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Lecture - 16 Semantic Analysis with Attribute Grammars Part - 5

(Refer Slide Time: 00:19)

Welcome to part five of the lecture on attribute grammars. We will continue with semantic analysis and attributed translation grammars today as well.

(Refer Slide Time: 00:28)

So, let us start looking at the symbol table structure, which is necessary to perform semantic analysis. So far I only added a few routines to search and insert into the symbol table, and showed you how to do some semantic analysis. But I did not give you a structure for the symbol table and date structure for the symbol table. So, let us do that now, a symbol table stores names of all kinds that occur in a program along with the information about them. So, for example, the type of the name you know whether it is an integer or a floating point number or function, etcetera. The level at which it has been declared. So, it is possible to have blocks in C and in Pascal and you know Algol we can even have procedures and functions embedded within other procedures and functions.

So, the level at which the name has been declared. So, which block you know the level of the block whether it is a declared parameter of a function or it is an ordinary variable all this information must along with the name itself. In the case of a function we also need to access the list of parameters from the function name along with their types of course. And we must also be able to say that these are the set of local variables corresponding to this particular function the result type of the function, etcetera, etcetera. All these must be stored along with the function name in the symbol table.

During semantic analysis of course, we use the symbol table we already know that it is necessary. But we actually perform you know intermediate code generation in which the variables that we use including the temporaries that are necessary will all be installed in the symbol table you know. So, at the end of the intermediate code generation phase we will still have pointers into the symbol table for all the names. Therefore, during the machine independent code optimization phase, it becomes essential to access the symbol table as well. And during machine code generation we definitely need to access the symbol table to find out the type of the name, how much storage is needed for a, what is the format in which must be stored. These are can be these all this can be determined only by looking at the type of that particular name how do we organize the symbol table.

So, it must be organized to enable a search based on the level of declaration this will become clear as we go along. And what are the data structures that can be sued to organize a symbol table. Well if we organize it as a binary search tree then it is fairly straight forward to insert, delete, search this search tree. But then the amount of time needed to search or insert or delete a name is proportional to log n where n is the number of nodes in the tree that is assuming that the binary search tree is also a balanced binary search tree. To get a better you know search time a hash table is quite easy to use. So, we can sue a hash table to store the symbol table, but there may be some issues regarding levels. And one must organize the hash table carefully if you want to you know search based on levels, a simple array that is always possible a link list is also possible.

(Refer Slide Time: 04:38)

So, let us look at a simple structure to store a symbol table. So, we will our data structure will be a very simple data structure. And it is going to be quite restricted and not really very fast the reason is the description of a complex symbol table. You known is actually an unrelated topic any complicated data structure may be suitable for a symbol table. And it does not add value to the semantic analysis or other compiler functions as far as the lecture goes.

So, we will use a simple symbol table and then I will leave it to the students to understand how to use more complicated symbol tables. We will have it as an array called as the function name table and this table stores the function name records. Assuming that there are no nested function definitions of there are nested function definitions. Then the table can be changed its possible to do that I will show you how to do it little later each function name record has fields, it has name it has result type parameter list pointer and variable list pointer.

(Refer Slide Time: 06:02)

So, let me show you a picture. So, the function name table is a simple array or a table. So, with several fields name result type parameter list pointer you know local variable list pointer and then the number of parameters. So, each function name record you know has fields. So, and then the parameter and variable names are stored as lists. So, I showed you the pointer to these lists. So, why should we store these as lists? So, for example, we want to access all the parameters possibly together and similarly we may want to search only variable names and not get mixed up with parameters and so on.

So, it is for this reason the order in which the parameters are stored is also very important for us while checking the declaration and the call. So, each parameters and variable name record has many fields. So, it has name it has type it has parameter or variable tag and the level of declaration. So, the level is set as one for the parameters and two or more for the variables. So, this is how a parameter variable name record looks like there is name type a tag and then level of declaration.

(Refer Slide Time: 07:28)

Suppose the, let me not describe the procedure for searching and inserting names etcetera. Suppose there are two variables in the same function, with the same name, but declaration levels. These are; obviously, treated as different variables in the respective scopes this is governed by the language specification itself and the implementation will also support it. If your variable at level greater than two and a parameter have the same name then the variable name overwrites the parameter name. So, only within the corresponding scope this is very important, but let me read the next point. And then let us see what the implications are; however, a declaration of a variable at level two with the same name as a parameter is flagged as an error.

So, that implication is at the level just after the parameter declaration if you have a name which is the same as that of a parameter then it is an error. But if you declare it an interior level a name which is the same as that of a parameter then the local name which is declared in the block overwrites the parameter name. So, these cases must be checked very carefully and we will see how to do that. And whenever we search a symbol table for a given name then you know suppose we start at level L. The name has been used at level L then we must search the name in the symbol table at level L and if it is not found then at level minus one etcetera, till level 2 in that order where L is the current level. So, if you find the name at level L itself and that is the declaration which is taken as relevant to us. Otherwise whenever we as soon as we hit a declaration which is the, which satisfies our requirement we take that as the relevant declaration.

(Refer Slide Time: 09:48)

So, let me show you how the symbol table looks like for a small sample program here there is a function f 1. And there is another function f 2, f 2 does not return any result whereas, f 1 returns an integer result f 1 has 2 parameters P 1 and P 2 the first one is of type floating point the other one is of type integer. So, whereas, f 2 it does not have any parameters either. So, let us look at the name function name record in the function name table. So, the name of the function is f 1 it is it returns a result of type int whereas, f 2 returns a result which is y void and then the name the function f 1 has a parameter list.

So, the parameter list points to a link list containing P 1 and P 2 in which the information about its type real whether it is a parameter or otherwise and the level are all stored. And then the second function f 2 does not have any parameters. So, this becomes a nil pointer and within the function f 1 we have float V 1 and int V 2 at the level just below the parameters. And then somewhere inside there is a nested block with int V 3 and float v one. So, corresponding to that there is a link list you know of variables which is pointed to by the local var list pointer. So, the variables are stored in the order of declaration.

So, first is V 1 its type is real it is a variable and its level is 2. The next one is V 2 it is an integer it is a variable and level 2 the third one would be V 3 integer variable. But the level is 3 similarly the fourth one again is V 1 real variable and level three. So, what we must observe here is this name V 1 is the same as this name v one. But since this has been declared in an interior block, this name actually holds within this block whereas, this name does not hold within this block. So, whenever you make an assignment or read from the variable V this is the declaration which is valid for us. So, this could have been integer as well. So, if you had made it int V 1 then int V 1 would have been relevant within this block.

So, and similarly suppose this name P 1 was again redeclared here you know. So, say int P 1 this would have been an error, because it is just below the parameter list. Whereas, here it we had another int P 1 it would have actually overwritten this declaration within this particular block it would not have been flagged as an error what about function f 2. So, the function f 2 also has 2 variables V 3 and V 4. So, they are linked in this list and its pointer is present in the local var list pointer here the number of parameters of f 1 is 2 and the number of parameters of f 2 is 0.

So, this is the structure of our simple symbol table. So, the variables V 1 at level 2 and V 1 at level 3 in the function f 1 are different variables they are not treated as the same. And when we search for a name we actually start from let us say we are within this block. So, we really start from this point then you know we search this list and then we need to search the rest of it as well if we do not find anything within this list then we need to search the others as well. So, this is how it is. So, what we really need to do is make sure that we get the right variable.

So, of course, it is always possible to have another you know maintain another link which is in the reverse directions. So, that the search becomes faster and. So, on, but that is you know a minor detail. So, if we have a reverse link as well then whenever we want to search something we could search here if you do not get anything. Then we could start search in the reverse direction, but we should be careful to make sure that the search covers the levels at you know in the appropriate order.

(Refer Slide Time: 14:47)

So, carrying this discussion further now, let us see what are the various global variables and function we require to operate the symbol table. So, we require a variable active func p t r its stores a pointer to the function name entry in the function name table of the function that is being currently compiled. So, this will tell us that you know we are now looking at a particular function and it is being processed. The global variable level stores the current nesting level of a statement block. The global variable call name pointers stores a pointer to the function name entry in the function table of the function that is being whose call is being currently processed.

So, there is a difference between the call name pointer and the active function pointer. Active function pointer is useful when we compile functions and call name pointer is useful when we process calls to a particular function. Then the search function function the it actually takes three parameters n found and f n p t r it is you know starts for its searches the symbol table for the name n its searches only the functions and then if it is found it returns found as true otherwise it returns found as false if the name is found then a the pointer to that particular name is returned in f n p t r. So, this is the use of such function routine.

(Refer Slide Time: 16:43)

Then the routine search PARAM searches the parameter list of the, you know function at f n p t r. So, this, the function pointer whose parameter list has to be searched and if you find it this found is made as true otherwise it is made as false. And if it is if we find a parameter declaration then a pointer to that is a turned in p n p t r. So, the function search var does the similar thing on the variable list. So, the name is v the function in which we want to search is f n p t r the pointer to that the level is L found is a flag and v n p t r is the pointer to it if the name is found.

So, this search must be started at level L and then it should go to lower levels. So, this is where you know providing a reverse link is useful in this list so, but I am only showing you the minimal structure that is needed to make the symbol table functional. But as I said efficiency is not the most important thing it is the understanding of how semantic analysis is performed and how the information is stored in the symbol table that is important to us at this point. So, the other symbol table routines will be explained as we go on.

(Refer Slide Time: 18:22)

So, here is the grammar that we consider for as analyzing the functions and calls to functions. A function declaration consists of a function head then it has a variable declaration list and a body function head says there is a result and I d. So, this is a, you know we are breaking up this production to enable better semantic analysis. So, there is result is either integer float or void i d is the name of the function and then we have a parameter lists here. So, the declaration PLIST generates several declarations.

So, DECL P L of epsilon so, this is necessary to make sure that we can have 0 parameters or more than you know 0 parameters. So, if you have 0 parameters then we use the epsilon option otherwise we use the DECL P L option. So, DECL P L option so, DECL P L generates a list of params. So, declaration of a parameter is a type followed by name. So, the type can be either integer or float and variable declaration here again this we have seen already there is a list of declarations and each declaration is of the form D going to T l. So, L is a list of names for this declaration.

(Refer Slide Time: 20:02)

Going further the body has variable declarations followed by statement lists. So, these are the variables which are local to the block and the block is began using the flower bracket. And ended with another flower bracket statement list in the block generates a list of statements that is quite easy to understand and each statement could be again a body itself. So, the, it starts a new body a block it could be a function call it could be an assignment and many others we have already considered the other types of statements. So, we will consider only these three to show our semantic analysis on function declarations and function calls.

So, the body actually can be regarded as a compound statement and assignment statement has been singled out. Because we want to show how functions can be functions calls can be handled an assignment has a form left hand side and then there is a, an assignment operator and E an expression. So, the left hand side we have already seen this can be either an identifier or it you know array expressions are all leftover exercises. So, we are not we have done that already to some extent.

So, extension of the symbol table for arrays etcetera is left for exercises then the expression on the right hand side. So, L H S can only be a name expression on the right hand side can be either L H S which generates the name. Or it could be a function call or many other types of expressions which we are not concerned with. So, what is a function call? It is a name followed by a parameter list. So, the parameter list can be empty or it could be one or more parameters. So, we generate the parameters as expressions here using this production.

(Refer Slide Time: 22:11)

So, let us look at the semantic analysis for the function declarations first function declaration starts with function head var declaration and body. So, we now look at s a T g that is the, with synthesized attributes. So, there is no need to write the arrow. So, what is it that we require? So, when we process the function declaration by the time we try execute this action the entire function has been parsed and analyzed. So, at this point we really delete the variable list of functions which we have function which we have just now parsed and analyzed why. And that is pointed to by active func p t r, the level of the function of course, is level itself which is; obviously, one at this point. If why should we delete the list well we have no use for the variable list after the body of the function has been completely analyzed. So, that is the reason we do not need the variable list anymore.

So, at this point I want to show you that the deletion is important, but later I will also show you how to keep this variable list for use in a two parse compiler. The assumption here is the intermediate code generation also happens along with semantic analysis and parsing. So, after the intermediate code has been generated we do not require the variable list. However, if you observe this we have not deleted the parameter list there reason is one the function body has been completed. We do not need the, we do not need the variable list, but we are going to use the function at a later point in time. So, at that point we definitely require the parameter list to check against the parameters in the call.

So, we must be careful to delete only their variable list which is not needed anymore, but not the parameter list. So, we just reset the active function pointer to null and the level is made as 0 to make sure that we start all over again. So, here function head goes to res i d and then a declaration of the PLIST the parameter list. So, at this point in the production we have completed the analysis of this entire right hand side. So, the level can be raised to two to make sure that we now start processing variables. So, at this point where the level is 0 and then functions are entered with at level 0 parameters at level one and variables a level two or more the res i d non terminal expands to result followed by name.

So, now, there is some action we need to search the function table for this name if the name is already present. Then there is an error which is declared that the function is already declared and I the name is not present we enter the function with this particular name this particular type. And this name p t r is the pointer returned by the routine and this pointer points to this particular function entry in the symbol table. So, active func pointer is set as name p t r, because that is the function which we are now going to analyze level is set as one. So, now, level one implies parameter list. So, that is why we need to parse this next. So, result of course, either goes to int or float or void and the actions are very simple the result type is set as an integer real or void appropriately. So, now, let us look at the declaration PLIST.

(Refer Slide Time: 26:26)

So, this declaration PLIST going to DECL P L or epsilon there is nothing to do similarly this also expands to DECL P L DECL PARAM or DECL PARAM there is nothing to do. But once we have a concrete declaration DECL PARAM goes to T i d we have an action as well. So, as usual we search whether this name has already been declared as a parameters using the routine search PARAM. So, if it is already found to found in the symbol table there is an error parameter already declared otherwise we enter the name into the symbol table using the routine enter PARAM.

The type of the name is T dot type the pointer at which the function corresponding to this parameter list exists is active func p t r. So, enter PARAM does its job and enters the name into the a symbol table at the appropriate place T expands to int or float which is trivial we have seen this. So, many times already var DECL going to DLIST or epsilon and DLIST list going to D or D list semicolon D these are quite simple there is nothing true really. Now, once we expand D we will have some action. So, we will show the analysis of simple variable declarations and handling arrays is let as a exercise.

(Refer Slide Time: 27:59)

D going to T L so, now, L has generated a list of names. So, we have seen this before, but let me just repeat it you know for the sake of continuity patch var type patches. The entire list, L dot list at the level L with all the names in this L dot list at the level L, with the type T dot type. So, that takes care of completing the information within the symbol table or the particular name then L going to I d. So, this generates either a single name or many names. So, let us see, what happens? When we search or a name. So, here so far you know we have already processed the parameters.

So, now we are processing variables. So, that is why we search whether the name has already been declared in the variable list at the appropriate level. So, if the name is found and the level is the current level then we are not allowed to declare the name again. So, the error message variable already declared at the same level is issued and we make the list as null. So, there is nothing more to do here otherwise if the level is two so; that means, we dint find the variable in the variable list anywhere. But we also have to check whether it has been declared before as a parameter which is also an erroneous situation.

So, search PARAM or this name and if it is found when redeclaration o a parameter as variable that is the error message we see which is issued. And we make L dot list as null if no there are no errors found and the name is not in the symbol table. We enter the variable with the name i d dot name at the appropriate level and the place where to enter is pointed to by active func p t r. So, this is the function in which we are analyzing the variables. So, once the entry is made a pointer to that entry is returned in v n p t r. So, L dot list now has make list v n p t r. So, v n p t r is one of the nodes in that list. So, this is a single variable.

(Refer Slide Time: 30:43)

I there is a list o variables there is nothing very different we search the var list issue and error if found search the parameter list issue an error if found. And otherwise we simply attain the new name to L 2 dot list and pass it on as L 1 dot list. So, whereas, here we have just passed on L 1 dot list equal to L 2 dot list. So, whatever was previously found here is passed on to this he variable which was already declared is not added to the list again. So, here we add it an send it out to L_1 dot list. So, this L_1 dot list now contains all the names. And D to T L now the types information is available in this production.

So, patch var type operates properly and patches all the types o. These particular names body expands to begin block that is the parenthesis flower brackets. And then the var DECL statement list and finally, the parenthesis end you know now the block ending parenthesis. So, what do we do here we really have an action to increment the level, because we are now inside this block. So, the level has increased. So, increase the level then parse these and finally, we delete all the variables the level the current level that is after the incrementation decrement the level and get out. So, this is the action corresponding to body and statement list generates many statements, the statement itself can be anyone of these.

(Refer Slide Time: 32:36)

So, now let us see how the functions calls etcetera are processed. So, we have seen how to process the declarations and now we move on to the call this is an assignment statement. So, we have already you know seen this in great detail with coercion and all that possible. So, here we just do the most basic things L H S dot type equal not equal to error type and E dot type not equal to error type. And then if h L s dot type is not equal to E type we have an error type mismatch in operants otherwise if everything is there is nothing to do.

So, here of course, type conversion etcetera needs to be checked as well whether e's type can be converted. So, the L H S type has to be checked L H S expands to i d, because we have not considered arrays in this particular example. So, when we get an i d we search for that name at the current level in the variable list of the current function active func p t r. So, if it is found then you know see this is a, an assignment which has happened in a particular function. So, the unction is still active it has not closed that is why we are searching with this name in with the currently active function.

And if it is not found then we search whether it is a parameter. So, so if the PARAM (()) the parameter then find otherwise if it is a its an error identifier not declared. So, if the name is found as a parameter then L H S dot type is P n pointer type if it was found as a variable then L H S dot type is v n pointer type. So, that takes care of the L H S part which can be checked here again along with E e goes to L H S. There is only a type copy

E dot type equal to L H S dot type and if it is a function call. Then E dot type becomes function call dot type, because function call itself is yet to be expanded it returns a type.

(Refer Slide Time: 35:07)

So, what is function call? It is a name and a parameter list. So, when we have a name we must check whether it is a function. So, such func searches for this name and if it is found then it returns the pointer in f n p t r I it is not found we issue an error function not declared. And if it is found we assign function call dot type to the appropriate type obtained by executing get result type f n p t r. So, this function goes into the symbol table looks at the result type of the function at f n p t r and returns it as this result. So, call name pointer is f n p t r that is because this is the pointer we have just now obtained by searching. And we also need to check whether the number of parameters in the parameter list is the same as the number o parameters in the declaration.

So, if call name pointer dot num PARAM is not equal to parameter list dot p n o we have not yet seen parameter list. But it you can assume that it returns the number of parameters or number of expressions in this parameter list and p n o. So, if the number obtained from the symbol table is not equal to the number obtained through the parameter list. Then there is a mismatch in the number of parameters in declaration and call and this error message is printed out. What does parameter list expand to? Parameter list expands to PLIST. So, here there is nothing to do really parameter list dot p n o is

PLIST dot p n o or parameter list can also expand to epsilon in which case we there are no parameters then we set it as 0.

(Refer Slide Time: 37:10)

PLIST generates E. So, in this case this is the first parameter. So, PLIST dot P num p n o is set as one then we check the parameter type by using check param type unction. So, the function pointer is call name p t r, this is the first parameter and the type of the, you know a parameter is E dot type and is a flag. So, if the types are matching then is true otherwise is returned as false. So, if it is false then the error message parameter type mismatch in declaration and call is issued. So, otherwise everything is in this so; that means, the first parameter has matched with the declaration. Now this is the next production PLIST going to PLIST comma E. So, this says we have checked all these parameters and we need to check this. So, PLIST one dot p n o is PLIST 2 dot p n o plus 1. So, the plus one corresponds to this E now check the parameter type corresponding to this E. So, call name pointer PLIST 2 dot p n o plus 1 E dot type and if it is not then issue the same error message as before. So, this is how we actually process the parameter list in a call.

(Refer Slide Time: 38:41)

Let us move on and find out how we can process multidimensional arrays. So, as I told you I am going to give you only the basics. And leave the implementation as an exercise length of each dimension must be stored in the symbol table and connect it to the array name while processing declarations because it is possible to assign array slices c allows it. So, therefore, size and types of slices must check during the semantic analysis of assignments. That is why this particular statement is very important we must store information about every dimension carefully. So, consider this example there is an array declaration a 10 b 20 and another declaration b 20 and third declaration c 10 10.

So, this is a two dimensional array this is single dimensional and this is a two dimensional. So, if you write a five equal to b let us analyze and find out the types. So, a of five is actually a array of size 20, because we have provided a subscript only or the first part. So, a each element of the this dimension is an array of size 20 integers. So, a f size is an array of 20 integers the right hand side b is an array of 20 integers. So, the types match and the first this assignment is definitely valid. So, this is an example of assignment to a slice of an array in the second case c 7 is an array of size ten whereas, a eight is an array of size 20.

So, the types do not match and therefore, this is an erroneous assignment. So, if getting down to the slices and checking the compatibility with respect to the size of the array the type of the elements etcetera is called as a structure equivalence. So, this is basically structure equivalence, what we have done here is structure equivalence and it is different from name equivalence which will be explained shortly. So, for multidimensional arrays with assignment of array slices, we require structure equivalence.

(Refer Slide Time: 41:05)

What about structs? The name inside structs belong to a higher level. So, the names inside can do not collide with the names outside, and equivalence of structs is based on what is known as a name equivalence and not on structure equivalence. So, let us take an example here is a structs int a comma b then float c ten char d. So, these are the 3 fields, 4 fields of this struct and x and y are variables of this type. The second struct has char D then float 10 and finally, int a comma b, a and b are two variables of this type. So, observe that this a and b and this a and b are different there is no collision between these two. Now, if you observe carefully the two structs are almost the same, you know this int a b is in the first two fields of the first struct. Whereas, it is in the last two fields of the second struct similarly char D is the last one here and the first one here float is in the middle in both of them.

So, when we write x equal to y we are actually looking at the same structure declaration. So, x and y belong to the same structure declaration and this you know the assignment is correct this is the name equivalence, because we are just looking at the same declaration corresponding to both x and y, if you had provided a name to this struct. Then you know we would really have said x and y are o that particular type name. Whereas, the second one a equal to x require search to look at a permutation of the second struct. And then compare it with the first which is not really done by any compiler.

Because with large structures any number of permutations large number of permutations will be possible and checking all of them is very time consuming and possibly erroneous as well. So, when we checked the struct assignments we check whether they belong to the same declaration. So, if they are then we say yes they are equivalent otherwise we say they are not equivalent. So, this is basically the name equivalence and for storing the names of the fields, inside a struct an extra pointer pointing to the fields of the struct variable along with their level can be maintained in the symbol table. So, just to avoid and extra pointer and store it that should be good enough.

(Refer Slide Time: 44:00)

So, let us look at operator overloading this is something know well known. So, operators such as plus are usually overloaded in most languages for example, we use plus with integers and we use plus with reals as well. But then in C plus plus operators such as plus can be given new or we can define new functions or the existing operators in C plus plus in other this is called as operator overloading. For example, we can define plus on complex numbers, we can plus on define plus on rational numbers. Or we can say at time you know two objects which are of time type time, etcetera.

So, here is an example complex operator plus this is the declaration of the overloaded operator plus its parameters are two complex quantities. So, we just want to add them. So, we have a temporary then temp dot real is temp dot real plus L H S dot R H S dot real. So, we had initialized it to L H S and similarly we had the imaginary parts and return temp. So, whenever we write when there are say two complex numbers x and y. And we simply write x plus y automatically the result is produced to be of type complex and the appropriate addition function is called. So, this is called a operator over loading.

(Refer Slide Time: 45:30)

There is function overloading as well. So, whatever we did with operator we can do with functions as well now we can have the functions with the same name or. And then there must be some difference between these, they that various functions can written results with different types of or they can have different types of parameters or different number of parameters. So, something must be different between the functions which have the same name. So, so that the compiler can differentiate between the various functions. So, the meaning of the overloaded operators in C plus plus with built in types as parameters cannot be redefined. So, this is with respect to operator overloading. So, for example, we already have a plus on integers. So, now, we cannot redefine plus on integers to mean something else and we cannot say that you know plus will now have three parameters.

So, we must always have exactly two parameters for the overloaded operator plus irrespective of what type of parameters it takes. So, both function and operator overloading are resolved at to compile time and both are different from virtual functions or function overloading overriding function overriding really is useful in inheritance. So, when there is a subclass and we redefine a function which was defined in the base class that is called as function overriding and virtual functions of course, are the methods inside the inherited class. So, at a point in time I could possibly call the function with the subclass or some other base class as well. So, this is these two are very different from the overloading that we are talking about.

(Refer Slide Time: 47:29)

So, here is the function overloading example. So, the same name area is used for square rectangle and circle in this case it return integer here also it returns integer r. Whereas, here it returns a float and the number of parameters it is 1 here 2 here and 1 here the types of parameters are also different. So, here it is float and here it is int. So, when we write something like this, this area 10 corresponds to square area 12 comma 8 corresponds to rectangle and area 2.5 corresponds to the circle.

(Refer Slide Time: 48:08)

How is this really implemented? So, for operator overloading we need a list of operator functions along with their parameter types. So, we can store this as a hash table and the hash function must be designed very carefully it must be designed to take the operator and its parameter types into account. So, for example, when we handle the production such as E 1 E going to E 1 plus E 2 the above hash table is searched with this signature plus E 1 dot type comma E 2 dot type.

So, in other words we hash using plus then E 1 dot type and E 2 dot type look at the entries in the hash table match them appropriately. So, if there is exactly one match with the same operant types then we have resolved the overloading and if there is more than one match an error is flagged. But in practice the situation is a little more complicated in C plus plus. Because conversions of operant types char to int int to float etcetera are also possible before we make a decision as to which function operator is relevant in this point.

(Refer Slide Time: 49:23)

Function overloading is also not so trivial to implement the symbol table should be able store multiple instances of the same function name along with their parameter types and other information. So, while resolving a function call say test a b c, all the overloaded functions with the name test are collected. So, and the closest possible match is chosen so, what is the closest possible match? Suppose the parameters a b c are all type int in this case and we have two of these tests routines, with first one with int int and float. The second one with float int and float if the first one is chosen, because we need to convert only you know one of the parameters possibly from int to float these are all int. So, whereas, for the second one we need to convert two of them to float. So, converting one is faster than converting both. So, the first one is chosen.

(Refer Slide Time: 50:30)

So, now let me also introduce you to semantic analysis on functions and declarations in a two pass compiler. Suppose we have we permit the variable declarations before the body and after the body instead of just before the body and the body itself has variable declarations then statement list and then variable declarations. So, we would actually be permitting declarations before and after the use. So, in such a case the symbol table must be constructed in the first pass declarations are processed in the first pass. But the statements are analyzed and errors are issued only in the second pass. The second pass of course, can be made over the parse tree whereas; the first pass can be integrated with L R parsing.

(Refer Slide Time: 51:21)

So, let me show you an example here. So, along with the name we need to store you know the here we call it as a block table instead of a symbol table just to distinguish between the various types. And this is the indexed using the block number 1 2 3 4 and we also store what is known as a surrounder block number along with this extra information.

(Refer Slide Time: 51:47)

So, let me show you an example first.

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Here is the program which in which we have int f 1 then we have the blocks and the, we have blocks inside again. And then the end of f 1 and f 2 the reason we want to show this is you know the variables etcetera. Here will have to be retained within the symbol table and cannot be disposed off. So, in other words we need the symbol table to be persistent it cannot be destroyed after the block or function is processed in pass 1. And it should be stored in a form that can be accessed according to levels in pass 2.

So, here these are the various functions. So, we have a function f 1 and then we entered it this is block number 1 function f 1 is block one whereas, block number 2 is within function 1. So, it has no type or parameters etcetera, but it definitely has a list of variables attached to it block number 3 again has a list of variables attached to it block number 4 is within block 4. And it has a list of variables attached to it, but the, and then function if f 2 corresponds to block number 5. The important factor here is the surrounder block number for example, block 4 is enclosed within nested within block 3, block 3 is nested within block 1.

So, corresponding to that we have surrounder block number as three and for 3, we have the surrounder block number as 1. And for 1 we have the surrounder block number as 0 otherwise the variables are all maintained as a separate list for equal block. So, this is the specialty in the case of the two pass compiler. So, the symbol table is indexed by block numbers and there were no separate entries for blocks in the previous case here there is a surrounder block corresponding to the enclosing block. So, all the blocks below the function entry f correspond to the function f up to the next function of course. And to get the name of the parent function we just have to use the surrounder block numbers to until it becomes a 0. So, here for example, if you are in block 4, we just you know use the surrounder block number to go to 3 then to 1 and then if becomes a 0. So, f 1 is the function which nests these blocks.

(Refer Slide Time: 54:35)

So, block number begins from 1 and there is a counter last block number which generates new block numbers and current block number is the currently open block. So, while we open a new block current block number becomes the surrounder block number and similarly while closing a surrounder block number is copied into the current block.

(Refer Slide Time: 54:55)

So apart from the current you know active function pointer we need call name pointer. And of course, we also need the active block pointer itself level remains the same. Search function remains the same except that the entry is corresponding to surrounder block number equal to 0 are the only one search. Search param remains the same search var is also almost the same it is just that we need to now search the blocks separately and instead of level we use the active block pointer.

So, the search starts from active block pointer and proceeds upwards using the surrounder block numbers until the enclosing function is reached. So, in other words here we search from the innermost block till we reach the function as in the previous case it is just that we have all the information about all the blocks stored separately. And therefore, in the second pass of the compiler you know searching these is possible. So, we will stop here. So, this completes the semantic analysis phase of a compiler. And from the next lecture, we will concentrate on intermediate code generation.

Thank you.