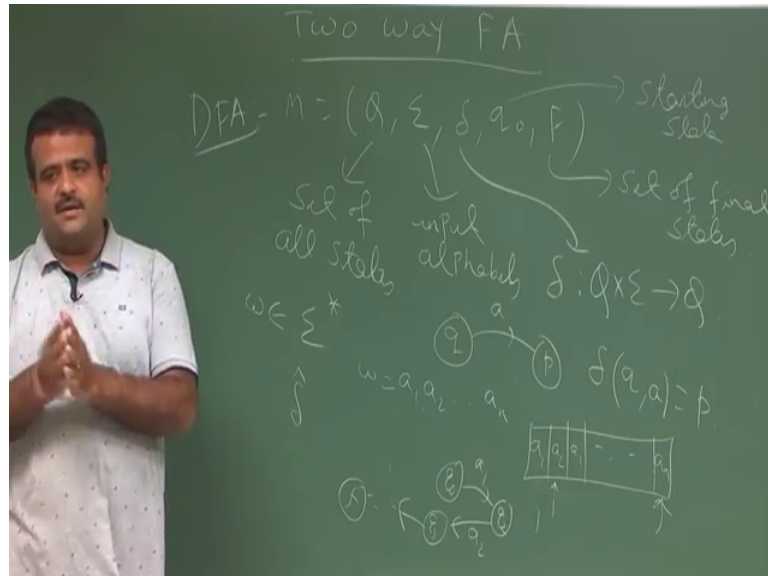


Introduction to Automata, Languages and Computation
Prof. Sourav Mukhopadhyay
Department of Mathematics
Indian Institute of Technology, Kharagpur

Lecture – 33
Two Way FA

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So we are will start the concept of Two Way DFA, two way finite automata. Two way means so far we have seen given a finite automata say DFA, NFA suppose you have given a DFA which is $Q, \Sigma, \delta, q_0, F$ and the Q is set of all; set of all states and this is the input alphabet, all are finite and this is the transition rule. For DFA it is, if it is DFA transition rule is like this δ is a function from $Q \times \Sigma$ to Q .

So, given a state suppose we are at state q and suppose you are reading a input alphabet a will go to state p . So, $\delta(q, a) = p$ this is for deterministic move this for DFA, but in case of NFA the move is non deterministic, we cannot define we cannot have a definite p , I mean there is a option; I mean this move is not deterministic it is a non deterministic that is why.

And this we know is the starting state or the initial state and this is the set of all final state final states and there may be one or more or many final states, but starting state is 1. Our automata our finite automata is starting from a one starting state there is that is

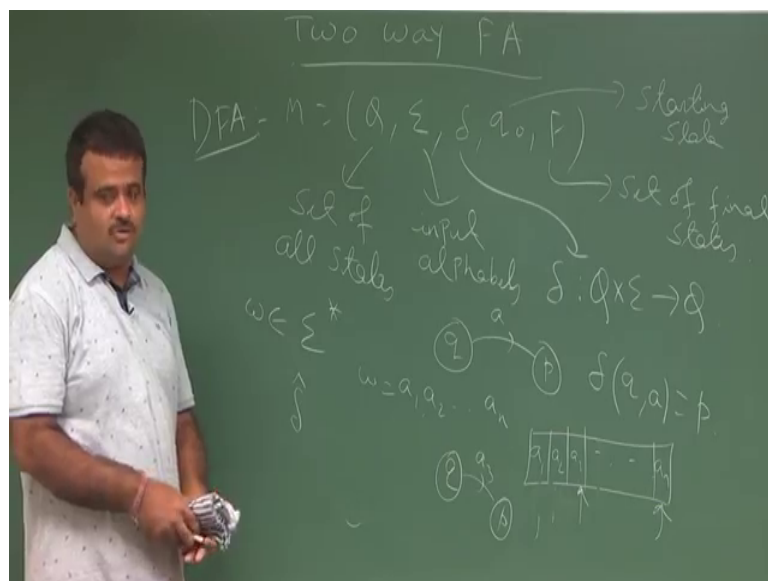
represented by q_0 . So, far what we are, how to read a string? Suppose we have a string which consists of the input alphabets.

So, this is what we do we, suppose w is $a_1 a_2 \dots a_n$ implementing. So, how to read this? So, we use the extended delta to read this. So what we do? We put the string in a tape $a_1 a_2 a_3$ like this and we start our automata at q_0 state and our tape is heading like this and every time we are moving the tape right wise. So, that is only one way it is the movement so, tape is moving tape head tape head is moving only one direction right side.

So, first it will read the delta of so suppose with a_1 it is go to some q_2 or q_1 with again it will move to here like this. So, again with a_2 from q_2 we are going to q_3 like this. So, finally, with a_n if we are reaching to some of the state say f and if f is happened to be a final state, then we say this is the accepted string. So, this will know about the finite automata.

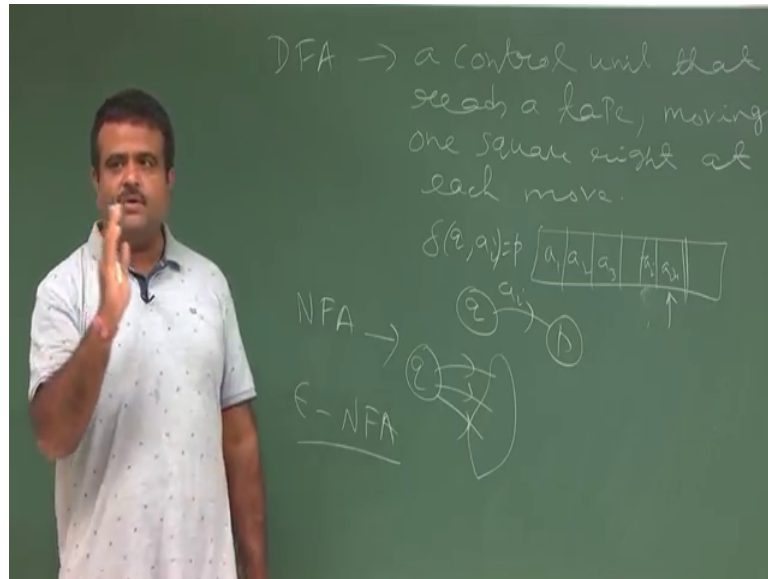
So, this the tape is moving only one direction so right side, it has no two way moving so tape head header this is the header of the tape. So, header of the tape we are reading that string left to right like this. So tape is at each point of time tape is moving from left to right ok. But in case of two way automata, tape can move left also. So it can suppose we are here and our present state is say our present state is say q and we are here.

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Now, with this input a 3 we can go to either the tape can go point to here or point to there and it will move to some state p that is ok, but the tape header can go to right side or left side so there is a option there, so that that is the sense it is called two a. So, we will formally define that two a finite automata, this is which is something different so far we have seen.

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So, let us just recap. So we have seen the DFA which is a control unit DFA has a control unit that read the tape from left to right, tape that read the tape from they read the tape and it is moving one square; and it is moving one square right at each move each move. So; that means, given a tape we have given this a 1 a 2 this is the 6 string say a i and suppose at some point of time, tape header is pointing there.

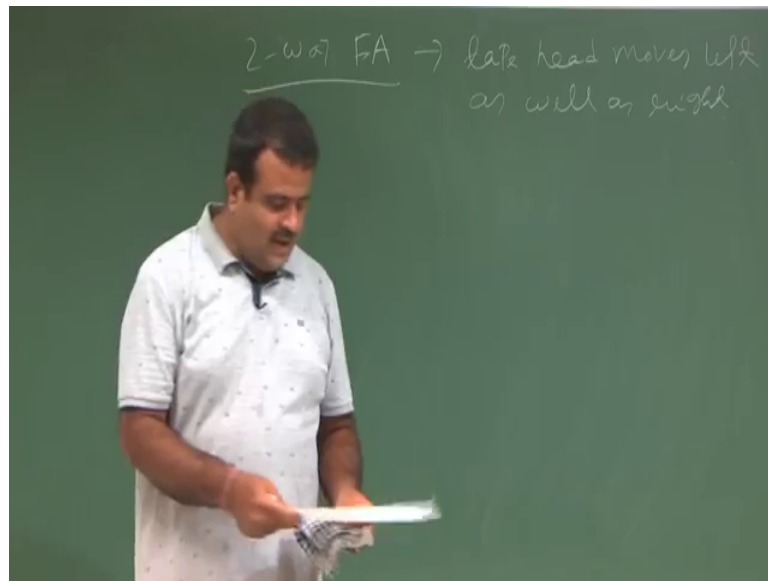
So, suppose at that point we are at state q . Now it will go to so suppose $\delta(q, a_i)$ is say p . So, it will go to state p and the header will move to the next a_{i+1} ; next input of the of the string. So it is moving one square right at each time. So, there is no move the in the left side which is there in that two a automata.

And then we have seen the NFA. NFA is basically the it is a it is also finite automata with one side move and only difference is the non deterministic; the move in move is non deterministic. So, from q with the same input we have many options so this move is non deterministic and then we have seen the epsilon NFA. Epsilon NFA is the tape head

moves without reading the input symbol. So, without reading the input symbol we can move the we can change the state so that is the epsilon NFA.

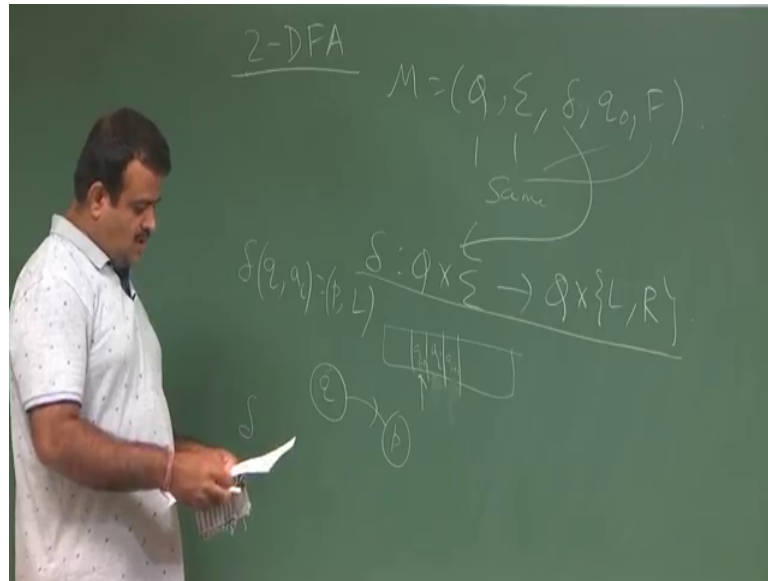
Tape is pointing header is pointing somewhere, but we are not reading that symbol without reading the symbol the state can move our automata can I mean. Now 2 way DFA is 2 way finite automata is basically we have movement both the side 2 way finite automata.

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So, in this case the tape head; the tape head moves left as well as right. So, that is the that is called two way finite automata so we have a option to go to left or right. So, its increased little more power than the conventional finite automata which is, but eventually it will accept the I mean it will give the same regular set. There is no I mean in terms of language there is no benefit of having this so eventually, it will accept the regular sets only. So, let us define the two way deterministic finite automata [noise].

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So, this is called 2 DFA; Two way Deterministic Finite Automata. So, it is basically M tuple a five tuple again Q, δ, q_0, f , we know all this symbol Q is the set of set of finite number of states possible all possible state which is finite and the Σ is the input alphabet and δ is the transition rule. But here we have a option to move left or right the tape head next step and q_0 is the starting state and f is the set of final states.

So, those are all the things, so these are same; these are same as earlier all the differences here this is different. So, this is now a function to it will go to another state, but the movement so, tape head movement will be either left or right so, that we have to point out L or R ok.

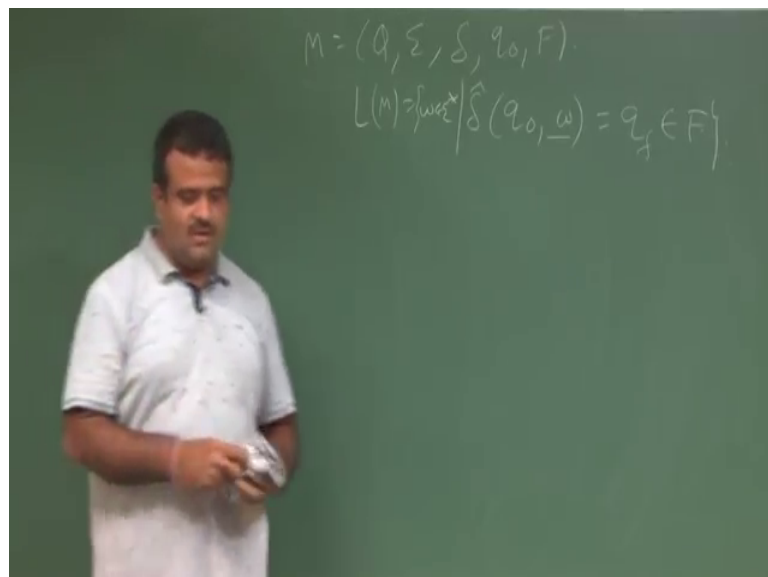
So, suppose we are we are just here a_i and this is say a_{i+1} a_{i-1} and a_i suppose it is pointing. So suppose at that point of time we are at state q . Now here suppose $\delta(q, a_i)$ so now, this is a output will be a state along with a the sign I mean movement of the taper tape head; it will either go to left side or right side.

So, if it is p, R p is a state so, it will go to p and the tape head will point to the next it is going to the right. But if it is but if it is p, L ; p, L so, it will go to p , but tape head will point to this that is the difference. So, tape head for the next move will point to this, so again you have to scan this. So, it is like movement of the head.

So, we may eventually sometimes we may we may put into the infinite loop; so that is why when you talk about Turing machine whether Turing machine will halted or not. So, depending on the movement over here we may eventually end up with an infinite loop, we go then a comeback, go come back like this ok. So, this is the only difference; so this is the only difference in the function transition function or transition rule ok.

So, in that case how we define the language of this two way DFA so you have given a two way DFA. So, for one way DFA we know how to for one way DFA this is our DFA q_0 f .

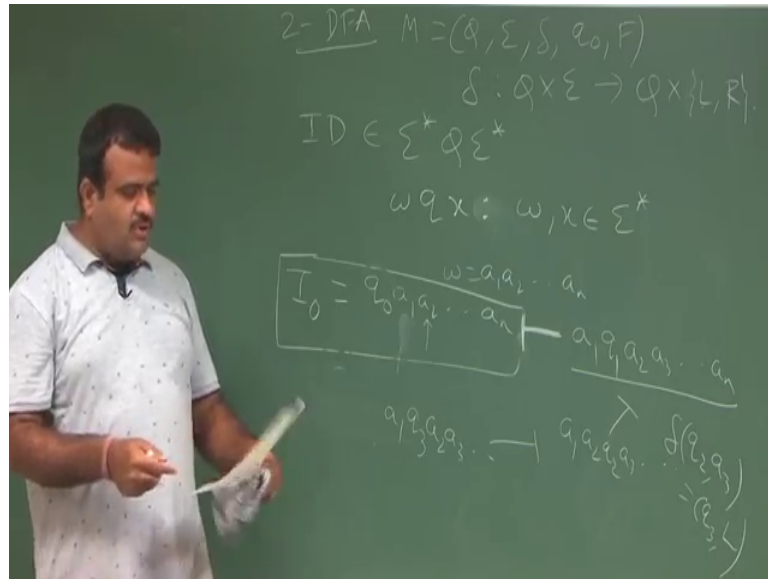
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Now, for one way DFA what we did? We extend this delta to delta hat; that means, which is accepting the string and then we start with q_0 and if w we read and if it ends up with some f or q_f which belongs to F , then we say this is the set of I mean this is the language of this M say for all w such that this happened ok.

Now, now we are in two way DFA. So for two way DFA extending this delta hat is insufficient I mean it is not I mean we because you are moving left to right again. So in that case what we will do we will take help of what is called Instantaneous Description or ID. So, it is basically a snapshot of the process, then in the next move the snapshot of the process again like this. So, we will define the ID or Instantaneous Description of the finite automata.

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So, we have given a two way DFA M which is Q sigma delta q_0 , f and we know here delta is Q cross Σ comma R so our tape head can move to the left to right left or right ok. So, M is the two way DFA. So, ID or instantaneous description is basically of the form is coming from this q sigma star ok. So, basically it is of the form $w q x$ so w is w , x are coming from; w, x are coming from this is $w x$ are coming from this sigma these are all string.

And q is the state that is that point of time state the starting I mean it is not starting state starting state is q_0 . So, at some point of time this is the snapshot of the system of the automata of the finite machine. So, like for initially what you have? We have given a tape, we have given a string say w ; w is a_1, a_2 say a_n and initially ours automata is at state q_0 .

So, this is the initial ID $q_0 a_1 a_2 a_n$ this is the initial ID of the this is the I_0 we can say. This is the initial ID of the M because initially we are at q_0 this is nothing, but a snapshot we are taking a photo of the present situation of this system of this machine finite machine. So, at the starting we are at q_0 our tape this is the position of containing the tape position and our header is here ok. So, header will be pointing always the right side of this q_0 that is the convention will follow.

Now if it is say for example, after this suppose we start with q_0 and suppose our delta is like this so, a_1 and say it is going to q_1 and it is right say. So, what will happen? So, it

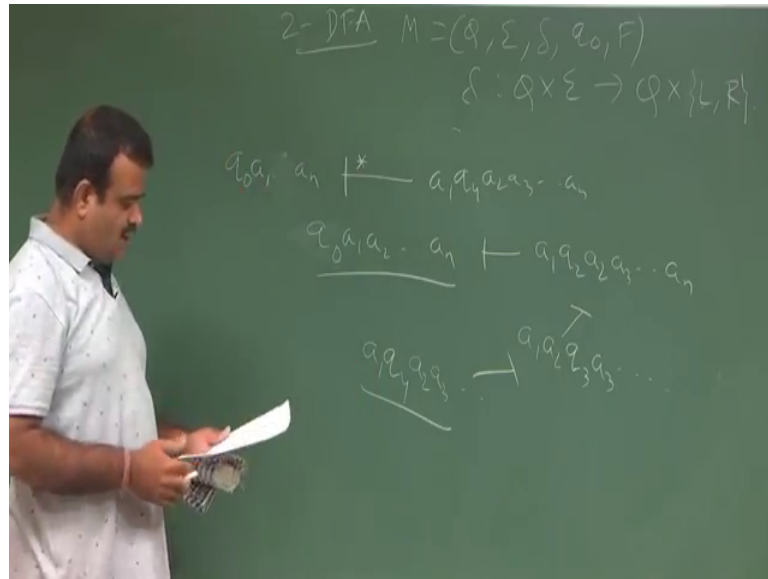
is going to basically we can say this is going to. So, next so what is the next position? So, now, the next position is we are at q_1 and our tape is moving right so tape is here. So, we will write this a_1 then q_1 , now we are at q_1 because our state change to q_1 and next you have to read $a_2 a_3$ and this is the way.

So, this we can say this is the current snapshot or current ID of the machine and this will say by this is going here like this symbol. So, this is the initial instant initial instead ID and this is the next ID if the our delta is like this ok. Now suppose in the next time if it is going to q_2 and if the right, then it will go to again it will go to say it will go to $a_1 a_2$ say $q_2 a_3$ like this. Now suppose so, again you have to read the symbol which is write to q_2 .

Now suppose so now, we are going to read q_3 , now suppose if delta of $q_2 q_3$ is q_3 but if it is left; if the header is pointing to the lefts then where it will go, then the header will be pointing left; that means, you have to read here. So; that means, this state will be pointing here and the state is q_3 . So, this will now go to like this a_1 then $q_3 a_2 a_3$ like this. So, because that is the next state is next symbol is q_2 which we are going to this is the this is the wherever we are putting the state, the next symbol is the pointing the tape head so that is the conventional will follow.

So, this is going there because next we are going to read again q_2 , since it is a left moved over here. So, this is the way we take the snapshot of the finite machine and we go to that from one state to one state to another state like this ok. So, now, when we say yeah so when we say we are accepting a string.

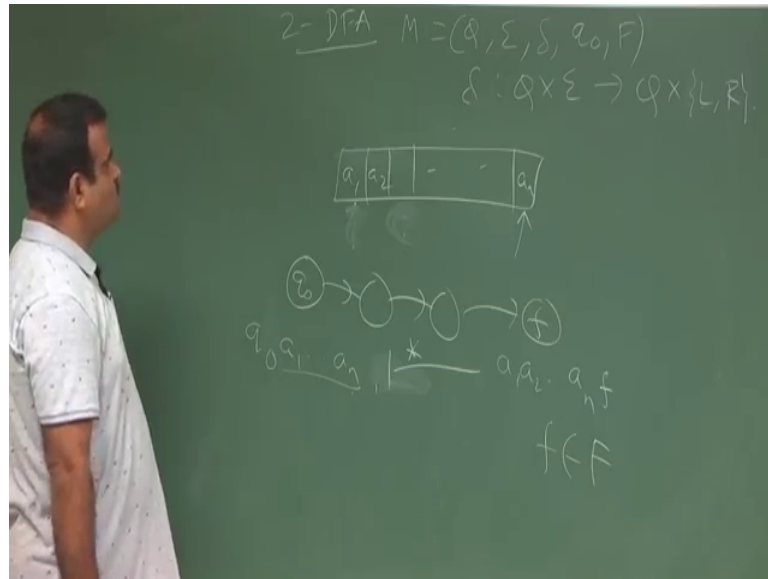
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So if we so, this star means if we apply this recursively then it will give us a star so; that means, if 1 push or suppose a 1. So, initially it is $q_0 a_1 a_2 a_3 \dots a_n$ say. Now suppose next step will going to say a 1 $q_2 a_2 a_3 \dots a_n$. Suppose in next step we are going to a 1 $a_2 q_3 a_3$ like this, suppose in next step our tape is pointing to the left side so; that means, insert so after reading this we have to read this. So, that means, and suppose it is going to q_4 , so $q_1 q_4$ our current state, but we have to this q_2 will be the next symbol to be read I mean header is pointing to there because it is a left move a 2 a 3 like this.

So, now this means this is this id is going to this id by more than one operation of the transition so that is the star so; that means, you can say $q_0 a_1 a_2 a_3 \dots a_n$ is going to a 1 $q_4 a_2 a_3 a_n$ so this is the star. So, by this using the star we can just define the language accepted by this. So, when you say a language accepted by this if eventually it will reach to a final state and all string has been explore; that means, if eventually we can reach to like this.

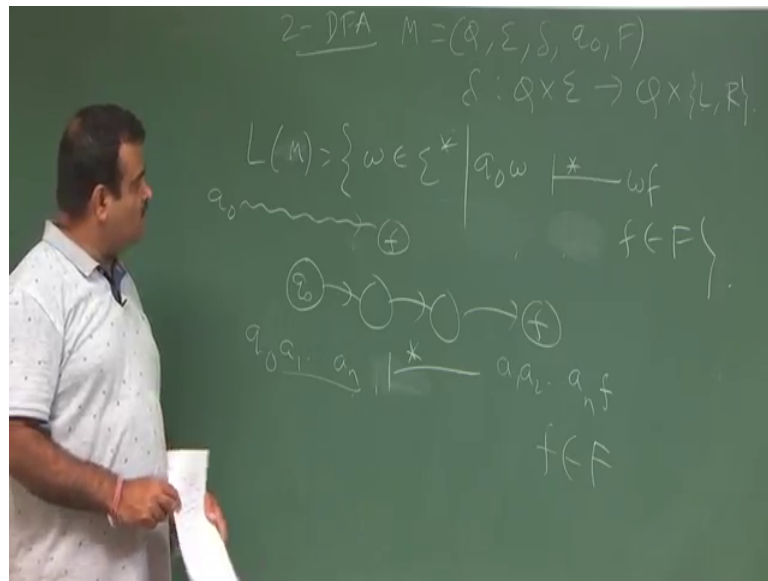
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So, suppose we are starting with a one a two suppose we put this in a tape a 1 a 2 a n and we keep on reading you start with q 0, we read the tape will go to some state some state and tape will move here and there like this. Now suppose at the end we reach to the some of the state f and if it is happened to be a final state.

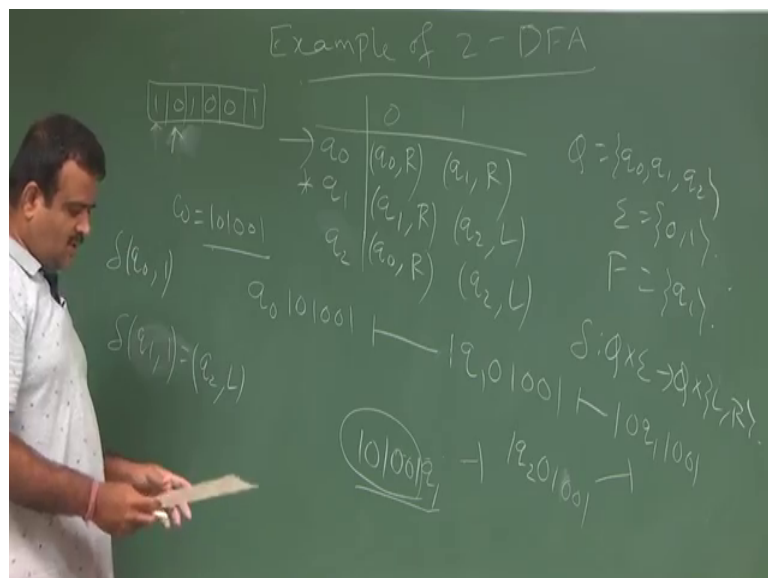
And if we exhaust of reading all these symbols then and if we exhaust to reading all the symbols means then what is the position there at the end at the end it will be a 1 a 2 a n and f will be pointing here that is one. So; that means, if q 0 a 1 a n if it is going to this where f is a final state, then we show a this string is accepted by this two way DFA. So, this set we are this set is our language so, we can formally define this.

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So, language of the same is nothing, but set of all w such that $q_0 w$ we will end up with a f , for some state f belongs to or some state I mean that should be at least I mean for some state f belongs to this. So, that means, we start with q_0 and eventually will reach to f and we exhaust thereading that tape ok. So, tape header is just reach to the end of the string. So, then we stop and we say this string is accepted by this DFA. Now we will take an example.

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So, let us take an quick example, suppose we have given this two way DFA we have two input alphabet 0 and 1 and these are the state q_1 q_2 q_0 q_1 q_2 and this is the starting state and this is a final state ok.

Now, delta we have to define so Q is basically q_0 q_1 q_2 and Σ is 0 1 and f is q_1 and delta we have to define. So, delta is basically a function form $q \times \Sigma \rightarrow Q$ ok. So, if we add q_0 , then with the input 0 will go to q_0 and it will be R and this is q_1 and it will be R again and with q_1 with 0 input is go to q_1 it will be R, q_2 it will be L and same q_0 , R I mean with q_2 R and with q_2 here at q_1 ok.

So, this is the transition rule and here we are indicating the next position of the tape after reaching to that state. Now if we want to see if we want to read a string say w which is 101001, then how to read so we start with q_0 and we put the w over here this is the initial idea of the initial position we are at q_0 and our tape is tape is this 1 0 1 0 0 1 this is the tape and we are header is pointing here. So, if the header is pointing here, so we have to read that delta of q_0 1.

So, delta of q_0 1 is basically q_1 L so L means header will go here so, this is basically one we have exhaust. So this will be now q_1 and header is pointing this so this is 1. So, now, next so now, we are at; now we are at q_1 ; we are at q_1 and we are reading the 0 so we are at q_1 you are reading 0 so we will go to again q_1 and header will be moved to right so header will move here and we will again go to q_1 .

So, that will be 1 0 q_1 again 1 0 0 1 so like this. So, now, we are at q_1 now it is 1. So, now, header will move to the left so, this is the we are at q_1 so delta of q_1 1 now we are reading 1. So, this is again q_2 L so L means header will come back here. So, this will be basically this is going to q_2 , but we have to read this so 1 q_2 1 0 I sorry 0 0 0 1 like this.

So, if you continue like this we will end up with this 1 0 1 0 0 1 q_1 . So, you have to do little more step and eventually we will reach to this that is all. So, that; that means, we are reaching to this position means this string is accepted so this string belongs to L of G . So, this is one example where yeah where this is this is belongs to the language of this two way automata.

Thank you very much.