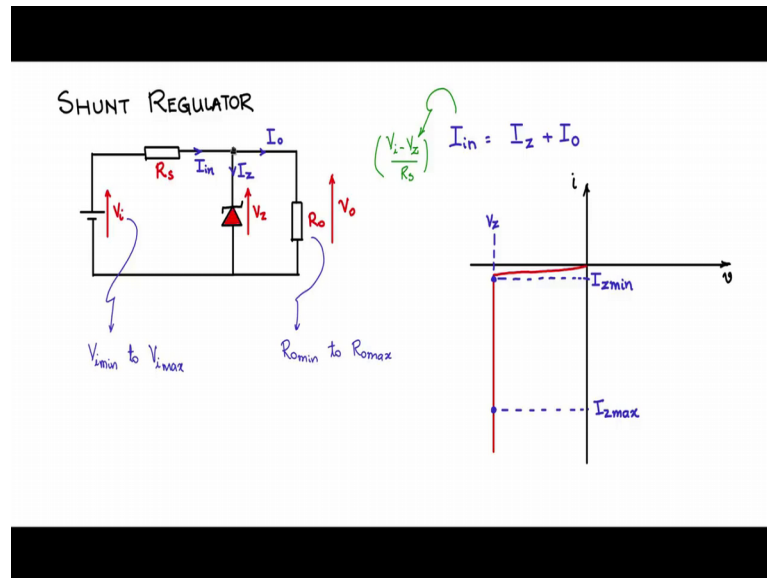


Fundamentals of Power Electronics
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Lecture – 32
Shunt regulator

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Let us now discuss the Shunt regulator circuit. So, let us draw the input unregulated voltage V_i , it contains a series component here and a shunt component here, it is a Zener diode and the load. So, this is the structure of a shunt regulator. The hero of this is this Zener diode. This is V_i , the unregulated V_i , we will call this as R_s , this is V_z and this is the load resistance R_o and you have V_o and V_o is equal to V_z .

So, if I name this as I_s or I_{in} and this is I_z and I_o . So, these are the various parameters in a shunt regulator. How does the regulation happen? Basically, V_z is a reference Zener, the voltage across the Zener is constant and it tries to maintain V_o constant in spite of the fluctuations in V_i or fluctuations in R_o . Let us see how the operation, how the regulation operation functions.

Now, look at the Kirchhoff's current law here at this node. You have I_{in} , I_z , I_o . I_{in} is equal to I_z plus I_o , I_z plus I_o and this is the core equation which performs the regulation. Now, V_i can vary from a $V_{i_{min}}$ value to a $V_{i_{max}}$ value and R_o is not under our control again can vary from $R_{o_{min}}$

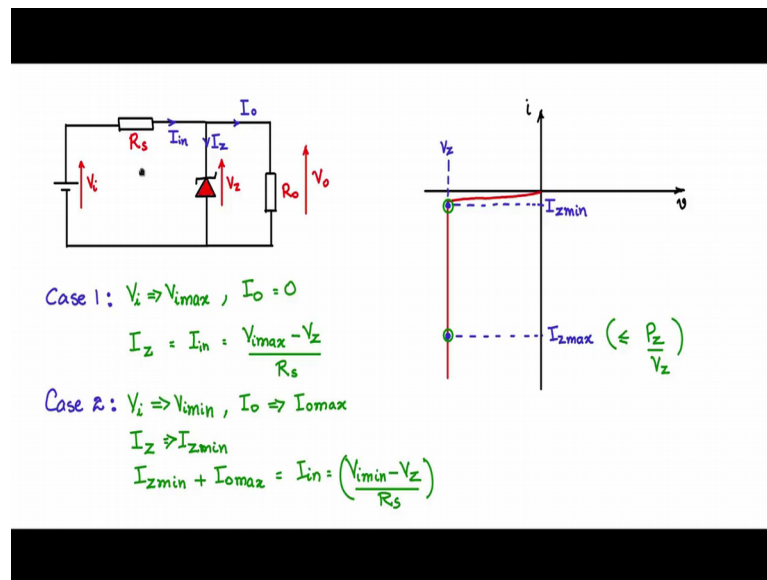
value to R_{naught} max value and as a consequence when R_{naught} is minimum I_{naught} is maximum and R_{naught} is max I_{naught} is minimum.

The operation of the shunt regulator hinges on this device which is the Zener diode. Let us try to understand the characteristics of that Zener diode static characteristics of Zener diode and how it affects the regulation performance here. So, let me draw the $i-v$ characteristics, this is the v , this is the i and let me take only the reverse characteristic the Zener reverse characteristic which will be something like this, where this line intercept will be V_z on the voltage.

So now, this I in here the current is given by V_i minus, this is V_z point this potential here is V_z at this node V_i minus V_z divided by R_s . So, this is the current flows in through here and this current is independent of the value of R_{naught} or value of I_{naught} . So, depending upon the value of R_{naught} there is commutation between I_{naught} and I_z to maintain I in fix to this value.

So, the current through the Zener has flexibility. It can operate from a max value I_z max to a min value I_z min and this in fact, gives you the regulation. If suppose I_{naught} is 0 then the whole of the I in current flows into I_z , so the operating point will be somewhere here. If I_{naught} is a maximum value then I_z will decrease and it will probably be sitting at min value the operating point will be here. So, it is I_z here that actually is adjusting its value. The regulation happens because of the capability of the Zener to take varying currents through it at a constant voltage. The Zener current can vary from I_z min to I_z max depending upon the value of the load.

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Consider now few operational cases. Let us say case 1. Now, here V_i is at its max value $V_{i\max}$ and let us say I_o is 0 which means this is open circuited, then the entire I_{in} current flows through the Zener. So, I_z will be equal to I_{in} because I_o is 0 and that is $V_{i\max} - V_z$ divided by R_s . Now, this is the max value of the current that can flow into the Zener in this circuit. So, it will get, this will be the operating point it will get positioned here and that will be $I_{z\max}$ for the circuit and see to it that it is less than or equal to P_z / V_z , P_z is the Zener power rating.

So, when you go and choose or select a Zener it will have a power rating in the data sheet. So, you will have a 1 watt Zener, you have 400 milli watt Zener. So, whatever that power rating divided by V_z Zener V_z will be the limiting or the max permissible value of I_z . So, this I_z value which you calculate here should be less than that so that the Zener does not blow.

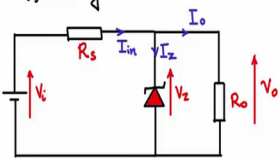
The second case, the second limiting case happens when V_i is $V_{i\min}$ and I_o is maximum, that is when R_{load} is at a minimum value. So, you have I_o max. Under this condition this I_o plus I_z should be equal to I_{in} , there should be at least the minimum value of I_z to pass through the Zener in order that the Zener provides a constant voltage V_z .

So, therefore, $I_{z\min}$ at least should flow through this. So, I_z should be set at $I_{z\min}$ as the operating point. So, we know that $I_{z\min}$ now, plus I_o max should be

equal to I_{in} and I_{in} under this case is $V_i - V_z$ divided by R_s . So, this is another limiting case where the operating point as for the Zener is concerned is here. So, these two limiting cases will actually determine what should be the value of R_s that you have to choose. It will become clear if we work out an example.

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Efficiency



$$\eta = \frac{P_o}{P_i} = \frac{V_o I_o}{V_i I_{in}} = \frac{V_o I_o}{V_i \left(\frac{V_i - V_o}{R_s} \right)}$$

Let $\Delta V_{io} = (V_i - V_o) \Rightarrow$ input-output voltage differential.

$$\eta = \frac{V_o I_o \cdot R_s}{V_i \cdot \Delta V_{io}} = \frac{P_o \cdot R_s}{V_i \cdot \Delta V_{io}}$$

as $\Delta V_{io} \uparrow$, $\eta \downarrow$

Let us now see what is the efficiency of this circuit? Efficiency is defined as the output power divided by the input power P_i , output power which is $V_o I_o$ input power $V_i I_{in}$. So, we can write it down as $V_o I_o$ by $V_i I_{in}$.

Let us express I_{in} in terms of input voltage and output voltage. So, we have $V_o I_o$ by V_i into I_{in} is $V_i - V_o$ by R_s , $V_i - V_o$ by R_s and let us define another term ΔV_{io} which is $V_i - V_o$ it is called the input output voltage differential, $V_i - V_o$ which is the input output voltage differential.

So, now therefore, we can rewrite efficiency as $V_o I_o R_s$ divided by V_i into ΔV_{io} . So, this will be the efficiency relationship. Observe that as ΔV_{io} input output voltage differential increases the efficiency will decrease, which basically means that if I am having a linear shunt regulator let us say with input output differential as some voltage. For example, if I take V_i of 10 volts, V_o of 5 volts input output differential would be 10 minus 5, 5 volts. For the same 5 if I am having V_i of 15 volt then input output differential would be 10. So, the 15 volt input would have a lower efficiency than that 10 volt input linear regulator.

So, V_{naught} I_{naught} is nothing but P_{naught} which is the which can be obtained from this spec, R_s is calculated by design, V_i is given from the input spec, ΔV_{io} is also an input spec and from here we can calculate the efficiency of the circuit. So, the important thing to note here is the input output differential voltage, higher rate is lower the efficiency.