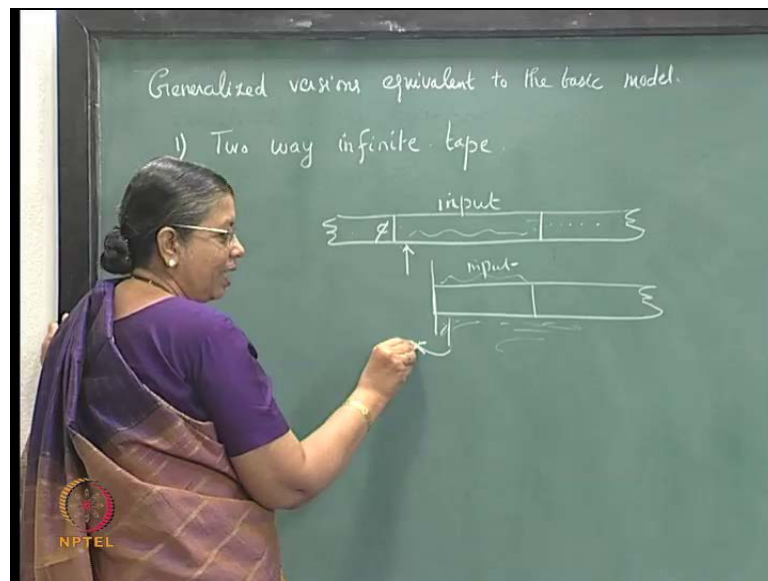


Theory of Computation
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Lecture No. # 29
Generalized Versions of Turing Machines

Today we shall consider some generalized versions of the Turing machine which are equivalent to the basic model. Actually, when we were considering as an input and output device we had a two way infinite tape. When we looked at it as an accepting device it was one way infinite left hand was fixed or we justified in doing that. Actually it does not matter whether you consider it as two way infinite or one way infinite you can do the same thing.

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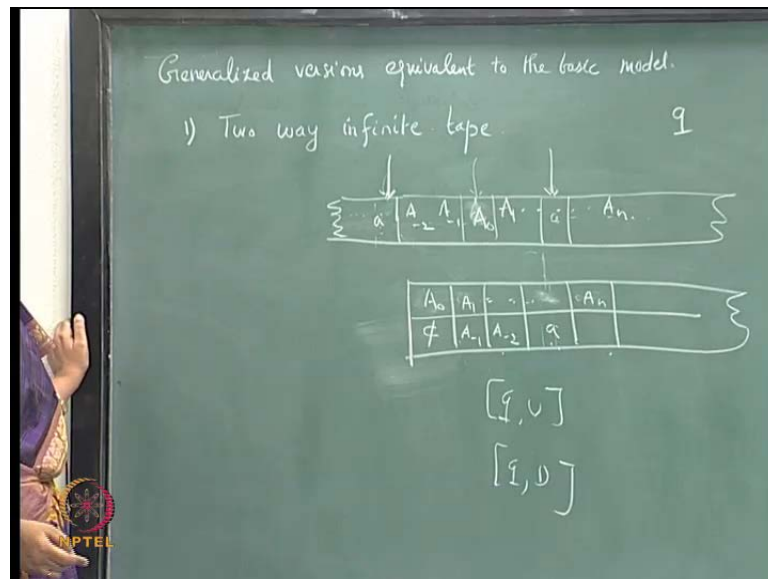


So, the first thing is you make the tape two way infinite for acceptance, two way infinite tape is equivalent to one way infinite tape. How do we prove that? You have a two way infinite tape and the input is given here, when you look it as acceptance you start from hereafter making some moves it goes to the final state and accepts. We can make use of some blank cells in this side; we can make use of some blank cells in this side

also. But if you look at it as a one way infinite tape the input is given here you will start from here and you can make some moves and then accept it. If the Turing machine ever tries to move of the left end then it will halt, it will reject the input you should not move of the left end of the tape, when you look at it as a one way infinite.

Now you can very easily simulate a one way infinite tape with the two way infinite tape, is not it. Only thing is when the input is given you make a marker here, on this cell and so, then you just simulate it as you behave here you can just simulate it. If at all it tries to move of the left end it will go to this marker cell then you have to reject that is all. To simulate a one way tape by an two way tape is very easy.

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Now how do you simulate a two way tape with the one way tape? Now if you have a two way tape we can make use of some cells here also for that you take a tape which has got two tracks. Consider a one way infinite tape which has got two tracks if in the two way tape at sometime after some moves you started at this position say A naught some symbols are there A_1, A_2, A_n . You might have use some symbols A minus 1, A minus 2, etc. Here you start initial position was this then you have made use of some cell cells here input was here then you could make use of some blank cells here, you have made use of some blank cells to the left also.

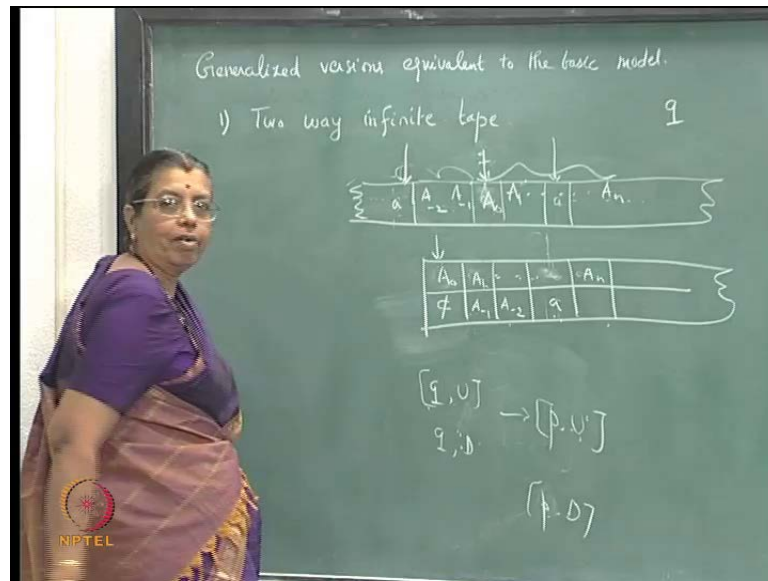
Now in that case how do you simulate it with the one way infinite tape you start with this A naught, A_1 whatever was the input suppose the input was s A naught. I will write a

naught, a 1 a n. The input will be here like this, the lower track will be just blank at this stage then after making some moves see when you want to first move say A naught first here originally it was replaced by A naught and you move right. This will be replaced by A naught and you move right, but first what you do is you whenever you make the first move print a symbol some marker on the lower track at the first cell. Then after some time this is the content of the tape say after some time these symbols A naught, A 1 A n will be there on the first track A minus 1, A minus 2 these symbols will be there on the lower track in the reverse order A 1 this way it will be like this.

So, at some time you are reading a symbol here you will be reading that symbol here, but you will be reading from the upper track only. So, whether you are going to read from the upper track or the lower track that information you have to keep in the state. In the original machine if q is the state in this machine you will take q, U as the state or q, D as the state. Upper track q, D down or something like that or you can say q, L lower track. So, the state will keep the information we have earlier seen that you can make use of the state to store some information, here you are making use of that to store the information. Whether you are going to bother about the symbol in the upper track or in the lower track.

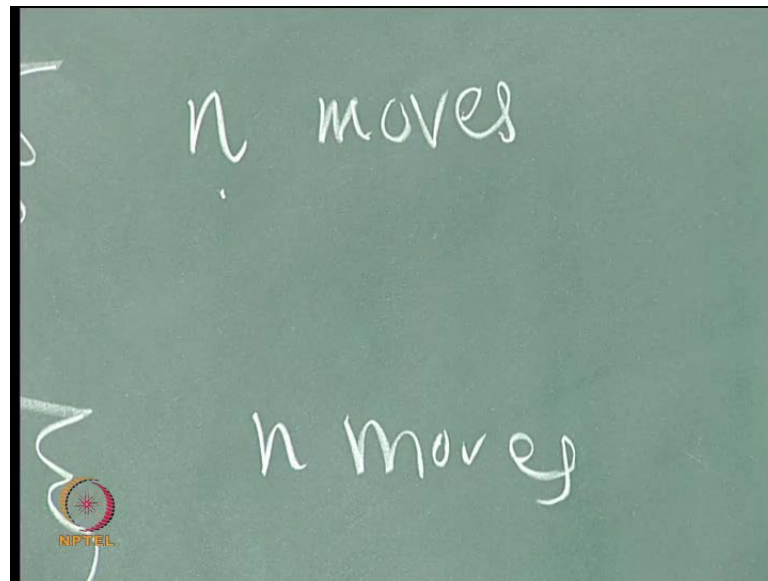
So, in this case suppose you are going to read a symbol a that is here then after reading that you move right means here also you will move right. If you move left means here also you will move left, on the other hand if you are reading some symbol here say some a then after making the move if you move left here you have to move right, if you move right here you have to move left here. So, if you are reading the symbol this symbol the tape head here will be pointing to this.

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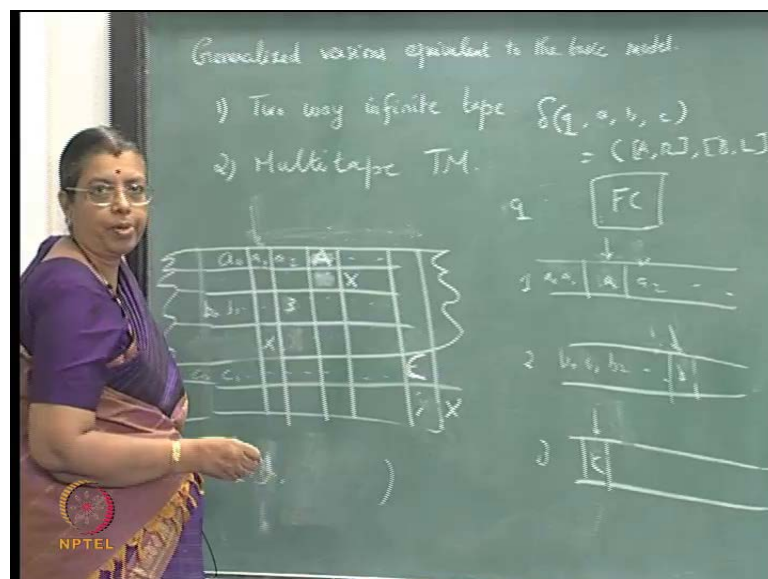


Now if the move is to the right in the state you will change it whatever this when you are reading here if the state will be either q, U or q, D whatever it is then if the move is to the right the state will change to some p, U . If the move is to the left then the state will change to move will be right whatever you read here the next move will be to the right, but in the original one way tape I mean in the in one track if you move right then the state will change to p, U . If you move left the change will state will change to p, D . You are reading this in state q and you are going to change to state p and move right means here from q, U you will change the state to p, U . If you are going to move left means from this or this you will change the state to p, D and move right. That way whatever happens in this portion you simulate in the upper track and whatever happens in this portion you simulate in the lower track.

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So, two way infinite tape can be simulated by a one way infinite tape. So, it does not matter whether you take it as two way infinite or one way infinite both are equivalent the language accepting power is the same. Now if this two way infinite tape an input is accepted in n moves, how many moves will this make one way infinite tape for one move? Here how many makes it moves just one move only one move here is simulated by a move here it may be move left or moves right change may be there, but one move here is simulated by one move here. So, if this makes n moves before acceptance how many moves it will make? This also make n moves the number of moves is the same. (Refer Slide Time: 10:20)



While printing this you are counting this printing the symbol that the first move itself it can print and move initial or separately you can use one move that in that case $n + 1$, but in the first move itself you can print and move that does not matter. So, anyway it isn't goes to n or $n + 1$ does not matter linear. So, number of moves is not very much affected by this simulation, the next is we consider multi tape turing machine this is different from multi track. We have already considered multi track for turing machine construction techniques, now we are going to consider a generalized version this turing machine has a finite control I will write here it has a finite control and several tapes for example, three tapes I can take you can have any finite number of tapes cannot be infinite it can have 1, 2, 3 upto k tapes.

Now each tape is provided with the tape head, each tape has a separate tape head multi track there will be only one tape and that tape is divided into several tracks and there will be only one tape head it will be reading a tuple that is the main idea the tape alphabet is taken as a tuple that is the idea of multi track, multi tape turing machine you have several tapes finite number of tapes each tape will have a separate tape head. Suppose it is reading this a symbol b here a symbol as an example I have taken a three tape a, b, c then the move will be like this δ of q, a, b, c will be some $A R, B L, C R$ something like that the move will be something like this.

The state can change and that should also be taken care of that is instead of a it will print A and move right instead of b it will print aB and move left instead of c it will print aC and move right. So, the move depends on the state and each one of the symbol read and the tape head can move independently one tape head can move left another one can move right and each one will print another symbol on that. So, this is a way the moves are defined, now how is this equivalent to a single tape model originally we had this. So, how can you say that a multi tape turing machine is equivalent to a single tape turing machine you can simulate a multi tape turing machine of course, single tape turing machine is a particular case of a multi tape turing machine that is one.

The other way round you can simulate a multi tape turing machine with the single tape, simulate a multi tape turing machine with the single tape, the single tape if you have k tapes here it will have two k tracks. So, here there are 6, 3 tapes so, there will be six tracks. So, you can have infinite in both direction does not matter, if so the order tracks represent the contents of the tapes. So, here something like a naught a 1 something is there

that will be represented as a naught, a 1, a 2 etc. At a particular instance the symbol a is being read and similarly, here if you have some b naught, b 1, b 2 that will be there in the third track b naught, b 1 etc. It will be leaving a symbol b at a particular instance.

This is the fourth track third track will contain this b naught, b 1 and etc, reading a, b and the fifth track will contain say the contents of the third tape that is some c naught, c 1 etc, so this reading c say at a particular instance. So, it is multiple track like this the even number of tracks they are all blanks except that one cell will contain a marker. Pointing the I mean it represent the tape head position for example, if a is being read there will be X here rest of this portion will be blank similarly, if b is read in the second tape at a particular instance there will be a marker here in the fourth track, but rest of them will be blank.

Similarly there will be a marker here so, how do you simulate one move of a turing machine, multi tape turing machine with a single tape turing machine you start moving from left to right and then moving from right to left you make one pass moving from left to right and make another pass moving from right to left. Start somewhere here the state will have here the state is q say the state will be q then there will be a counter here **there will be a counter** how many tapes are there 3 tapes are here. So, there will be a counter which keeps the value 1,2,3 like that up to k. It can have from 1 to k it can store a number what is the move the move here is q, a, b, c this is AR, B L, CR.

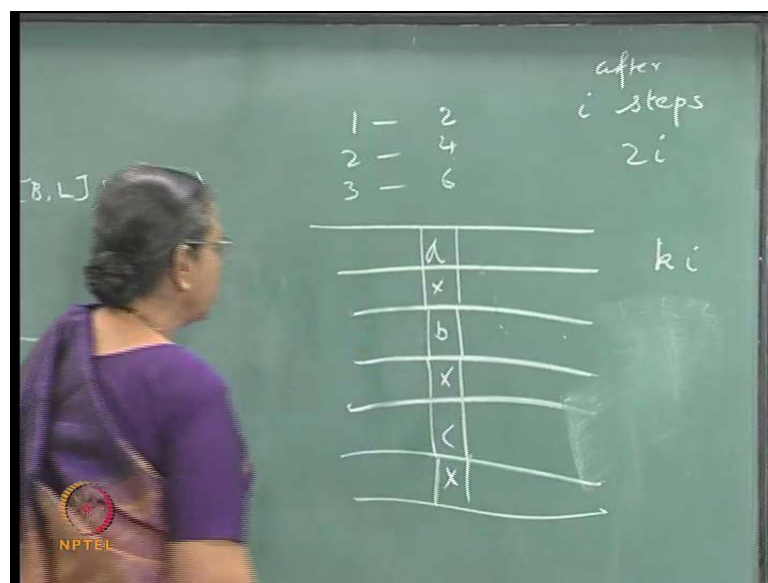
So, it has to remember that it is reading a from the first tape b from the second tape c from the third tape. So, it makes a pass there will be three positions in the state to keep track of that so, it makes a pass and then when it comes here it sees that there is a X in the fourth track, that means the second symbol is second tape it is reading the symbol b. So, it will place that b here then move again now it sees another X here that means in the first tape it is reading the symbol a so, it will put a whenever it is filling this it is also incrementing initially it was zero.

So, when it fills b it has seen one symbol so, it will increment to one then when it sees a it will this will increment to 2 then it will move again and when it sees an X in the sixth track that means in the third tape it is reading a symbol c. So, that c will be put here and now the count reaches the maximum value 3 that means it has read all the symbols. Once it knows that it has read all the symbols it starts moving the move is determined now q a

b c means it has to go to a a should be replaced by A and move right b should be replaced by B and move left and so on.

So, what it does is it starts moving like this and this c will be replaced by C move is to the right X will be placed there. Then it will continue moving left and at this point again it is a move to the right this will be replaced by A and this X will be placed here then it will move again now this b will be replaced by B and X will be moved to the left. Now while doing so, you can erase each symbol whenever it has been replaced we can erase that also and this three will be you will be decrementing that so, when you at this stage it will become after you do this it will become 2 after you do this it will become 1 and after you do this it will become 0 when it becomes zero that means you have changed all the symbols and positioned the head in a proper way.

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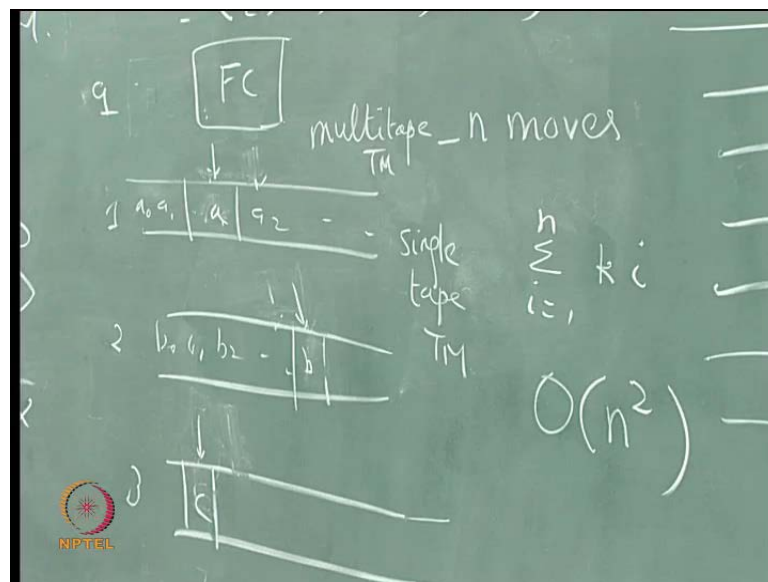


So, that means you have completed simulating one move of the multi tape turing machineso, one move of the multi tape turing machine you have simulated by making one path from left to right and again a pass from right to left. So, how much time it would have taken how many moves it would have taken to simulate one move initially the initial position you can keep like this initially we may start this after one move you may move right sometimes you may move left there can be two cells apart after second move there can be four cells apart after the i th move there can be $i + 2$ cells apart or something

like that is not it initially you start after one move they can be two cells apart the X can be maximum after one move you can move one cell to the right and one cell to the left.

So, there X can be two cells apart after making the second move it can be four cells apart after making the third move it can be six cells apart and so on. So, after i steps the distance between two X will be maximum $2i$ there can be $2i$ cells apart so, you have to make one move this way one move this way. Not only that some more moving right or left you have to make a 1 or 2 moves again extra. So, if you move $2i$ cells to the right and then $2i$ cells to the left you are making $4i$ moves, but while writing the X you have to shift while coming back if it is a move right you will come back here and then put it here and go back.

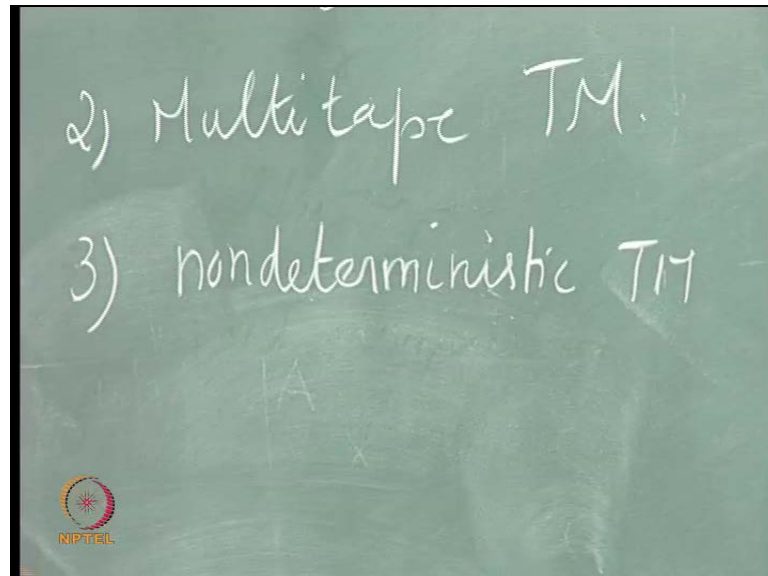
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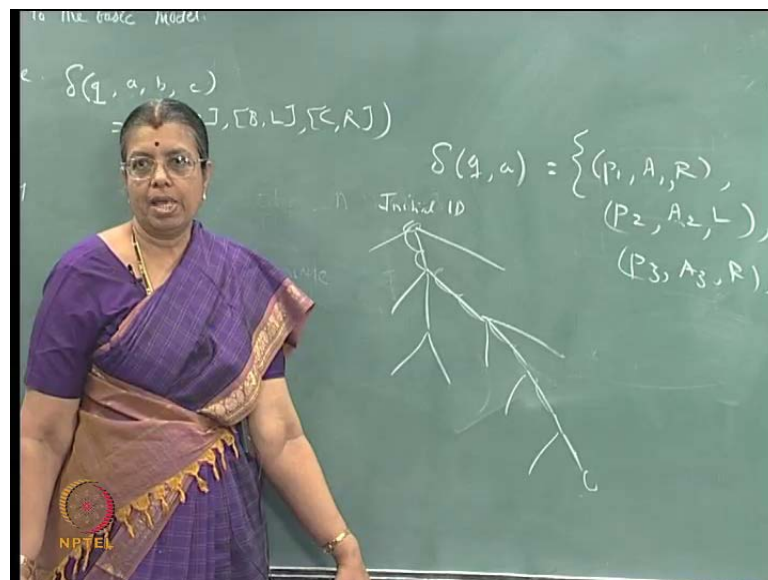
So, it will be something like know not exactly $4i$ slightly it may be more than $4i$. So, maximum i will put is some k_i , k will be k can be between 4 and 6 for that matter any way it is finite. So, if it makes n moves with a multi-tape Turing machine n moves, single-tape Turing machine how many moves? it will make it will be $\sum_{i=1}^n k_i$. k_i is a constant so, it is order n squared terms. So, summing up will be i into i minus 1 by 2 so, k into i into i minus 1 by 2 plus 1 by 2 i into i plus 1 by 2 so, it will be order n square constant does not matter. So, while simulating a multi-tape Turing machine the single-tape Turing machine makes quadratic number of moves, this simulation does not affect the polynomial property if something is accepted by a multi-tape Turing machine in

polynomial time it will also be accepted by a single tape turing machine in polynomial time.

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So, this is another generalized version that is a multi tapeturing machine.

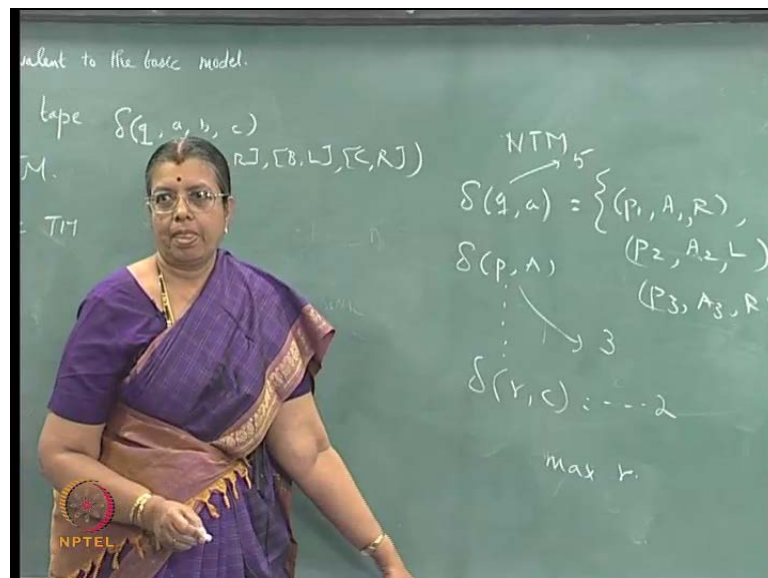
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The third is non deterministic turing machine, what is a non deterministic turing machine? So, instead of delta of q, you may have a finite

choice $P_1A_1R, P_2A_2L, P_3A_3R$ and so on. some finite number of choices will be possible for each move when you are in state q and reading a symbol a then either you can go to P_1 print a A_1 and move right or you can go to P_2 print A_2 move left or print go to P_3 print a A_3 and move right it is like this. But please remember that it cannot go to P_1 print a A_2 you cannot combine like this. The triples are specified it has to choose from one of the triples.

So, starting with the initial ID you may have some choices from each one you may have choices from each you may have more choices and so on. So, when will the string be accepted if there is one sequence which leads to acceptance the string will be accepted. Other sequences may not lead to acceptance does not matter, if there is one sequence which leads to acceptance the string will be accepted just as we defined for a push down automata. So, how do you simulate a non deterministic turing machine with a deterministic turing machine **how can you simulate a non deterministic turing machine with a deterministic turing machine**. Now the idea is like this there will be mappings for the non deterministic turing machine will be given like this $\delta(q, a)$, a $\delta(p, A)$ there will be some moves defined for the non deterministic turing machine.

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Now for this for example, there may be five possible choices for this there may be three choices for something like that there may be two choices only and so on. Take the maximum value maximum of these choices for one move there may be five for another

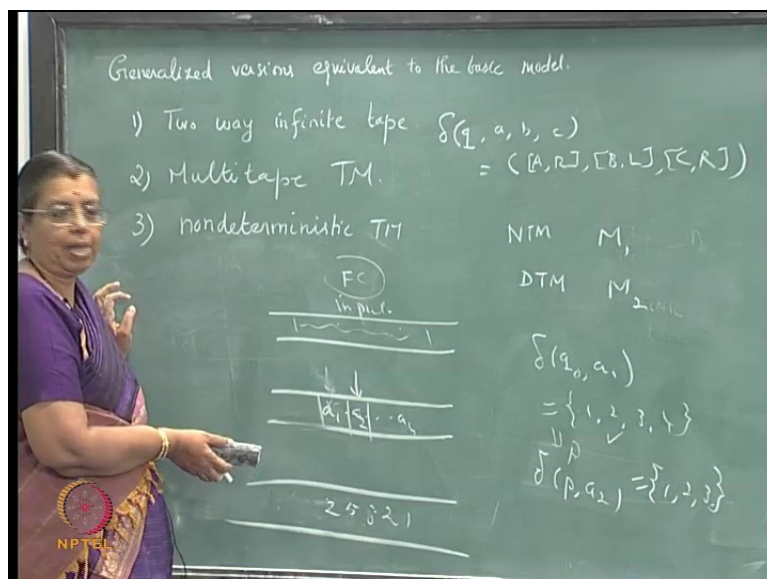
move there may be three choices for another one there may be two choices and so on. So, take the maximum value maximum is r say among this.

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Now from the letter from this consider sigma s is equal to 1 to r and generate sequences over 1 to r in the standard ordering we have studied lexicographic ordering and standard ordering you remember. So, if we generate strings in the standard ordering what will be the order 1,2,3 upto r, 11,12,13 up to 1r, 21, 22 like that you can generate sequences over 1 to r in the standard ordering.

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So, in order to simulate a non deterministic Turing machine with the deterministic Turing machine, the deterministic Turing machine will have a finite control and it will have three tapes. We are taking a non deterministic Turing machine to have one tape, you can extend the result when it has got multi tape also, in the non deterministic Turing machine has one tape whatever is there it is input it is copied on here the first tape then what it does is it copies the input on to the second tape and 1 by 1 it generates the sequence there. So, first it will generate 1 then simulate the behaviour of the non deterministic Turing machine if I call it as M1 the deterministic Turing machine which is going to simulate I call it as M2, M2 has 3 tapes.

So, in one tape the input is there the second tape and the third tape are initially empty. **second tape and the third tape are initially empty** you copy the input onto the second tape then generate the sequence 1 by 1. First you generate one sequence and then simulate the behaviour of M1 by M2 you simulate M2 simulates the behaviour of M1 on this input using this sequence. Suppose at particular time the sequence is say 25321 and the input is copied on here the head will be pointing to that initially. So, in the initial state is q $\delta(q, a)$ there will be 1, 2, 3, 4 choices say for this the number is 2 here. So, it will select the second choice and behave like that it will simulate the second choice on this so, suppose it is moving right printing something here and then the symbol read is 2 state changes to P say then the second move is $\delta(P, a)$.

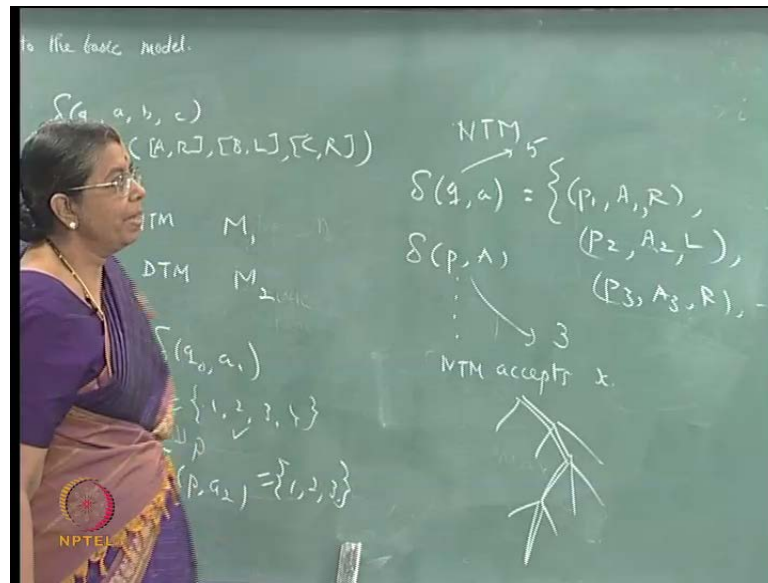
Now $\delta(P, a)$ this has got say 1, 2, 3, 4, 5 choices then this number is 5. So, it will select the fifth choice and simulate similarly, for the next move it will select for that there will be some choices it will select the third. Now it may so, happen that for this there are only three choices possible then number 5 is appearing here that means it will halt I mean it will halt means it will discard that it cannot simulate the fifth choices there are only three choices for that, but the number 5 is here.

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So, it cannot proceed further, now once if it accepts **it accepts** if it does not accept suppose after simulating the moves with this sequence 25321 it finds that it not accepting then what it will do is it will erase the n th the content should have been changed by now. So, it will erase this write the next number in the next sequence in the lexicographic in the standard ordering that is 25322 something like that. Then copy the input again here tries to simulate with this sequence and so on. If the string is accepted by the non deterministic Turing machine then if a suppose some string is accepted by the non deterministic Turing machine then there will be some sequences **some sequence** which leads you to acceptance and when you are creating the sequence 1 by 1 here at some time that sequence will appear here on the third tape, then you copy the input on to the second tape and when you simulate it will be get accepted.

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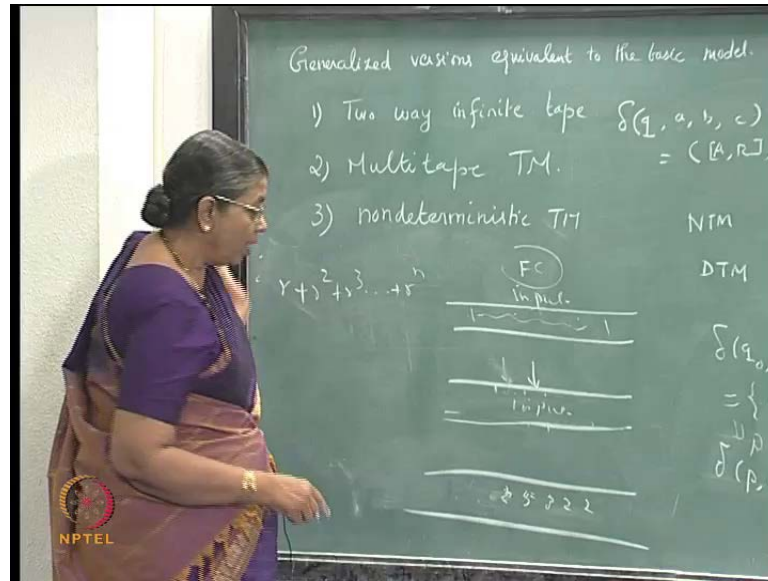


So, if a string is accepted it will be accepted through a sequence of moves and that sequence will be a sequence over the alphabet Γ to read sometime or the other that will appear here, because you are going to generate the sequence 1 by 1 here when that particular sequence appears here you copy the input on to the second tape and simulate the behaviour of M_1 with this sequence then it will accept, but if a string is not accepted what will happen if a string is not accepted one string you will generate here it will not get accepted then you will try the next sequence it will not get accepted then you will try the next sequence it will not get accepted then you try it will not get accepted and so on.

So, you will go on and on it may not halt machine may not halt for strings which are not accepted. For strings which are accepted after sometime that particular sequence in which it accepts will appear on the third tape and when you are trying to simulate the behaviour of M_1 with M_2 using that sequence you will reach an accepting state so, the string will be accepted. So, in this way the non-deterministic Turing machine can be simulated by deterministic Turing machine, but how many moves it will take too much is not it because if it accepts in n move that sequence of length n has to appear here for that you have to write sequences of length 1, length 2, length 3, length 4, length 5 and so on.

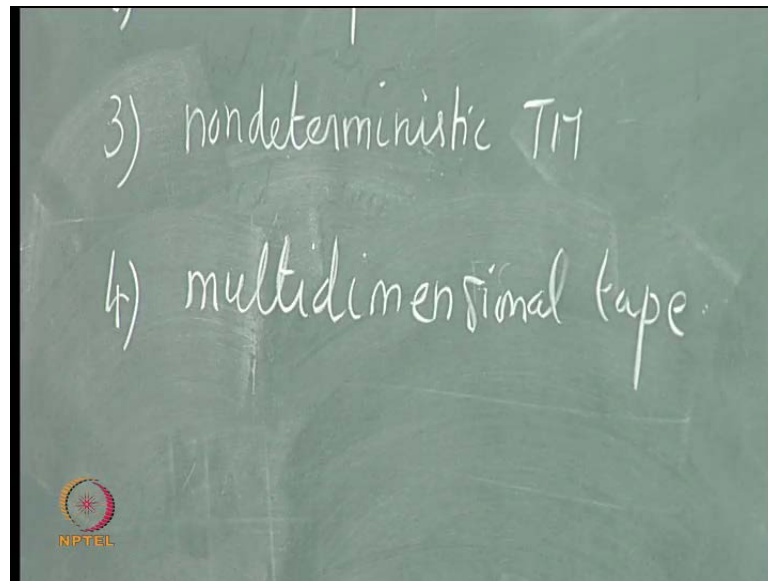
How many sequences of length 1 will be there it will be r length two will be r^2 length three will be r^3 length four will be r^4 length five will be r^5 and so on. One by one all these sequences have to be written here and each time you have to simulate the behaviour and so on.

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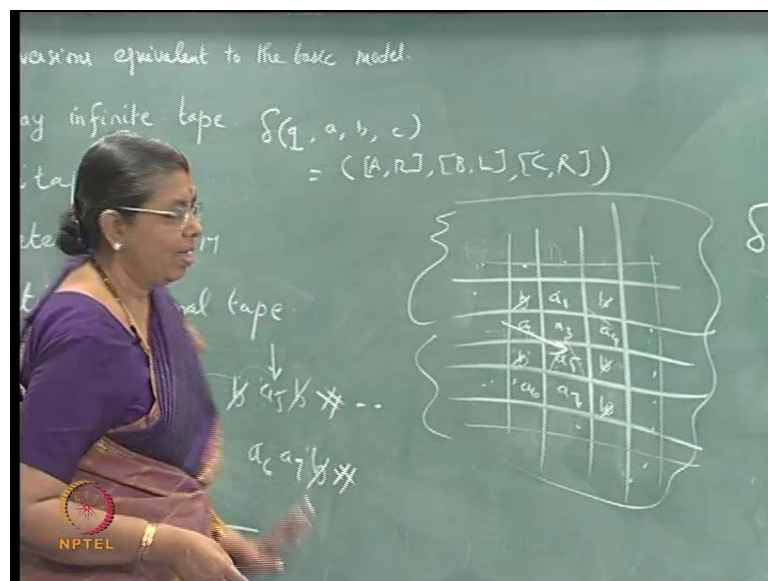


So, the number will be too much it will be the time will increase exponentially you can simulate a non deterministic turing machine with a deterministic turing machine, but the time will increase exponentially, but the language acceptance power is not changed whatever you can do with non deterministic turing machine you can do deterministic with the deterministic turing machine. Whereas in the case of push down automata there are languages which cannot be accepted by deterministic turing machine, but here any type zero language can be accepted by a deterministic turing machine it can be accepted by a non deterministic turing machine. As far as language acceptance power is considered they are equivalent, but the difference comes in the number of moves.

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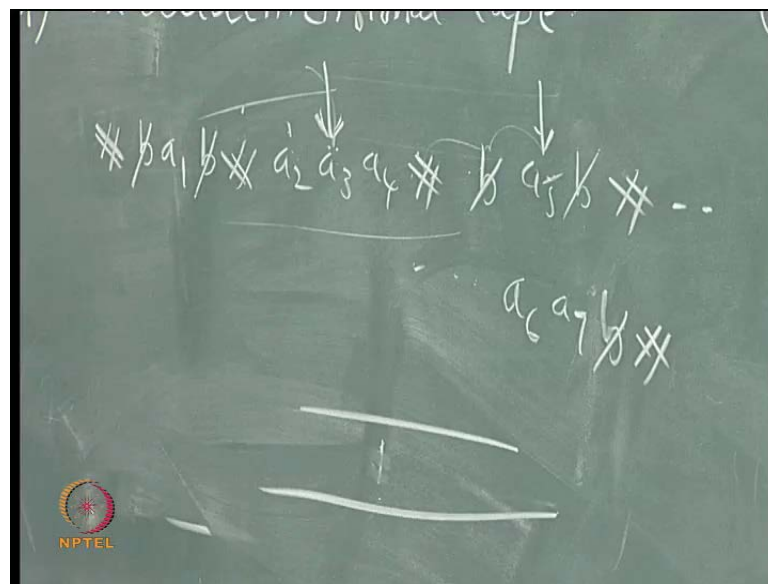
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So, this is another generalization another is multidimensional tapes I will consider two dimensional tape you can also have three dimensional tape in fact abstract way you can even think of k dimensional tape. So, when you have a two dimensional tapes suppose this is input a 1, a 2, a 3, a 4, a 5, a 6, a 7 this is the input. The tape is infinite in this direction, in this direction, in this direction and the tape head will be reading one cell after reading that symbol it can change that symbol and then move left right up or down. So, the mapping will be from it will be of this form P, A, L, R, U, D it can move left, right, up, down.

Thus it give a additional power **will this give additional power**, but will it will not give additional power,because this one suppose this is the portion non blank portion this is blank, this is blank,this is blank,this is blank,So, this can be represented by say somehash blank,a 1 blank, hash,a 2, a 3, a 4,hash blank, a 5 blank,hash, a 6,a 7hash this is continuationsame tape.You can write it like this a 6, a 7 blankso, the whole thing you can write as strings within the hash mark each row you can write like this.

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So, if you are reading a symbol a 5 the tape head will be here and after reading a 5 if you want to move left you can move left or move right hereno problem,if you want to move up or down how will you do? the tape suppose after reading a 5 you have to move up you have to go to a 3how will you do thatin the secondtape there will be this can be contained in one tape in the second tape when you move like this youhave a counter whichisincrements and say that you have movedtwo cellsthen when you go to the left one if it is move up means left block you go, then reach this hash symbol move two cells to the right that will show that you have to be in a three.

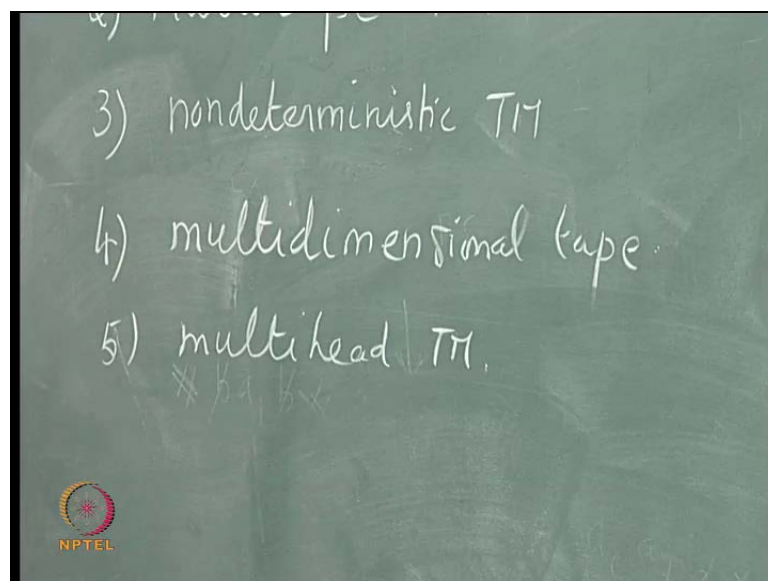
If you have to move from here to here when you move this head in this direction how many cells you have moved to reach this hash you keep a count in another tape and then move to the next hash symbol then by the same amount of same number you move the tape head to the right that means the tape head position is changed accordingly.Similarly, if you move down instead of moving to the left block you will move to the right block

that is one thing then suppose you are here and you move right that means you have to add a column one more column you may have to add one more column or one more row or up or one more row left.

If we are going to add one more row up you have to create one new block on the left if you are going to create one more row down you have to create one more block to the right, if you are going to create one more column to the left each block you introduce one blank and use the technique of shifting over. You know how to shift the symbols to the left or to the right make use of that and create one blank symbol in every block to the left, if you are creating one column to the right shift again and then create one blank at the end of the row.

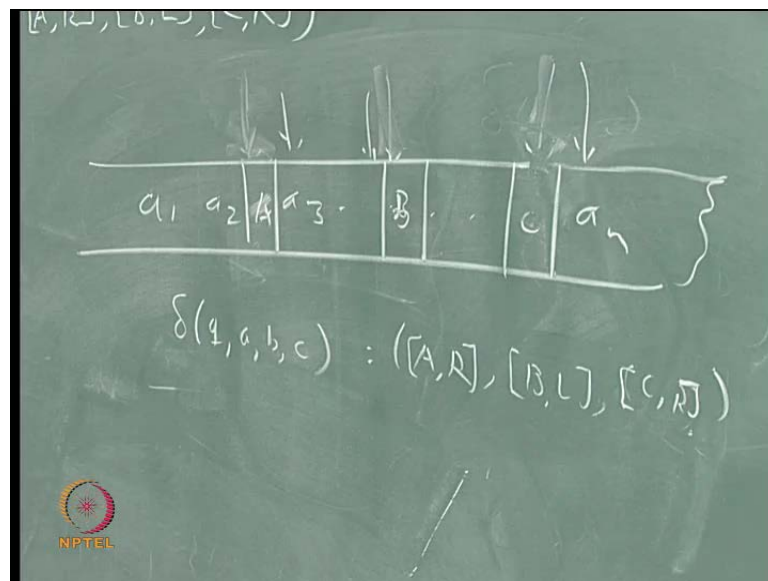
So, whatever you can do with the two dimensional tape we can do with one dimensional tape, but the number of moves will be more this number that will not be just, but it will not be exponentially increased. There will be more moves if you want to specially if you want to create a new column you have to do a lot of things, but it will not be as bad as simulating a non deterministic Turing machine with the deterministic Turing machine. So, this is two dimensional tape we can have a three dimensional tape where you can move left, right, up, down or this way or this way. Six possibilities will be therein an abstract manner you can even think of k dimensional tapes, this is another variation.

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Then multi head Turing machines

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If you have only one tape, but there may be many heads three heads reading the symbols a, b and c. Now depending on the symbol read state again the move will be like this delta of q, a, b, c is some A move right, B move left and so on C move right. So, depending upon these symbols it will print aA and move right print a symbol and move left print a symbol and move right and so on.

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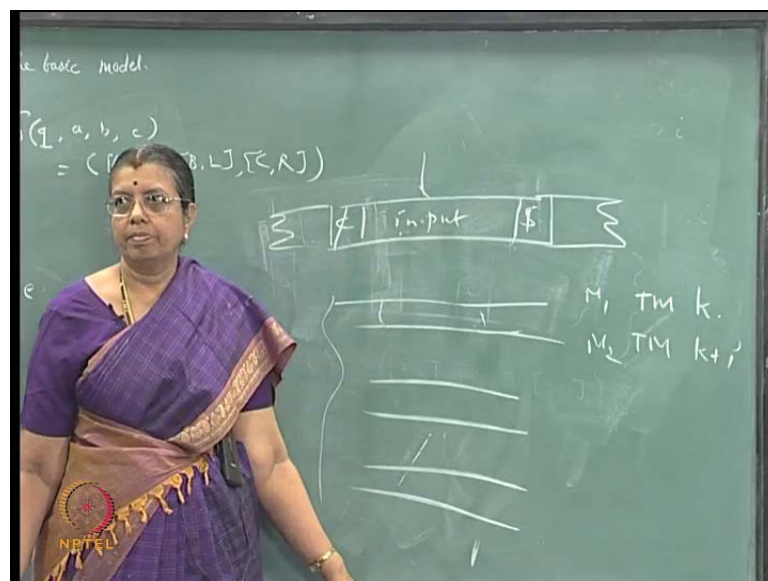


Now how can this be simulated multi track again the same idea of multi track if you are having k heads you will have k plus 1 track. Suppose I have three heads input will be therein the first track and the tape head position will be marked first tape head position will be marked in the second track, second head portion will be marked on the and so on. Again in a similar making a left right move right to left move we can simulate the behaviour. There is one small point you have to note here what that is?

Conflict.

If there is a conflict. Suppose tape head two and three read the same symbol then which one will you follow? move up the second head or third head you have to rewrite and move right head can move left or right does not matter, but a symbol rewriting how will you do that you must specify some priority in that case, second head will have higher priority than the third one and so on. Some priority has to be specified so, you can simulate a multi head turing machine with the single head turing machine.

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Then offline turing machines, what is an offline turing machine? offline turing machine is a turing machine where the input is given in one tape and it is read only there is one tape which keeps the input with markers and there will be other it is a multi tape turing machine there will be other tapes, but the input is read only you can only this on this tape the head only moves this way it cannot move beyond this it cannot move beyond that

other tapes you can do for computation. So, this is a particular case of multi tape turing machine.

So, obviously it can be simulated by a single tape turing machine another thing is whatever you can do with a single tape turing machine you can do with an offline turing machine any turing machine is you have the input and then one more tape suppose there is a multi tape turing machine with k tapes to make it offline have a turing machine with $k + 1$ tapes, copy this on to this input then afterwards you do not bother while copying only use this copy this onto this and in this k tapes you be simulate the behaviour of the first machine.

So, you have a turing machine with k tapes M_1 you want to make it offline M_2 will have one more tape which contains the input first stage is to copy this input on to this then just behave like M_1 , if it accepts it will accept if it does not accept it will does not accept. So, this way you can simulate a simulator of any multi tape turing machine by an offline turing machine. Now these are some of the generalized versions see you are making the machine more general and then you are saying that it is still is equivalent to the basic model. Now you can also have restricted version some restricted versions of turing machines which have the same power as the original turing machines. We shall consider them next and also you can look at the turing machine as a generating device.


So, far we have considered the turing machine as an accepting device or a computing device. We can also look at the turing machine as a generating device you have a tape output tape in which 1 by 1 the words will be printed between some marker symbols and because you are able to do that that is why it is called a recursively enumerable set the language accepted is usually called a recursively enumerable, because you can innumerate the strings using an output tape.

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Construct a TM M with a 2-dimensional tape. M starts with input

$$\begin{array}{ccccccc} b & b & b & b & \dots & b & b & b & b \\ b & X & X & X & \dots & X & X & X & b \\ b & b & b & b & \dots & b & b & b & b \end{array}$$

i.e., a row of n x 's surrounded by blanks. It has to halt with the final output.

$$\begin{array}{ccccccc} b & b & b & \dots & b & b & b \\ b & b & X & \dots & X & b & b \\ b & X & & \dots & & X & b \\ b & b & X & \dots & X & b & b \\ b & b & b & \dots & b & b & b \end{array}$$


So, we shall study about this later in the next lectures. So, we have seen that there are several generalized versions of Turing machine. As an example, we will consider a Turing machine with a two-dimensional tape. The problem is like this: Construct a Turing machine M with a two-dimensional tape and it has the input like this: a row of n X 's and finally, you want a pattern like this: that is the row of n X 's preceded by a row of n minus $2X$'s and followed by a row of n minus $2X$'s. So, you want to generate this pattern. From this pattern, this is our idea and you want to construct a Turing machine for this. You know that a two-dimensional tape Turing machine has got four types of moves depending upon the state and the symbol read: it can move left, it can move right, it can move up or it can move down. Four types of moves are possible.


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i.e., above and below the row of n X's, a row of $(n-2)$ X's is printed, centrally adjusted.

Solution


$$K = \{q_0, \dots, q_{11}\}$$
$$\Gamma = \{X, Y, \emptyset\}$$

δ is given by

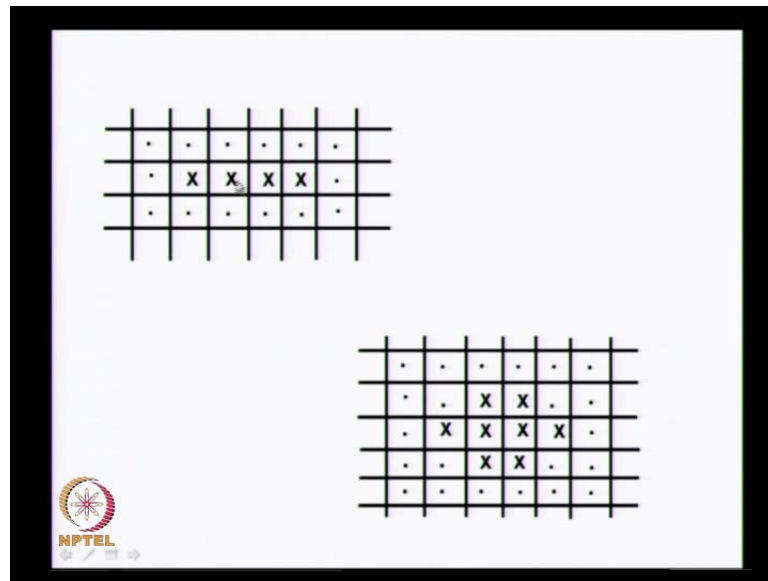
$$\delta(q_0, X) = (q_1, Y, R)$$
$$\delta(q_1, X) = (q_2, Y, U)$$
$$\delta(q_2, \emptyset) = (q_3, X, D)$$


So, with this idea let us see how we can obtain this pattern from this pattern. So, the corresponding Turing machine has 12 states q_0 to q_{11} , q_0 is the initial state we use three symbols X , Y and blank \emptyset . X is occurring in the pattern the blanks are denoted by dot in the figure in the two dimensional tape we denote by a dot the symbol blank. The mappings are given by this we will see how we are using the mappings.

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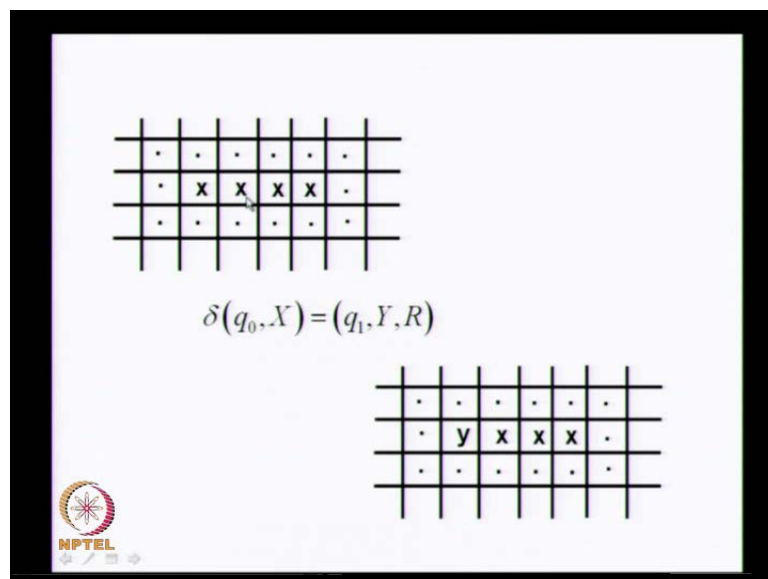
$$\delta(q_3, Y) = (q_4, Y, D) \quad \delta(q_9, X) = (q_{10}, \emptyset, U)$$
$$\delta(q_4, \emptyset) = (q_5, X, U) \quad \delta(q_{10}, Y) = (q_{10}, X, L)$$
$$\delta(q_5, Y) = (q_1, Y, R) \quad \delta(q_{10}, \emptyset) = (q_{11}, \emptyset, \text{halt})$$
$$\delta(q_1, \emptyset) = (q_6, \emptyset, L)$$
$$\delta(q_6, Y) = (q_7, Y, U)$$
$$\delta(q_7, X) = (q_8, \emptyset, D)$$
$$\delta(q_8, Y) = (q_9, Y, D)$$


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So, some more mappings these are the mappings which define the moves of the Turing machine. So, let us consider a pattern where you have 4X's initially the machine begins in this position in the state q_{naught} and it ends here after printing 2X's above and 2X's below. So, it ends up with this pattern and a halting position is this it starts with the initial state in this position. Let us see how we get this pattern from this pattern.

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$\delta(q_1, X) = (q_2, Y, U)$

So, initially we have this position the tape head is here and the mapping used is delta of q naught, X's equal to q 1, Y, R. So, it changes this x into a y and moves right, now the tape head is in this position the second mapping is delta of q 1, X is equal to q 2, Y, U. The second x it changes this into ay and moves up so, the next situation is this x has been changed to y and the tape head is in this position. Now we want it to print a x here we also want to print a x here, let us see how this happens now the tape head is here and the state is q 2 the move is given by this mapping delta of q 2, blank is q 3, X, D. So, it prints a x over this blank and then moves down.

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$\delta(q_2, \text{blank}) = (q_3, X, D)$

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The slide displays a transition function $\delta(q_3, Y) = (q_4, Y, D)$. Above the equation is a 6x6 grid with the following content:

| | | | | | |
|---|---|---|---|---|---|
| . | . | . | . | . | . |
| . | . | x | . | . | . |
| . | y | y | x | x | . |
| . | . | . | . | . | . |
| . | . | . | . | . | . |
| . | . | . | . | . | . |

Below the equation is another 6x6 grid, identical to the one above, with an arrow pointing from the 'y' in the third row, second column to the 'y' in the third row, third column.

The NPTEL logo is visible in the bottom left corner.

So, the next stage it prints a blank x here and then moves down. So, the tape head position is here now so, the tape head position is here and the map used is this delta of q 3, Y is equal to q 4, Y, D. It does not change this y, but then moves down in state q 4. So, its tape head position is here and in q 4 it reads a blank here and then goes to state q 5 changes the blank into X and moves up.

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The slide displays a transition function $\delta(q_4, \text{blank}) = (q_5, X, U)$. Above the equation is a 6x6 grid with the following content:

| | | | | | |
|---|---|---|---|---|---|
| . | . | . | . | . | . |
| . | . | x | . | . | . |
| . | y | y | x | x | . |
| . | . | . | . | . | . |
| . | . | . | . | . | . |
| . | . | . | . | . | . |

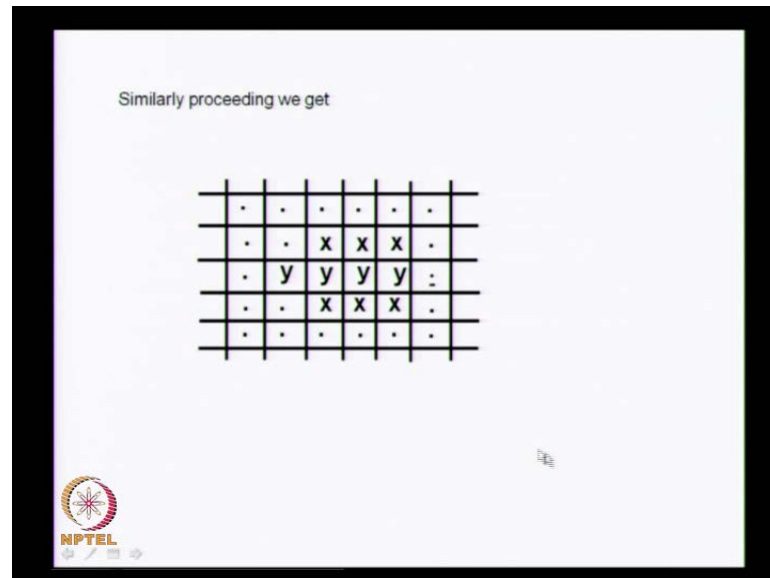
Below the equation is another 6x6 grid, identical to the one above, with an arrow pointing from the 'x' in the second row, third column to the 'x' in the third row, third column.

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So, at this stage it prints a x and moves up here so, in this column it initially changes the x into a y and then moved up printed a x moved down again moved down printed a x and it

came to this position. Now moving to the right it does the same thing in the next column and in the last column also though we do not want x initially it prints a x and then afterwards it starts it erases this x and this x.

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So, moving to the right and repeating the same thing it prints a x above this and below this changing the x into a y similarly, changing this x into a y it prints a x above and x below. Now when it moves right it does not see a x, but it sees a blank now it knows that it has come to the end of the first row of x's and so, it moves left and erases this x and erases this x.

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Using $\delta(q_1, b) = (q_6, b, L)$

| | | | | | |
|---|---|---|---|---|---|
| . | . | . | . | . | . |
| . | . | x | x | x | . |
| . | y | y | y | y | . |
| . | . | x | x | x | . |

It erases the last X's using

$$\delta(q_7, X) = (q_8, b, D)$$

and

$$\delta(q_9, X) = (q_{10}, b, U)$$


So, that is done by this mapping when it sees a blank here it moves left and then it moves up and then it erases this x using this mapping coming down here and then going down here it erases this x and goes up. Now these 2x's have been erased and the tape head is here, but this whole of this is y and we want to change the y's into a x that is done by this mapping.


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| | | | | | |
|---|---|---|---|---|---|
| . | . | . | . | . | . |
| . | . | x | x | . | . |
| . | y | y | y | y | . |
| . | . | x | x | . | . |
| . | . | . | . | . | . |

State q_{10}

In q_{10} it changes the Y's into X's moving left and halts on seeing a blank. Thus the final pattern is

| | | | | | |
|---|---|---|---|---|---|
| . | . | . | . | . | . |
| . | . | x | x | . | . |
| . | x | x | x | x | . |
| . | . | x | x | . | . |
| . | . | . | . | . | . |



The last one and so after changing the y's into a x we get this pattern in q_{10} it changes the Y's into X's moving left it keeps on doing this and when it sees this blank it knows that

it has exhausted the rows with which it started position and halts on seeing a blank thus the final pattern is this way, we can get a pattern from another pattern this is a very simple example just to illustrate how a two dimensional tape turing machine works.