

**Model Checking**  
**Prof. B. Srivathsan**  
**Department of Computer Science and Engineering**  
**Indian Institute of Technology – Madras**

**Lecture - 46**  
**EX, EU, EG**

Welcome to the second module of this unit. In the last module, we saw that a CTL formula can be rewritten in terms of EX, EU and EG. We called it the existential normal form. In this module, we will look at algorithms for CTL formulae of the form EX  $\phi$ , E  $\phi_1$  until  $\phi_2$  and EG  $\phi$ .

(Refer Slide Time: 00:41)

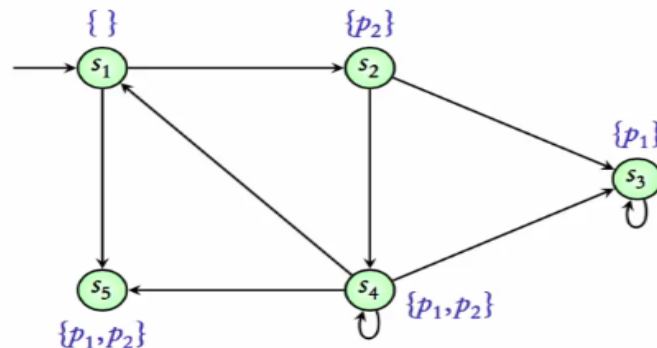
## CTL model-checking problem

Given transition system  $M$  and a CTL formula  $\phi$ , find all  
states of  $M$  that satisfy  $\phi$

So here is the CTL model checking problem, given a transition system  $M$  and a CTL formula  $\phi$ , find all states of  $M$  that satisfies the formula. This is the problem that we are interested in, in this unit. So in this module, we will look at the special case when  $\phi$  is of the form EX  $\phi_1$ , E of  $\phi_1$  until  $\phi_2$  or EG  $\phi$ .

(Refer Slide Time: 01:23)

$$E X (p_1 \wedge p_2)$$



Let us start with algorithms for EX phi. This is the given transition system and these are the labelling of the states with atomic propositions. We want to check if the formula EX p1 and p2 is true in this transition system. How would we do it? As a first step, find the states where this sub-formula p1 and p2 is true. Here it is not true, here it is not true, here it is not true, here since the labelling contains both p1 and p2, the sub-formula p1 and p2 is true in s5, P1 and p2 is true in s4.

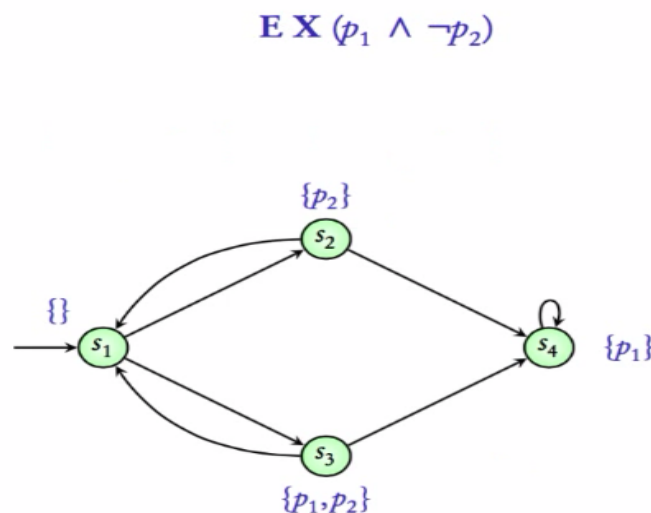
Once you do this to check the states when EX p1 and p2 is true, look at the states which have a transition to a state labelled with p1 and p2, okay. Look at s1, there exists an edge going to a state, which satisfies p1 and p2. Similarly, look at s2, there exists an edge which goes into a state that satisfies p1 and p2, so s2 satisfies this formula.

Similarly, look at s4 there exists an edge, so this is an edge right, there exists an edge back to s4 and s4 satisfies p1 and p2, hence s4 satisfies EX p1 and p2 as well, okay. If you look at the computation tree starting from s4, there will exists a path which satisfies X of p1 and p2 and finally this satisfies EX p1 and p2 as well, because of this transition.

Let me repeat this, the first step was to label the states where p1 and p2 is true. Then what you can do is consider each of these states, look at s4 first, look at all incoming transitions as in the transitions that come into s4, those states, so here there are two incoming transitions, one from s2 and one from s4 and the sources of these two incoming transitions will satisfy EX p1 and p2.

Because from these states there exists a transition to a state satisfying  $p_1$  and  $p_2$ , which means from these states if you look at the computation tree, there exists a path satisfying  $X$  of  $p_1$  and  $p_2$ . We have looked at  $s_4$ , now look at  $s_5$ . It is labelled by  $p_1$  and  $p_2$ , look at all incoming transitions. There are two incoming transitions,  $s_1$  and  $s_4$ ,  $s_4$  is already labelled with  $EX\ p_1$  and  $p_2$ , you need to label  $s_1$ , okay.

(Refer Slide Time: 05:11)



Let us see another example, this is the transition system that is given to us and we want to find the states of this transition system, which satisfy the formula  $EX\ p_1$  and not  $p_2$ . The first step, look at this sub-formula, it is made of  $p_1$  and not  $p_2$ . Let us first mark the states that satisfy this sub-formula  $p_1$  and not  $p_2$ .

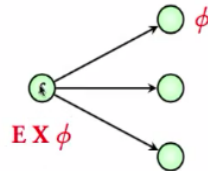
$s_4$  is one state, because it satisfies  $p_1$  and  $p_2$  is not there, so it satisfies  $p_1$  and not  $p_2$ . In fact,  $s_4$  is the only state, because  $s_3$  satisfies  $p_2$  and  $s_2$  does not satisfy  $p_1$ ,  $s_1$  does not satisfy  $p_1$ , okay. So  $s_4$  is the only state which will be labelled  $p_1$  and not  $p_2$ . The algorithm for  $EX$  of  $p_1$  and not  $p_2$  what it will do? Once it has labelled this it will look at all incoming transitions to this state.

There are three incoming transitions, all these states would be labelled with  $EX\ p_1$  and not  $p_2$ . So this state is labelled, this state is labelled, and this state is labelled. So this will be the set of states which satisfy  $EX\ p_1$  and not  $p_2$ . The initial state does not satisfy  $EX\ p_1$  and not  $p_2$ , hence the transition system as a whole does not satisfy  $EX\ p_1$  and not  $p_2$ , but there are these states in the transition system, which satisfy  $EX\ p_1$  and not  $p_2$ .

(Refer Slide Time: 07:10)

## Algorithm for $E X \phi$

Suppose states satisfying  $\phi$  have been labelled



State  $s$  is labelled with  $E X \phi$  if there **exists a successor** which is labelled  $\phi$

Let me summarize the algorithm for  $EX \phi$ . First we need to label states satisfying  $\phi$ , and then once you do that for every state satisfying  $\phi$ , you look at its predecessor. In other words, a state  $s$  is labelled with  $EX \phi$  if there exists a successor labelled  $\phi$ . This is the algorithm, it looks at the every state of the transition system and marks  $\phi$  first.

Once it is done, it will look at predecessors of the states that have been marked with  $\phi$ , and those predecessor states will satisfy  $EX \phi$ .

**(Refer Slide Time: 08:04)**

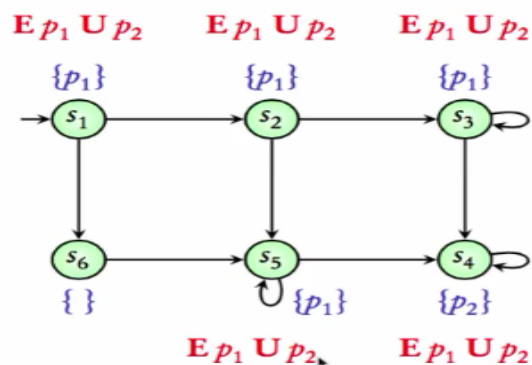
## Part 2:

## Algorithm for $E U$

So we are done with algorithm for  $EX$ , now let us see algorithm for  $E$  of  $\phi_1$  until  $\phi_2$ , which is shortly written as  $EU$ .

**(Refer Slide Time: 08:18)**

$$E(p_1 \cup p_2)$$



This is a transition system, we want to check, which state in this transition system satisfy  $E$  of  $p_1$  until  $p_2$ . First step, look at all states here which satisfy  $p_2$ ,  $s_4$  satisfies  $p_2$ . So clearly  $s_4$  will satisfy  $E$  of  $p_1$  until  $p_2$ . We assume that there are no terminal states. So there will exist a path from  $s_4$  and in that path, the initial state itself satisfies  $p_2$ , so  $s_4$  satisfies  $E$  of  $p_1$  until  $p_2$ .

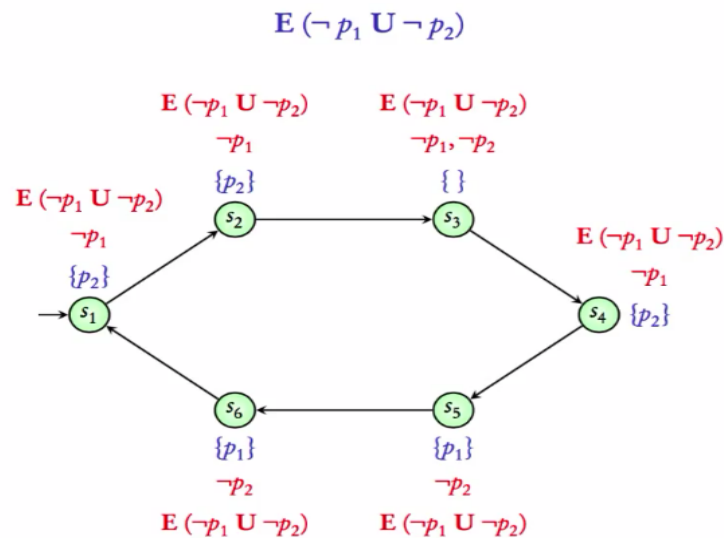
Now what? Look at the incoming transition to  $s_4$ ,  $s_5$ ,  $s_3$  and  $s_4$ . In these incoming transitions, if the state satisfies  $p_1$  then label those states with  $E$  of  $p_1$  until  $p_2$  as well.  $s_5$  satisfies  $p_1$  and there exists a path which satisfies  $E$  of  $p_1$  until  $p_2$ . So  $s_5$  satisfies  $E$  of  $p_1$  until  $p_2$  as well. If you look at this path,  $s_5$  satisfies  $p_1$  and  $s_4$  satisfies  $p_2$ , sorry  $s_5$  satisfies  $p_1$  and  $s_4$  satisfies  $p_2$ .

Similarly,  $s_3$  satisfies  $p_1$  and  $s_4$  satisfies  $p_2$ , so this path satisfies  $p_1$  until  $p_2$ . So at  $s_3$  there exists a path satisfying  $p_1$  until  $p_2$ , fine. Now, continue this process, look at the predecessor of these newly labelled states. Look at  $s_5$ , look at the predecessor  $s_2$ ,  $s_2$  satisfies  $p_1$  and there exists a path to a state that satisfies  $E$  of  $p_1$  until  $p_2$ , which means that this state will also satisfy  $E$  of  $p_1$  until  $p_2$ , correct, because if there exists a path to a state which satisfies this, that means from this state there exists a path which satisfies  $p_1$  until  $p_2$ .

So from here also there will be a path which will satisfy  $E$  of  $p_1$  until  $p_2$ , okay. So this is a newly labelled state. Continue the process, look at the predecessor of this state. There is one predecessor and it satisfies  $p_1$ . So mark it with  $E$  of  $p_1$  until  $p_2$ . Note that, when we look at the predecessor of  $s_5$ , we also had  $s_6$ . But since  $s_6$  does not satisfy  $p_1$ , we will not mark it

with E of p1 until p2. So these are the states of the transition system, which satisfy E of p1 until p2.

(Refer Slide Time: 11:57)



Let us look at another example, we want to check the formula E of not p1 until not p2 on this transition system. Let us mark the states of this transition system that satisfy not p1, not p2. This satisfies not p1, this satisfies not p1, this satisfies both not p1 and not p2, this satisfies not p1, s5 satisfies not p2 and s6 satisfies not p2. Now what does the algorithm do, it first looks at all states that satisfy not p2.

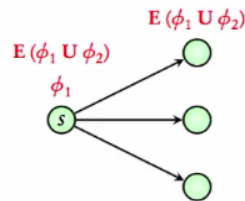
So this is the second formula here know, something until something. So it looks at all states that satisfy not p2 and labels them with E of not p1 until not p2, because if you look at this state there exists a path and already this state satisfies not p2, correct. So this state will automatically satisfy E of not p1 until not p2, same for s5, same for s3. Let us now look at the predecessors of these states.

Look at s5, the predecessor of s6 is already marked, so let us look at s5. The predecessor of s5 is s4 and it satisfies not p1, so it has to be marked with E of not p1 until not p2. Similarly, the predecessor of s3 also satisfies not p1, so it should also be marked with E of not p1 until not p2. Now look at the newly labelled states, this one and this one. The predecessor of this satisfies not p1, so this has to be marked with E of not p1 until not p2.

Now there are no more states left to be marked, so the algorithm will terminate.

(Refer Slide Time: 14:16)

### Algorithm for $E(\phi_1 \text{ U } \phi_2)$



- ▶ If any state is labelled with  $\phi_2$ , label it with  $E(\phi_1 \text{ U } \phi_2)$
- ▶ *Repeat:*  
 Label any state with  $E(\phi_1 \text{ U } \phi_2)$  if it is labelled with  $\phi_1$  and at least one successor is labelled with  $E(\phi_1 \text{ U } \phi_2)$   
*until no change*

Let us now summarise the algorithm for E of phi one until phi two. Assume that states with phi 1 and states with phi 2 are labelled. If any state is labelled with phi 2, then should label it with E of phi 1 until phi 2, that is the first step. Then we need to repeat this process. We need to label any state with E of phi 1 until phi 2, if it is labelled with phi 1 and at least one successor is labelled with E of phi 1 until phi 2.

We need to keep doing this until there is no change. Let us see, suppose this state is marked with E of phi 1 until phi 2. Look at state s, it is marked with phi 1, in that case this should also be marked with E of phi 1 until phi 2, okay. So this is the algorithm, you can check this with the previous examples. In the previous examples, we did E of not p1 until not p2. So we first marked the states with not p1 and not p2.

Next we looked at states where not p2 has been marked. And those states were labelled with E of not p1 until not p2. And then we did this step repeatedly until there was no change, you can have a look at it.

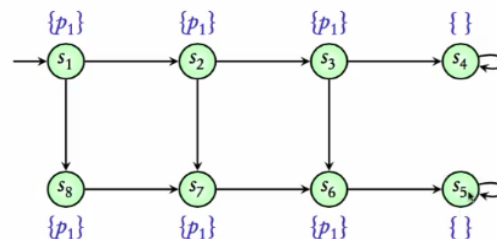
**(Refer Slide Time: 15:50)**

## Part 3:

# Algorithm for E G

We have seen algorithms for EX and EU, let us now look at an algorithm for EG  
(Refer Slide Time: 16:00)

$E G p_1$



No state of the above transition system satisfies  $E G p_1$

So here is a transition system, we want to check the formula  $E G p_1$ . Here the algorithm would be bit different from the last time. In the first step, label all the states with the formula  $E G p_1$ . Now you look at states which do not satisfy  $p$ ,  $s_4$ ,  $s_5$  do not satisfy  $p_1$ . So first remove the labels from them. Now look at the predecessor of  $s_5$  which is  $s_6$ . Look at the paths out of  $s_6$ , or rather the transitions out of  $s_6$ .

There is only one transition out of  $s_6$ , and this transition leads to a state which does not satisfy  $E G p_1$ . So we need to remove  $E G p_1$  from this state as well, because the only path out of this state does not satisfy  $G p_1$ . So remove it from  $s_6$ . Now look at the predecessors of  $s_6$ ,



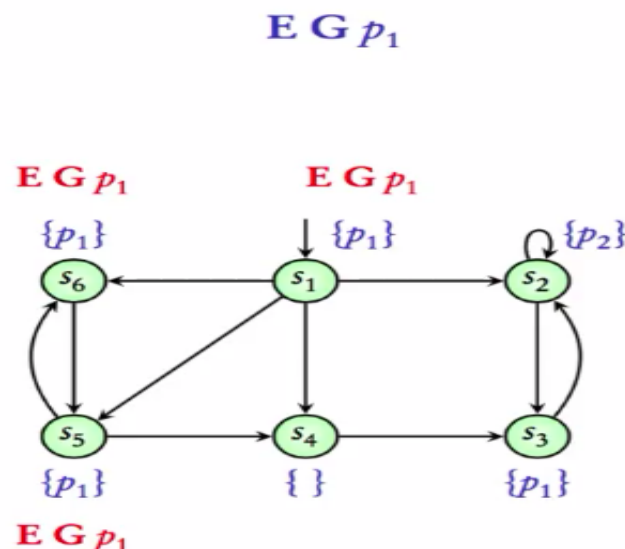
s3 and s7. Look at s3, look at all transitions out of s3. There are two of them, one going to s4, and one going to s6. Both of them do not satisfy EG p1.

As in we have removed the label from both of them. In that case, we need to remove it from here as well, because there does not exist a path satisfying G p1 from this state. Similarly look at s7, the only transition out of it leads to a state, which does not satisfy EG p1. So remove the label from s7 and s3 as well. Look at the predecessor of s7 now, s2 and s8. Look at s2, all transitions out of s2 go to a state where EG p1 is not present.

So you should remove it from this state. Similarly, for s8, the only transition out of it, so all transitions out of it lead to a state where EG p1 is not labelled, so we removed it from here. Finally look at this state, all transitions out of it lead to a state where EG p1 is not marked. So EG p1 has to be removed, here as well. In fact, no state in this transition system satisfies EG p1, you look at any state.

Finally, it has to end up either an s5 or an s4, any path from that state will have to end up in s4 or s5, and both s4 and s5 do not satisfy p1. No state in this transition system satisfies EG p1.

(Refer Slide Time: 19:25)



Let us look at another example, this is a transition system and we want to check EG p1 on this transition system. First step, mark every state with EG p1. Second step, remove this label from states which do not satisfies p1, s4, s2. You remove the label from s4 and s2, because

they do not satisfy  $p_1$ . Now look at the predecessors of these states. Let us start with  $s_2$ , its predecessors are  $s_3$  and  $s_2$  itself.

We have already removed the label from  $s_2$ , now let us look at  $s_3$ . Look at all transitions out of  $s_3$ . There is only one transition and it goes to a state which is not labelled with EG  $p_1$  so the label at  $s_3$  should be removed. Now look at the predecessor of  $s_4$ , say  $s_5$ .  $s_5$ ,  $s_6$  and  $s_1$  are still marked with EG  $p_1$ , let us see what happens. Look at  $s_5$ , there exists an edge which leads to a state satisfying EG  $p_1$ . So we do not remove the label as of now.

Look at  $s_1$ , there exists a transition that goes to a state satisfying EG  $p_1$ . So we do not remove the label from this state as of now. What about  $s_6$ , there exists a transition leading to a state which satisfies EG  $p_1$ . So we do not remove the label from this as well. In fact, these three states indeed satisfy EG  $p_1$ . Since there is no change in the labels the algorithm will start. The algorithm starts like this; all states are marked with EG  $p_1$ .

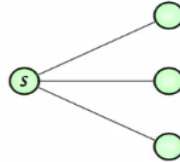
Then states where  $p_1$  is not present, you remove EG  $p_1$ . Then look at a state, if all edges out of it lead to a state where EG  $p_1$  is not marked, then remove the label. Now in the rest of the states check this property, from every state is there an edge which leads to a state marked with EG  $p_1$ . In that case do not modify this label, with this property these three states the labels will not be removed, and the algorithm will stop.

So if you look at this state, there exists a path that goes to  $s_6$ ,  $(s_5, s_6)$ ,  $(s_5, s_6)$  which satisfies  $G p_1$ . Similarly, from  $s_6$  you can keep doing this again and again, and  $G p_1$  will be satisfied, same for  $s_5$ , do  $(s_6, s_5)$ ,  $(s_6, s_5)$ , and so on and that path will satisfy  $G p$ .

**(Refer Slide Time: 22:50)**

### Algorithm for $EG\phi$

- ▶ Label all states with  $EG\phi$
- ▶ If any state is **not** labelled with  $\phi$ , **delete** the label  $EG\phi$



- ▶ *Repeat:*  
Delete the label  $EG\phi$  from a state if **none** of its successors is labelled with  $EG\phi$   
*until no change*

Let us now summarise the algorithm for  $EG\phi$ . Step one label all states in the transition system with  $EG\phi$ . Second step, if any state is not labelled with  $\phi$ , then delete the label  $EG\phi$ . Then, there is going to be a repeated step, delete the label  $EG\phi$  from a state if none of its successors is labelled with  $EG\phi$ . So let me illustrate it. First all states are marked with  $EG\phi$ , then by doing this process if you end up with this picture.

That is the exists a state from which none of its successors is labelled with  $EG\phi$ , then we need to remove the label from the state as well. We need to keep doing this process till it saturates in the sense that, we need to keep doing this till there is no change in the labelling of the transition system. Once you do this, the states which are labelled with  $EG\phi$  are the ones from where there exists a path satisfying  $G\phi$ .

So this is the algorithm for checking  $EG\phi$  on a transition system. So in this module, we have seen three algorithms, given a formula of this kind, we have seen how the algorithm labels the states that satisfy the corresponding formula. In the next module, we will look at a generic algorithm for any CTL formula.