

**Theory of Computation**  
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**Lecture 53**  
**HAM – PATH is NP - Complete**



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Hamiltonian Path

Given a directed graph  $G$ , and designated vertices  $s, t$  of  $G$ , is there a path from  $s$  to  $t$  that goes through each vertex of  $G$  exactly once?

$HAM-PATH = \{ \langle G, s, t \rangle \mid G \text{ is a directed graph, } G \text{ has a Hamiltonian path from } s \text{ to } t \}$

Theorem:  $HAM-PATH$  is NP-complete.



Hello and welcome to lecture 53 of the course Theory of Computation. In the previous lecture, we discussed two NP-complete languages, clique and vertex cover, which are both based on graphs. In this lecture, we will cover another NP-complete problem called Hamiltonian path. This lecture focuses on directed graphs.

A directed graph is a graph where the edges have directions. Previously, our edges were undirected, meaning the edge from  $i$  to  $j$  was the same as the edge from  $j$  to  $i$ . In directed graphs, edges are like arrows with directions, so an edge from  $i$  to  $j$  is not the same as an edge from  $j$  to  $i$ . In an undirected graph, given two vertices  $i$  and  $j$ , there could be no edge between them, one edge from  $i$  to  $j$ , one edge from  $j$  to  $i$ , or both edges could exist. These are the four possibilities: no edge, an edge from  $i$  to  $j$ , an edge from  $j$  to  $i$ , or both edges existing. This explains directed graphs.

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Hamiltonian Path

Given a directed graph  $G$ , and designated vertices  $s, t$  of  $G$ , is there a path from  $s$  to  $t$  that goes through each vertex of  $G$  exactly once?

$HAM-PATH = \{ \langle G, s, t \rangle \mid G \text{ is a directed graph, } G \text{ has a Hamiltonian path from } s \text{ to } t \}$

Theorem:  $HAM-PATH$  is NP-complete.



What is the Hamiltonian path? A Hamiltonian path is a path in a graph that goes through all the vertices exactly once. In this lecture, we will explore this concept with two designated vertices,  $s$  and  $t$ . The question is whether there is a path from  $s$  to  $t$  that visits every vertex in the graph.

In the given example, there is no such path. There is a path from  $s$  to  $t$  via  $a$ , but there is no path from  $s$  to  $t$  that includes both  $a$  and  $b$ . From  $s$ , you can go to  $a$ , but then you must go to either  $b$  or  $t$ . If you go to  $b$ , there is no way to reach  $t$ . Thus, this graph does not have a Hamiltonian path.

Consider another example with vertices  $s, t, a,$  and  $b$ . In this case, there is a Hamiltonian path. You can go from  $s$  to  $b$ , then to  $a$ , and finally to  $t$ . This path covers all vertices exactly once. However, if you go from  $s$  to  $a$ , then  $a$  to  $b$ , you cannot reach  $t$ . The correct Hamiltonian path is  $s$  to  $b$  to  $a$  to  $t$ .

A Hamiltonian path is a path from  $s$  to  $t$  that covers all vertices in the graph exactly once, without repeating any vertex. As a problem, it is given as a 3-tuple  $(G, s, t)$ , where  $G$  is a graph,

and  $s$  and  $t$  are vertices in the graph. It is a "yes" instance if there is a Hamiltonian path from  $s$  to  $t$  and a "no" instance if there is no such path. This problem is NP-complete.

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Hamiltonian path problem:  $G$  is a directed graph,  
 $G$  has a Hamiltonian path  
from  $s$  to  $t$ ?

Theorem: HAM-PATH is NP-complete.

Proof: (1) HAM-PATH ∈ NP. *Easy*

→ Guess  $n-2$  vertices other than  $s, t$ :  
Say  $v_1, v_2, \dots, v_{n-2}$ .

→ Check that  $s, v_1, v_2, \dots, v_{n-2}, t$  is a path  
and that all the above are distinct.

(2) 3-SAT  $\leq_p$  HAM-PATH.

Given  $\phi$ , we need to construct  $\langle G, s, t \rangle$  such that



Like in the previous lecture, we will do two things. First, we will show that it is in NP. Second, we will reduce a known NP-complete problem to the Hamiltonian path. Showing that it is in NP is easy. We simply guess a sequence of  $(n-2)$  vertices. Suppose there are  $n$  vertices in the graph. We guess a sequence of  $(n-2)$  vertices, say  $v_1, v_2, \dots, v_{n-2}$ . Then we check whether starting from  $s$ , followed by  $v_1, v_2, \dots, v_{n-2}$ , and ending at  $t$ , forms a Hamiltonian path.

We verify whether this sequence forms a path by checking if there is an edge from  $s$  to  $v_1$ , from  $v_1$  to  $v_2$ , and so on. We also ensure all vertices are distinct. This verification takes polynomial time, so we guess and verify the sequence, demonstrating it is in NP. We will not spend too much time on this part.

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(2)  $3\text{-SAT} \leq_p \text{HAM-PATH}$ .

Given  $\phi$ , we need to construct  $\langle G, s, t \rangle$  such that

$\langle \phi \rangle \in 3\text{-SAT} \Leftrightarrow \langle G, s, t \rangle \in \text{HAM-PATH}$ .

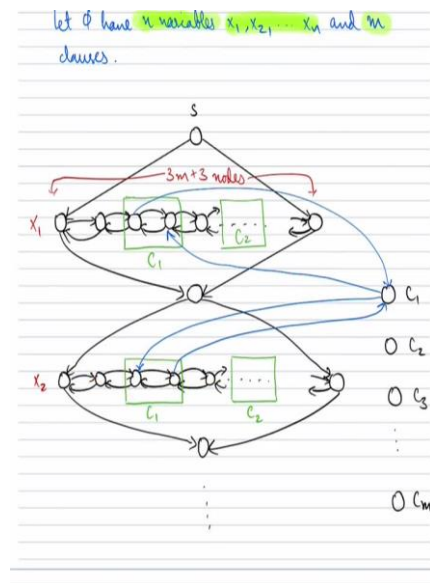
Let  $\phi$  have  $n$  variables  $x_1, x_2, \dots, x_n$  and  $m$  clauses.



The more interesting part is showing that 3-SAT is reducible to Hamiltonian path. The NP-complete language that we picked is 3-SAT. Given a 3-SAT formula, we have to construct  $G, s, t$ , which is an instance of Hamiltonian Path such that this is a "yes" instance of 3-SAT if and only if it is a "yes" instance of Hamiltonian Path. In other words, the formula  $\phi$  is satisfiable if and only if the graph  $G$  has an  $s$  to  $t$  Hamiltonian path.

So, let us see how to construct this. The construction is a bit more involved than vertex cover, so I will mostly be explaining through pictures rather than writing. Let  $\phi$  be a formula that has  $n$  variables and  $m$  clauses. Let the  $n$  variables be  $X_1, X_2, \dots, X_n$  and  $m$  clauses. Now, we are going to see how to build the Hamiltonian Path instance.

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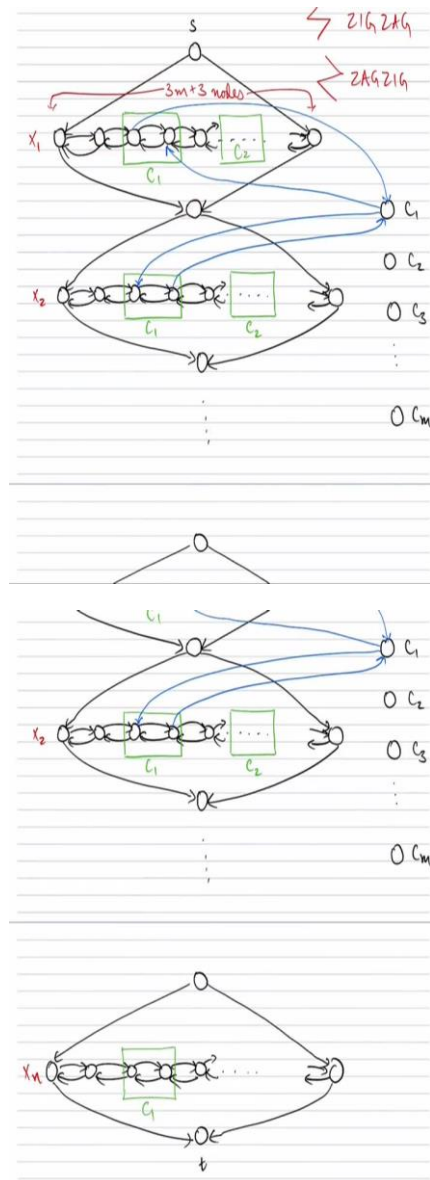


So, what we do is, we have this diamond-shaped structure for each variable. We start with  $X_1$ , so the top diamond corresponds to  $X_1$  as marked here. It starts with  $s$  at the top. This vertex is  $s$ . I have this diamond structure where all arrows are pointing downward. The intermediate vertices, or nodes, have edges in both directions (left to right and right to left). There are  $3m$  plus 3 vertices here, including the leftmost and rightmost ones. There is a path from the right to the left and a path from the left to the right in both directions.

Between each of these edges and vertices, there is an arrow from left to right and an arrow from right to left. I will explain why there are  $3m$  plus 3 vertices. After the first two endpoints, we skip one vertex, and the next two vertices correspond to clause  $C_1$ . Then, we skip another vertex, and the next two vertices correspond to clause  $C_2$ , and so on, up to  $m$  clauses. Finally, we skip another vertex, and the last vertex is the rightmost one. This gives us  $3m$  plus 3 nodes. There are  $2m$  for the clauses and the rest will be  $m$  plus 3, so we get  $3m$  plus 3 nodes.

Once again, we have a diamond starting from  $s$  at the top, going down to the left and right, and then converging to another vertex. There is a series of  $3m$  plus 3 nodes with a path from left to right as well as right to left. We have identified some correspondence between two vertices and a clause, then skip another one, and the next two correspond to  $C_2$ , and so on, for each  $m$  clauses.

The same structure repeats in the next diamond for  $X_2$ . The top of the  $X_2$  diamond is the bottom of the  $X_1$  diamond with the same vertex. The same pattern continues, with a path from left to right and right to left, and identified boxes for  $C_1, C_2$ , etc. (Refer Slide Time: 10:22)



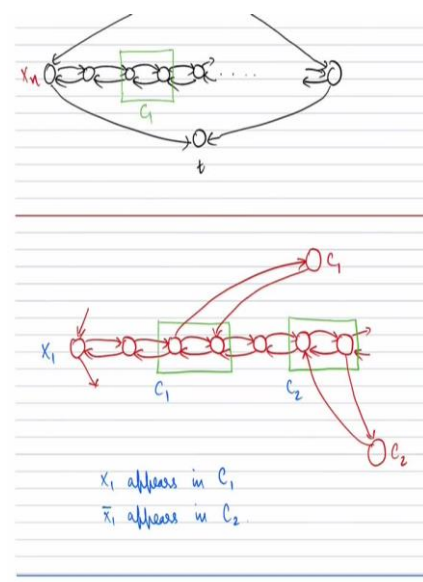
And finally, I have the  $n$ th diamond corresponding to the variable  $X_n$ . Similarly, I have these boxes corresponding to  $C_1, C_2$ , and so on. The bottom vertex of the  $n$ th diamond is  $t$ . The top vertex of the first diamond is  $s$ , and the bottom vertex of the  $n$ th diamond is  $t$ . There are more vertices that will come in a bit.

Ignoring the vertices on the right side for a moment, let's consider the diamonds and their vertices. How can we start from  $s$ , cover all these vertices, and reach  $t$ ? One way is to start at  $s$ , go left, cover all these intermediate vertices going right, and then come down. Another way is to go right, cover all these vertices going left, and then come down. These are the two ways to cover the top diamond: one is a zigzag motion, and the other is a zagzig motion. Zigzag corresponds to the variable being set to true, and zagzig corresponds to the variable being set to false.

Starting from  $s$ , zigzag or zagzig determines the value of the variable. The same can be done for  $X_2$ . We can choose to zigzag on  $X_1$  and then zagzig on  $X_2$ . We have two choices in each diamond, and there are  $n$  such diamonds. Therefore, there are  $2^n$  ways to start at  $s$  and reach  $t$ , ignoring the vertices on the right side. So, there are  $2^n$  Hamiltonian paths from  $s$  to  $t$ .

Now, let's consider how the additional vertices influence the paths. If we just add these vertices without a way to access them, there won't be any Hamiltonian path. We need to ensure that these vertices are reachable to maintain the Hamiltonian path from  $s$  to  $t$ .

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So what we do is the following. Consider this figure: suppose a variable  $x_1$ , let us say this is the diamond of  $x_1$ . I have zoomed in a bit, focusing only on the diamond of  $x_1$ . Suppose  $x_1$

features in clause 1. In the middle row of vertices of  $x_1$ , there is a box that corresponds to  $c_1$ , as we marked earlier.

From the left vertex of that box, we put a directed edge to the  $c_1$  vertex. Before that, let me explain that there are going to be  $m$  vertices on the right side, corresponding to the  $m$  clauses. You have  $n$  diamonds, one for each variable, and  $m$  vertices, one for each clause. Let's take  $c_1$  and see how we connect  $c_1$  to this structure.

If  $x_1$  appears in  $c_1$ , we look for the box marked  $c_1$  in  $x_1$ . From the first vertex on the left, we put a directed edge to  $c_1$ , and from  $c_1$ , we put a directed edge to the second vertex in the box. If  $x_1$  appears in  $c_2$ , we do the same thing. However, if  $x_1$  complement appears in  $c_2$ , the order is reversed. From  $c_2$ , we put a directed edge to the first vertex in the box, and from the second vertex, we put a directed edge to  $c_2$ .

So, if the literal is positive, from the first vertex, we put a directed edge to the clause, and the second vertex receives the directed edge from the clause. If the literal is negative, from the clause, we put a directed edge to the first vertex, and from the second vertex, there is a directed edge to the clause. This is the setup for when  $x_1$  appears in  $c_1$  and when  $x_1$  complement appears in  $c_2$ .

From the box marked  $c_1$ , we only connect to  $c_1$  and nothing else. Similarly, from the box marked  $c_2$ , we only connect to  $c_2$  and nothing else. That is why we have separate earmarked boxes for each clause.

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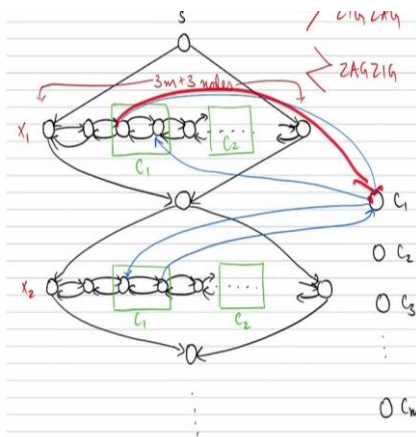




→ How can we go from  $s$  to  $t$ ? At each  $x_i$  "diamond", we can go zigzag ↖ or we can zagzig ↗

This gives us  $2^n$  ways to go from  $s$  to  $t$ , covering all the nodes, except the clause nodes. To cover the clause nodes, we need to take detours.

We can cover clauses in which  $x_i$  is present



And this is something I already mentioned: we can go from  $s$  to  $t$  if we ignore the clauses. There are  $2^n$  ways to go from  $s$  to  $t$ , as each diamond can be zigzagged or zagzigged. Now, how are we going to include these clause vertices? I have already marked some blue edges based on what I said. Here, as per the figure,  $x_1$  appears in clause 1 because the first vertex goes to clause 1, and from clause 1, you get back to the second vertex.

$x_2$  complement appears in clause 1 because the order is reversed: the first vertex is receiving a directed edge from clause 1, and the second vertex is sending a directed edge to clause 1. So, here  $x_1$  appears in clause 1, and  $x_2$  complement appears in clause 1. If  $x_1$  appeared in clause 2, you would connect similarly.

Now, we have the Hamiltonian path, and we need to incorporate the clause vertices. If  $x_1$  features in clause 1 and we are zigzagging, it's easy. Zigzagging means we can start from  $s$ , come to the left side, enter the box for clause 1, move to the clause vertex, come back to the next vertex, and continue our zigzag journey. This is how we incorporate the clause vertex.

If  $x_2$  complement appears in clause 1, zigzagging will not work as the edges are in the opposite order. However, if we are zagzigging, this order is correct. We can come from the right side to clause 1, then come back to the first vertex, and continue.  $x_1$  can cover clause 1 if we are zigzagging in  $x_1$ , and  $x_2$  can cover clause 1 if we are zagzigging in  $x_2$ .

To summarize, zigzagging indicates that  $x_1$  is set to true, and zagzig indicates that  $x_1$  complement is set to true (or  $x_1$  is set to false). Zigzagging allows us to cover all clauses where the variable appears as a positive literal. Zagzigging allows us to cover all clauses where the variable appears in its complemented form (negative literal).

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This gives us  $2^n$  ways to go from  $s$  to  $t$ , covering all the nodes, except the clause nodes. To cover the clause nodes, we need to take detours.

We can cover clauses in which  $x_1$  is present.

We can cover clauses in which  $\bar{x}_1$  is present.

This completes the construction. Given  $\Phi$ , this

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So if we are zigzagging we can cover the clauses in which  $x_i$  is present and zagzigging, we can cover the clauses in which  $x_i$  complement is present. And that is the construction. So I have explained the diamonds, the top and the bottom,  $s$  and  $t$ , and how, for each and these clause vertices and how these are connected.

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$\bar{x}_i$  is present.

This completes the construction. Given  $\Phi$ , this takes only time polynomial in  $n$  and  $m$ .

( $\Rightarrow$ ) Suppose  $\Phi \in \text{SAT}$ . That is, there exists an assignment satisfying all the clauses. For each clause  $C_j$ , there is a true literal.

We start from  $s$  and move down. If  $x_i$  is set to true in the sat. assignment, we zigzag  $M x_i$ . If  $x_i$  is set to false, we zag zig.

Each clause can be crossed by a detour from one of the true literals in it.

crosses.



Now, one point that I am somewhat glossing over is that this construction is clearly polynomial in size and has a very repetitive structure. So, we can build this in polynomial time for sure. As an exercise, you can count how many vertices are there and understand why this instance can be generated in polynomial time given the Boolean formula.

What remains is to show the correspondence:  $\phi$  is satisfiable if and only if this graph has an  $s$  to  $t$  Hamiltonian path, including the clause vertices by the side. Suppose the formula is satisfiable, meaning you can set variables to true or false such that every clause has a true literal.

Now, we need to show that the graph has a Hamiltonian path. Suppose the assignment satisfies the formula. If  $x_1$  is true, we zigzag. If  $x_1$  is false, we zagzig. Now, how do we cover the clauses?

Suppose  $c_1$  contains  $x_1$ . If  $c_1$  contains a true literal, and  $x_1$  is true in the satisfying assignment, we zigzag. We come down the left side, and within the zigzag, we include  $c_1$ . If  $x_1$  is false, we zagzig and cannot cover  $c_1$ . But if  $c_1$  is covered by  $x_2$  complement, then  $x_2$  complement must be true, meaning  $x_2$  is set to false in the satisfying assignment, and we zagzig in  $x_2$ . When we zagzig, we naturally visit  $c_1$  and come back, continuing our zagzig journey.

Since it is a satisfying assignment, every clause has a true literal. When we reach that literal, we detour to the clause vertex and come back. The way the variables and the gadget are set up allows us to detour to the clause vertex and then return to the next vertex without missing anything, continuing the zigzag or zagzig path.

Finally, we keep going down, and eventually, we reach  $t$ . In the meantime, we will have covered all the variables and all the clauses because each clause is satisfied by some variable. Whenever we cross the variable or literal that satisfies a clause, we make sure to cover that clause. Thus, all these clause gadgets will be covered.

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takes only time polynomial in  $n$  and  $m$ .

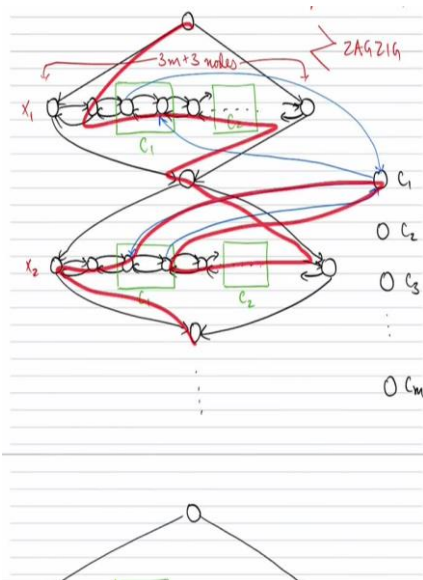
( $\Rightarrow$ ) Suppose  $\Phi \in \text{SAT}$ . That is, there exists an assignment satisfying all the clauses. For each clause  $C_j$ , there is a true literal.

We start from  $s$  and move down. If  $x_i$  is set to true in the sat. assignment, we zigzag  $M x_i$ . If  $x_i$  is set to false, we zag zig.

Each clause can be covered by a detour from one of the true literals in it.

Hence  $G$  has an  $s$ - $t$  Hamiltonian path.

( $\Leftarrow$ ) Suppose  $G$  has an  $s$ - $t$  Hamiltonian path.



Let us say the same thing: there is a true literal for each clause. We start from  $s$  and move down. If  $x_i$  is set to true, we zigzag; if  $x_i$  is set to false, we zagzig. Each clause can be covered by a detour, which gives a Hamiltonian path.

Now, the opposite direction: suppose there is a Hamiltonian path. How do we show that there is a satisfying assignment? Suppose the Hamiltonian path works as described in the forward direction: it zigzags or zagzigs, and whenever there is a clause, we make a detour and immediately jump back and continue. If this happens, it is fairly clear.

If this is the way the path is—zigzagging or zagzigging, and making detours to cover all the clauses—then we set a variable to true if it is zigzagging, and set it to false if it is zagzigging. By the same argument as in the forward direction, this implies that because we cover all the clause vertices, every clause is satisfied. We can only cover a clause vertex if we are moving in the correct direction. Thus, if zigzag means true and zagzig means false, we end up with a satisfying assignment because we are able to cover all the clauses.

To cover a certain clause  $c$  from a certain variable  $x_i$ , we should either be zigzagging on  $x_i$  with  $x_i$  present in  $c$ , setting  $x_i$  to true, or zagzigging on  $x_i$  with  $x_i$  complement present in  $c$ , setting  $x_i$  to false. If the path is of this form—starting from the top, making a detour, coming back to the same diamond, and continuing—then we know how to generate the satisfying assignment: set the zigzagging variables to true and the zagzigging variables to false.


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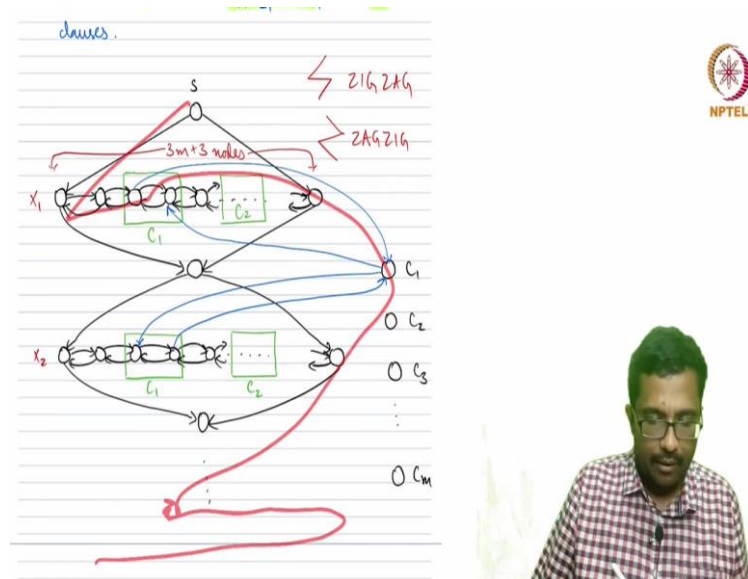
( $\Leftarrow$ ) Suppose  $G$  has an  $s$ - $t$  Hamiltonian path. There is a path from  $s$  to  $t$  that goes through all the vertices.

If this path is normal (goes through all the diamonds in order from top to bottom), set each variable to True (False accordingly—(as per zigzag or zagzig)).

Each clause is covered and has to have at least one true literal.

How can a path not be normal? This can happen only through  $C_j$  nodes. Enter a  $C_j$  from  $x_i$  and exit into  $x_{i'}$ , say.





Suppose  $G$  has an  $s$  to  $t$  Hamiltonian path. If the path is normal—meaning it goes through all the diamond vertices in order from top to bottom—then we set each variable to true or false as per the zigzag or zagzig pattern. As explained, this means that all the clauses are satisfied.

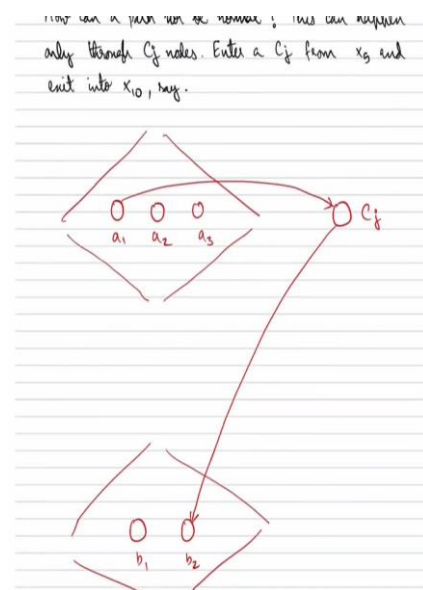
Now, there is an assumption that if this path is normal, everything is fine. But is there a way in which the path may not be normal? The only way a path may not be normal is if we start at the top, go to a clause, then instead of reentering back to the first diamond, we reenter some other diamond, continue for a while, and then maybe come back to the first diamond and to another clause. This is possible.

So, if the Hamiltonian path takes the normal standard zigzag or zagzig pattern with detours, we know it satisfies the clauses. The question is, what if the path is not normal? What if it goes somewhere else and then comes back later? How do we determine if it is zigzag or zagzig?

I argue that such non-normal paths—where you enter a clause, go to another diamond, and later return to the original diamond—cannot happen. This is because we have buffer vertices between these clause boxes. These buffer vertices play a crucial role.

Let's see how. I have a zoomed-in figure to explain this.

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Either  $a_2$  or  $a_3$  is a separator node.

→ If  $a_2$  is separator, then the only way to enter  $a_2$  is through  $a_1$  (covered) or  $a_3$ . If we enter  $a_2$  from  $a_3$ , then no exit is possible.

→ If  $a_3$  is separator, then the only way to enter  $a_2$  is through  $a_1$  (covered),  $C_j$  (also covered) or  $a_3$ . If we enter  $a_2$  from  $a_3$ , then no exit is possible.

So the path has to be normal. We can assign True/False to each  $x_i$  as per whether we zig zag or zag-zig at the respective diamond. This gives us a satisfying assignment for  $\phi$ .



How can a path not be normal? That can happen if we leave a certain diamond, go to a clause, and then reenter some other diamond. Let's say you exit the fifth diamond and enter the tenth diamond, and later maybe from the fifteenth diamond, you go back to the fifth diamond. Can this happen? We argue that if this is attempted, it will not be a Hamiltonian Path. Let's see why.

If we have this arrow from  $a_1$  to  $C_j$ , there are two possibilities. One is that this diamond  $a_1$  and  $a_2$  are grouped together, and  $a_3$  is a separator. At some point,  $a_2$  needs to be covered if it is a Hamiltonian path. If this box corresponds to clause  $C_j$ , it means there is an arrow coming from  $C_j$  here, and also  $a_3$  connects to  $a_2$ .



Now, if we enter  $a_2$  through  $a_3$ , there is an issue because there is no next step. The neighbors of  $a_2$  are  $a_3$ , from which we just came,  $a_1$ , which is already covered, or  $C_j$ , which is also already covered. So there is no exit out of  $a_2$ . These two cannot be in one block. The other possibility is  $a_1$  and the vertex to its left form a block, and  $a_2$  is a separator vertex.

If  $a_2$  is a separator vertex, it is not connected to any clause vertex. The only way we can reenter  $a_2$  is through  $a_1$  or  $a_3$ . But  $a_1$  has already been visited. If we enter through  $a_3$ , there is no way out again. So if  $a_2$  is a separator, entering through  $a_3$  means we can only go back to  $a_1$ , which is already covered, or to  $a_3$ , from which we just came. Thus,  $a_2$  to  $a_3$  has no exit.

This shows that regardless of whether  $a_2$  or  $a_3$  is a separator, we cannot leave a diamond and then enter some other diamond; this will not form a Hamiltonian path. If we try to cover it, we cannot come out and reach the end. There is no exit option.


Hence, the only possible Hamiltonian paths are the ones where we start at the top, zigzag or zagzig a diamond, and then, wherever necessary, go to a clause and immediately rejoin and continue. For these paths, we know how to handle it: if it is zigzag, we assign true; if it is zagzig, we assign false. This results in a satisfying assignment.

Thus, if there is a Hamiltonian path, it has to follow this normal structure, giving us a satisfying assignment. This completes both directions. If the formula is satisfiable, we have a Hamiltonian path. If the graph has a Hamiltonian path, we have a satisfying assignment for the formula. This completes the correspondence and shows that Hamiltonian path is NP-complete.

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Exercises: (1) Show that UHAMPATH is NP-complete.  
 ↓  
 HAMPATH in undirected graph.  
 We can reduce from HAM PATH.

(2) Show that HAM-CYCLE is NP-complete.  
 ↓  
 Hamiltonian Cycle: A cycle that goes through all the vertices exactly once.




Now, two more small things before I end this lecture: one is that we can take the undirected Hamiltonian path. So far, we talked about the directed Hamiltonian path, but the undirected Hamiltonian path is the same problem in an undirected graph. This is also NP-complete. In undirected graphs, we do not have directed edges, so the direction does not play a key role. However, we can reduce from the directed version of the problem. This is explained in the book; essentially, we replace each vertex with three vertices or something similar, ensuring that if a directed graph has a Hamiltonian path, the constructed undirected graph also has a Hamiltonian path, and vice versa.

The second thing is the Hamiltonian cycle. What is the Hamiltonian cycle? It is a directed cycle that goes through all the vertices exactly once, with no beginning or end. This is also NP-complete. This is not covered in the book, but I encourage you to think about it. One approach is to take a graph with an  $s$  to  $t$  Hamiltonian path and add a directed edge from  $t$  to  $s$ . If the original graph has an  $s$  to  $t$  Hamiltonian path, this new edge forms a Hamiltonian cycle.

However, a Hamiltonian cycle does not necessarily imply an  $s$  to  $t$  Hamiltonian path, as the cycle may not use the new edge. To ensure an  $s$  to  $t$  Hamiltonian path, we can add an intermediate vertex,  $r$ , with directed edges from  $t$  to  $r$  and  $r$  to  $s$ . If the new graph has a Hamiltonian cycle, it must include an  $s$  to  $t$  Hamiltonian path because there is no other way to cover  $r$ . This is the basic idea, but I leave it to you to think about and work out the details.

That is it for lecture number 53, where we saw that the Hamiltonian path is NP-complete, with a reduction from 3-SAT using an interesting construction. In the next lecture, we will see yet another NP-complete problem. Thank you.