

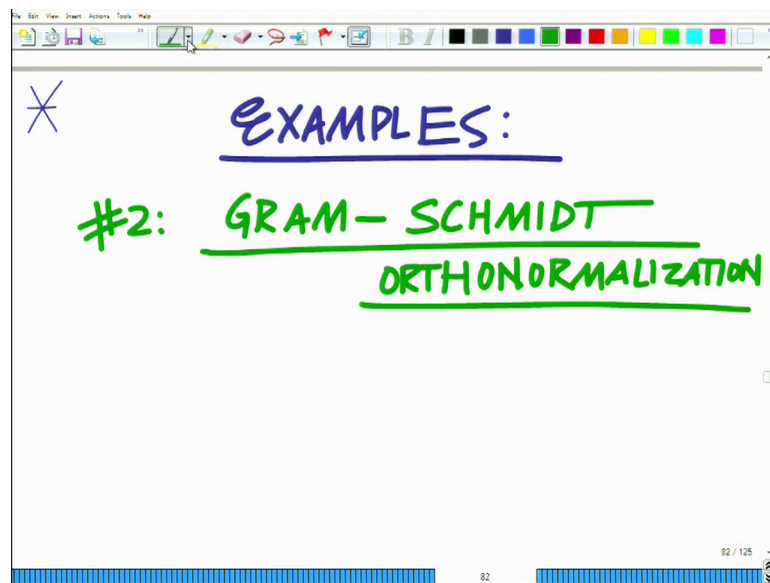
Applied Optimization for Wireless, Machine Learning, Big Data
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Lecture - 07
Gram Schmidt Orthogonalization Procedure

Hello, welcome to another module in this massive online open course. So, let us we are looking at examples to understand the mathematical preliminaries of optimization. Let us look at another example and this is something that is very important and has a lot of practical utility, this is termed as the Gram Schmidt Orthonormalization Process ok.

So, we are looking at examples correct?

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And as part of the second example; what we want to look at is the Gram Schmidt procedure for Orthonormalization, Gram Schmidt procedure for Orthonormalization.

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#2: GRAM-SCHMIDT
ORTHONORMALIZATION

$U = \{ \bar{u}_1, \bar{u}_2, \dots, \bar{u}_n \}$.

Given set of Linearly independent vectors.

Creates "orthonormal" set of vectors that span the same subspace.

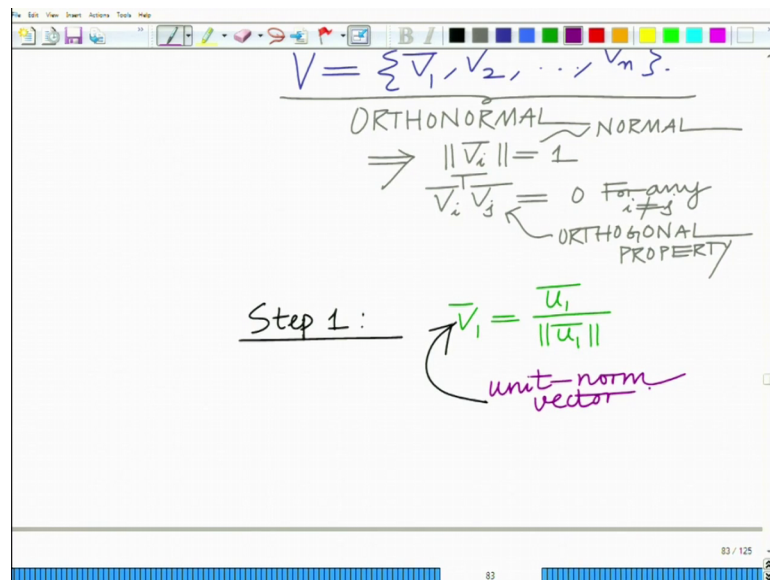
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And what this does is for a given set of linearly independent vectors; $\bar{u}_1, \bar{u}_2, \dots, \bar{u}_n$. So, this is a set of linearly given set of linearly independent vectors. What the Gram Schmidt Orthonormalization procedure does; is it creates an orthonormal set creates, I am just going to explain in a moment what this means it is it creates an orthonormal set of vectors that span the same surfaces span the same subspace in the sense that; linear combinations of this vectors can be used to generate any vector in that subspace all right.

So, both these subspaces spared by these sets are the same. And what is the meaning of this term orthonormal? An orthonormal set of vectors is a set in which each vectors has unit norm that is, the normal right. We said the process of making the norm of vector unity is normalization. And orthogonal represents the fact that the vectors in this set all the vectors in this set are pair wise orthogonal to each other.

So, that makes it an orthonormal set of vectors.

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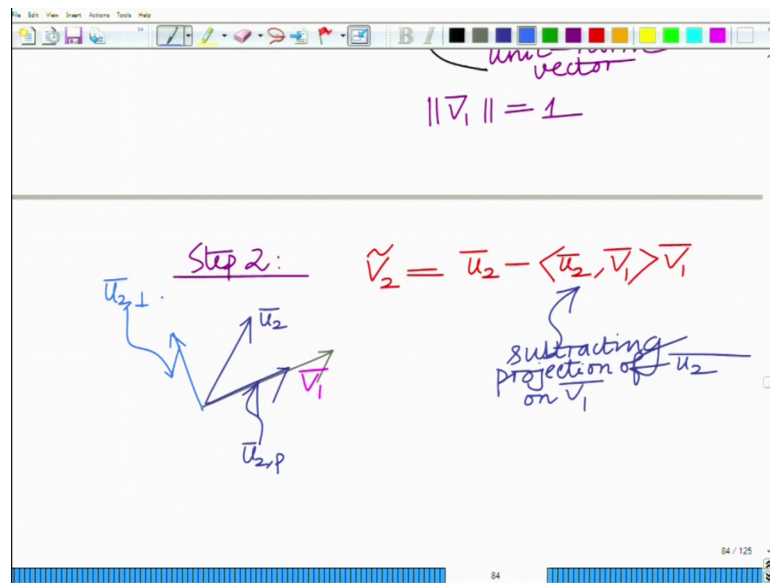


So, we have an orthonormal bases, which is frequently very convenient to consider for as the basis of a vectors space. So, v_1, v_2, \dots, v_n . Now this is orthonormal implies; norm v_i each vector norm v_i equals to 1 this is basically your normal property. And if you look at any pairs of vectors v_i or the real vectors v_i transpose, v_j equal to 0 if i not equal to j , for any i not equal to j all right. And this basically represents the orthogonal property.

So, they are orthonormal in the sense; all the vectors in the set are orthogonal to each other and each vector has unit norm all right and they span the same subspace. So, how does this procedure work? Well the procedure works a various steps the Gram Schmidt Orthonormalization procedure and that can be described as the follows ok.

So, what we do is; we start with the first vector is the first step. You can think of this as step one, what we do is we create a unit norm vector that is; we create first v_1 equals well u_1 divide. So, in each step we create a set of orthonormal vectors. So, the first step is we create a vector v_1 equals u_1 divided by norm u_1 . So, you can observe that this is unit norm because in fact, what we are doing is we are normalizing vector u_1 by it is norm so this is unit norm ok.

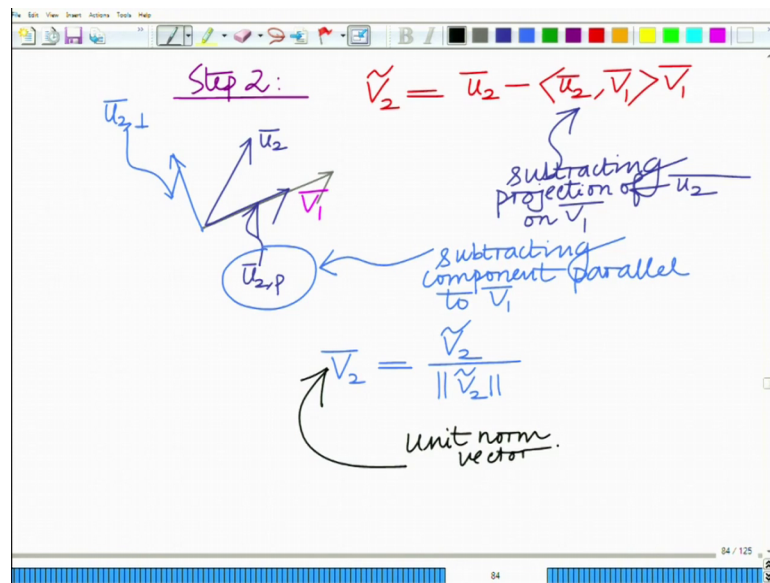
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So, that implies norm v_1 equals one so far satisfies the criterion for Gram Schmidt Orthonormalization. Now in step 2 what we do is; we want to create a vector that is orthogonal to v_1 remember. So, we look at v_2 equals u_2 minus, what we do is we will subtract the projection of u_2 on v_1 that is what we are doing.

And so what we are doing here is we are subtracting projection of u_2 on v_1 that is we have these 2 vectors remember, let us say this is v_1 and now you have this vector u_2 and this can be represented as the sum of 2 components, one is the projection, which we can term as the parallel component $u_{2,p}$ the parallel component. You can write as $u_{2,p}$ and the other is the perpendicular component and this can be written as $u_{2,\perp}$.

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So, what we are doing is, we are subtracting this component along V_1 ; to create something that is parallel to V_1 bar. So, subtracting and retaining whatever is perpendicular to V_1 , but that creates basically to the orthogonality property ok. And that is what the Gram Schmidt Orthonormalization procedure is achieving and of course, now we have to ensure unit norm. So now, V_2 bar equals V_2 tilde divided by norm of V_2 tilde, and this makes it unit norm.

And you can see orthogonality as follows consider just a quick demonstration of orthogonality.

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Unit norm vector

$$\begin{aligned} & \vec{v}_2^T \cdot \vec{v}_1 \\ &= \frac{\tilde{v}_2^T}{\|\tilde{v}_2\|} \cdot \vec{v}_1 \\ &= \frac{1}{\|\tilde{v}_2\|} \cdot (\vec{u}_2^T - \langle \vec{u}_2, \vec{v}_1 \rangle \cdot \vec{v}_1^T) \cdot \vec{v}_1 \end{aligned}$$

Consider \vec{v}_2 bar we have already seen \vec{v}_2 bar is unit norm \vec{v}_2 bar transpose is \vec{v}_1 bar equals \tilde{v}_2 bar transpose divided by norm \tilde{v}_2 bar times \vec{v}_1 bar, because \vec{v}_2 bar equals \tilde{v}_2 bar divided by norm \tilde{v}_2 bar something that we have already just seen.

Now, this is 1 over norm \tilde{v}_2 bar times, well \tilde{v}_2 bar is nothing but what we have seen. \tilde{v}_2 bar transpose is well as we just seen that is \vec{u}_2 bar transpose minus \vec{u}_2 bar transpose times \vec{v}_1 bar inner product into \vec{v}_1 bar transpose times \vec{v}_1 bar.

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$$\begin{aligned} &= \frac{\tilde{v}_2^T}{\|\tilde{v}_2\|} \cdot \vec{v}_1 \\ &= \frac{1}{\|\tilde{v}_2\|} \cdot (\vec{u}_2^T - \langle \vec{u}_2, \vec{v}_1 \rangle \cdot \vec{v}_1^T) \cdot \vec{v}_1 \\ &= \frac{1}{\|\tilde{v}_2\|} (\langle \vec{u}_2, \vec{v}_1 \rangle - \langle \vec{u}_2, \vec{v}_1 \rangle \underbrace{\|\vec{v}_1\|^2}_{=1}) \\ &= \frac{1}{\|\tilde{v}_2\|} (\langle \vec{u}_2, \vec{v}_1 \rangle - \langle \vec{u}_2, \vec{v}_1 \rangle) \\ &= 0 \Rightarrow \vec{v}_1 \text{ orthogonal to } \vec{v}_2 \\ &\quad \vec{v}_1 \perp \vec{v}_2 \end{aligned}$$

Now, if you expand this what you obtain is; this is known of \tilde{v}_2 times u_2 bar transpose. \tilde{v}_1 bar that is the inner product of u_2 bar comma \tilde{v}_1 bar minus the inner product of u_2 bar comma \tilde{v}_1 bar times \tilde{v}_1 bar transpose \tilde{v}_1 bar is norm \tilde{v}_1 bar square, but this is nothing but this is equal to 1. Since this is equal to 1 over norm \tilde{v}_2 times u_2 bar \tilde{v}_1 bar minus u_2 bar \tilde{v}_1 bar, which you can now see is basically nothing but is equal to 0 implies; \tilde{v}_1 bar orthogonal to \tilde{v}_2 bar.

And this can also be represented as \tilde{v}_1 bar perpendicular to \tilde{v}_2 bar, because remember we said the cosine of the angle between these 2 vectors is related to the inner product. If the inner product is 0 angle, which means the cosine of the angle is 0 all right, which means the angle is theta is 90 degrees and therefore, the vectors are perpendicular to each other ok.

And now so, basically now we have created \tilde{v}_1 bar \tilde{v}_2 bar. So, basically at every step we are creating a set of orthonormal vectors. Now expect 3 you can clearly see how we can generate.

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The image shows a whiteboard with handwritten mathematical notes. At the top, it states $= 0 \Rightarrow \tilde{v}_1$ orthogonal to \tilde{v}_2 , which is also written as $\tilde{v}_1 \perp \tilde{v}_2$. Below this, it says "Step 3:" and shows the formula for the unnormalized vector $\tilde{v}_3 = u_3 - \langle u_3, \tilde{v}_1 \rangle \tilde{v}_1 - \langle u_3, \tilde{v}_2 \rangle \tilde{v}_2$. A green arrow points from the text "Projections on \tilde{v}_1, \tilde{v}_2 " to the subtracted terms. Another green arrow points from the text "creates unit Norm vector" to the normalization formula $v_3 = \frac{\tilde{v}_3}{\|\tilde{v}_3\|}$. The whiteboard also has a toolbar at the top and a page number "86 / 125" at the bottom right.

We have \tilde{v}_3 equals well u_3 bar minus, remove the projection of u_3 bar on \tilde{v}_1 bar minus, remove the projection of u_3 bar on \tilde{v}_2 bar. So, this inner product is basically giving the projection of the unit norm vector. Inner product with the unit norm vector just the projection ok. So, these are basically projections on \tilde{v}_1 bar comma \tilde{v}_2 bar and these

are being subtracted. And now we create a unit norm vector by \tilde{v}_3 equals v_3 tilde divided by norm v_3 tilde.

So, what this does is this creates a unit this creates a unit norm vector ok. And now you can quickly check quickly check the orthogonality property once again.

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$$\begin{aligned} \tilde{v}_3^T \tilde{v}_2 &= \frac{1}{\|\tilde{v}_3\|} \cdot \tilde{v}_3^T \tilde{v}_2 \\ &= \frac{1}{\|\tilde{v}_3\|} \left(\tilde{u}_3^T - \langle \tilde{u}_3, \tilde{v}_1 \rangle \cdot \tilde{v}_1^T - \langle \tilde{u}_3, \tilde{v}_2 \rangle \tilde{v}_2^T \right) \cdot \tilde{v}_2 \\ &= \frac{1}{\|\tilde{v}_3\|} \left(\langle \tilde{u}_3, \tilde{v}_2 \rangle - \langle \tilde{u}_3, \tilde{v}_1 \rangle \times 0 - \langle \tilde{u}_3, \tilde{v}_2 \rangle \|\tilde{v}_2\|^2 \right) \end{aligned}$$

$\tilde{v}_1^T \tilde{v}_2 = 0$

If you do \tilde{v}_3 transpose \tilde{v}_1 let us say; or \tilde{v}_3 transpose \tilde{v}_2 just to make sure it is orthogonal to the previous vector. So, I have 1 over norm \tilde{v}_3 \tilde{v}_3 transpose \tilde{v}_2 . This is 1 over \tilde{v}_3 norm times \tilde{u}_3 minus \tilde{u}_3 inner product \tilde{v}_1 \tilde{v}_1 transpose, of course this is all \tilde{v} transpose because we have to take the transpose minus \tilde{u}_3 comma \tilde{v}_2 into \tilde{v}_2 transpose whole times \tilde{v}_2 .

And now you can see; this will be 1 over norm \tilde{v}_3 \tilde{u}_3 transpose \tilde{v}_2 because \tilde{u}_3 \tilde{v}_2 inner product minus \tilde{u}_3 \tilde{v}_1 inner product into \tilde{v}_1 transpose \tilde{v}_2 equals 0 ok. Observe the \tilde{v}_1 transpose \tilde{v}_2 equal to 0 ok, into 0 minus \tilde{u}_3 inner product \tilde{v}_2 , into \tilde{v}_2 transpose \tilde{v}_2 that is norm \tilde{v}_2 square which is once again 1.

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Handwritten derivation on a whiteboard:

$$= \frac{1}{\|\tilde{v}_3\|} \left(\langle u_3, v_2 \rangle - \langle u_3, v_2 \rangle \right)$$

$$= 0$$

$\Rightarrow \underline{v_1, v_2, v_3}$
 = orthonormal set
 Procedure can be similarly continued.

So, this is basically again norm 1 over, norm \tilde{v}_3 over $\langle u_3, v_2 \rangle - \langle u_3, v_2 \rangle$ is equal to 0, this quantity is 0. So, this implies and even similarly verify orthogonality of \tilde{v}_3 to v_1 as well. So, this implies v_1, v_2, v_3 is an orthonormal set and this procedure can similarly be continued.

So, we have v_1, v_2, v_3 this is a orthonormal set, and the procedure can be similarly continued.

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Handwritten derivation on a whiteboard:

Step n:

$$\tilde{v}_n = u_n - \langle u_n, v_1 \rangle v_1 - \langle u_n, v_2 \rangle v_2 - \dots - \langle u_n, v_{n-1} \rangle v_{n-1}$$

$$v_n = \frac{\tilde{v}_n}{\|\tilde{v}_n\|}$$

And what we do in step n ; if you look at the n th step correct in step n , what we do is we have \tilde{v}_n this will be \bar{u}_n minus \bar{u}_1 bar into \bar{v}_1 bar minus projection of \bar{u}_1 bar on \bar{v}_2 bar remove that \bar{v}_2 bar minus so on so forth.

Last one is you remove the projection along \bar{v}_{n-1} ; I remove the projection along \bar{v}_{n-1} bar ok. And finally, we have \bar{v}_n bar \tilde{v}_n divided by norm \tilde{v}_n ok, and this generates the unit norm. Remember the orthogonality property is not affected by the norm. So, all we have to do is take the vector and simply divide by its magnitude to get the divide by the norm to get the corresponding unit norm vector. That basically summarizes the Gram Schmidt Orthonormalization procedure.

Let us look at a specific instance of this procedure application of this procedure considering a set of vectors to demonstrate how this procedure actually works in practice. So, this is to think of this is an example inside an example.

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Illustration:
 Consider
 $\bar{u}_1 = \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$, $\bar{u}_2 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$, $\bar{u}_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$

$$\bar{v}_1 = \frac{\bar{u}_1}{\|\bar{u}_1\|}$$

You can think of this as an illustration a practical illustration of the Gram Schmidt Orthonormalization Procedure.

So, consider 3 vectors that is, \bar{u}_1 that is, the vector 1 1 minus 2, \bar{u}_2 bar equals the vector 1 2 minus 3 and \bar{u}_3 bar equals the vector 0 1 1. And now we have \bar{v}_1 bar equals \bar{u}_1 bar divided by norm \bar{u}_1 bar.

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The image shows a whiteboard with handwritten mathematical work. At the top, there is a toolbar with various drawing tools. The main content is as follows:

Step 1: $\vec{v}_1 = \frac{\vec{u}_1}{\|\vec{u}_1\|}$ $\|\vec{u}_1\| = \sqrt{1+1+4} = \sqrt{6}$.

$\vec{v}_1 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$

unit-norm vector

Step 2: $\tilde{v}_2 = \vec{u}_2 - \langle \vec{u}_2, \vec{v}_1 \rangle \vec{v}_1$

$= \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$

At the bottom right of the whiteboard, there is a small text "89 / 125".

Now observe that norm \vec{u}_1 equals square root of well one square plus 1 square plus 2 square equals square root of 6. So, this \vec{v}_1 equals 1 over square root of 6 times 1 1 minus 2. So, this is your unit norm vector ok.

Observe that this is a unit norm vector, this is the first step. Step one we do not remove any projection because there is no vector in the set V yet ok. Remember we have to remove the projections on the previously chosen vectors \vec{v}_1 \vec{v}_2 \vec{v}_{n-1} at step $n-1$. So, step 2 onwards we remove the projection, so that is \tilde{v}_2 equals your \vec{u}_2 minus the projection of \vec{u}_2 on \vec{v}_1 , which is given by this inner product since \vec{v}_1 is a unit norm vector.

And this is basically 1 2 so \vec{u}_2 is 1 2 minus 3 the vector 1 2 minus 3 minus.

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$$\begin{aligned} \text{Step 2: } \tilde{v}_2 &= \bar{u}_2 - \langle \bar{u}_2, \bar{v}_1 \rangle \bar{v}_1 \\ &= \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \frac{9}{\sqrt{6}} \cdot \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} \\ &= \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 0 \end{bmatrix} \quad \|\tilde{v}_2\| = \sqrt{\frac{1}{4} + \frac{1}{4} + 0} \\ &= \frac{1}{\sqrt{2}} \end{aligned}$$
$$\bar{v}_2 = \frac{\tilde{v}_2}{\|\tilde{v}_2\|} = \sqrt{2} \cdot \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 0 \end{bmatrix}$$

You can check the inner product $\bar{u}_2^T \bar{v}_1$ is 9 over square root of 6 times 1 over square root of 6 into $1 \cdot 1$ minus 2 . And this will basically be so \tilde{v}_2 is minus half half comma 0 . And norm of \tilde{v}_2 is square root of 1 by 4 plus 1 by 4 plus 0 that is square root of half that is 1 over root 2 .

So, \bar{v}_2 equals \tilde{v}_2 divided by norm of \tilde{v}_2 . This is basically you are 1 over 1 over square root of 2 , so square root of 2 times minus half half 0 taking the fact of half outside this becomes 1 over square root of 2 times minus $1 \cdot 1 \cdot 0$.

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$$\begin{aligned} &= \frac{1}{\sqrt{2}} \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 0 \end{bmatrix} \\ \bar{v}_2^T \cdot \bar{v}_1 &= \frac{1}{\sqrt{2}} \cdot [-1 \ 1 \ 0] \\ &\quad \times \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} \\ &= \frac{1}{\sqrt{2}} \times 0 = 0. \end{aligned}$$

$\bar{v}_2 \perp \bar{v}_1$
 \bar{v}_2, \bar{v}_1 are orthogonal.

And you can clearly see this is a unit norm vector and you can also see this will be orthogonal to \bar{v}_1 . So, $\bar{v}_2^T \bar{v}_1$ is well $\frac{1}{\sqrt{2}}$ minus $\frac{1}{\sqrt{2}}$ which is 0. And you can clearly see this is 0 plus 0 which is 0.

So, $\frac{1}{\sqrt{2}}$ times 0 so this is 0. So, implies these are orthogonal that is, \bar{v}_2 perpendicular to \bar{v}_1 or the same thing as saying $\bar{v}_2^T \bar{v}_1$ or orthogonal. So, that completes your step 2, plus remove the projection of \bar{v}_1 from \bar{u}_2 and then divide by its norm that is, you obtain \tilde{v}_2 divide by the norm of \tilde{v}_2 to obtain the orthonormal vector alright. And \bar{v}_2 you can see is also orthogonal to \bar{v}_1 therefore, it makes it an orthonormal sector.

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\bar{v}_2, \bar{v}_1 are orthogonal.

Step 3:
$$\begin{aligned} \bar{u}_3 - \langle \bar{u}_3, \bar{v}_1 \rangle \bar{v}_1 \\ - \langle \bar{u}_3, \bar{v}_2 \rangle \bar{v}_2 \\ = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \left(\frac{1}{\sqrt{6}}\right)\left(\frac{1}{\sqrt{6}}\right) \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \\ - \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \end{aligned}$$

Now, step 3 is again similar very similar. So, \bar{u}_3 minus \bar{u}_3 bar projection along \bar{v}_1 bar into \bar{v}_1 bar minus \bar{u}_3 bar \bar{v}_2 bar inner product \bar{v}_2 bar, and this will be; you can check this is \bar{u}_3 bar is you have seen this is given $\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$, this is the vector $\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ minus the project the inner product is $\frac{1}{\sqrt{6}}$ times $\frac{1}{\sqrt{6}}$ times $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$, that is your \bar{v}_1 bar minus $\frac{1}{\sqrt{2}}$ times $\frac{1}{\sqrt{2}}$ times $\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$ all right.

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The image shows a whiteboard with handwritten mathematical work. The top part shows the calculation of a vector \tilde{v}_3 as a linear combination of three vectors:

$$= \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \frac{1}{6} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

The next line shows the result of this calculation:

$$\tilde{v}_3 = \begin{bmatrix} \frac{2}{3} \\ \frac{2}{3} \\ \frac{2}{3} \end{bmatrix} = \frac{2}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

The bottom part shows the calculation of the norm of \tilde{v}_3 :

$$\|\tilde{v}_3\| = \sqrt{\frac{4}{9} + \frac{4}{9} + \frac{4}{9}}$$

$$= \frac{2}{3} \sqrt{3}$$

Finally, the normalized vector v_3 is calculated:

$$v_3 = \frac{\tilde{v}_3}{\|\tilde{v}_3\|} = \frac{2}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \times \frac{1}{\frac{2}{3} \sqrt{3}}$$

The whiteboard interface includes a toolbar at the top with various drawing tools and a status bar at the bottom showing '92 / 125'.

So, and that will be basically if you can simplify this this will be 0 1 1 plus 1 over 6 1 1 minus 2 minus 1 over 2 minus 1 1 0. So, this will be 0 plus 1 by 6 so if you look at this 0 plus 1 by 6 that is half, so half plus 1 by 6 half plus 1 by 6 that is 4 by 6. So, this will 2 by 3, you can also check second entry will also be 2 by 3 and third entry will also be 2 by 3, so that is 2 by 3 into 1 1 1.

And norm and this is basically your V_3 tilde ok. And norm of V_3 tilde you can also compute that very easily, that is square root of well that will be 4 by 9 into 3 4 by 9 plus 4 by 9 plus 4 by 9; that will be 2 by 3 square root of 3. And therefore, finally, V_3 bar equals V_3 tilde divided by norm V_3 tilde equals well 2 by 3 1 1 1 divided by the norm into 1 over 2 by 3 square root of 3 and that will be equal to well 1 over square root of 3 times 1 1 1.

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Handwritten derivation on a whiteboard:

$$= \frac{2}{3} \sqrt{3}$$

$$\vec{v}_3 = \frac{\tilde{\vec{v}}_3}{\|\tilde{\vec{v}}_3\|} = \frac{2}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \times \frac{1}{\frac{2}{3}\sqrt{3}}$$

$$= \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\vec{v}_1 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}, \vec{v}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \vec{v}_3 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

↑
orthonormal set of vectors ✓

So, finally, we have the orthonormal set of vectors, which has the same span space as $\vec{u}_1, \vec{u}_2, \vec{u}_3$ remind you. So, this is $\frac{1}{\sqrt{6}}$, $\frac{1}{\sqrt{2}}$, $\frac{1}{\sqrt{3}}$ equals $\frac{1}{\sqrt{2}}$, apologize $\frac{1}{\sqrt{2}}$ minus $\frac{1}{\sqrt{2}}$ and \vec{v}_3 equals $\frac{1}{\sqrt{3}}$, and this is $\frac{1}{\sqrt{3}}$. This is 0 orthonormal set of vectors ✓ ok.

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Handwritten derivation on a whiteboard:

$$\vec{v}_1 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}, \vec{v}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \vec{v}_3 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

↑
orthonormal set of vectors ✓

$$\vec{v}_3^T \cdot \vec{v}_1 = \frac{1}{\sqrt{3}} [1 \ 1 \ 1] \times \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$$

$$= \frac{1+1-2}{\sqrt{18}} = 0$$

And you can once again check if you do $\vec{v}_3^T \cdot \vec{v}_1$, let us do a quick check that would be; $\vec{v}_3^T \cdot \vec{v}_1$. So, that would be well $\frac{1}{\sqrt{3}}$

times $\frac{1}{\sqrt{6}}$ the rho vectors times $\frac{1}{\sqrt{6}}$ minus 2, which is basically one plus 1 minus 2 divided by square root of 18 and you can see this is equal to 0.

And therefore, $v_1 \cdot v_2 = 0$ and you can similarly check for the inner product of v_2 or $v_3 \cdot v_2$ that in fact, you can readily see that they are also orthogonal therefore, $v_1 \cdot v_2 \cdot v_3$ is an orthonormal set. And remember the important thing about this is the span the same subspace as the original vector $u_1 \cdot u_2 \cdot u_3$.

So, that is the connection between this set, the new set V and the old set u . And in several times it is very convenient to represent to find out an orthonormal span. So, although both the given sets has the same subspace, it is very convenient to deal with V rather than u because V is an orthonormal set of vectors that spans the same subspace. And in fact, this can be used to not only find the orthonormal span for the vector subspace remember this can be used for any inner product space all right and we have already said that the set of functions, so and so continuous functions forms an inner product space continuous functions on the interval a and b .

So, given a set of basis functions linearly dependent functions on that right? Which spans subspace on that one can similarly determine an orthonormal set of functions, that is functions with an orthogonal to each other and have unit norm and that span the same subspace of continuous functions on the interval ab .

So, this Gram Schmidt Orthonormalization procedure is something that is very convenient, very handy and it is very popular or it is highly applicable a practice because of it is first, because it is a low complexity procedure and 2, it has immense utility in terms of simplifying, either be it either deriving the span of a subspace or the representation of a set of or representation of a new vector, to represent it in a this subspace can be much readily derived or much more easily derived using the orthonormal span for the same subspace. So, we will stop here and we will continue with other aspects in the subsequent modules.

Thank you very much.