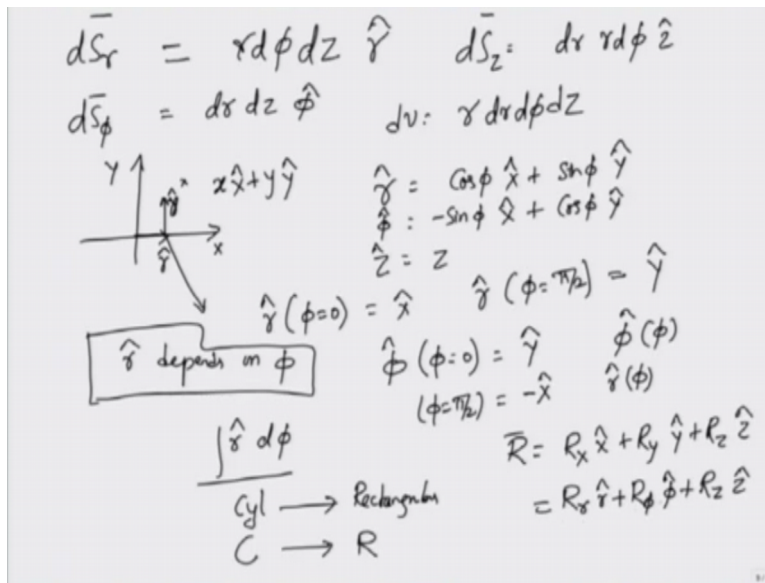


Electromagnetic Theory
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Lecture - 09
Transformation & Electric Field-II

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Suppose that vector is \vec{R} and I can write this vector \vec{R} as consisting of 3 vectors R_x , I can resolve this vector \vec{R} as $R_x \hat{x} + R_y \hat{y} + R_z \hat{z}$. The same vector in the cylindrical co-ordinate system can also be written as $R_r \hat{r} + R_\phi \hat{\phi} + R_z \hat{z}$. The same vector in the cylindrical co-ordinate system can also be written as $R_r \hat{r} + R_\phi \hat{\phi} + R_z \hat{z}$ where R_r will be the component of the vector \vec{R} along \hat{r} vector along the radial component plus $R_\phi \hat{\phi}$ plus $R_z \hat{z}$.

You can guess from intuition that R_z will be equal to R_z in both cases and you will be right. However, we are now interested in R_x , R_y , R_r and R_ϕ .

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$$\begin{aligned} \vec{R} &= R_x \hat{x} + R_y \hat{y} + R_z \hat{z} = R_r \hat{r} + R_\phi \hat{\phi} + R_z \hat{z} \\ \vec{R} \cdot \hat{x} &= R_x = R_r \hat{r} \cdot \hat{x} + R_\phi \hat{\phi} \cdot \hat{x} + \underbrace{R_z \hat{z} \cdot \hat{x}}_{=0} \\ \hat{x} \cdot \hat{x} &= 1 & R_x &= \cos\phi R_r - \sin\phi R_\phi + 0 R_z \\ \hat{x} \cdot \hat{y} &= 0 & R_y &= \sin\phi R_r + \cos\phi R_\phi + 0 R_z \\ \hat{x} \cdot \hat{z} &= 0 & R_z &= 0 R_r + 0 R_\phi + 1 R_z \end{aligned}$$

$$\begin{pmatrix} R_x \\ R_y \\ R_z \end{pmatrix} = \begin{pmatrix} \cos\phi & -\sin\phi & 0 \\ \sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} R_r \\ R_\phi \\ R_z \end{pmatrix} \quad T_{R-C} = \begin{pmatrix} \cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Exercise

So I know that R is equal to $R_x \hat{x}$ plus $R_y \hat{y}$ plus $R_z \hat{z}$. This is also equal to $R_r \hat{r}$ plus $R_\phi \hat{\phi}$ plus $R_z \hat{z}$. Now if I try to find out the component of the R vector along the \hat{x} vector that is along the x axis, I would be obtaining, I can do that 1, by finding out the dot product of \vec{R} along \hat{x} . So if I do this I am going to get the component of R along \hat{x} , correct? So if I do this operation I am going to get R_x . Why?

What would happen when you take \hat{x} dot with respect to this 1. it stands out that, $\hat{x} \cdot \hat{x}$ will be equal to 1 because the length of 1 vector upon itself will be giving the length of the vector itself. However, what happened to $\hat{x} \cdot \hat{y}$. This became equal to 0 because \hat{x} is perpendicular to \hat{y} and dot product will be equal to 0 when theta is equal to 90 degrees, right?

So this is another definition of perpendicularity or normality or orthogonality. Two vectors are said to be perpendicular to each other or normal to each other or orthogonal to each other when the dot product between the two vanishes. Similarly, $\hat{x} \cdot \hat{z}$ will also be equal to 0. In fact, the corresponding vectors \hat{x} , \hat{y} and \hat{z} they form mutually perpendicular set of vector, something that we looked at in the last class.

$\vec{R} \cdot \hat{x}$ will give you the R_x component. Now I have to dot this R vector in the cylindrical co-ordinate by the \hat{x} vector, right? So if I do that 1, this would also be equal to $R_r \hat{r} \cdot \hat{x}$ plus $R_\phi \hat{\phi} \cdot \hat{x}$ plus $R_z \hat{z} \cdot \hat{x}$. This component is equal to 0 or this value is equal to 0. So R_x will be equal to, what is $\vec{R} \cdot \hat{x}$, this is nothing but $\cos\phi$.

So have $\cos \phi R_r$ and what about $\phi \cdot x$, in the previous slide we have already seen that this is equal to $-\sin \phi R_\phi$, so therefore this is $-\sin \phi$ multiply this 1 by R_ϕ . What will be R_y , you can show similarly by considering the dot product of R with y . This will be equal to $\sin \phi R_r$ plus $\cos \phi R_\phi$ plus 0 times R_z plus 0 times R_z just to complete the equations.

I can also write down R_z as 0 times R_r plus 0 times R_ϕ plus 1 time R_z , okay? Now this might be looking very suspiciously like a set of linear equations and these are the set of linear equations and these are the set of linear equations. We can obtain R_x , R_y and R_z , if I know the component value of R_r , R_ϕ and R_z by a transformation matrix which takes me from cylindrical to rectangular co-ordinate systems.

This is the cylindrical to rectangular co-ordinate system and the matrix is $\cos \phi$ minus $\sin \phi$ 0, $\sin \phi$ $\cos \phi$ 0 1 0 and 0, this is a 3 by 3 matrix which transforms any vector which is in the cylindrical co-ordinate system into rectangular co-ordinate system. If you are interested in finding what would be the corresponding transformation from rectangular to cylindrical you can actually show that this transformation is nothing but the inverse of this matrix T_{CR} .

And you can show that this will be equal to $\cos \phi$, $\sin \phi$, 0, there is a 0 here, 1 here, minus $\sin \phi$, $\cos \phi$, 0 and 0, okay? I will leave this as an exercise to you to show this 1. Now these two matrices are very useful to you. In fact, you can take a look at any electromagnetic text book, they are going to give you these kind of formulas which will allow you to convert of vectors in 1 co-ordinate system to another co-ordinate system.

I will give you 1 simple example of conversion, how to do this particular conversion and I will point out 1 very important aspect of cylindrical co-ordinate systems to you. What is that problem?

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$$\begin{aligned} \bar{A} &= A_x \hat{x} + A_y \hat{y} & \bar{A} \text{ in cyl.} & \quad x^2 + y^2 = r^2 \\ A_x &= \frac{x}{x^2 + y^2} & A_y &= \frac{y}{x^2 + y^2} \\ \begin{pmatrix} A_r \\ A_\phi \end{pmatrix} &= \begin{pmatrix} \cos \phi & \sin \phi \\ -\sin \phi & \cos \phi \end{pmatrix} \begin{pmatrix} A_x \\ A_y \end{pmatrix} & \Rightarrow & A_r = \frac{\cos \phi x}{r^2} + \frac{\sin \phi y}{r^2} \\ & & & A_\phi = \frac{-\sin \phi x}{r^2} + \frac{\cos \phi y}{r^2} \\ \bar{A} &= \frac{1}{r^2} \left((x \cos \phi + y \sin \phi) \hat{r} + (y \cos \phi - x \sin \phi) \hat{\phi} \right) \\ \begin{matrix} (x, y) \\ (r, \phi) \end{matrix} & \begin{matrix} x = r \cos \phi \\ y = r \sin \phi \end{matrix} & A_r &= \frac{r \cos^2 \phi + r \sin^2 \phi}{r^2} = \frac{1}{r} \\ & & A_\phi &= \frac{-r \cos \phi \sin \phi + r \sin \phi \cos \phi}{r^2} = 0 \\ \boxed{\bar{A} = \frac{\hat{r}}{r}} & & \text{No!} & \quad \phi = \tan^{-1}\left(\frac{y}{x}\right) \\ & & & \quad A_\phi \phi = \tan^{-1}\left(\frac{A_y}{A_x}\right) \end{aligned}$$

I have a vector A which is described in the rectangular co-ordinate systems having components A_x and A_y , okay? A_x and A_y where A_x is equal to x by x square plus y square, A_y is equal to Y by x square by y square. Now I want you to find out the vector in the cylindrical co-ordinate systems. How do I find the vector in the cylindrical coordinate system? I have to use the formula that I developed earlier. So what is that formula?

I have to use this transformation matrix. I know A_x , A_y , I know A_z . A_z in this case is 0 and then I have to find out A_r , A_ϕ and A_z . Okay, let me proceed to find that 1 out. A_r , A_ϕ will be equal to because there is no z component there, I am not going to write down the z component for you, I mean because there is no point in writing down that 1, this will be equal to $\cos \phi \sin \phi$ minus $\sin \phi \cos \phi$ times A_x , A_y . Hopefully this is alright.

So let us go back to the matrix and check. $\cos \phi$, $\sin \phi$ minus $\sin \phi$ and $\cos \phi$ so we are on the right track. Now substitute for A_x and A_y . If you substitute for A_x and A_y you are going to get A_r will be equal to $\cos \phi$ times A_x and $\sin \phi$ times A_y , but I also know that x square plus y square is actually equal to r square in cylindrical co-ordinate systems and substituting therefore A_x as x by r square and for A_y as y by r square what will be A_r ?

A_r will be equal to $\cos \phi$ x by r square plus $\sin \phi$ y by r square, okay? But what is $x \cos \phi$ and $y \sin \phi$ and what is A_ϕ ? A_ϕ is minus $\sin \phi$ x by r square plus $\cos \phi$ y by r square, okay? Now let us right down the vector in the cylindrical co-ordinate system. This vector in the co-ordinate system will be equal to 1 by r square is a common factor that is coming out everywhere, so I can take that common factor out.

So I have $x \cos \phi + y \sin \phi$ along the radial direction plus $\cos \phi$, $y \cos \phi - x \sin \phi$ along the ϕ direction, okay? But I also know that x is equal to $r \cos \phi$, y is equal to $r \sin \phi$. So I can substitute for x and y in this expression. So if I substitute for that 1, this expression, $x \cos \phi + y \sin \phi$ that is A_r term will become x is equal to $r \cos \phi$, so that becomes $r \cos^2 \phi + r \sin^2 \phi$ plus y is $r \sin \phi$.

Therefore, this becomes $r \sin^2 \phi + r \cos^2 \phi$ which is equal to 1 by r and A_ϕ is equal to $-x \sin \phi + y \cos \phi$ by r square plus y is $r \sin \phi \cos \phi - r \cos \phi \sin \phi$ by r square which is equal to a big 0. So the vector A in cylindrical co-ordinate system is simply given by \hat{r} divided by r . is this surprising to you. If you are not surprised, then you should be surprised.

Why you should be surprised, because in order to represent a point which is originally represented in Cartesian coordinates as x and y or x by $x^2 + y^2$ and y by y^2 , $x^2 + y^2$, we had to give the values of x and y , both the values of x and y . To represent the same point in cylindrical co-ordinate system, I still have to give the values of r and ϕ .

I have to tell you what distance that particular point is located and what is the angle with respect to the x axis that I have to locate that point on. If I do not give you r and ϕ you will not be able to pin point that this point in the cylindrical co-ordinates will correspond to the same point in the rectangular co-ordinates, right? There are an infinite number of choices. Yet, my vector A which was originally $A_x \hat{x} + A_y \hat{y}$ is actually giving me component only along r .

There is no mention of ϕ component. The ϕ component is 0 in this case. Z of course is also 0 in this case. Does it really mean that if $\hat{\phi}$ is equal to 0 or if A_ϕ is equal to 0, that is any ϕ component is equal to 0, does this imply that ϕ is equal to 0? No. ϕ is not 0, just because there is no ϕ component it does not mean that the ϕ component is also equal to 0, in fact the ϕ component is given by $\tan^{-1}(y/x)$.

If you know what is the value of A_x and A_y or this is equivalent of writing this as \tan^{-1} of A_y by A_x , if you know what is A_y and A_x you should be able to find out what is the value of ϕ , similarly you know what is the value of r , or the A_r component, you should be able to find ϕ and you will see that this ϕ will not be 0. So this is a very important step for me to highlight to you.

Just because ϕ is equal to 0 it does not mean that the A_ϕ component is 0, it does not mean that ϕ is also equal to 0. This is not correct. Do not think that A_ϕ component is 0 means ϕ is also equal to 0. But this makes sense physically because after all where is my vector pointing, on this particular radius, let us say this is the point where I had originally in Cartesian co-ordinate system represented as x and y component.

And I had set up a particular vector also. The corresponding vector in the cylindrical co-ordinate would be directed from the origin passing through this particular point, right? This point no doubt is given by r and ϕ values, but the direction of the vector is only along r direction because there is no component of ϕ direction or there is no component of the vector along ϕ direction, okay?

This you keep in mind; it is very important. Now we have seen this result, let us put this result into good use by resolving the same problem of infinite line charge, okay?

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The image shows a handwritten derivation of the electric field \vec{E} for an infinite line charge with linear charge density ρ_L . The derivation is as follows:

- A diagram shows a cylindrical coordinate system with \hat{z} along the vertical axis and \hat{r} in the horizontal plane. A small charge element $\rho_L dz'$ is located at z' on the \hat{z} axis. A point (r, ϕ, z) is shown in the horizontal plane.
- The position vector from the origin to the point is $\vec{r} = r\hat{r} + z\hat{z}$.
- The position vector from the charge element to the point is $\vec{r} - \vec{r}' = r\hat{r} + (z - z')\hat{z}$.
- The distance between the charge element and the point is $(r^2 + (z - z')^2)^{1/2}$.
- The electric field contribution from the charge element is $\frac{\rho_L dz'}{4\pi\epsilon_0} \frac{(r\hat{r} + (z - z')\hat{z})}{(r^2 + (z - z')^2)^{3/2}}$.
- The total electric field is $\vec{E}(r, \phi, z) = \frac{\rho_L}{4\pi\epsilon_0} \int_{-\infty}^{+\infty} \frac{(r\hat{r} + (z - z')\hat{z})}{(r^2 + (z - z')^2)^{3/2}} dz'$.
- The \hat{z} component of the field is shown to be zero due to symmetry.
- The final result is $\vec{E}(r, \phi, z) = \frac{\rho_L}{2\pi\epsilon_0 r} \hat{r}$.

We consider the infinite line charge problem earlier, we are going to revisit the same problem and learn how to use the cylindrical co-ordinate systems. This is sometimes called as circular

cylindrical co-ordinates. It does not really matter. I have again a uniform line charge of line charge density ρ_L kept on the z axis, going all the way from minus infinity to plus infinity. I again consider a line segment at a height of z' from the z is equal to 0 plane, starting from the horizontal plane and I consider a small segment dz' .

The total charge there will be ρ_L multiplied by dz' , okay? Now I have to find out the field at any point in the plane which I am now going to consider any general r, ϕ and z point, okay? I am not looking for z is equal to 0, although you can solve the problem with z is equal to 0. Let me consider any z value and see what happens. You will see that the problem does not become complicated at all. So what is the unit vector for this 1 ?

Okay, what is the unit vector for the field point and what is the unit vector for the source point? The vector for the source point is r', z' , this is at a height of z' and what is the vector for the field point. It turns out that the vector for the field point has no ϕ component. Again remember just because there is no ϕ component it does not mean that ϕ itself is 0. So I have this as r, z .

Again remember, there is no ϕ component, no ϕ component, does not mean ϕ is equal to 0. In fact, ϕ will be non 0. We will later see why ϕ does not enter into picture over here. So what is this vector now from the source the field point, the vector is $r - r'$ which is $r - r'$ along z , okay? Now we use the expression for electric field. We integrate in the appropriate dimensions.

I am looking at the electric field at a particular point r, ϕ, z in the plane. This will be equal to ρ_L by $4\pi\epsilon_0$. I am going to take this constant anyway outside. So I am going to put that constant outside of the integral first. Integral is going along z' direction from minus infinity to plus infinity and inside I have $r - r'$ by magnitude of r' to the power 3, right?

So I have $r - r'$ multiplied by z' divided by r^2 by $z - z'$ to the power 3 by 2 and this entire thing is actually integrated along z' . Now I still have an integral which have this component of 3 by 2, but I know how to solve that integral. But what is the big change I have done. If you see what is the big change what has happened, out of the 3 integrals 1 integral has dropped out.

Now there are only two integrals for me to work around. However here I have to be careful a little bit. Again the integral will be the sum of the integral for r and sum of the integral for z because there is an r hat inside the integral, z hat inside the integral. However, in this particular case, it turns out that at any point on the z axis I might be, r hat does not change or does not depend on z , z also does not depend on z .

We remember that r hat and ϕ hat depend only on ϕ and not on z . They also do not depend on r , so in this case there is no integration of r . So r hat does not depend on z , therefore that also becomes a constant and can easily come out of the integral. So when it comes out of the integral you can use the same ideas that we develop in the last class to solve for this integral in the last class and you can basically show that this integral.

This entire integral will turn out to be ρL by $2\pi\epsilon_0 r$ in the r direction. Okay? So the fields are in the radial direction, radially outward if it is a positive line charge, radially inward if it a negative line charge density. Okay, so I have ρL by $2\pi\epsilon_0 r$, r hat and there is no ϕ component, also the integral for the z component drops out. So this is the electric field at r ϕ and z .

This is completely independent of z , depends only on r and they are only going away along r direction. Let me give you briefly why this particular electric field has come out the way it has come out. See we have chosen a proper co-ordinate system. But what we have not talked about is the symmetry of the problem. Symmetry is a very very very important concept in electromagnetic.

If you look at the textbook that we are using for this course, electromagnetic engineering electromagnetic by Hayt, the way he solves this problem, the infinite line charge problem is that he gives you the first statement of the solution saying that in solving such problems, you have to look for symmetry because symmetry simplifies calculation. There are two things that we have to do which are paramount important.

One is choosing the right co-ordinate system and then exploiting the symmetry. So if you choose the right co-ordinate system in this case, instead of 3 integrals I am now down to two integrals and if I had actually exploited the principle of symmetry, I would not even have

worried about the z component. Let us see, symmetry what does it do. Symmetry asks two kinds of question.

It first says, at any given particular point which way the electric field will be pointing and then it will also ask on what variables, what co-ordinates does this electric field depends on. Imagine that there is no infinite line charge out here and then you are at a particular distance, may be you are in that horizontal plane, you are at a particular distance r and you look around this charge and you move along the ϕ direction.

So imagine yourself moving along the ϕ direction, the line charge is uniformly infinite and the line charge basically does not have any dependence on the ϕ . So as you keep moving along ϕ direction, you will not see any difference in the line charge. So the line charge looks the same no matter what value of ϕ you are in. Therefore, there is clearly no way the electric field is going to depend on ϕ . It does not matter if the line is infinity long or if the line is finitely long.

As long as the line is symmetric with respect to the ϕ axis or the azimuthal direction, there will be no dependence on the ϕ component. Similarly, for an infinite line charge we can move up and down. There will again be no z dependence, because you move up you are going to see the same charge, you move down you are going to see the same charge. You can move up and down and you are going to still see the same uniform line charge.

Therefore, there cannot be any dependence on the z component. The only way you can have your electric field magnitude decrease is if you move away from the charge. So you have the charge and you keep moving away from the charge and you can expect that as you move away from the charge there will be some drop in the magnitude of the electric field. So that is why the electric field is dependent only on the r co-ordinate.

Only along the radial distance from the charge. Suppose you are at a particular point and now you say can there be a ϕ component in the electric field, the answer is no because to have a ϕ component remember electric field is a force, essentially in some sort of a force. You can place the test charge at a point and then see if there is a to be a component along ϕ , there has to be some other charge which has to be giving you the force in the ϕ direction.

There has to be a charge in the phi direction. But we have no such charge, we have only 1 charge and that is along the z axis and that would not give you the phi component. So there is no phi component in the electric field. Can there be a component along the z direction? For an infinite line charge, if I have to say that okay if there is some non 0 z hat direction, it also means that there is a charge somewhere which is giving you a field along z axis, but that is not the case here.

The only electric charge that we have, charge distribution that I have is sitting on the z axis and it is sitting along all the way from minus infinity to plus infinity. If at this distance if this is the charge and therefore this distance I need to have a z component then I need to have a force somewhere over here which is pushing the charge, test charge around in this upward direction or in the downward direction, right, if I have a negative component.

So there is no z component, there is no phi component, there can only be r component. Because for the r component, there is a charge here. It will exert a force up there. So if you had actually exploited all these symmetry you would have concluded that we need not even have perform the integral for the z axis. I did not introduce this for a very specific reason. There is another law which we are going to study very shortly called as Gauss's law.

Gauss's law is specifically meant for exploiting symmetries. The problem that we took for two classes, to solve two classes can actually be solved very easily if you apply Gauss's law and we are going to do that 1 once we get acquainted with that particular law. So for now we are not putting any symmetry arguments, however we are only going to choose the appropriate co-ordinate systems. That is what I have done here.

There are couple of other problems that you might be interested and these are very important as well. At this point I will give them as an exercise and therefore you can work them out and if time permits we will come back to those distributions. I will like to move on from solving these type of charge distribution problems to introduce you to a different concept in our study of electromagnetic and this concept is called potential.