}$$

$$= \frac{y_{21}}{y_{11}} = -\frac{z_{21}}{z_{22}} = -\frac{1}{D} = h_{21}$$

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And you can show that this is equal to Y_{21} over Y_{11} equals minus Z_{21} over Z_{22} equals minus 1 over D equals h_{21} .

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The image shows a chalkboard with a circuit diagram and the following handwritten equations:

Circuit diagram: A rectangular box representing a two-port network. An input current I_1 is shown entering the left side. An output current I_2 is shown entering the right side. The output terminals are short-circuited.

$$\frac{I_1}{I_2} \Big|_{V_2=0} = \alpha_{12}(s)$$

$$\frac{1}{D} = h_{21}$$

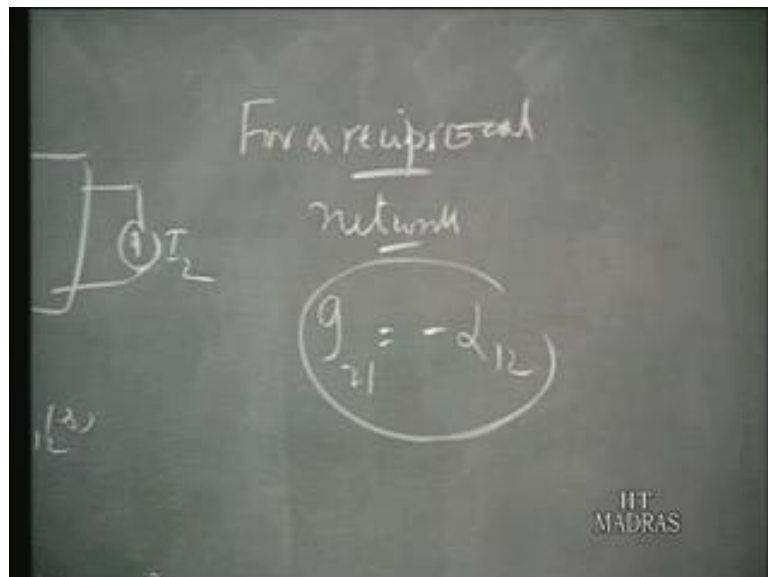
$$= \frac{y_{12}}{y_{22}} = \frac{-z_{12}}{z_{11}} = -\frac{\Delta_T}{A} = \frac{-h_{12}}{h_{22}}$$

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And to complete this picture you might have a situation where you want to find out the ratio of I_1 to I_2 when V_1 is 0 this is α_{12} of s. And this can be shown to be $\frac{Y_{12}}{Y_{22} - Z_{21} - Z_{12}}$ by Z_{11} equals $\frac{\Delta T}{\Delta h}$.

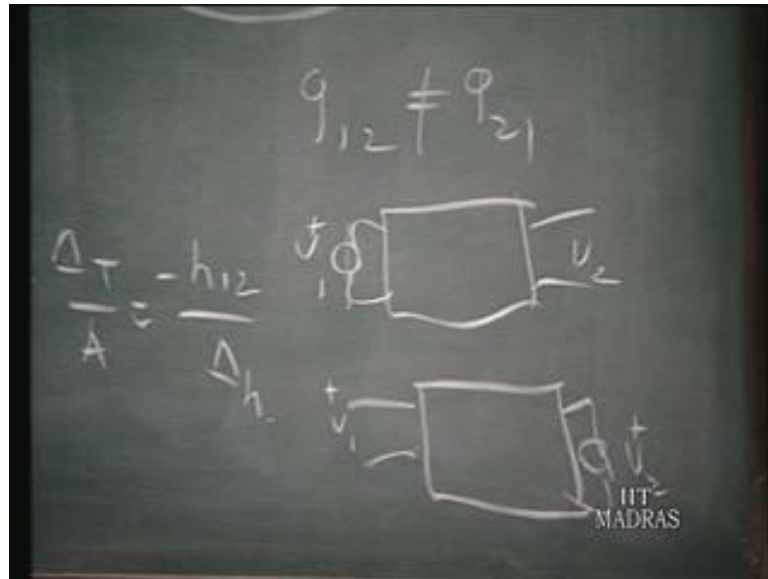
The important thing to note in this one important thing that you can note is that the transfer voltage ratio in the forward direction which is $\frac{Z_{21}}{Z_{11}}$ will turn out to be the negative of the short circuit current ratio in the opposite direction $\frac{I_1}{I_2}$ because Z_{12} is same as Z_{21} for a reciprocal network.

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So for a reciprocal network, we can say for a reciprocal network g_{21} equals minus α_{12} . The open circuit voltage ratio in the forward direction is the negative of the short circuit current ratio in the reverse direction.

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We cannot say that g_{12} is not equal to g_{21} , because when you are measuring g_{21} you are keeping this open and you are applying a voltage source. This is V_2 over V_1 to find out g_{21} . On the other hand when you want to measure g_{12} you are keeping this open and you are applying a voltage here. So, this is V_1 divided by V_2 .

You observe that in the natural configuration natural state of the system when you short circuit this port 1 is shorted port 2 is opened in this port 2 is shorted port 1 is opened. So, the natural state of these two networks before the excitation is introduced is different. Therefore, even though we may have reciprocal elements here it does not follow the reciprocity theorem.

Because, the natural states of the 2 networks are different one is short circuited here kept open? The other is short circuited here and this is kept open therefore, g_{21} is not equal g_{12} is not equal to g_{21} even in the case of a reciprocal network. On the other hand for a reciprocal network g_{21} equals minus g_{12} .

So, in this lecture, we have expanded our knowledge of the 2 port network parameters. We considered various examples saw the consequences of the reciprocity and symmetry on the values of the network parameters. We saw that when we have dependent sources inside the network reciprocity property is violated. And at particularly appear occurs when we have active elements inside.

And then, we also saw that in the case of a open circuit of a um port 1. We define what is meant by an open circuit voltage transfer ratio g_{12} which can be expressed in terms of Z parameters and Y parameters. Similarly, the short circuit current ratio can be expressed in terms of these parameters. And we saw reciprocal network the open circuit voltage ratio in one direction is the negative of the short circuit current ratio in the opposite direction. We will continue our discussion in the next lecture.