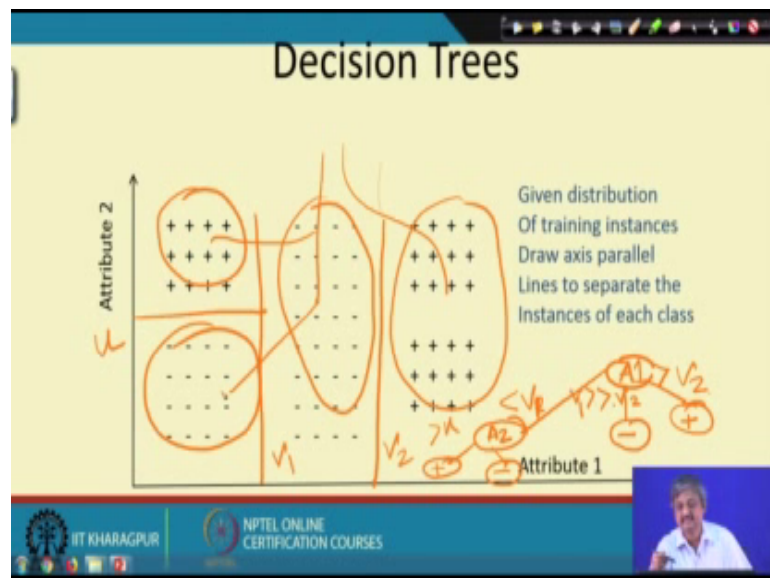


Data Mining
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Lecture - 10
Decision Tree - III

We continue our discussion on the Decision Tree.

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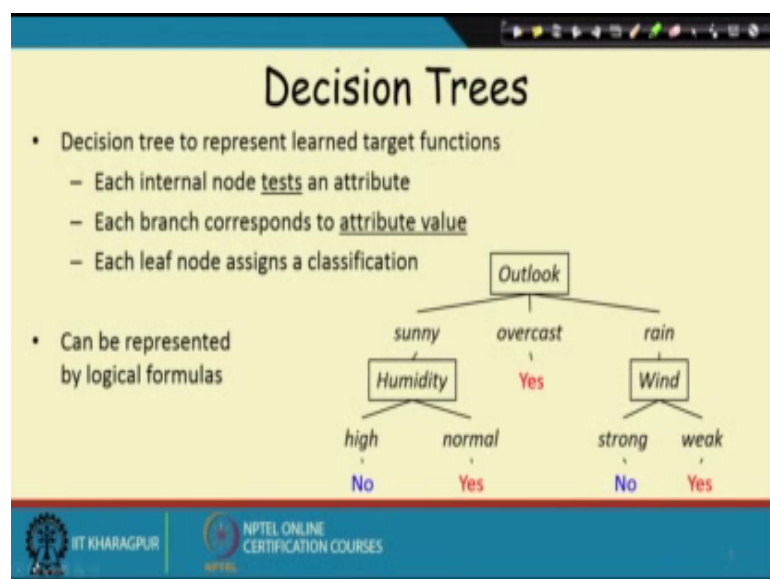
So, to recapitulate we have a training set. If we look at the examples, we have a training set where I have some examples and their corresponding class levels yes or no.

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Training Examples

Day	Outlook	Temp	Humidity	Wind	Tennis?
D1	Sunny	Hot	High	Weak	No
D2	Sunny	Hot	High	Strong	No
D3	Overcast	Hot	High	Weak	Yes
D4	Rain	Mild	High	Weak	Yes
D5	Rain	Cool	Normal	Weak	Yes
D6	Rain	Cool	Normal	Strong	No
D7	Overcast	Cool	Normal	Strong	Yes
D8	Sunny	Mild	High	Weak	No
D9	Sunny	Cool	Normal	Weak	Yes
D10	Rain	Mild	Normal	Weak	Yes
D11	Sunny	Mild	Normal	Strong	Yes
D12	Overcast	Mild	High	Strong	Yes
D13	Overcast	Hot	Normal	Weak	Yes
D14	Rain	Mild	High	Strong	No

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So, I want to construct a decision tree of a particular form, where each node is an attribute and each branch is a value of the attribute. The leaf nodes correspond to class.

So, if a example comes and if we check against the values of the each node, it will follow one of the branch and then we will check another attribute it will follow another branch, till it reaches the leaf. And every leaf is associated with a class in this case only 2 yes and no, and I will classify that example as belonging to that class. So, now, the question is how do we construct the decision tree; that means, which attribute should I check first

and then which attribute, then which attribute where do I stop all these are part of the decision tree construction. I will explain this with an sort of geometric example.

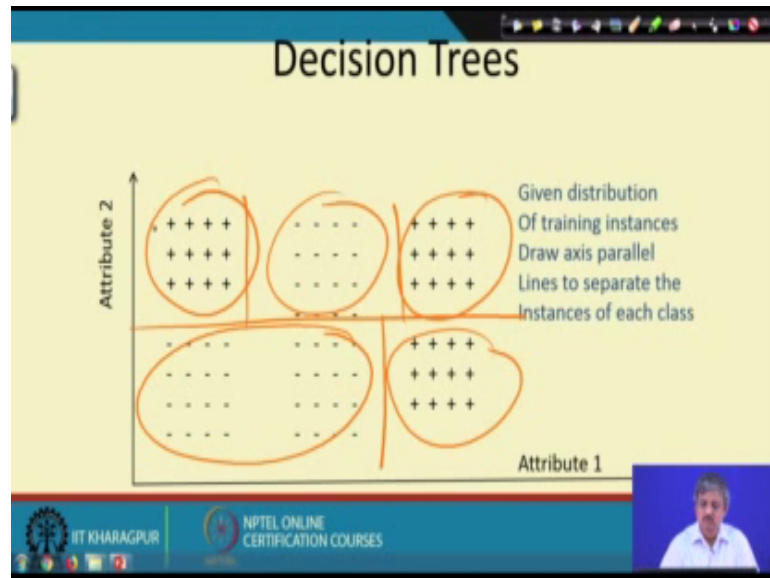
So, as I have told you before any instance can be described as a vector consisting of that actual values. So, if for example, we have 2 attributes, I can represent it by A^2 a every instance as A^2 dimensional vector. So, in this figure what I have is, I have a set of points in 2 dimension which are belonging to S class I mark them as plus and no class I mark them as minus. And what I do is that I construct a decision tree of this particular form where first I check attribute, I check the value of attribute one and suppose it is greater than some value, I say it is a leaf belonging to class.

And then I check if it is greater than some other value, and less than this value it is this region minus class and if it is less than this certain. So, I if I call this as V_1 V_2 , if it is greater than V_2 , if it is greater than V_2 , I say at this class between V_1 and V_2 between sorry the other way round it should be; between V_1 and V_2 this class and less than V_2 sorry less than V_1 I have messed up completely.

So, less than V_1 it is this part; if it is this part then I again check the value of attribute 2 because whereas, this region and this region contains only point from one class, I can infer that belong to that class, it is a mixed. So, I again check the value up attribute A_2 and let us say if it is above a value of u I check, if it is greater than u or less than u . If it is greater than u I call it as plus if it is less than you I call it as minus. So, the point to be noted is that you can visualize any decision tree as a set of axis parallel cuts, which split up the points training set points into small small regions.

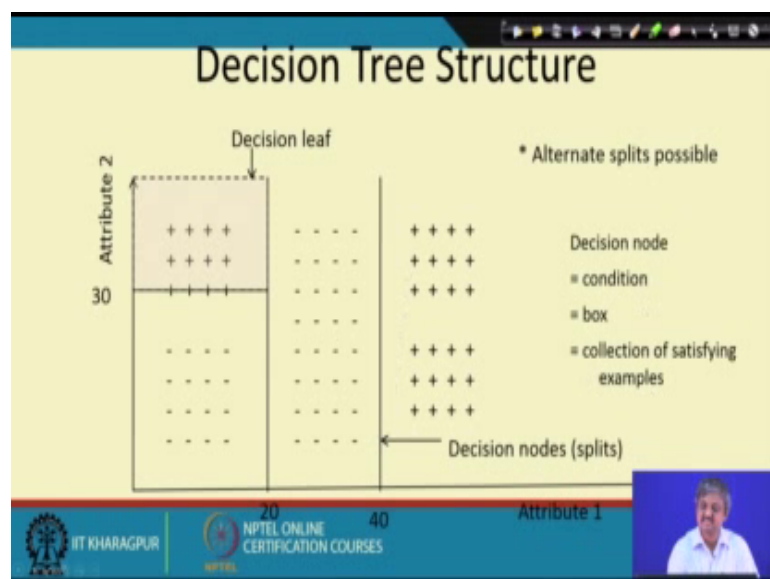
Finally leafs, they will be one of the region which I do not split further. So, this is a leaf because I do not split it further, this is a leaf I do not split, this is a leaf and this is a leaf, I do not split them further. And what I want is the points note that again if a new point x if I push down to that tree, I will just check these cuts and it will be falling in either in this region or this region or this region or this region a point will fall, I will check the values of attribute and decide. And if this regions are pure; that means, content points from a single class only I have a good decision tree. So, I could have as well drawn another decision tree say like this.

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I could have maybe first split on this, and then I could have split each of the region further on this and then on this and then on this, then also I get pure leaf classes. If we if you see it will be a slightly different decision tree; if we actually draw this tree you will see the previous tree was actually smaller cell one than this tree, it has less number of checks if conditions. So, I would prefer this tree. Now, I ask you the question that you tell me. So, this is what I have drawn.

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It so, this is my tree this is my decision leaf, note these values every decision nodes correspond to a condition a particular box, and a set up samples training samples which satisfy those conditions and fall in this box.

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Decision Tree Construction

- Find the best structure
- Given a training data set

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So this is my problem given a training set find the best structure.

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Top-Down Construction

- Start with empty tree
- Main loop:
 1. Split the "best" decision attribute (A) for next node
 2. Assign A as decision attribute for node
 3. For each value of A , create new descendant of node
 4. Sort training examples to leaf nodes
 5. If training examples perfectly classified, STOP, Else iterate over new leaf nodes
- Grow tree just deep enough for perfect classification
 - If possible (or can approximate at chosen depth)
- Which attribute is best?

Handwritten tree diagram showing a root node A_1 with children T_1 , A_2 , and A_3 . T_1 has children T_4 and T_5 . A_2 has child T_6 . A_3 has children A_4 and A_5 . A circled T is also present at the top right.

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I will follow this top down construction rule for doing this, what we do is start with an empty tree and then I define something called a best attribute, I will later explain what a best attribute means. So, I choose which attribute is the best that I choose as my leaf say

A 1 is the best attribute I choose as my leaf and I make branches for each different value of A1 I make a branch. So, again I will come back to another question that you might have already have is that suppose A 1 is continuous valued A 1 has a range of values say temperature or something then, how do I decide the branches. For the moment I will come back to that question later for the moment assumes that A 1 has only a discrete set of values in the domain. So, now, this is a decision attribute. So, if we look at the training examples, you say I call it as T, some of the examples will fall follow this branch satisfy this condition some examples will satisfy this condition, and some examples will satisfy this condition.

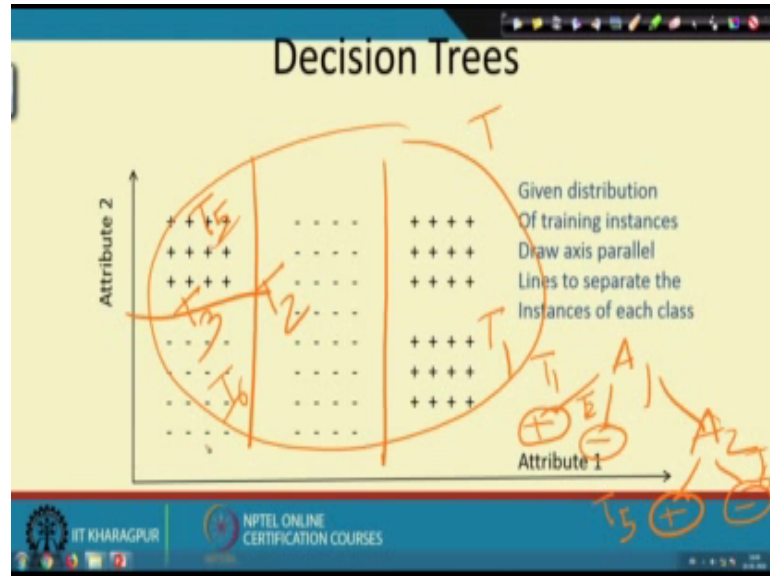
Now, as if I recursively carry on this. So, what I do, as if I start building a new tree here, but not using this T examples, I decide what is the next best node to split, again what is best and I am defining later. So, I find out an attribute which will be split this T 1 in the best possible way. To give you a hint this best possible way corresponds to the way the attribute which sort of discriminates 2 classes yes or no classes as much as possible, maybe A 2 and for here maybe it is A 3, and from here maybe it is A 4 or something.

And then this examples I split further and maybe I get T 5 T 4 set of examples, T 5 set of example, note that T 4 plus T 5 plus T 6 will give me T 1, similarly T 1 plus T 2 plus T 3 will give me all that (Refer Time: 10:24) examples T they are getting distributed among the nodes. Now if a particular branch all or if it this set of example T 5, belong to a single class I do not split it further and make this as a leaf. And whatever is the class of T 5 I put that class here. Similarly I check a node if it is pure; that means, all the points in T 6 are from a single class, I make it a leaf I do not split further say they are minus class I make it like this otherwise I keep on splitting.

Till all the leaf nodes all the examples belong to a single class. So, till I get, till I reach a leaf node and. So, I grow that tree and then I stop. So, if I do it you can visualize that I will get perfect classification, all the examples training examples will be perfectly classified. I am not yet commenting on what about future examples a unknown examples. So, this algorithm is clear it is a top down algorithm initially consider the entire training set choose an attribute which best splits it say it splits into T 1, T 3 and T 2 examples, each T 1 again recursively split further using what is the best example considering T 1 only.

So, if we actually look at the previous example, it will become clear. So, what I do is that. So, initially my entire training set is T. So, initially this entire set is my T.

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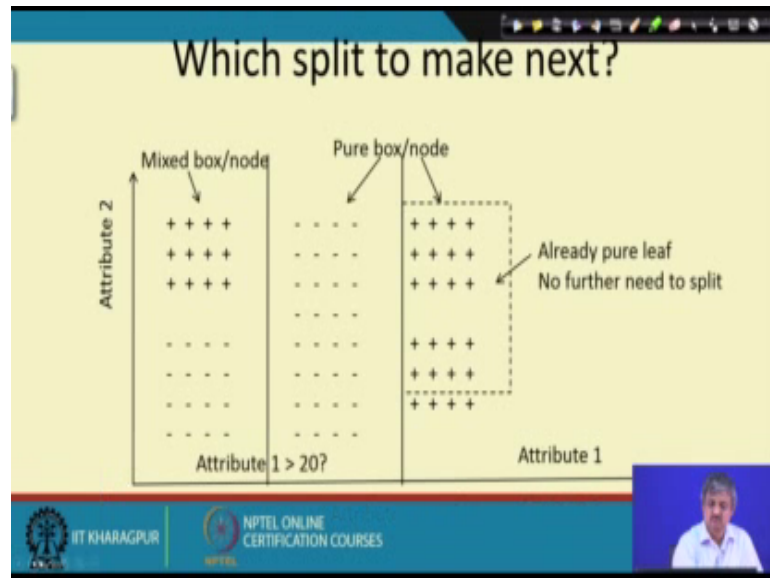


So, now, if I split along A 1 into 2 3 branches actually, then this is my T 1, this is my T 2 and this is my T 3 they get split. So, I have 3 branches. So, now, T 1 T 2 they are pure they need not be split further. So, they are if I call this T 1 this is T 2 their leaves.

This is a T 1 is a plus leaf T 2 is a minus leaf, T 3 is not yet pure. So, I have to split it further. But now considering T 3 you look A 1 attribute one is no longer the best attribute to split along considering only T 3 considering entire T A 1 as the split considering only T 3 A 2 is a special split, attribute 2 is a better split. So, I split it further using A 2 into say 2 groups. So, one of the groups become plus and one of the groups becomes minus plus. So, let me call it as T 5 and this as T 6. So, this is my T 5 and this is my T 3 gets split into T 5 T 6 and then we stop. So, this is the algorithm.

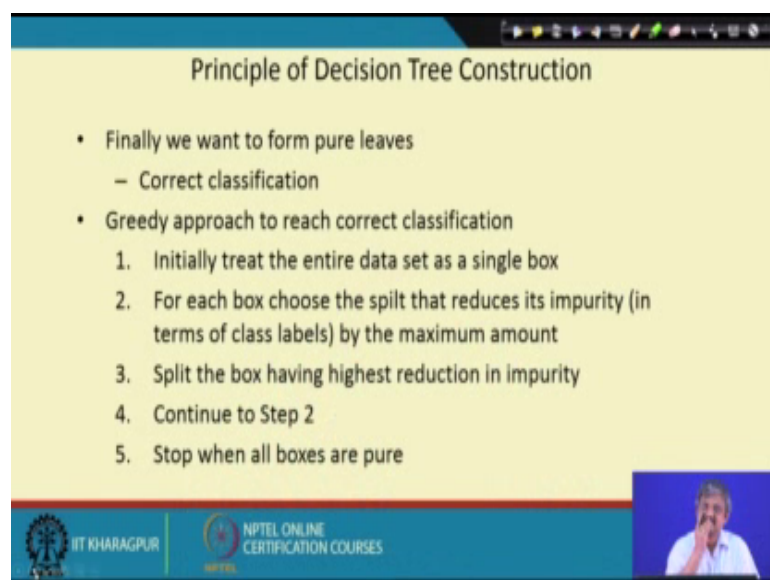
So, let me now sorry this is the algorithm. So, let me now formally write this down. So, I repeat again find the best attribute split on it, and on each of the branch again find the best till you get a pure leaf, now to answer the next question what is a best attribute.

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You think a bit when you built a tree we consider the first split, it is better to split along attribute one why because this attribute produces as child directly pure classes it produces a child a pure class is. So, this purity of class can be sort of used as to decide what is a best attribute. So, I can use this. So, let me show it. So, this is the principle what I had I have already explained.

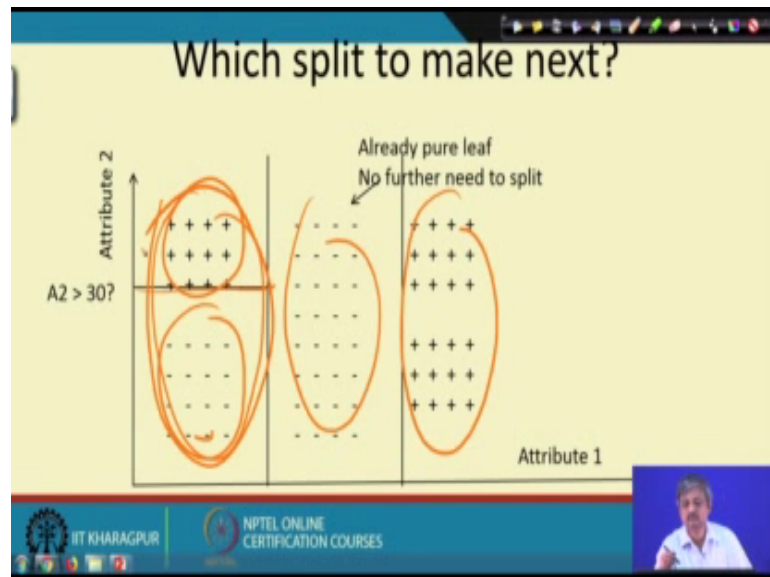
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So, this concept of purity of the split how pure a split leads to plus finally, you want a absolutely pure leaf that is my criteria of best attribute.

So, what is this criteria? The criteria is if you again look carefully here is that for example, this one initially this segment was impure it contained both and splitting this led to more purity of the child.

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So, every split similarly here this was T 3 splitting led to more purity of these and these and this is still impure. So, every split should led to increase in purity of the resultant boxes. So, compared to the parent the child's are purer.

How to quantify this? I will quantify this using a function called the entropy; you know entropy is nothing but a measure of the purity or order liners' or something. So, I will do this.

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Choosing Best Attribute?

- Consider 64 examples, 29⁺ and 35⁻
- Which one is better?

$E(S)$

$E(S_1)$

$E(S_2)$

$IG = E(S) - (E(S_1) + E(S_2))$

- Which is better?

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So, let me give an example to do this, suppose your initial training example initial training set contain 64 examples, and of them 29 are S class and 35 are no class.

Suppose using A 1 I take a value of A 1 is a binary valued attribute which takes on a value true or false out of this 64 I see how many examples have A 1 equal to true, let Us say thirty examples have A 1 equal to 2 and remaining 34 examples have A 1 equal to false. out of these 30 examples 25 are plus 5 are minus yes and no and here 4 are plus 30 are minus whereas, if we split along using attribute A 2 this is the picture this is the split. So, which split is better? Naturally this split is better because here there are a 50 50 mixture of both class, now the classes become purer here still they are mixed.

So, naturally this is a better thing. So, similarly here which one is better? So, what I do is that I define a measure called entropy to do this.

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Entropy

- A measure for
 - uncertainty
 - purity
 - information content
- Information theory: optimal length code assigns $(-\log_2 p)$ bits to message having probability p
- S is a sample of training examples
 - p_+ is the proportion of positive examples in S
 - p_- is the proportion of negative examples in S
- Entropy of S : average optimal number of bits to encode information about certainty/uncertainty about S
 $Entropy(S) = p_+(-\log_2 p_+) + p_-(-\log_2 p_-) = -p_+ \log_2 p_+ - p_- \log_2 p_-$
- Can be generalized to more than two values

Handwritten notes: n, n^+, n^-
 $p^+ = \frac{n^+}{n}, p^- = \frac{n^-}{n}$

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The measure is defined this way. Suppose S is my set of training points. So, in the previous case there are 64, S has a size 64. Now let us say p_+ fraction of them are positive S examples S class and p_- are negative term. So, in other words I can easily find define it this way, suppose you have n examples of which n_+ are positive, plus n_- a negative plus, then p_+ is n_+ by n and p_- is n_- by n . If you have more than 2 classes you can easily generalize it to fraction belonging to each class. So, it will be if you have 1 2 3 classes it will be $p_1 p_2$ and p_3 . So, the entropy of this set of examples S is defined by this formula.

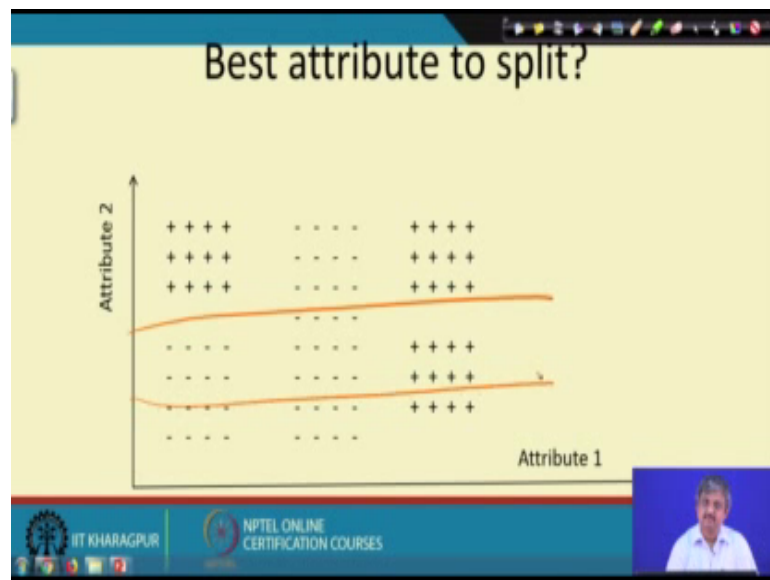
It is p_+ into minus log of p_+ plus note that p_+ is a less than 1. So, log of p_+ will be negative. So, I put a minus in front. So, p_+ into log of p_+ plus p_- into log of p_- , let us say log base 2 you can actually take any base. So, if you had more class say 1 2 3 plus then I will write p_1 into log of p_1 plus p_2 sorry p_1 into minus log of p_1 , plus p_2 into minus log of p_2 , plus p_3 into minus log of p_3 . So, suppose this is that S is the entropy. So, now, what I can do is the following, I can say for this split.

So, this is my training set S , I can find its entropy. let me call it E_S . It splits into 2 child's; let us say I call them set S_1 of these thirty examples, and S_2 of these 34 examples and similarly I can define entropy for this set S_1 and for this set S_2 . I will say the information gain that you get by this split is the reduction in entropy as a result of

this split. So, if I define information gain, I can define as entropy of the parent minus sum of entropy of the child's.

So, this is the total entropy of the child $E(S_1) + E(S_2)$. $E(S)$ is the entropy of the parent, the reduction in entropy is the gain in information; information is kind of negative of entropy. Now what I will say is that my best split among this 4 is the one which leads to highest information gain or maximum reduction in entropy; so again if I come back to that illustrative example.

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So this splits leads to good reduction in entropy because they become purer whereas, this split is or maybe this kind of split does not lead to much reduction in entropy, because the child's are also impure. So, the previous split will be having a better score than this split. So, look at if you carefully examine some properties of this entropy you will notice one thing that, when $p_+ = p_-$, there are equal number of points from both class entropy is the highest. When there are points from only one class pure S only $p_+ = 1$, $p_- = 0$ or other way around $p_- = 1$, $p_+ = 0$, then entropy is 0 actually entropy is 0.

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Entropy

- A measure for
 - uncertainty
 - purity
 - information content
- Information theory: optimal length code assigns $(-\log_2 p)$ bits to message having probability p
- S is a sample of training examples
 - p_+ is the proportion of positive examples in S
 - p_- is the proportion of negative examples in S
- Entropy of S : average optimal number of bits to encode information about certainty/uncertainty about S
 $Entropy(S) = p_+(-\log_2 p_+) + p_-(-\log_2 p_-) = -p_+ \log_2 p_+ - p_- \log_2 p_-$
- Can be generalized to more than two values

Handwritten notes:
 $p_+ = 1, p_- = 0$
 $p_+ = 0, p_- = 1$
 $p_+ = p_- = 0.5$

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So, the purer the class; that means, if we have p_+ equal to 1, p_- equal to 0 or p_+ equal to 0, p_- equal to 1 pure class then we have high entropy sorry we have a low entropy they are pure less disorderliness, whereas, if you have p_+ equal to p_- equal to 0.5 you have the highest entropy, you can work out the evaluate the expressions and check. So, my training algorithm is very simple, I just follow this rule I am giving you the description of $E(S)$, description of the algo I follow this rule recursively split on attributes first choose the best attribute on the entire training set then each of the branches individually what is the best attribute.

Where the best attribute is defined as the amount of information gained that split on that attribute leads to and then we stop, when there is a 0 entropy or pure leaf. So, that is my algorithm alright. So, I think that is clear. So, that is my algorithm. So, if we I have walked out I will upload the slide. So, I have walked out all the values I am not repeating them now you can check the values that we get.

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Information Gain

- $Gain(S, A)$: reduction in entropy after choosing attr. A

$$Gain(S, A) = Entropy(S) - \sum_{v \in \text{Values}(A)} \frac{|S_v|}{|S|} Entropy(S_v)$$

$29^+, 35^-$ A_1 $E(S)=0.993$

0.650 $25^+, 5^-$ 0.522 $4^+, 30^-$

$29^+, 35^-$ A_2 $E(S)=0.993$

0.989 $15^+, 19^-$ 0.997 $14^+, 16^-$

Sometimes there is a slight modification to the entropy value or information gain value, it is I have mentioned entropy of the parent minus sum of the entropy of that your child entropy S_1 plus entropy S_2 it is sometimes.

Weighted sum of the entropy of the child where a larger child which has more examples will be given more; so fraction of examples of S which fall in the child ϕ . So, weighted by that ratio that is the entropy, sometimes this form is also used. So, what I will do is that I will use this if I do I will do the calculation. So, just to summarize my algorithm is like that, I will start with the entire training set see which attributes leads to best information gain, split on that. Now examples will be distributed across branches and on each branch again recursively is find out which is leads to highest information gain do that till each branch contain a 0 entropy or a pure set of examples, pure leaf then I stop.

So, in the next lecture I will give some more extensions of this on while dealing with not discrete values, but continuous attributes and on dealing with the training examples contain some noise and over fitting may happen, how to deal with that. We will continue that on the next lecture.

Thank you for this lecture.