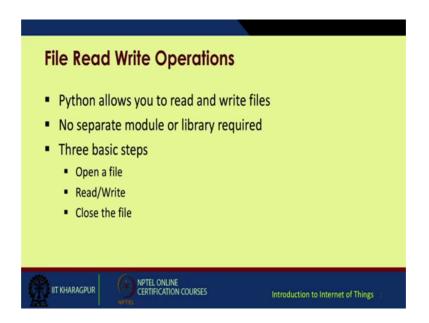
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Lecture - 27 Introduction to Python Programming- II

Hello, in this lecture in Continuation to Python Programming, I will be covering a few interesting applications, you can develop using normal python programming.

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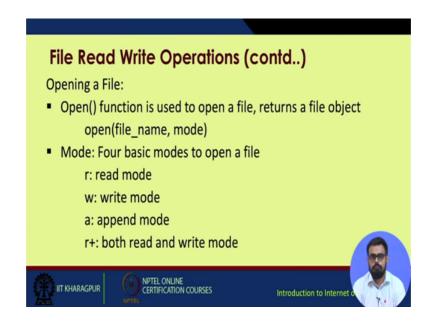
So, to start off with, we will be covering a few basic operations starting from file, read/write, operations, we will be dealing with normal text files as well as csv files. Csv are basically comma separated value files. So, each value in the file is separated by a comma.

Next we will move on to your developing a network socket using python scripting. So, we will develop two parts. First, we will develop a udp host or a server and a udp client and in the third part, we will be dealing with some basic image, read, write operations using python PIL library. So, to start off with the file read write operations as necessary in normal IoT based applications, imagine your senses or lots and lots of sensors are uploading the data on a particular database or a file system.

So, the data is separated, separately stored or data is collectively stored using various time stamps or signatures or identifiers. It may be in a text file for small scale systems, it may be in a csv file, but larger scale systems and then, again for much larger implementations of IoT, people normally prefer using data bases like MySQL or Oracle ecetera. So, python allows us the functionality to read and write files.

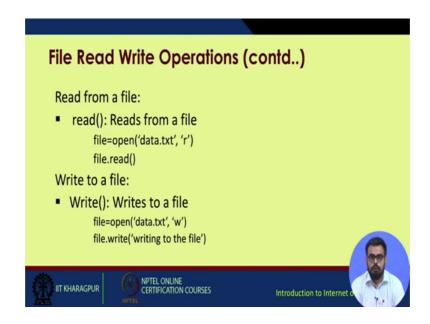
Generally no external module or library is required. It is available with the basic distribution of python itself and while reading or writing a file, three basic steps have to be followed. First and foremost is opening a file itself. Next is reading or writing operation and third one is closing the file. So, keeping these three in mind, we will dive into a bit more details about these.

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So, the open function is used to open a file and return a file object. That means, whenever you give the syntax, open first argument is filename and the second argument is mode. There are the following four modes, r for read or w for write, a for append and r plus for both read as well as write. Modes through reading from a file as you can see the syntax is pretty simple.

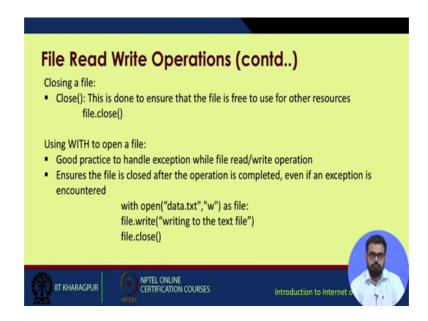
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So, imagine you have a file text, file named data data dot txt. So, we are going to attempt to open it using this line file equal to open data dot txt comma r point to notice both the filename as well as the mode are within quotations because these are taken as strings and then, in the next line we have file dot read. So, this file equal to open function, the file is actually a variable. You can assign any other name to it. Next is the writing to a file part.

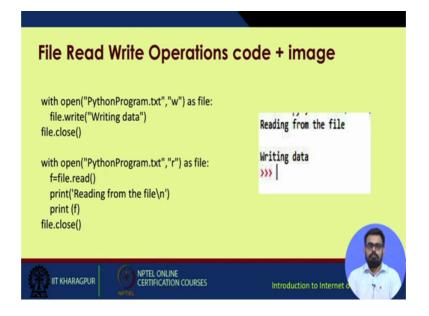
So, whenever we are writing to a file, again we have to open the file. Only the mode changes from r to w, then file dot write and within arguments, you just put in the string here about to write to the file you can. Obviously, put various variables you can store your incoming sensor data and some variable and iteratively write those variables using the file dot write function.

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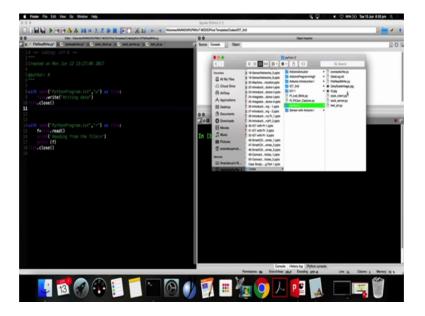
Now, at the end, once a file access has been done, you must ensure that your file handle is closed by using this function file dot close and whenever since in normal scenarios specially IoT based scenarios, there is a significant need to iteratively access the same file over and over again. So, using this script with open data dot txt in write mode as file in file dot write, we write the string which has to be written to the text file and then, we release the file handle by calling file dot closed.

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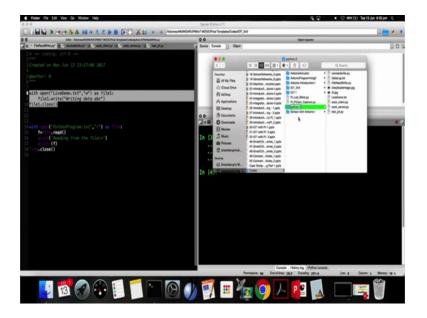
So, it would be better if we give a bit of hands on to this thing. So, as you can see I have already kept the program ready.

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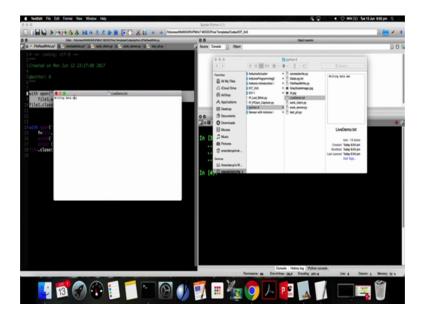
So, we just have to call a file, any file name we want to put over here. We have python program dot txt. We can change it to something else also. So, my files and folders basically recite in this directory. So, as you can see there is no python program dot txt file in this list. So, maybe we can just change the name to live demo dot txt.

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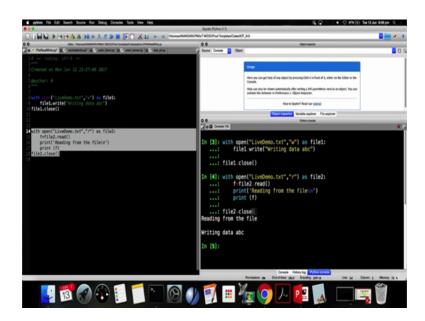
Then, in the next line for speed, iteratively we have to write something on it. So, with open live demo, the txt as w or in write mode as file, let us call it by another name file 1. Then, file 1 dot write, we are writing this writing data abc and then, we release the file handle by calling file 1 dot close. So, once we run this thing, we have executed this thing, these three lines of code. Again we will check the directory.

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Here we have the file named as live demo dot txt. We open it as you can see the intended data has been written to the text file. So, this was part one. Half of the job it is reading that is writing to the file. Next part comes that is reading from that file.

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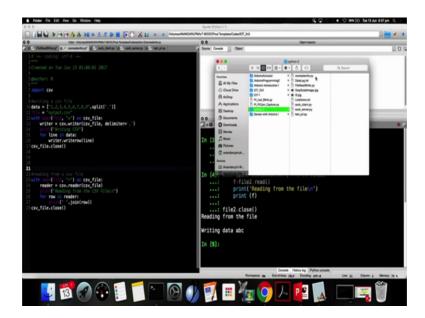
So, now I have a filename live demo dot txt. So, in the same manner as before I will open the same text file, but in read mode. So, I will change the mode to r initial. It was w, now changing it to r.

So, I am opening the file mode in read opening, the file in reading mode assigning the variable let us call file 1 or maybe just for the sake of it file 2 f equal to file 2 dot read. Then, I print reading from the file and then, again I print whatever has been read and again I release the file handle. I release this file 2 by calling file 2 dot close. So, once again I will execute these lines.

See once this execution is complete, the first line has been printed reading from the file. This was a first print statement and then, if you recall we had earlier written data to the text file like writing data abc. So, this has been extracted from the text file and put up and printed on the console. So, this was part one, reading and writing from normal text files. So, they can be multiple operations, we can consider while doing file read write operations.

So, not to go into that much details, you can easily avail various resources online to check those.

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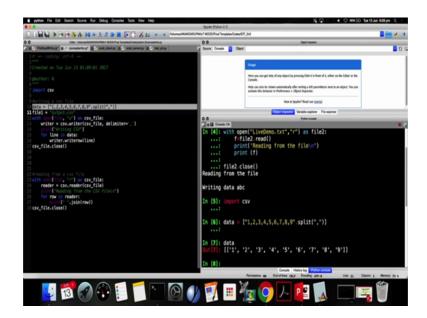


Another common thing being used is this csv file format or comma separated values. You can again check I do not have any csv file in my directory list. So, I am using this script csv read write or py. So, once this has been executed, it will generate a file with the extension dot csv.

For this I have to import an external library or csv library. Once this library has been imported, I define the data. I want to write to the file. First I will write to the file, then once the file has been created and the data written to it, I will read from that same file. So, one point to remember is whenever I am trying to open a file in write mode, if the file does not already exist, the system will automatically create that file, that same file.

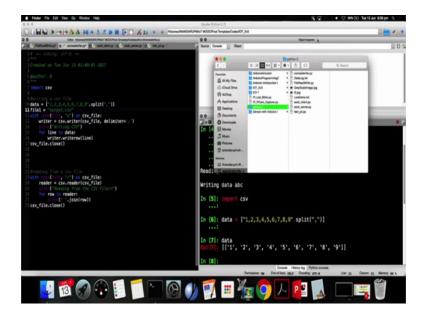
So, I am giving the file name as output dot csv. Let us name the variable as file 1. The data is within since we are putting up a string data. So, we are giving 1 2 3 4 upto 9 and we split it using the comma character, you can use other characters also like semicolon, colon so on, but for the sake of demonstration, I am just using a comma. Let us see what happens when I execute this line. So, this script has been executed and I will check what is stored in this.

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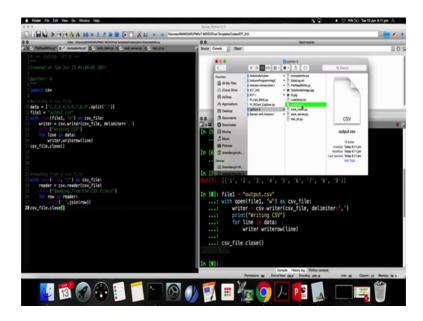
So, you can see individually you have various strings separated by comma. The first string is 1, second string is 2, and so on upto 9. So, whatever input you had given, it has been individually separated into substrings. Then, next I open I create a variable file 1 and try to open output dot csv. So, in this directory, we have nothing called an output dot csv file.

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So, we are assigning this output dot csv string to variable file 1. Now, again using with open file 1 in write mode as csv file, we call another variable writer equal to csv dot.

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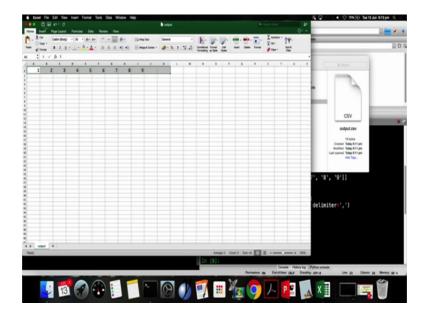
Writer in csv file delimiter is comma. Suppose you had given a semicolon as delimiter, you could have replaced this comma by a semicolon and we print a normal statement to check whether it is working fine or not and then, whatever data is being written into the file.

So, we call the writer again and each row report in a separate value like 1 in the first row, 2 on the second row, 3 on the third row and so on. Then, eventually we call the close function file dot close. Now, let us see what happens when we run this collectively. So, my print statement writing csv has been executed. Let us check. So, the file name was output dot csv. Yes we have a file called output dot csv over here.

So, by default it is opening with microsoft excel. So, for my system, the default csv file viewer is microsoft excel. So, it is directly opening through excel. This will take some time. Let it load. In the meanwhile, we will look into this writing from a csv file part. Now, again we go on with open in a name variable file 1 in read mode as csv file and reader equal to csv reader csv file.

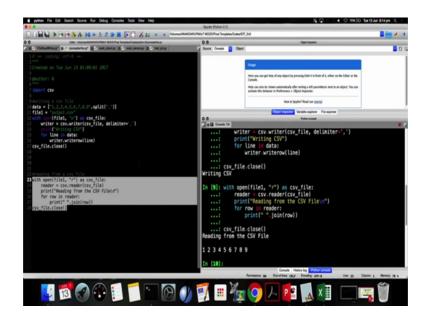
We print that it is reading from a file that is we will just give an indicator to the user that this script is executing and then, for each row being read by the reader, the value being read will be printed one at a time and eventually, we will release the handle by calling the filename dot close function.

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So, I have finally managed to open my excel file. As you can see the values 1 2 3 4 have been written in separate columns. So, instead of these static values, we can acquire data from various sensors and we can keep on updating this csv file in a iterative manner. So, this will give me a database, a rudimentary database, ok.

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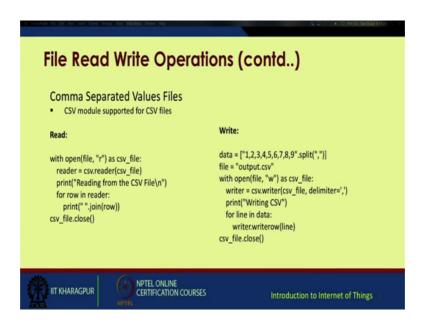


Now, I know my output dot csv file is in place. I will try reading from that file. Now, the first after the script has finished executing, the first print statement was reading from the

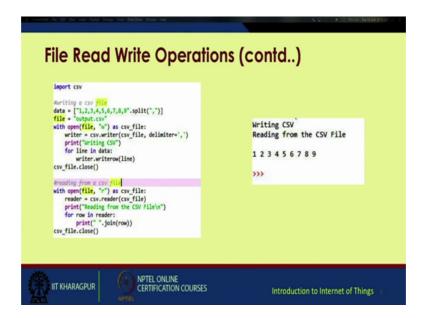
csv file and it has read the values individually like 1 to 9. So, I hope this was quite easy. We will move on to the next part.

So, we have already completed these. Now, the next part is a, but interesting since it will deal with various images.

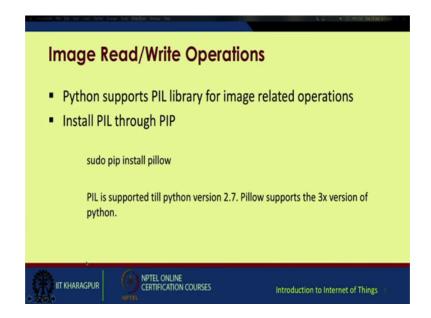
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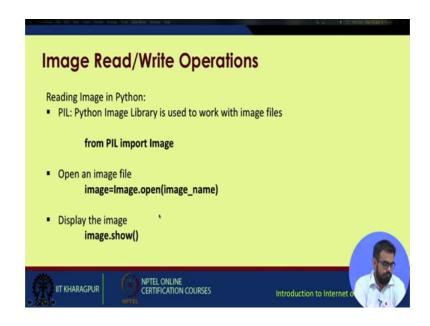
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So, we will functionally work with image read write operations. Now, python supports this library called PIL or python imaging library. This is generally used for image related operations. So, if by default your PIL is not on the system, we use PIL or we acquire PIL using sudo pip install PIL low.

So, normally PIL is supported in the python version 2.7 till 2.7, otherwise for higher versions PIL needs to be installed to get this working.

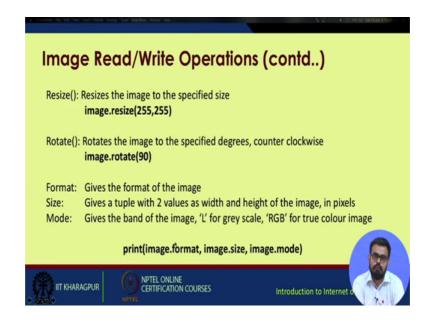
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So, for image read write operations, first of all we have to call this PIL library either we import PIL directly or if we have any particular function in mind like the function image, we just import that particular function.

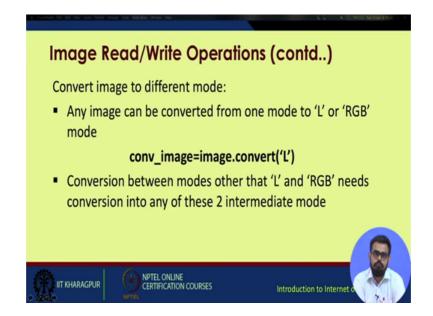
So, for that we have from PIL import image, then opening that image file, image equal to image dot open name of the image and for displaying the image, we just write image dot show.

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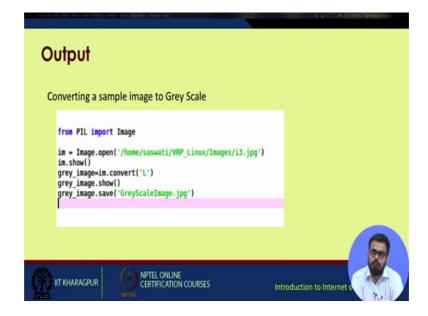
So, you have multiple functions related to images. You want to resize your image, you call the resize function and within arguments you give the number of rows and columns you want to rotate your image.

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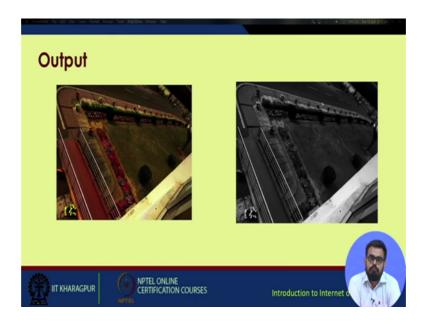


You call rotate and within arguments, the degrees you want to rotate your image, also you can convert between various colour maps. So, for example you can convert your normal images acquired from standard cameras. We call them as RGB images because of the presence of three channels red, green and blue. We can convert this into grey scale also. So, the conversion function is pretty simple. Image dot convert and within the arguments within quotes, you write that mode. I stands for pay scale and RGB stands for the normal RGB mode. So, you can alternatively convert between these two.

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So, this is just for the sake of demonstration. See for example, once we execute, this script will come to that in the hands on part. Once we execute the script, it will give you the following output. The left hand side, this image was taken as the input image and after conversion using image dot convert function, it has converted to your grey scale. So, we will check out this function.

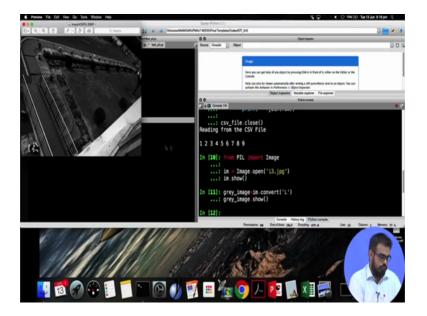
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So, now I have from PIL import image and assigning a variable to the function image dot open. So, I have a input image, I three dot jpeg in my folders, same folder as the script,

then I execute this im dot show. I will just execute these three lines you see. Once the im dot show has been executed, the default image viewer application of your system opens up and this is the input image null convert it to grey scale.

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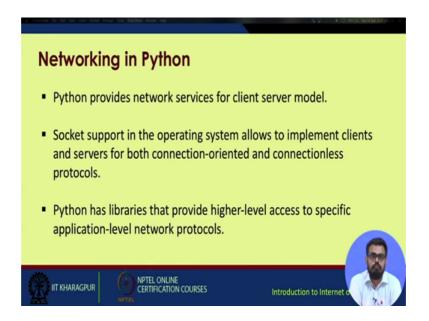
So, im dot convert and within quotes I and again, last the system to show the image. So, as you can see again on the default image doing application, the image has been converted to grey scale from RGB. Now, I need to save this image. So, since the converted colour map of the grey scale image is stored in a variable grey underscore image, I need to save this grey underscore image dot save and the name I want to save it as.

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So, once save function has executed, I get the required file in my directory. These are just some of the very basic functions I can work with.

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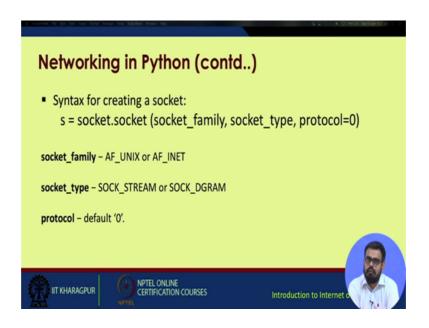
Next we will move on to basic networking in python. So, for this we will create udp sockets. So, we will try to simulate two systems like you will have a client and then, you will have a server. So, server will expect data from the client. Later on you can actually now itself you can actually imagine your client to be deployed IoT devices which read

various sensorial data and transmit it over the network to the server. It works in a same principle.

So, for starters we will just see how this networking part happens. So, maybe your server is located far apart, but connected to the network using this same code, same principle. With a bit of modifications, you can get your field deployed IoT devices to send data to a remotely located server. So, python provides this network services using the client server model and then, this socket support in operating system, it allows the clients to implement servers.

It allows the implementation of clients and servers for both TCP IP that is connection oriented as well as UDP protocols which are mainly connectionless protocol and python has additionally libraries which allow higher access to specific application level network protocols.

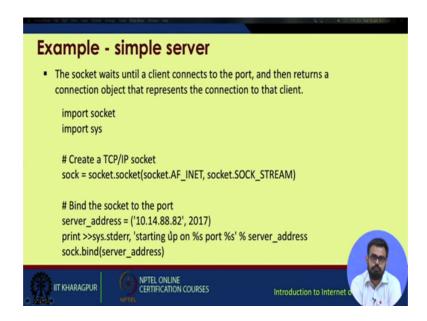
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So, general syntax is locating the socket a variable which is equal to socket dot socket in socket family socket type protocol. By default the protocol is 0. So, within socket family you have AF underscore UNIX or AF underscore INET.

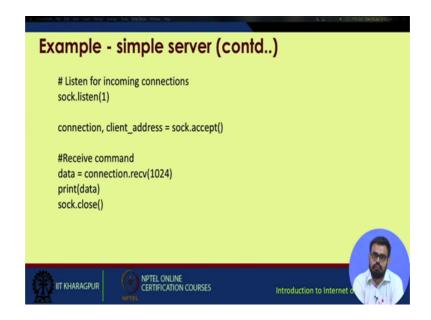
So, generally UNIX option is only available for UNIX base systems, where as INET stand for all internet protocols. Socket type is sock stream or sock datagram and protocol by default is 0.

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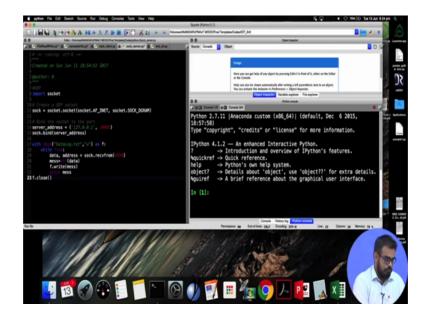
So, we have created a TCP IP socket, we give the server address as this is a particular IP address, then we give a particular port to which server your client will bind and just some print statements and eventually, the main functions sock dot bind and server address, so that this will be listening for connections and then, we have sock dot. Listen this initializes the listening part that the server is expecting connections from client.

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So, it would be better if I give a demonstration of this thing. So, I will need two consoles for this. From 1, I will run the server and from another, I will run the client.

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So, this is my socket server. For the server address, I have given a normal loopback address that is 127.0.0.1

I given a random port 10000 and one and we intend to write the data which is being generated into a text file. So, data log dot txt in write mode and this data socket will be expecting the data which it receives from the client in junks of 4096 bytes and whenever this data is received, it will convert the data to string and write the data to the file and eventually once the transaction has finished, it will close the file.

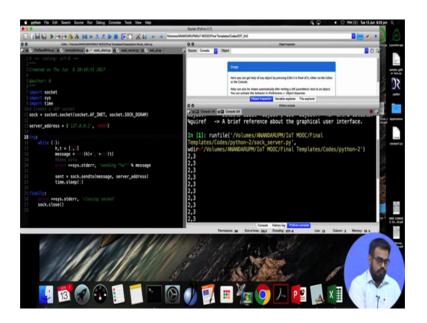
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So, till this part the socket operations take place and within this the data read write operation take place, similarly for start I will get the server running. So, it does not show anything because it is expecting data from a client. On the client side, I give the same loopback address as the server, then the same port number. It is very important to have the same port numbers.

Now, finally we just iteratively loop again and again and send two values h and t. I have fixed it to 2 and 3 and this will keep on sending these values over the socket. You see this sent equal to this sock dot sent to message, the message that is 2, 3 to the server address that was this loopback address.

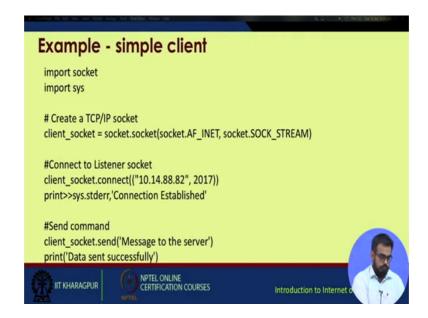
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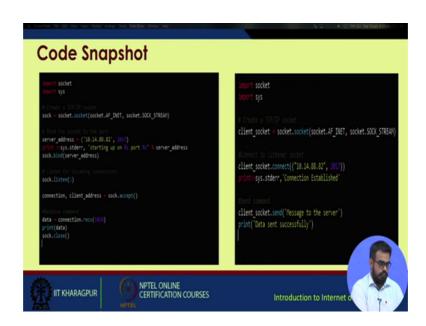
So, in the second console, I will run the client. You see the client is sending 2 3 2 3. It will keep on sending this until I terminate the execution and at the server side, you are receiving this 2 and 3.

So, this thing you can implement on two different machines connected to the network. It may be in the same room, it will be in different cities, it may be in different countries, but your server, your IP and port needs to be the same.

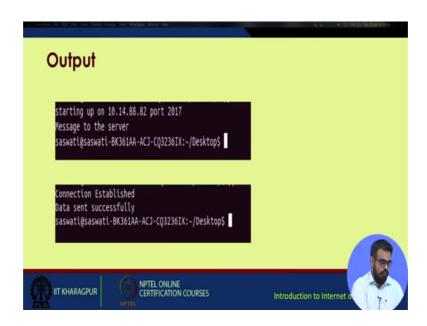
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So, we have covered this client. You have seen the code for stand and outputs you have seen. So, I hope you can now use this knowledge to generate some interesting applications on python.

Thank you.