

Course on Design of Steel Structures
Professor Damodar Maity
Department of Civil Engineering
Indian Institute of Technology Kharagpur
Lecture 21
Module 5
Design Strength of Tension Member

Hello today I am going to discuss about the codal provisions for calculation of design strength of members under axial tension. So as I told in last class that design strength calculation will be calculated on three criteria one is the due to gross yielding of the section and due to rupture and due to block shear. And the strength calculations will be done on the basis of these three criteria and the minimum of these three will be the design strength of the tension member.

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Clause 6 IS 800-2007

$$T < T_d$$

$T_d \rightarrow (T_{dg}, T_{dn}, T_{db})$

Clause 6.2

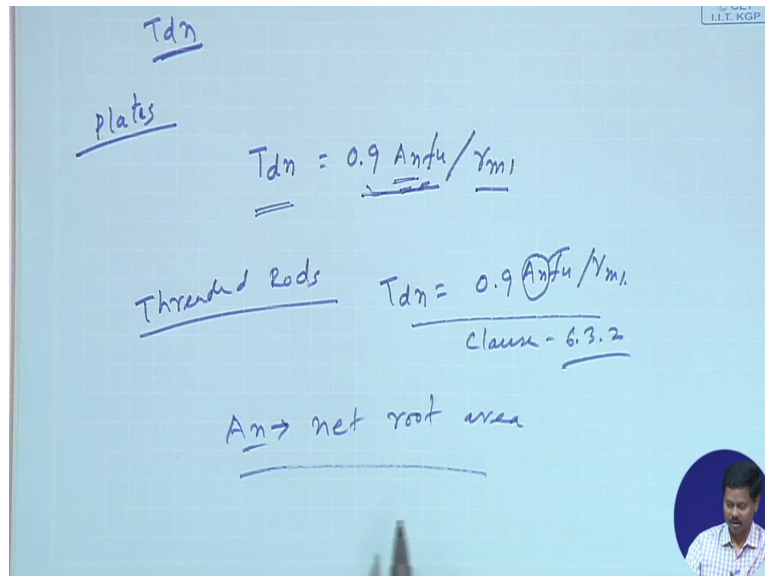
$$T_{dg} = \frac{A_g \cdot f_y}{\gamma_{m0}} \rightarrow \text{Table 5}$$

So coming to the codal provisions if we see that in clause 6, we will go we will get the design strength calculation of tension member clause 6 of IS: 800-2007. So details you can find out from this and in clause 6.1 it is told that the factor design tension T should satisfy the requirement of this T_d where T_d is the design strength of the member under axial tension and T_d will be the least of these three, one is the yielding of gross section T_{dg} , then rupture of critical section T_{dn} and then block shear failure T_{db} .

So on the basis of these three the T_d will be decided. So T_d will be the least of these three and that T_d has to be less than the factor tensile force coming into the member. So coming to clause 6.2 if we see clause 6.2 we will see that the gross yielding strength the design strength

due to gross yielding T_{dg} can be calculated as A_g into f_y by γ_{m0} , we can calculate from this where f_y is the yield stress of the material and A_g is the gross area of the cross section and γ_{m0} is the partial safety factor and this we can find out from table 5 of the IS code from table 5 the partial safety factor the material has been given. So $A_g f_y$ by γ_{m0} , if we calculate this value we can find out the design strength due to gross yielding.

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- T_{dn}
- plates
- $$T_{dn} = \frac{0.9 A_n f_u}{\gamma_{m1}}$$
- Threaded Rods
- $$T_{dn} = \frac{0.9 A_n f_u}{\gamma_{m1}}$$
- clause - 6.3.2
- $A_n \rightarrow$ net root area

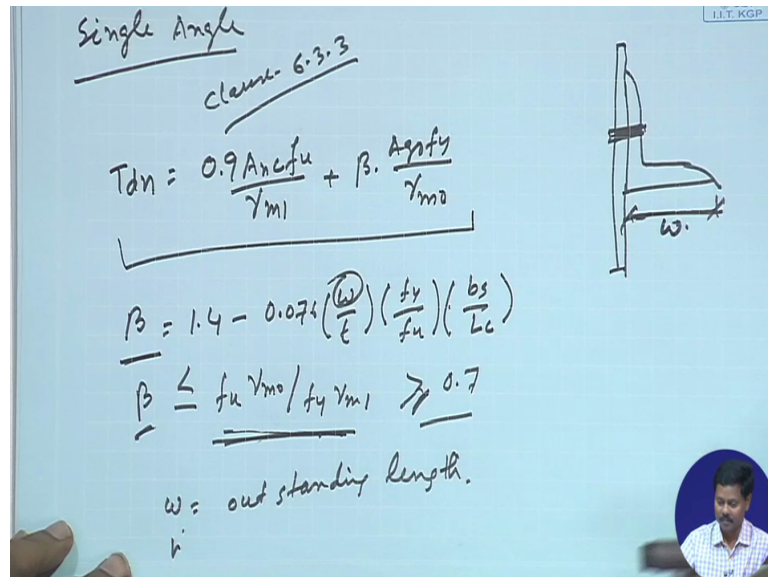
And similarly I can find out design strength due to rupture of critical section rupture of critical section T_{dn} we will try to find out design strength due to rupture of critical section. So this can be found this is given in clause 6.3 and in clause 6.3.1 you will get about plates design strength in tension of a plate. So that is calculated T_{dn} is equal to $0.9 A_n f_u$ by γ_{m1} . Here f_u is the ultimate stress of material and A_n is the net area of the cross section and γ_{m1} is the partial safety factor of failure in tension at ultimate stress, right.

So the design strength due to rupture of critical section of plate can be found from this formula that is T_{dn} is equal to $0.9 A_n f_u$ by γ_{m1} , right. Now this is true for plate, so for plate in earlier lectures we have seen that how to calculate the net area of the plate net area of the plate means about the critical section what will be the net area net effective area of the plate that we have seen how to calculate. So this net area will be required to find out the rupture strength of the section, so here this net area will be required.

Now in threaded rods in case of threaded rod also this this will be same formula we can use that is T_{dn} will be is equal to $0.9 A_n f_u$ by γ_{m1} , so this is also same in clause 6.3.2 it is given clause 6.3.2 it is given where A_n here A_n in case of threaded rod it will be the net root

area of the threaded section A_n will be the difference with plate is that here A_n will be the net root area area of the threaded section, right. So this is how we can calculate the design strength of threaded rod.

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Single Angle
 clause 6.3.3

$$T_{dn} = \frac{0.9 A_n f_u}{\gamma_{m1}} + \beta \cdot \frac{A_g f_y}{\gamma_{m0}}$$

$$\beta = 1.4 - 0.076 \left(\frac{w}{t} \right) \left(\frac{f_y}{f_u} \right) \left(\frac{b_s}{L_c} \right)$$

$$\beta \leq \frac{f_u \gamma_{m0}}{f_y \gamma_{m1}} \geq 0.7$$

w = out standing length.

Similarly for angle section say for single angle, now in case of single angle as I told that if it is connected with some gusset plate, or some other plates, or some other members then if it is connected with this then shear lag effect will be going to be occur because this portion is not connected therefore we have to calculate the T_{dn} value taking care of the shear lag effect.

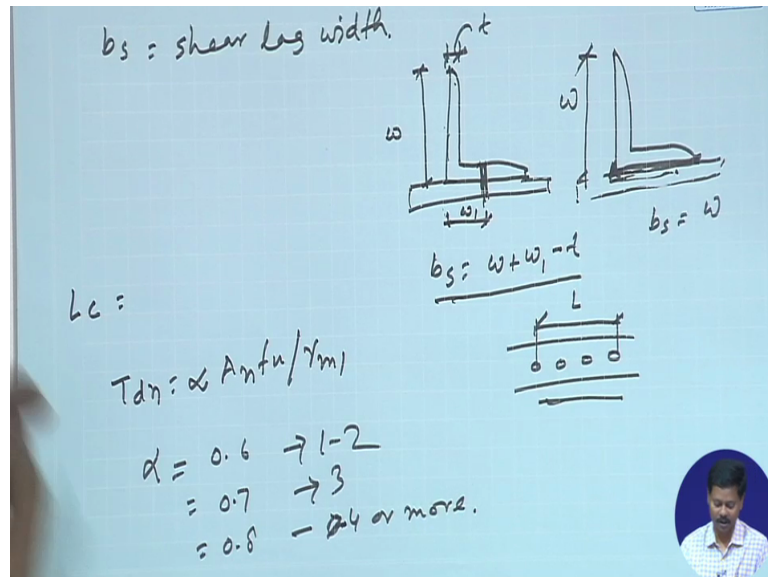
So this T_{dn} value can be calculated from this formula $0.9 A_n f_u$ by γ_{m1} plus beta into $A_g f_y$ by γ_{m0} , right and this you can find out in clause 6.3.3 of IS: 800-2007 in clause 6.3.3 you can find out this value where the rupture strength of angle is effected by the shear lag and that shear lag effect has been taken into consideration in this formula.

Here beta is a factor which can be calculated from this formula that is 1.4 minus 0.076 into w by t into f_y by f_u into b_s by L_c , right and this should be less than or equal to this beta should be less than or equal to $f_u \gamma_{m0}$ by $f_y \gamma_{m1}$ and should be greater than or equal to 0.7.

So beta should vary from this value to this value means it should be greater than 0.7 and it should be less than this and that means beta we have to calculate and we have to check with this value whether it is coming under this condition or not if not then we have to consider the remaining value.

Now this w is basically outstanding length of the section that means this is in this case this is w , this w when we are going to consider this w will be the outstanding length in this case, right.

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So next is the b_s b_s is the shear lag width so b_s we can find out here it is shear lag width, how to calculate say you will get details in figure 6 of IS: 800-2007, I am just representing that graph here and the figure here that is if a angle say it is connected with a plate with the bolt connection then this is as I told that outstanding lag is the w outstanding lag width and this we can consider as w_1 , then this b_s will be here b_s will be w plus w_1 minus t t is the thickness of the angle this is t , right.

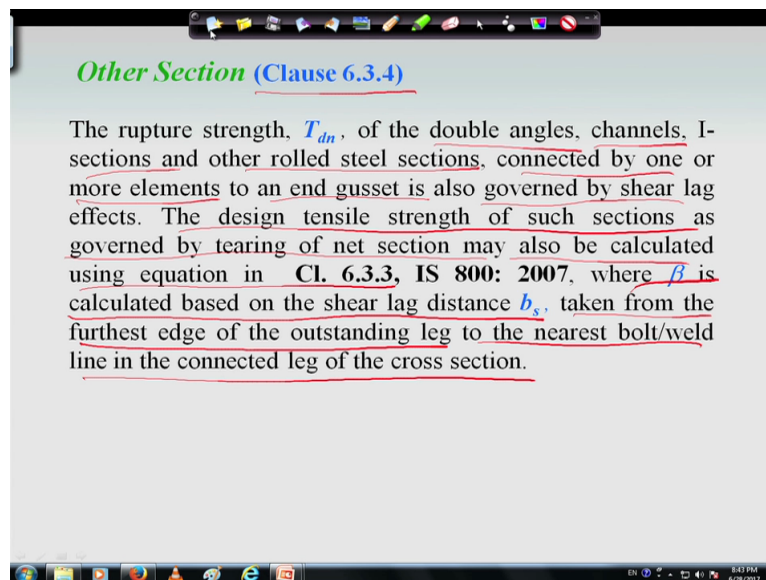
So when angle with single lag connection then b_s can be calculated from this shear lag width b_s will be w plus w_1 minus t but if it is connected with weld connections then connected with weld connections means basically it will be connected here and here means throughout right. So here we can calculate b_s as simply w , because it is connected upto this right. So b_s is the outstanding lag width and the width which are not connected from outstanding lag width site right so w plus w_1 .

And L_c L_c is the length of n connection that is the distance between the outermost bolt that means if it is connected with bolts then this this will be the L_c the distance between outermost bolt in the n joint, measure along the load direction or length of the weld along the load direction. So this is how the L_c can be calculated.

And at the beginning we may not find out because we may not know that the all the details, so for preliminary sizing we can calculate T_{dn} as this formula from this formula also we can calculate approximately it will be like this α into A_n by γ_{m1} , where α is a factor which can be consider as 0.6 for 2 number 1 or 2 bolts 1 to 2 bolts, α is equal to 0.6 and 0.7 for 3 bolts and 0.8 for more than 3 bolts means 4 or greater than or equal to 4 means 4 or more, right.

So for preliminary sizing one can find out T_{dn} as α into A_n by γ_{m1} , where A_n is the net area of the cross section and α is the factor which we can take 0.6 if 1 to 2 bolts are there and it is 0.7 if it is 3 bolts and it is 0.8 if we can if we take 4 or more bolts.

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For other section other sections we can see here which is given here that is written in clause 6.3.4 which I have represented here that is the rupture strength T_{dn} of the double angle because earlier we have calculated for single angle, for double angle channels I-sections and other rolled steel sections connected by one or more elements to analysis end gusset is also governed by shear lag effect.

The design tensile strength of such sections as governed by tearing of net section may also be calculated using (equation 6.) equation in clause 6.3.3, right where β is the is calculated based on the shear lag distance b_s , and b_s is taken from the furthest edge of the outstanding leg to the nearest bolt or weld line in the connected leg of the cross section. So for rupture strength calculation other than the single angle section we can use this clause that is clause 6.3.4.

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Other section
Block shear

Clause 6.4

$$T_{db1} = \frac{A_{vg} \cdot f_y}{\sqrt{3} \gamma_{m0}} + \frac{0.9 A_{tn} f_u}{\gamma_{m1}} \quad \text{Avg, Avn}$$

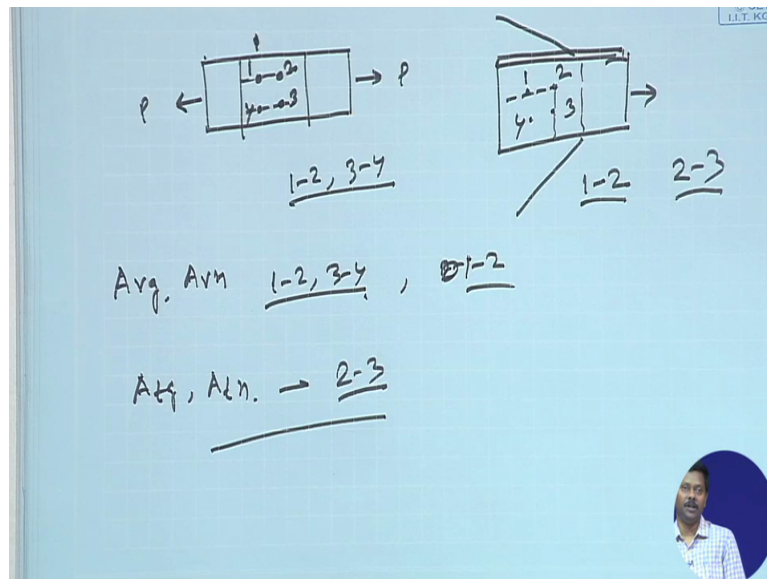
$$T_{db2} = \frac{0.9 A_{vn} f_u}{\sqrt{3} \gamma_{m1}} + \frac{A_{tg} f_y}{\gamma_{m0}}$$

$$T_{db} = \text{least of } (T_{db1} \text{ \& } T_{db2})$$

Then we will come to block shear design strength due to block shear, right. So the block shear we can calculate from clause 6.4 of the IS code, it is given in clause 6.4. The block shear strength T_{db} can be calculated from this formula that is T_{db} is equal to A_{vg} into f_y by root 3 gamma m_0 plus $0.9 A_{tn}$ into f_u by gamma m_1 or T_{db} also may be this is because of tension fracture and shear yield, if shear means due to shear yield and tension fracture the block shear can be calculated or tension yield and shear fracture also we can calculate that will be $0.9 A_{vn} f_u$ by root 3 gamma m_1 plus $A_{tg} f_y$ by gamma m_0 .

So block shear can be calculated due to tension fracture and shear yield or tension yield and shear fracture whichever is less means T_{db1} and T_{db2} we can calculate and T_{db} will be least of least of these two T_{db1} and T_{db2} , right. So this is how we can calculate. Now what are the parameters means this A_{vg} and A_{vn} what are this, now we have to know.

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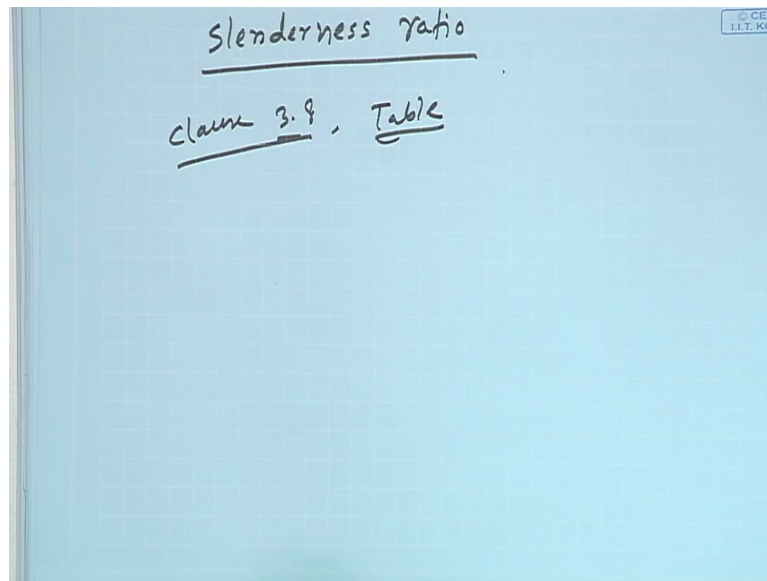
So to know this let us draw a picture which I am reproducing from figure 7 of IS: 800-2007 from figure 7 it is given if we see if a plate are connected with some bolt connections say like this and if axial force are in this direction then we can see that this I can write 1, this bolt 1 1, 2, this is 3, this is 4 and also let us come to the angle section if we can see this angle section is connected to a plate and under tensile force and bolt are connected in this way so it can we can see 1, 2, 3, 4, ok.

Now Avg and Avn, Avg is the minimum gross area and (Av) is the Avn is the net area in shear along bolt line parallel to external force that means along line 1-2 and 3-4 and here along 1-2, right. So Avg and Avn will be the minimum gross and net area in shear along bolt line parallel to external force, right.

Similarly Atg and Atn will be the minimum gross and net area in tension t for tension from the bolt hole to the toe of the angle that means along 2-3 perpendicular to the line of the force respectively, right. So this will be along 2-3 then perpendicular to the force and this will be along 1-2 or 3-4 and in case of angle along 1-2. So this is how we can calculate the Avg, Avn, Atg and Atn and f_u and f_y are as usual meaning f_u is the ultimate strength of the plate and f_y is the yield strength of the plate.

Now for weld connections Tdb can be checked for welded connections by taking analysis appropriate section in the member around the end weld and this which can shear of as a block. So this weld connections also we can use means we can calculate the Tdb value for weld connection as well.

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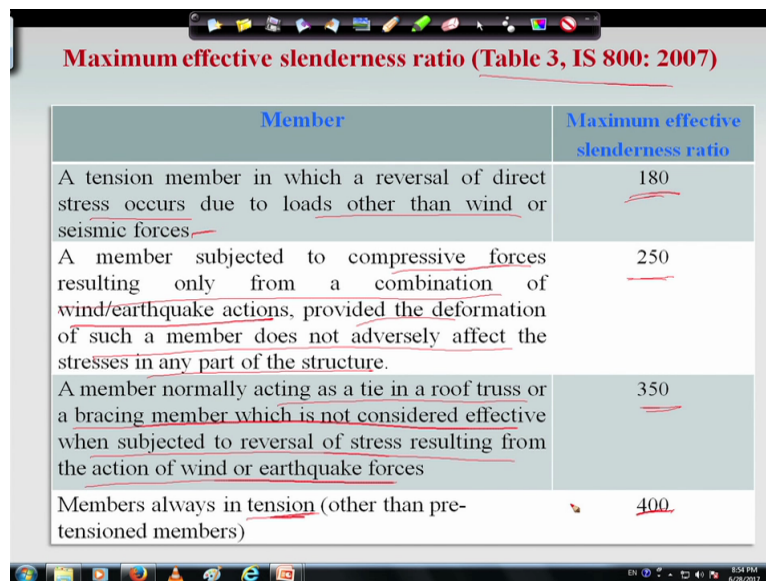


Now another things we have to check that is slenderness ratio slenderness ratio theoretically there should not be any upper limit of the slenderness ratio because it is under tension if it is compression then there is a chance of buckling so for that we have to consider the limiting value of slenderness ratio but in this case theoretically we should not, but we consider certain slenderness ratio from serviceability point of view, right limitation is necessary because to prevent undesirable vibration and (())(21:05) movement.

So this is given with this limitation limited values means permissible values are given in clause 3.8 clause 3.8 of or table 3 in the IS code table 3 in clause 3.8 the permissible value of slenderness ratio are given, right. So why we are providing slenderness ratio means in case of tension member because to make sure that vibration is not going to be more from limit state of serviceability point of view, we have to take care means we have to restrict certain slenderness ratio so that the excessive deformation can be restricted, also sometimes the member get reverse load means which was means due to wind and earthquake if reverse effect may happen.

So in that case slenderness ratio will be a big factor means will come into picture that is why IS code has provided certain permissible value with respect to slenderness ratio. (I am just changing the).

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Maximum effective slenderness ratio (Table 3, IS 800: 2007)

Member	Maximum effective slenderness ratio
A tension member in which a reversal of direct stress occurs due to loads other than wind or seismic forces.	180
A member subjected to compressive forces resulting only from a combination of wind/earthquake actions, provided the deformation of such a member does not adversely affect the stresses in any part of the structure.	250
A member normally acting as a tie in a roof truss or a bracing member which is not considered effective when subjected to reversal of stress resulting from the action of wind or earthquake forces	350
Members always in tension (other than pre-tensioned members)	400

So the slenderness value slenderness ratio value are given in table 3 of IS: 800-2007, if we see that we will see that when the tension member has reversal of direct stress due to loads other than wind and seismic it is 180 180, right.

Whereas when a member subjected to compressive forces resulting only from a combination of wind and earthquake actions, provided the deformation of such a member does not adversely affect the stresses in any part of the structure. In that case the permissible value of slenderness ratio is 250.

And if a member normally acting as a tie in a roof truss or a bracing member which is not considered effective when subjected to reversal of stress resulting from the action of wind or earthquake we can consider as 350.

And when members are always in tension other than pre-tensioned members we can consider as 400. So this is how the IS code has provided certain limit on maximum effective slenderness ratio, so that has to be keep in mind.

So that means when we are going to design a tension member not only we have to find out the strength point of view the section is shape but also we have to find out whether it is under the permissible limit of slenderness ratio or not, so both the things we have to see.

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Design Strength of Tension Members

The factored design tension T , in the members shall satisfy the following requirement (**Clause 6.1, IS:800-2007**) :

$$T < T_d$$

Where T_d = design strength of the member under axial tension.
 T_d is the lowest of the design strength due to the

- (i) yielding of gross-section, T_{dg} ,
- (ii) rupture of critical section T_{dn} and
- (iii) block shear failure, T_{db} .

So if I see quickly the design strength calculation for tension member we have to see that these three criteria we have to calculate one is yielding of gross section, then rupture of critical section and block shear failure and the least of these three will be the design strength of member and which should be means the factor design tension should be less than that design strength.

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Design Strength due to Yielding of Gross-section

The design strength of the member under axial tension, T_{dg} as governed by yielding of gross section is given by (**Clause 6.2, IS 800: 2007**)

$$T_{dg} = A_g f_y / \gamma_{m0}$$

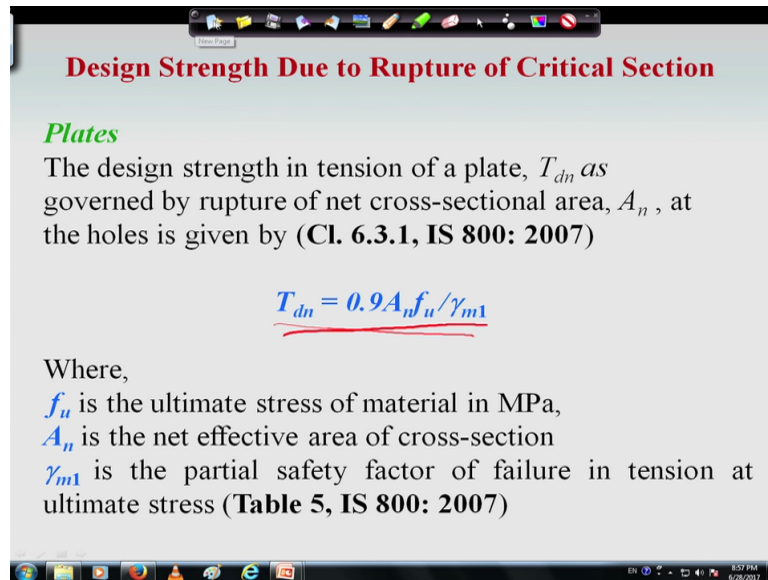
Where,

- f_y is the yield stress of material in MPa,
- A_g is the gross area of cross-section
- γ_{m0} is the partial safety factor of failure in tension by yielding (**Table 5, IS 800: 2007**)

So to find out this we have to calculate the design strength due to yielding of gross section, that we can calculate this is the T_{dg} is equal to $A_g f_y$ by γ_{m0} . Now A_g is the gross area of the section and f_y is the yield stress of material and γ_{m0} is the partial safety factor

and this gamma m0 value we can find out from table 5, right. So this is how we can find out the design strength due to yielding of gross section.

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Design Strength Due to Rupture of Critical Section

Plates

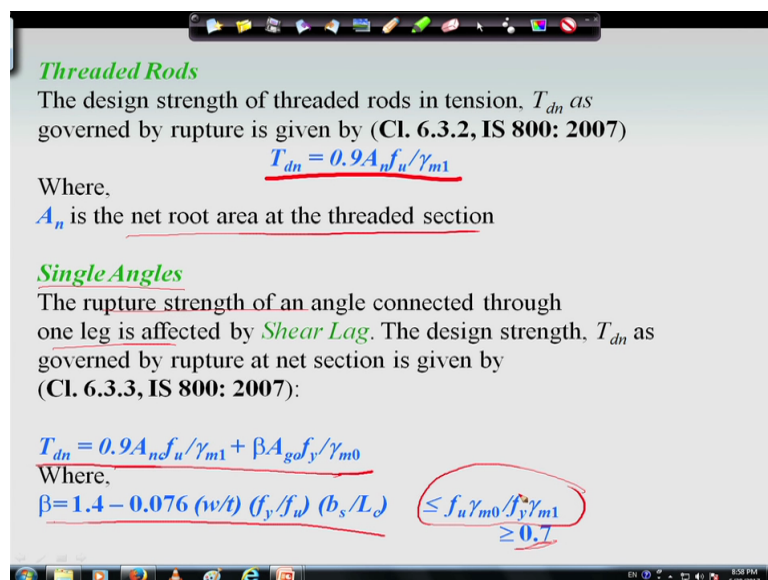
The design strength in tension of a plate, T_{dn} as governed by rupture of net cross-sectional area, A_n , at the holes is given by (Cl. 6.3.1, IS 800: 2007)

$$T_{dn} = 0.9A_n f_u / \gamma_{m1}$$

Where,
 f_u is the ultimate stress of material in MPa,
 A_n is the net effective area of cross-section
 γ_{m1} is the partial safety factor of failure in tension at ultimate stress (Table 5, IS 800: 2007)

Then design strength due to rupture of critical section if we see we can find out that T_{dn} is equal to $0.9A_n f_u$ by γ_{m1} , where f_u is the ultimate stress of material and A_n is the net effective area of the cross section and γ_{m1} is a partial safety factor. So for plate simply we can find out T_{dn} as $0.9A_n f_u$ by γ_{m1} .

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Threaded Rods

The design strength of threaded rods in tension, T_{dn} as governed by rupture is given by (Cl. 6.3.2, IS 800: 2007)

$$T_{dn} = 0.9A_n f_u / \gamma_{m1}$$

Where,
 A_n is the net root area at the threaded section

Single Angles

The rupture strength of an angle connected through one leg is affected by *Shear Lag*. The design strength, T_{dn} as governed by rupture at net section is given by (Cl. 6.3.3, IS 800: 2007):

$$T_{dn} = 0.9A_n f_u / \gamma_{m1} + \beta A_g f_y / \gamma_{m0}$$

Where,
 $\beta = 1.4 - 0.076 (w/t) (f_y / f_u) (b_s / L_e) \leq f_u \gamma_{m0} / f_y \gamma_{m1}$
 ≥ 0.7

But in case of angle we have to consider the shear lag effect when before going to angle first we will see how to calculate the T_{dn} value of threaded rods. So in case of threaded rod

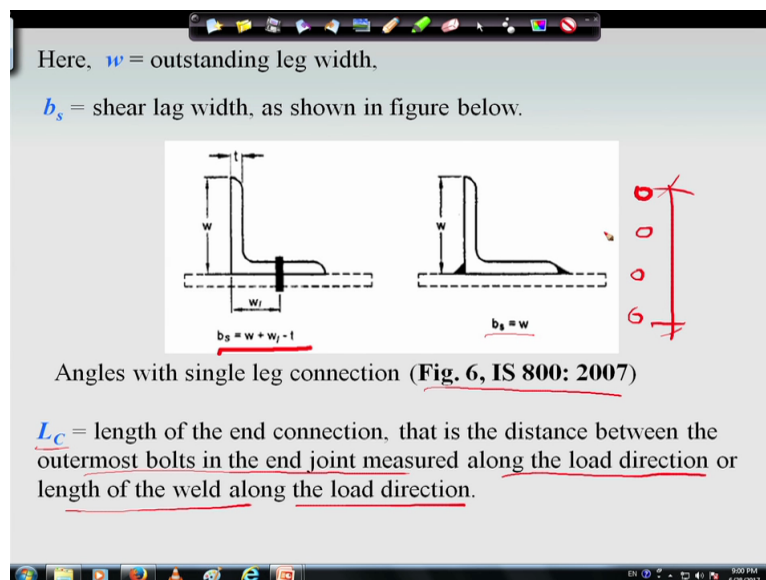
formula is same only the A_n will be the net root area net root area of the threaded section. So while calculating the net area of the section we have to calculate net root area of the threaded section in case of threaded rod.

And if we have a single angle connection means if the angle is connected with a plate then the rapture strength of that angle which is connected through one leg can be found from this because if it is connected through one leg then shear lag effect will be will come into picture, so that has to be taken care.

So Tdn as we see will be $0.9A_{nc}f_u$ by γ_{m1} plus beta into A_gf_y by γ_{m0} and beta can be calculated from this formula that is $1.4 - 0.076 \left(\frac{w}{t} \right) \left(\frac{f_y}{f_u} \right)$ and $\left(\frac{b_s}{L_c} \right)$ and the beta value should not exceed this value that is $f_u \gamma_{m0}$ by $f_y \gamma_{m1}$ and should not be less than means it should be should not be less than $(0.07) 0.7$.

So this is how we can find out the design strength of angle due to rapture and while calculating we need to know what is the b_s the shear lag width and L_c . So these two we have to know.

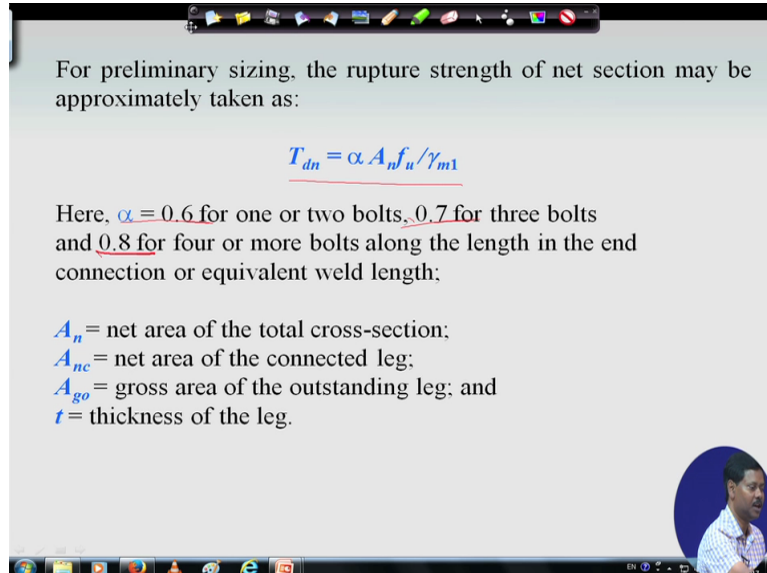
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So if we see here that the b_s value can be calculated as b_s is equal to w plus w_1 minus t , if it is connected with bolt and if it is connected with one leg with weld then b_s is equal to simply w . So this is given in figure 6 of IS: 800-2007 from which directly I am showing here and L_c will be the length of end connection that is the distance between the outermost bolts in the end joint measured along the load direction or length of the weld along the load direction. So this is how I can find out the L_c .

So in case of bolt connections it will be if we have bolt like this so end to end connection the distance between end to end bolt and along the load direction and if it is weld simply length of the weld along load directions means we have to find out the length of the weld along load direction, this is how we can calculate.

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For preliminary sizing, the rupture strength of net section may be approximately taken as:

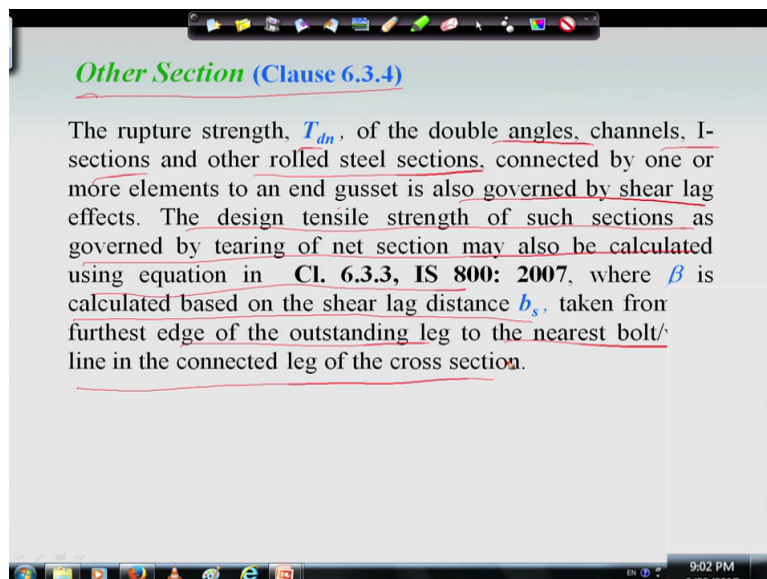
$$T_{dn} = \alpha A_n f_u / \gamma_{m1}$$

Here, $\alpha = 0.6$ for one or two bolts, 0.7 for three bolts and 0.8 for four or more bolts along the length in the end connection or equivalent weld length;

A_n = net area of the total cross-section;
 A_{nc} = net area of the connected leg;
 A_{go} = gross area of the outstanding leg; and
 t = thickness of the leg.

And for preliminary sizing we can find out the rupture strength approximately as this T_{dn} is equal to $\alpha A_n f_u / \gamma_{m1}$ and this α value has been given in the code as 0.6 for one or two bolts, 0.7 for three bolts and 0.8 for four or more bolts along the length in the end connection, so this is how we can approximately find the T_{dn} value.

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Other Section (Clause 6.3.4)

The rupture strength, T_{dn} , of the double angles, channels, I-sections and other rolled steel sections, connected by one or more elements to an end gusset is also governed by shear lag effects. The design tensile strength of such sections as governed by tearing of net section may also be calculated using equation in Cl. 6.3.3, IS 800: 2007, where β is calculated based on the shear lag distance b_s , taken from furthest edge of the outstanding leg to the nearest bolt/line in the connected leg of the cross section.

And for other sections the codal provisions sorry codal provisions are given in clause 6.3.4 where it is mentioned that the rapture strength T_{dn} of the double angle channel I-sections and other rolled steel sections, connected by one or more elements to an end gusset is also governed by shear lag. So the design tensile strength of such sections as governed by tearing of net section may also be calculated using equation given in clause 6.3.3. Here beta is the calculated based on the shear lag distance b_s, which we have calculated earlier we have seen taken from the furthest edge of the outstanding leg to the nearest bolt or weld line in the connected leg of the cross section. So this is what clause 6.3.4 describes, so for other sections we have to keep in mind for calculating the T_{dn} value.

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Design Strength due to Block Shear
(Cl. 6.4, IS 800: 2007)

The strength as governed by block shear at an end connection of plates and angles is calculated as follows:

Bolted Connections

The block shear strength, T_{db} of connection shall be taken as the smaller of,

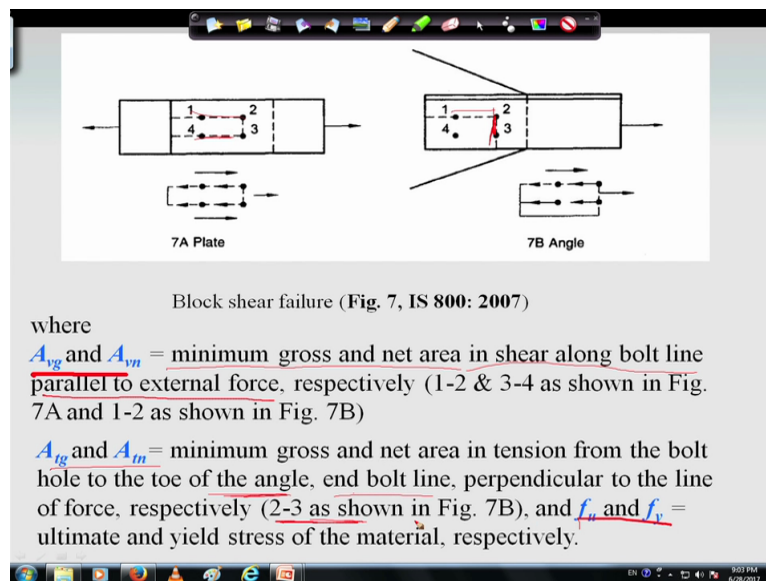
$$T_{db} = \frac{A_{vg} f_y}{\sqrt{3} \gamma_{m0}} + \frac{0.9 A_{tn} f_u}{\gamma_{m1}} \quad (\text{For tension fracture and shear yield})$$

OR

$$T_{db} = \frac{0.9 A_{vn} f_u}{\sqrt{3} \gamma_{m1}} + \frac{A_{tg} f_y}{\gamma_{m0}} \quad (\text{For tension yield and shear fracture})$$

And another factor we have to consider that is block shear. So the strength as governed by block shear at the end connection of plates are this that is T_{db} is equal to A_{vg}f_y by root 3 gamma m₀ plus 0.9A_{tn}f_u by gamma m₁, or T_{db} is equal to 0.9A_{vn}f_u by root 3 gamma m₁ plus A_{tg}f_y by gamma m₀. This is for tension fracture and yield shear yield and this is for tension yield and shear fracture. So least of these two will be the strength due to block shear failure.

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Now while calculating block shear failure we have to know the A_{vg} and A_{vn} value how to calculate this is given in the code in figure 7 it is mentioned that this will be the minimum gross and net area in shear along bolt line parallel to the external force, that means 1-2 and 3-4 in plate and 1-2 in angle.

And A_{tg} and A_{tn} will be the minimum gross and net area in tension from the bolt hole to the toe of the angle bolt hole to the toe of the angle, that means the end bolt line perpendicular to the line of force respectively that means 2-3 as shown in figure so this is right and f_u and f_y are has the usual meaning. So this is how we can calculate A_{vg} , A_{vn} , A_{tg} , A_{tn} and then the block shear T_{db} .

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Welded Connection

The block shear strength, T_{db} shall be checked for welded end connections by taking an appropriate section in the member around the end weld, which can shear off as a block.

Slenderness Ratio

The slenderness ratio is the ratio of unsupported length and least radius of gyration. Theoretically there should not be any upper limit of the slenderness ratio for a tension member as stability is of little importance. However, a tension member may be subjected to reversal force like wind, earthquake etc. Also, the limitation is necessary to prevent undesirable vibration and lateral movement. For this, IS 800-2007 code (clause 3.8, Table 3) has specified the maximum values of effective slenderness ratio.

In case of weld connection the codal provisions says that the block shear strength T_{db} shall be checked for welded end connections by taking an appropriate section in the member around the end weld, which can shear off as a block so that we have to take care. And in case of slenderness ratio the maximum (33:27) slenderness ratio are given in table 3 of IS: 800-2007 and in clause 3.8 it is mentioned.

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Maximum effective slenderness ratio (Table 3, IS 800: 2007)

Member	Maximum effective slenderness ratio
A tension member in which a reversal of direct stress occurs due to loads other than wind or seismic forces	180
A member subjected to compressive forces resulting only from a combination of wind/earthquake actions, provided the deformation of such a member does not adversely affect the stresses in any part of the structure.	250
A member normally acting as a tie in a roof truss or a bracing member which is not considered effective when subjected to reversal of stress resulting from the action of wind or earthquake forces	350
Members always in tension (other than pre-tensioned members)	400

So that also I am showing that is given here that maximum effective slenderness ratio slenderness ratio means L/R where R is the minimum radius of (33:56) and L is the effective length. So we can calculate the effective slenderness ratio and from that we have to check that which condition it is coming, then accordingly the maximum limiting value has to be checked whether it is ok or not.

So this is how one can calculate the particular section capacity, design capacity and check whether that section is (34:31) the slenderness ratio means ratio the codal provisions of the slenderness ratio or not, right.

So in today's lecture if we see that in short we can say that how to calculate the design strength of a member under axial load, axial tension that we have gone through and also we have seen that what will be the maximum permissible effective slenderness ratio of the member for different loading case. So considering all this we can next design the things, right thank you very much.